based on various sources, including slides from: José Nelson Amaral – University of Alberta, David Walker – Princeton University



Register Allocation

Compilers course

Masters in Informatics and Computing Engineering (MIEIC), 3rd Year



João M. P. Cardoso



Dep. de Engenharia Informática Faculdade de Engenharia (FEUP), Universidade do Porto, Porto, Portugal Email:jmpc@acm.org

Outline

- Introduction to Register Allocation
- Variables' Live Ranges
- Left-Edge Algorithm
- Register Allocation by Graph Coloring
 - Heuristics
 - Spilling
- Summary

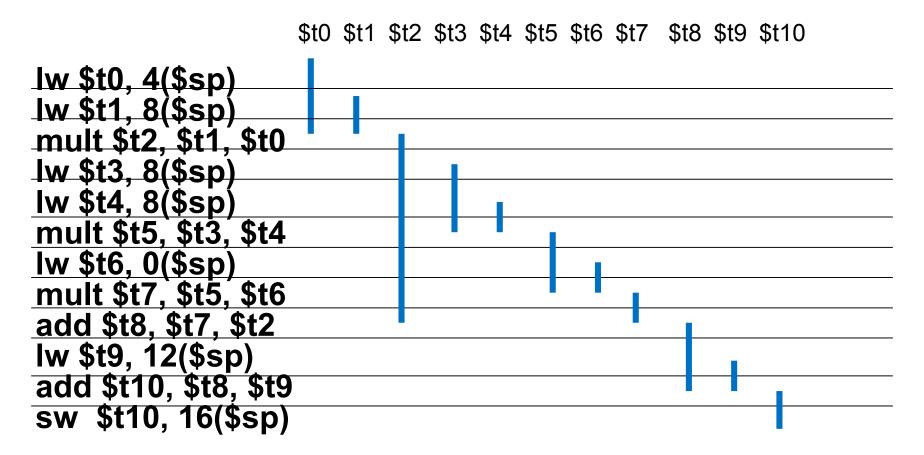
- > Store as many variables as possible in registers
- Use each register to store as many variables as possible (registers are limited resources)
 - use live range (also known as "lifetime interval") of variables
- One the optimizations with highest impact (code size and performance)

Variables' Live Ranges

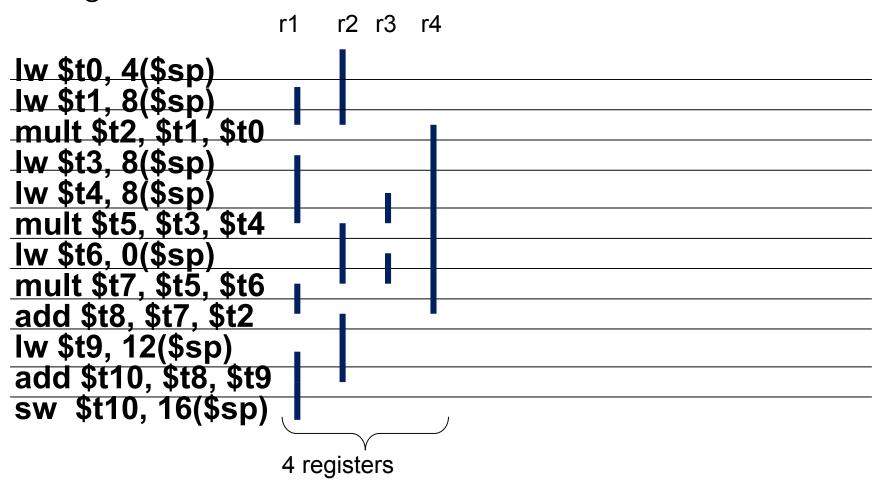
- Duration in the code from a definition of a variable and a use of this variable reached by that definition
- See Liveness Analysis

Variables' Live Ranges

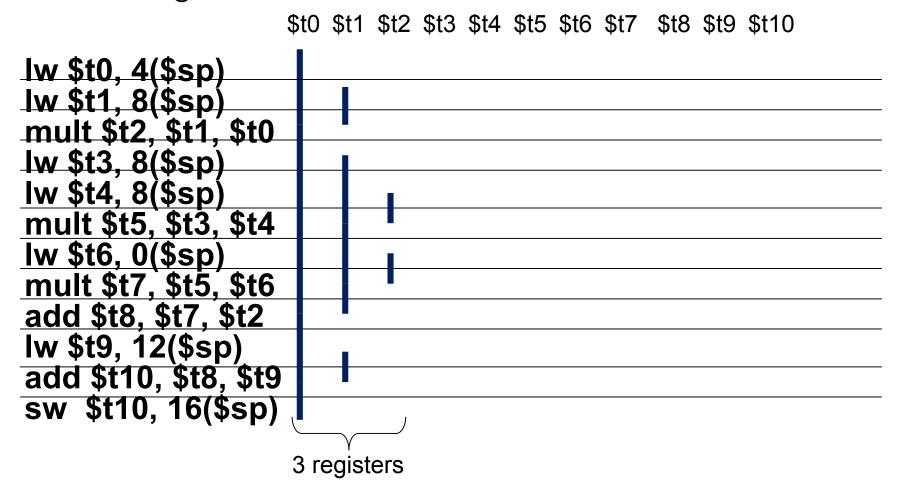
Variables' live ranges in the following MIPS code



Based on the variable's live ranges try to use each register to store more than one variable



Let's try to reduce the number of registers t in the following MIPS code



- > Determine the live range for each variable
- > Allocate a register to one or more variables
- ➤ Hows
 - Left-Edge Algorithm
 - Graph Coloring (problem NP-complete)
 - Use heuristics

- Left-edge Algorithm
 - Sort segments (live range) by their start time (ascending order)
 - 2. Start by the first segment and try to merge each of the other segments with this one (two segments are merged is they don't overlap)
 - 3. When there is no possibility to merge other segments goto step 2 considering the next segment in the sorted list
 - 4. Number of register = number of columns with segments

Left-edge Algorithm

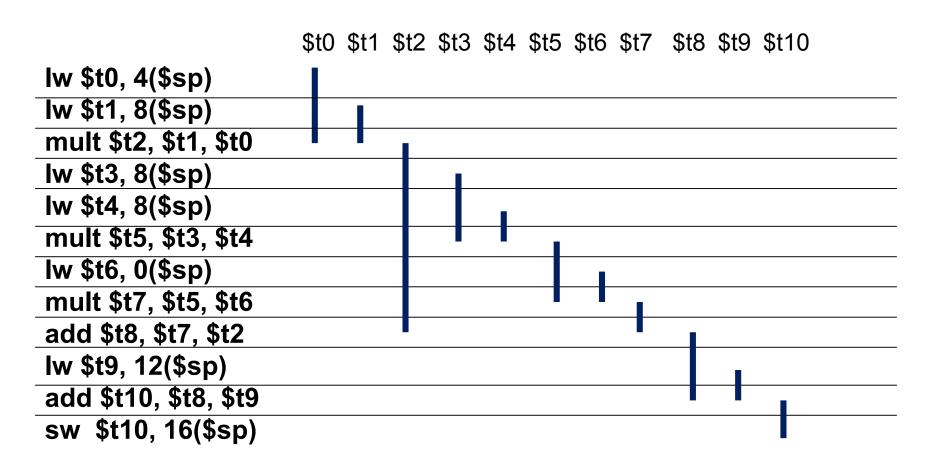
```
LEFT_EDGE(I) {
  Sort elements of I in a list L in ascending order of
  c = 0;
  while (some interval has not been colored ) do
      S =∅;
      r = 0;
      while (\exists s \in L \text{ such that } ls > r) do
          s = First element in the list L with <math>ls > r;
          S = S \cup \{s\};
          r = rs;
          Delete s from L;
      c = c + 1;
      Label elements of S with color c;
```

- Do register allocation for the basic block (B) of instructions shown below using the left edge algorithm
- > Consider:
 - live-in(B) = {a,x,b,c}
 - live-out(B) = $\{y\}$
- How many registers we need?

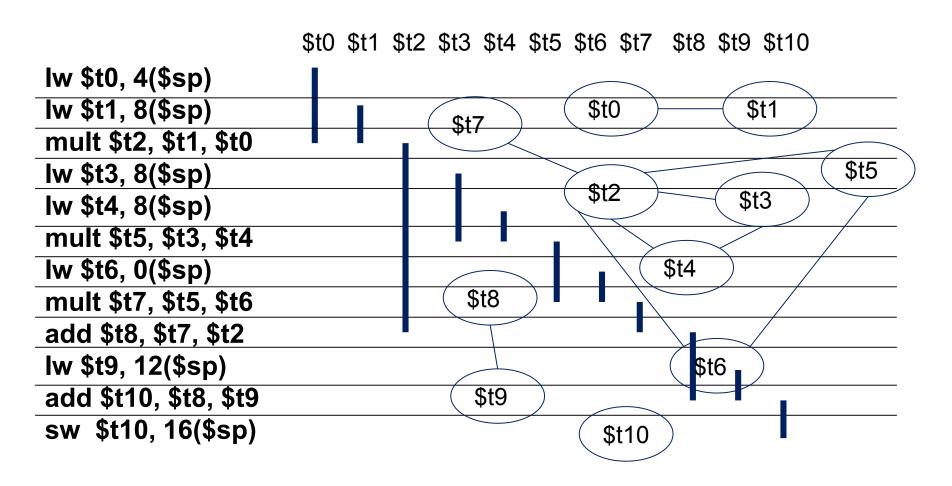
```
t1=x*x;
t2=a*t1;
t3=b*x;
t4=t3+c;
t5=t4+t2;
y=t5;
```

- Graph Coloring
 - Calculate the live range for each variable
 - Construct the Register-Interference Graph* (there is interference when 2 variables have lifetimes with non-null intersection)
 - Edges represent interference
 - Nodes represent variables
 - Find the minimum colors or the k colors
 - Each color corresponds to a register
 - i.e., number of registers = number of colors
- * Also known as Register-Conflict Graph

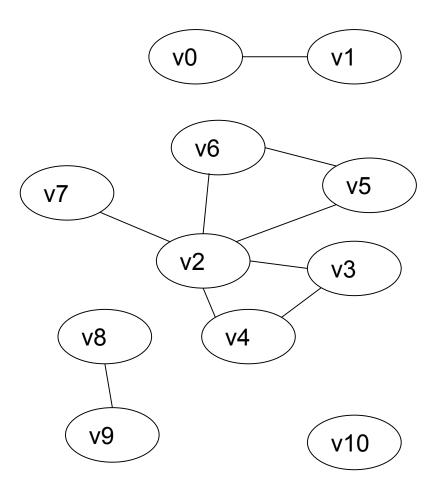
Variables' Live Range



Register-Interference Graph (IG)

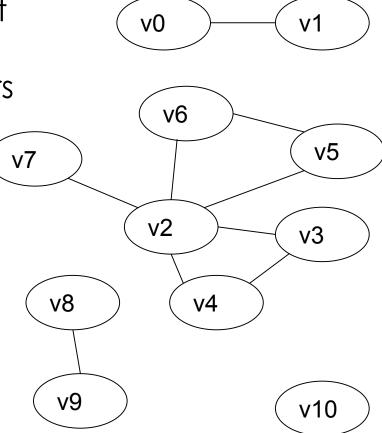


- Register-Interference Graph
 - Interference (edge)
 between two
 variables (nodes)
 indicates that the two
 variables could not
 be stored in the same
 register



Register-Inference Graph > After Coloring: v6 Number of colors indicate the number of necessar, v7 registers v2 ٧3 **v**4

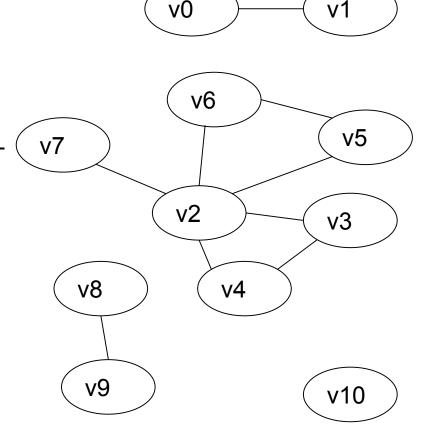
A graph is k-colorable if each node can be assigned one of k colors in such a way that no two adjacent nodes have the same color.



Steps:

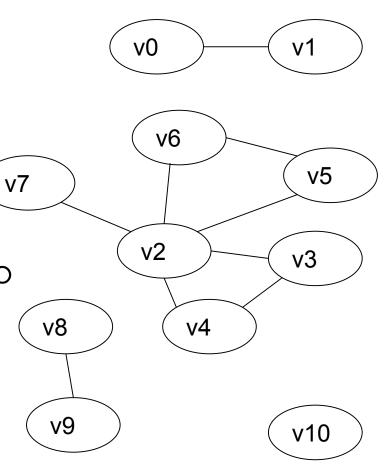
1. Build the register interference graph,

2. Attempt to find a k-coloring for the interference graph.

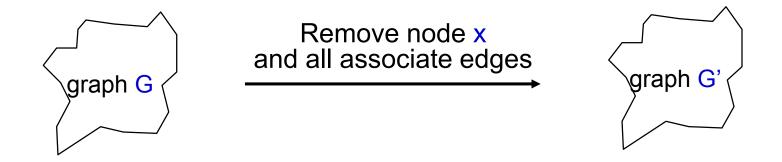


The problem of determining if an undirected graph is k-colorable is NP-hard for k≥3

It is also hard to find approximate solutions to the graph coloring problem

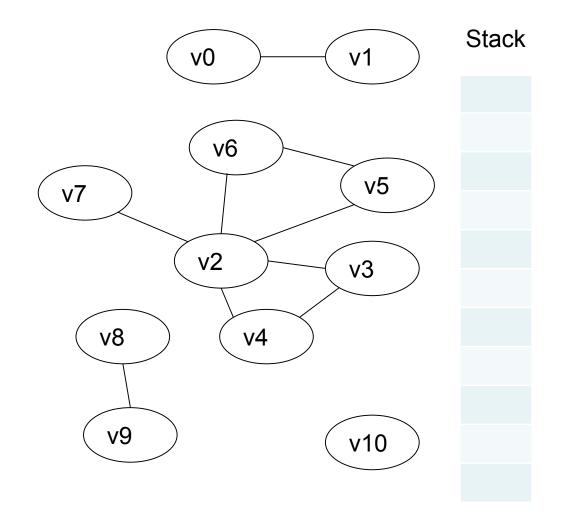


- > Key observation:
 - Let G be an undirected graph
 - Let x be a node of G such that degree(x) < k

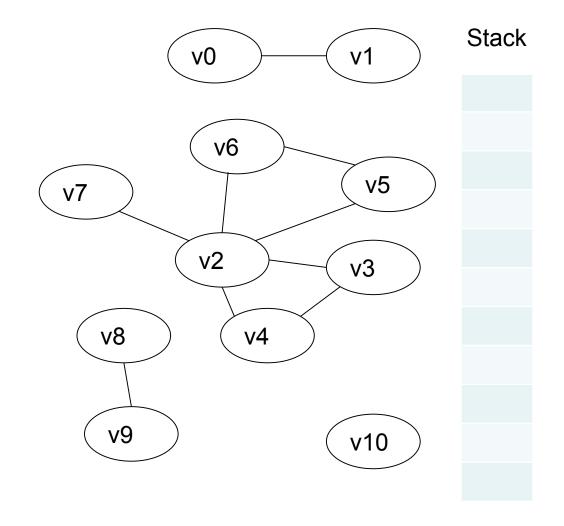


Then G is k-colorable if G' is k-colorable.

- Kempe's algorithm [1879] for finding a K-coloring of a graph
- Find a node n with degree(n)<k and cut it out of the graph (remember this node on a stack for later stages)



- Once a coloring is found for the simpler graph, we can always color the node we saved on the stack
- > Step 2 (color): when the simplified subgraph has been colored, add back the node on the top of the stack and assign it a color not taken by one of the adjacent nodes

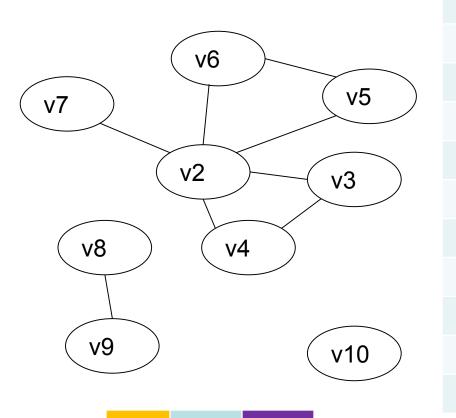


> Let's go back to the example

<u>v0</u> <u>v1</u>

Stack

Consider k=3



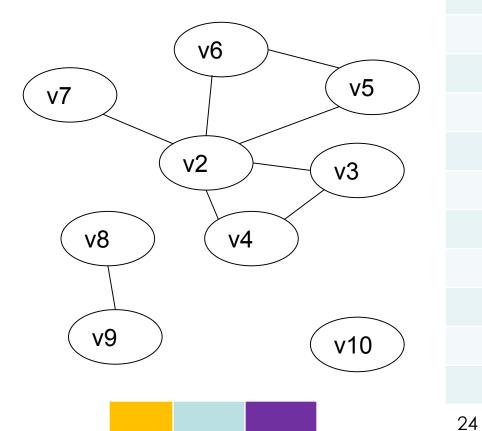
Let's go back to the example

v0 v1

Stack

Consider k=3

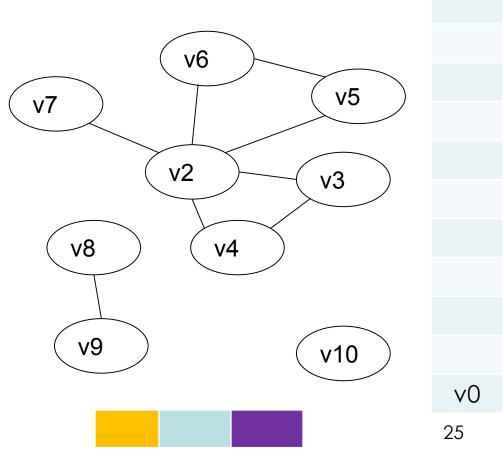
 \rightarrow Edges(v0) < 3



Let's go back to the example

Stack

Consider k=3



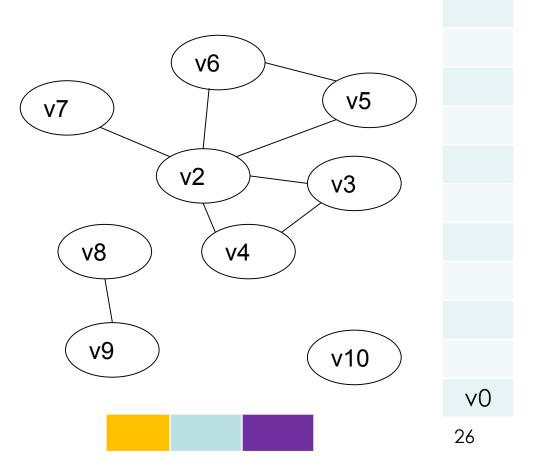
Let's go back to the example

v0 v1

Stack

Consider k=3

 \rightarrow Edges(v1) < 3

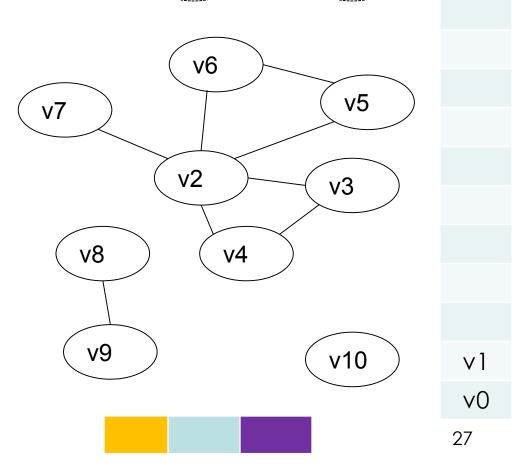


Let's go back to the example

v0 _____v1

Stack

Consider k=3



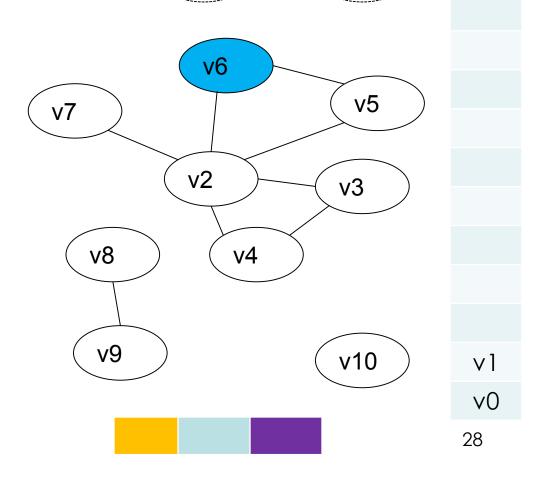
Let's go back to the example

v0 _____v1

Stack

Consider k=3

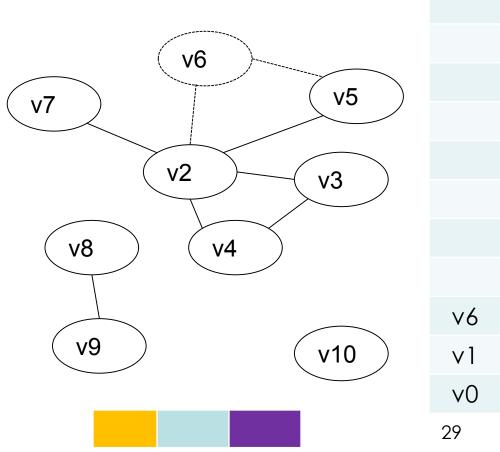
 \rightarrow Edges(v6) < 3



Let's go back to the example

Stack

Consider k=3



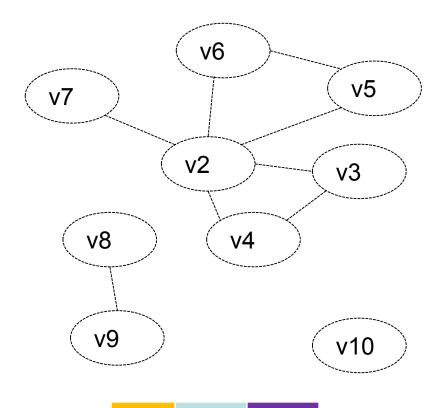
> Let's go back to the example

v0 v1

Stack

Consider k=3

> After some steps...



v10

v9

v8

v7

v2

v4

v3

v5

٧6

v1

Let's go back to the example

v0

Stack

> Consider k=3 **v**10 **v**9 Now we start coloring using v6 the top of the stack 8٧ **v**5 v7 **v**7 **v**2 **v**2 ٧3 **v**4 **v**3 8v v4 **v**5 ٧6 v9 v10 **v**1 **V**0

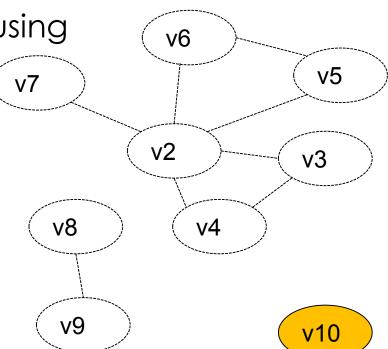
> Let's go back to the example

Stack

> Consider k=3

Now we start coloring using the top of the stack

v10



v9

v8

v7

v2

v4

v3

v5

٧6

v1

> Let's go back to the example

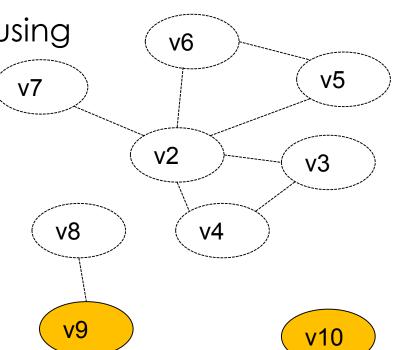
v0 ______v1

Stack

Consider k=3

Now we start coloring using the top of the stack

v9



v8

v7

v2

v4

٧3

v5

٧6

v1

Let's go back to the example

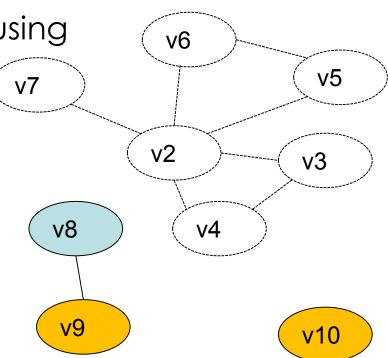
v0 ______v1

Stack

> Consider k=3

Now we start coloring using the top of the stack

V8



v7

v2

v4

v3

v5

٧6

v1

> Let's go back to the example

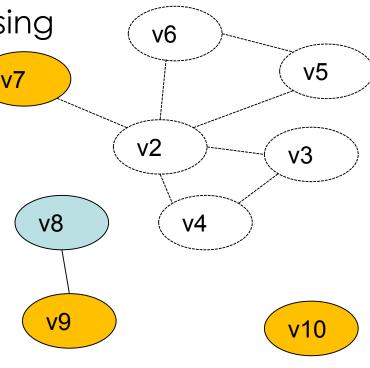
v0 ______v1

Stack

> Consider k=3

Now we start coloring using the top of the stack

v7



v2

v4

v3

v5

٧6

v1

> Let's go back to the example

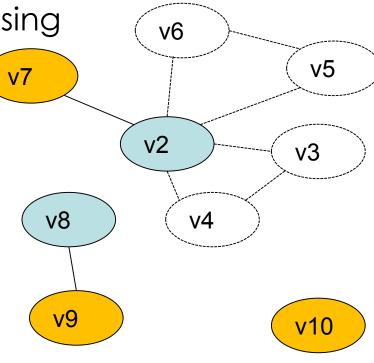
v0 ______v1

Stack

Consider k=3

Now we start coloring using the top of the stack

v2



v4

٧3

v5

٧6

v1

> Let's go back to the example

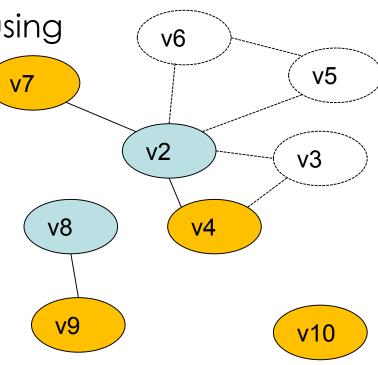
v0 ______v1

Stack

> Consider k=3

Now we start coloring using the top of the stack

• ∨4



v3

v5

٧6

v1

v0

37

Let's go back to the example

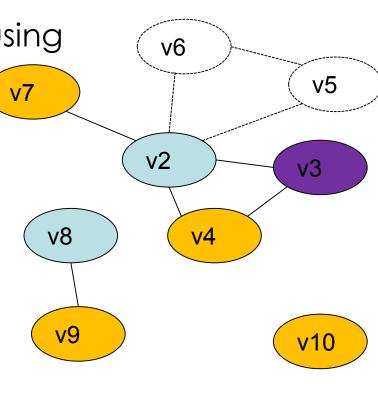
v0

Stack

> Consider k=3

Now we start coloring using the top of the stack

v3



v5

٧6

v1

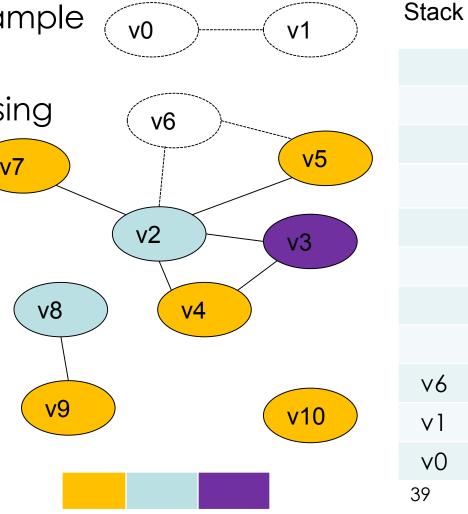
V0

Let's go back to the example

➤ Consider k=3

Now we start coloring using the top of the stack

v5

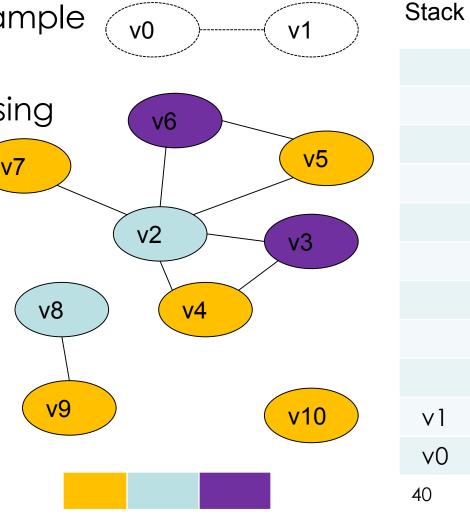


> Let's go back to the example

➤ Consider k=3

Now we start coloring using the top of the stack

v6

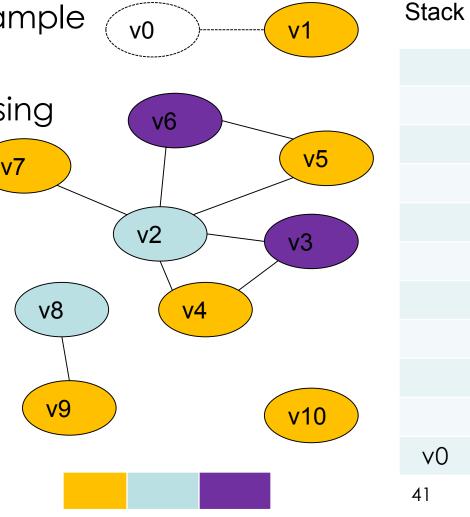


Let's go back to the example

> Consider k=3

Now we start coloring using the top of the stack

• ∨1



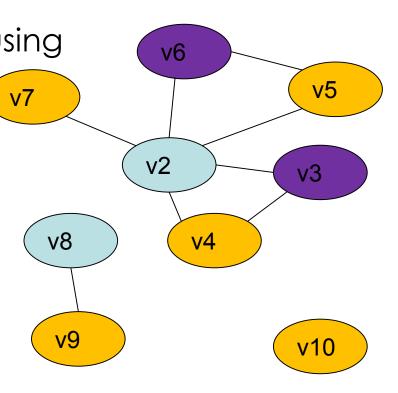
> Let's go back to the example

v0 v1

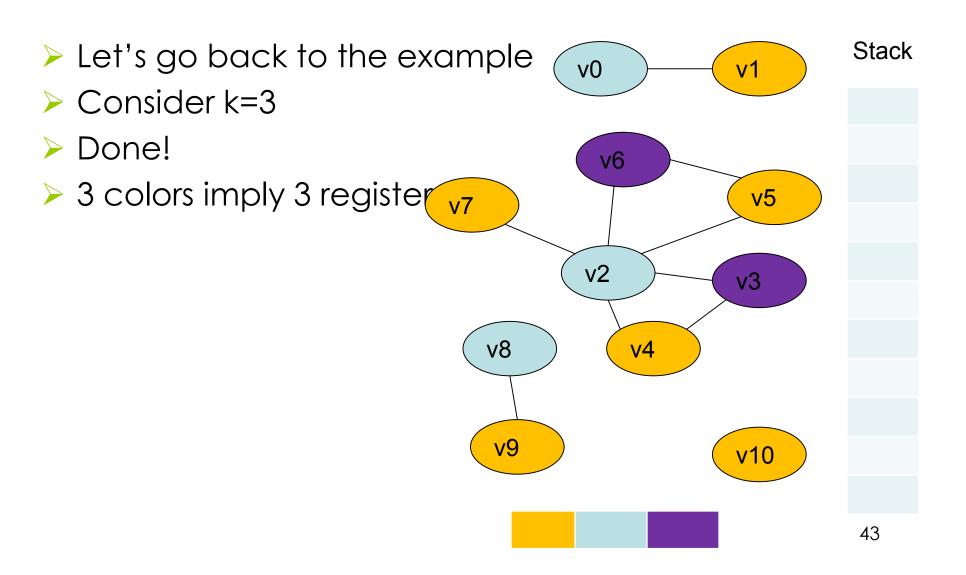
> Consider k=3

Now we start coloring using the top of the stack

v0



Stack



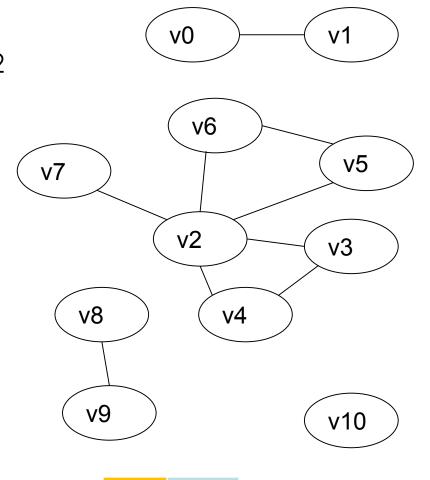
Register Allocation

Question: What to do if a register-interference graph is <u>not</u> k-colorable? Or if the compiler cannot efficiently find a k-coloring even if the graph is k-colorable?

Answer: Repeatedly select less profitable variables for "spilling" (i.e. not to be assigned to registers) and remove them from the interference graph until the graph becomes k-colorable.

> Example:

 What if we only have 2 registers, i.e., k=2?

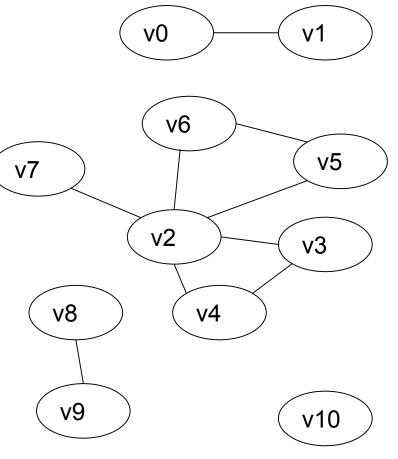


Step 3 (spilling): once all nodes have K or more neighbors, pick a node for spilling

Storage on the stack

There are many heuristics that can be used to pick a node

• E.g., not in an inner loop



- We need to generate extra instructions to load variables from stack and store them
- > These instructions use registers themselves. What to do?
 - Stupid approach: always keep extra registers handy for shuffling data in and out: what a waste!
 - Better approach: ?

- We need to generate extra instructions to load variables from stack and store them
- > These instructions use registers themselves. What to do?
 - Stupid approach: always keep extra registers handy for shuffling data in and out: what a waste!
 - Better approach: rewrite code introducing a new temporary; rerun liveness analysis and register allocation

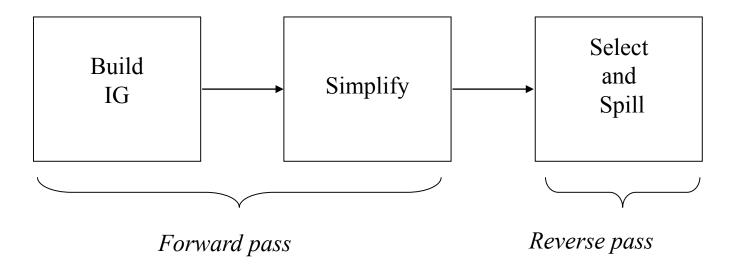
- Consider: add t1, t2, t3
 - Suppose t3 is selected for spilling and assigned to stack location [8+\$sp]
 - Invented new temporary t35 for just this instruction and rewrite:
 - **lw \$t35**, **8(\$sp)**; add t1, t2, t35
 - Advantage: t35 has a very short live range and is much less likely to interfere
 - Rerun the algorithm
 - fewer variables will spill

- Variables selected to Spill?
- > The selection can be based on a number of properties:
 - frequencies of execution of uses/defs (based on the iteration count, profiling results)
 - number of uses/defs
 - number of adjacent nodes for the variable in the Interference Graph
 - Lifetime duration
 - etc.

Precolored Nodes

- Some variables are pre-assigned to registers
- > Treat these registers as special temporaries; before beginning, add them to the graph with their colors
- Can't simplify a graph by removing a precolored node
- Precolored nodes are the starting point of the coloring process
- Once simplified down to colored nodes start adding back the other nodes as before

> A 2-Phase Register Allocation Algorithm



Remarks

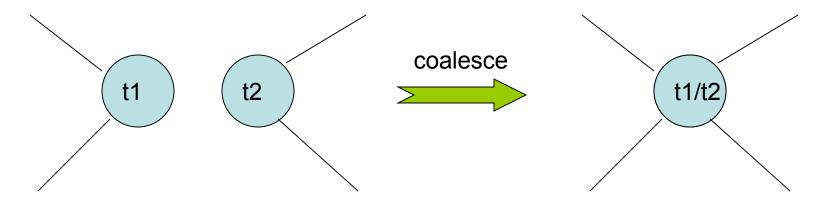
- > This register allocation algorithm, based on graph coloring, is both efficient (linear time) and effective (good assignment)
- It has been used in many industry-strength compilers to obtain significant improvements over simpler register allocation heuristics

Optimizing Moves

- Code generation produces a lot of extra move instructions
 - mov t1, t2 ($t1 \leftarrow t2$)
 - If we can assign 11 and 12 to the same register, we do not have to execute the mov
 - Idea: if t1 and t2 are not connected in the interference graph, we coalesce into a single variable
 - First: Include in the register interference graph a move-related edge between two variables used in a move instruction

Coalescing

Problem: coalescing can increase the number of interference edges and make a graph uncolorable



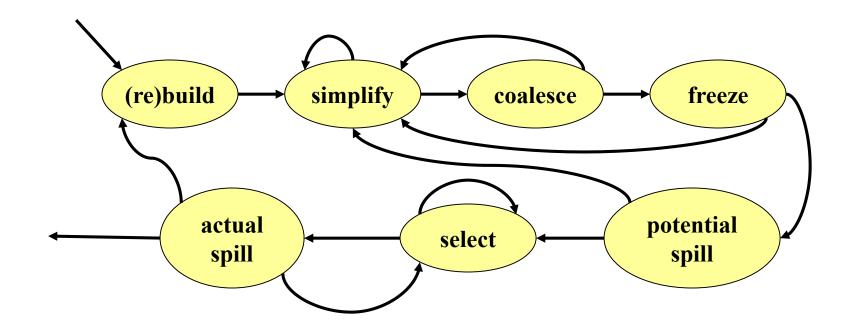
- > Solution 1 (Briggs): avoid creation of high-degree (>= K) nodes
- > Solution 2 (George): a can be coalesced with b if every neighbor t of a:
 - already interferes with b, or
 - has low-degree (< K)

Simplify and Coalesce

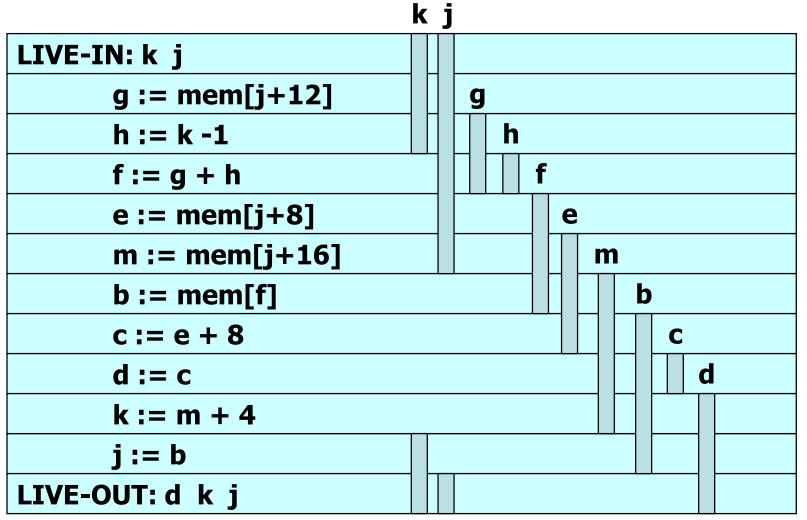
- Step 1 (simplify): simplify as much as possible without removing nodes that are the source or destination of a move (moverelated nodes)
- Step 2 (coalesce): coalesce move-related nodes provided low-degree node results
- Step 3 (freeze): if neither steps 1 or 2 apply, freeze a move instruction: registers involved are marked not move-related and try step 1 again
- Step 4 (spill): if there are no low-degree nodes, select a node for potential spilling
- Step 5 (select): pop each element of the stack assigning colors and turning potential spill into actual spill if needed
- Step 6 (rewrite the program): rewrite the program based on the register allocation, remove move operations with coalesced variables, and inserting spilling code. If there is spill build a new register-inference graph and goto Step 1

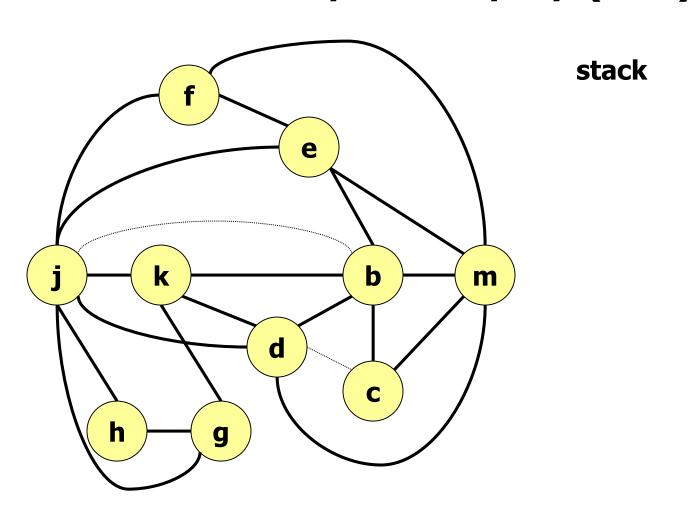
Overall Algorithm

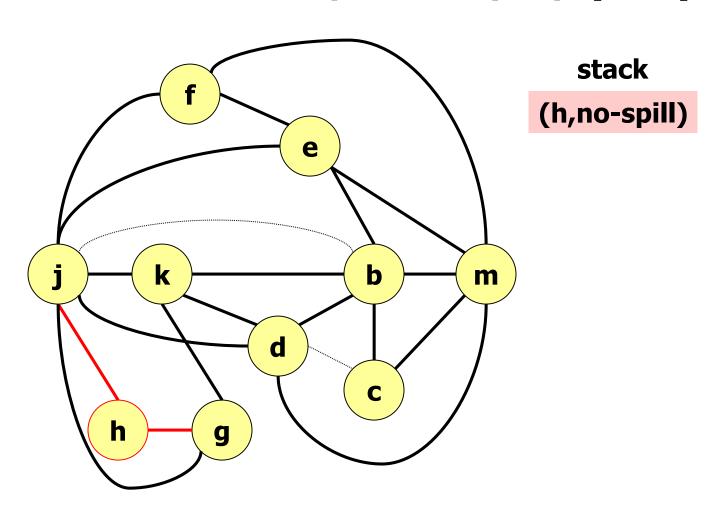
From Tiger Book (by Appel)

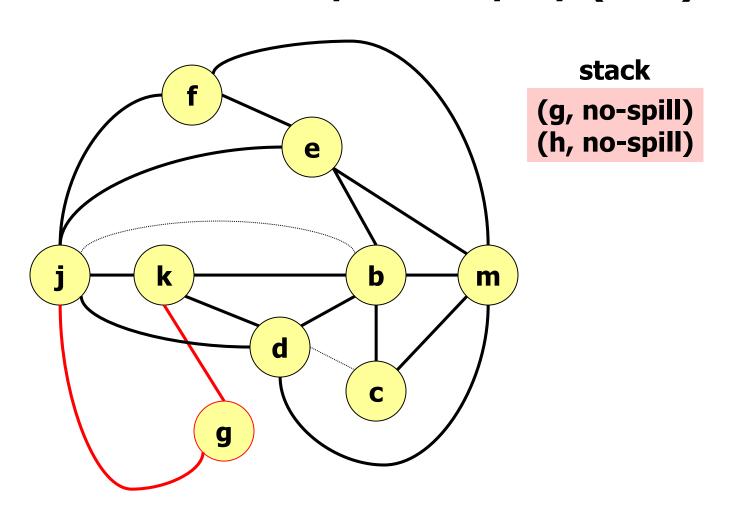


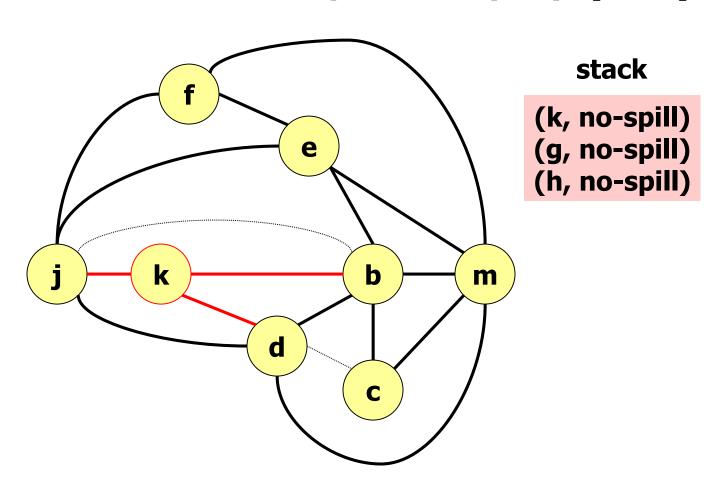
Example: Step 1: Compute Live Ranges

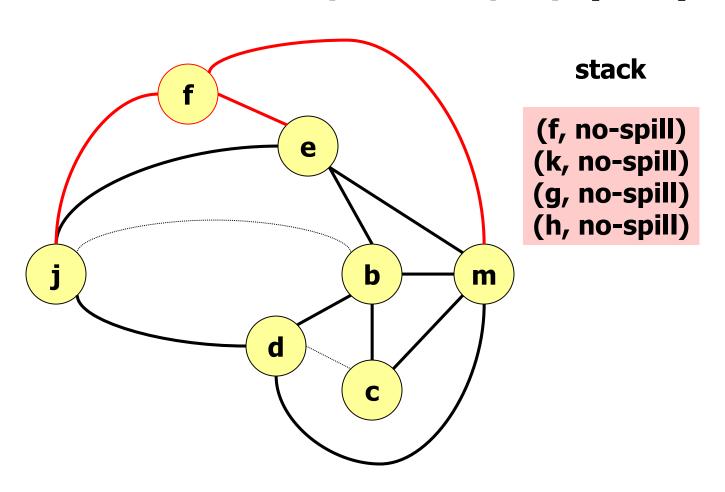


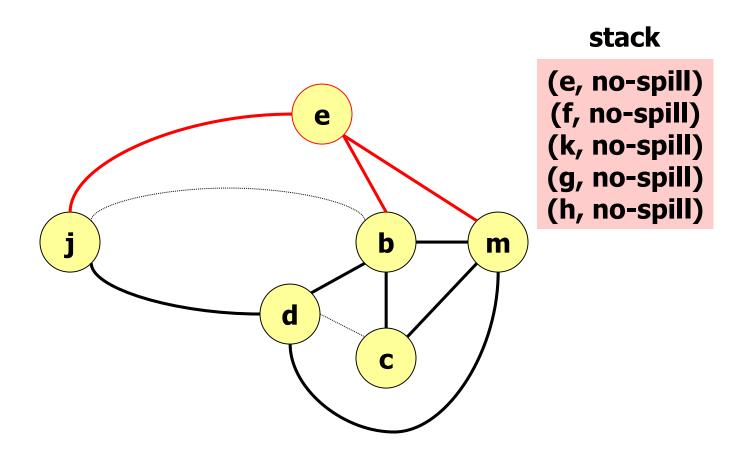




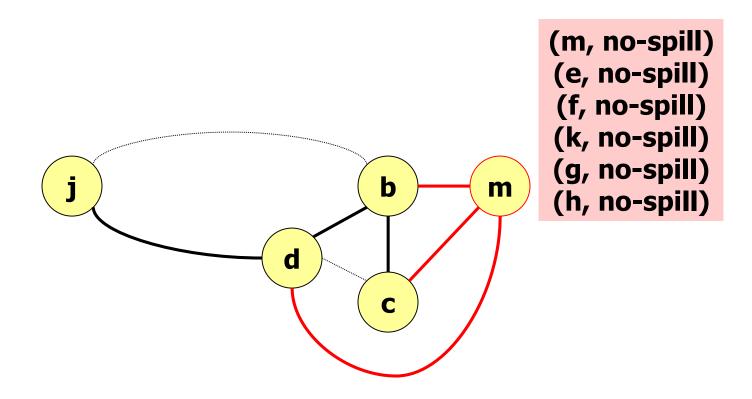






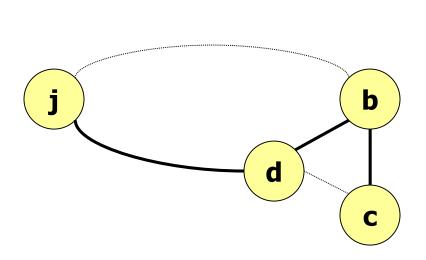


stack



Example: Step 3: Coalesce (K=4)

stack



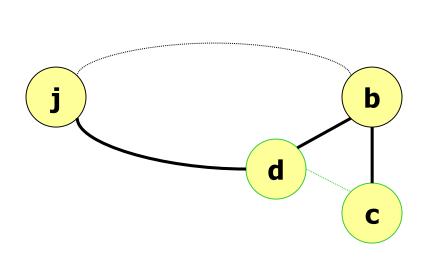
```
(m, no-spill)
(e, no-spill)
(f, no-spill)
(k, no-spill)
(g, no-spill)
(h, no-spill)
```

Why we cannot simplify?

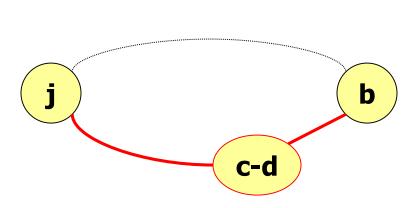
Cannot simplify move-related nodes.

Example: Step 3: Coalesce (K=4)

stack



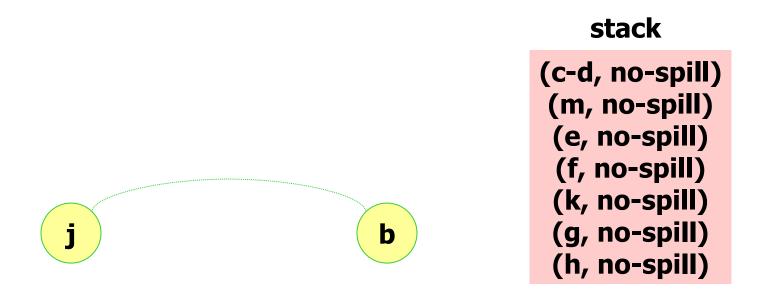
```
(m, no-spill)
(e, no-spill)
(f, no-spill)
(k, no-spill)
(g, no-spill)
(h, no-spill)
```



stack

```
(c-d, no-spill)
(m, no-spill)
(e, no-spill)
(f, no-spill)
(k, no-spill)
(g, no-spill)
(h, no-spill)
```

Example: Step 3: Coalesce (K=4)

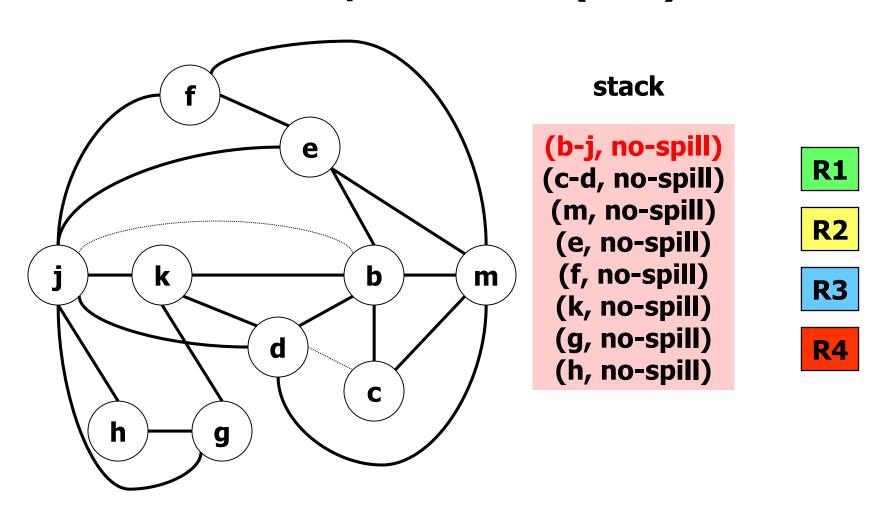


stack

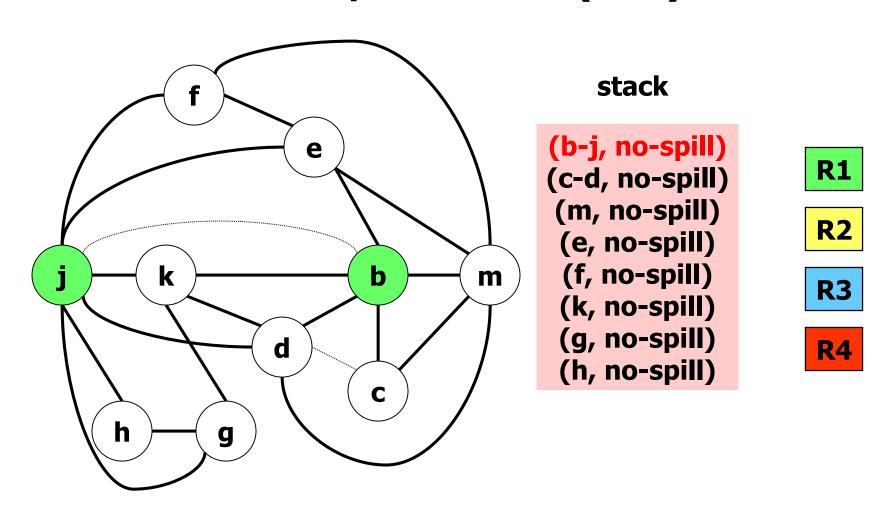
b-j

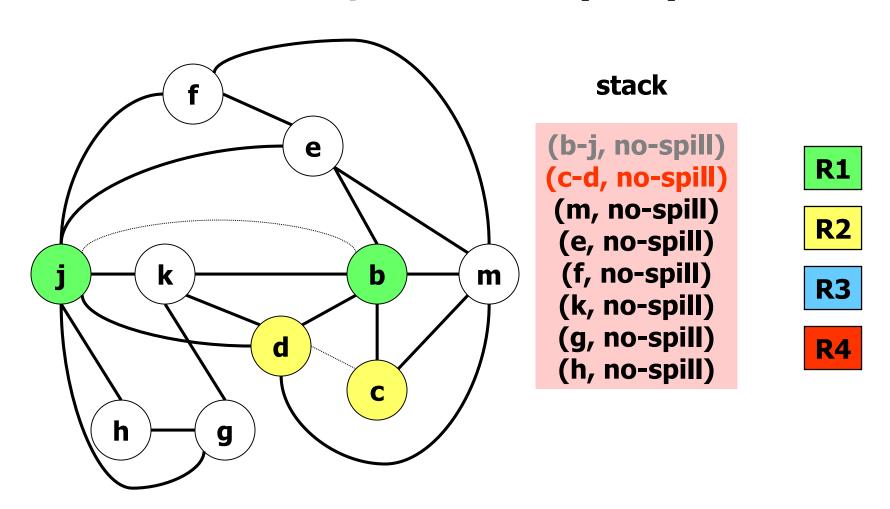
```
(b-j, no-spill)
(c-d, no-spill)
(m, no-spill)
(e, no-spill)
(f, no-spill)
(k, no-spill)
(g, no-spill)
(h, no-spill)
```

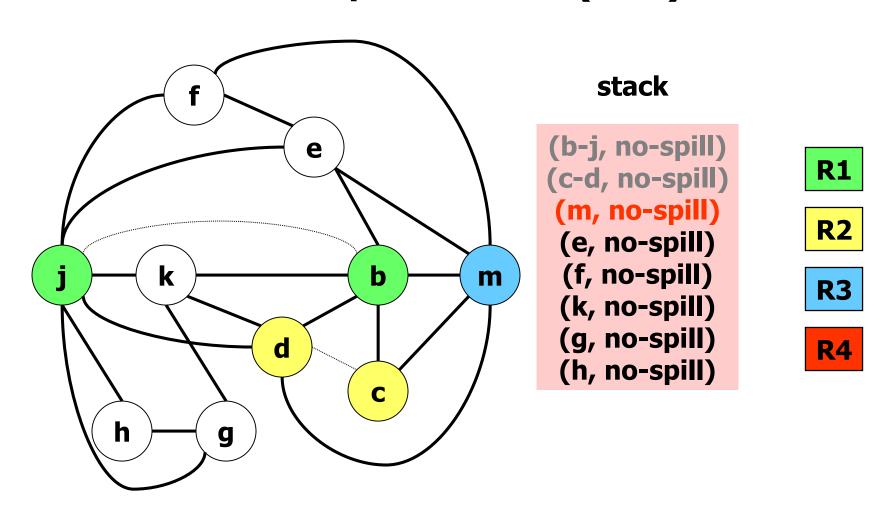
Example: Step 3: Select (K=4)

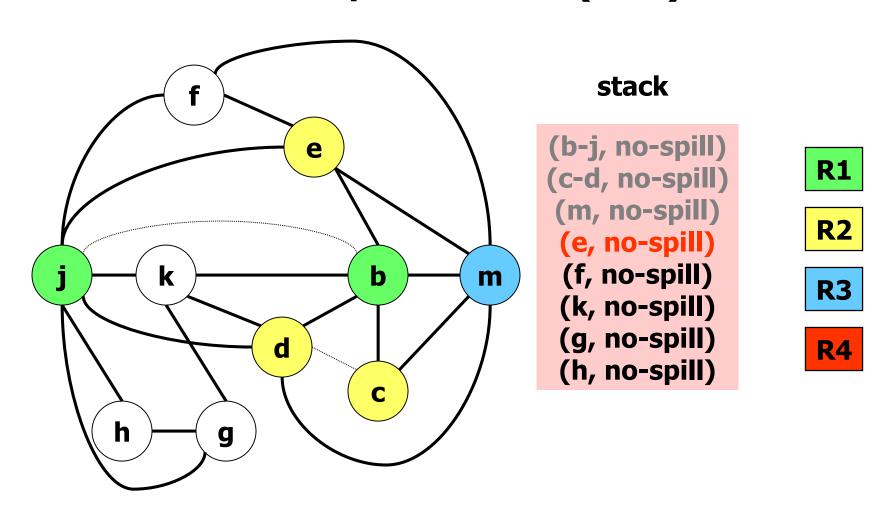


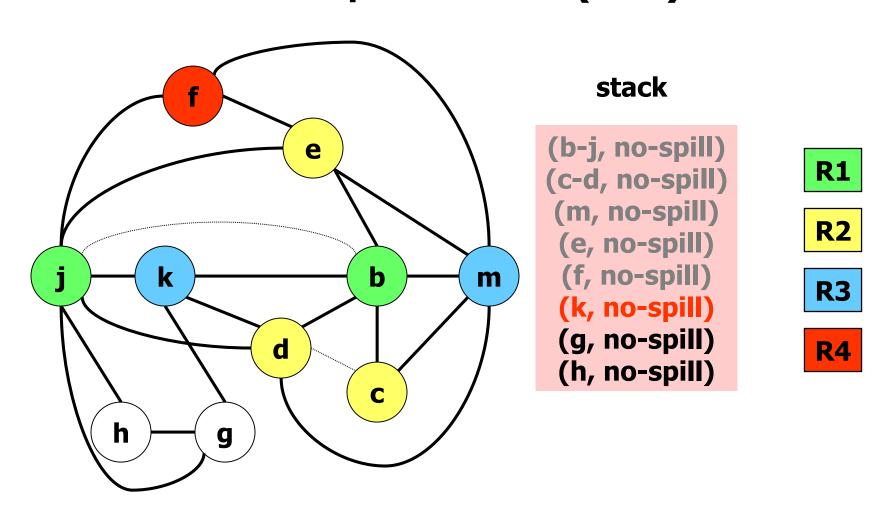
Example: Step 3: Select (K=4)

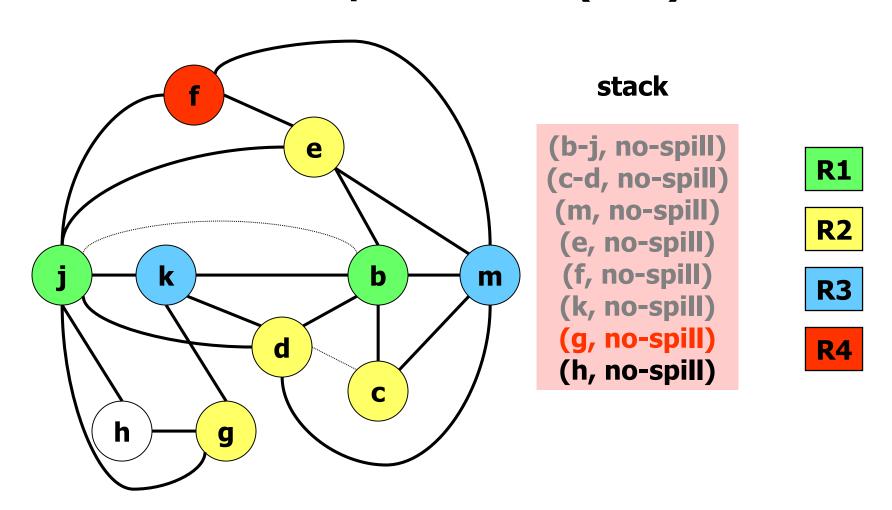


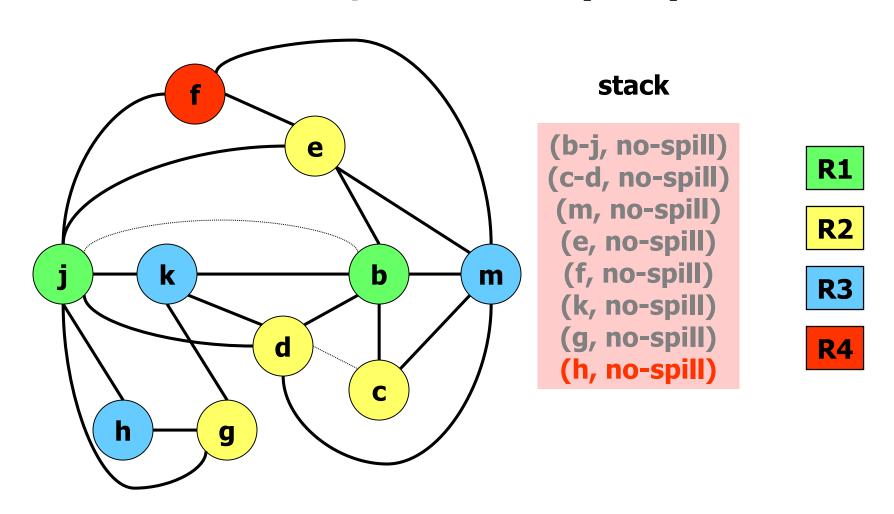






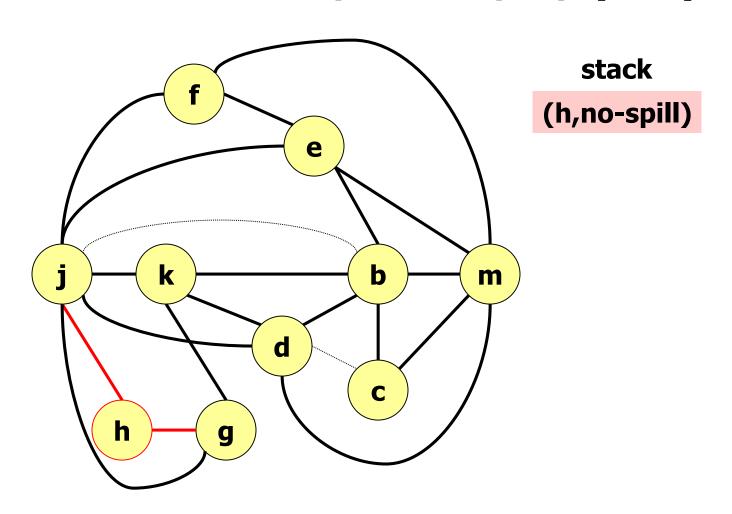




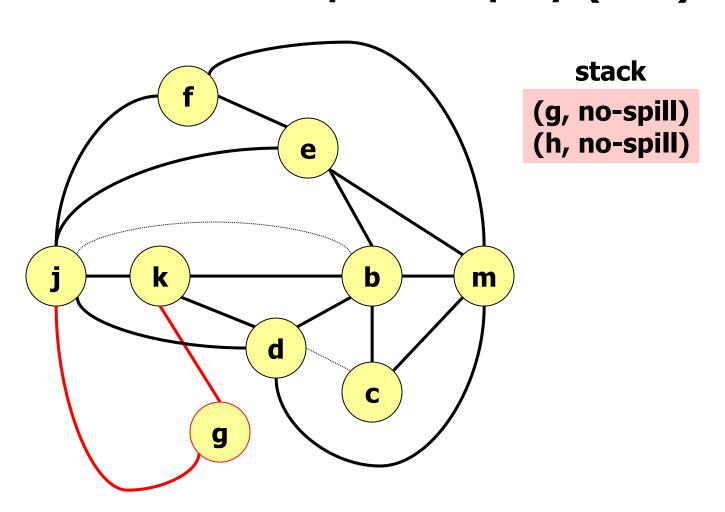


Could we do the allocation in the previous example with 3 registers?

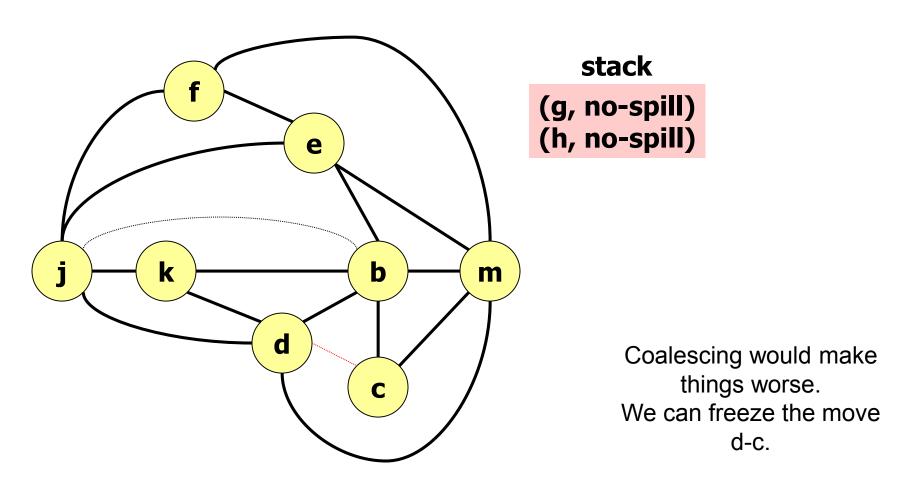
Example: Step 3: Simplify (K=3)



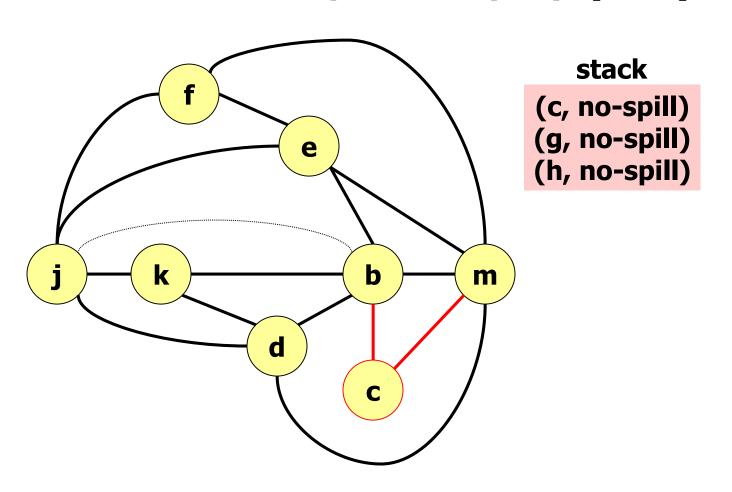
Example: Step 3: Simplify (K=3)



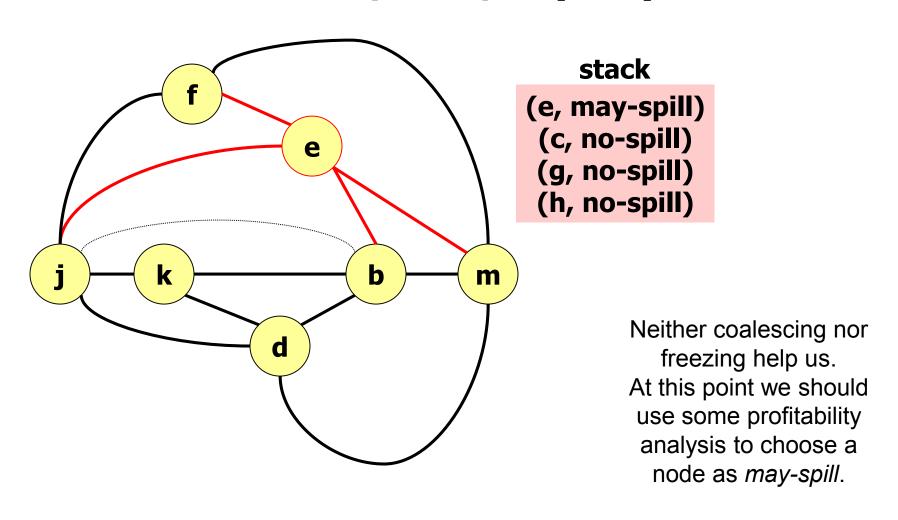
Example: Step 5: Freeze (K=3)



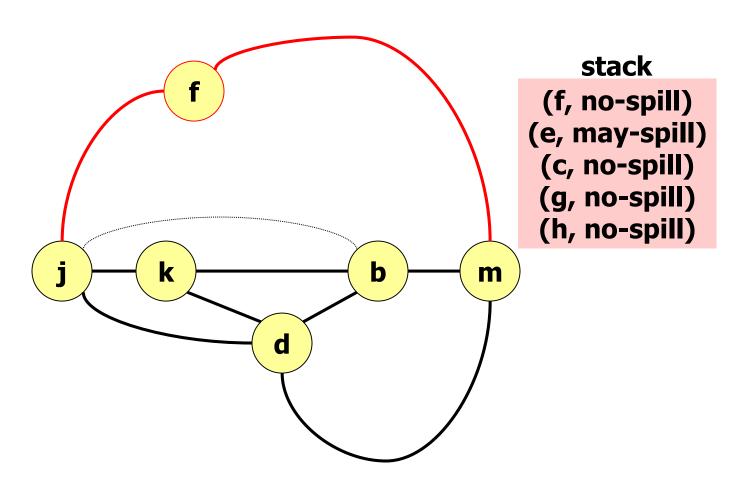
Example: Step 3: Simplify (K=3)



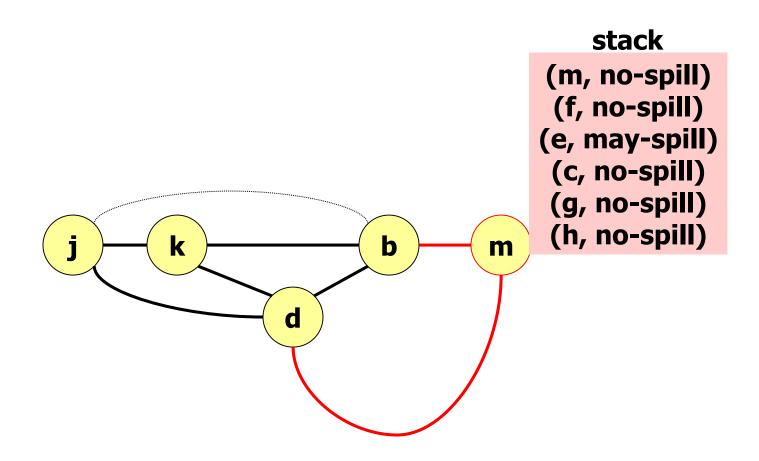
Example: Step 6: Spill (K=3)

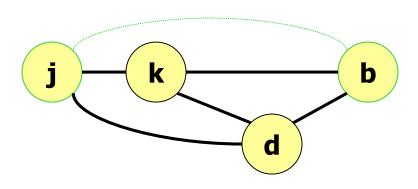


Example: Step 3: Simplify (K=3)

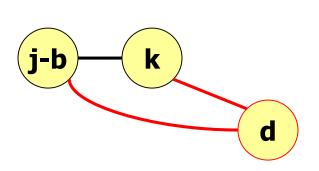


Example: Step 3: Simplify (K=3)





stack (m, no-spill) (f, no-spill) (e, may-spill) (c, no-spill) (g, no-spill) (h, no-spill)



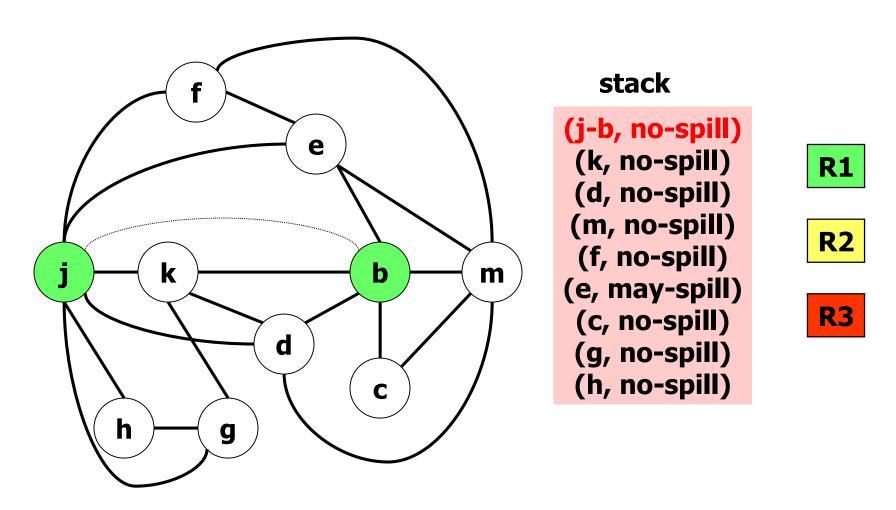
```
stack
(d, no-spill)
(m, no-spill)
(f, no-spill)
(e, may-spill)
(c, no-spill)
(g, no-spill)
(h, no-spill)
```

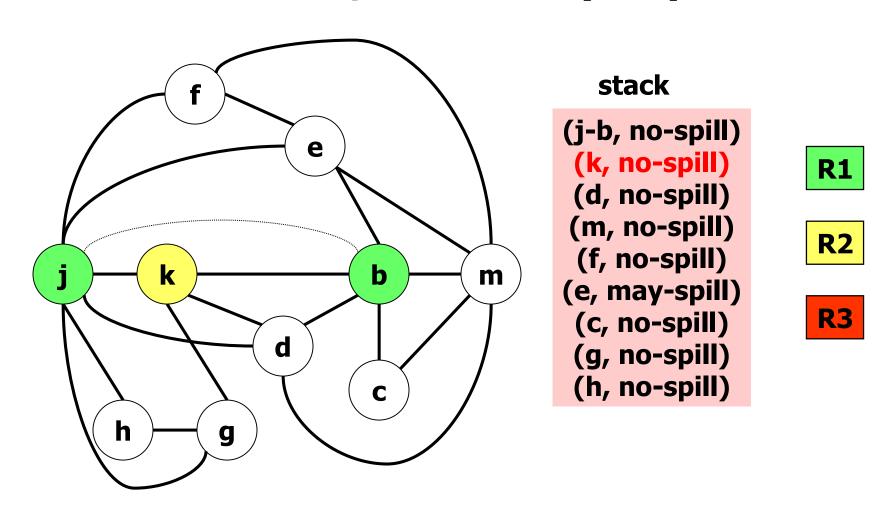
j-b k

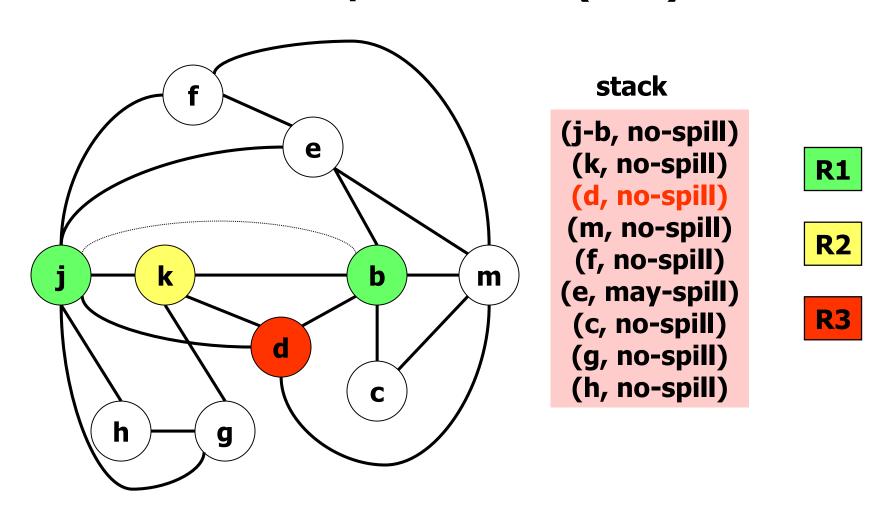
```
stack
(k, no-spill)
(d, no-spill)
(m, no-spill)
(f, no-spill)
(e, may-spill)
(c, no-spill)
(g, no-spill)
(h, no-spill)
```

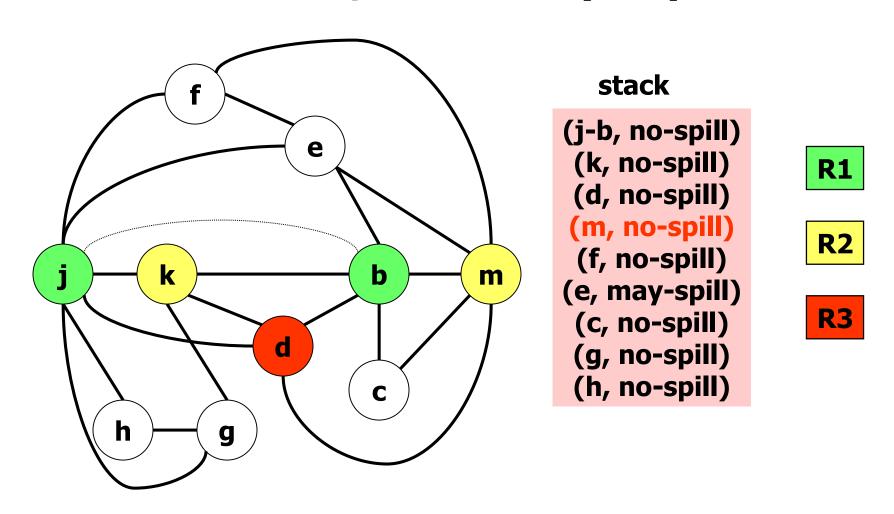
j-b

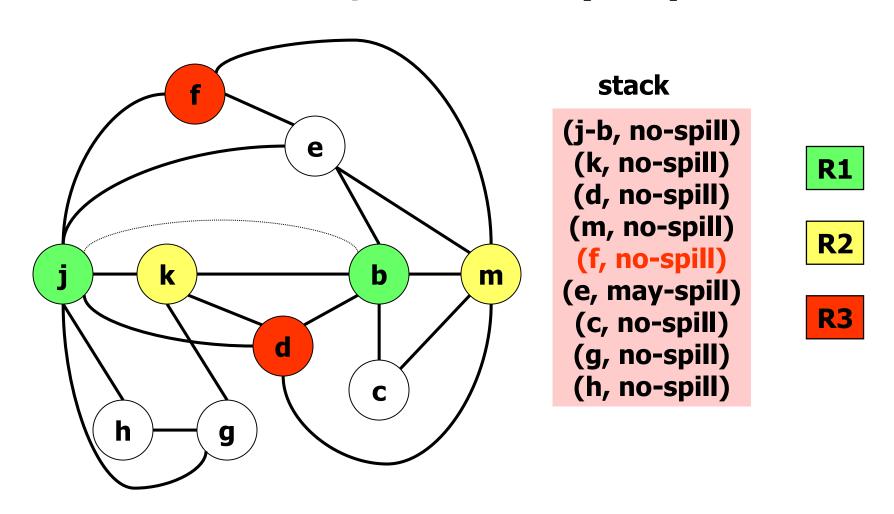
```
stack
(j-b, no-spill)
(k, no-spill)
(d, no-spill)
(m, no-spill)
(f, no-spill)
(e, may-spill)
(c, no-spill)
(g, no-spill)
(h, no-spill)
```

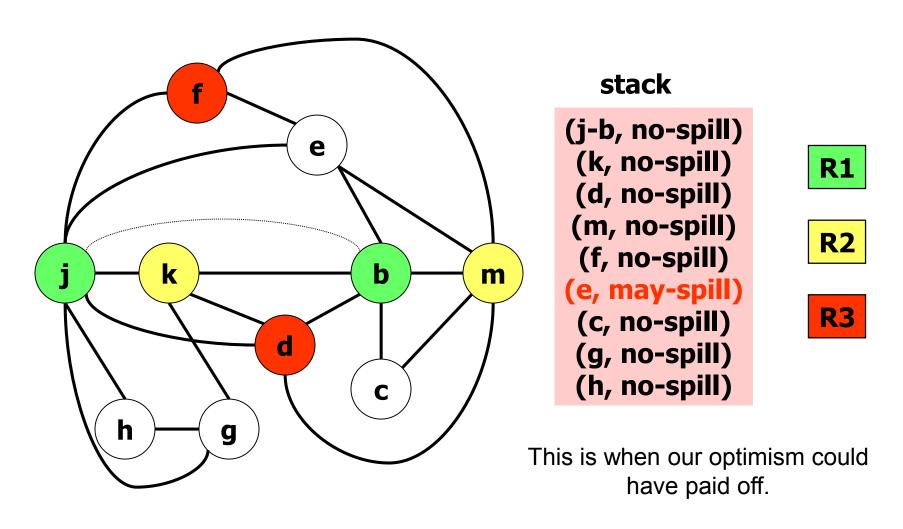


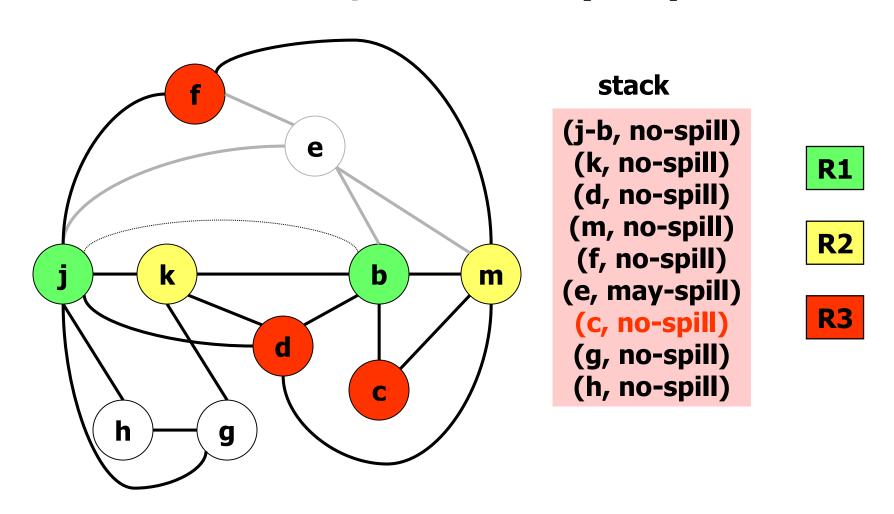


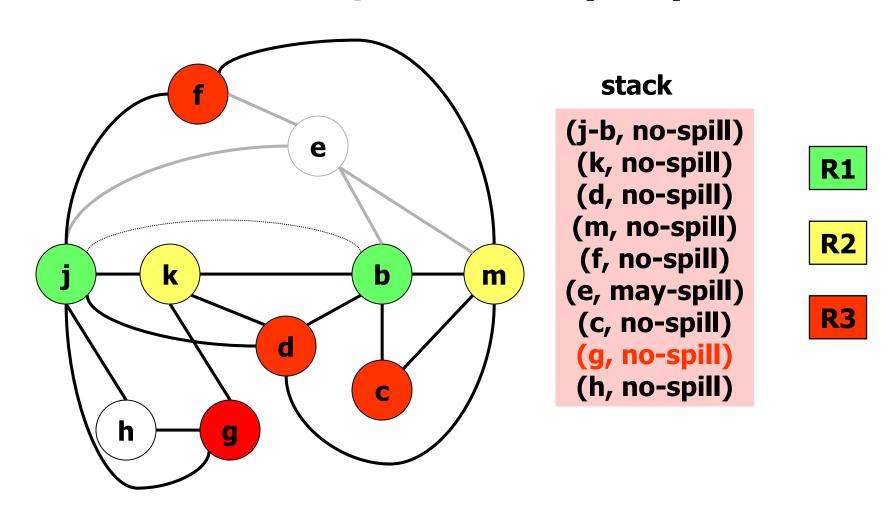


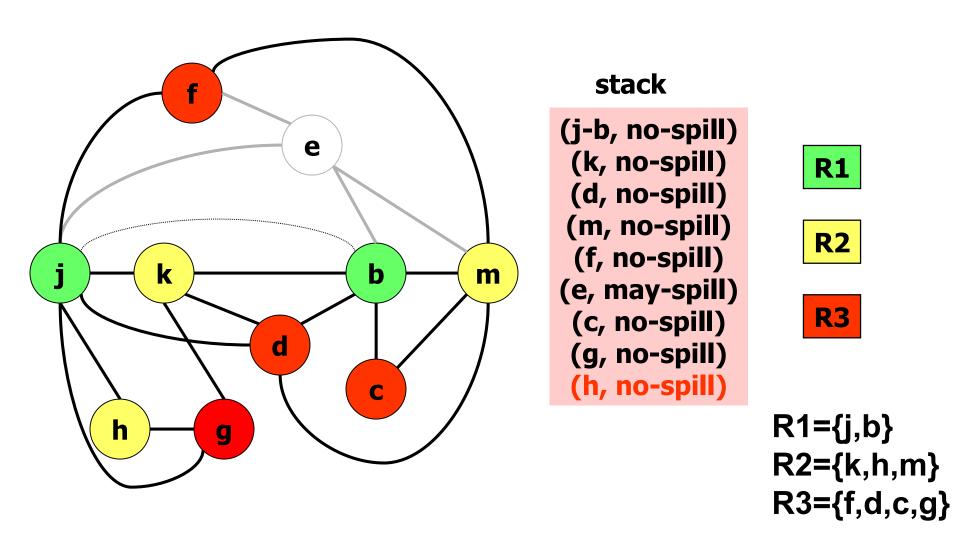


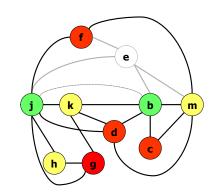










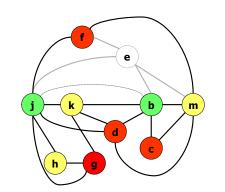


R1={j,b} R2={k,h,m} R3={f,d,c,g}

R3

```
LIVE-IN: r2(k) r1(j)
  r3 := mem[r1+12]
  r2 := r2 -1
  r3 := r3 + r2
  e := mem[r1+8] \Rightarrow t4 := mem[r1+8]; mem[$sp+4] := t4
  r2 := mem[r1+16]
  r1 := mem[r3]
  r3 := e + 8 \Rightarrow t5 := mem[$sp+4]; r3 := t5 + 8
  r3 := r3
                        A good optimizing compiler would recognize that
  r2 := r2 + 4
                        the assignment to "e" can be moved to just before
                        its use and no spilling would be needed!
  r1 := r1
```

LIVE-OUT: r3(d) r2(k) r1(j)

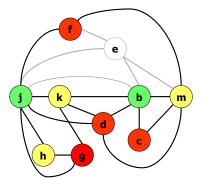


R1={j,b} R2={k,h,m} R3={f,d,c,g}

R3

```
LIVE-IN: r2(k) r1(j)
  r3 := mem[r1+12]
  r2 := r2 -1
  r3 := r3 + r2
  e := mem[r1+8] \Rightarrow t4 := mem[r1+8]; mem[$sp+4] := t4
  r2 := mem[r1+16]
  r1 := mem[r3]
  r3 := e + 8 \Rightarrow t5 := mem[\$sp+4]; r3 := t5 + 8
  r2 := r2 + 4
LIVE-OUT: r3(d) r2(k) r1(j)
```

101



R1

R2

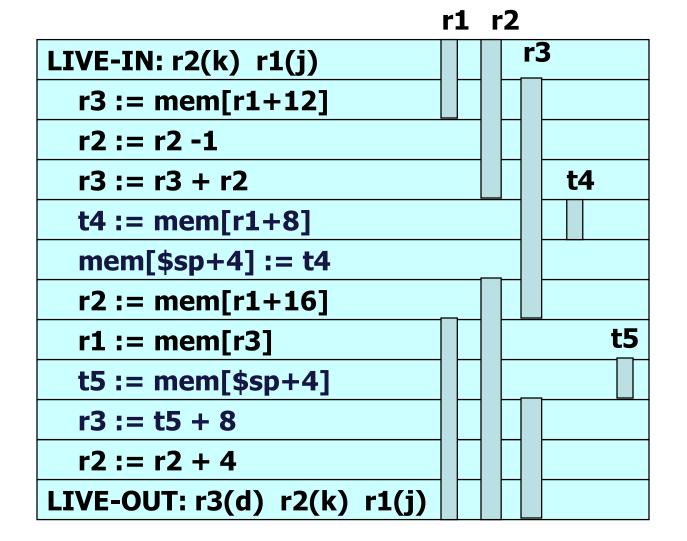
R3

```
LIVE-IN: r2(k) r1(j)
  r3 := mem[r1+12]
  r2 := r2 -1
  r3 := r3 + r2
  t4 := mem[r1+8]
  mem[$sp+4] := t4
  r2 := mem[r1+16]
  r1 := mem[r3]
  t5 := mem[\$sp+4]
  r3 := t5 + 8
  r2 := r2 + 4
LIVE-OUT: r3(d) r2(k) r1(j)
```



R2

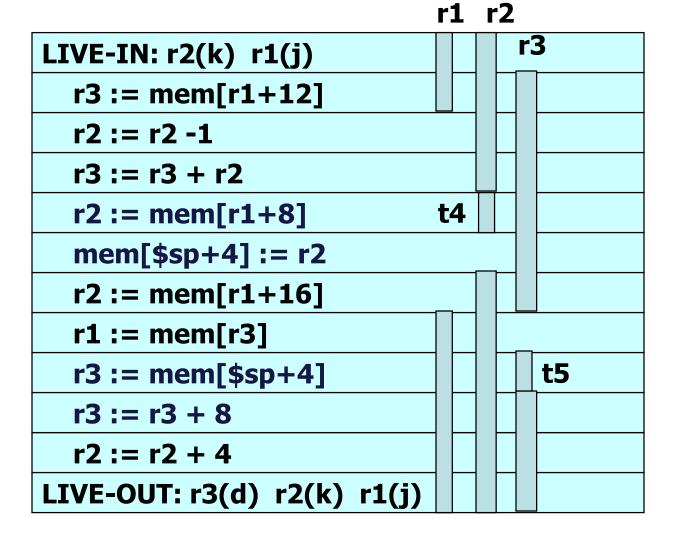
R3



R1

R2

R3



After repeating Register Allocation

. .

Live Range Splitting

- The basic coloring algorithm does not consider cases in which a variable can be allocated to a register for part of its live range
 - Some compilers split live ranges within the iteration structure of the coloring algorithm
 - When a variable is split into two new variables, one of the new variables might be profitably assigned to a register while the other is not

Length of Live Ranges

- The interference graph does not contain information of where in the CFG variables interfere and what the length of a variable's live range is
- For example, if we only had few available registers in the following intermediate-code example, the right choice would be to spill variable w because it has the longest live range:

$$x = w + 1$$
 $c = a - 2$
 $y = x * 3$
 $z = w + y$

Summary

- > Register allocation has three major parts
 - Liveness analysis
 - Graph coloring
 - Program transformation (move coalescing and spilling)
- > See chapters 11.1-11.3 in the Tiger Book (Appel)

Register Allocation: Exercise

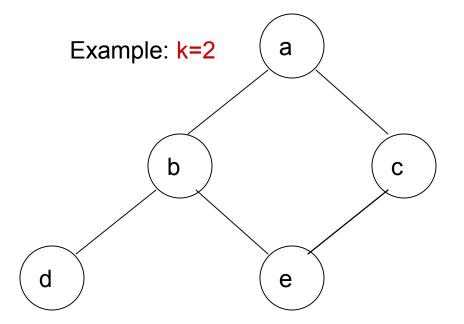
- Do register allocation for the basic block (B) of instructions shown below using graph coloring
- > Consider:
 - live-in(B) = {a,x,b,c}
 - live-out(B) = $\{y\}$
 - maximum of 4 registers

```
t1=x*x;
t2=a*t1;
t3=b*x;
t4=t3+c;
t5=t4+t2;
y=t5;
```

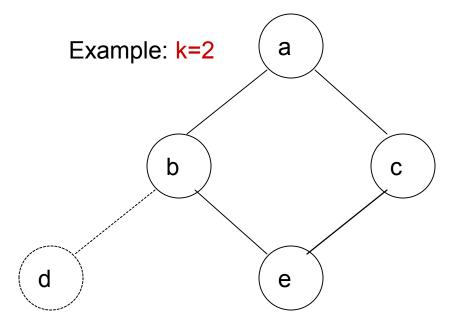
Example Showing that the graph coloring algorithm used does not find optimum colorable

REGISTER ALLOCATION

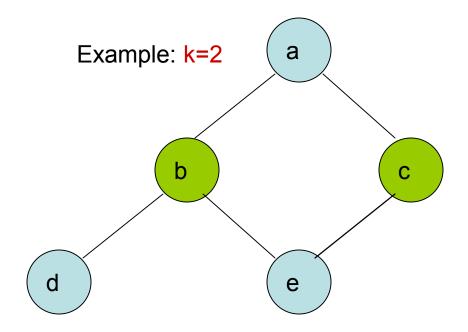
➤ If the graph cannot be colored, it will eventually be simplified to graph in which every node has at least K neighbors



➤ If the graph cannot be colored, it will eventually be simplified to graph in which every node has at least K neighbors



- ➤ If the graph cannot be colored, it will eventually be simplified to graph in which every node has at least K neighbors
- > Sometimes, the graph is still K-colorable!



- If the graph cannot be colored, it will eventually be simplified to graph in which every node has at least K neighbors
- Sometimes, the graph is still Kcolorable!
- Finding a K-coloring in all situations is an NP-complete problem
 - We have to approximate to make register allocators fast enough

