Who are we?

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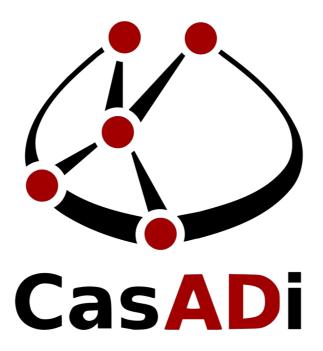
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FMI & Modelica		Consulting	Teaching	
		HVAC	Pharmacology	
Diagnostics	Motorsport		Trains, Boats	
Radiotherapy		Wind energy	Abstractions	Delays

What is CasADi?



"Define system"



"Define problem based on system"



"Solve/deploy problem"

static/kinematic/dynamic

Initial value problem

Rootfinding problem Nonlinear constrained optimization

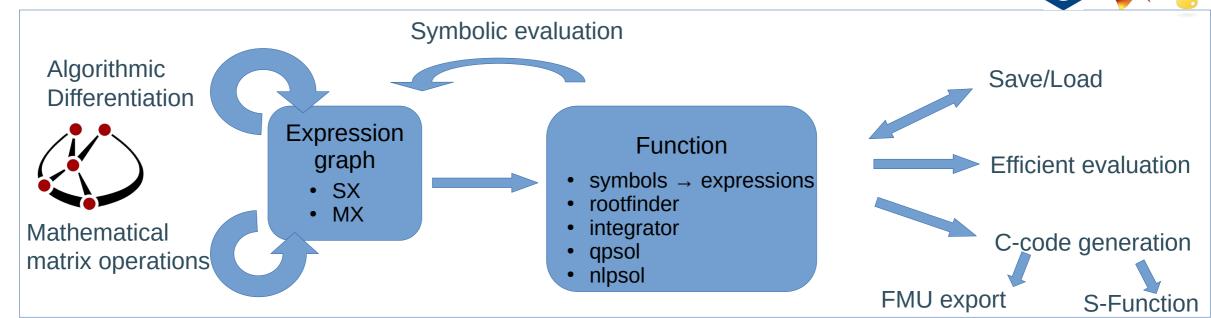
Ipopt, fatrop, SNOPT Cvodes OSQP, Highs CPLEX,Gurobi HPIPM... Capabilities

Win, Linux, Mac









Usage patterns

"Define system"

"Define problem based on system"



"Solve/deploy problem"

Ipopt, fatrop, SNOPT

Initial value problem static/kinematic/dynamic

From scratch

FMU Model-Exchange (e.g. modelica) Nonlinear constrained optimization

Callback class: tensorflow, pytorch

Virtual machine: mupad, sympy

Parsers: pymoca, simscape

Rootfinding problem

Cvodes OSQP, Highs

CPLEX, Gurobi

HPIPM...

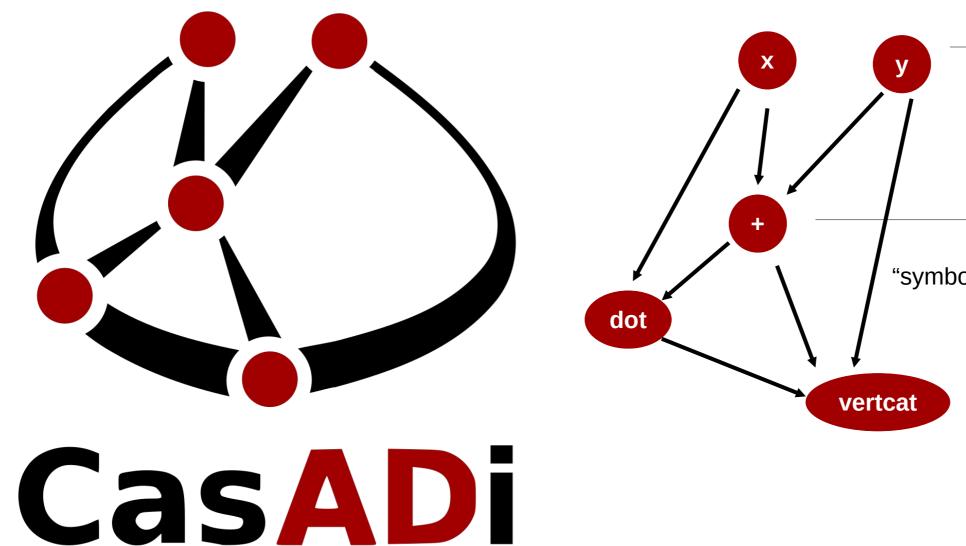
Aim

Support mathematical engineering

Open-Source

Foundation to build upon

Syntax: symbolic expressions



"symbolic expression" "symbol" ∈ "symbolic expression" import casadi.* x = MX.sym('x',2);y = MX.sym('y', 2);

"symbol"

w1 = x+y;

size(w3)

w2 = dot(x, w1);

w3 = [y; w1; w2];

Syntax: Functions

```
F = Function('f', \{x,y\}, \{w3\}, \{'x', 'y'\}, \{'z'\});
f:(x[2],y[2])->(z[5]) MXFunction
F([1,2],[3,4])
[3, 4, 4, 6, 16]
F.generate('F.c')
F('y',[3,4],'x',[1,2])
  struct with fields:
    z: [5×1 casadi.DM]
                                               dot
```

```
import casadi.*

x = MX.sym('x',2);
y = MX.sym('y',2);

w1 = x+y;
w2 = dot(x,w1);
w3 = [y;w1;w2];
size(w3)
5 1
```

vertcat

Syntax: algorithmic differentiation and sparsity

```
F = Function('f', \{x,y\}, \{w3\}, \{'x', 'y'\}, \{'z'\});
class(w3)
'casadi.MX'
J = jacobian(w3, y);
class(J)
'casadi.MX'
                                                                      class(A)
                                                                       'casadi.DM'
spy(sparsity(J))
                                                                      class(B)
                                                                       'casadi.DM'
                                                                      В
Fd = Function('Fd', \{x,y\}, \{w3,J\});
                                                                      [[1, 00],
                                                               vertcat
Fd:(i0[2],i1[2])->(o0[5],o1[5x2,6nz]) MXFunction
                                                                        [00, 1],
                                                                        [1, 00],
Fd = F.factory('Fd', {'x', 'y'}, {'z', 'jac:z:y'});
                                                                        [00, 1],
Fd:(x[2],y[2])->(z[5],jac_z_y[5x2,6nz]) MXFunction
                                                                        [1, 2]]
[A,B] = Fd([1 2],[3 4])
                                                                      full(A)
                                                                       sparse(B)
```