

exacthessian

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This file is part of CasADi.

CasADi -- A symbolic framework for dynamic optimization.
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1 Exact Hessian

```
[1]: from casadi import *  
     from numpy import *  
     import casadi as c
```

We will investigate the use of an exact Hessian with the help of the Rosenbrock function

```
[2]: x= SX.sym('x')  
     y= SX.sym('y')  
     obj = (1-x)**2+100*(y-x**2)**2  
     constr = x**2+y**2  
     nlp={ 'x':vertcat(x,y), 'f':obj, 'g':constr}
```

We solve the problem with an exact Hessian (default)

```
[3]: solver = nlpsol('solver', 'ipopt', nlp)
sol = solver(lbx=-10, ubx=10, lb=0, ub=1)
print('Optimal solution (exact Hessian): %s' % sol['x'])
```

```
*****
This program contains Ipopt, a library for large-scale nonlinear optimization.
Ipopt is released as open source code under the Eclipse Public License (EPL).
For more information visit https://github.com/coin-or/Ipopt
*****
```

This is Ipopt version 3.14.11, running with linear solver MUMPS 5.4.1.

```
Number of nonzeros in equality constraint Jacobian...:      0
Number of nonzeros in inequality constraint Jacobian.:      2
Number of nonzeros in Lagrangian Hessian...:           3
```

```
Total number of variables...:      2
      variables with only lower bounds:      0
      variables with lower and upper bounds:    2
      variables with only upper bounds:      0
```

```
Total number of equality constraints...:      0
Total number of inequality constraints...:      1
      inequality constraints with only lower bounds:      0
      inequality constraints with lower and upper bounds:    1
      inequality constraints with only upper bounds:      0
```

| iter | objective | inf_pr | inf_du | lg(mu) | d | lg(rg) | alpha_du | alpha_pr | ls |
|------|---------------|----------|----------|--------|----------|--------|----------|-----------|----|
| 0 | 1.0000000e+00 | 0.00e+00 | 2.00e+00 | -1.0 | 0.00e+00 | - | 0.00e+00 | 0.00e+00 | 0 |
| 1 | 6.8309610e+01 | 0.00e+00 | 4.32e+02 | -1.0 | 9.09e-01 | - | 1.36e-02 | 1.00e+00H | 1 |
| 2 | 6.2418830e+00 | 0.00e+00 | 7.25e+01 | -1.0 | 3.06e-01 | - | 6.76e-01 | 1.00e+00F | 1 |
| 3 | 6.3023184e-02 | 0.00e+00 | 5.46e-01 | -1.0 | 2.58e-01 | - | 9.97e-01 | 1.00e+00f | 1 |
| 4 | 6.5589711e-02 | 0.00e+00 | 5.27e-03 | -1.7 | 4.84e-02 | - | 1.00e+00 | 1.00e+00h | 1 |
| 5 | 5.0619847e-02 | 0.00e+00 | 3.07e-01 | -3.8 | 9.95e-02 | - | 9.05e-01 | 1.00e+00f | 1 |
| 6 | 4.6180852e-02 | 0.00e+00 | 2.45e-02 | -3.8 | 3.71e-02 | - | 1.00e+00 | 1.00e+00h | 1 |
| 7 | 4.5822797e-02 | 0.00e+00 | 1.76e-04 | -3.8 | 3.26e-03 | - | 1.00e+00 | 1.00e+00h | 1 |
| 8 | 4.5677137e-02 | 0.00e+00 | 3.59e-05 | -5.7 | 1.20e-03 | - | 1.00e+00 | 1.00e+00h | 1 |
| 9 | 4.5676652e-02 | 0.00e+00 | 3.22e-10 | -5.7 | 4.39e-06 | - | 1.00e+00 | 1.00e+00h | 1 |
| iter | objective | inf_pr | inf_du | lg(mu) | d | lg(rg) | alpha_du | alpha_pr | ls |
| 10 | 4.5674810e-02 | 0.00e+00 | 5.78e-09 | -8.6 | 1.52e-05 | - | 1.00e+00 | 1.00e+00h | 1 |

Number of Iterations...: 10

| | (scaled) | (unscaled) |
|--------------------------|------------------------|------------------------|
| Objective...: | 4.5674810088672947e-02 | 4.5674810088672947e-02 |
| Dual infeasibility...: | 5.7761012971635439e-09 | 5.7761012971635439e-09 |
| Constraint violation...: | 0.0000000000000000e+00 | 0.0000000000000000e+00 |

```

Variable bound violation:  0.0000000000000000e+00    0.0000000000000000e+00
Complementarity...:  2.5919940506206774e-09    2.5919940506206774e-09
Overall NLP error...:  5.7761012971635439e-09    5.7761012971635439e-09

```

```

Number of objective function evaluations      = 14
Number of objective gradient evaluations     = 11
Number of equality constraint evaluations     = 0
Number of inequality constraint evaluations   = 14
Number of equality constraint Jacobian evaluations = 0
Number of inequality constraint Jacobian evaluations = 11
Number of Lagrangian Hessian evaluations    = 10
Total seconds in IPOPT                      = 0.007

```

EXIT: Optimal Solution Found.

| | solver | : | t_proc | (avg) | t_wall | (avg) | n_eval |
|--|------------|---|---------|------------|---------|-----------|--------|
| | nlp_f | | 49.00us | (3.50us) | 24.30us | (1.74us) | 14 |
| | nlp_g | | 94.00us | (6.71us) | 38.90us | (2.78us) | 14 |
| | nlp_grad_f | | 46.00us | (3.83us) | 36.50us | (3.04us) | 12 |
| | nlp_hess_l | | 43.00us | (4.30us) | 20.30us | (2.03us) | 10 |
| | nlp_jac_g | | 39.00us | (3.25us) | 19.00us | (1.58us) | 12 |
| | total | | 13.74ms | (13.74ms) | 7.40ms | (7.40ms) | 1 |

Optimal solution (exact Hessian): [0.786415, 0.617698]

Same problem but with limited memory BFGS

```

[4]: solver = nlpsol('solver', 'ipopt', nlp, {'ipopt.hessian_approximation':
      ↪ 'limited-memory'})
sol = solver(lbx=-10, ubx=10, lb=0, ub=1)
print('Optimal solution (BFGS): %s' % sol['x'])

```

This is Ipopt version 3.14.11, running with linear solver MUMPS 5.4.1.

```

Number of nonzeros in equality constraint Jacobian...: 0
Number of nonzeros in inequality constraint Jacobian.: 2
Number of nonzeros in Lagrangian Hessian...: 0

```

```

Total number of variables...: 2
      variables with only lower bounds: 0
      variables with lower and upper bounds: 2
      variables with only upper bounds: 0
Total number of equality constraints...: 0
Total number of inequality constraints...: 1
      inequality constraints with only lower bounds: 0
      inequality constraints with lower and upper bounds: 1
      inequality constraints with only upper bounds: 0

```

```

iter    objective    inf_pr    inf_du lg(mu)  ||d||  lg(rg) alpha_du alpha_pr  ls

```

| | | | | | | | | | |
|------|---------------|----------|----------|--------|----------|--------|----------|-----------|----|
| 0 | 1.0000000e+00 | 0.00e+00 | 2.00e+00 | 0.0 | 0.00e+00 | - | 0.00e+00 | 0.00e+00 | 0 |
| 1 | 8.1099664e-01 | 0.00e+00 | 8.51e+00 | -5.2 | 1.67e+00 | - | 8.49e-01 | 1.24e-01f | 4 |
| 2 | 7.8913241e-01 | 0.00e+00 | 7.56e+00 | -0.7 | 3.79e-01 | - | 2.45e-01 | 1.00e+00F | 1 |
| 3 | 5.1038399e-01 | 0.00e+00 | 2.00e+00 | -1.6 | 1.47e-01 | - | 1.00e+00 | 1.00e+00h | 1 |
| 4 | 9.4636921e-01 | 0.00e+00 | 1.66e+01 | -1.7 | 2.10e-01 | - | 6.36e-01 | 1.00e+00H | 1 |
| 5 | 4.3659026e-01 | 0.00e+00 | 8.99e-01 | -2.6 | 1.70e-01 | - | 1.00e+00 | 1.00e+00f | 1 |
| 6 | 3.9428196e-01 | 0.00e+00 | 8.08e-01 | -3.2 | 5.30e-02 | - | 1.00e+00 | 1.00e+00h | 1 |
| 7 | 1.5277780e+00 | 0.00e+00 | 3.32e+01 | -4.2 | 3.31e-01 | - | 4.87e-01 | 1.00e+00H | 1 |
| 8 | 3.5006028e-01 | 0.00e+00 | 1.56e+00 | -3.3 | 5.71e-01 | - | 1.00e+00 | 1.00e+00f | 1 |
| 9 | 3.1926755e-01 | 0.00e+00 | 1.63e+00 | -3.9 | 1.60e-01 | - | 1.00e+00 | 1.00e+00h | 1 |
| iter | objective | inf_pr | inf_du | lg(mu) | d | lg(rg) | alpha_du | alpha_pr | ls |
| 10 | 2.7958742e-01 | 0.00e+00 | 4.47e+00 | -4.1 | 8.31e+00 | - | 1.00e+00 | 1.15e-02f | 4 |
| 11 | 4.1529404e-01 | 0.00e+00 | 1.74e+01 | -4.6 | 3.79e-01 | - | 7.49e-01 | 1.00e+00H | 1 |
| 12 | 1.9552435e-01 | 0.00e+00 | 7.94e+00 | -3.4 | 1.93e-01 | - | 1.00e+00 | 1.00e+00f | 1 |
| 13 | 1.0284176e-01 | 0.00e+00 | 1.20e+00 | -4.6 | 5.10e-02 | - | 1.00e+00 | 1.00e+00f | 1 |
| 14 | 7.9168874e-02 | 0.00e+00 | 1.74e+00 | -6.0 | 1.24e-01 | - | 1.00e+00 | 1.00e+00f | 1 |
| 15 | 6.4711554e-02 | 0.00e+00 | 3.50e+00 | -7.3 | 1.52e-01 | - | 1.00e+00 | 1.00e+00h | 1 |
| 16 | 5.5234143e-02 | 4.93e-03 | 3.01e+00 | -4.6 | 1.34e-01 | - | 1.00e+00 | 3.44e-01h | 1 |
| 17 | 4.7148548e-02 | 0.00e+00 | 9.32e-01 | -4.3 | 7.45e-03 | - | 1.00e+00 | 1.00e+00h | 1 |
| 18 | 4.5698648e-02 | 0.00e+00 | 1.46e-01 | -6.0 | 6.27e-03 | - | 1.00e+00 | 8.55e-01h | 1 |
| 19 | 4.5674859e-02 | 0.00e+00 | 1.07e-03 | -6.7 | 1.78e-04 | - | 1.00e+00 | 9.95e-01h | 1 |
| iter | objective | inf_pr | inf_du | lg(mu) | d | lg(rg) | alpha_du | alpha_pr | ls |
| 20 | 4.5674809e-02 | 0.00e+00 | 1.79e-07 | -8.8 | 1.52e-06 | - | 1.00e+00 | 1.00e+00h | 1 |
| 21 | 4.5674808e-02 | 0.00e+00 | 2.24e-09 | -11.0 | 1.39e-08 | - | 1.00e+00 | 1.00e+00h | 1 |

Number of Iterations...: 21

| | (scaled) | (unscaled) |
|---------------------------|------------------------|------------------------|
| Objective...: | 4.5674807514535586e-02 | 4.5674807514535586e-02 |
| Dual infeasibility...: | 2.2446746822391006e-09 | 2.2446746822391006e-09 |
| Constraint violation...: | 0.0000000000000000e+00 | 0.0000000000000000e+00 |
| Variable bound violation: | 0.0000000000000000e+00 | 0.0000000000000000e+00 |
| Complementarity...: | 1.0000913016783289e-11 | 1.0000913016783289e-11 |
| Overall NLP error...: | 2.2446746822391006e-09 | 2.2446746822391006e-09 |

| | |
|--|---------|
| Number of objective function evaluations | = 36 |
| Number of objective gradient evaluations | = 22 |
| Number of equality constraint evaluations | = 0 |
| Number of inequality constraint evaluations | = 36 |
| Number of equality constraint Jacobian evaluations | = 0 |
| Number of inequality constraint Jacobian evaluations | = 22 |
| Number of Lagrangian Hessian evaluations | = 0 |
| Total seconds in IPOPT | = 0.039 |

EXIT: Optimal Solution Found.

| solver | t_proc | (avg) | t_wall | (avg) | n_eval |
|--------|----------|-----------|---------|-----------|--------|
| nlp_f | 104.00us | (2.89us) | 51.60us | (1.43us) | 36 |

| | | | | | | |
|------------|--|----------|------------|---------|------------|----|
| nlp_g | | 264.00us | (7.33us) | 96.00us | (2.67us) | 36 |
| nlp_grad_f | | 97.00us | (4.22us) | 44.30us | (1.93us) | 23 |
| nlp_jac_g | | 68.00us | (2.96us) | 34.00us | (1.48us) | 23 |
| total | | 79.01ms | (79.01ms) | 39.61ms | (39.61ms) | 1 |

Optimal solution (BFGS): [0.786415, 0.617698]