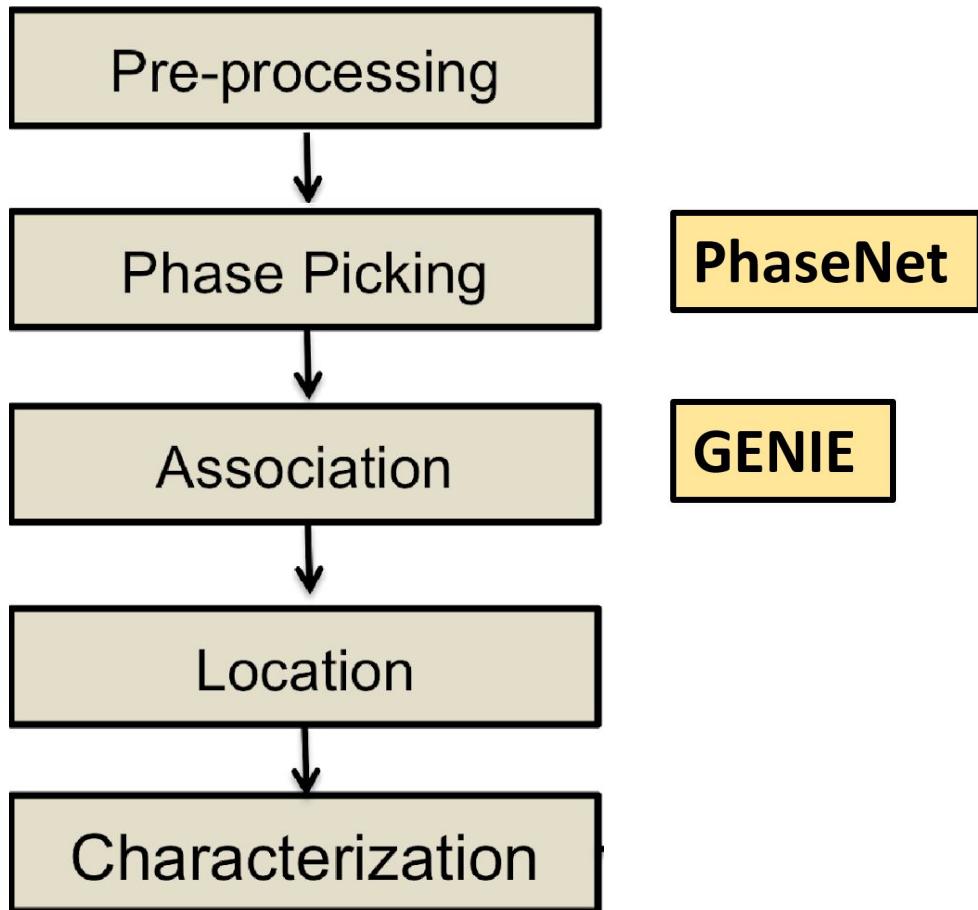
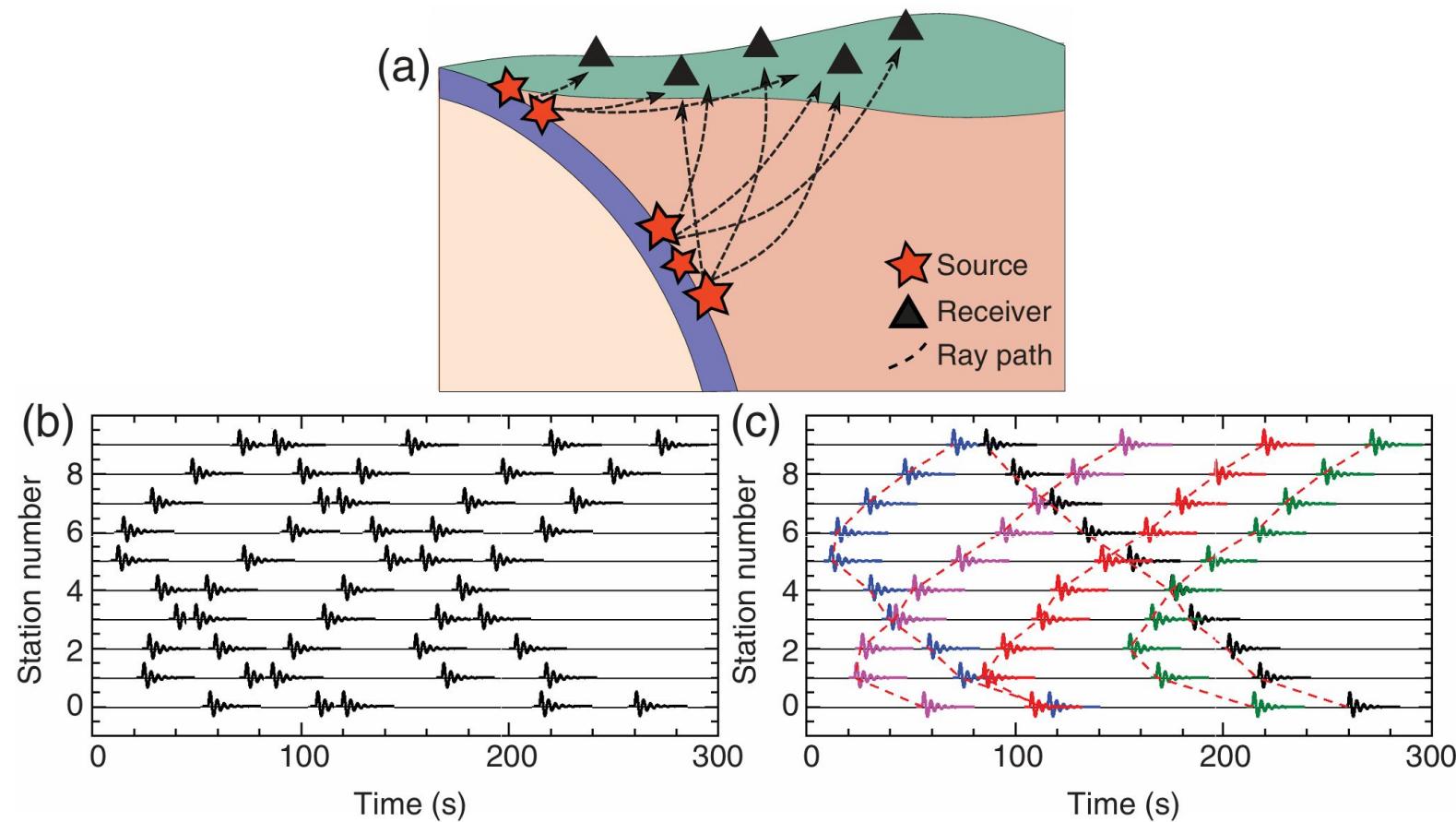


Earthquake Phase Association

Seismic Event Monitoring Workflow: From Continuous Waveforms to Catalogs



Association



“Associate” picks – (i.e., determine number of events and distinct assignments)

Location

Then use **associated picks** in a least squares optimization routine to find best fit location

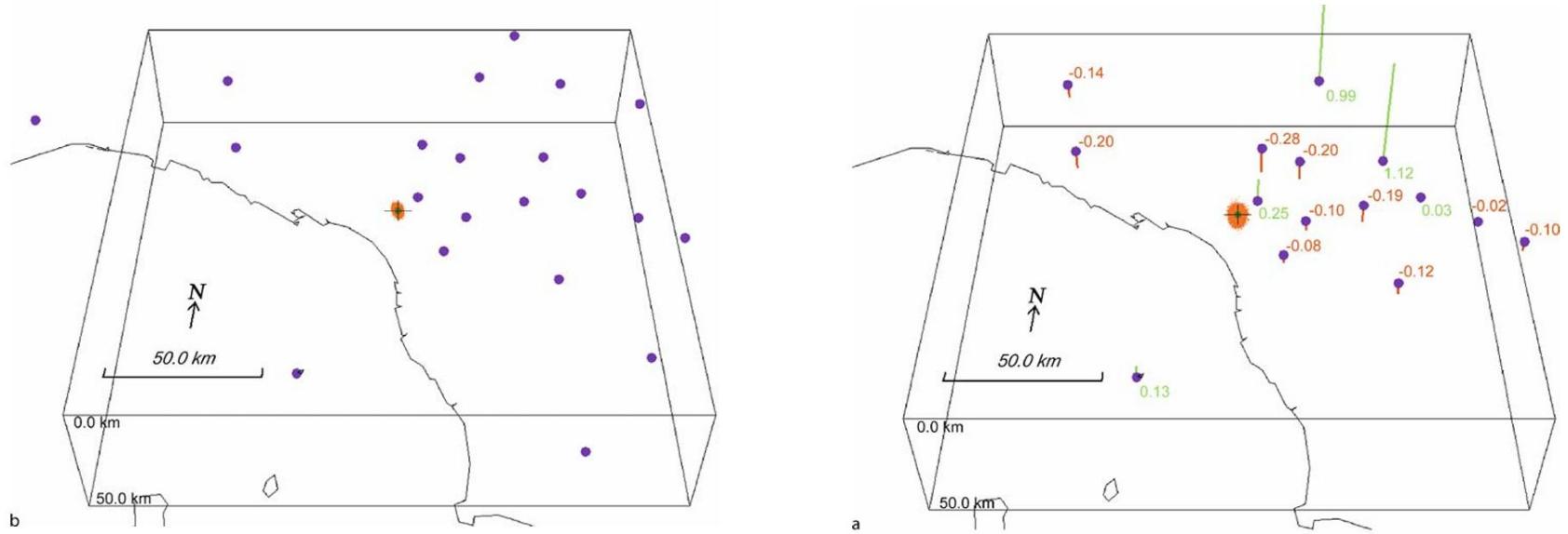
Posterior

$$\theta(\mathbf{X}) \propto \exp\left(-\frac{(\bar{T}_i^r(\mathbf{X}) - \bar{\tau}_i^r)^T C_{cov}^{-1} (\bar{T}_i^r(\mathbf{X}) - \bar{\tau}_i^r)}{2}\right)$$

$\bar{T}_i^r(\mathbf{X})$: travel time calculator
 $\bar{\tau}_i^r$: arrival time

Location

Then use **associated picks** in a least squares optimization routine to find best fit location



Posterior

$$\theta(\mathbf{X}) \propto \exp\left(-\frac{(\bar{T}_i^r(\mathbf{X}) - \bar{\tau}_i^r)^T C_{cov}^{-1} (\bar{T}_i^r(\mathbf{X}) - \bar{\tau}_i^r)}{2}\right)$$

$\bar{T}_i^r(\mathbf{X})$: travel time calculator

$\bar{\tau}_i^r$: arrival time

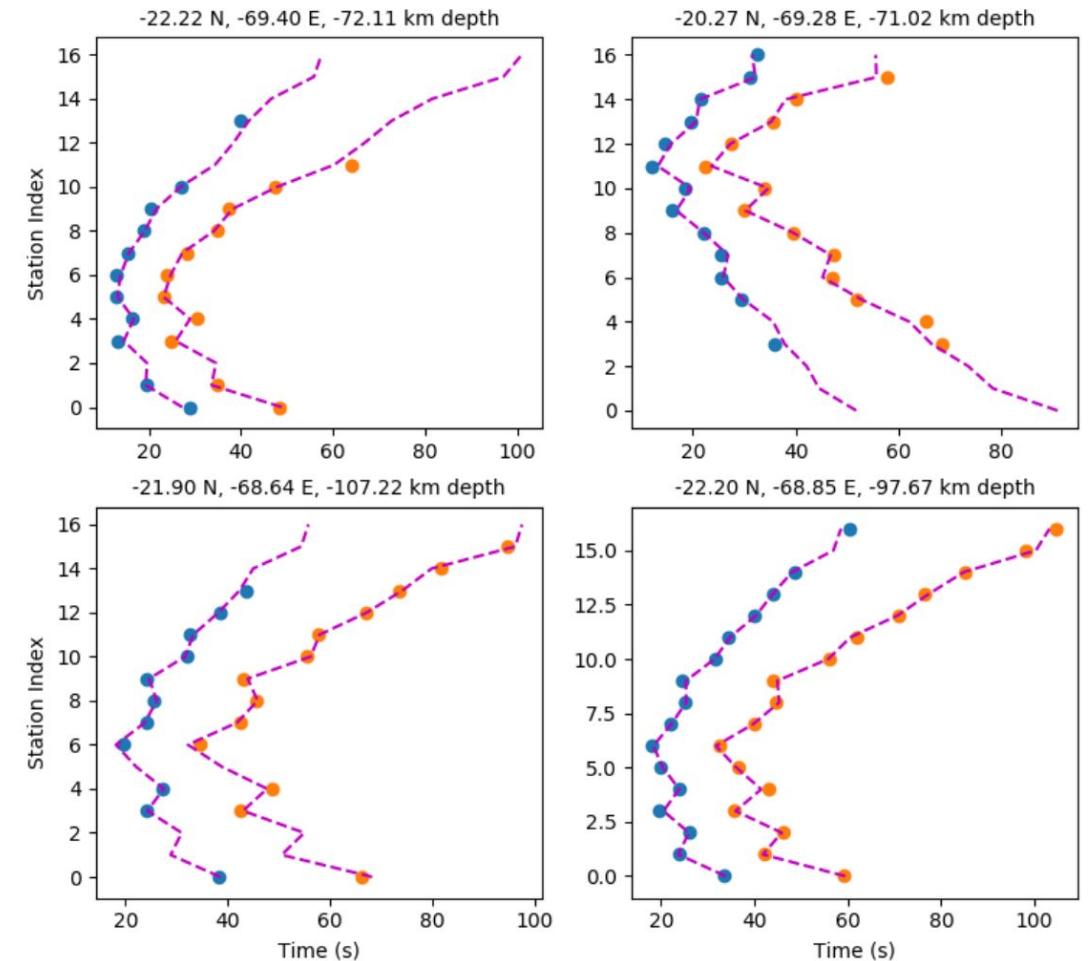
Lomax et al.,
2008

Location

Then use **associated picks** in a least squares optimization routine to find best fit location

Posterior

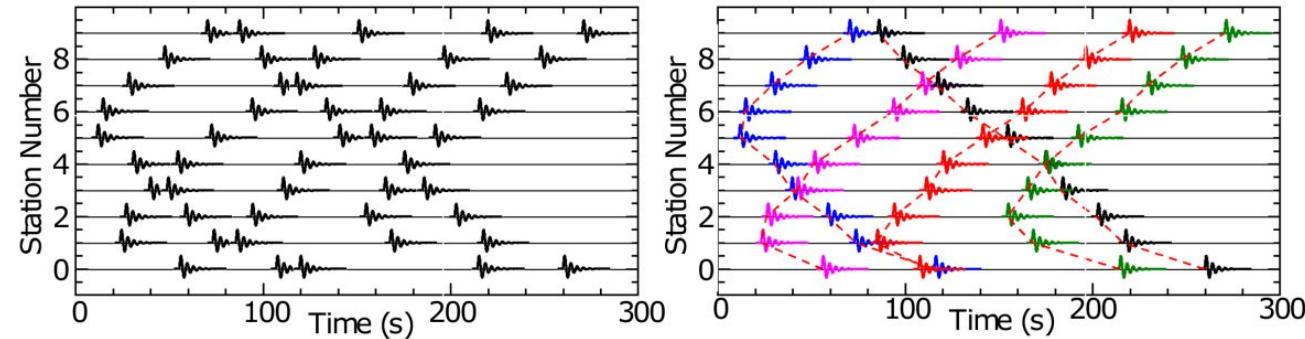
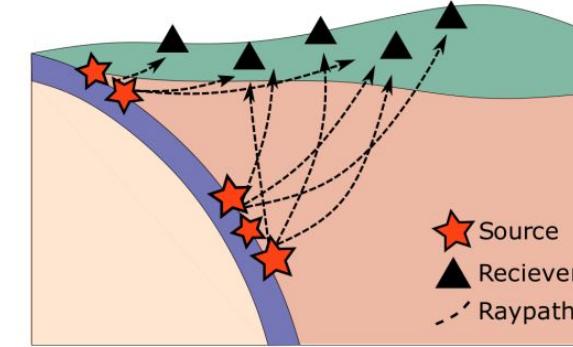
$$\theta(\mathbf{X}) \propto \exp\left(-\frac{(\bar{T}_i^r(\mathbf{X}) - \bar{\tau}_i^r)^T C_{cov}^{-1} (\bar{T}_i^r(\mathbf{X}) - \bar{\tau}_i^r)}{2}\right)$$



Phase Association connects waves with earthquakes.

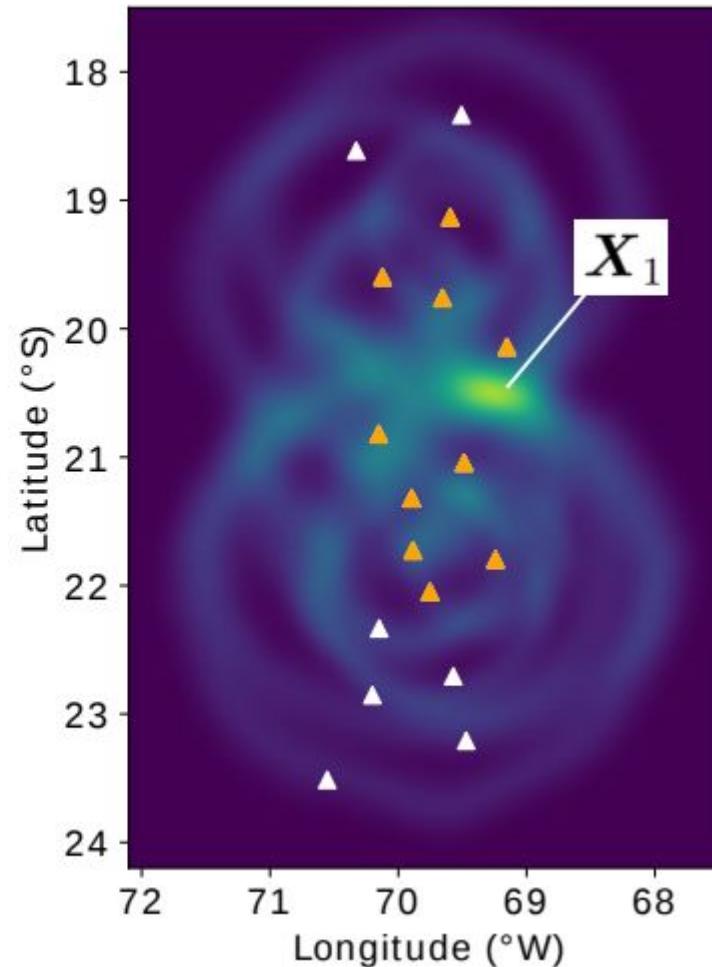
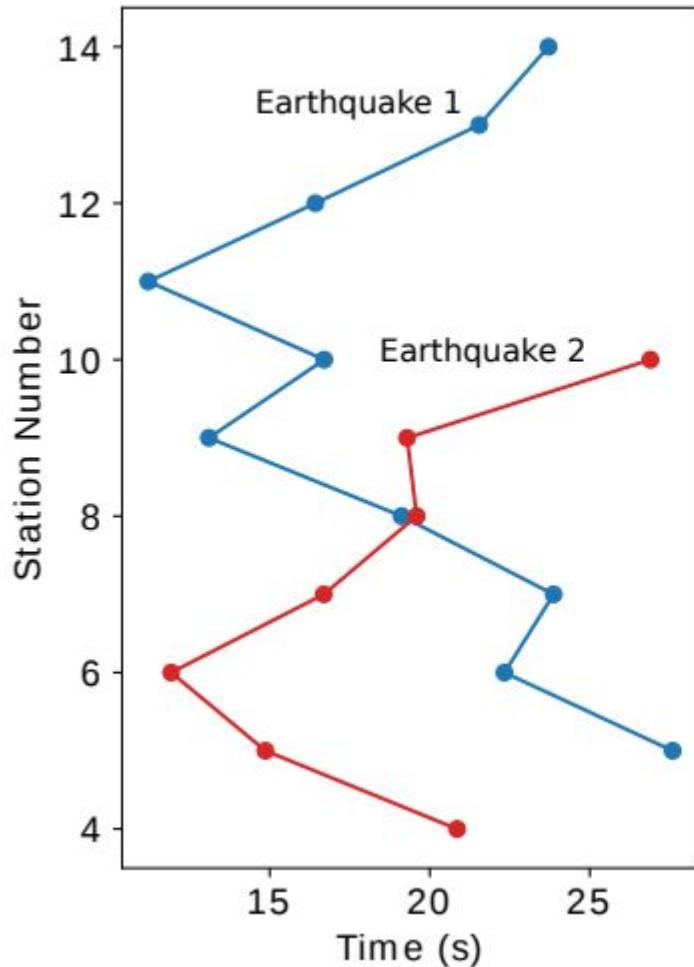
Why is it challenging?

- Number of earthquakes is unknown
- Events close in time have overlapping waveforms
- Recording network is irregular and varies with time
- Small earthquakes are only recorded on a few stations



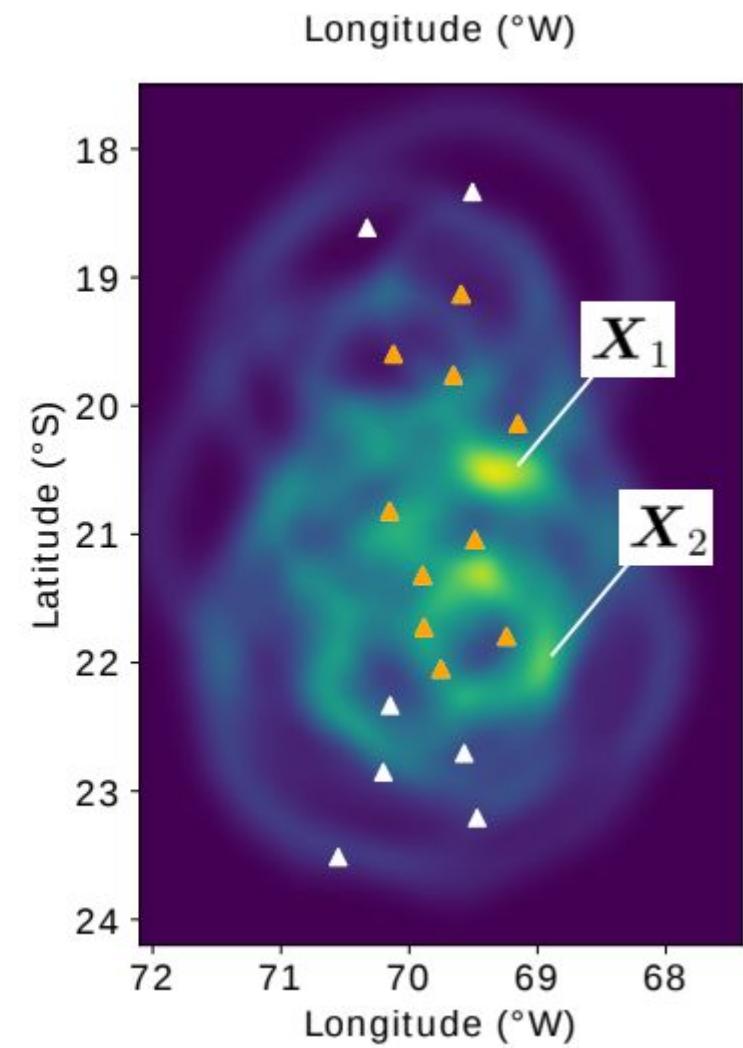
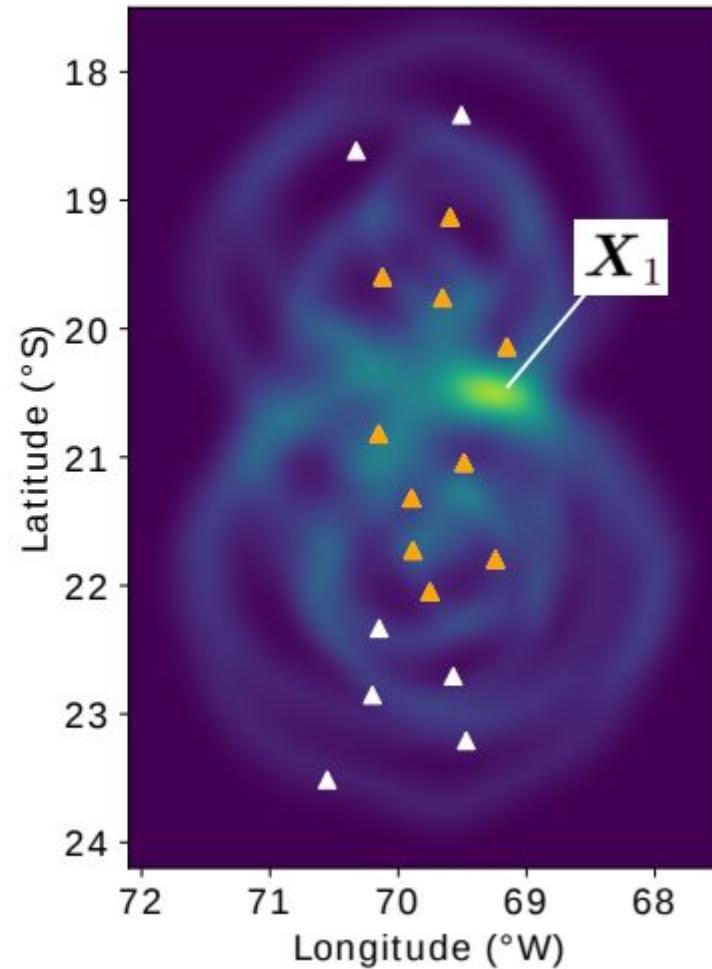
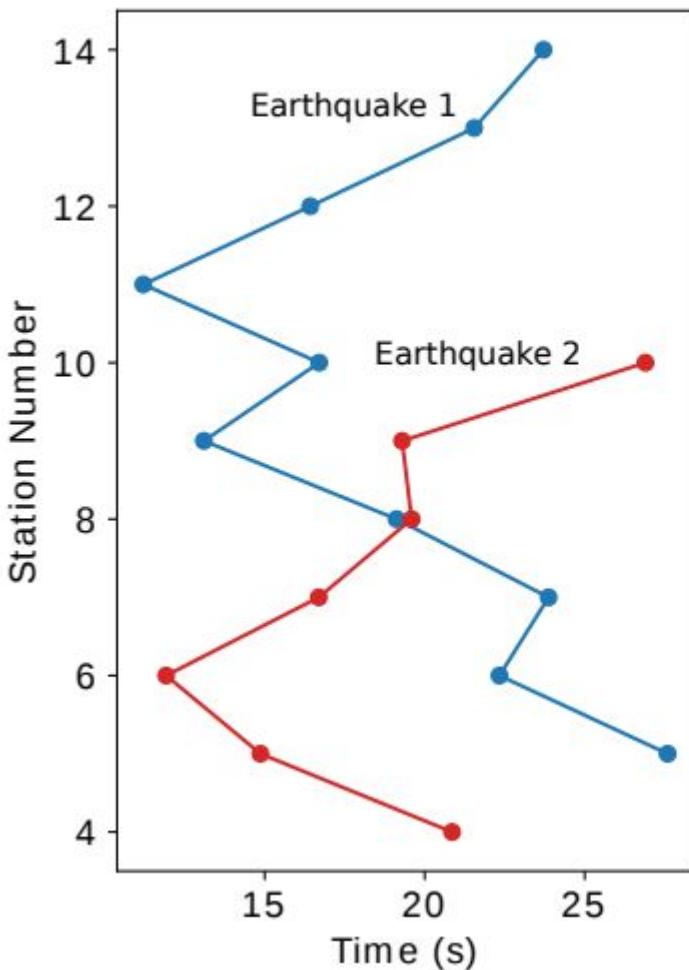
ML-based picks differ from traditional picks, which motivates another look at.

Ambiguity of Phase Association



Backprojection: Time reverse picks and stack over stations (e.g., find moveout that fits observed picks)

Ambiguity of Phase Association



Backprojection: Time reverse picks and stack over stations (e.g., find moveout that fits observed picks)

Brief History

Brief History

1930

FRODE RINGDAL AND TORMOD KVÆRNA

Ringdall and
Kværna
(1989)

Initial beam grid

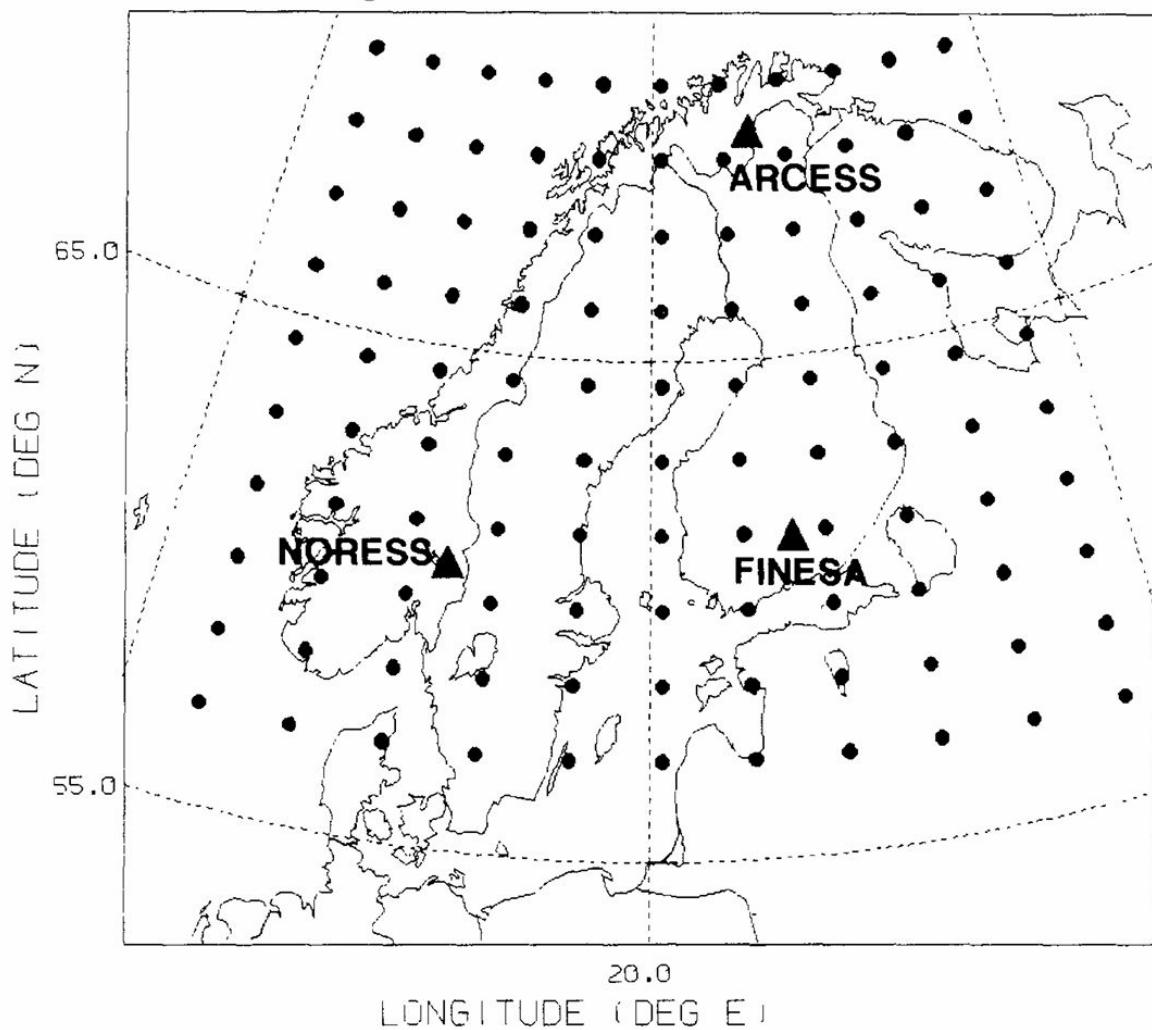
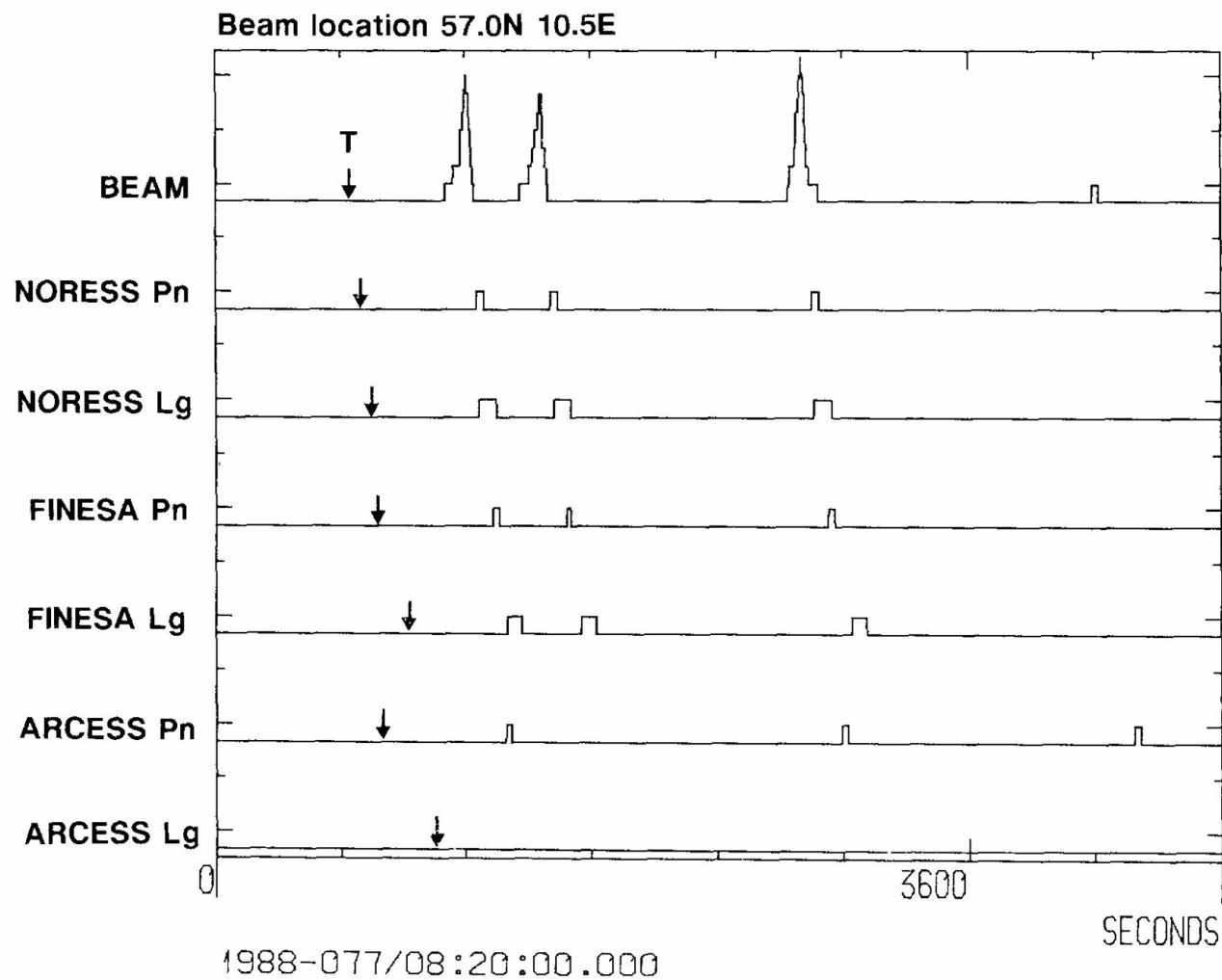


FIG. 1. Beam grid used in the generalized beamforming procedure for the purpose of associating regional phases from NORESS, ARCESS, and FINESA. The location of the three arrays is shown on the map.

Brief History

Ringdall and
Kvearna
(1989)



Standard travel-time tables are used in these computations. Thus, for the j th beam, we obtain a set of time-aligned channels:

$$\bar{s}_j(T) = \{s_{ijk}(T + \tau_{ijk})\} \quad k = 1, \dots, K_{ij}; \quad i = 1, \dots, N \quad (1)$$

Brief History

Ringdall and
Kvearna
(1989)

Events located by beampacking

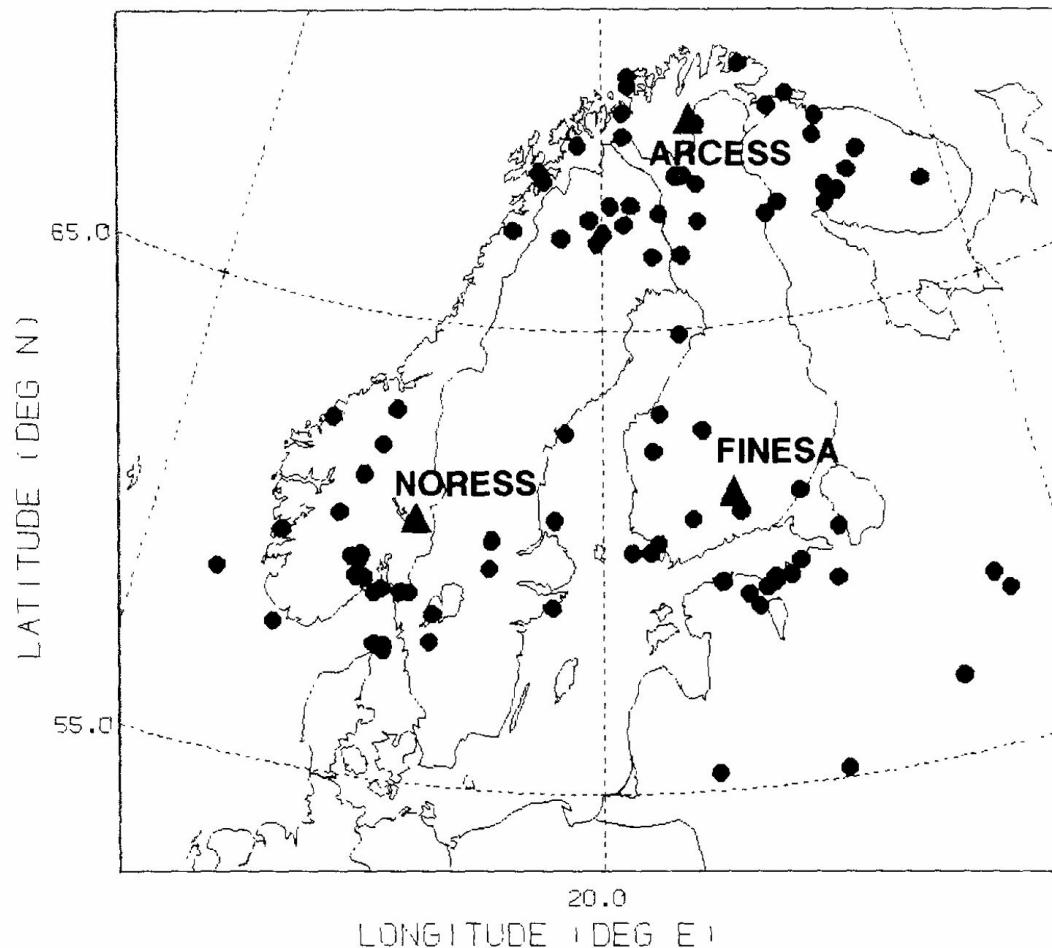


TABLE 3
LOCATION ESTIMATES

Event No.	Date (yy/mm/dd)	Time	Network		Mag. M _L	No. of phases
			Lat.	Lon.		
1	88/03/17	08.40.25.0	57.73	11.03	2.5	7
2	88/03/17	08.46.18.7	58.07	11.36	2.6	6
3	88/03/17	09.07.10.3	58.08	11.43	2.7	8
4	88/03/17	10.21.23.0	69.6	29.9	2.9	8
5	88/03/17	10.27.20.0	59.2	27.6	2.3	4
6	88/03/17	10.46.21.0	59.2	27.6	<2	2
7	88/03/17	11.18.48.0	59.3	27.2	2.3	5
8	88/03/17	11.54.41.0	65.8	24.7	<2	5
9	88/03/17	11.57.57.9	60.57	8.36	1.8	2
10	88/03/17	12.02.36.0	59.4	28.5	2.1	3
11	88/03/17	12.42.22.9	59.78	10.76	2.3	3
12	88/03/17	14.13.14.0	58.33	6.28	2.4	4
13	88/03/17	14.21.08.0	60.9	29.4	2.3	3
14	88/03/17	14.33.58.3	59.06	5.88	2.2	2
15	88/03/17	18.58.08.1	59.68	5.57	3.2	7

Location estimates obtained automatically from the beampacking program. The network locations from the Helsinki and Bergen bulletins. Note the events with more than one detecting array.

Brief History

Johnson et
al., (1997)

$$\text{Phs}_i := \{\dots, \text{phs}_{i-2}, \text{phs}_{i-1}, \text{phs}_i\}.$$

$$\text{Hyp}_i := \{\dots, \text{hyp}_{i,j-2}, \text{hyp}_{i,j-1}, \text{hyp}_{i,j}\},$$

Formulate problem as a discrete assignment
problem..

Brief History

Johnson et
al., (1997)

$$\text{Phs}_i := \{\dots, \text{phs}_{i-2}, \text{phs}_{i-1}, \text{phs}_i\}.$$

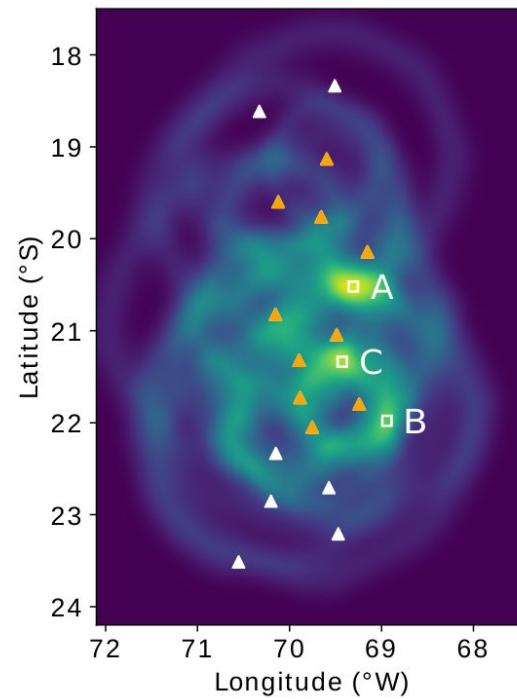
$$\text{Hyp}_i := \{\dots, \text{hyp}_{i,j-2}, \text{hyp}_{i,j-1}, \text{hyp}_{i,j}\},$$

$$A_{i,j} = \begin{cases} \frac{W}{(W+N_j)} \left| \frac{T_{obs_i} - T_{cal_{i,j}}}{\Delta(r_{ij})} \right| & \text{If } \text{phs}_i \text{ is associated with } \text{hyp}_j \\ 0 & \text{Otherwise} \end{cases}$$

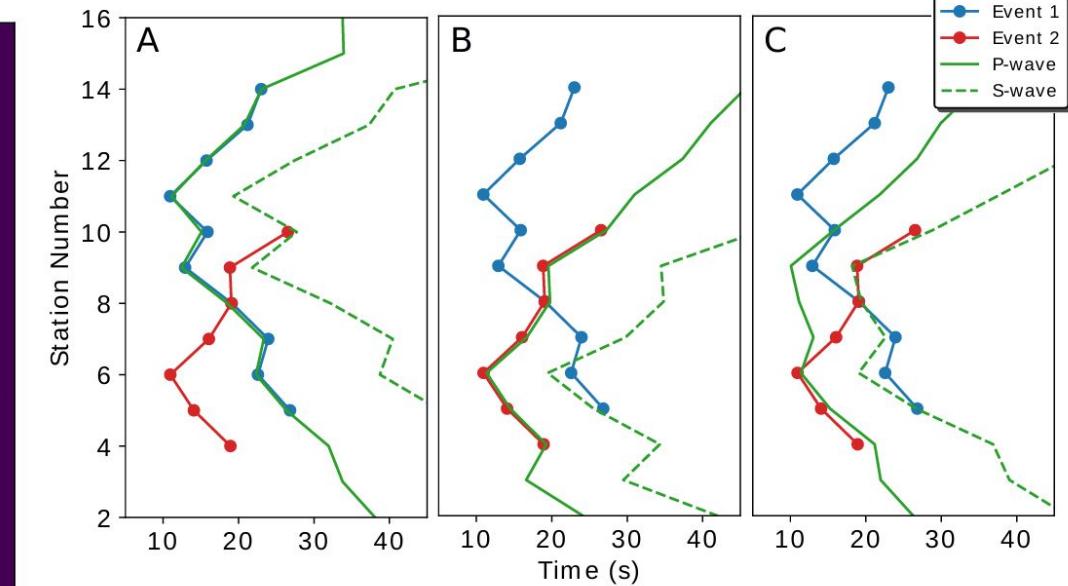
Formulate problem as a discrete assignment
problem..

Brief History

(a)

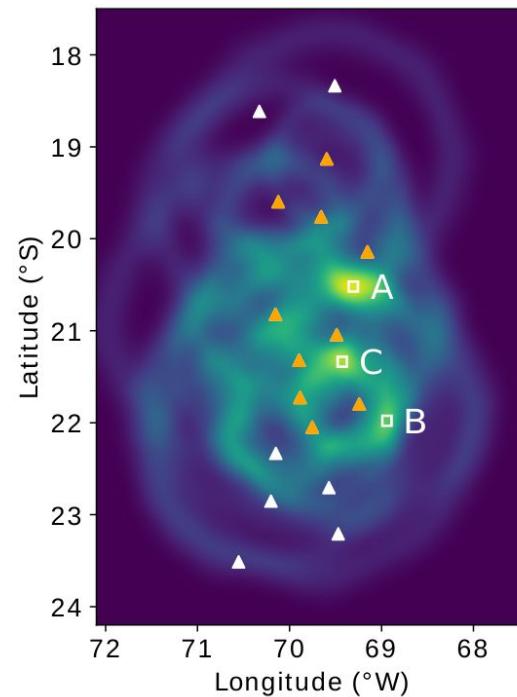


(b)

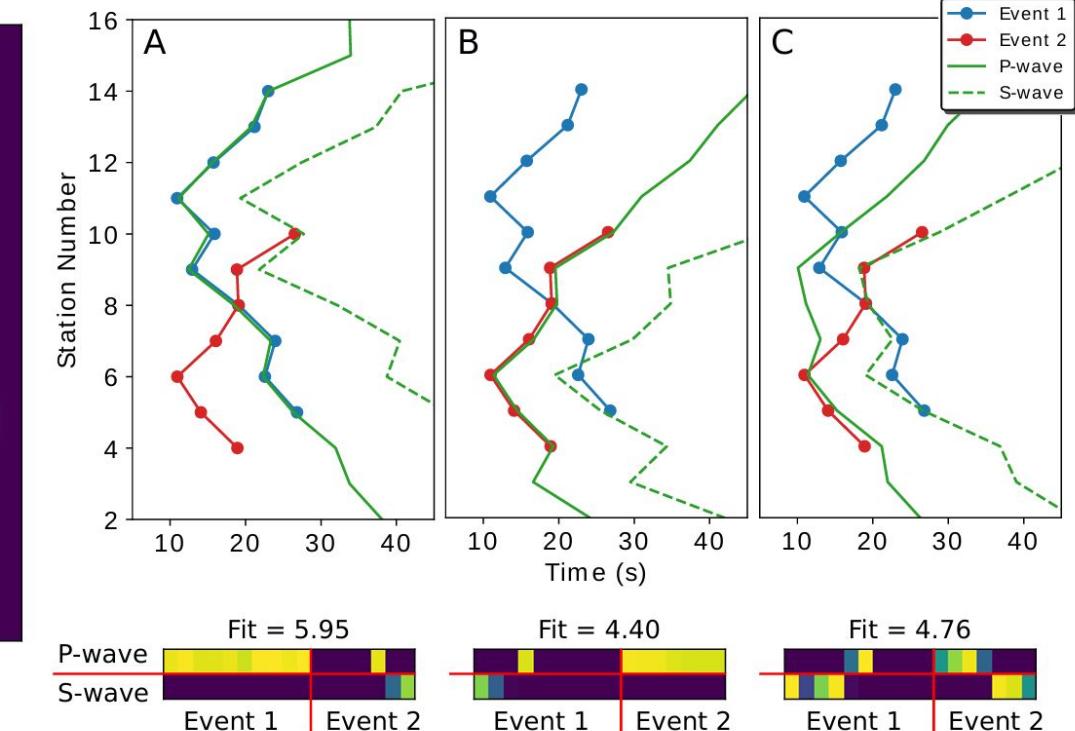


Brief History

(a)

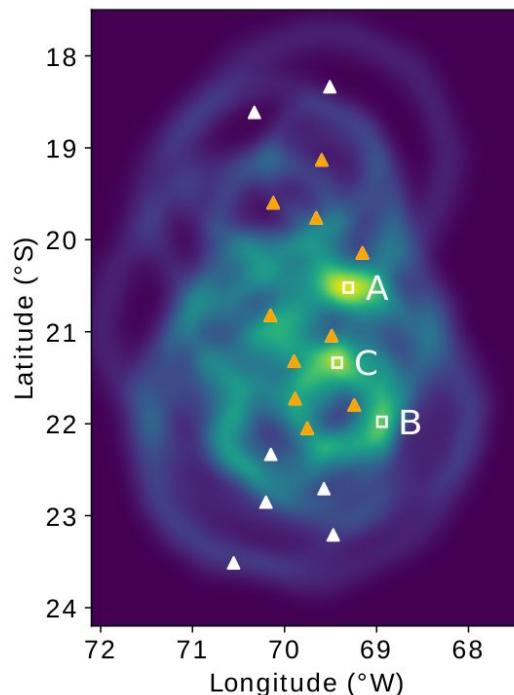


(b)

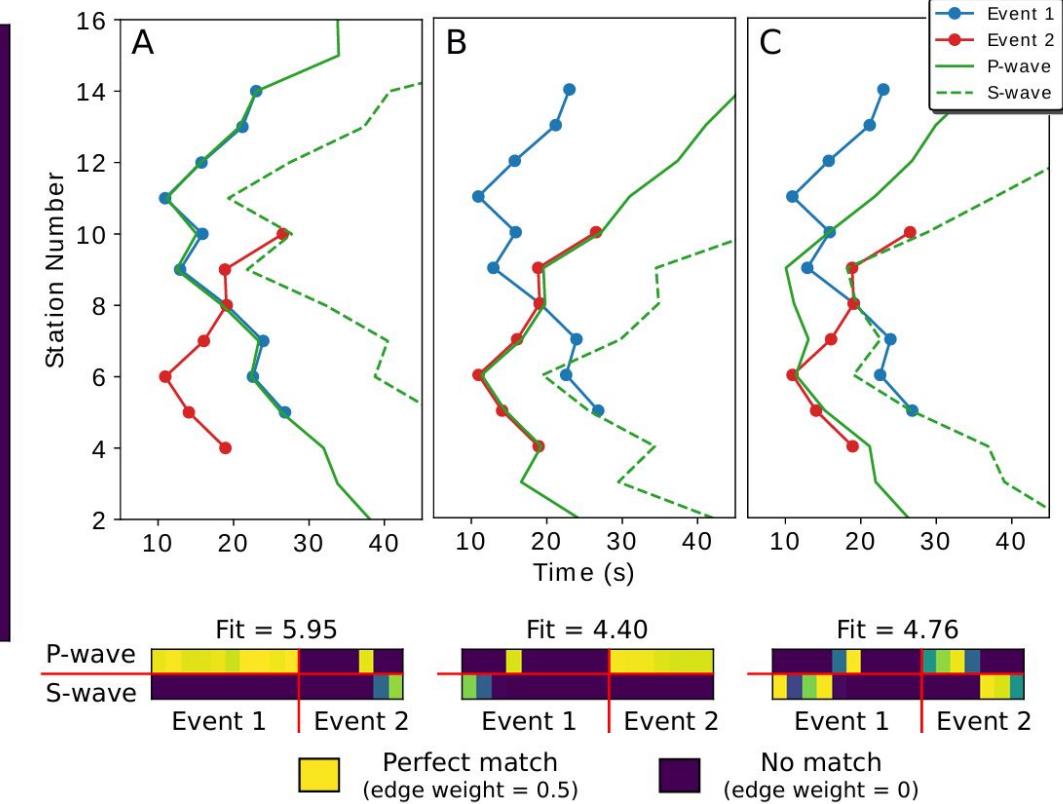


Brief History

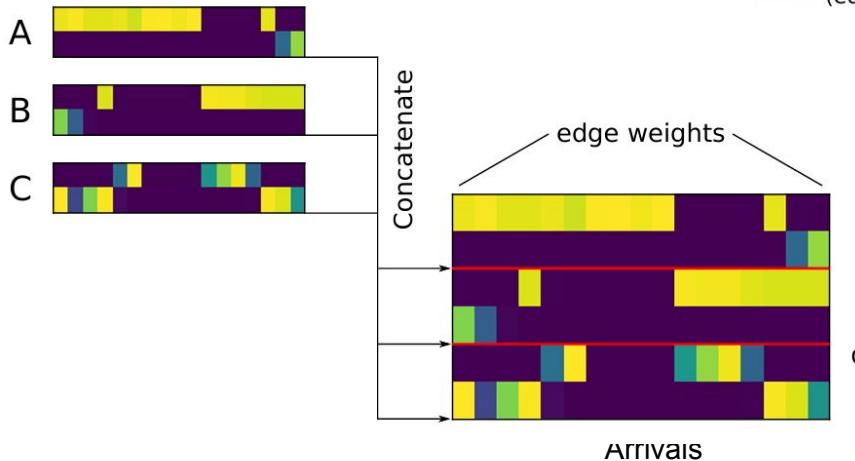
(a)



(b)



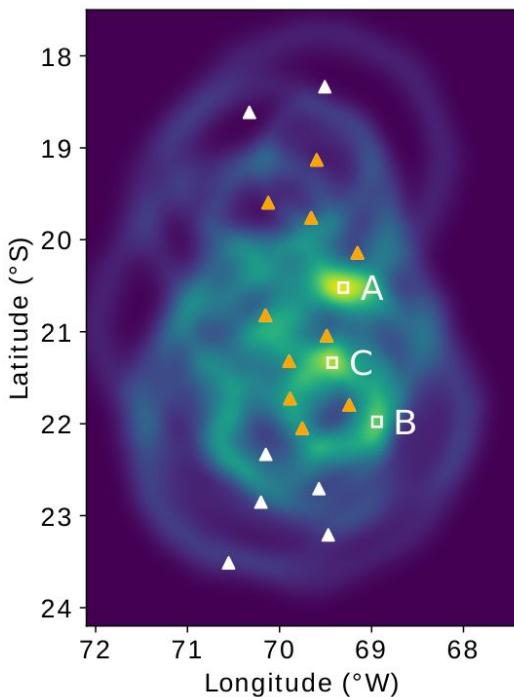
(c)



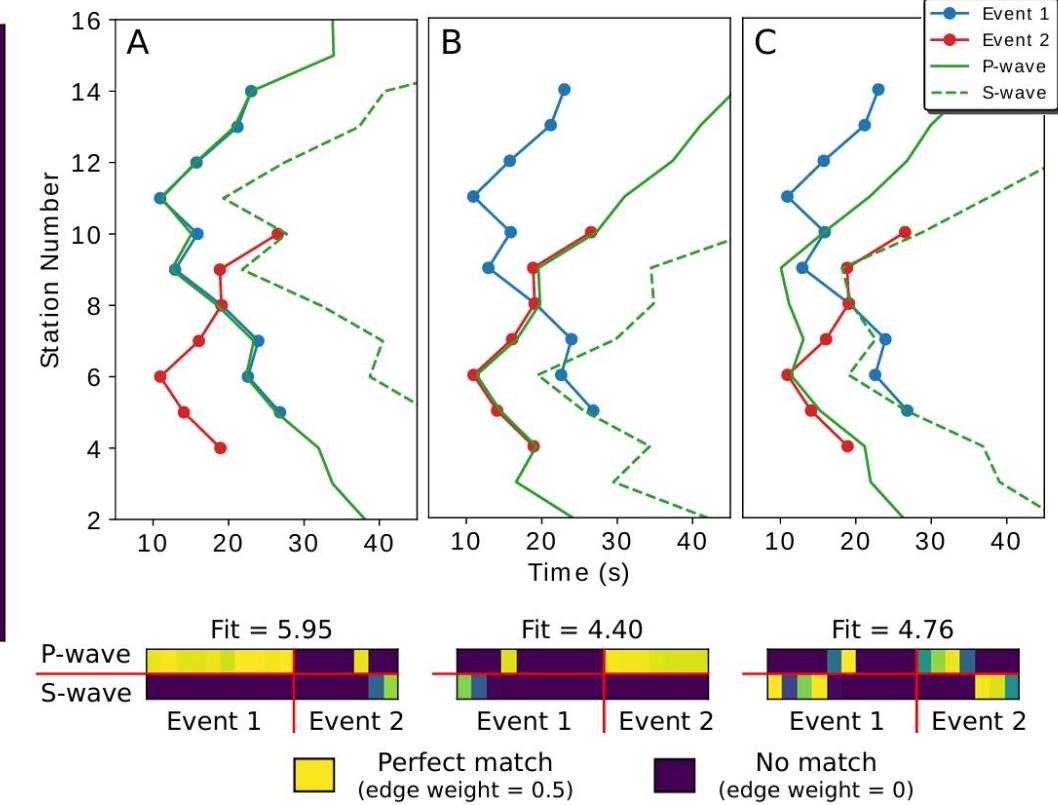
Problem – ambiguous assignments?

Brief History

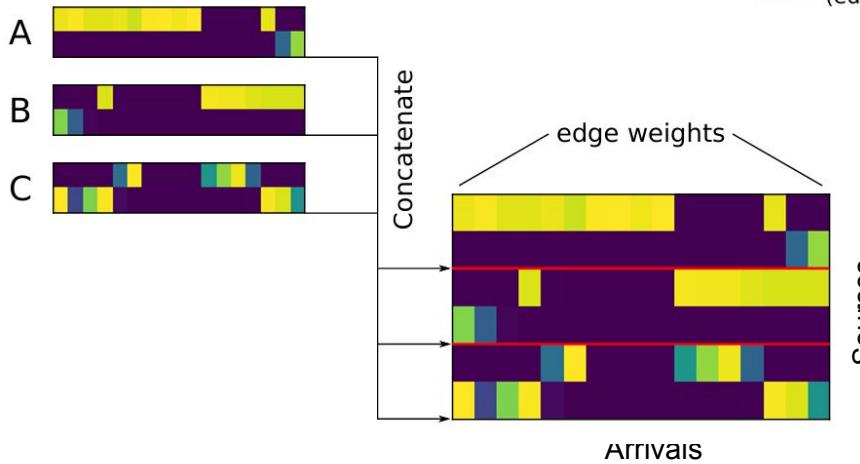
(a)



(b)



(c)



Brief History

Johnson et
al., (1997)

$\text{Phs}_i := \{\dots, \text{phs}_{i-2}, \text{phs}_{i-1}, \text{phs}_i\}.$

$\text{Hyp}_i := \{\dots, \text{hyp}_{i,j-2}, \text{hyp}_{i,j-1}, \text{hyp}_{i,j}\},$

$$A_{i,j} = \begin{cases} \frac{w}{(w+N_j)} \left| \frac{T_{obs_i} - T_{cal_{i,j}}}{\Delta(r_y)} \right| & \text{If } phs_i \text{ is associated with hyp}_j \\ 0 & \text{Otherwise} \end{cases}$$

Formulate problem as a discrete assignment
problem..

Algorithms

$$\text{Norm} = \sum_{i,j} A_{i,j}.$$

$$\text{Norm}_n^r = \sqrt{\frac{n}{(n-r)}} \sum_{ij} A_{ij}$$

Brief History

Johnson et
al., (1997)

$$\text{Phs}_i := \{\dots, \text{phs}_{i-2}, \text{phs}_{i-1}, \text{phs}_i\}.$$

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Formulate problem as a discrete assignment
problem..

Perspective

The association problem divides into three interconnected subsets problems. They are:

1. Identification
2. Location, and

3. Selection, or association,

Steps 2 and 3 will be looped through many times, as more arrivals associated with an event, the event relocated, etc..

A fourth step should probably be included, which can be roughly as:

4. Clean-up.

Algorithms

$$\text{Norm} = \sum_{i,j} A_{i,j}.$$

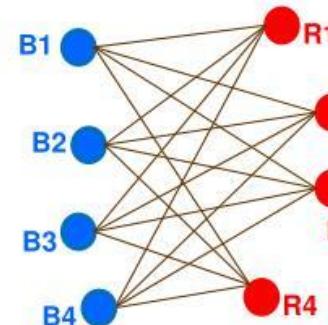
$$\text{Norm}_n^r = \sqrt{\frac{n}{(n-r)}} \sum_{ij} A_{ij}$$

Brief History

Johnson et
al., (1997)



Hungarian method - Example



	R1	R2	R3	R4
B1	8	17	3	23
B2	39	4	11	20
B3	13	2	41	6
B4	22	8	9	2

Step 1

First for each row we subtract the row minimum from the rest of the row

	R1	R2	R3	R4	
B1	8	17	3	23	-3
B2	39	4	11	20	-4
B3	13	2	41	6	-2
B4	22	8	9	2	-2

Step 2

Then for each column we subtract the column minimum from the rest of the column

	R1	R2	R3	R4
B1	5	14	0	20
B2	35	0	7	16
B3	11	0	39	4
B4	20	6	7	0
	-5	-0	-0	-0

Brun et
al., 2008

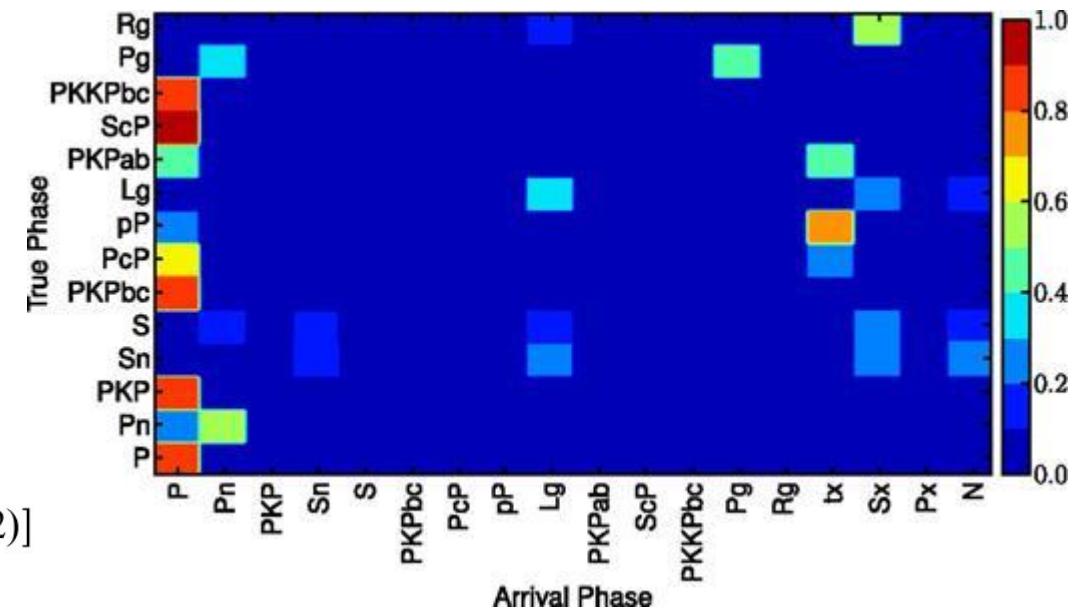
The **Hungarian method** is a [combinatorial optimization algorithm](#) that solves the [assignment problem](#) in [polynomial time](#) and which anticipated later [primal–dual methods](#). It was developed and published in 1955 by [Harold Kuhn](#), who gave it the name "Hungarian

Brief History

Arora et al.,
(2013)

Net-Visa: Probabilistic method – possibly more “accurate”, but difficult to implement, and still rule-based, iterative processing of data

$$P_{\theta}(e) = \exp(-\lambda_e T) \prod_{i=1}^{|e|} P_{\theta,l}(e_l^i) \frac{1}{D} \lambda_e \lambda_m \exp[-\lambda_m(e_m^i - 2)]$$



Brief History

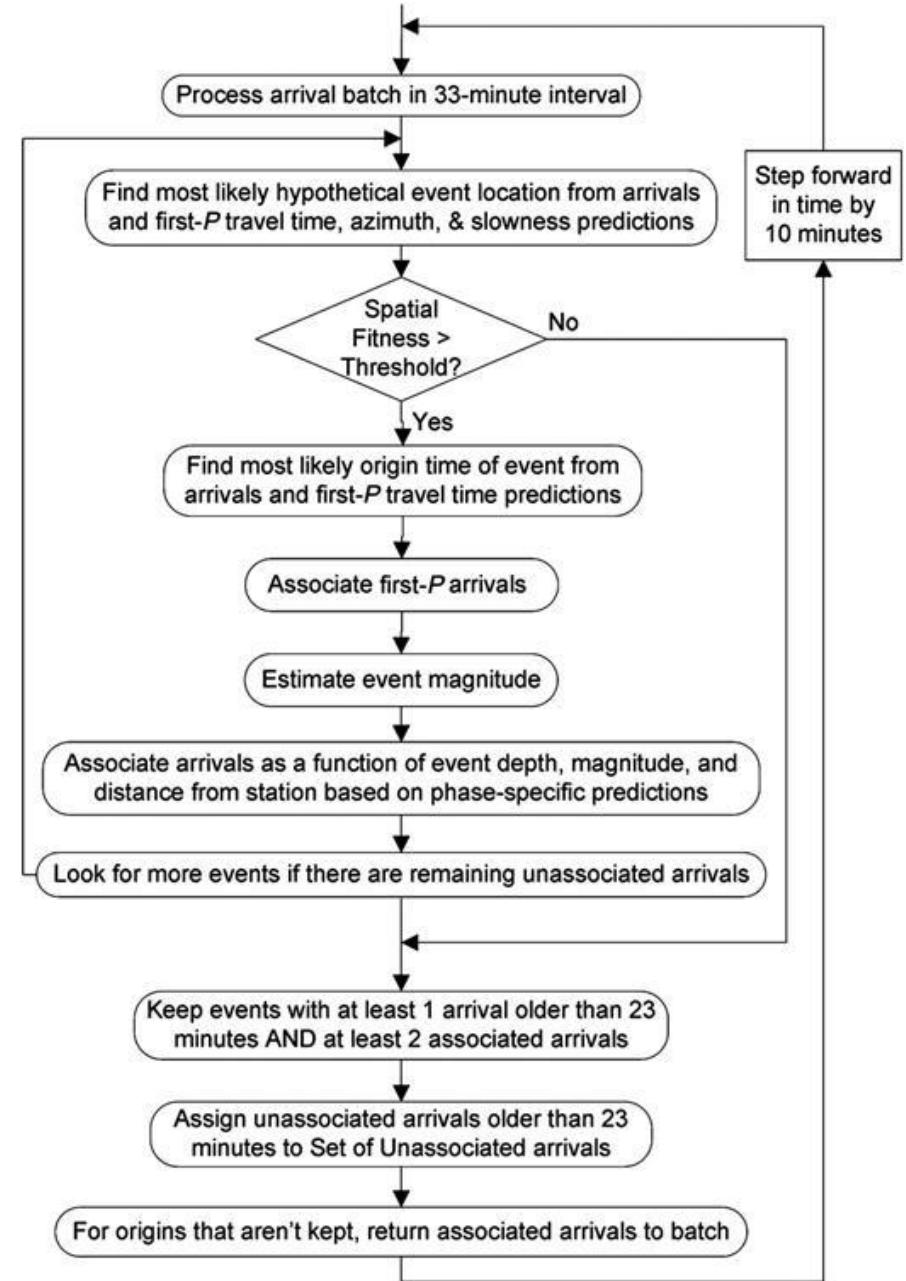
Draelos et al.,
2015)

Pedal (similar to GA; 1994): temporal energy stack, misfit tables, iterative processing logic/thresholding

$$g_{i,j} = P(d_{s_i}|E_\omega) \times P(d_{s_j}|E_\omega) \times Q_{s_i} \times Q_{s_j},$$

$$w_{i,j} = \frac{\frac{\sqrt{2}}{3}N_{tt}}{(\sigma_{tt,i,\omega}^2 + \sigma_{tt,j,\omega}^2)^{1/2}} + \frac{\frac{1}{6}N_{az}}{\sigma_{az,i,\omega}} + \frac{\frac{1}{6}N_{az}}{\sigma_{az,j,\omega}} + \frac{\frac{1}{6}N_{sh}}{\sigma_{sh,i,\omega}} + \frac{\frac{1}{6}N_{sh}}{\sigma_{sh,j,\omega}},$$

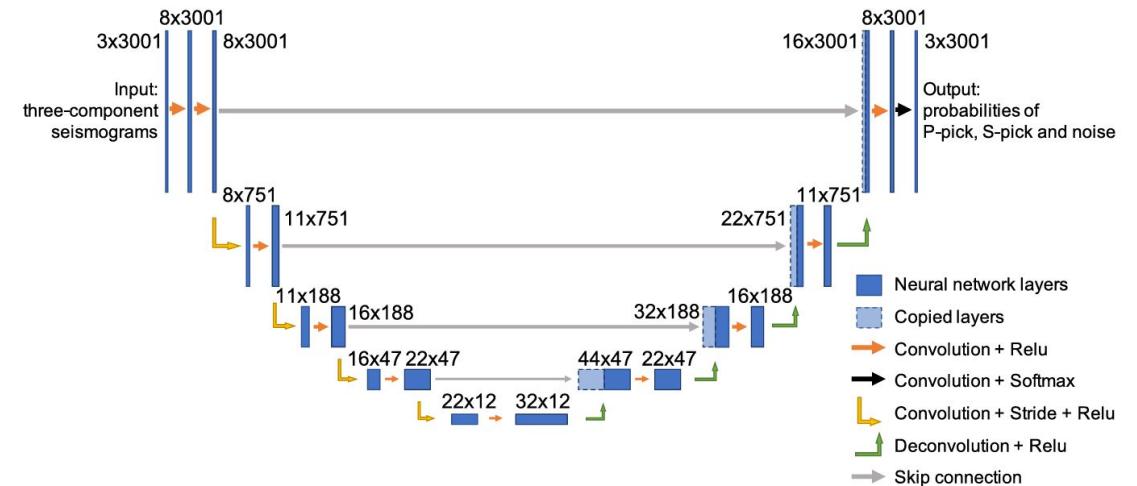
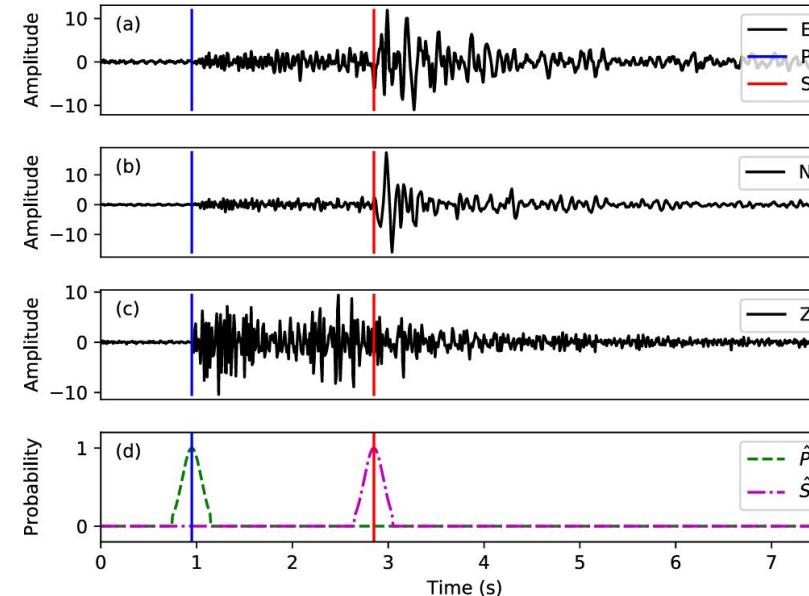
$$\text{and } r_{i,j}^2 = \frac{[(T_i - T_j) - (p_{tt,i,\omega} - p_{tt,j,\omega})]^2}{\sigma_{tt,i,\omega}^2 + \sigma_{tt,j,\omega}^2} + \frac{(az_i - p_{az,i,\omega})^2}{\sigma_{az,i,\omega}^2} + \frac{(az_j - p_{az,j,\omega})^2}{\sigma_{az,j,\omega}^2} + \frac{(sh_i - p_{sh,i,\omega})^2}{\sigma_{sh,i,\omega}^2} + \frac{(sh_j - p_{sh,j,\omega})^2}{\sigma_{sh,j,\omega}^2},$$



Brief History

Zhu et al.,
(2019)

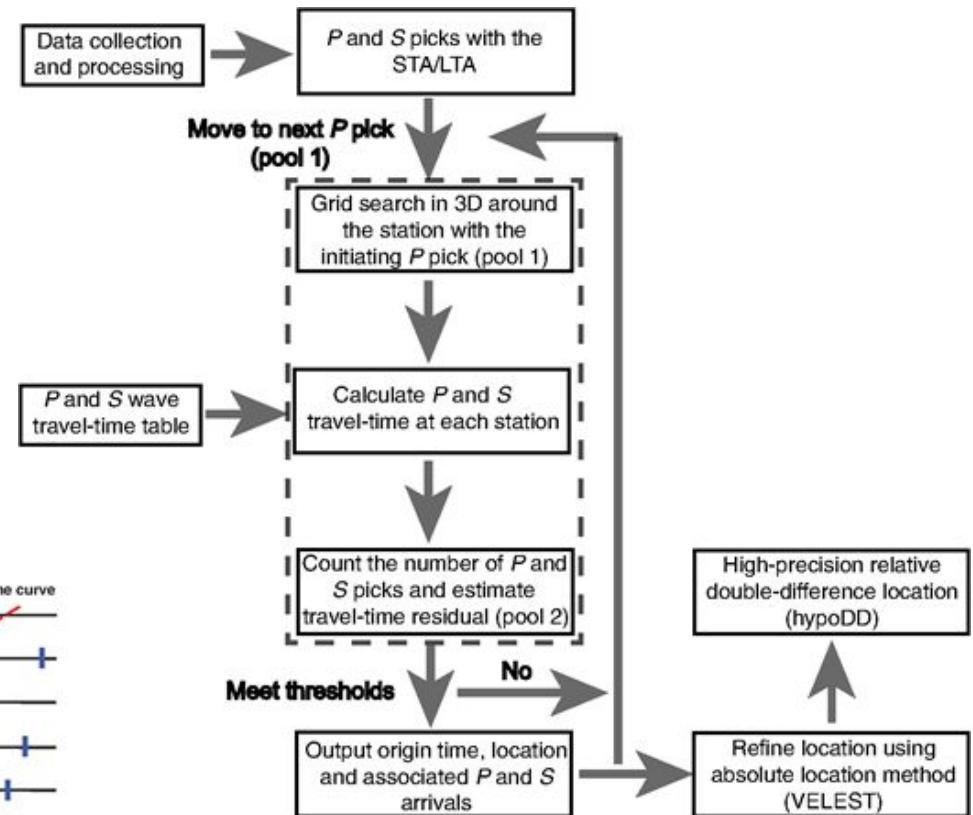
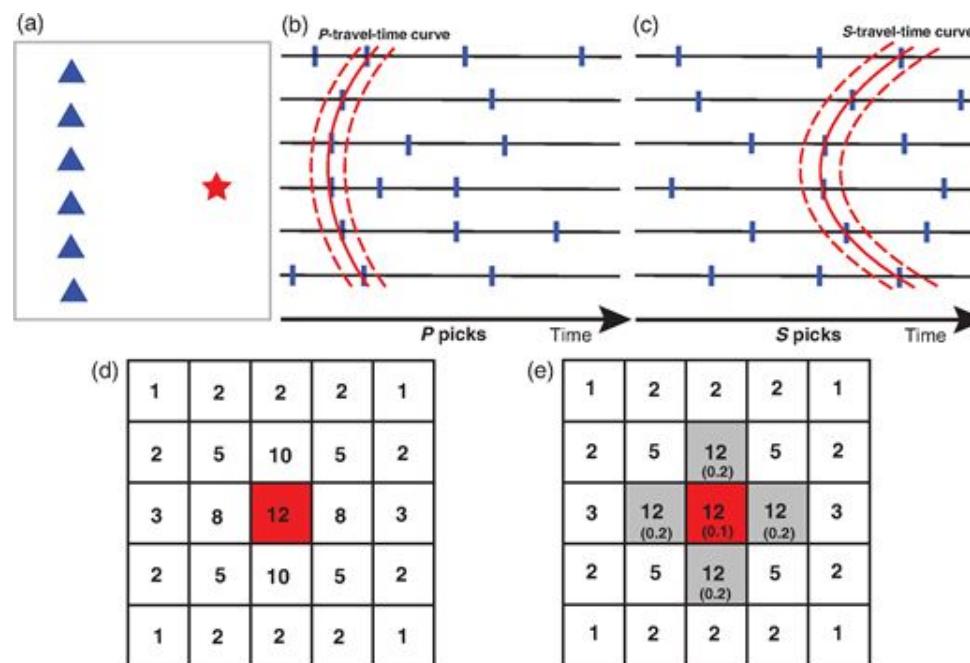
PhaseNet: More picks, more
data harder association
challenge



Brief History

Zhang et al.,
(2019)

REAL: back-projection
based association and
greedy association
assignment

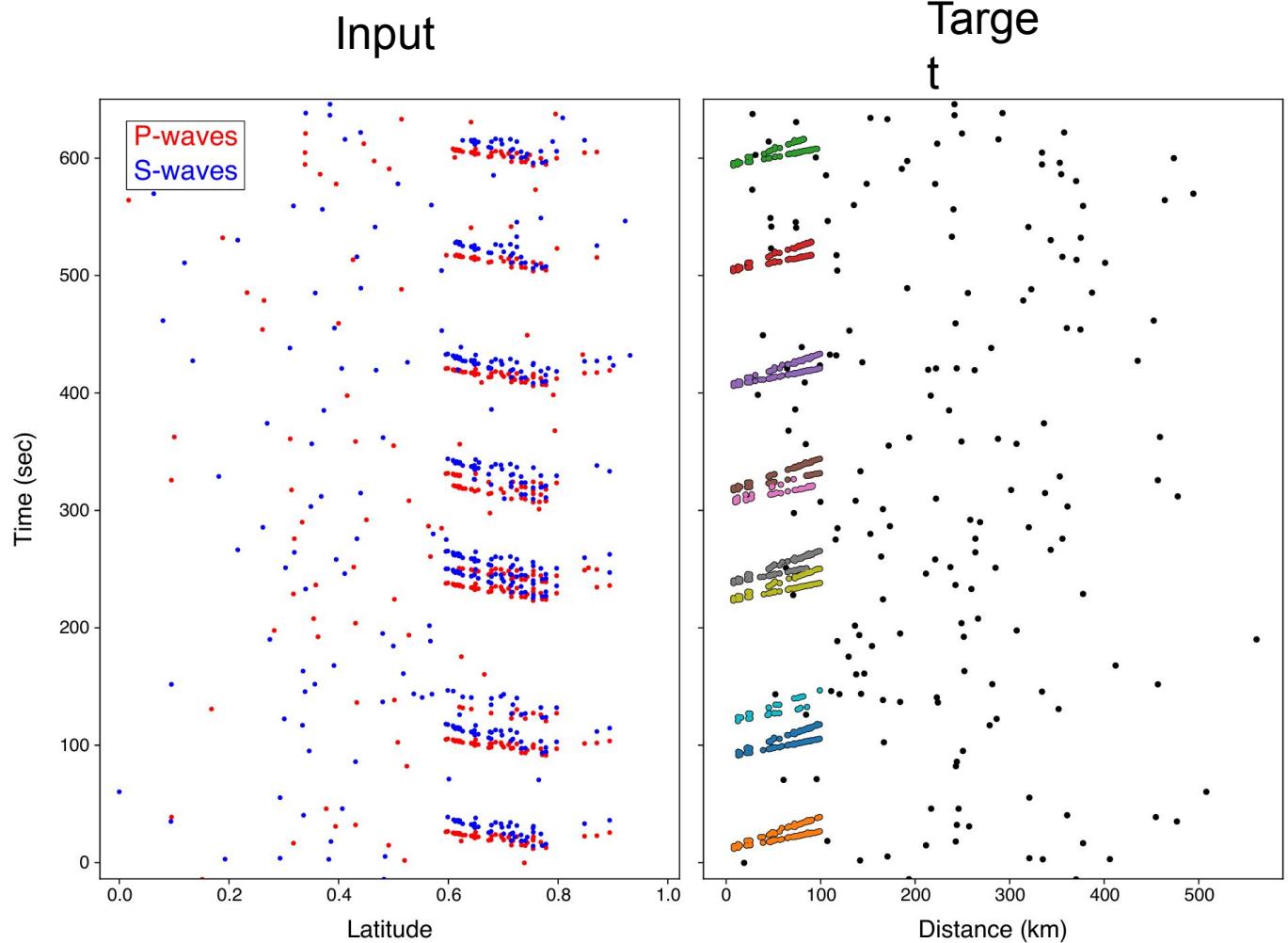


Brief History

Ross et al.,
(2019)

PhaseLink: RNN based association

- Train on synthetic examples and learn solution



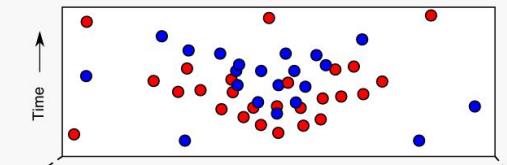
Brief History

Ross et al.,
(2019)

PhaseLink: RNN based association

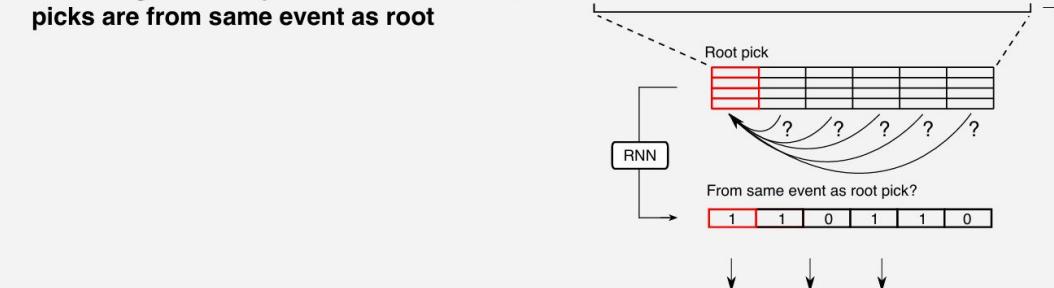
- Train on synthetic examples and learn solution

1. Collect picks over a seismic network

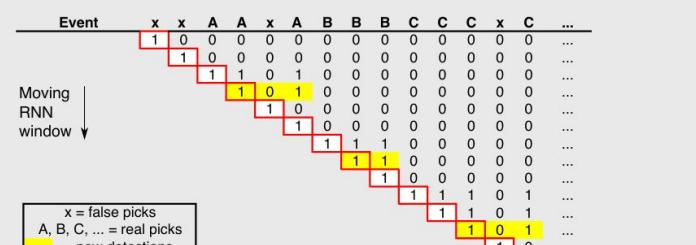


Station lat.	33.57	33.56	33.57	33.49	...	33.49	33.59	33.35
Station lon.	-116.67	-116.53	-116.22	-116.60	...	-116.60	-116.76	-116.56
Time (sec)	4.56	4.84	4.93	5.11	...	5.23	5.62	5.65
Phase type	P	P	S	P	...	S	P	S

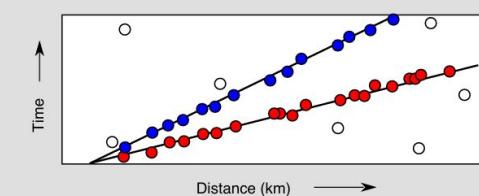
2. In moving window, predict which picks are from same event as root



3. Aggregate predictions for all windows



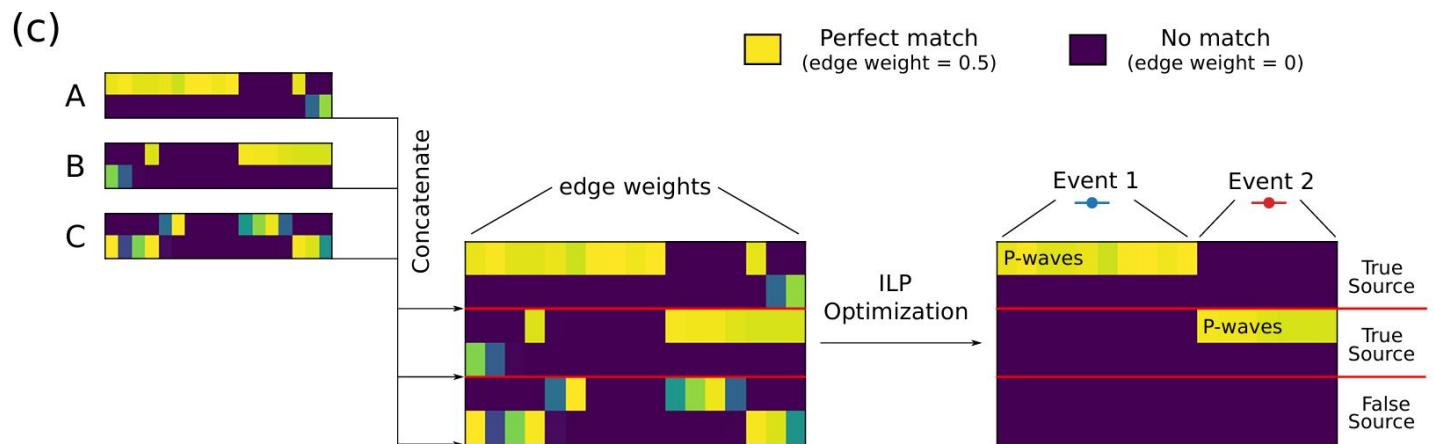
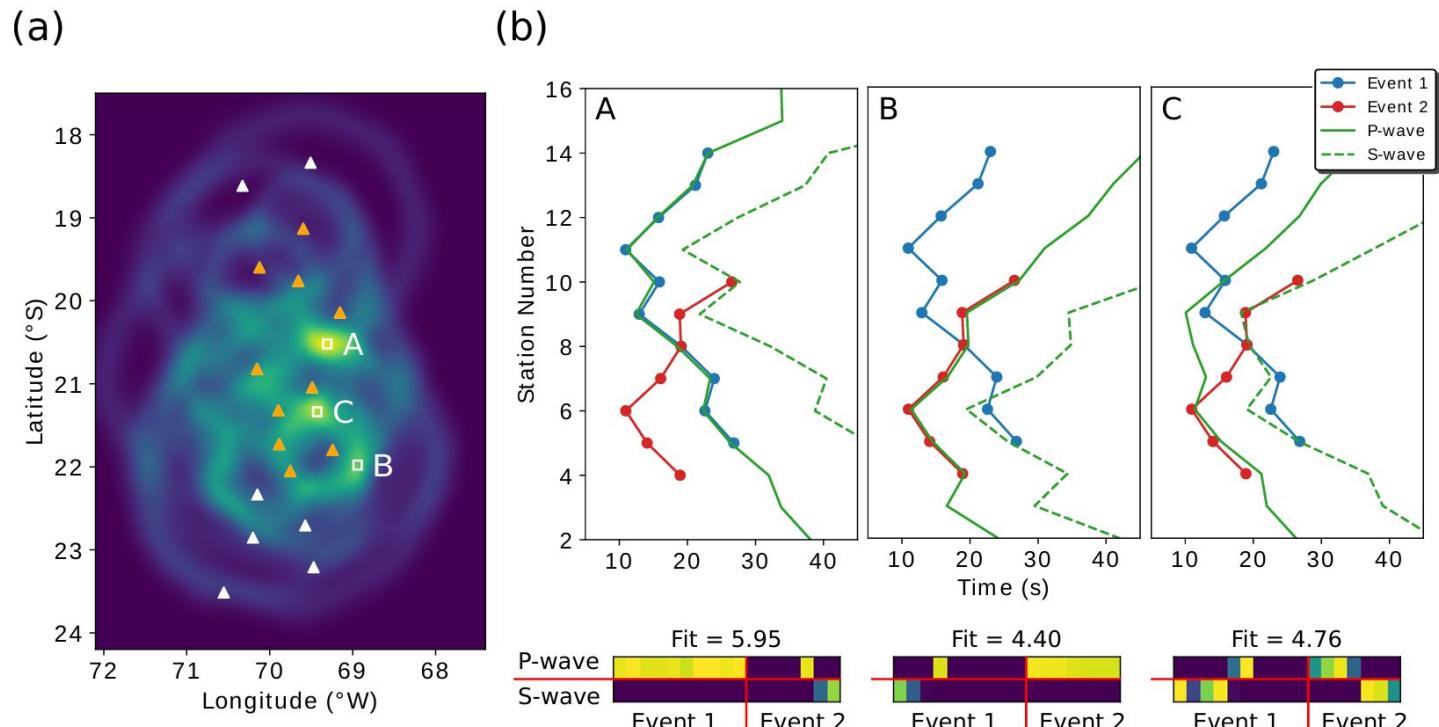
4. Pick sequence is fully associated



Brief History

McBrearty et al., (2019)

Use Backprojection
and Integer Linear
Optimization



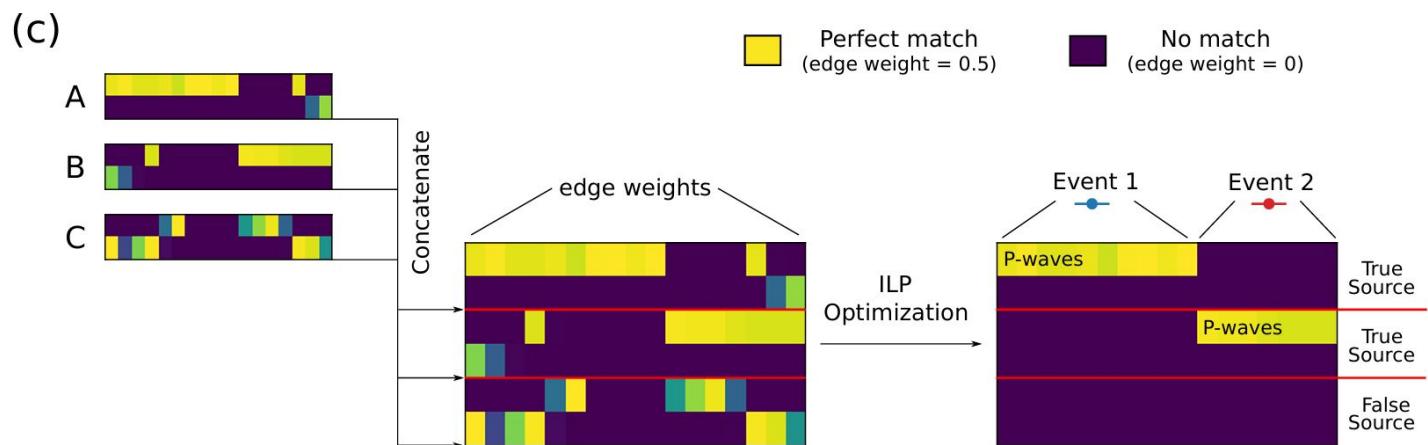
Brief History

McBrearty et
al., (2019)

Use Backprojection and Integer Linear Optimization

- Explicit optimization (more robust than Hungarian algorithm)
- Still must determine sources/scaling issues

$$\begin{aligned} & \max_x c^T x \\ & \text{s.t. } Ax \leq b \\ & x \in \{0, 1\} \\ & \{A, b, c\} \xleftarrow{\text{Algs. S1-S3}} \{\mathcal{D}, \mathcal{S}\}, \end{aligned}$$



Brief History

McBrearty et
al., (2019)

Use Backprojection and Integer Linear Optimization

- Explicit optimization (more robust than Hungarian algorithm)
- Still must determine sources/scaling issues

$$\max_x c^T x$$

```
# Solve ILP

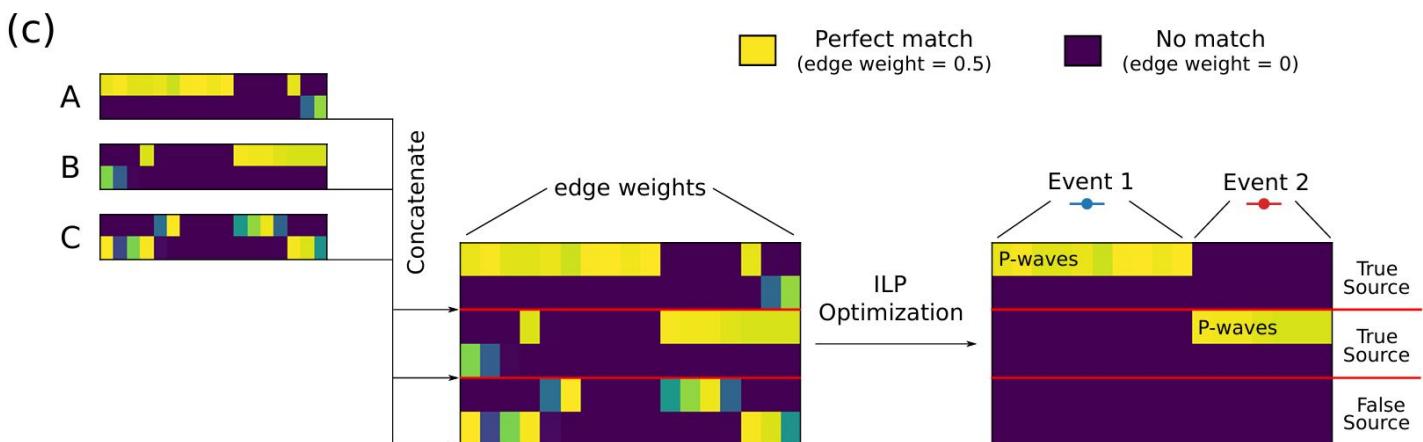
x = cp.Variable(n_phases*n_srcs*n_arvs + n_srcs, integer = True)

prob = cp.Problem(cp.Minimize(c.T@x), constraints = [A@x <= b.reshape(-1), 0 <= x, x <= 1])

prob.solve()

assert prob.status == 'optimal', 'competitive assignment solution is not optimal'
```

Python: Cvxpy
package



Brief History

Zhu et al.,
2022

GaMMA: Bayesian
Gaussian Mixture
model association
**(unsupervised
clustering)**

- "Iteratively" solve association and event location (i.e., "soft assignment")

E-step:

$$\gamma_{ik} = \frac{\phi_k \mathcal{N}(\mathbf{x}_i | \mu_k, \Sigma_k)}{\sum_{k=1}^K \phi_k \mathcal{N}(\mathbf{x}_i | \mu_k, \Sigma_k)}$$

M-step:

1. Effective number of picks assigned to the k -th earthquake:

$$N_k = \sum_{i=1}^N \gamma_{ik}$$
$$\phi_k = \frac{N_k}{N}$$

2. Earthquake location, origin time, and magnitude of the k -th earthquake:

$$\underset{(x_k, y_k, z_k, t_k)}{\text{minimize}} \quad l(x_k, y_k, z_k, t_k) = \sum_{i=1}^N \gamma_{ik} \mathcal{L}(t_i, \hat{t}_{ik}(x_k, y_k, z_k, t_k))$$

$$m_k = \frac{1}{N_k} \sum_{i=1}^N \gamma_{ik} \mathcal{F}'_a(a_i, d_{ik})$$

3. Theoretical travel time, amplitude, and statistics of residuals:

$$\mu_k = \begin{bmatrix} \hat{t}_{ik} \\ \hat{a}_{ik} \end{bmatrix} = \begin{bmatrix} \mathcal{F}_t(x_k, y_k, z_k, t_k) \\ \mathcal{F}_a(m_k, d_{ik}) \end{bmatrix}$$

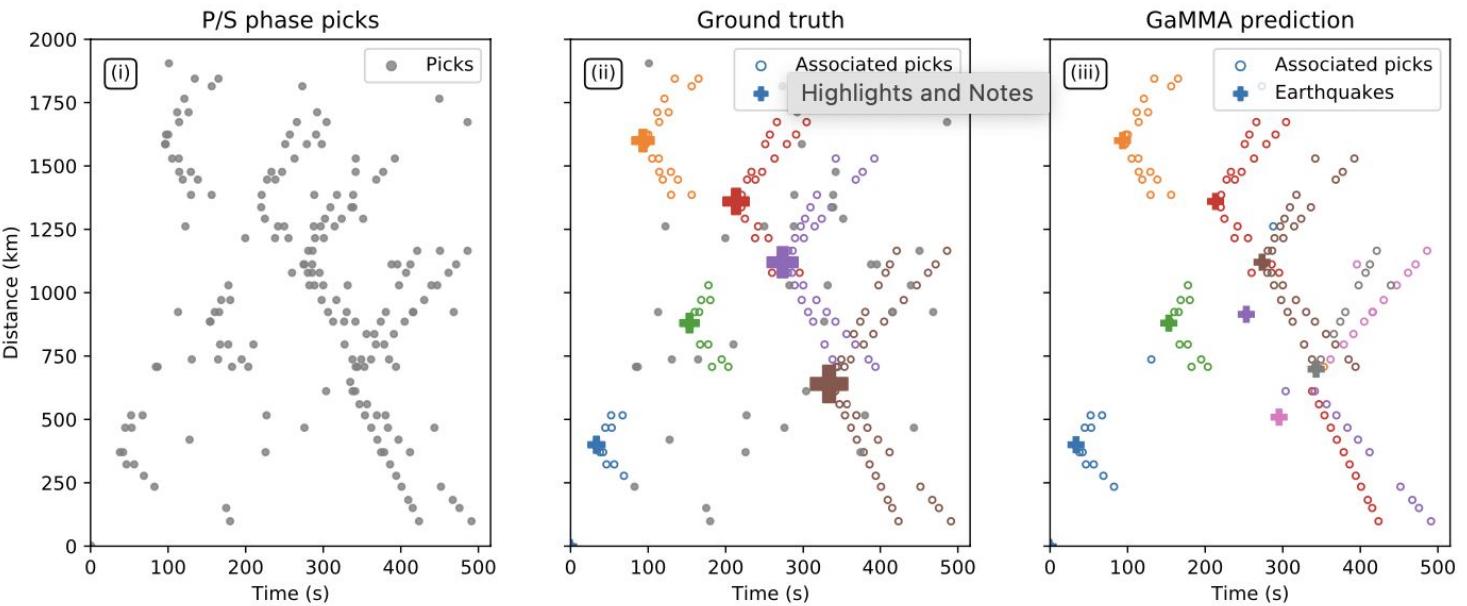
$$\Lambda_k^{-1} = \frac{1}{N_k} \sum_{i=1}^N \gamma_{ik} (\mathbf{x}_i - \mu_k)(\mathbf{x}_i - \mu_k)^T$$

Brief History

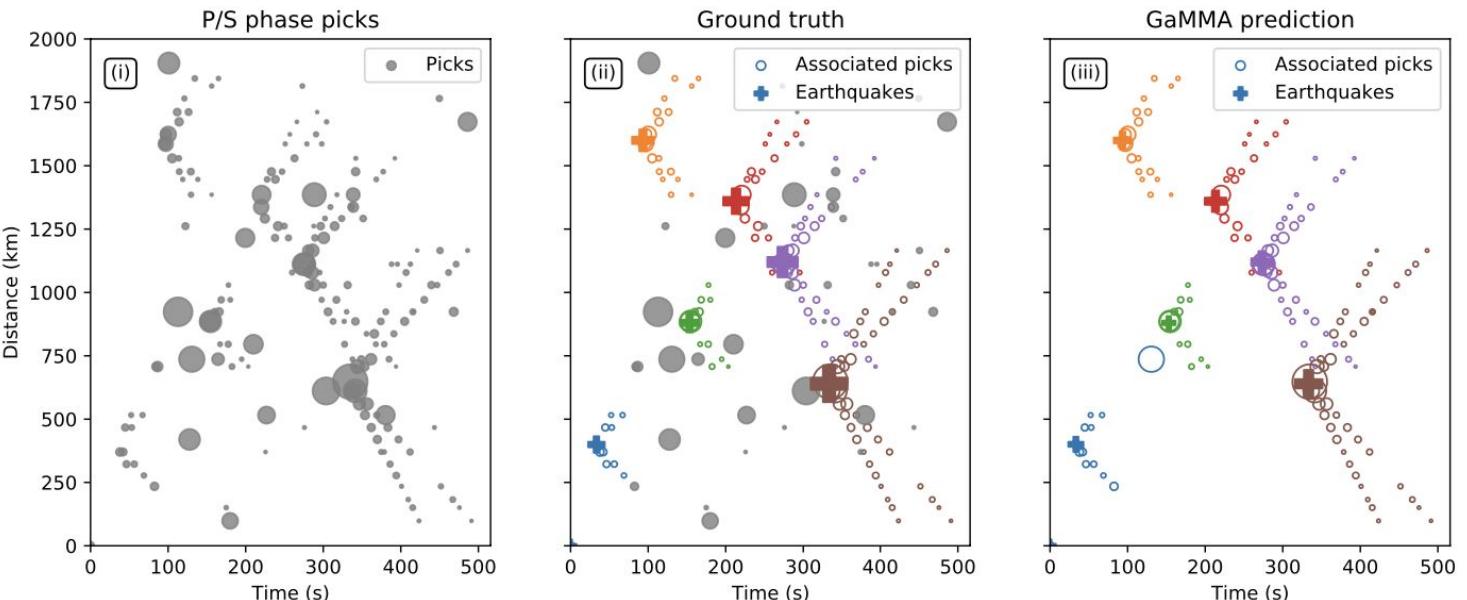
Zhu et al.,
2022

GaMMA: Bayesian Gaussian Mixture model association (unsupervised clustering)

- "Iteratively" solve association and event location (i.e., "soft assignment")



(a)

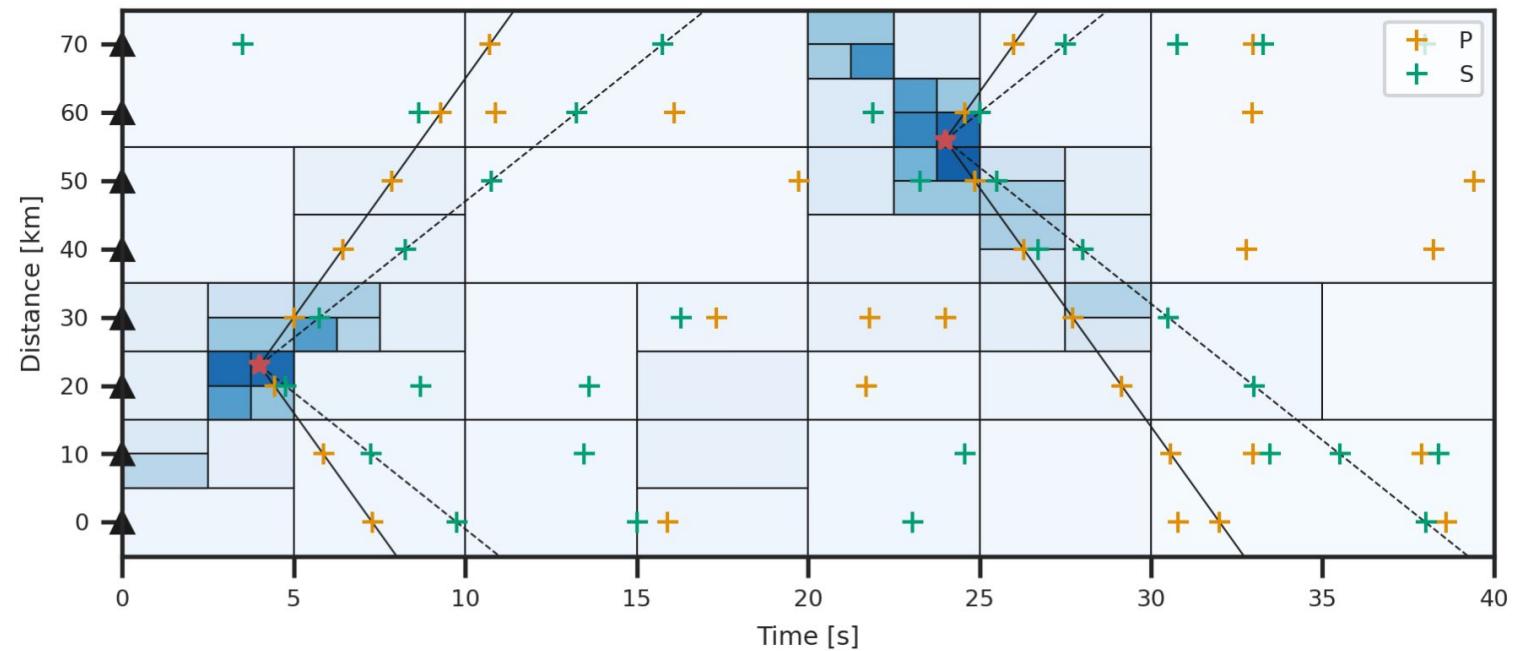
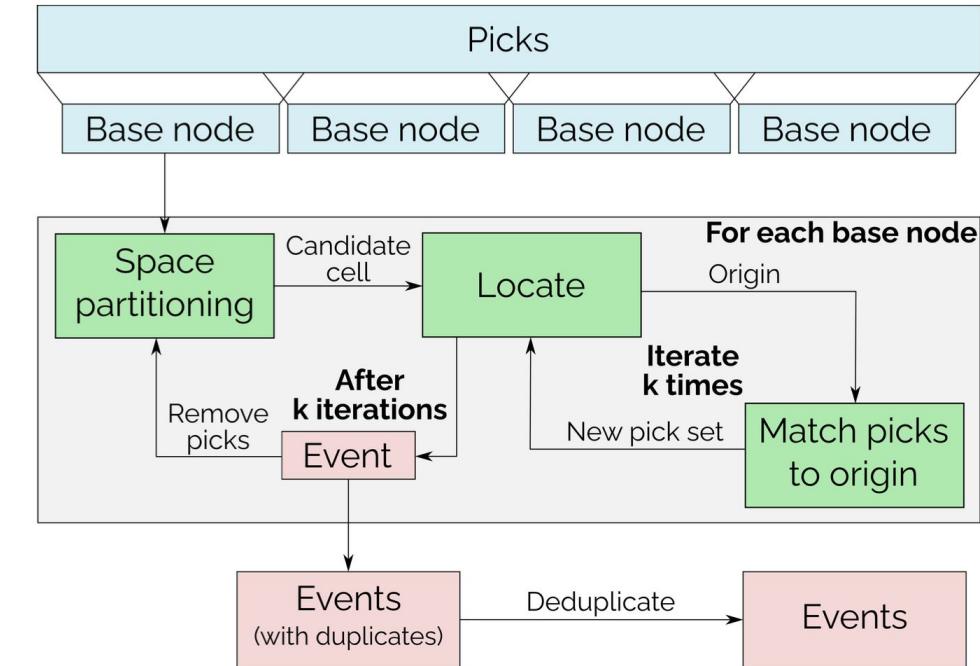


Brief History

Munchmeyer,
2024

PyOcto: Efficient back-projection search with Oct-Tree

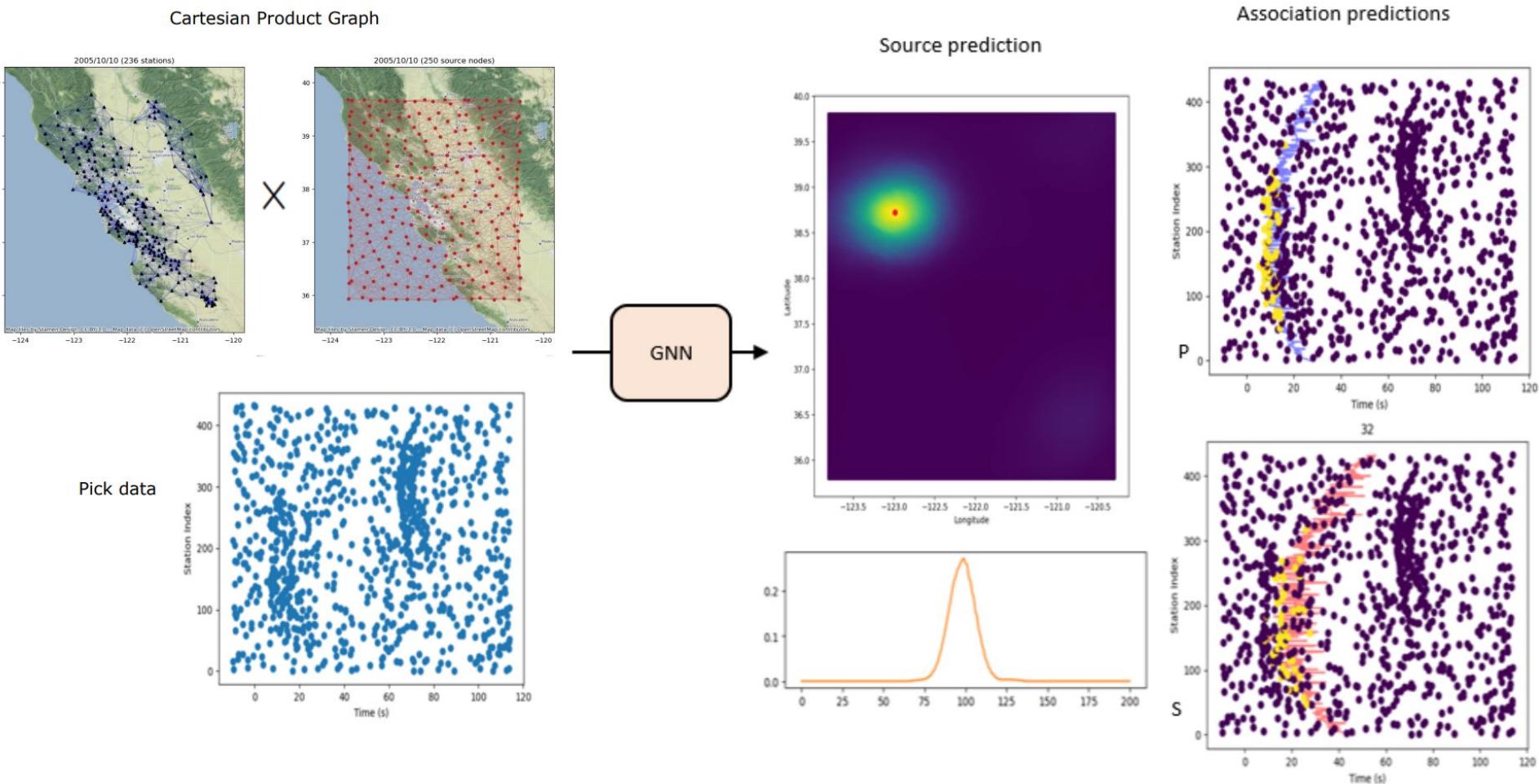
- Check optimal sources first; assign picks; iterate



Brief History

McBrearty and
Beroza, 2023

GENIE: GNN
based source
location and
phase
association

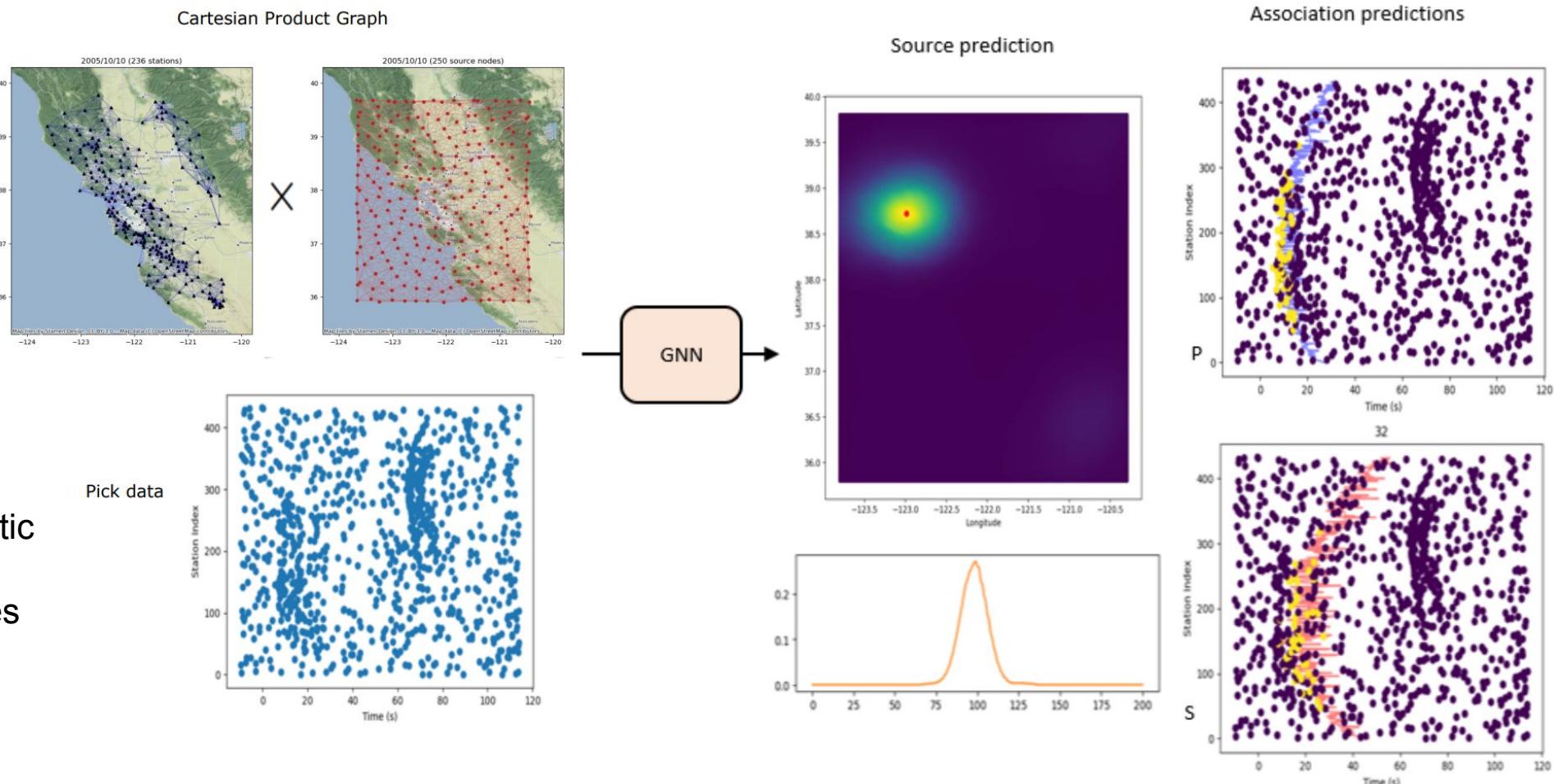


Brief History

McBrearty and
Beroza, 2023

GENIE: GNN
based source
location and
phase
association

- Trained on synthetic
data; simultaneous
prediction of sources
and associations

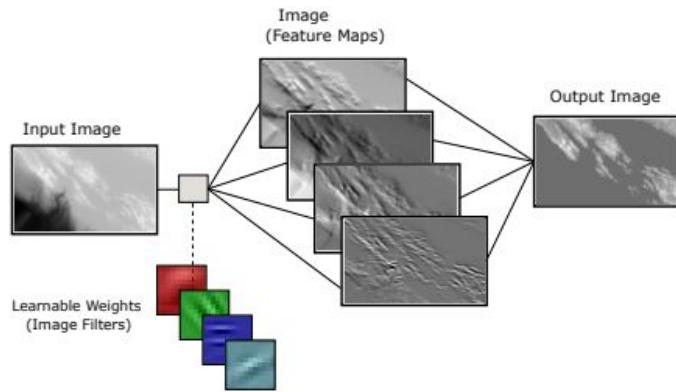


Association predictions are conditioned on source
predictions

Why GNNs?

Convolutional Neural Networks

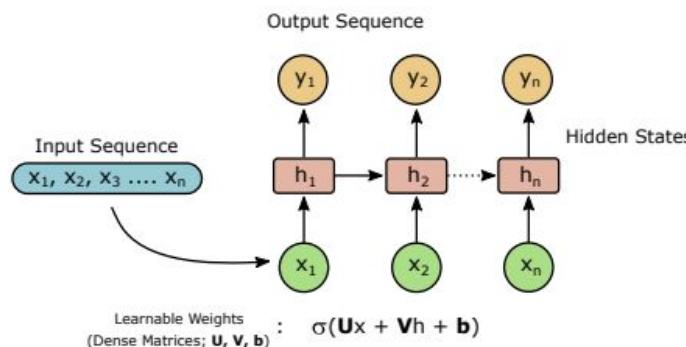
Effective for Euclidean data
(e.g., time series, images)



Relies on the distribution and type of spatial features (e.g., edges, shapes, gradients).

Recurrent Neural Networks

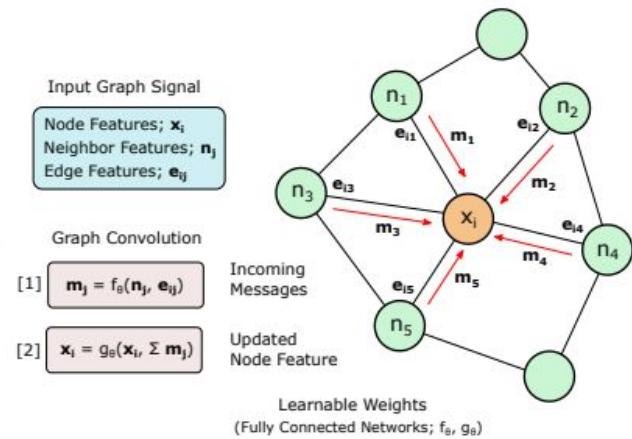
Effective for Euclidean data
(e.g., time series, text)



Relies on the timing/sequencing and strength of temporal signals.

Graph Neural Networks

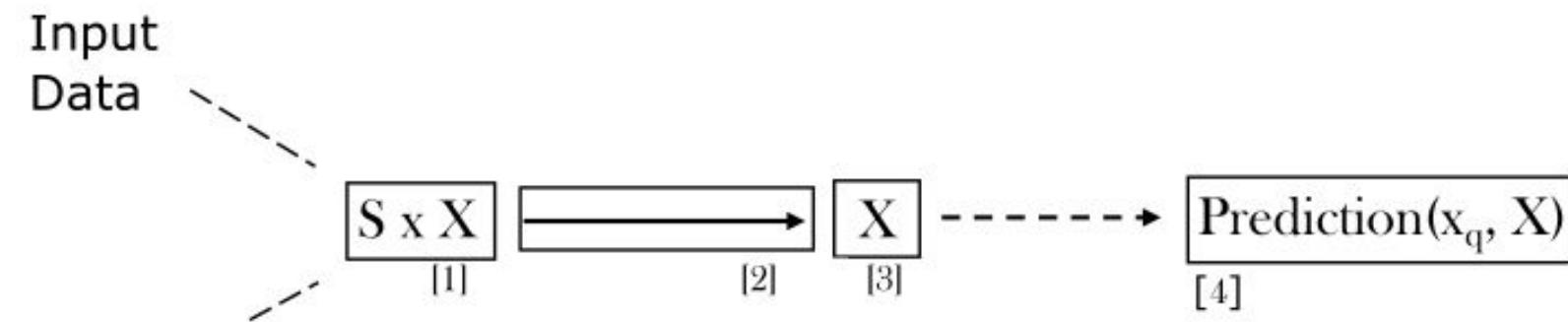
Effective for non-Euclidean data
(e.g., graphs, sensor arrays)



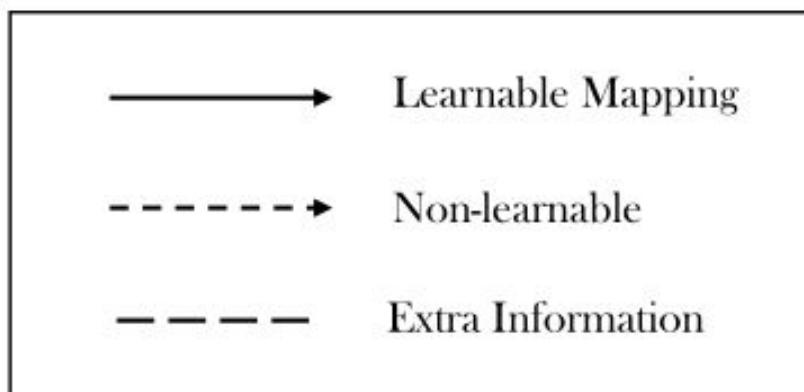
Relies on local information passing between nodes.

Relaxed conditions on the spatial regularity of data.

GNN: Architecture

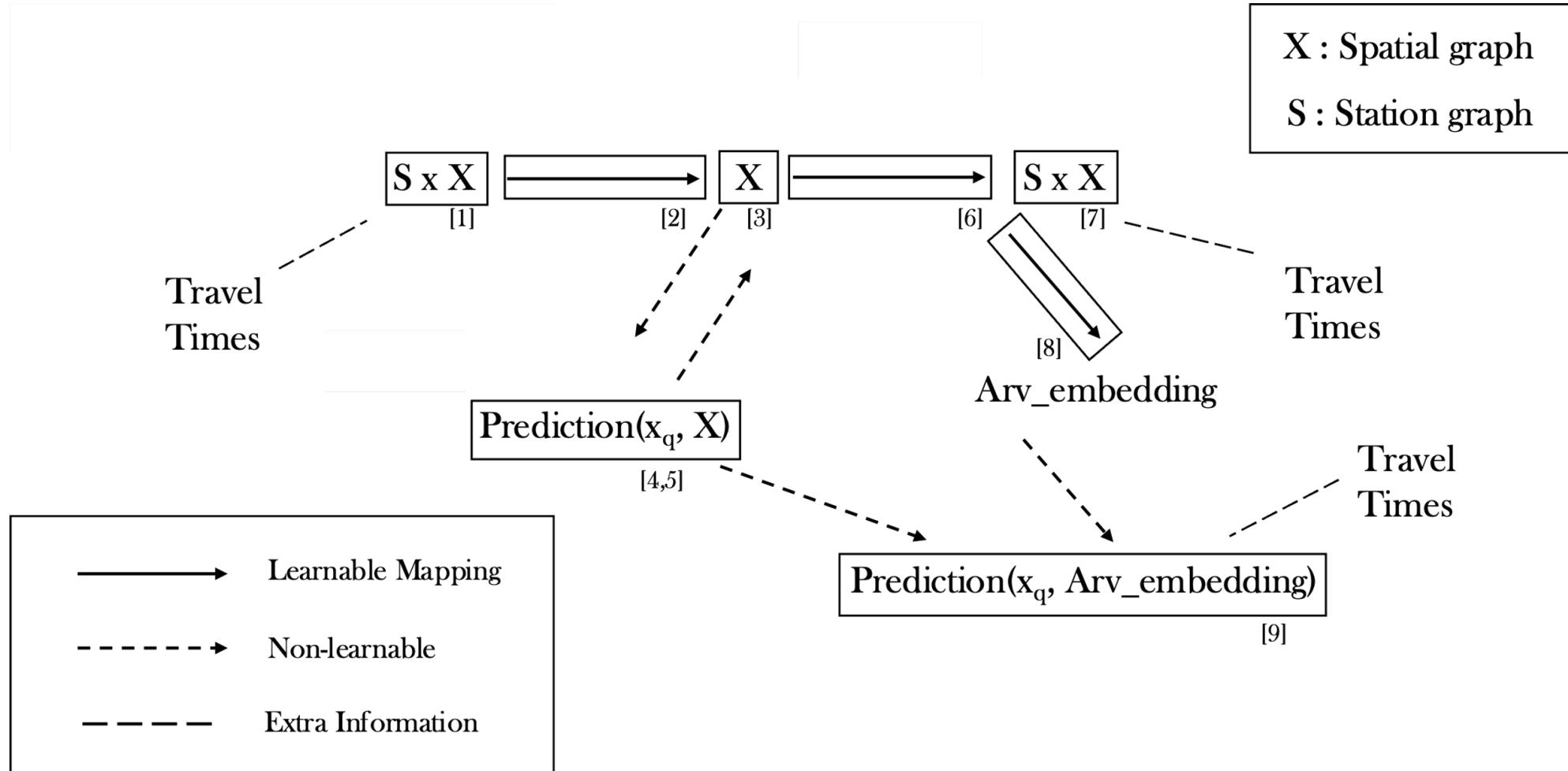


Travel
Times

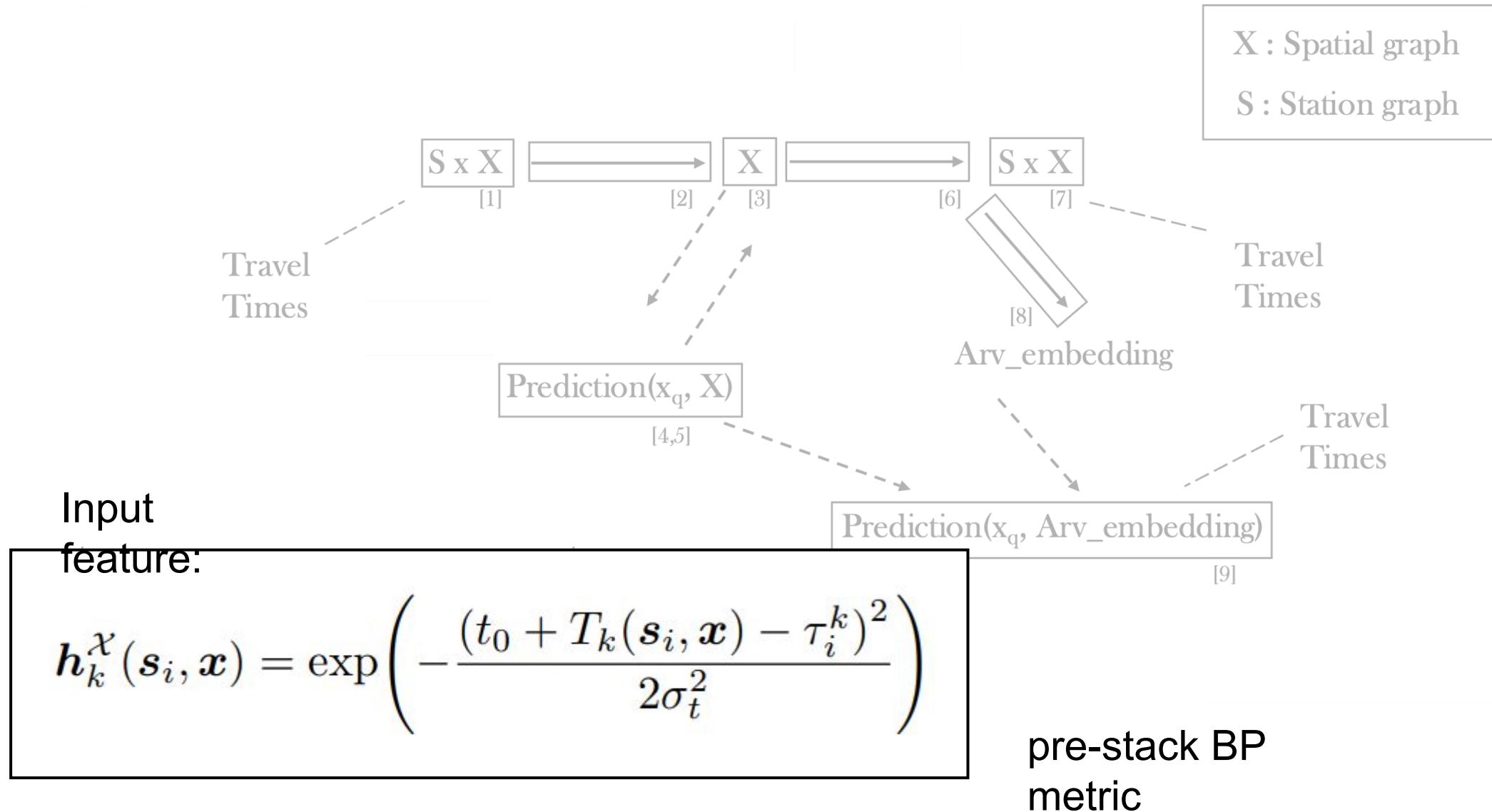


X : Spatial graph
 S : Station graph

GENIE: Architecture



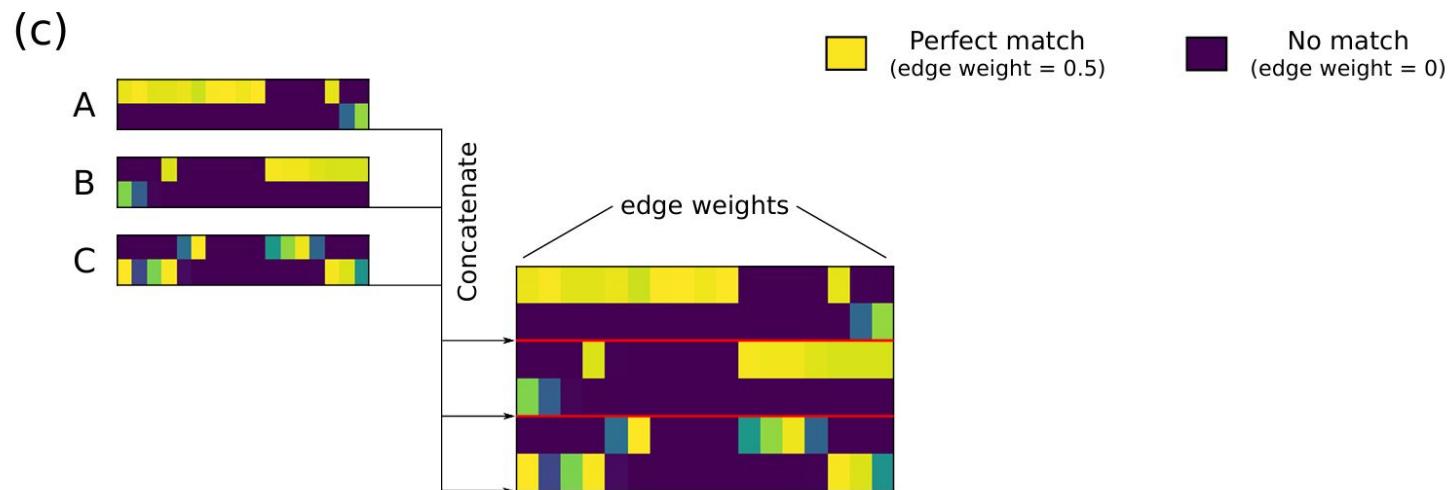
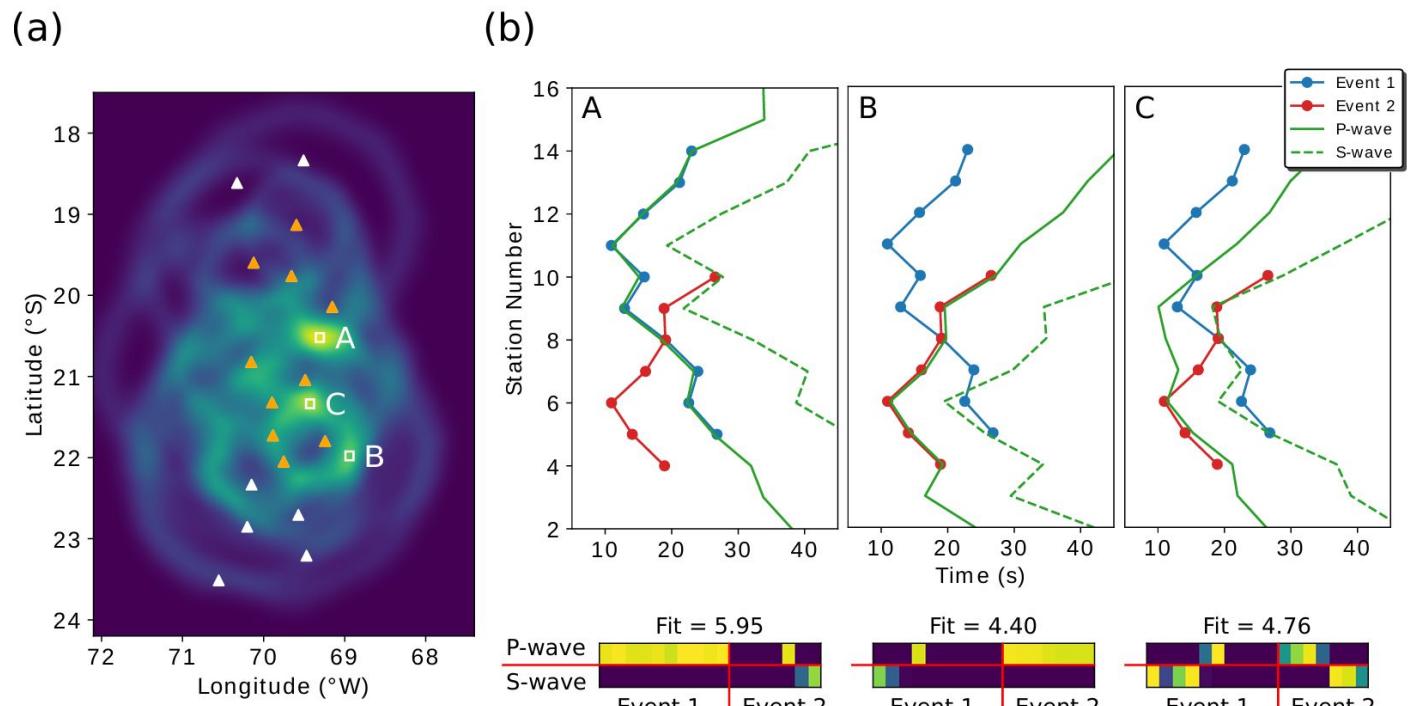
GENIE: Architecture



GENIE: Architecture

Strengths

- Input feature is the **misfit** between observed and theoretical arrivals
- Doesn't have to "learn" velocity model (unlike PhaseLink)
- "Knows" the relative position of stations, and weights them differently (unlike back-projection)



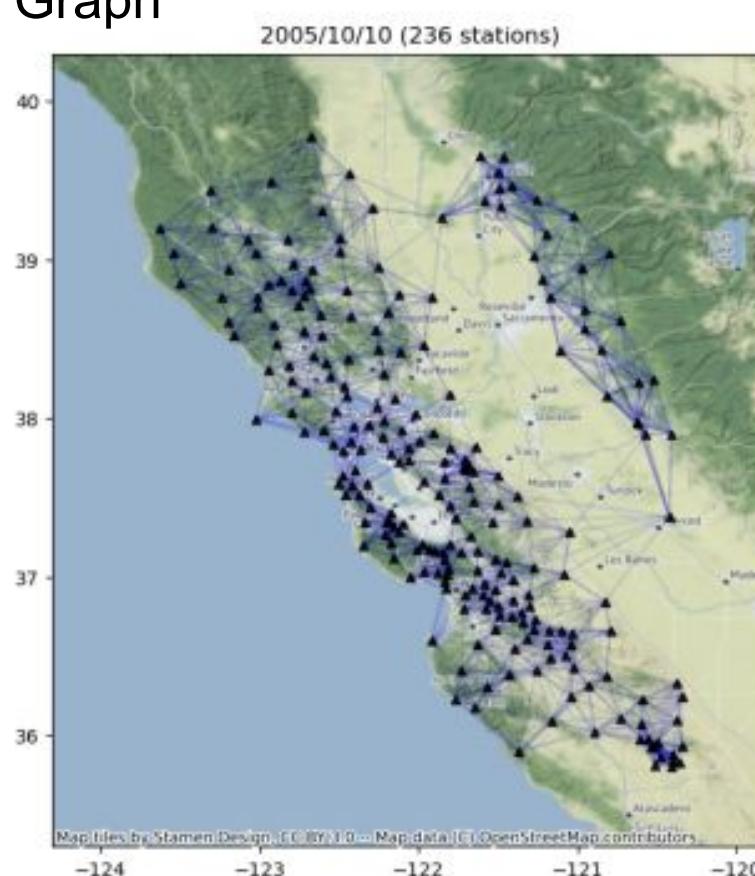
GENIE: Architecture

Strengths

:

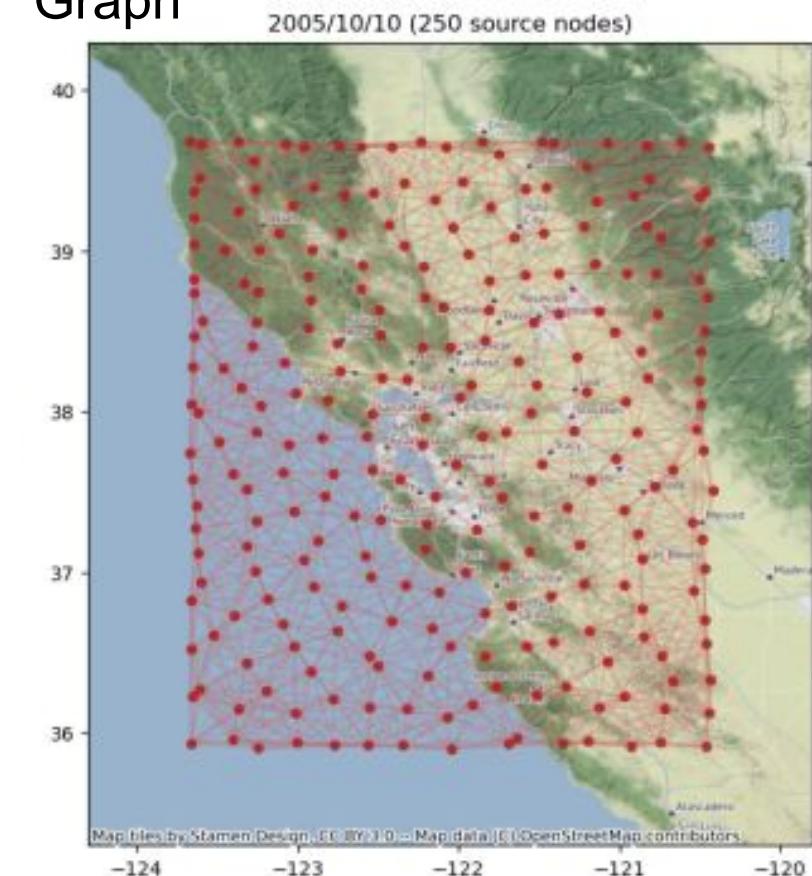
- Input feature is the **misfit** between observed and theoretical arrivals
- Doesn't have to "learn" velocity model (unlike PhaseLink)
- "Knows" the relative position of stations, and weights them differently (unlike back-projection)

Station Graph



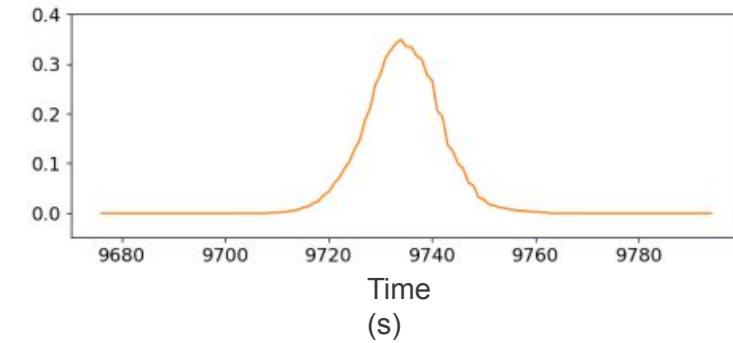
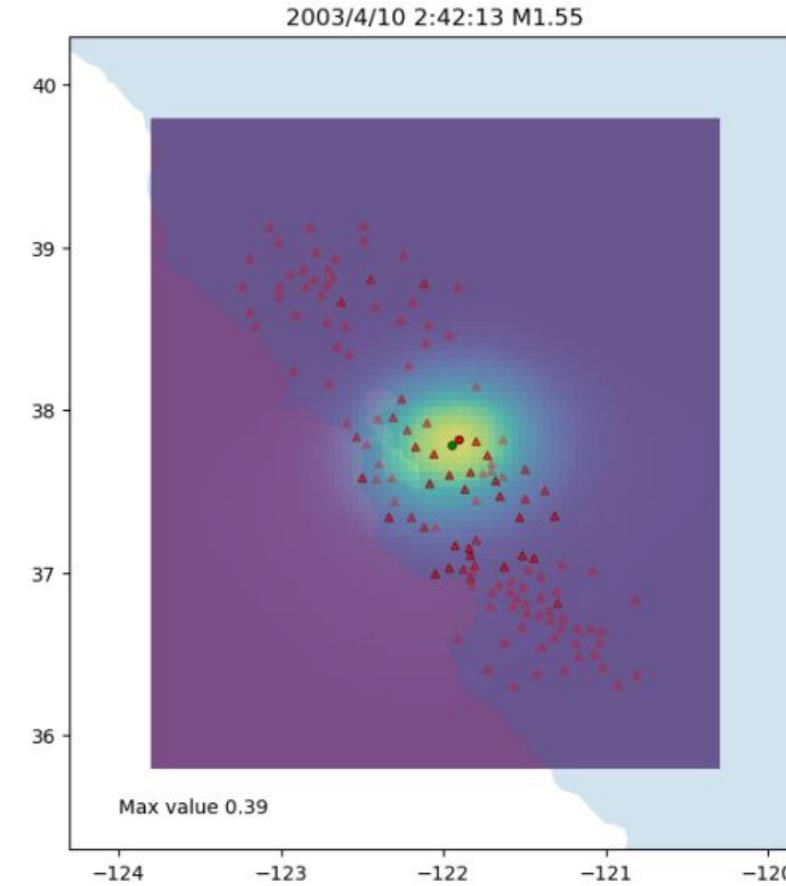
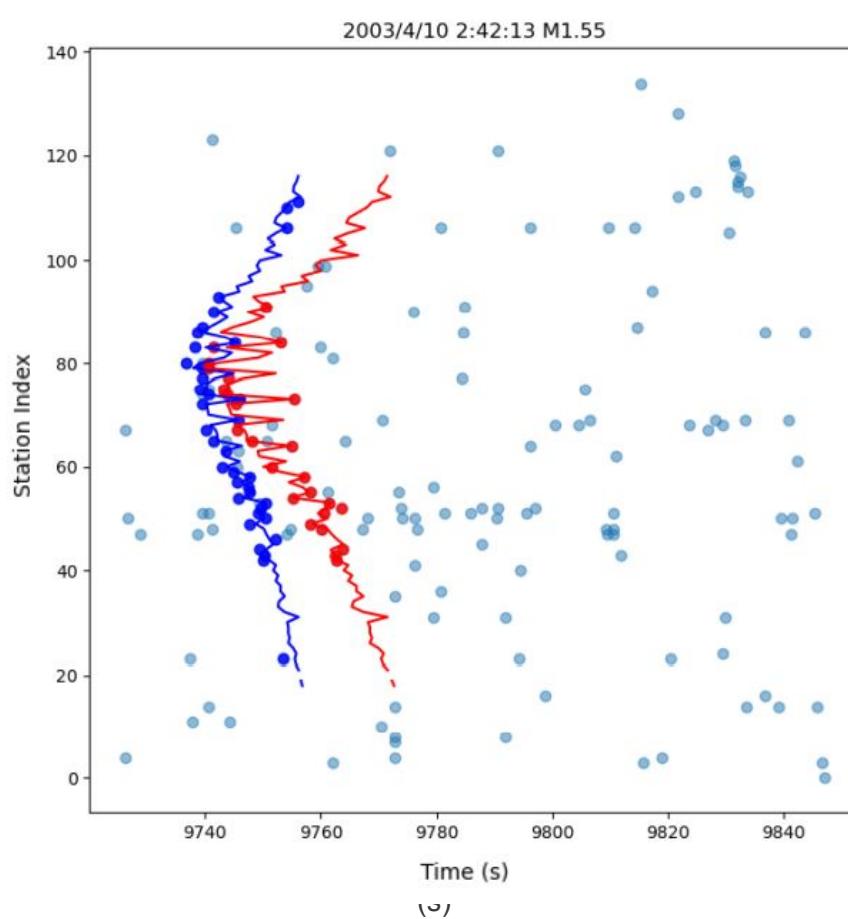
8-nearest-neighbors

Source Graph



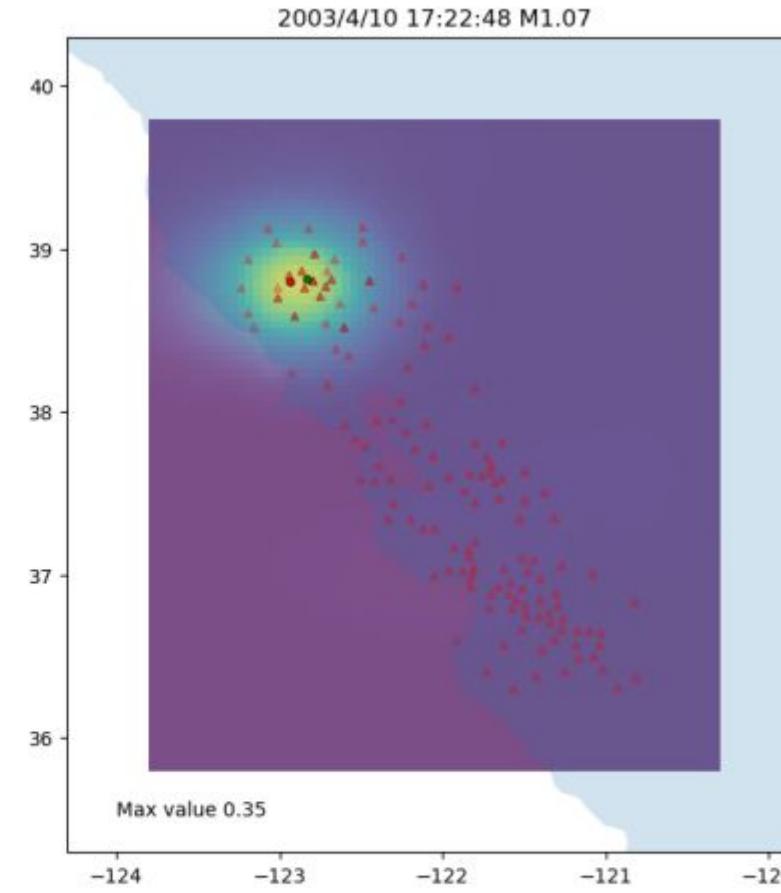
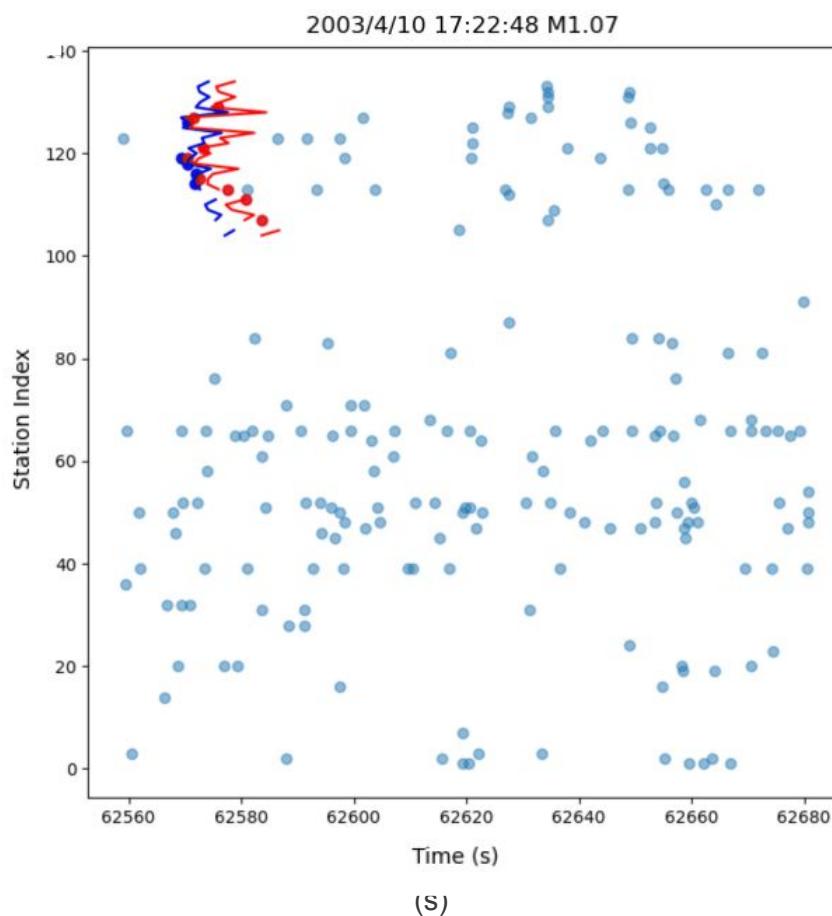
15-nearest-neighbors

Example Detections

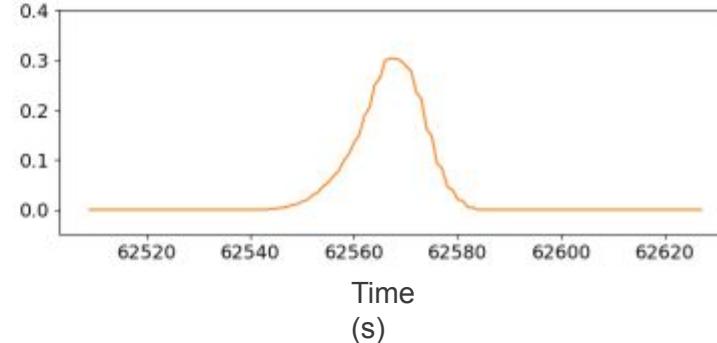


Spatio-temporally localized known **M1.5** earthquake on **Calaveras Fault**, and obtained P and S wave associations

Example Detections

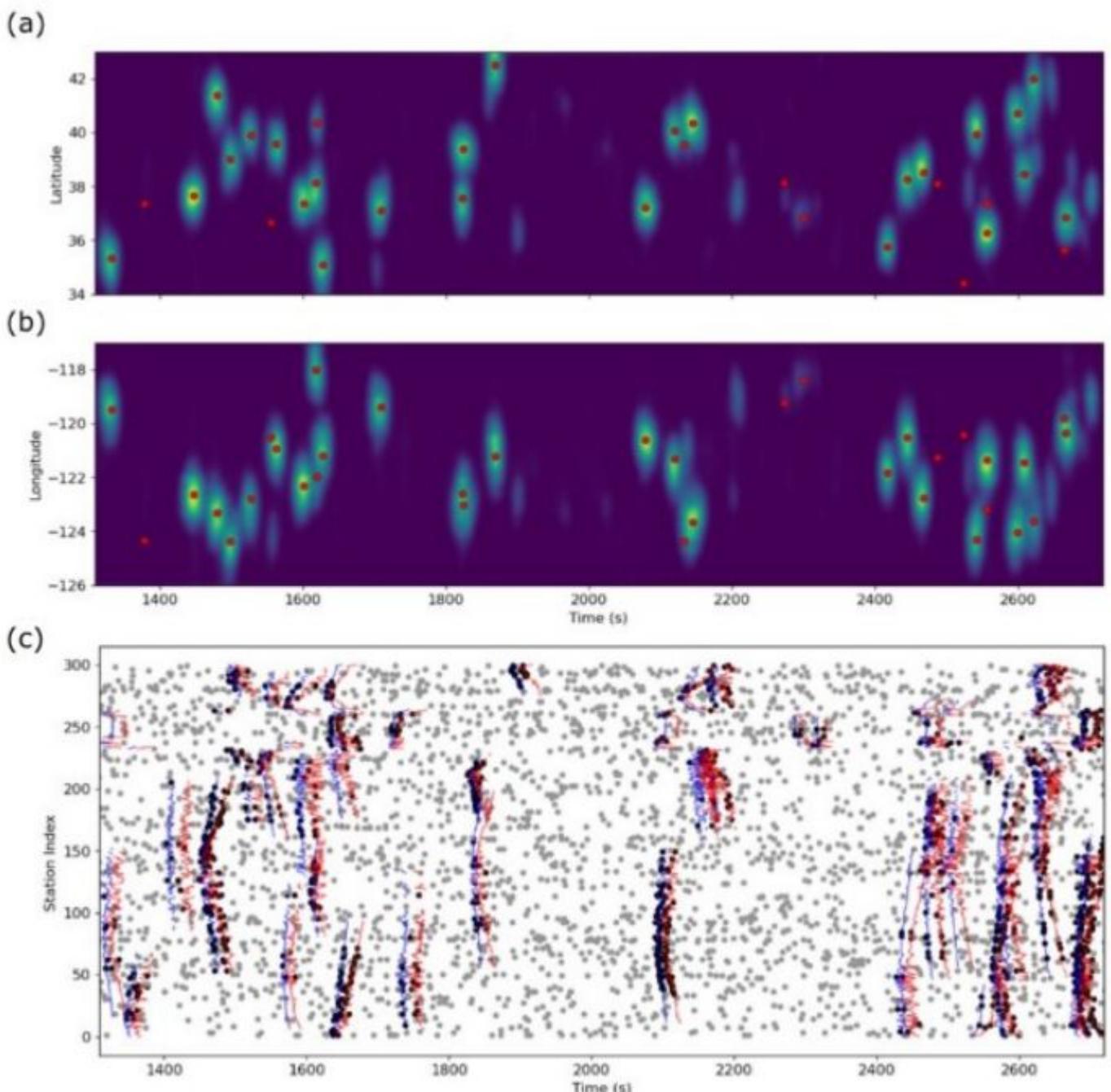


Spatio-temporally localized known **M1.1** earthquake at **Geysers**, and obtained P and S wave associations

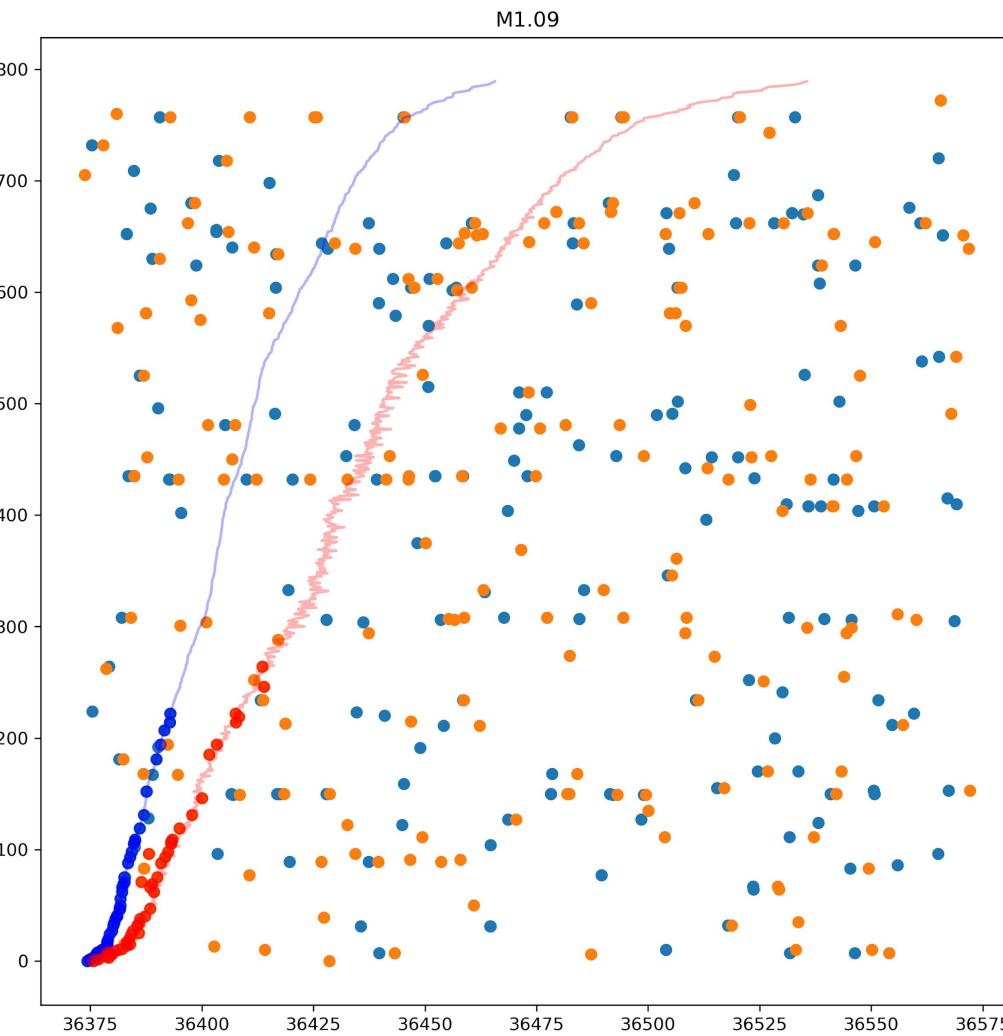
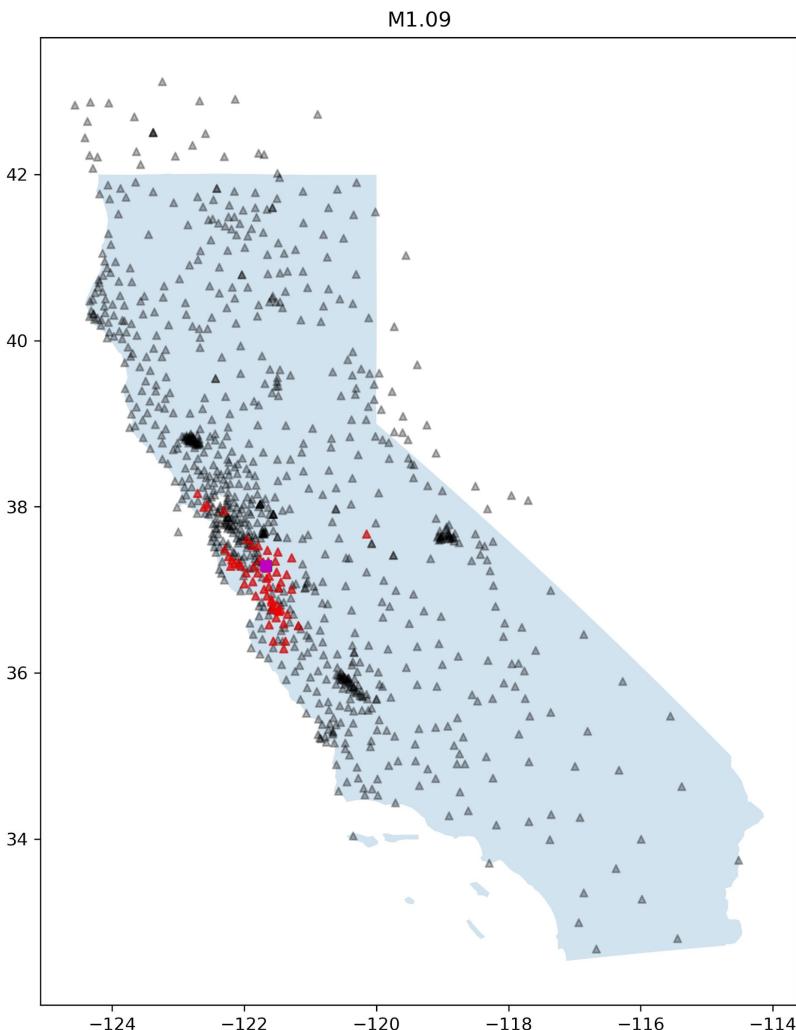


Example Detections

- Continuous space-time output
- Can handle even closely overlapping events and many false/noisy picks

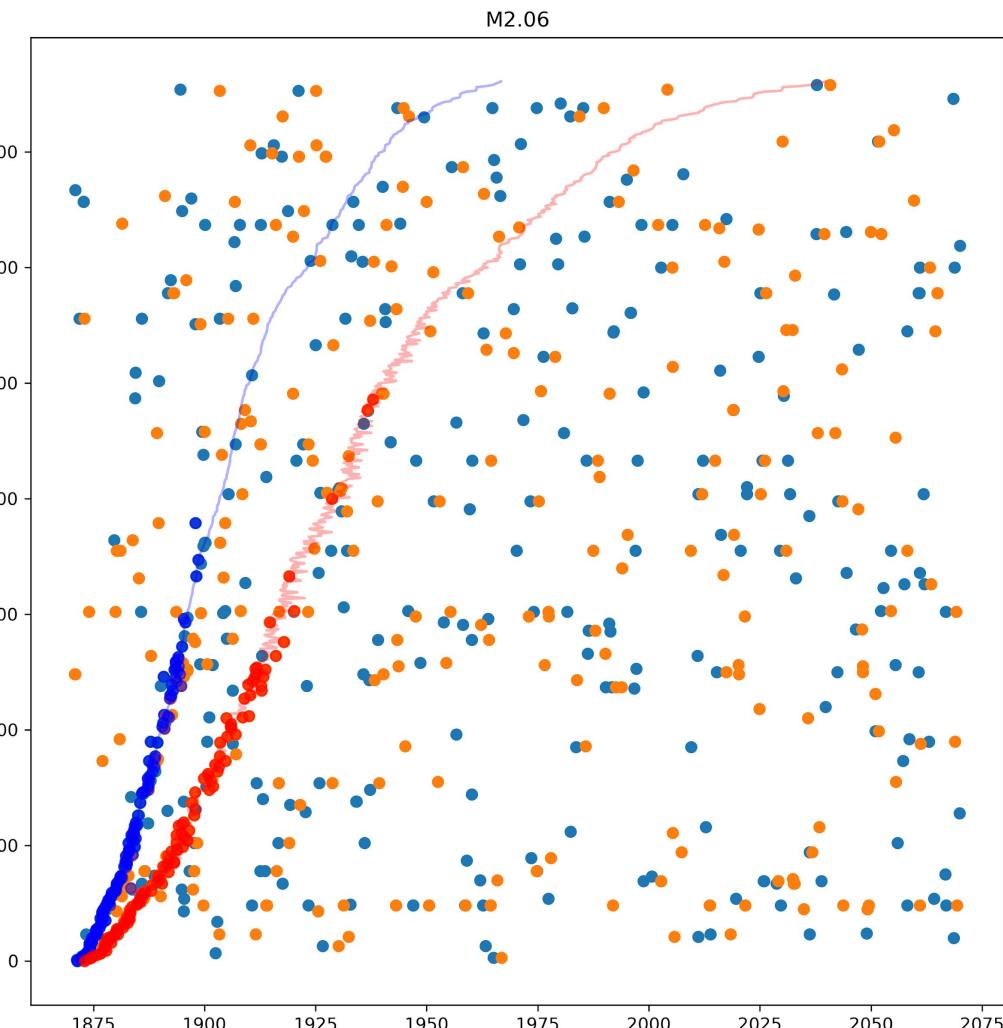
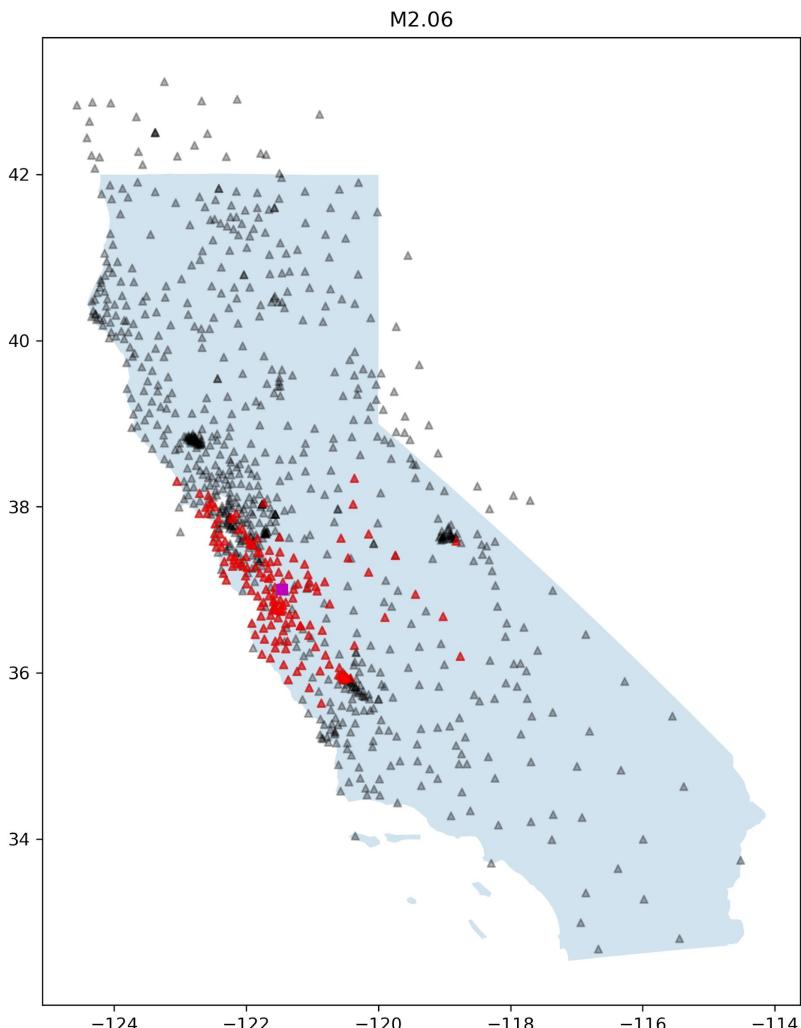


Example Detections



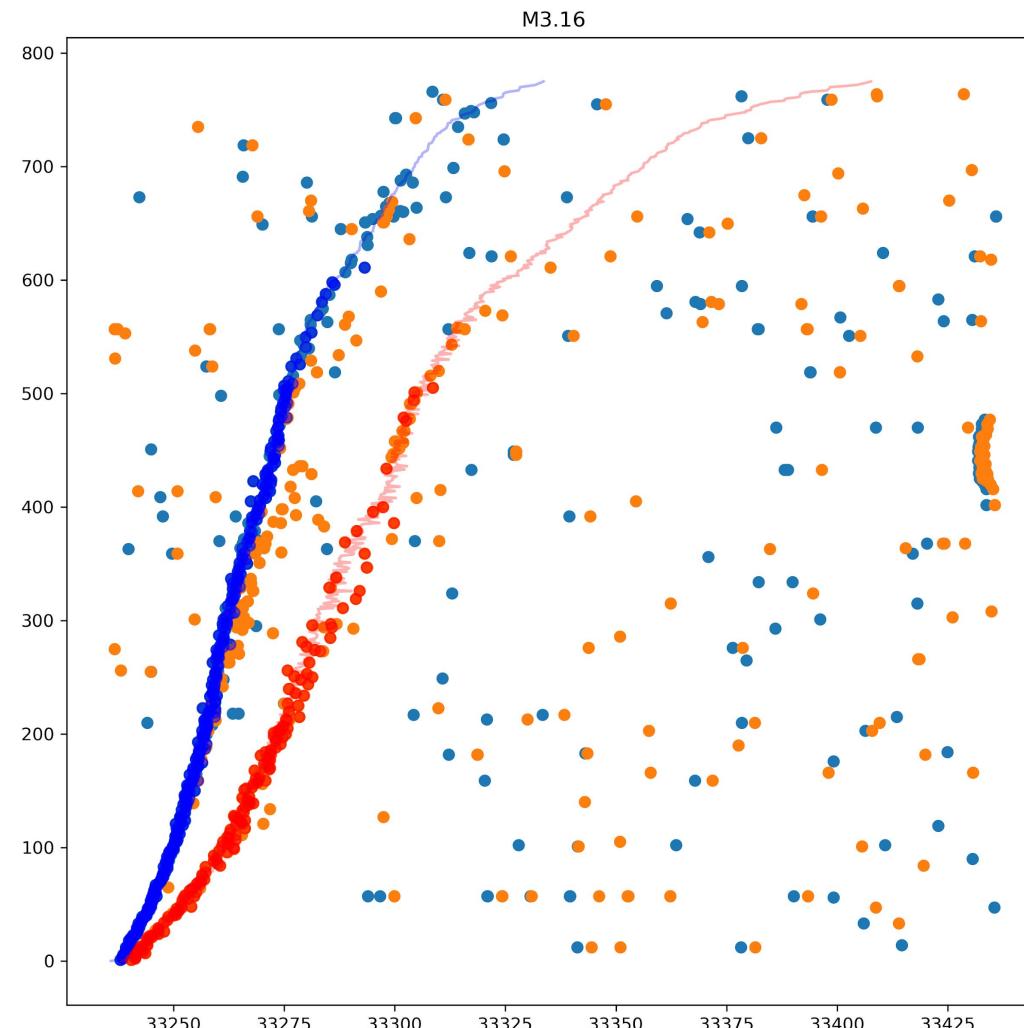
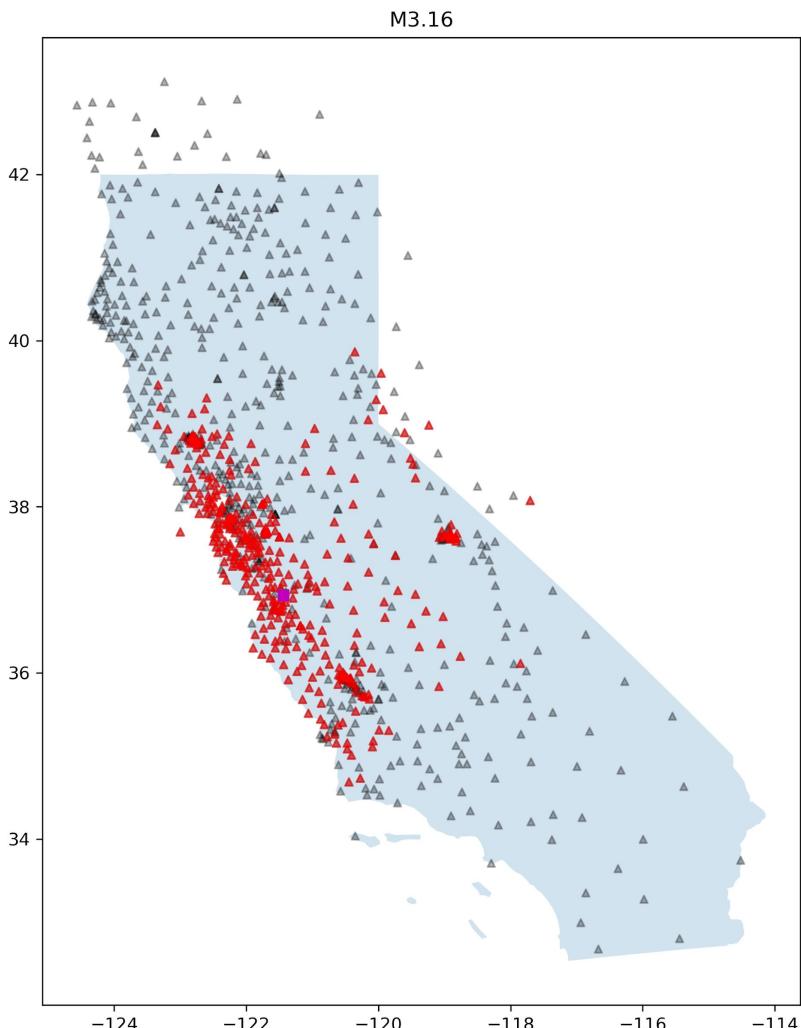
M1, Bay
Area

Example Detections



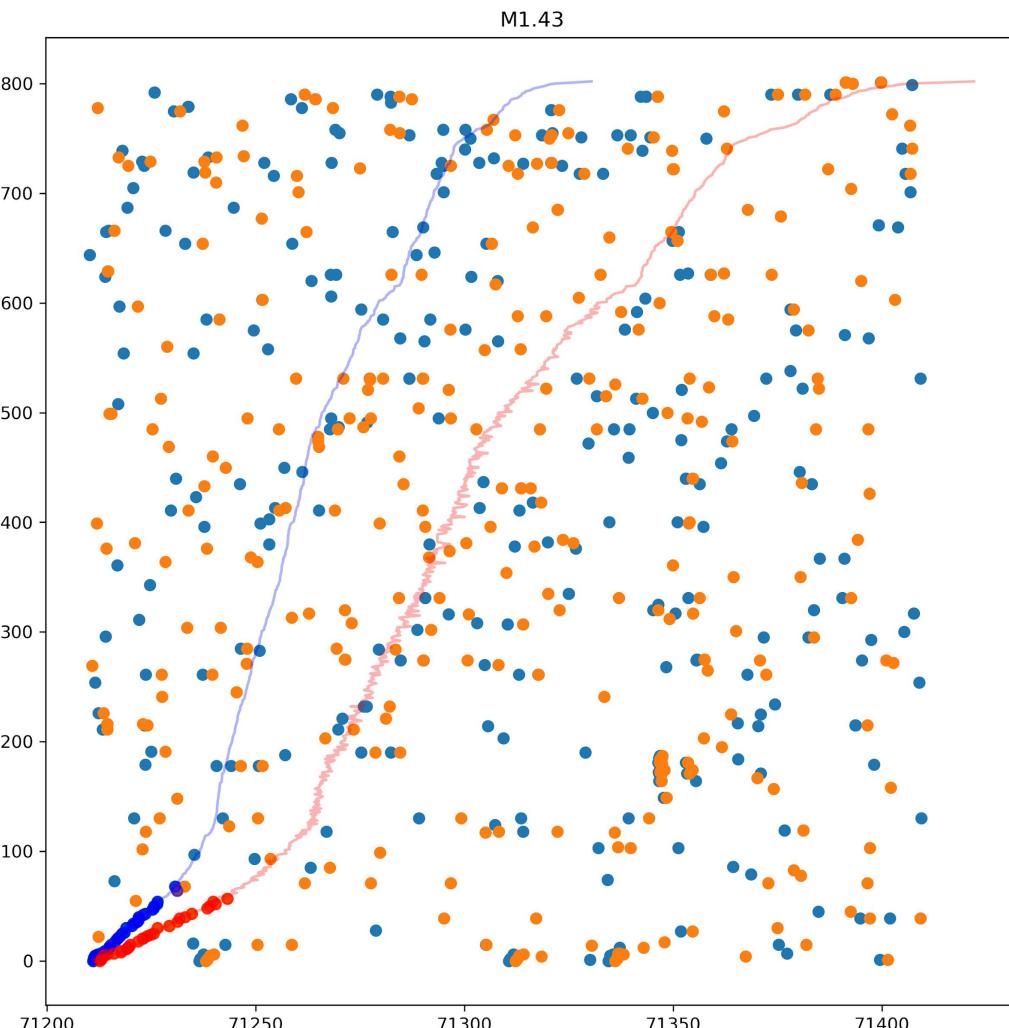
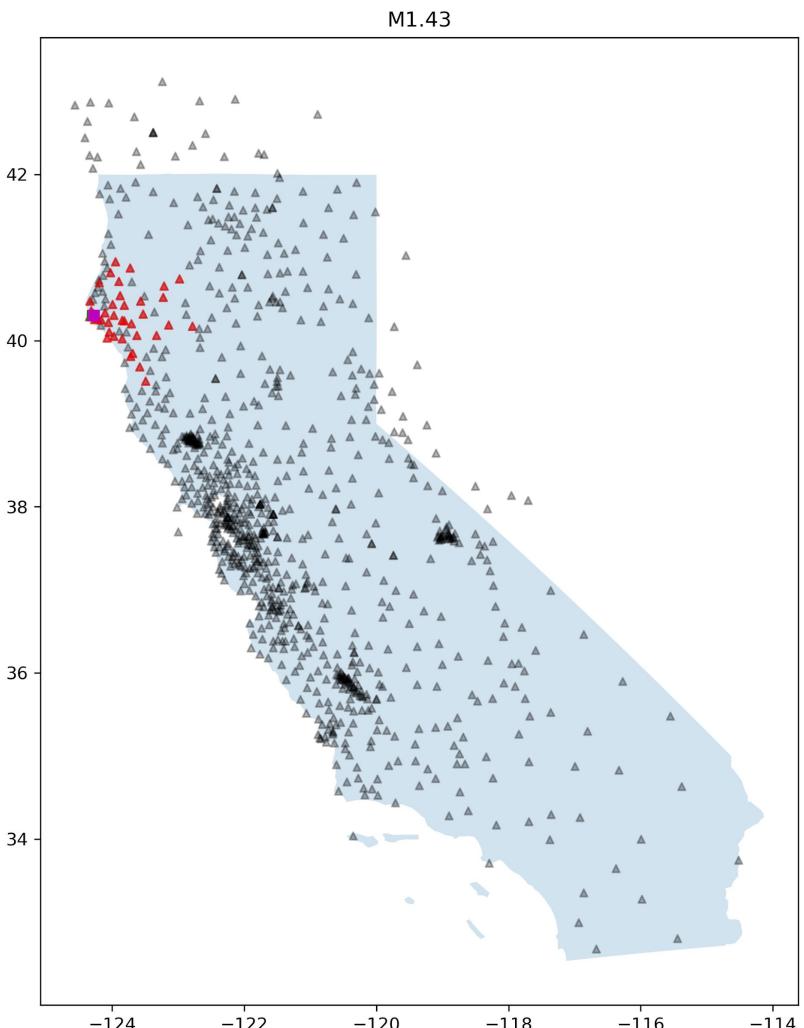
M2, Bay
Area

Example Detections



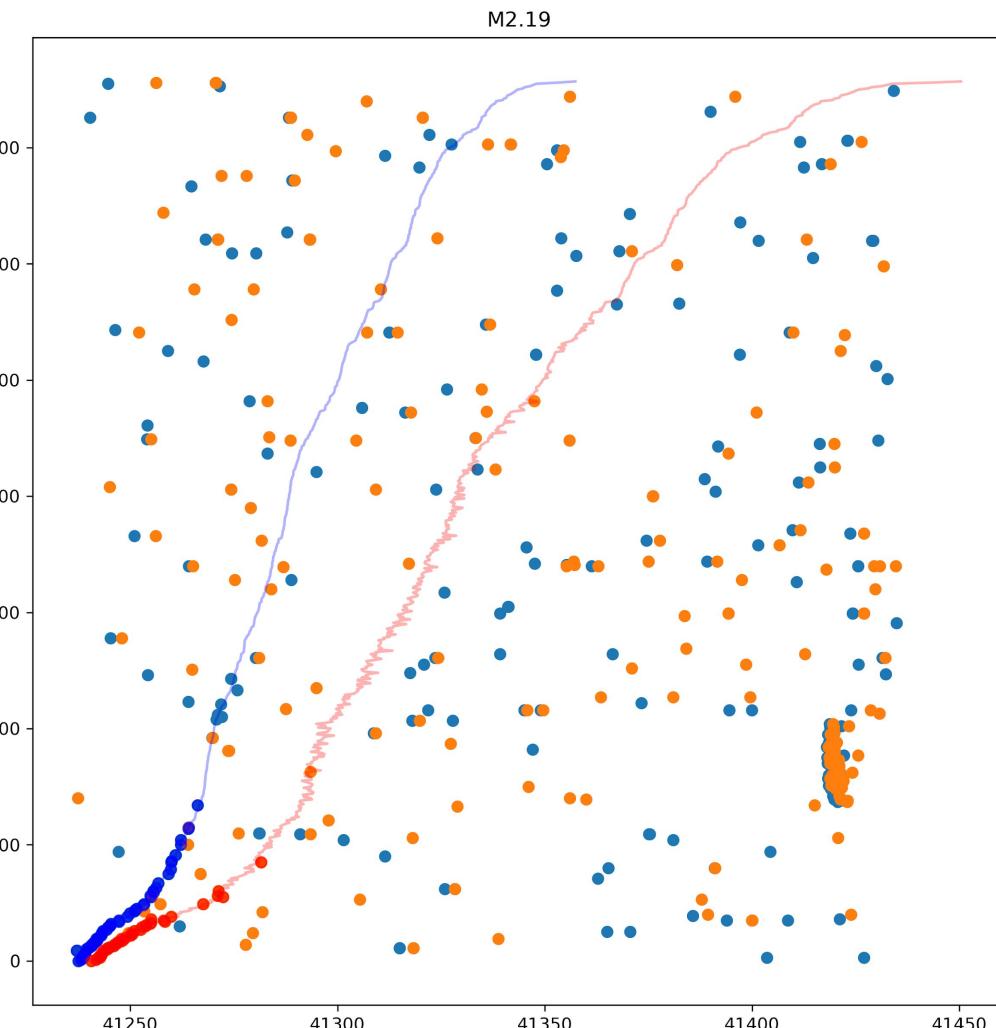
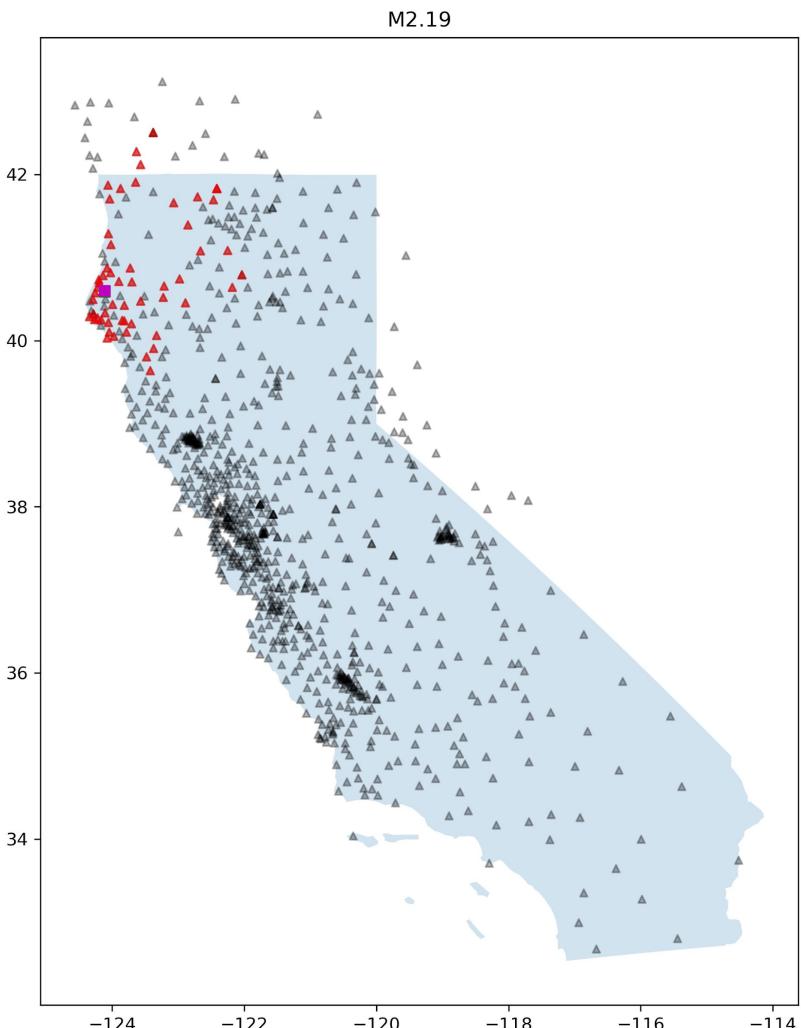
M3, Bay
Area

Example Detections



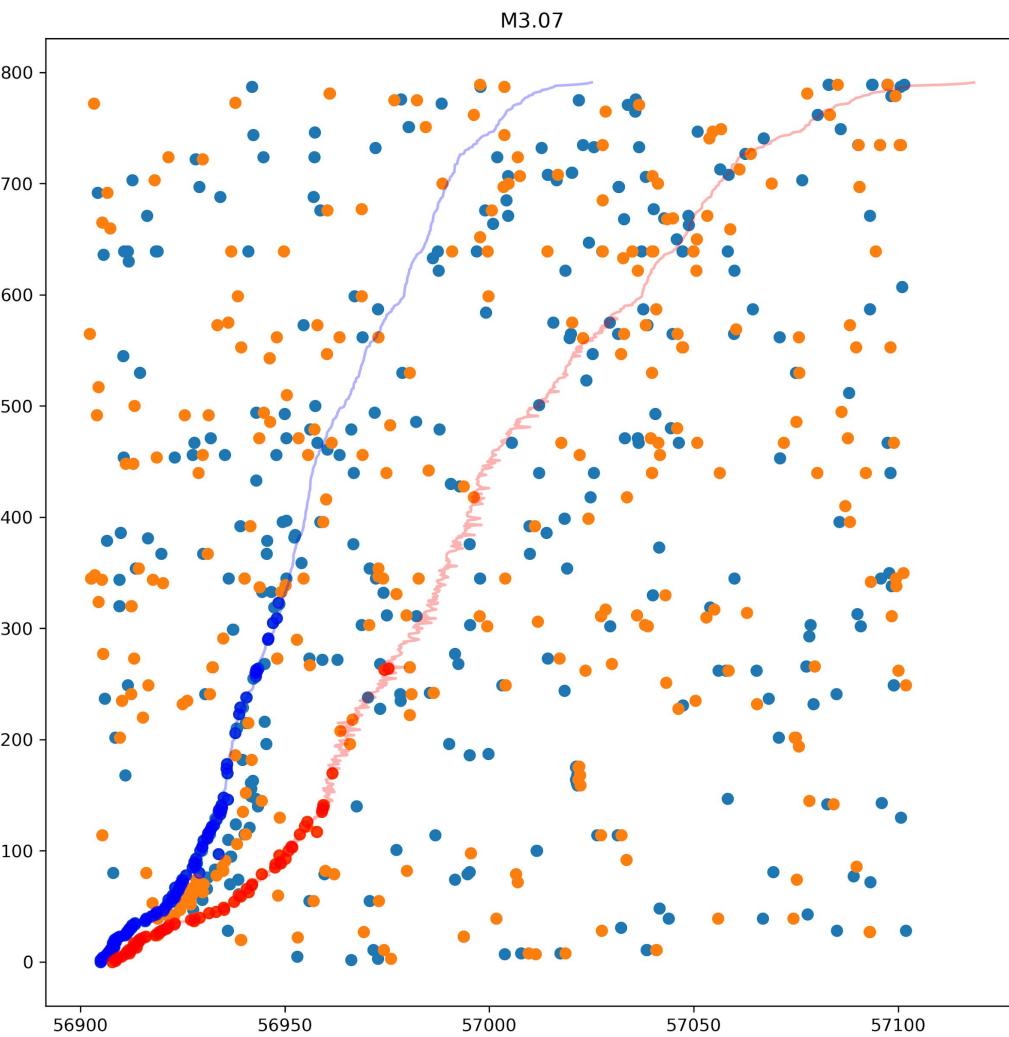
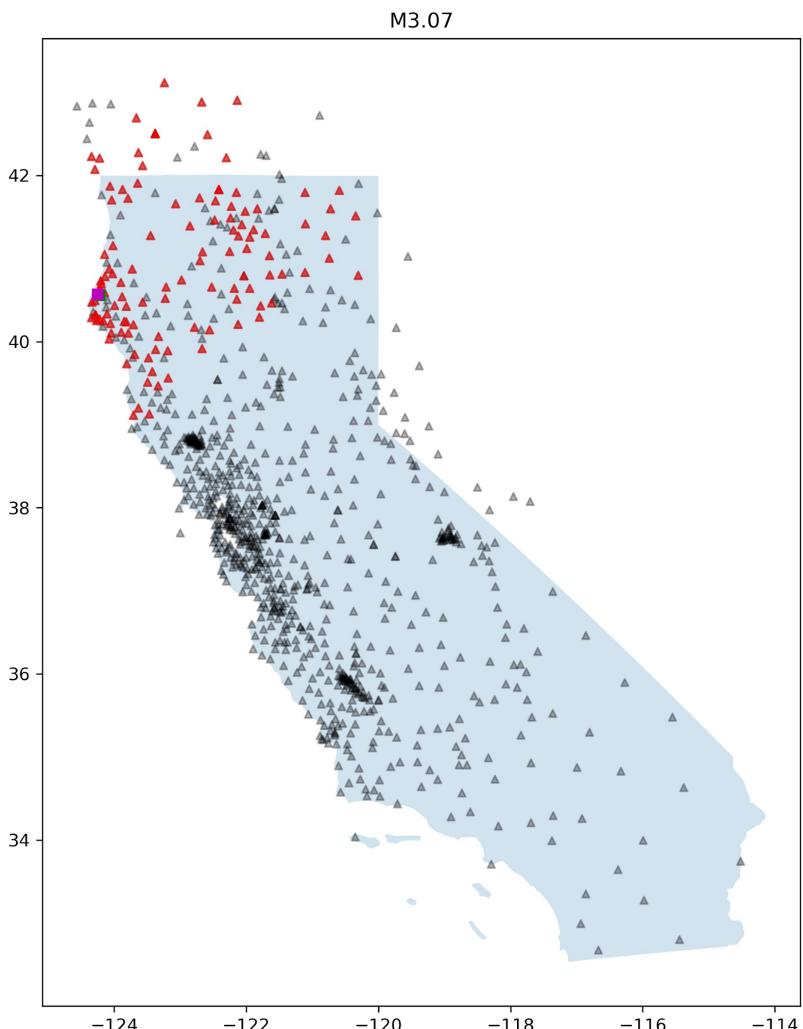
M1, Mendocino Triple
Junction

Example Detections



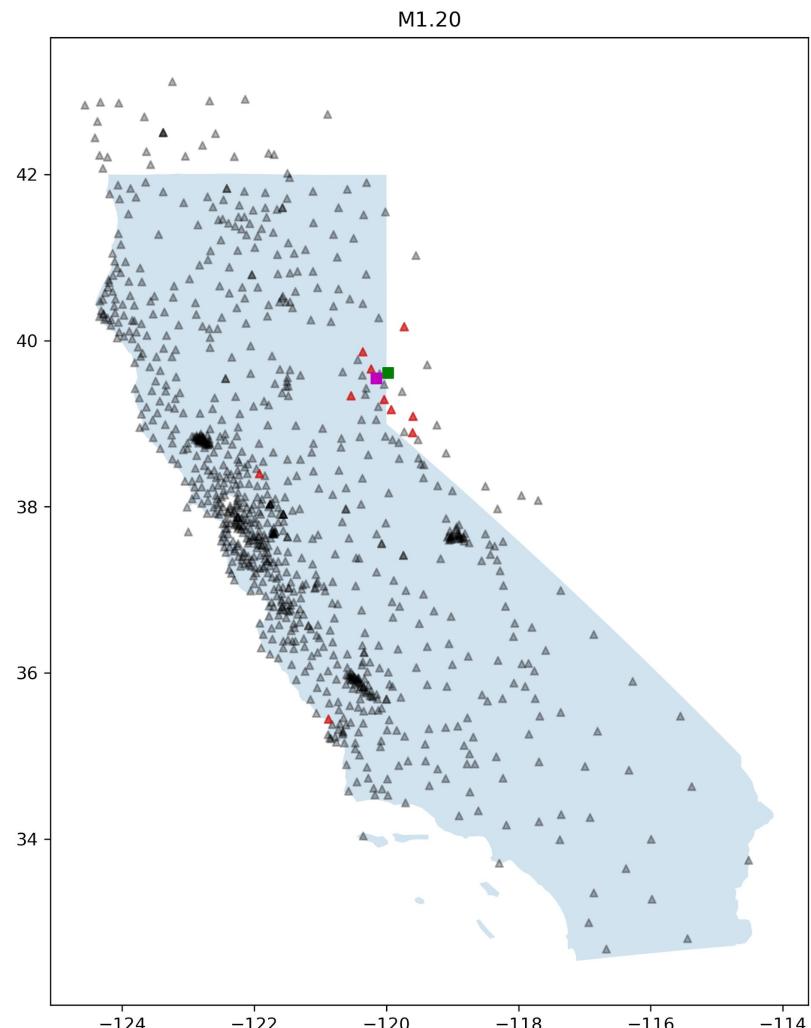
M2, Mendocino Triple
Junction

Example Detections

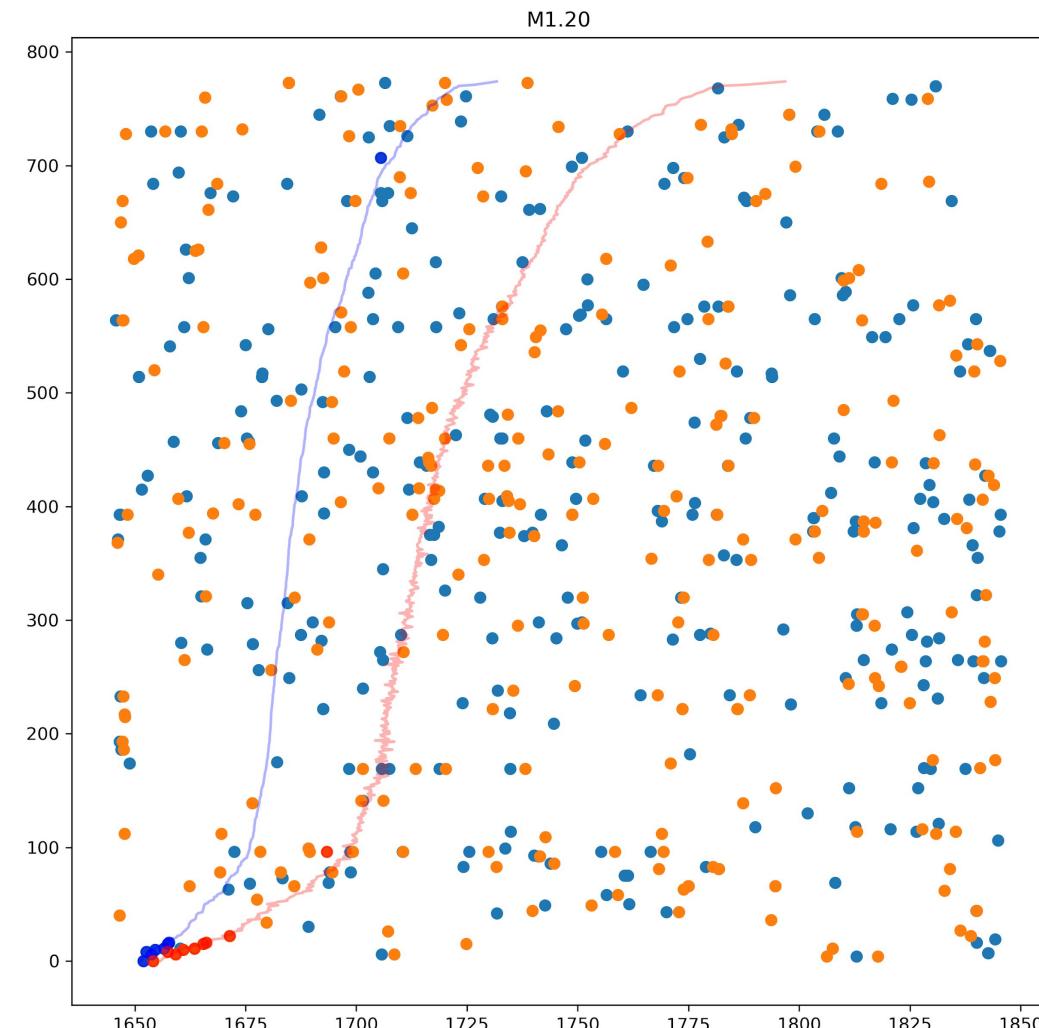


M3, Mendocino Triple
Junction

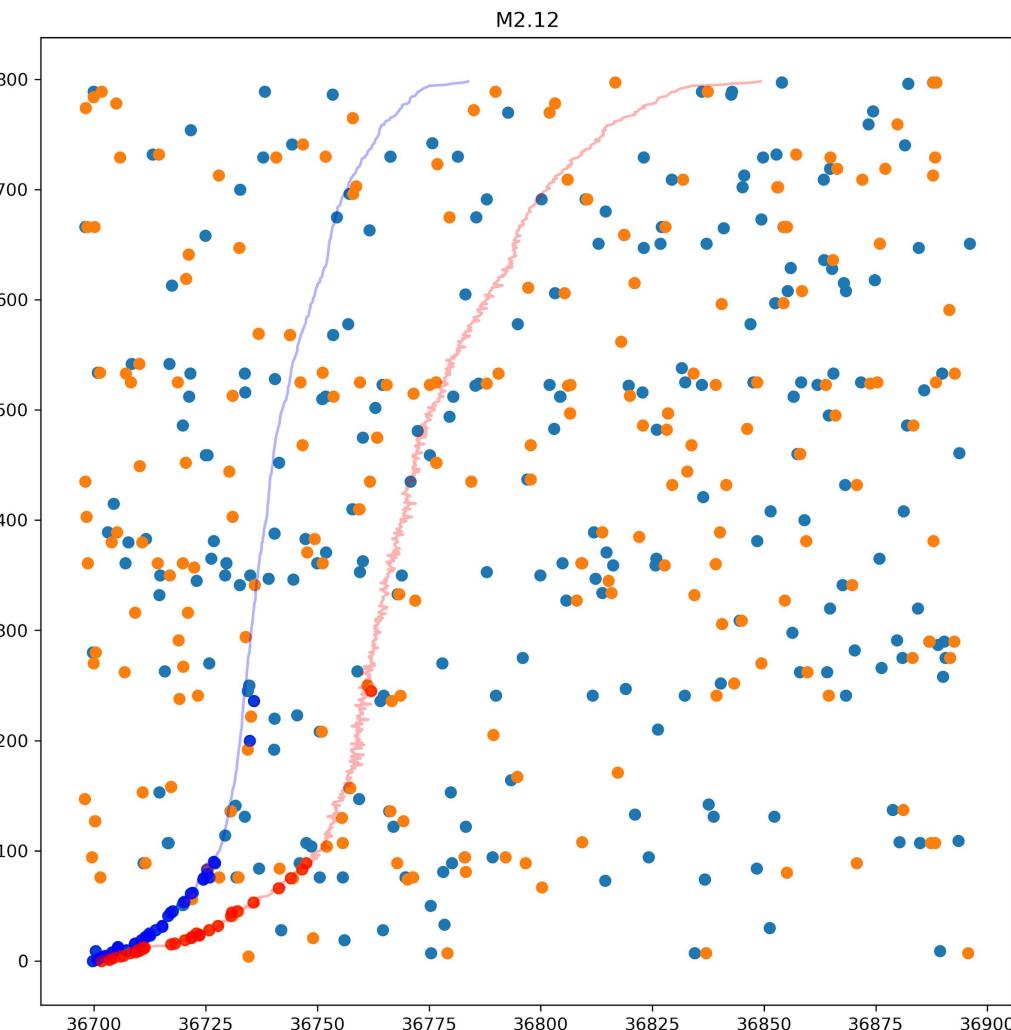
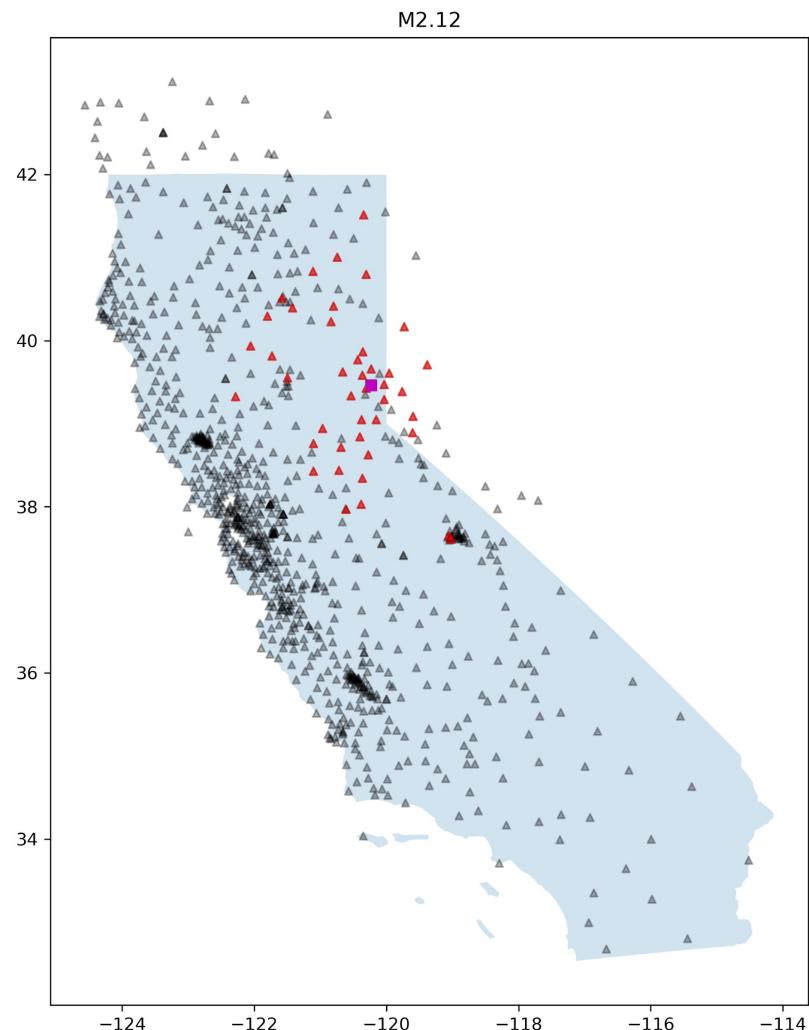
Example Detections



M1, California-Nevada
Border

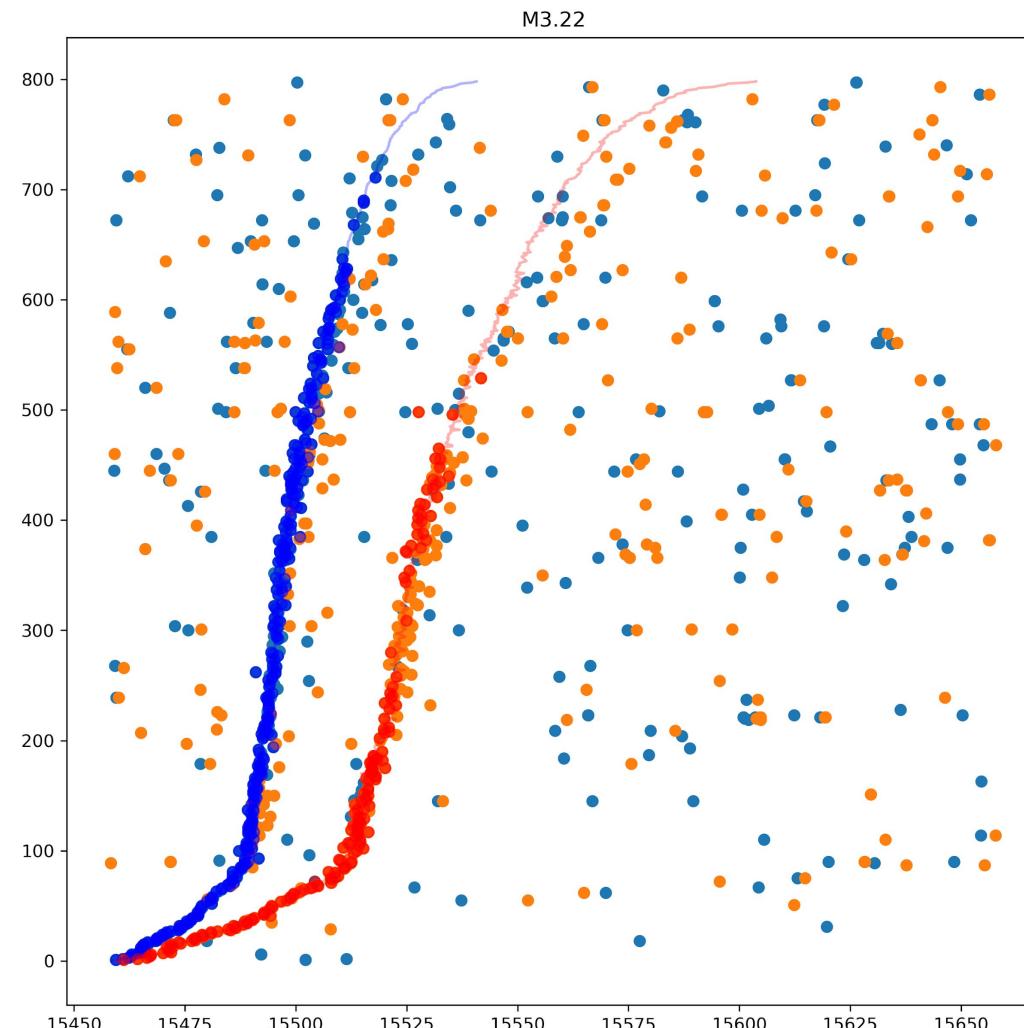
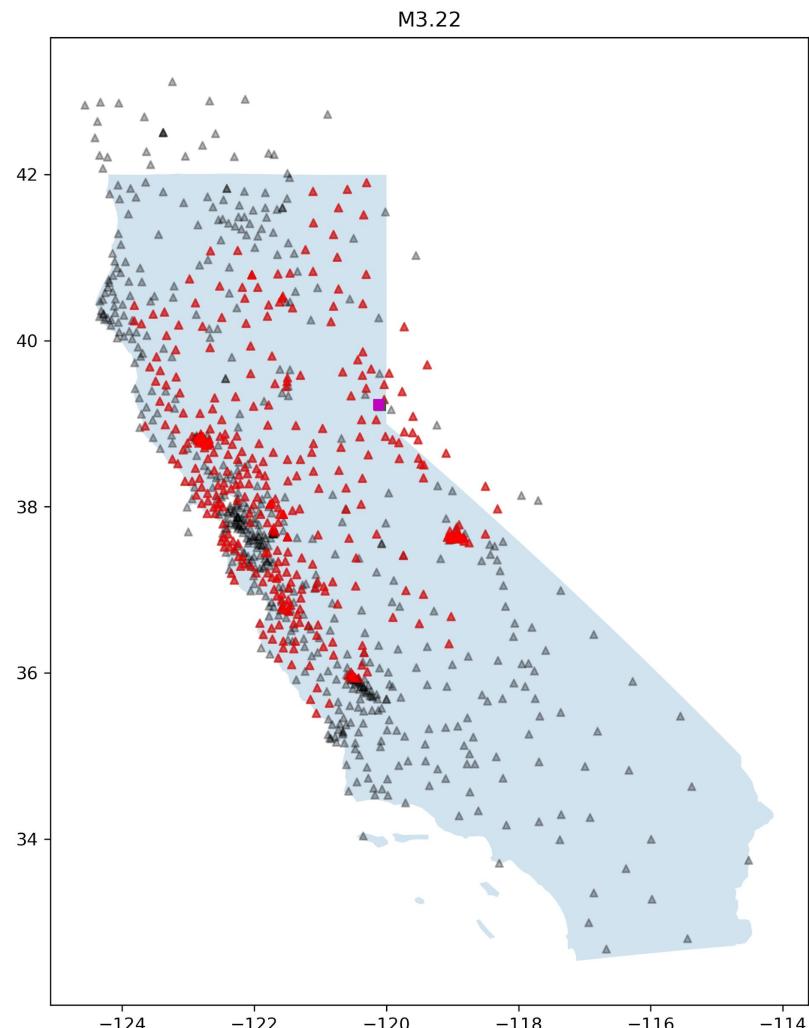


Example Detections



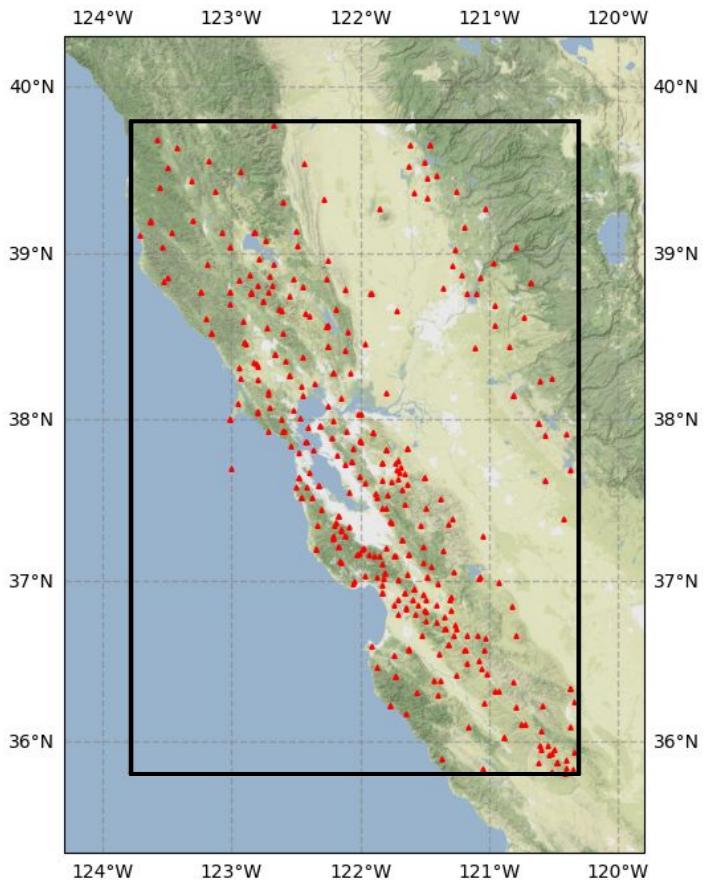
M2, California-Nevada
Border

Example Detections

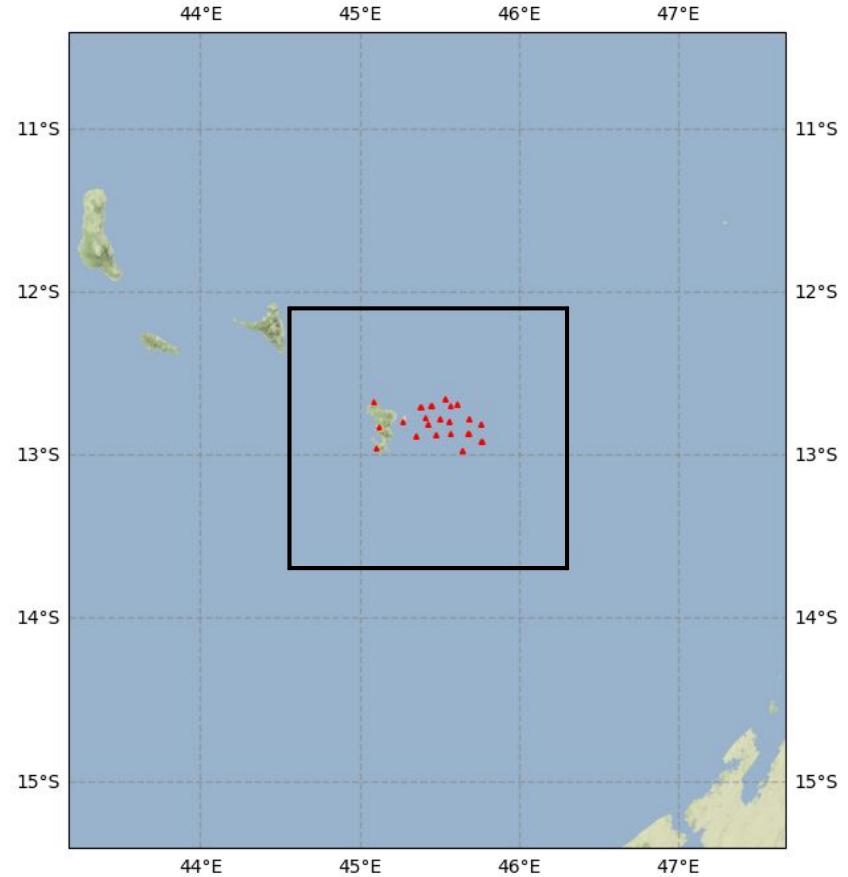


M3, California-Nevada
Border

Comparisons of Associators



~250
stations
~100's events per
day

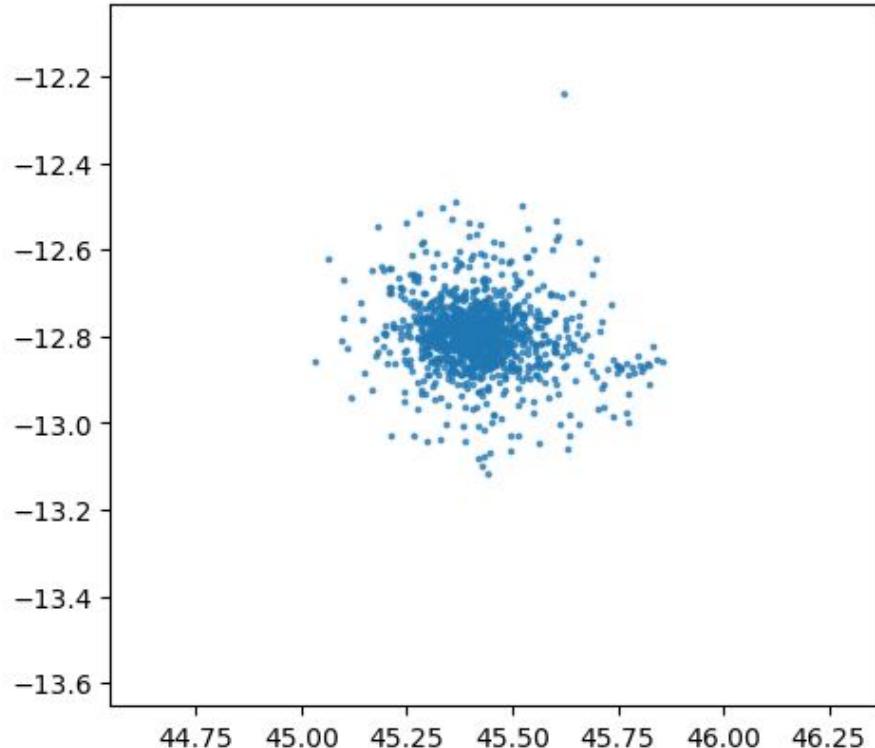


~1/4 scale, 25
stations
1000's events per
day

Spatial Localization

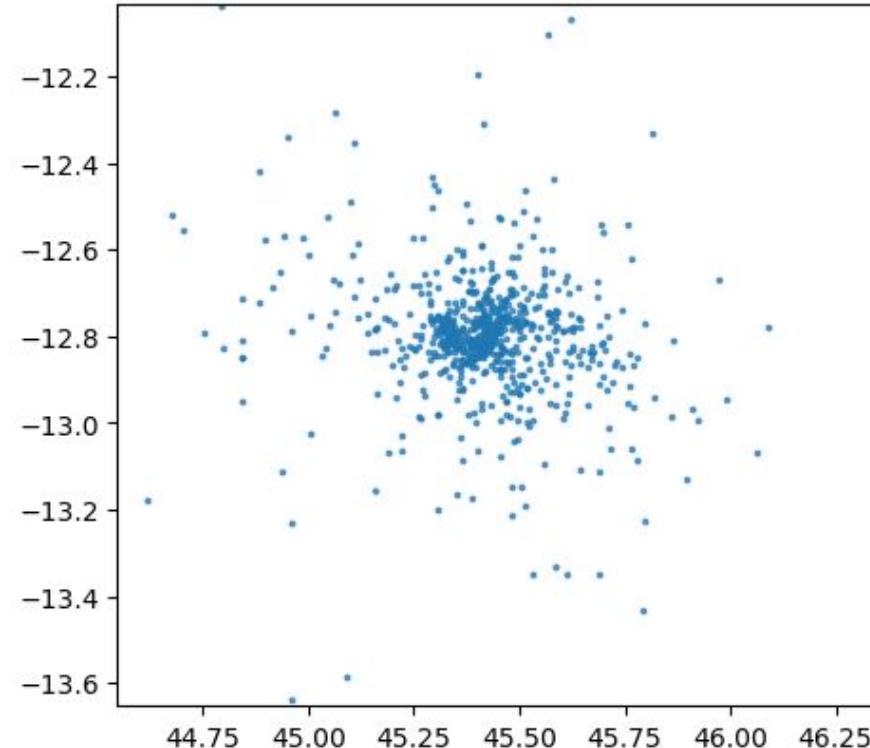
GENIE

Detected events : 1144



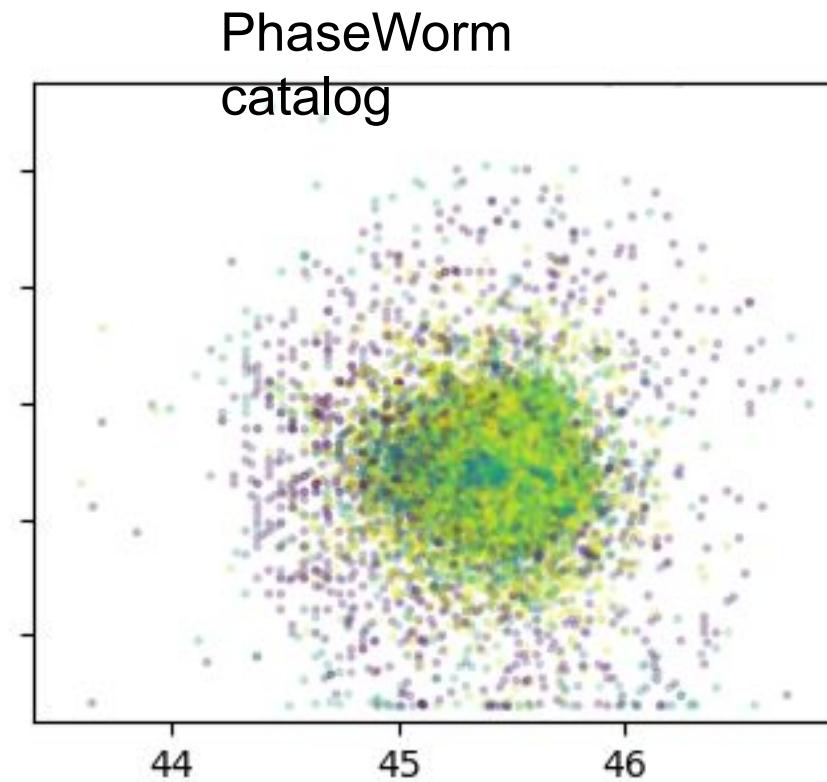
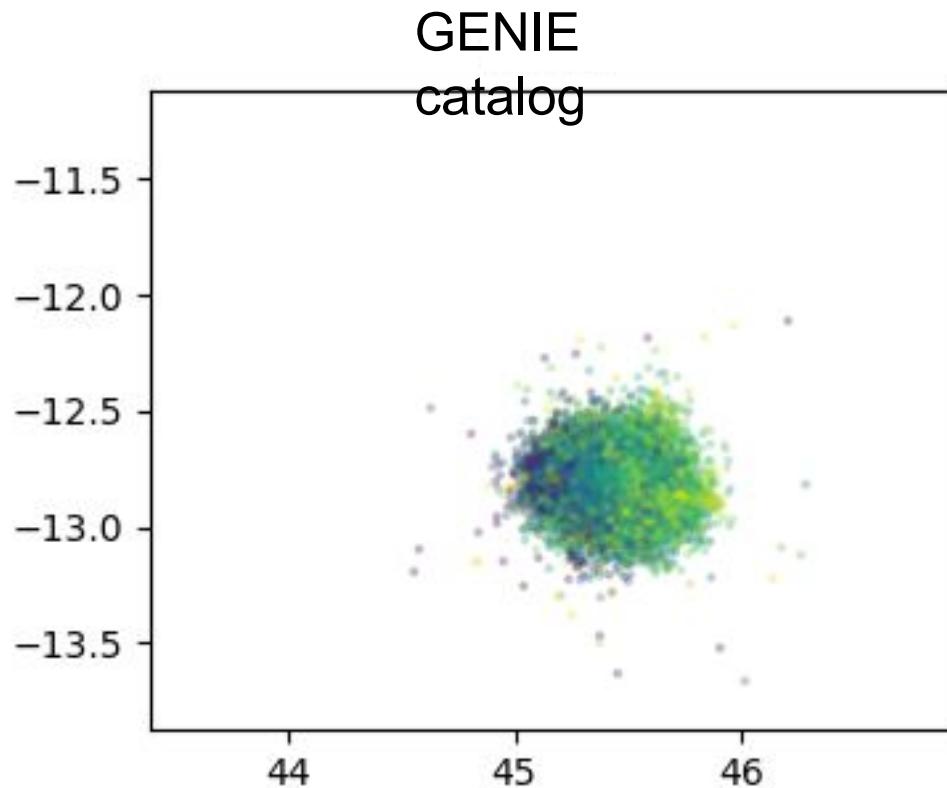
PhaseWorm

Known events : 727



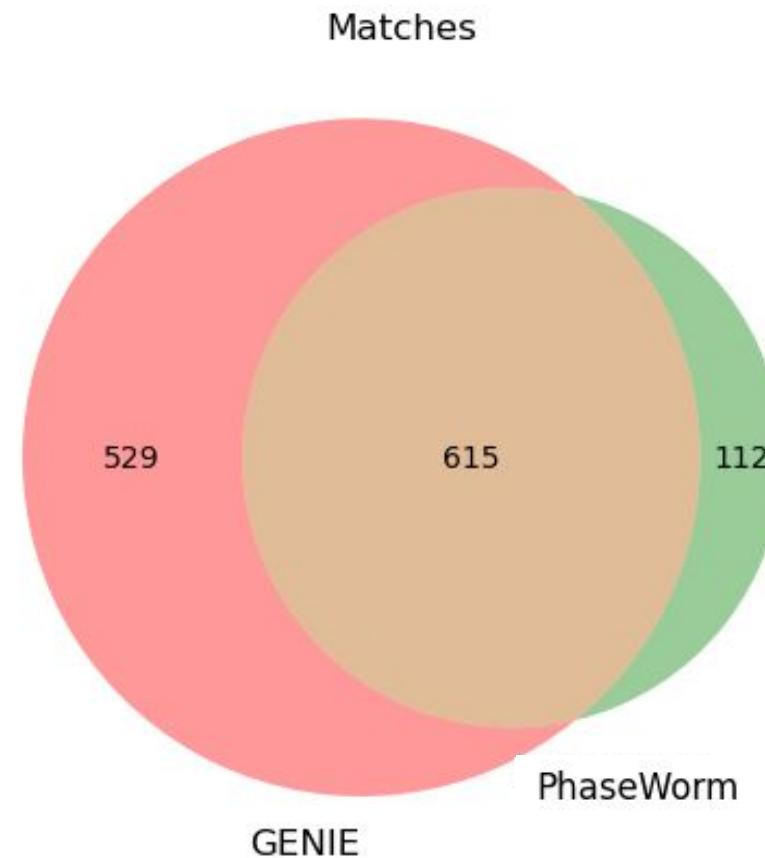
Less scatter in GENIE
catalog

Spatial Localization *(Full catalog)*



Event Comparison: Number of Events

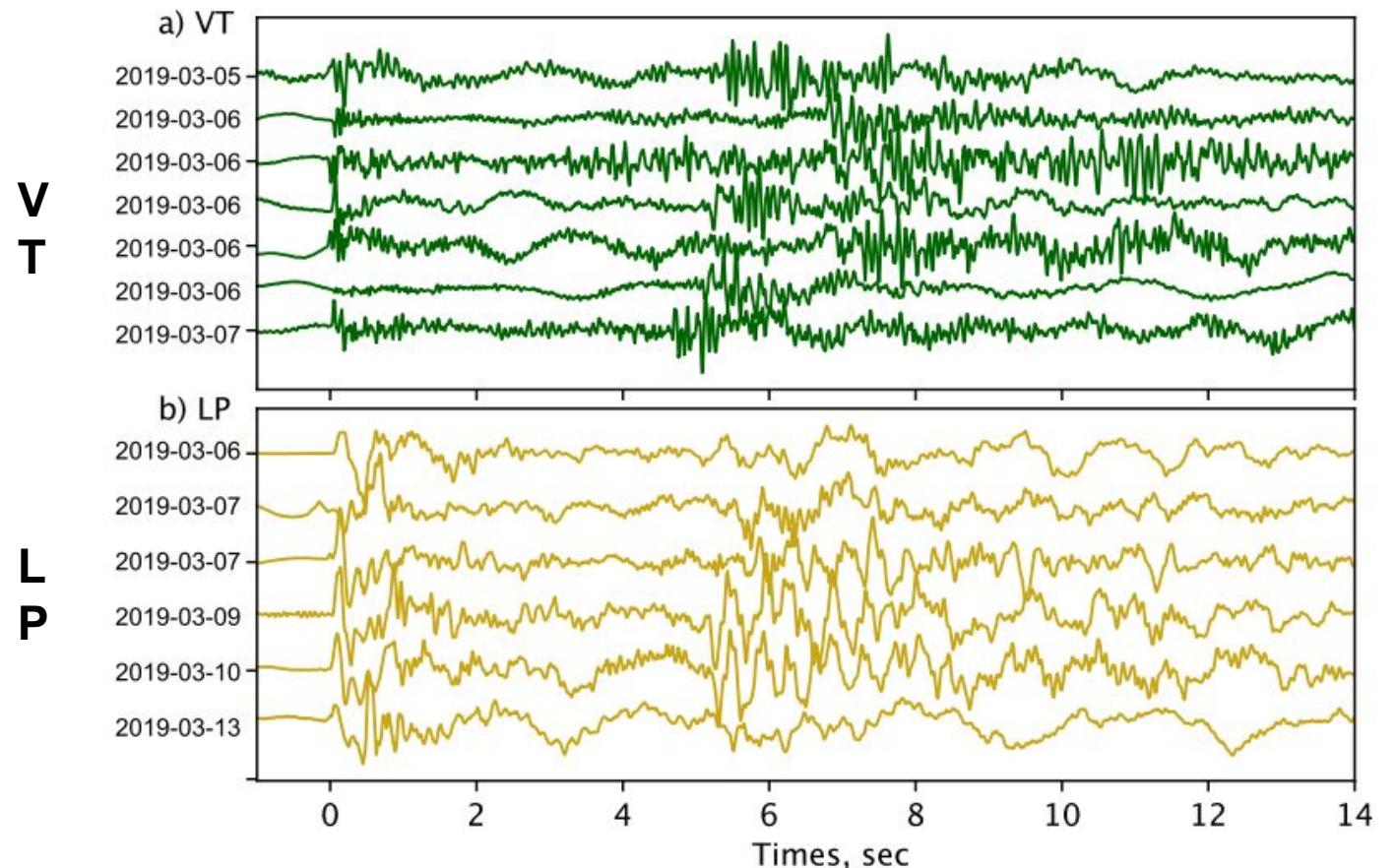
- Increased detection rate to 1.5x PhaseWorm catalog
- Re-detected ~85% of PhaseWorm catalog



(Using events with spatial window: 150 km)
(Temporal window: 8 s)

LP events in Earthworm catalog

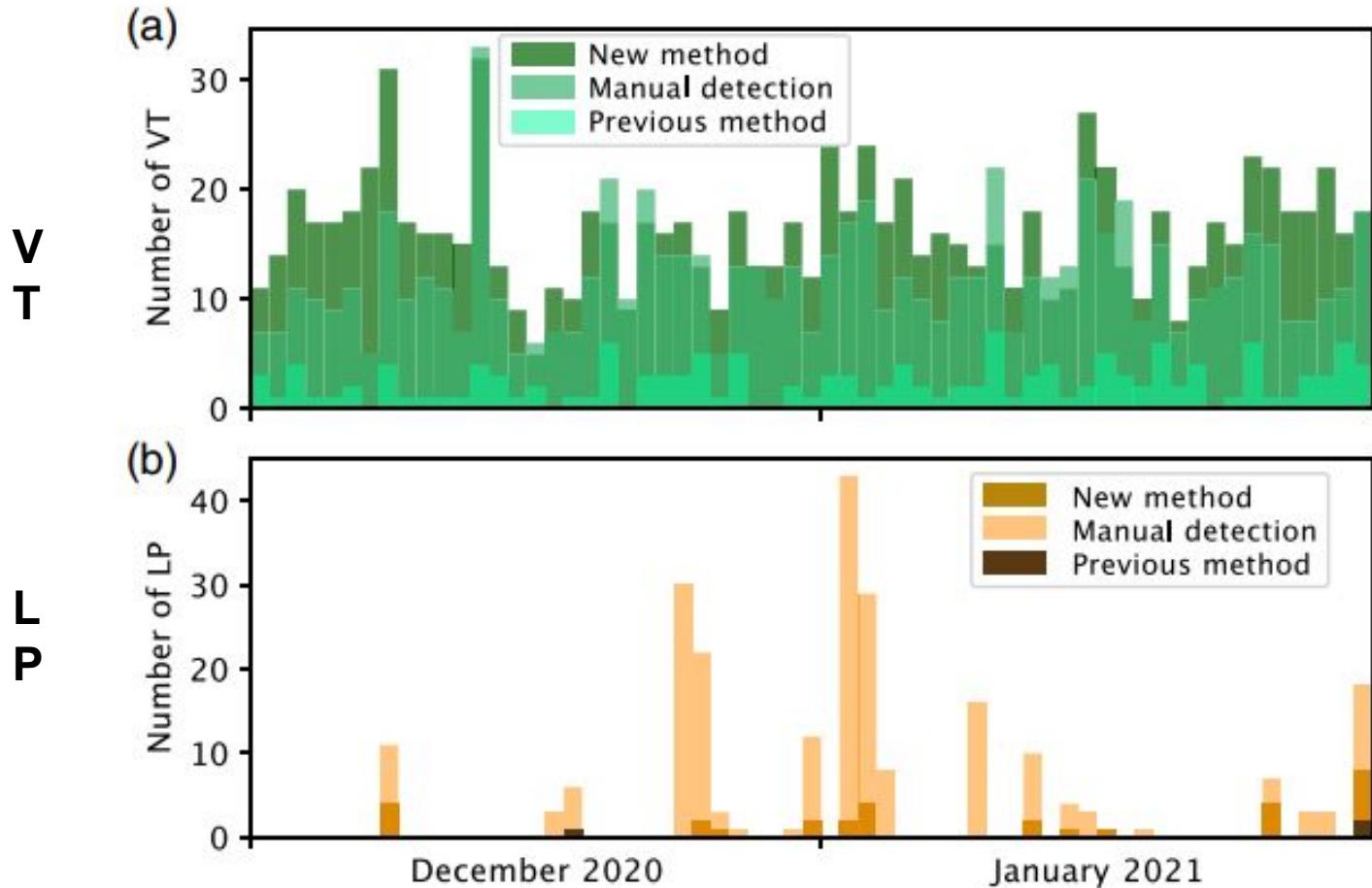
- VT events were well detected, but LP events harder to detect by PhaseWorm
- Increased rate of S vs. P phase picks
- Earthworm nucleates events based on P waves only



(Retailleau et al.,
2022)

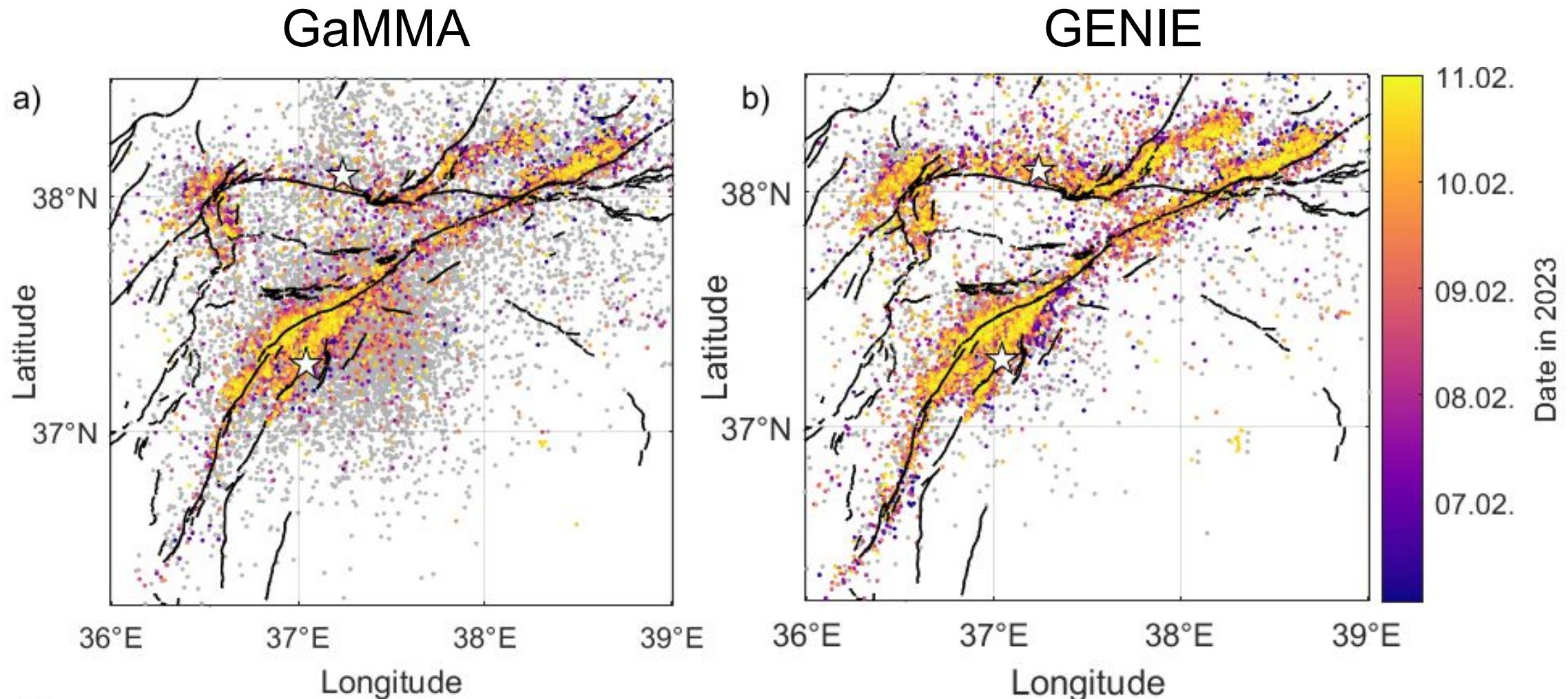
LP events in Earthworm catalog

- VT events were well detected, but LP events harder to detect by PhaseWorm
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(Retailleau et al.,
2022)

Kahramanmaraş Aftershock Sequence

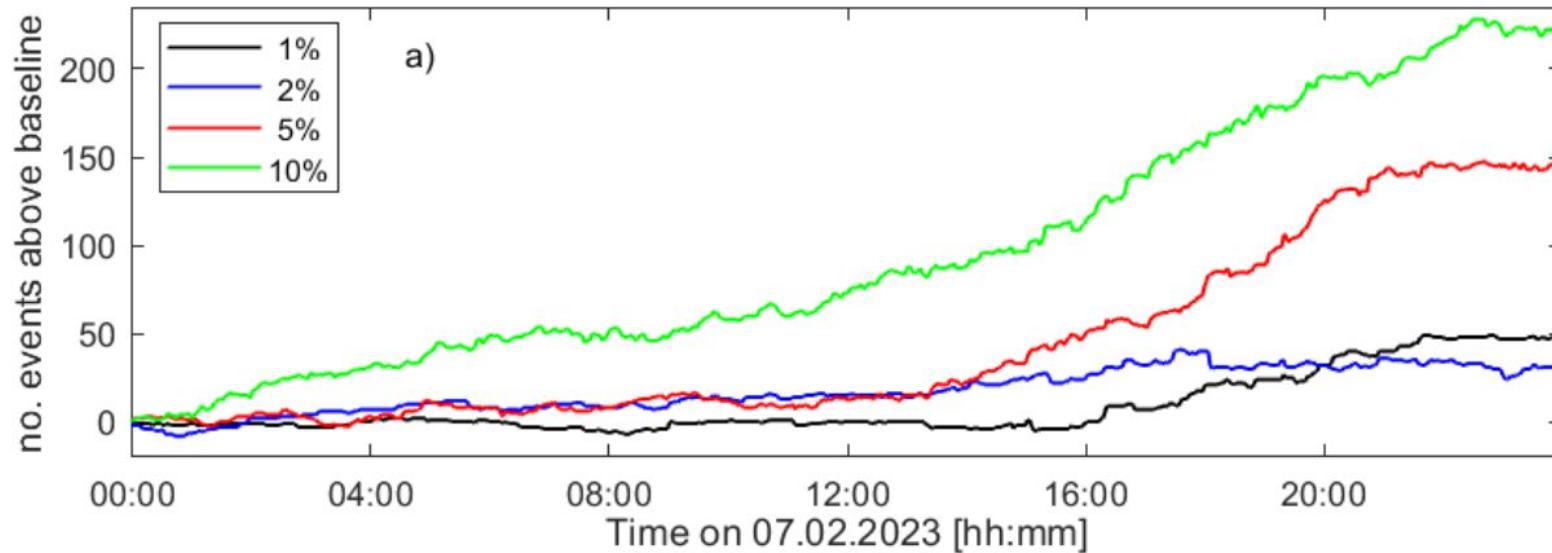


For this data set, GaMMA finds more events, while GENIE associates more phase per event

Becker et al. (2024)

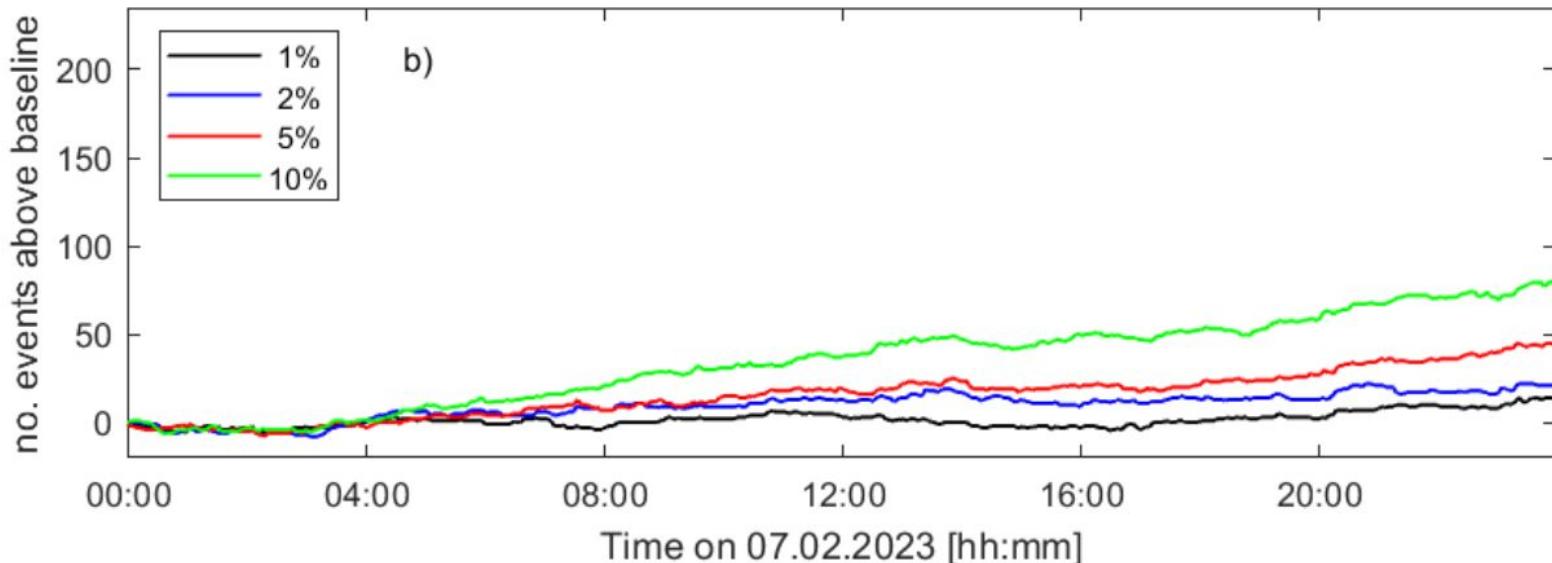
Influence of adding random picks

GaMM
A



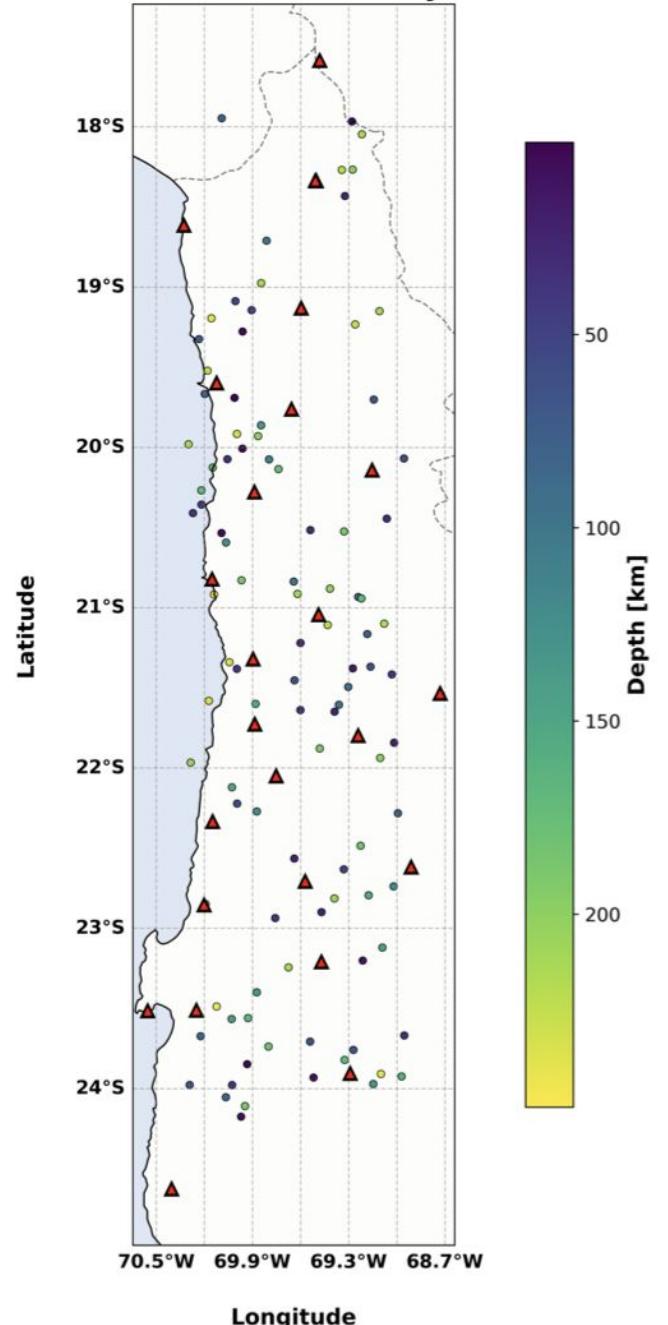
For this data set,
GaMMA seems
more prone to
mis-association.

GENIE



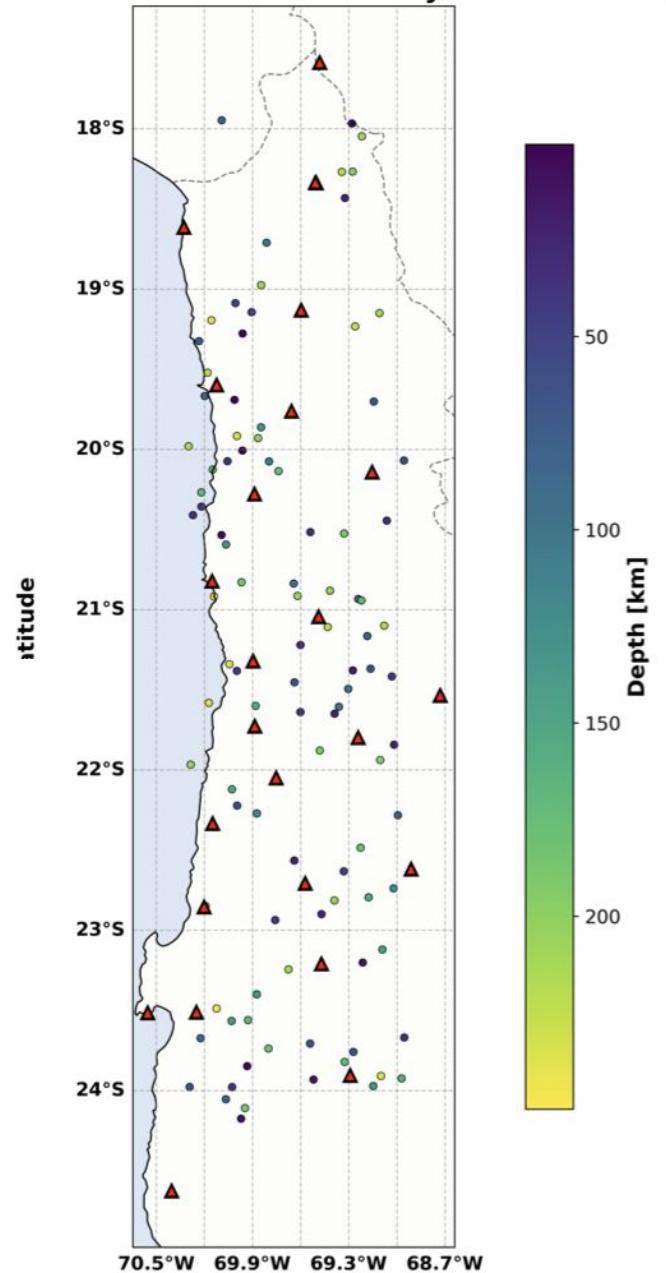
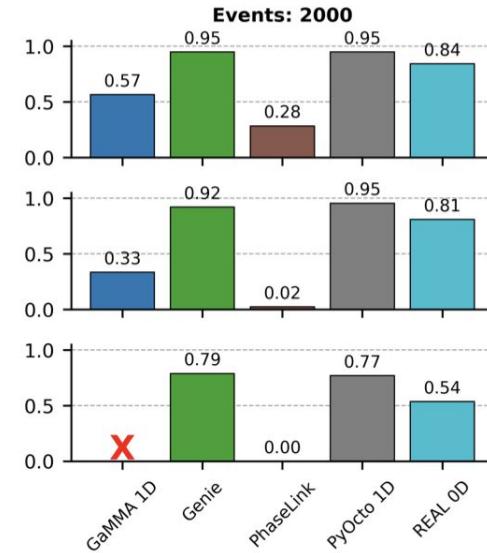
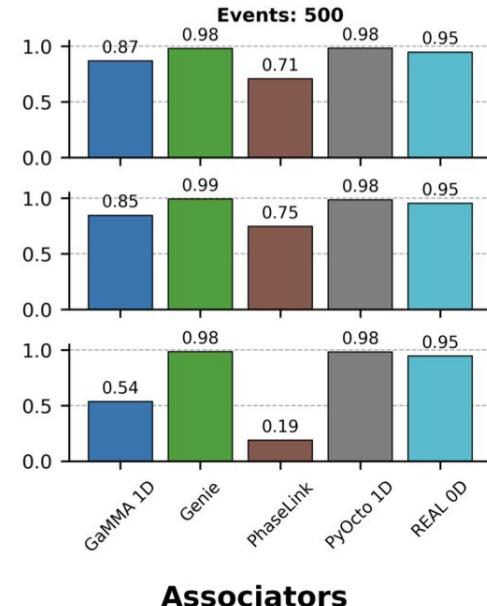
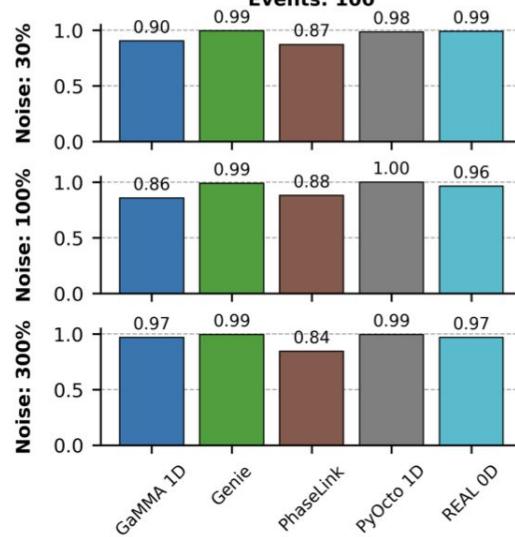
Associator Comparisons

- Tested performance of five different associators (GaMMA, PhaseLink, REAL, GENIE, PyOcto) on synthetic scenarios
- Found similar performance for low complexity cases, but large differences for high complexity data



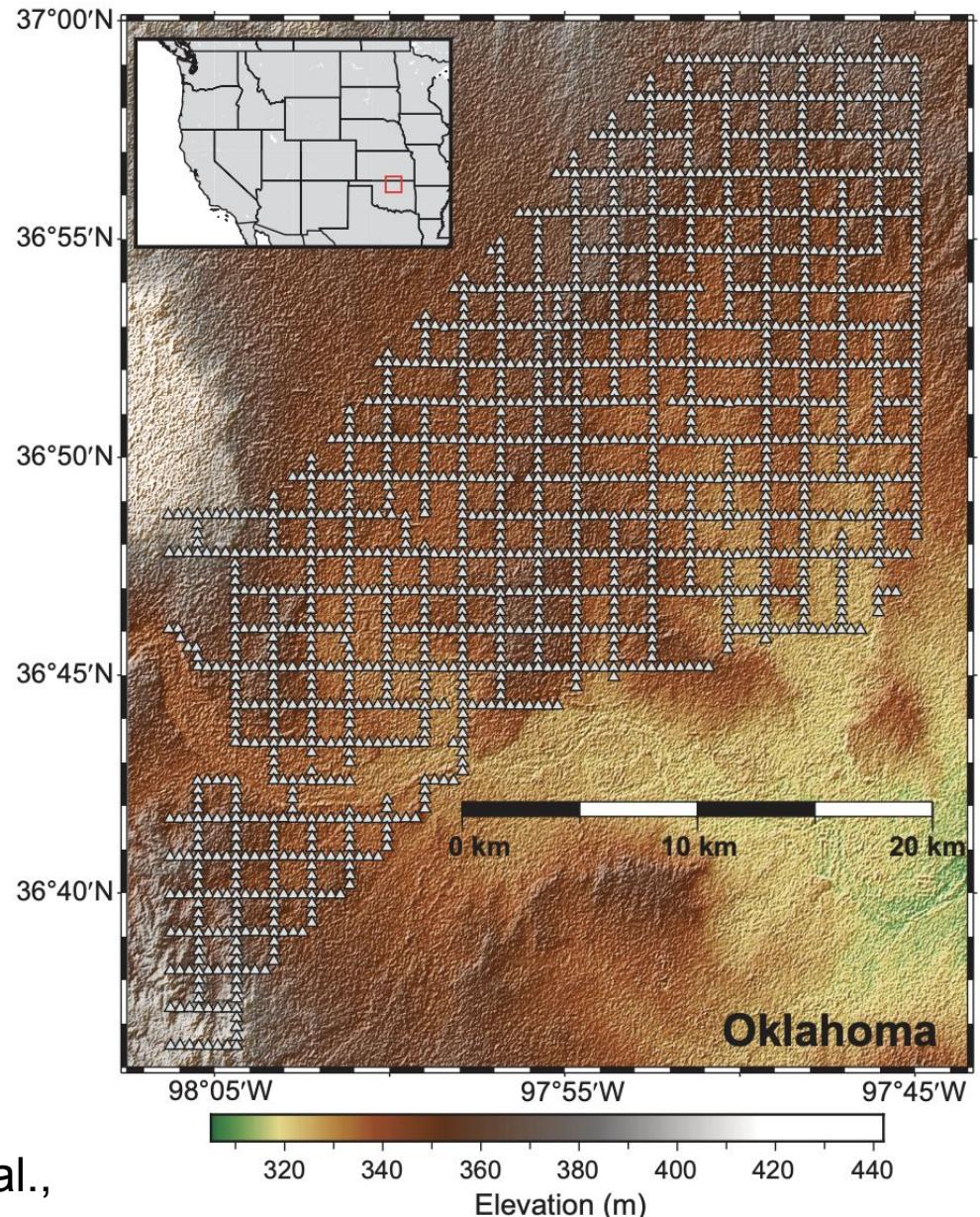
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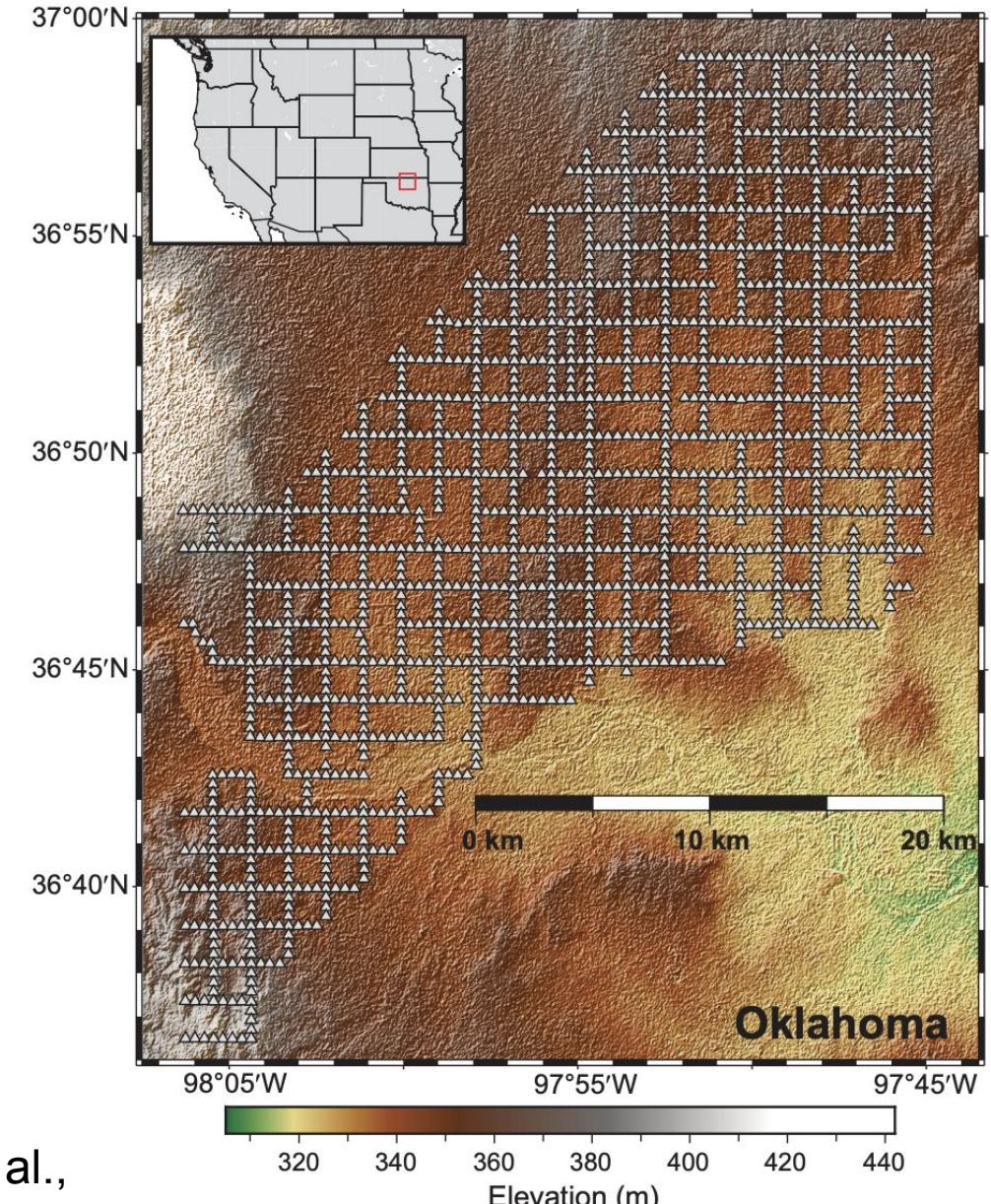
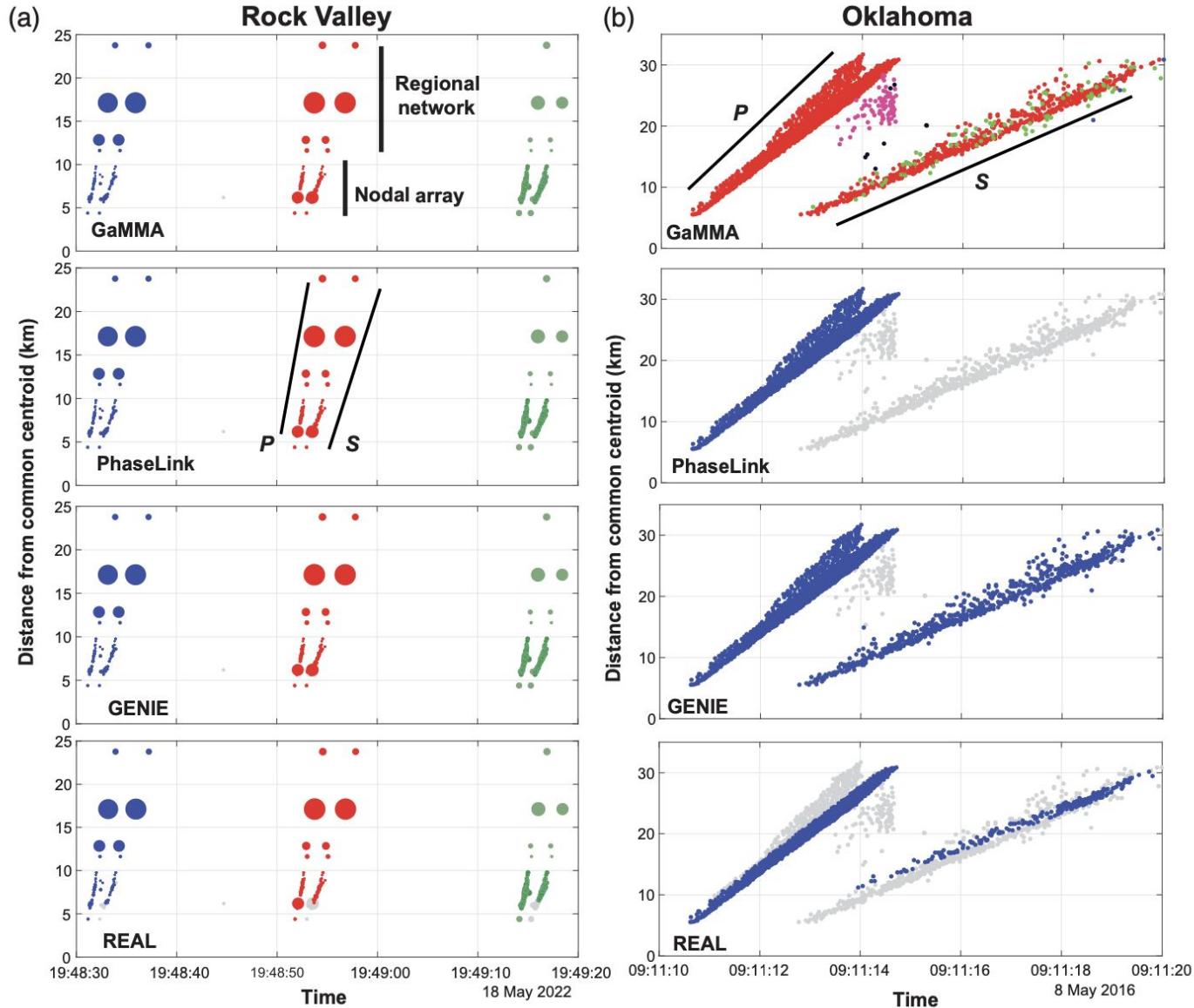


Associators applied to dense nodal arrays

- Tested performance of four different associators (GaMMA, PhaseLink, REAL, GENIE) on data from Rock Valley (52 nodes + 9 regional broadband sensors) and ~1800 geophones at LASSO

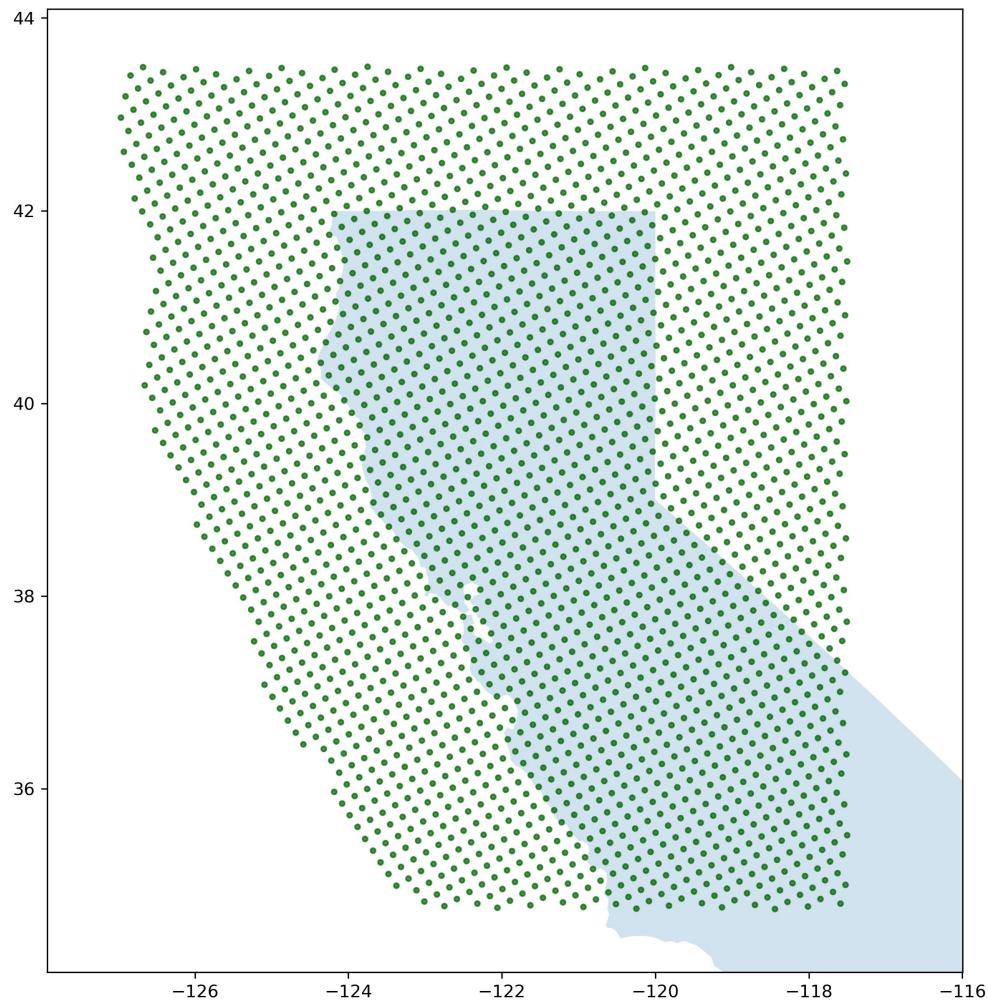


Associators applied to dense nodal arrays

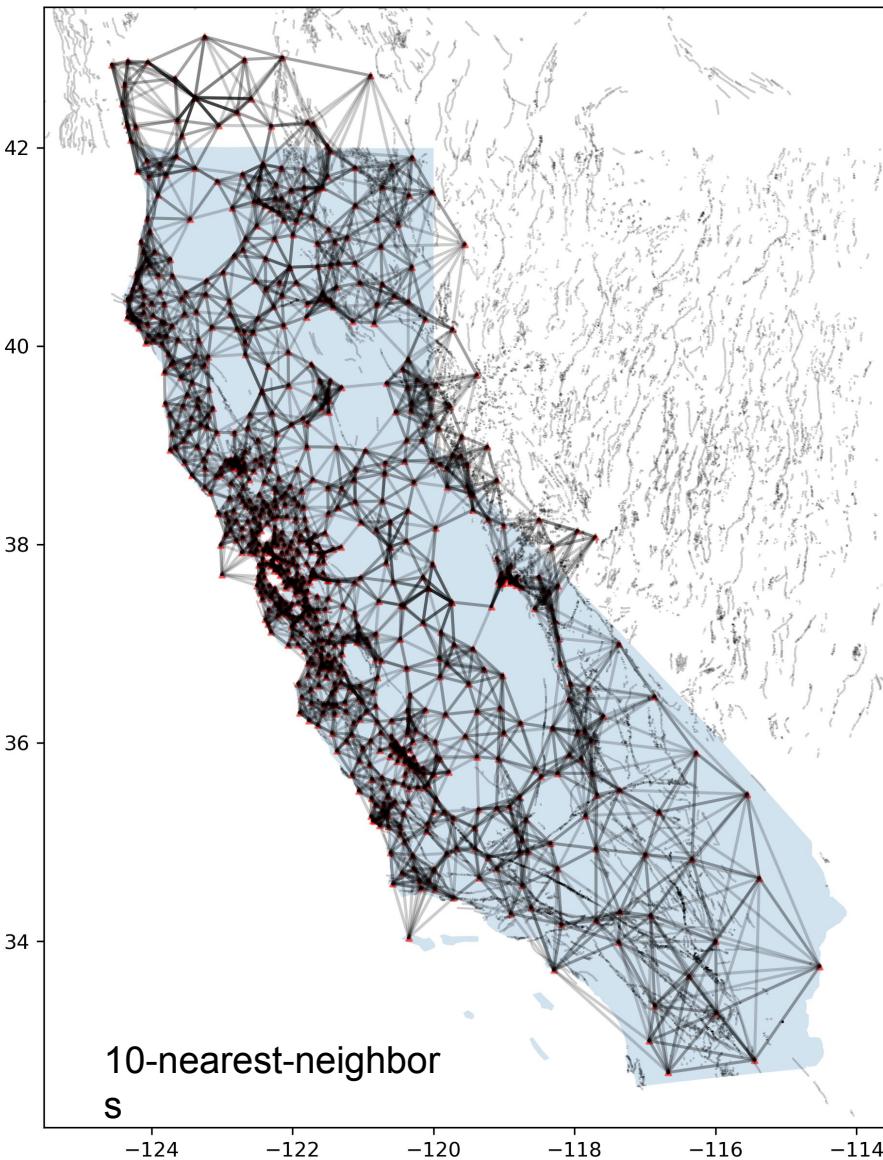


Northern California

Northern California



~1000 stations from many networks: NC, BK, PN, BG, UW, NN

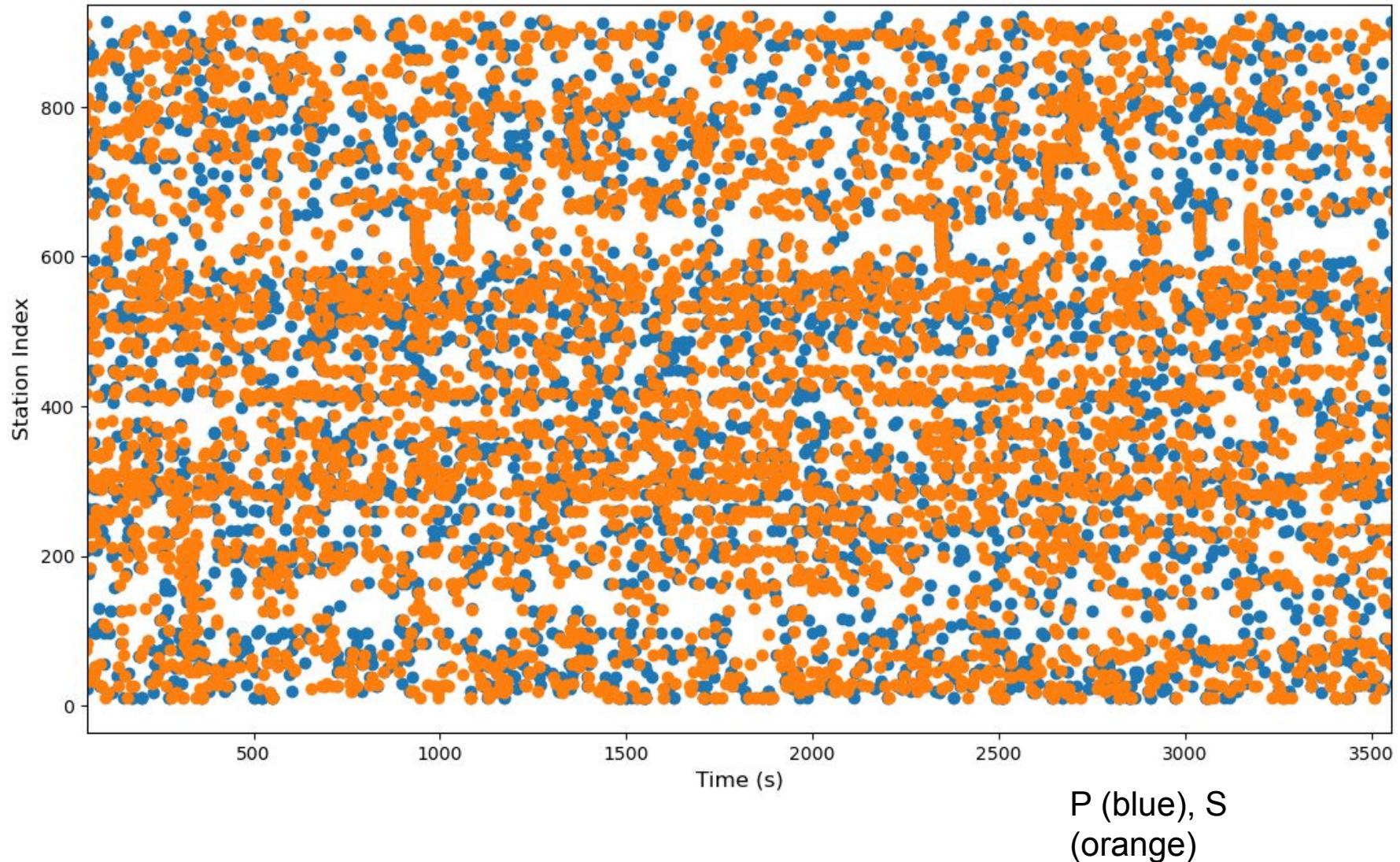


Picks

Average:
240,000
picks per day

P-waves
121,000
picks per day

S-waves
117,000
picks per day



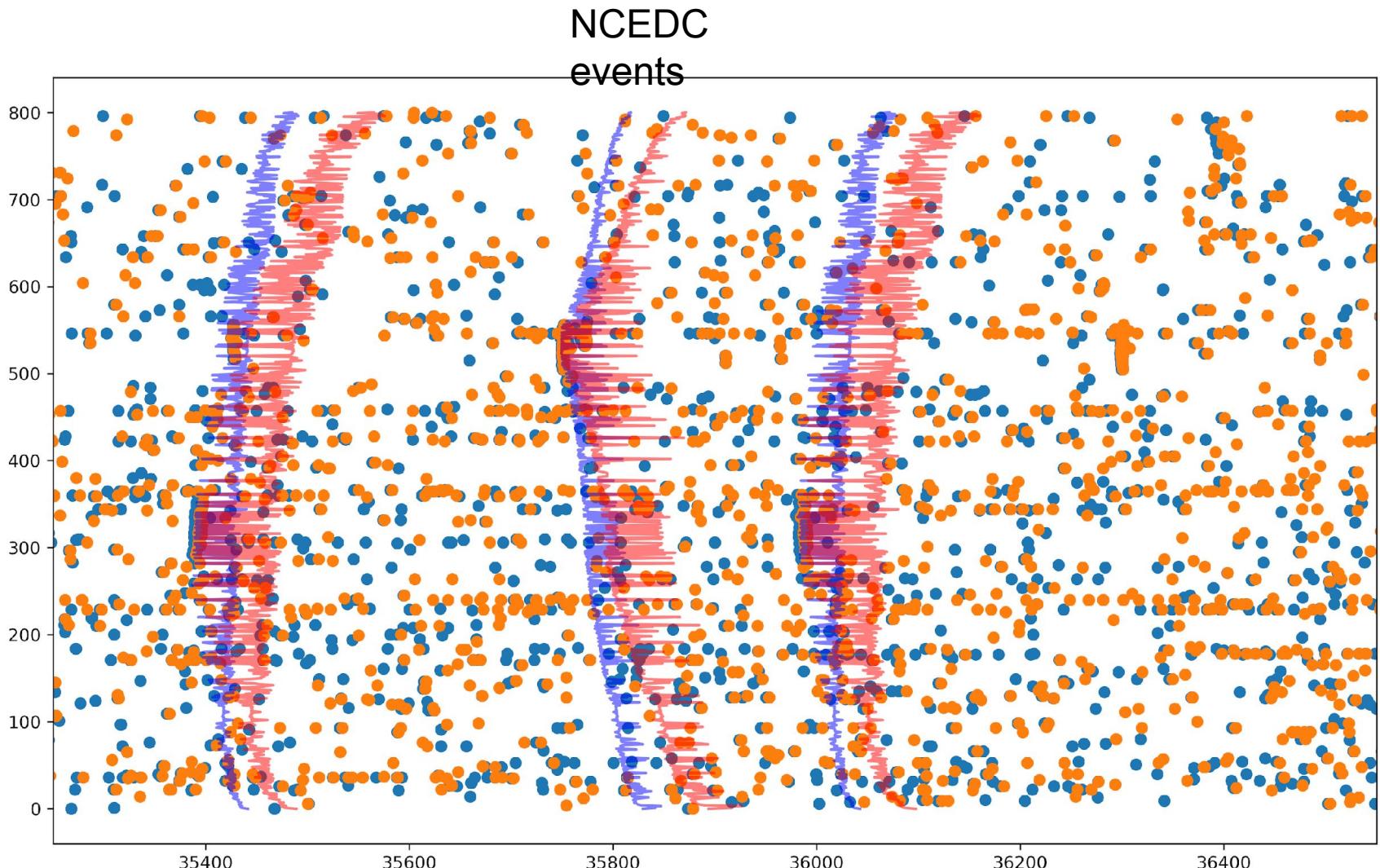
- Collaboration with Weiqiang Zhu to obtain PhaseNet picks

Picks

Average:
240,000
picks per day

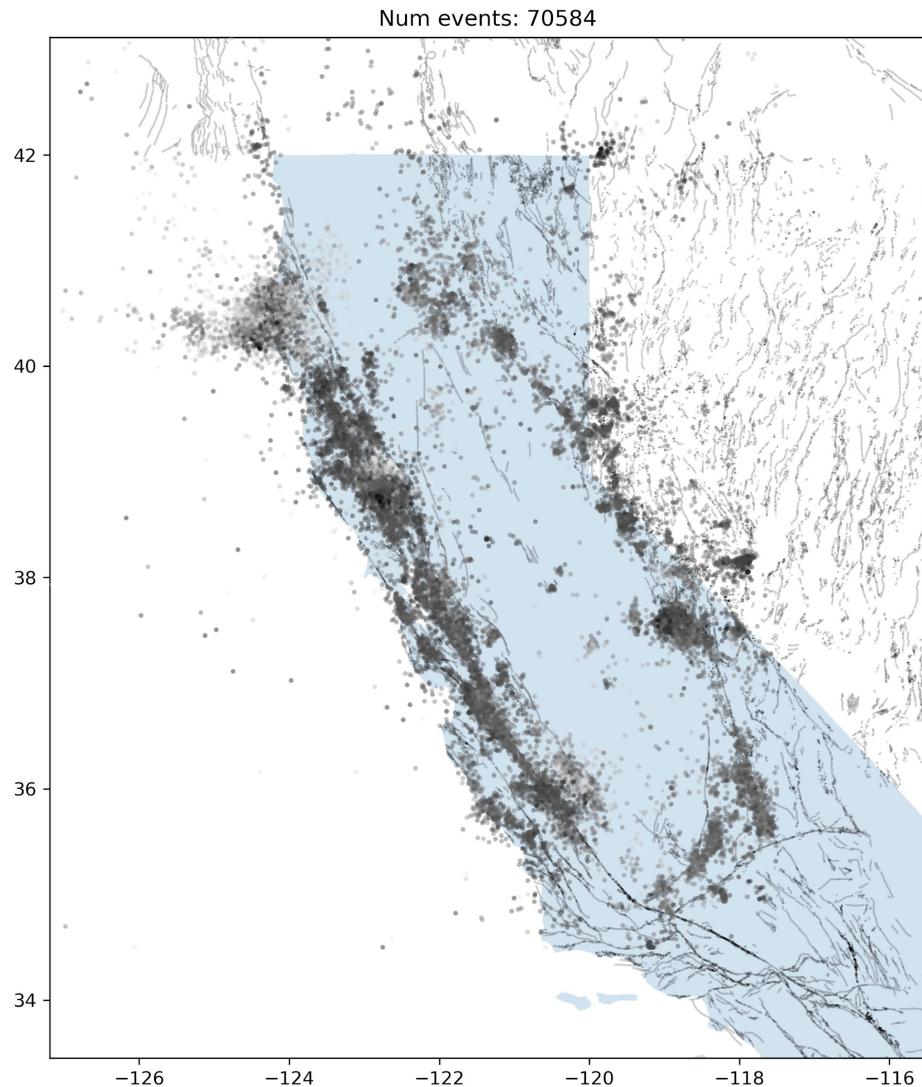
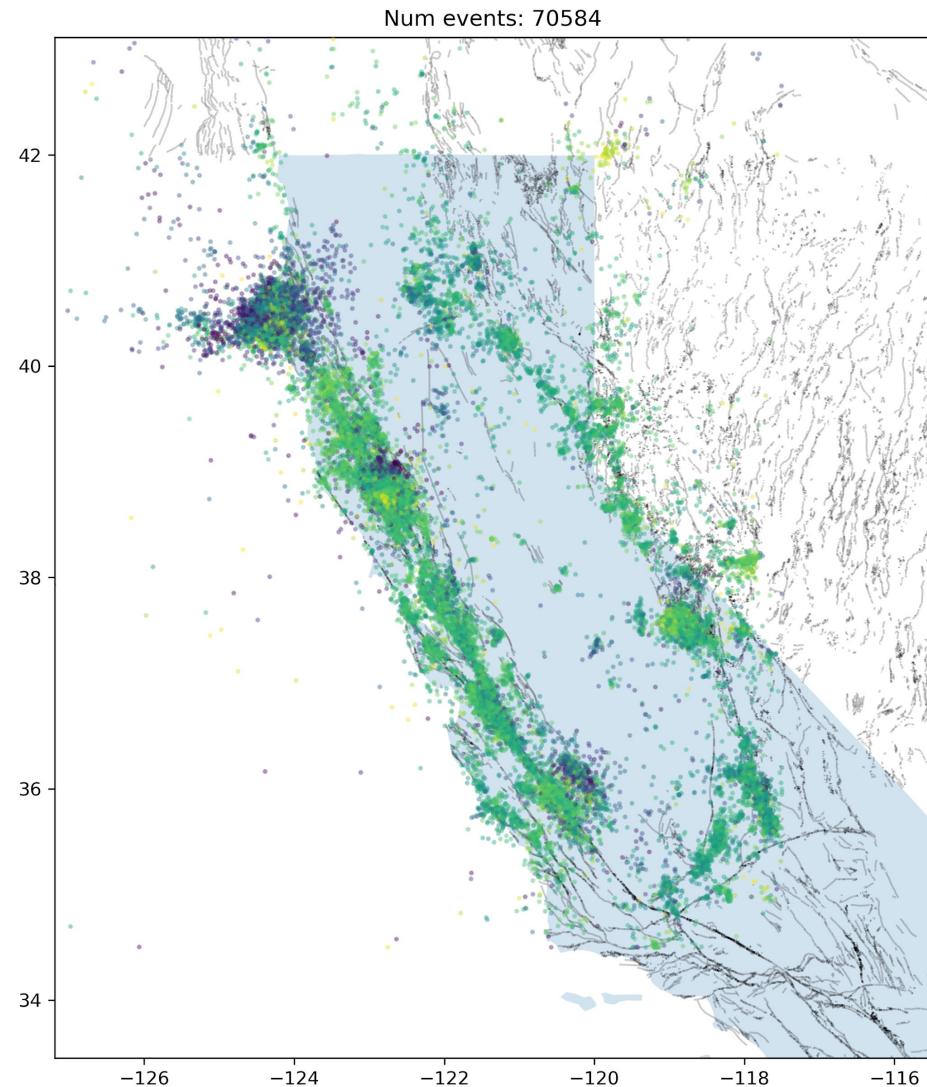
P-waves
121,000
picks per day

S-waves
117,000
picks per day



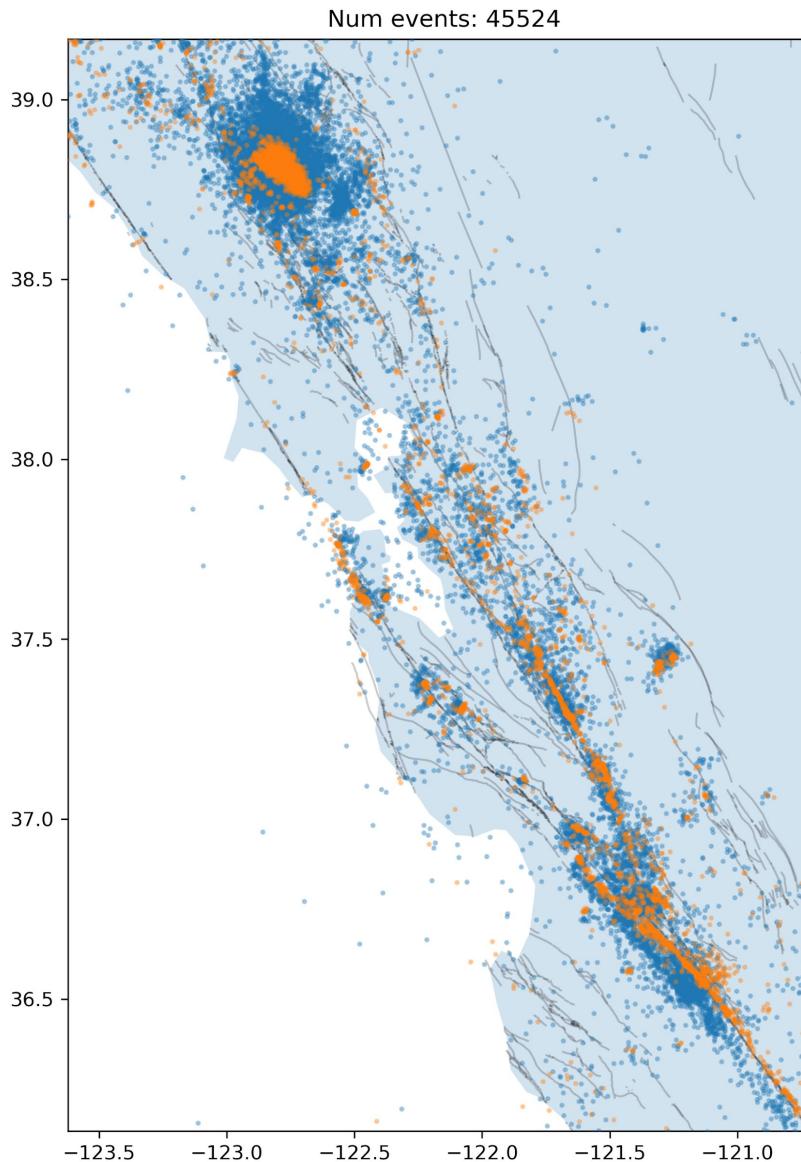
- Collaboration with Weiqiang Zhu to obtain PhaseNet picks

Initial Catalog (2023)



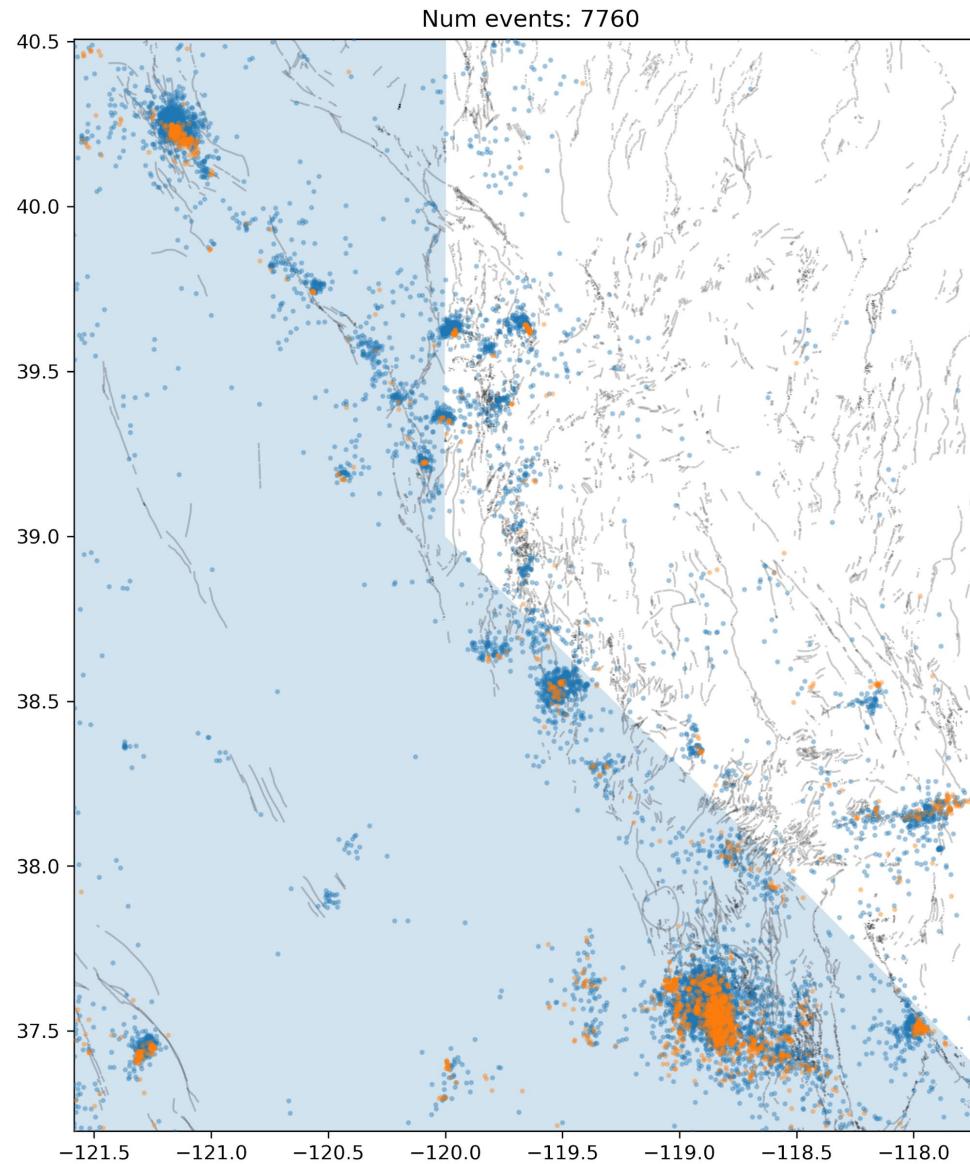
Example Catalog

Comparison of NCEDC
(orange) and our initial
catalog (blue)



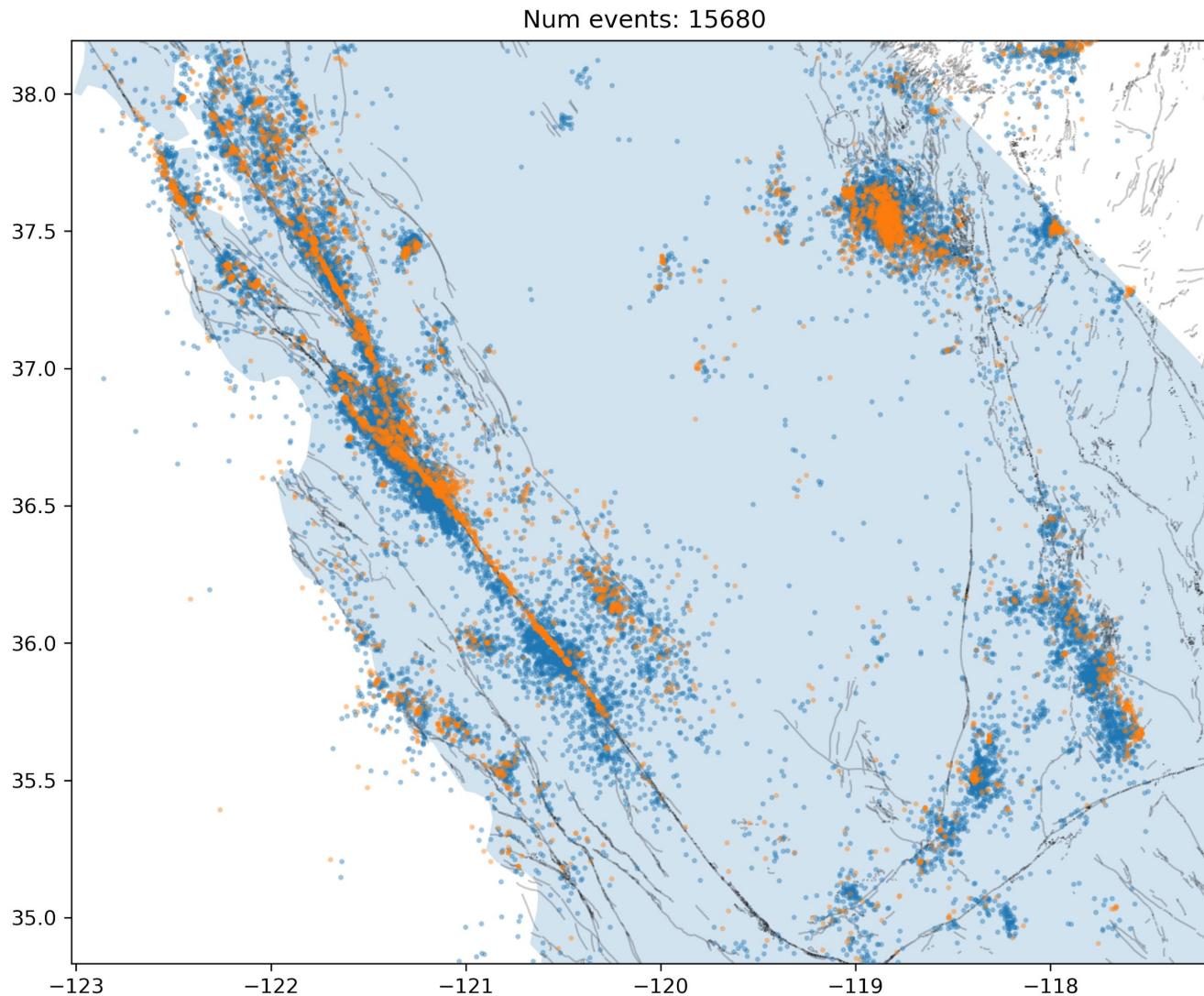
Example Catalog

Comparison of NCEDC
(orange) and our initial
catalog (blue)

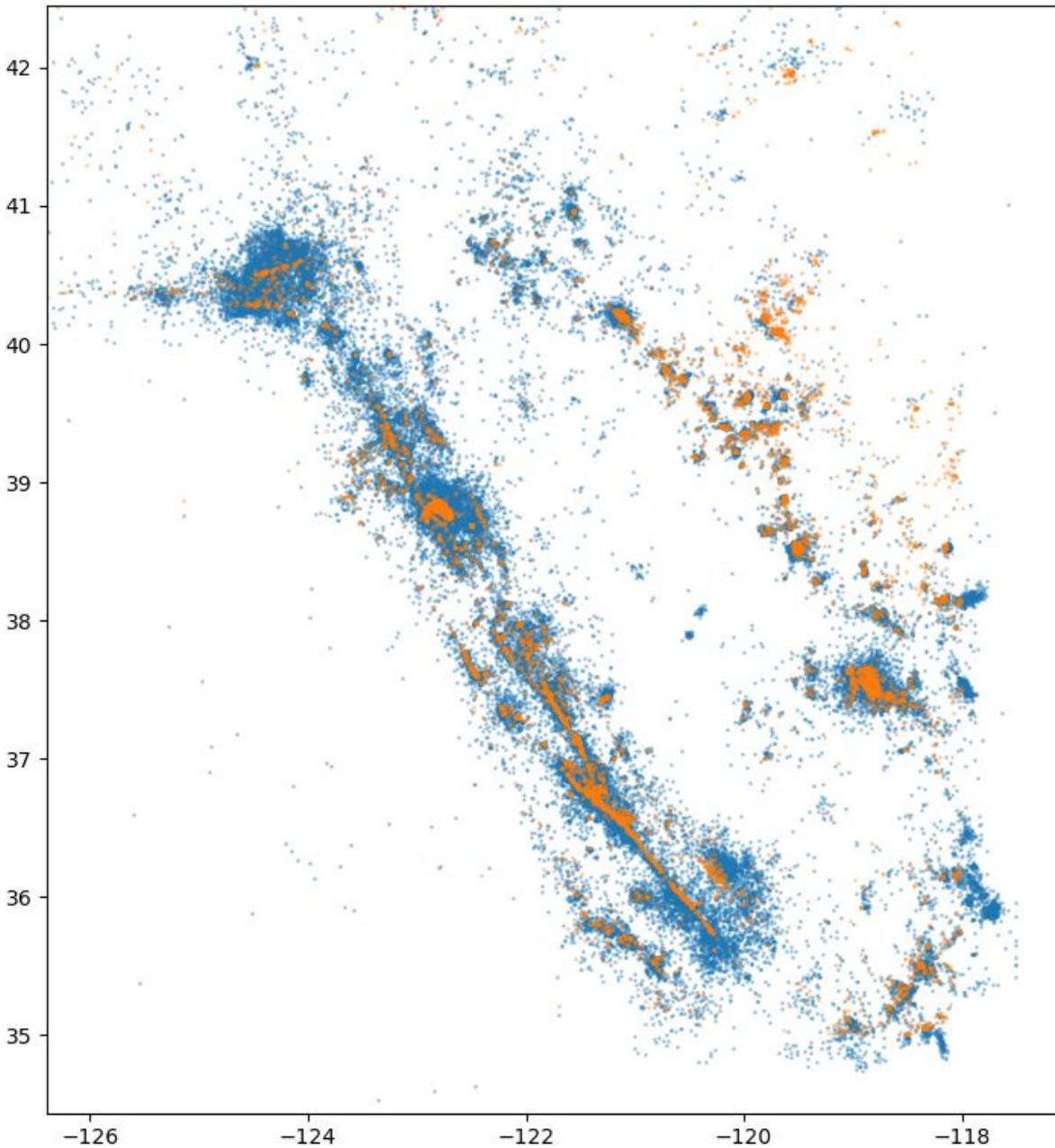


Example Catalog

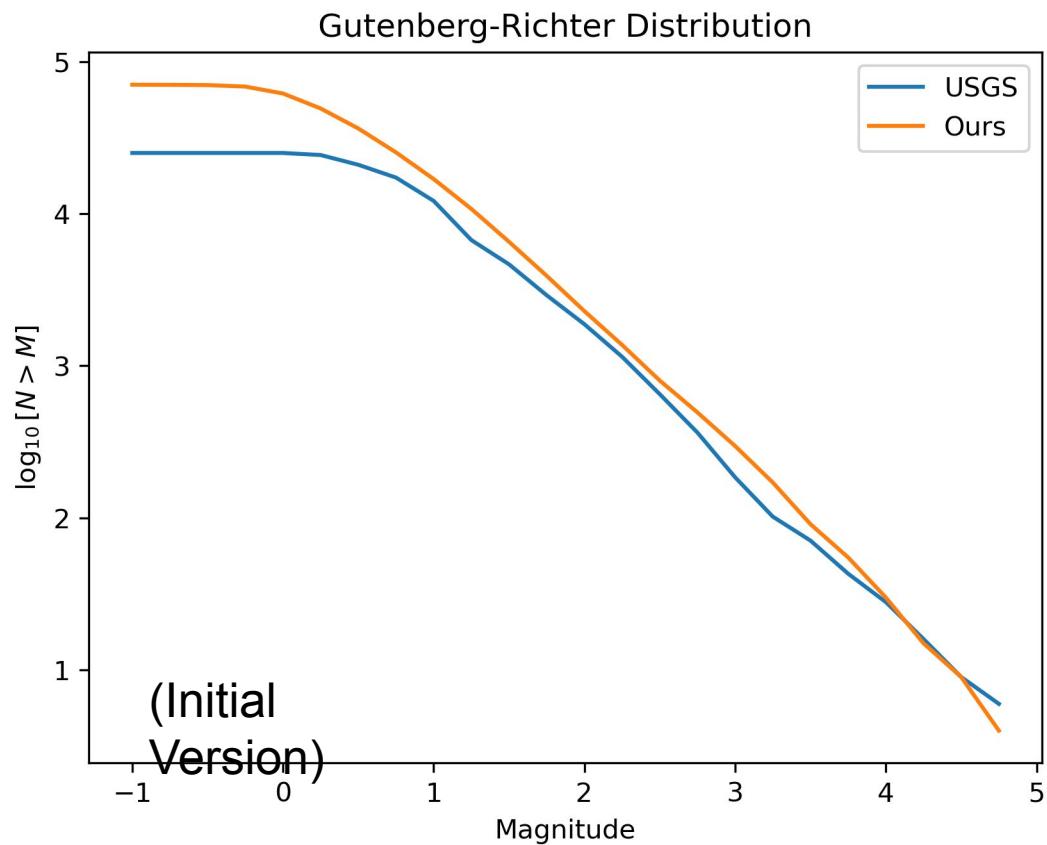
Comparison of NCEDC
(orange) and our initial
catalog (blue)



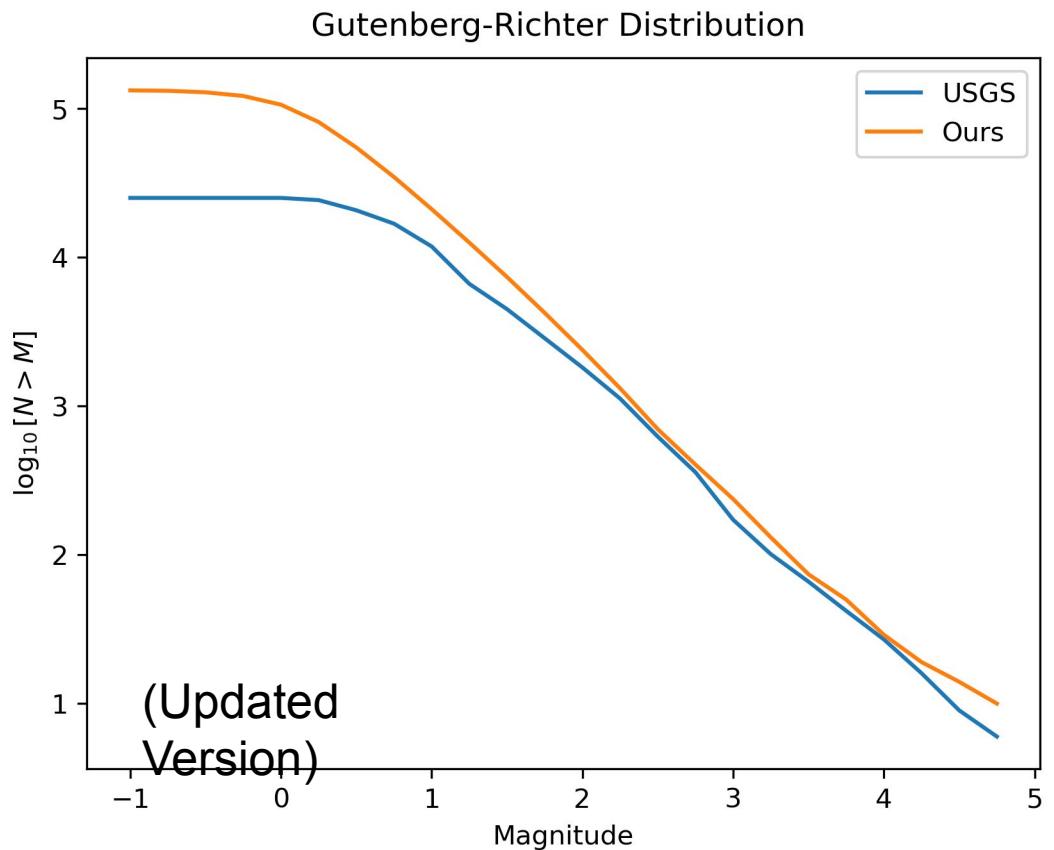
Increased Catalog (2023)



Event Counts



- 2.8x NCEDC catalog



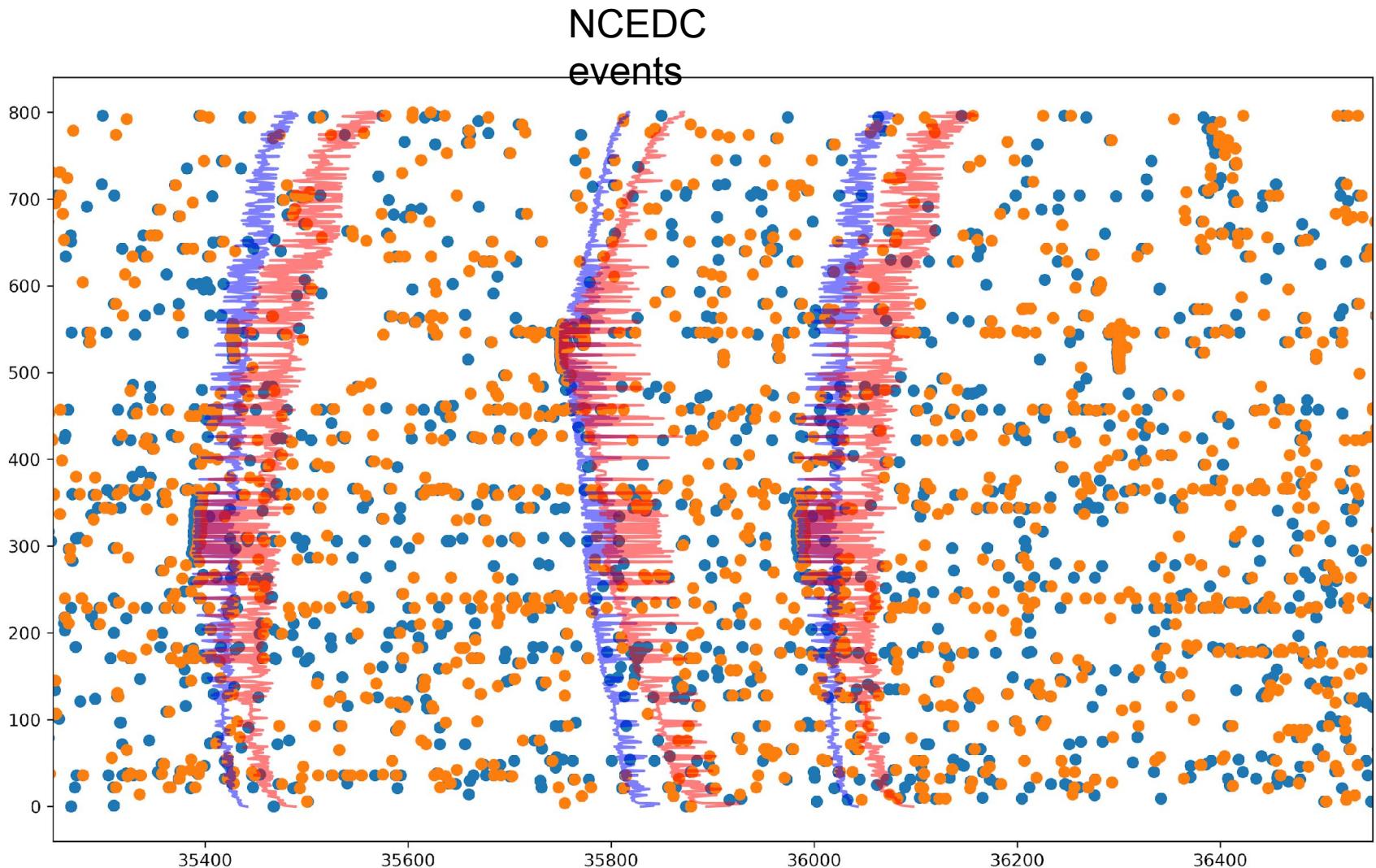
- 5.3x NCEDC catalog

Picks

Average:
240,000
picks per day

P-waves
121,000
picks per day

S-waves
117,000
picks per day



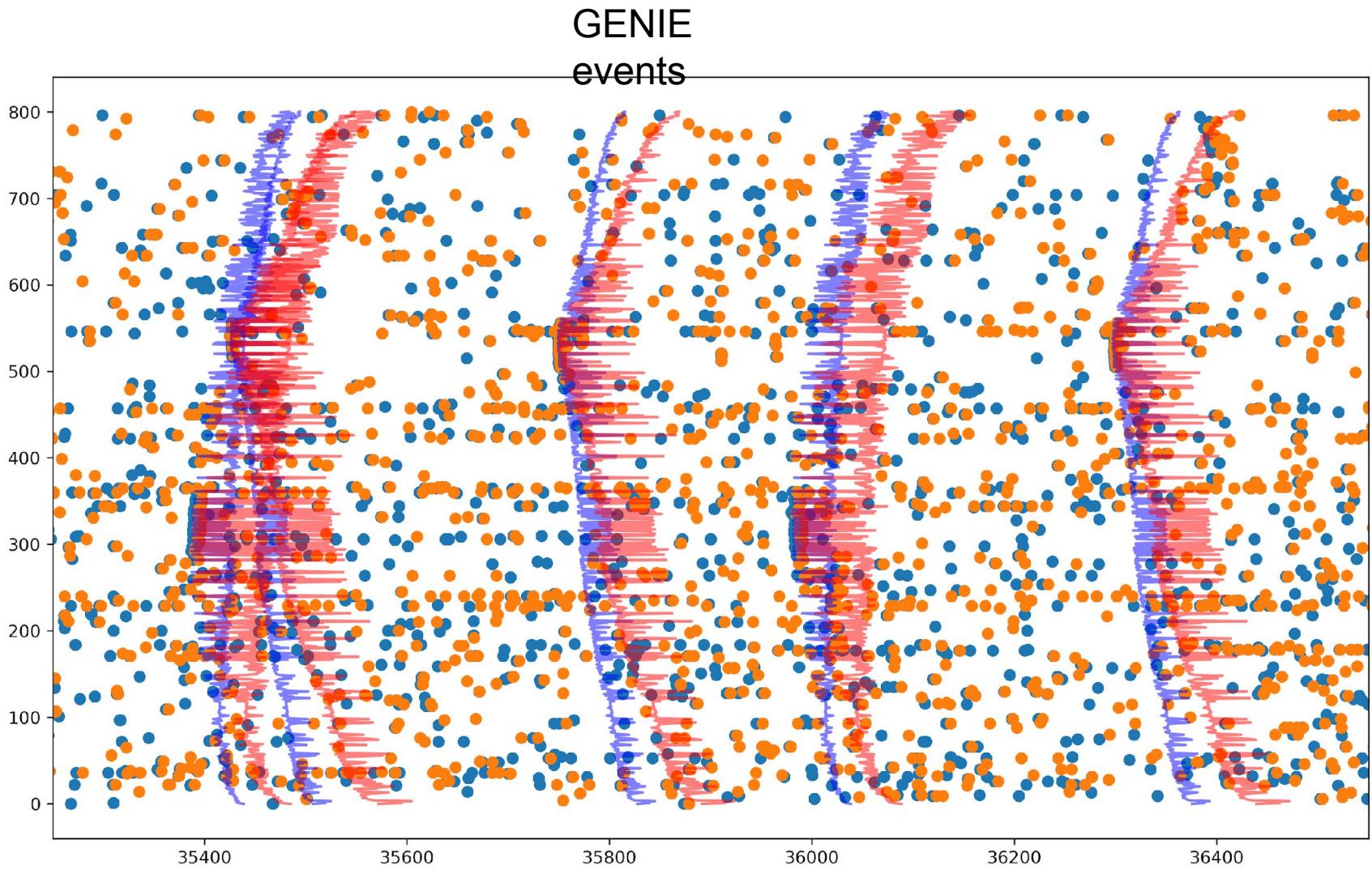
- Collaboration with Weiqiang Zhu to obtain PhaseNet picks

Picks

Average:
240,000
picks per day

P-waves
121,000
picks per day

S-waves
117,000
picks per day



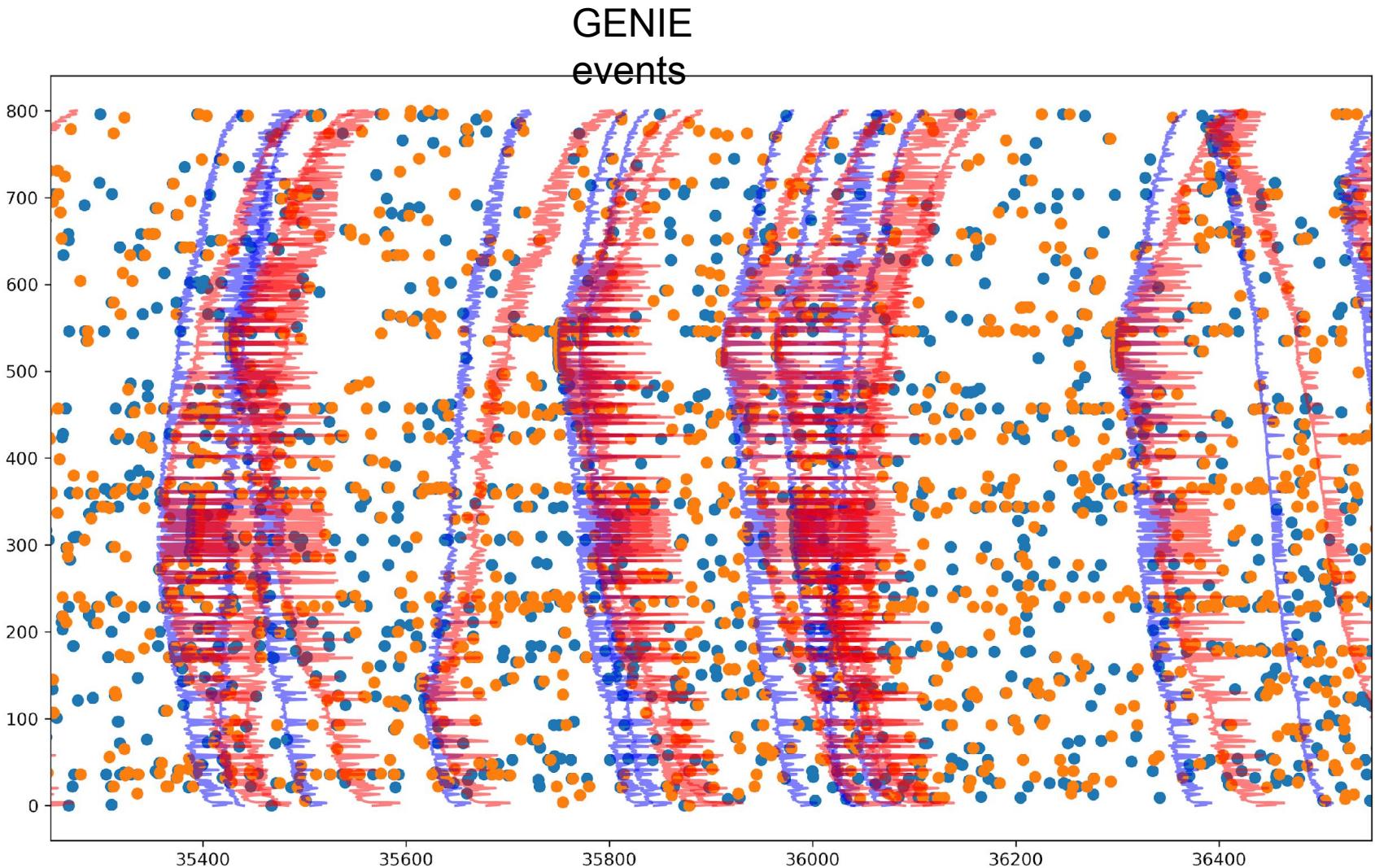
- Collaboration with Weiqiang Zhu to obtain PhaseNet picks

Picks

Average:
240,000
picks per day

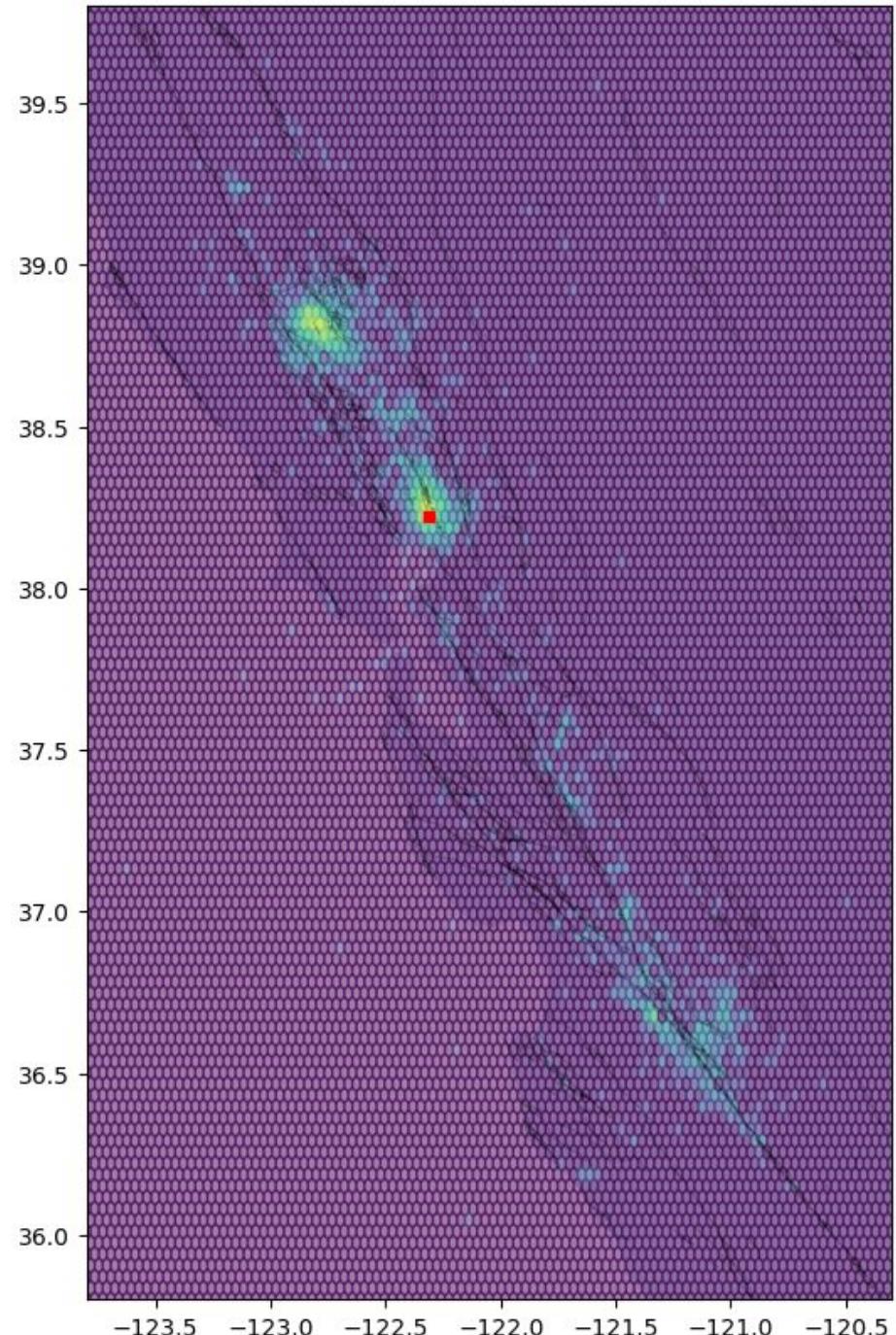
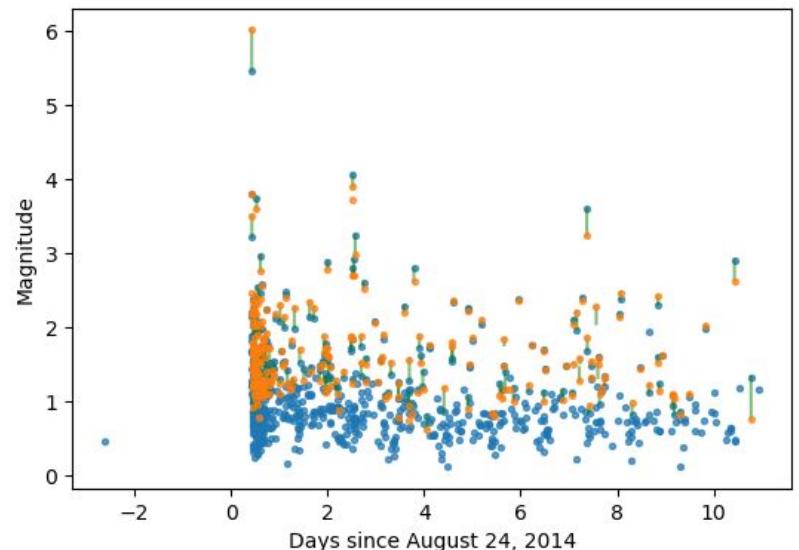
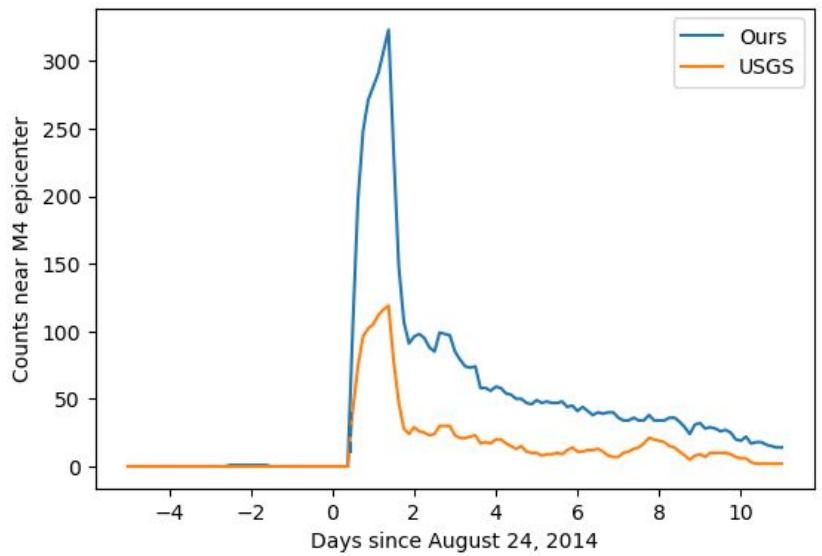
P-waves
121,000
picks per day

S-waves
117,000
picks per day

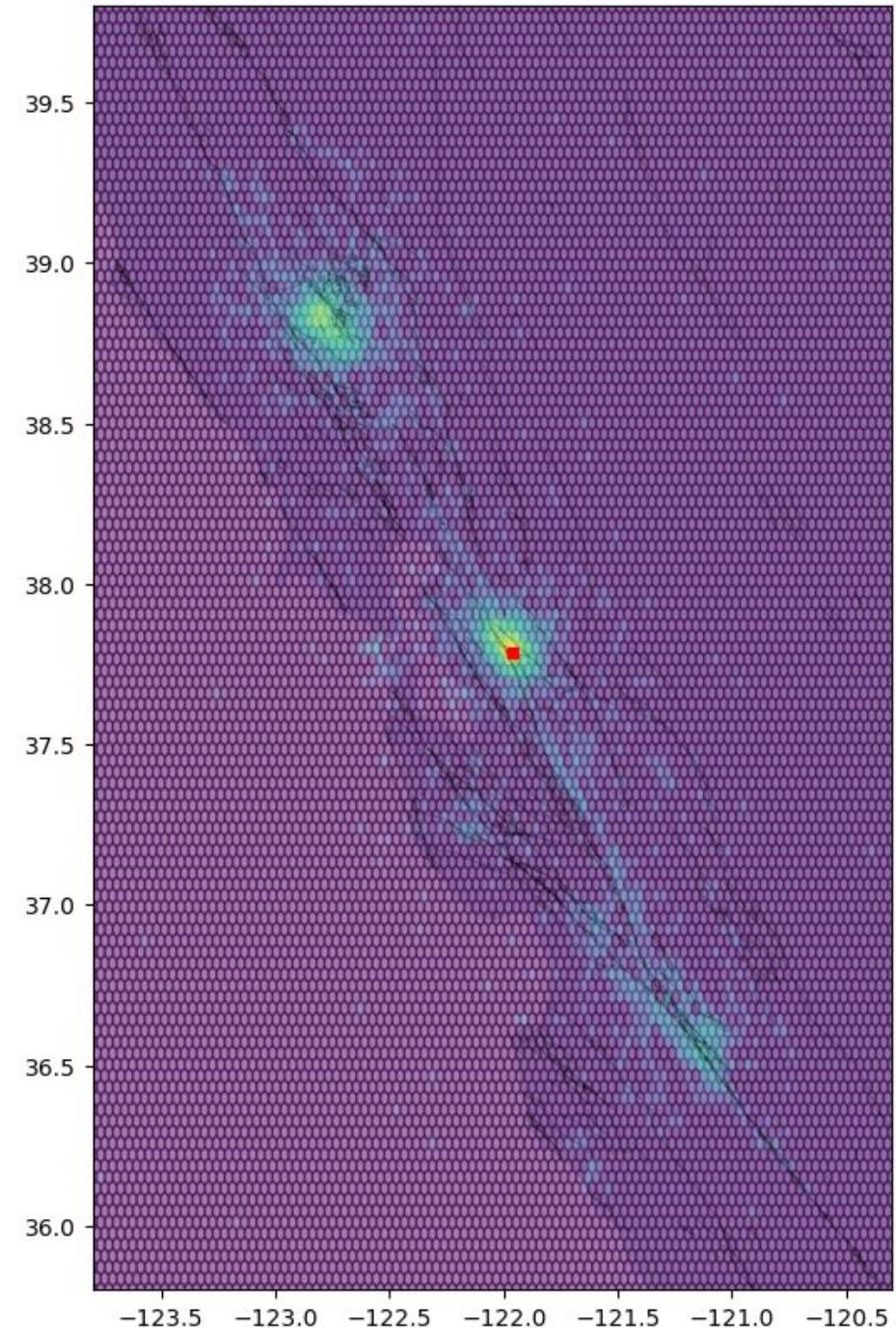
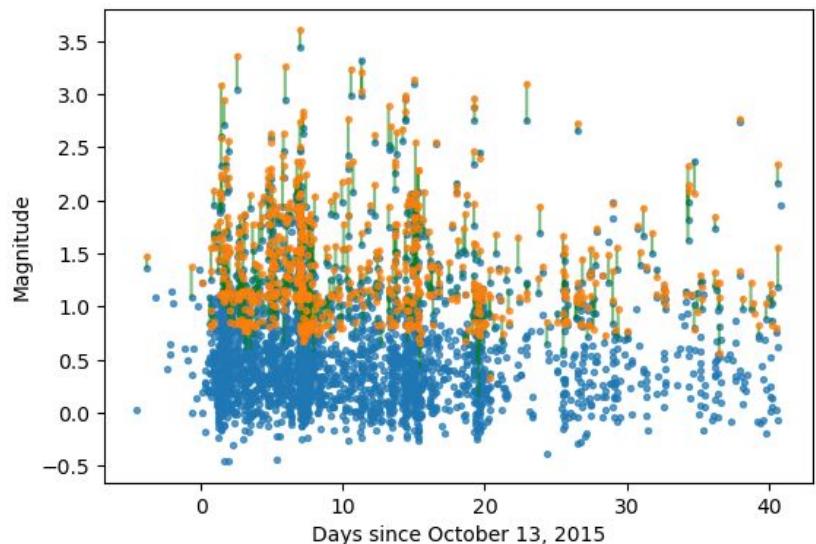
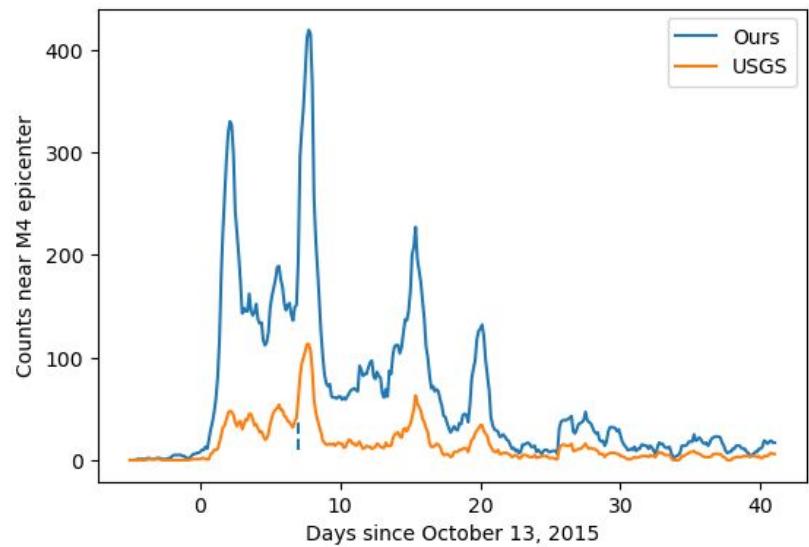


- Collaboration with Weiqiang Zhu to obtain PhaseNet picks

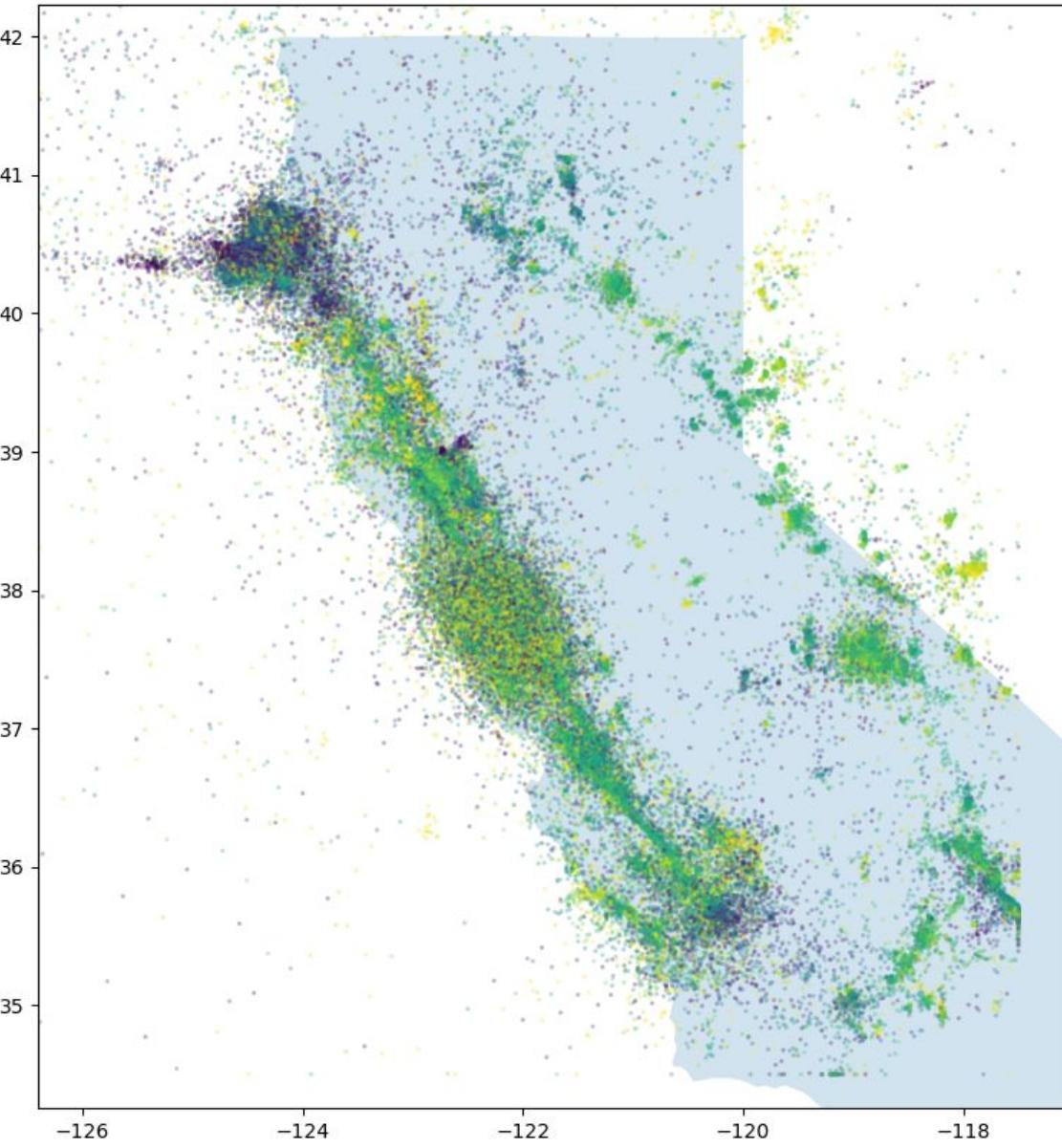
Mw 6.0 Napa Earthquake, 2014



San Ramon Swarm, 2015



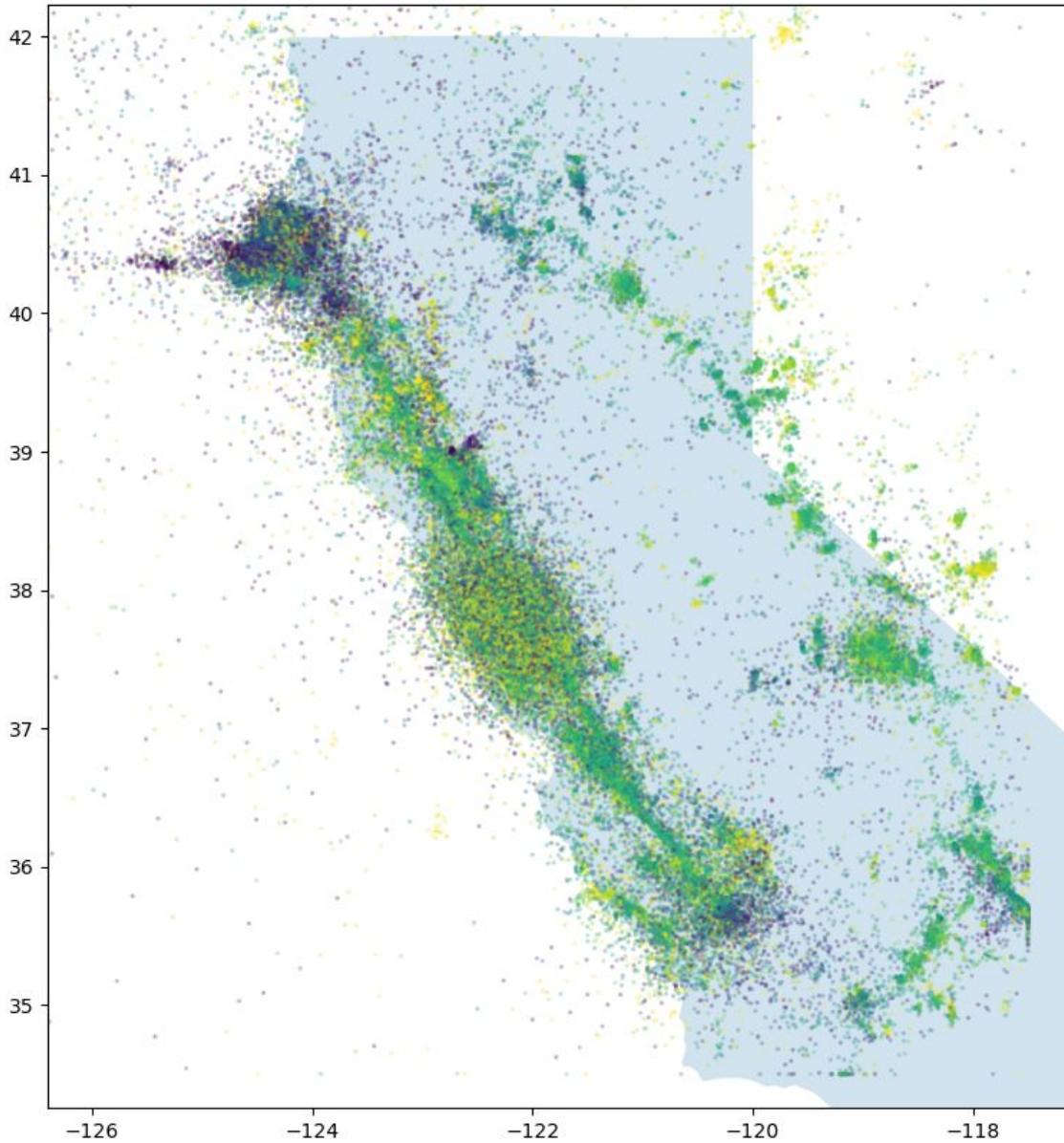
Bad Catalog



Bad Catalog

Training data too many events

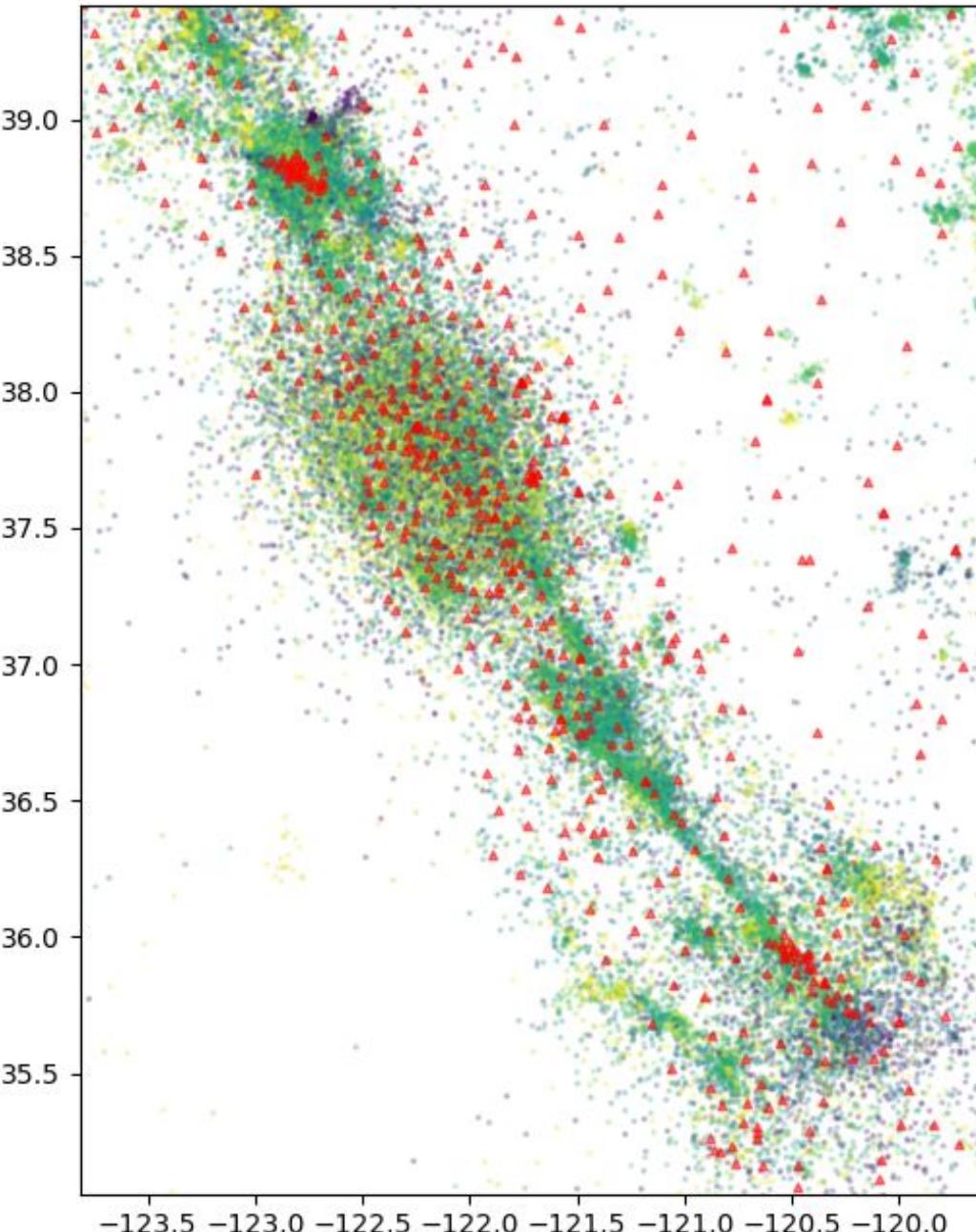
Also – set of associated picks in training, too random.



Bad Catalog

Training data too many events

Also – set of associated picks in training, too random.



How to use *GENIE*

The screenshot shows the GitHub repository page for 'GENIE' (Graph Earthquake Neural Interpretation Engine). The repository is public and has 1,213 commits, 9 forks, and 41 stars. It contains 2 branches and 3 tags. The repository description states: 'A Graph Neural Network (GNN) based earthquake phase associator and spatio-temporal source localization model.' The README file is visible, and there are sections for Releases, Packages, and Contributors.

GENIE

Public

Pin Unwatch 5 Fork 9 Star 41

main 2 Branches 3 Tags Go to file Add file Code

imcbrearty Update train_double_difference_model.py 9299a6b · last week 1,213 Commits

BSSA Add BSSA 2 years ago

Code Update config.yaml last week

DoubleDifference Update train_double_difference_model.py last week

LICENSE.md Create LICENSE.md 3 years ago

README.md Update README.md 3 months ago

Readme MIT license Activity 41 stars 5 watching 9 forks

A Graph Neural Network (GNN) based earthquake phase associator and spatio-temporal source localization model.

GENIE : Graph Earthquake Neural Interpretation Engine

A Graph Neural Network (GNN) based earthquake phase associator and spatio-temporal source localization model.

The paper associated with this work is given at
<https://pubs.geoscienceworld.org/ssa/bssa/article/doi/10.1785/0120220182/619845/Earthquake-Phase-Association-with-Graph-Neural>.

3 tags Create a new release

No packages published Publish your first package

Contributors 2

How to use GENIE

- (1). Set region and station file
- (2). Set velocity model
- (3). Compute travel times
- (4). Choose synthetic data parameters and train
- (5). Apply

How to use *GENIE*

[GENIE / Code / config.yaml](#) 

 **imcbrearty** Update config.yaml

Code [Blame](#) 90 lines (73 loc) · 6.42 KB  [Code 55% faster with GitHub Copilot](#)

```
1 name_of_project: 'Mayotte'
2 num_cores: 1 # How many cores would you like to use for travel time calculations? (it w
3 vel_model_ver: 1 ## Which travel time version to save when running calculate_travel_time()
4
5 ## Note, when running continuous days processing a number of parameters are also set in
6
7 latitude_range: [18.8, 20.3] # Latitude range of the region that will be processed
8 longitude_range: [-156.1, -154.7] # Longitude range of the region that will be processe
9 depth_range: [-40000, 5000] # Note: depths are in meters, positive above sea level, neg
10 time_range: # This sets up the Catalog and Pick files to have these years initialized
11     start: '2018-01-01'
12     end: '2023-01-01'
```

Set
region

How to use *GENIE*

```
[In [14]: z = np.load('stations.npz')

[In [15]: list(z.keys())
Out[15]: ['locs', 'stas']

[In [16]: print(z['locs'][0:10])
[[ 39.04446 -123.541092  687.
  [ 39.11709 -123.70883   144.
  [ 39.12745 -122.82347   858.
  [ 39.12997 -123.07651  1077.
  [ 39.133171 -123.46788   370.
  [ 39.17902 -122.63618   975.
  [ 39.1853   -123.2109   193.
  [ 39.20074 -123.63514   327.
  [ 39.205704 -123.301003  654.
  [ 39.30477 -123.19748   264.7 ]]

[In [17]: print(z['stas'][0:10])
['GHO.NC' 'GBL.NC' 'GHGB.NC' 'GCWB.NC' 'GMR.NC' 'GSR.NC' '79666.CE'
 'GNR.NC' 'GWR.NC' 'BARR.BK']
```

Set
stations

How to use *GENIE*

```
[In [30]: z = np.load('3d_velocity_model.npz')

[In [31]: list(z.keys())
Out[31]: ['X', 'Vp', 'Vs']

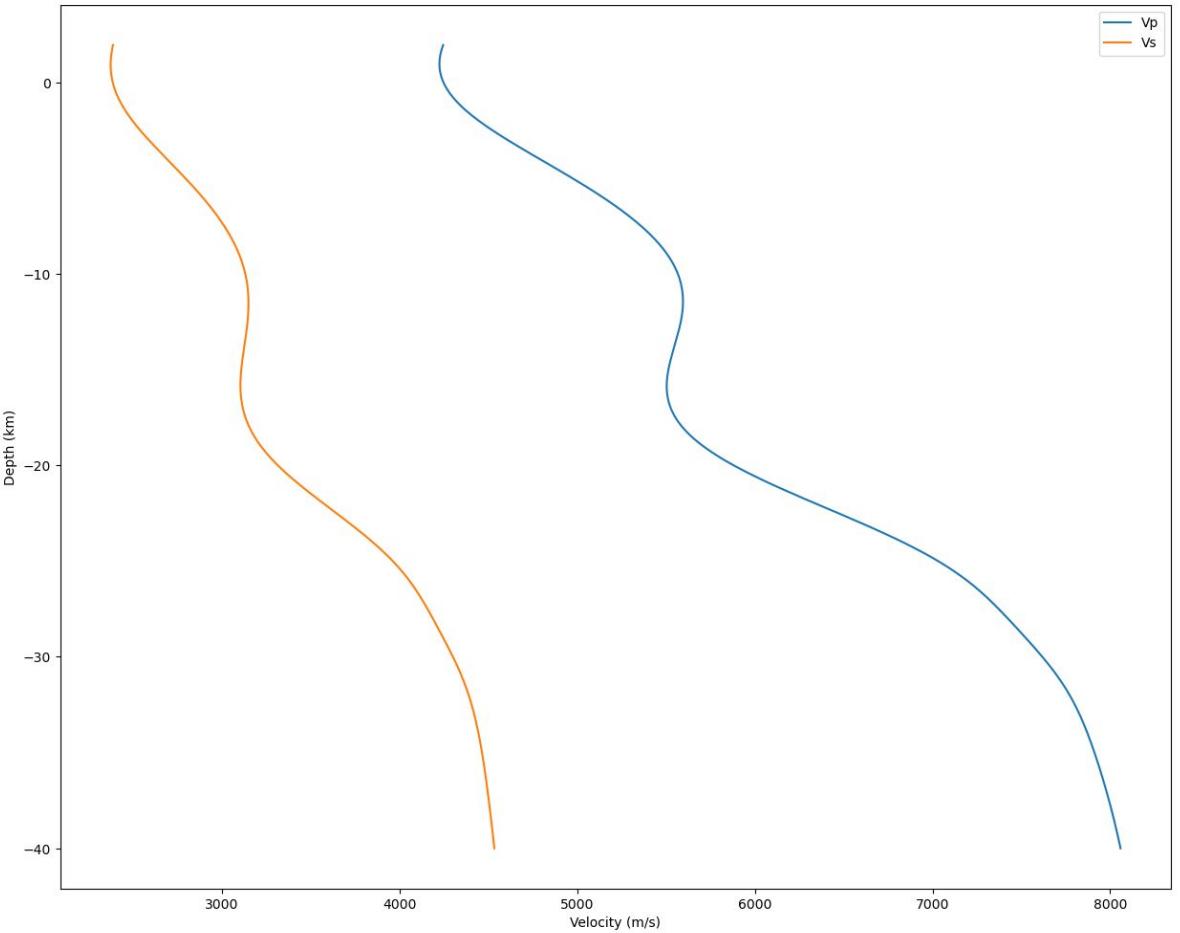
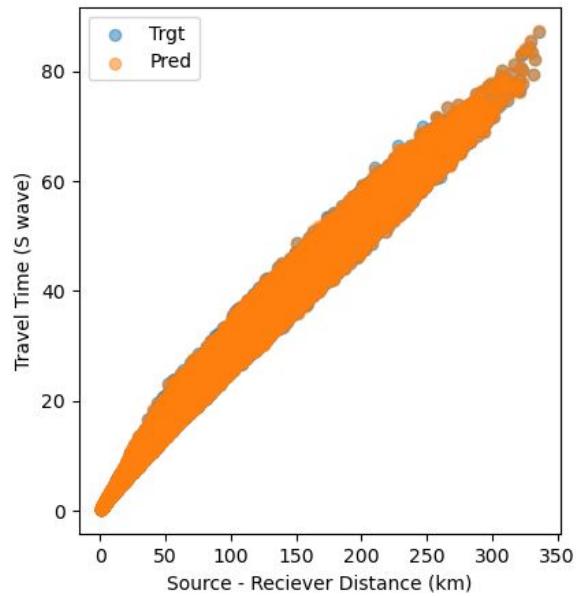
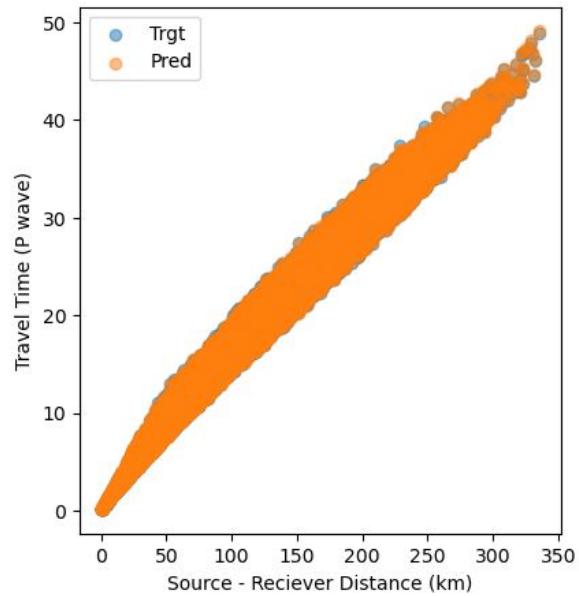
[In [32]: print(z['X'][0:10,:])
[[ 3.94651464e+01 -1.26163064e+02 -4.14937689e+04]
 [ 3.94652337e+01 -1.26162896e+02 -4.09940675e+04]
 [ 3.94653211e+01 -1.26162729e+02 -4.04943661e+04]
 [ 3.94654085e+01 -1.26162561e+02 -3.99946646e+04]
 [ 3.94654958e+01 -1.26162393e+02 -3.94949631e+04]
 [ 3.94655831e+01 -1.26162226e+02 -3.89952615e+04]
 [ 3.94656705e+01 -1.26162058e+02 -3.84955599e+04]
 [ 3.94657578e+01 -1.26161891e+02 -3.79958582e+04]
 [ 3.94658450e+01 -1.26161723e+02 -3.74961565e+04]
 [ 3.94659323e+01 -1.26161556e+02 -3.69964547e+04]]

[In [33]: print(z['Vp'][0:10])
[8027.197 8028.1963 8029.197 8029.8975 8029.9995 8029.9995 8029.9995
 8029.9995 8029.9995 8030.2964]

[In [34]: print(z['Vs'][0:10])
[4509.899 4510.299 4510.8984 4511.0005 4511.0005 4511.0005 4511.
 4511. 4511. 4511.2964]
```

Set velocity
model

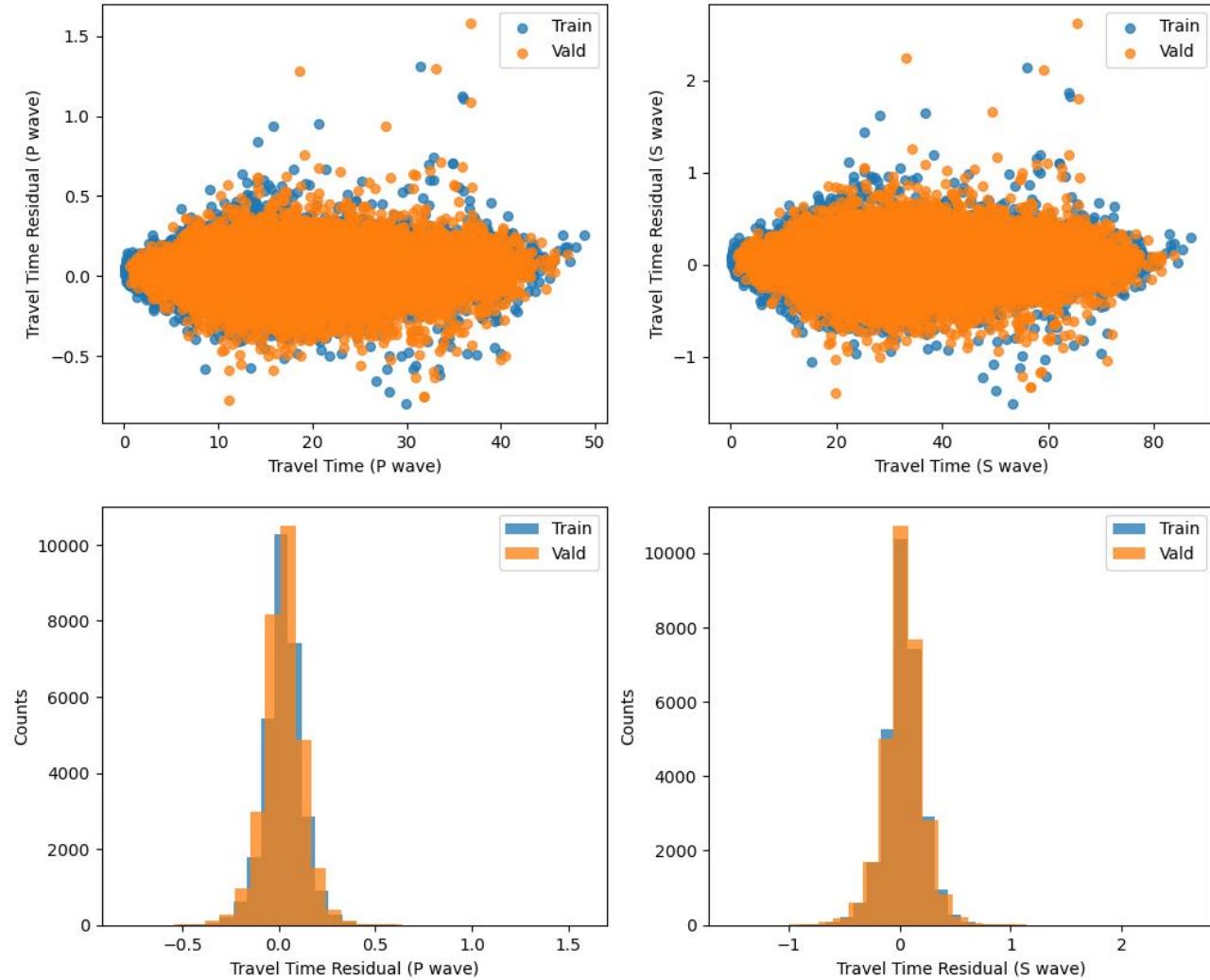
How to use GENIE



Train travel time PINN neural network

How to use GENIE

Accurate even for 3D
velocity models



Train travel time PINN neural
network

How to use GENIE

Set scale and event rate dependent training parameters

Set training data

```
## Prediction params
## These parameters should somewhat scale with the size of the application
kernel_sig_t: 3.5 # Kernel to embed arrival time - theoretical time misfit (s)
src_t_kernel: 3.5 # Kernel of origin time label (s)
src_t_arv_kernel: 3.5 # Kernel for arrival association time label (s)
src_x_kernel: 30000. # Kernel for source label, horizontal distance (m)
src_x_arv_kernel: 30000. # Kernel for arrival-source association label, horizontal distance (m)
src_depth_kernel: 30000. # Kernel of source label in Cartesian projection, vertical distance (m)

## Training params list 2
spc_random : 3500 # Spatial scale to randomly remove true picks from station
sig_t : 0.03 # Percent of travel time error on pick times (e.g., 3%)
spc_thresh_rand : 3500 # Spatial scale to randomly shift threshold distance
min_stations : 6 # Min number of unique stations required for a positive
coda_rate : 0.1 # Percent of picks with false coda picks (e.g., 3.5%)
coda_win : [0, 10.0] # Window that coda picks can occur over (e.g., 25 s)
max_num_spikes : 2 # Number of possible network wide spikes per window T of
spike_time_spread : 0.15 # The temporal spread of the network wide spikes
s_extra : 0.0 # If this is non-zero, it can increase (or decrease) the total
use_stable_association_labels : True # This flag only allows positive association labels
thresh_noise_max : 2.5 # ratio of sig_t*travel time considered excess noise
min_misfit_allowed: 1.0 # The minimum time (in seconds), beneath which, difference between predicted and observed travel times is ignored
total_bias: 0.03 ## Total possible bias on travel times (uniform across stations)
# training_params_2 = [spc_random, sig_t, spc_thresh_rand, min_stations, coda_rate, coda_win, max_num_spikes, spike_time_spread, s_extra, use_stable_association_labels, thresh_noise_max, min_misfit_allowed, total_bias]

## Training params list 3
dist_range : [20000, 225000] # This is the distance range over which to simulate
max_rate_events : 200 # 350 # 450 # Average rate of events per T window of time
max_miss_events : 204 # 225 # 325 # Average rate of missed picks per station
max_false_events : 2.25 # Now by default represents the ratio of false picks
miss_pick_fraction : [0.05, 0.35] # False # Average ratio of missed picks (in percent)
T : 10800 # Time window to simulate synthetic data. More variability occurs
dt : 30 # Time resolution to allow synthetic data parameters to vary in time
tscale : 3600 # Time scale that synthetic data parameters vary in time, during training
n_stations : [0.75, 1.0] # The ratio of possible stations from full set considered
use_sources : False
use_full_network : False
fixed_subnetworks : True ## If True, this uses realistic sets of stations available
use_preferential_sampling : True ## This concentrates more of the samples around source stations
use_extra_nearby_moveouts : True ## This up-samples the amount of sources within a radius
use_shallow_sources : False
```