

# Who are we?

Joel Andersson

FMIOPT AS, Norway  
joel@fmiopt.com



Joris Gillis

Yacoda BV, Belgium  
joris@yacoda.com



Consulting

Teaching

FMI & Modelica

Pharmacology

HVAC

Trains, Boats

Diagnostics

Motorsport

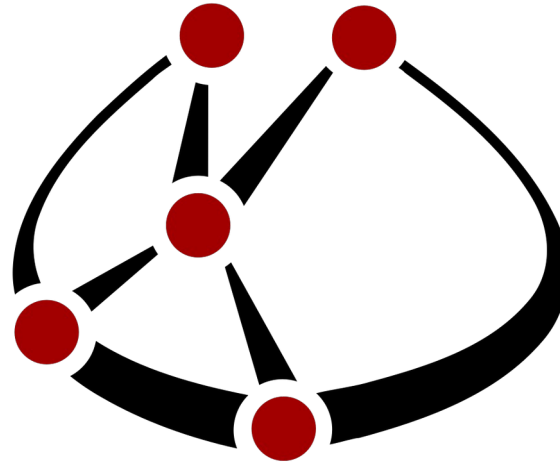
Delays

Radiotherapy

Wind energy

Abstractions

# What is CasADi?



# CasADi

“Define system”



“Define problem based on system”



“Solve/deploy problem”

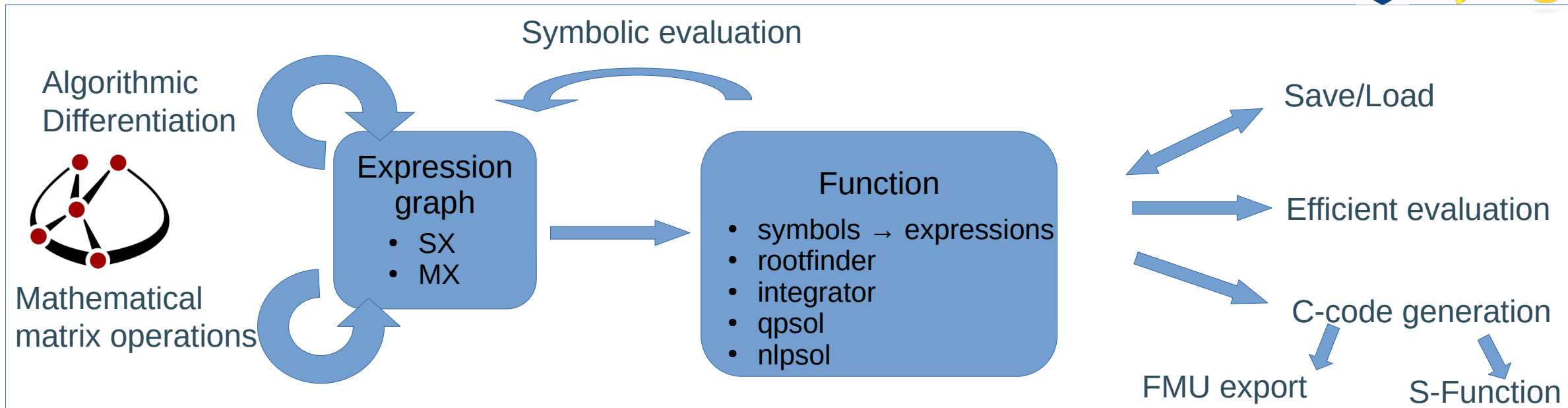
static/kinematic/dynamic

Initial value problem

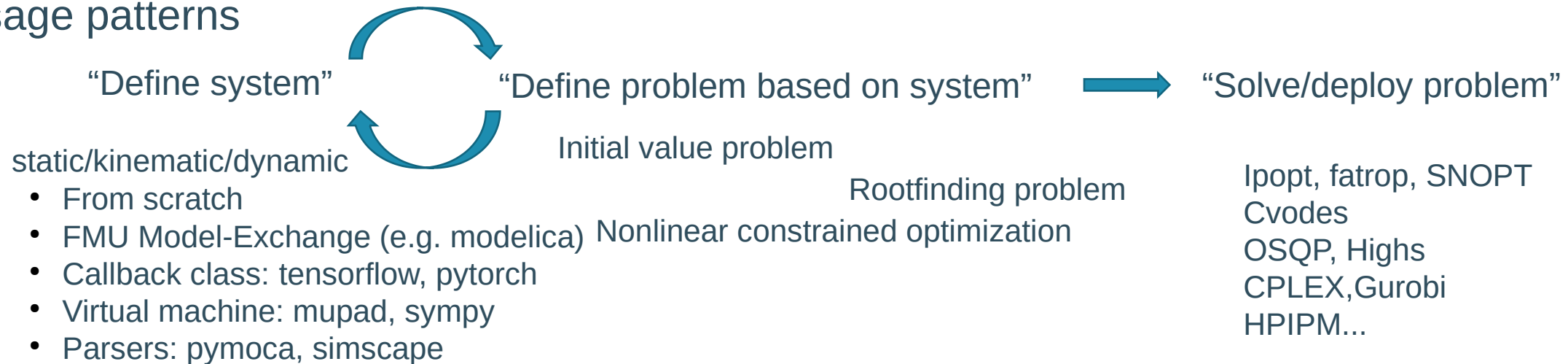
Rootfinding problem

Nonlinear constrained optimization

Ipopt, fatrop, SNOPT  
Cvodes  
OSQP, Highs  
CPLEX, Gurobi  
HPIPM...



## Usage patterns



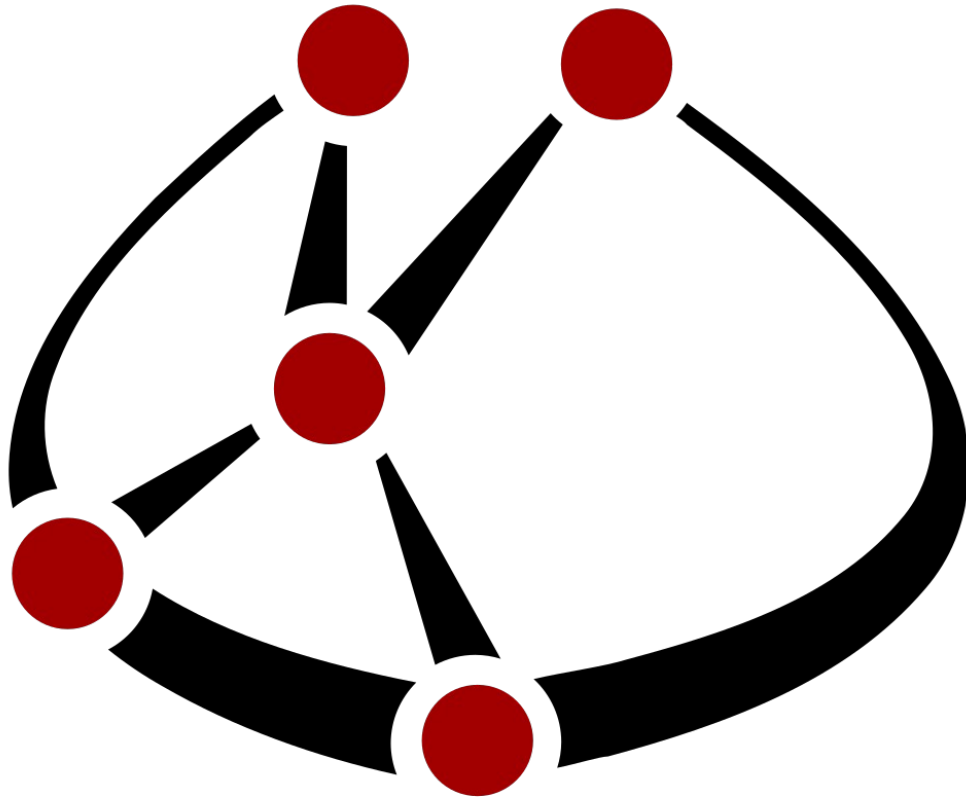
## Aim

Support mathematical engineering

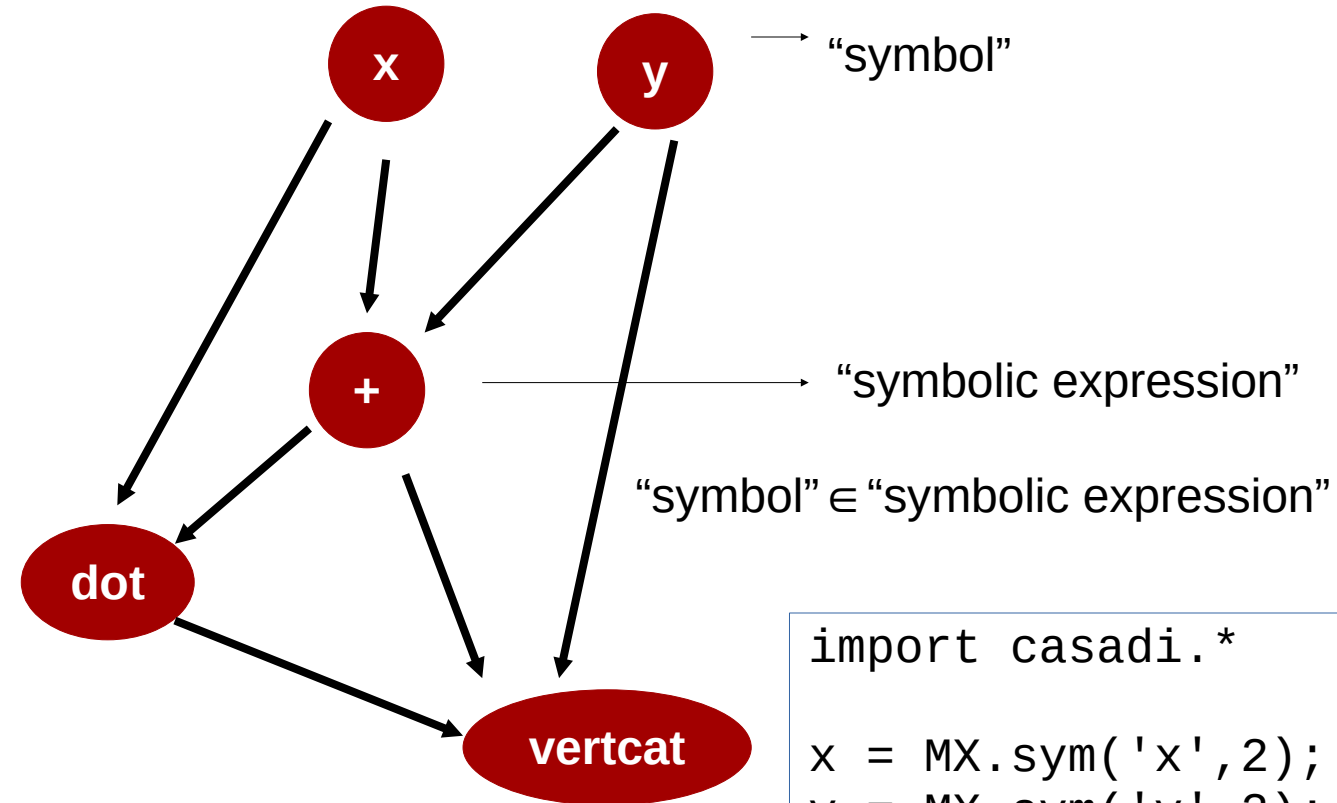
Open-Source

Foundation to build upon

## Syntax: symbolic expressions



# CasADi



```
import casadi.*
```

```
x = MX.sym('x',2);  
y = MX.sym('y',2);
```

```
w1 = x+y;  
w2 = dot(x,w1);  
w3 = [y;w1;w2];  
size(w3)
```

```
5 1
```

# Syntax: Functions

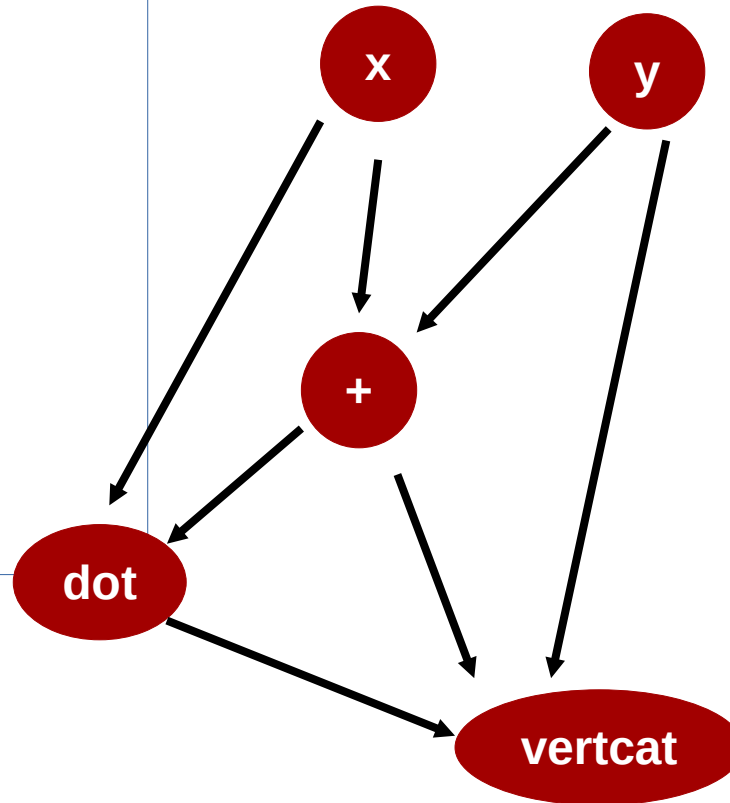
```
F = Function('f',{x,y},{w3},{ 'x','y'},{ 'z'});  
f:(x[2],y[2])-(z[5]) MXFunction
```

```
F([1,2],[3,4])  
[3, 4, 4, 6, 16]
```

```
F.generate('F.c')
```

```
F('y',[3,4],'x',[1,2])  
struct with fields:
```

```
z: [5×1 casadi.DM]
```



```
import casadi.*
```

```
x = MX.sym('x',2);  
y = MX.sym('y',2);
```

```
w1 = x+y;  
w2 = dot(x,w1);  
w3 = [y;w1;w2];  
size(w3)
```

```
5 1
```

# Syntax: algorithmic differentiation and sparsity

```
F = Function('f', {x,y}, {w3}, {'x','y'}, {'z'});
```

```
class(w3)
'casadi.MX'

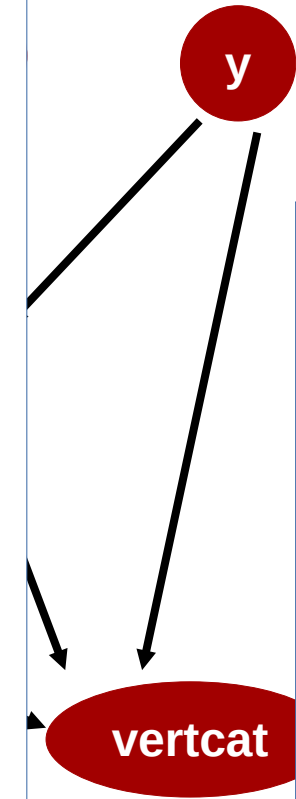
J = jacobian(w3,y);
class(J)
'casadi.MX'

spy(sparsity(J))
*
.
*
.
*
.
*
.
**

Fd = Function('Fd', {x,y}, {w3,J});
Fd:(i0[2],i1[2])->(o0[5],o1[5x2,6nz]) MXFunction

Fd = F.factory('Fd',{'x','y'},{'z','jac:z:y'});
Fd:(x[2],y[2])->(z[5],jac_z_y[5x2,6nz]) MXFunction

[A,B] = Fd([1 2],[3 4])
```



```
class(A)
'casadi.DM'
class(B)
'casadi.DM'
```

B  
B =

```
[[1, 00],
 [00, 1],
 [1, 00],
 [00, 1],
 [1, 2]]
```

full(A)  
sparse(B)