

Starting with the gear on the DC Motor:

$$\left. \begin{array}{l} \text{Diameter} = 6\text{mm} \\ \text{No. teeth} = 10 \\ \text{Module} = 0.5 \end{array} \right\}$$

$$m = \frac{D_p}{N} = \frac{1}{P} = 0.5$$

$$\therefore P = 2$$

$$\text{Hole diameter} = 1.4\text{mm}$$

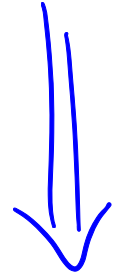
$$P = \frac{N}{D_p} \Rightarrow D_p = \frac{N}{P} = \frac{10}{2} = 5\text{mm.}$$

$$\text{Thickness} = 5\text{mm}$$

$$\Rightarrow \text{face width} = 5\text{mm.}$$

$$P = \frac{\pi}{p} = \frac{\pi}{2}$$

$$\text{tooth thickness} \approx \frac{P}{2} = \frac{(\frac{\pi}{2})}{2} = \frac{\pi}{4}$$



actually measured D_p
value is more like

$$\frac{6-5}{2} = \underline{5.5\text{mm}} \otimes$$

DC Motor speed:

$$6600\text{ rpm} = 691.15\text{ rad/s}$$

(no load)

Desired speed:

$$0.25\text{ m/s} \Rightarrow 20\text{ rad/s}$$

$$(\text{for } r = 0.025\text{m})$$

40 (below)

$$\left. \begin{array}{l} \omega_1 = 20\text{ rad/s} \\ \omega_2 = 691.15\text{ rad/s} \end{array} \right\}$$

$$\frac{\omega_1}{\omega_2} = \frac{20}{691.15} = 0.0289 = \frac{N_2}{N_1}$$

$$\begin{array}{l} \text{reduction} \\ \Rightarrow \text{ratio of} \approx 34.5:1 \end{array}$$

number of teeth
if using 1 gear.

$$N_2 = 10, N_1 = \frac{10}{0.0289} = \underline{346 \text{ teeth.}} \text{ X too much!}$$

SIMPLE gear train: $N_3 = 10, \omega_3 = 691 \text{ rad/s}, \omega_1 = 20 \text{ rad/s}$

$$\frac{\omega_1}{\omega_3} = \frac{N_2}{N_1} \frac{N_3}{N_2} \Rightarrow \frac{N_2 N_3}{N_1 N_2} = \frac{20}{691}$$

does not reduce the size of the final gear, just the direction it turns

$$\frac{10 \cancel{N_2}}{N_1 \cancel{N_2}} = \frac{20}{691}$$

$$\frac{10}{N_1} = \frac{20}{691}$$

$$N_1 = \frac{691}{2} = \underline{345.5}$$

Using COMPOUND gear train: $\omega_4 = \frac{N_1}{N_2} \frac{N_3}{N_4} \omega_1$

$$\Rightarrow \frac{\omega_4}{\omega_1} = \frac{N_1}{N_2} \frac{N_3}{N_4}$$

$$\frac{691}{20} = \frac{N_1}{N_2} \frac{N_3}{10} \therefore \frac{N_1 N_3}{N_2} = \frac{691}{2}$$

$\geq N_n \geq 10$ $\Rightarrow N_1 \& N_3$ too large.

USING $0.5 \text{ m/s} \Rightarrow 40 \text{ rad/s}$

$$\frac{\omega_6}{\omega_1} \frac{691}{40} = \frac{N_1}{N_2} \frac{N_3}{N_4} \frac{N_5}{10}$$

$$\Rightarrow \frac{691}{40} = \frac{x}{1000} \quad x = \frac{69100}{4}$$

smallest combo $\Rightarrow N_2 = N_4 (=N_6) = 10$

$$N_1 N_3 N_5 = 17275$$

$16 \times 27 \times 40 = 17280$

We have: compound gear train, $N_1 = 50$

$$N_2 = 10$$

$$N_3 = 25$$

$$N_4 = 10$$

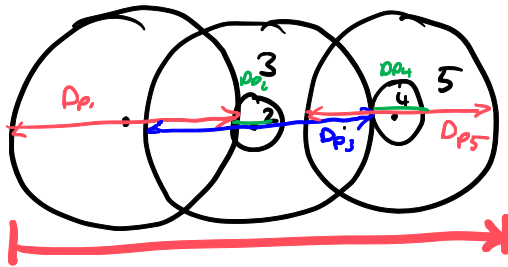
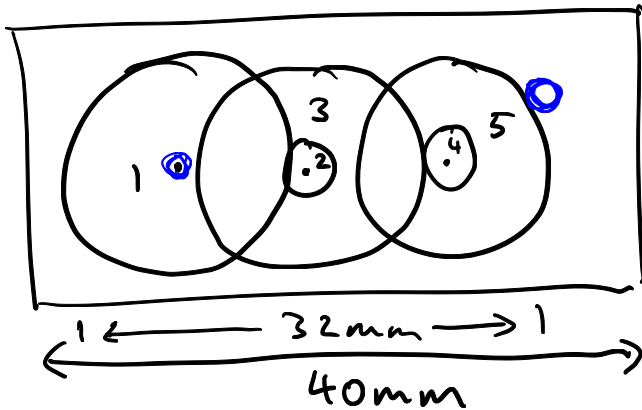
$$N_5 = 14$$

$$N_6 = 10$$

DESIGNING FOR SPACE LIMITATION:

Max length of space = 40mm

$$80\% = 32\text{mm}$$



$$D_{p1} + \frac{D_{p2}}{2} + \frac{D_{p3}}{2} + \frac{D_{p4}}{2} + \frac{D_{p5}}{2} = \text{TOTAL LENGTH}$$

$$\Rightarrow D_{p1} + \frac{1}{2}(D_{p2} + D_{p3} + D_{p4} + D_{p5}) = 32\text{mm}$$

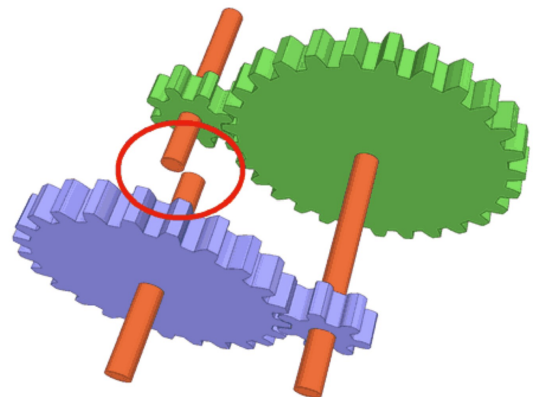
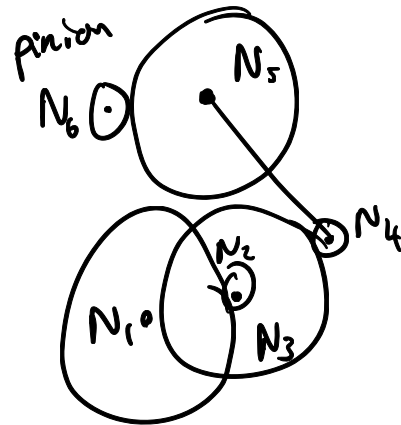
$$\omega_6 = 691 \text{ rad/s}, N_6 = 10$$

$$\omega_5 = \text{---}, N_5 = 14$$

$$\frac{\omega_5}{\omega_6} = \frac{N_6}{N_5} \Rightarrow \omega_5 = \frac{10}{14} \times 691 = 493.6 \text{ rad/s.}$$

$$\frac{\omega_6}{\omega_1} = \frac{N_1}{N_2} \frac{N_3}{N_4} \frac{N_5}{N_6} = \frac{691}{40} = 17.275$$

$N_6 \Rightarrow$ dc motor pinion,
 $d = 6\text{mm}$



ASSUMING HERE:

D_p follows same rules as N :

$$\frac{\omega_6}{\omega_1} = \frac{D_{p1}}{D_{p2}} \frac{D_{p3}}{D_{p4}} \frac{D_{p5}}{D_{p6}} = 17.275$$

$$\Rightarrow D_{P1} D_{P3} D_{P5} = 691$$

$$D_{P2} D_{P4} D_{P6} = 40$$

($D_{P6} = 6\text{mm}$, but also not worrying about this due to config.)

$$\Rightarrow D_{P2} D_{P4} = 40$$

$$\Rightarrow D_{P2} = 8\text{mm}, D_{P4} = 5\text{mm}$$

$$D_{P1} D_{P3} D_{P5} = 691, \quad N_1 > N_3 > N_4$$

$$50 > 25 > 14$$

$$14.4 \times 8 \times 6 = 691.2$$

$$D_{P1} \quad D_{P3} \quad D_{P5}$$

$$S_o, D_{P1} + \frac{1}{2}(D_{P2} + D_{P3} + D_{P4} + D_{P5}) = 14.4 + \frac{1}{2}(8 + 8 + 5 + 6)$$

$$= \underline{27.9\text{mm}}$$

Sooo, can increase: $17 + \frac{1}{2}(8 + 10 + 5 + 7)$

$$= \underline{32\text{mm}}$$

~~$$D_{P1} = 17\text{mm}, N_1 = 50$$~~

~~$$D_{P2} = 8\text{mm}, N_2 = 10$$~~

~~$$D_{P3} = 10\text{mm}, N_3 = 25$$~~

~~$$D_{P4} = 5\text{mm}, N_4 = 10$$~~

~~$$D_{P5} = 7\text{mm}, N_5 = 14$$~~

$$(D_{P6} = 6\text{mm}, N_6 = 10)$$

$$a = m = \frac{D_P}{N}$$

$$d = 1.25\text{m}$$

Gear Parameters:

Gear 6 = driving
DC motor
pinion.

Pitch Diameter, D_p [mm]

Number teeth, N

Diametral pitch, $P = \frac{N}{D_p}$ [1/mm]

Addendum, $a = m = \frac{D_p}{N}$ [mm]

Dedendum, $d = 1.25m$ [mm]

Base circle diameter, $D_b = D_p \cos \phi$ [mm]

Tooth depth, $I = a + d$ [mm]

Tooth thickness, $t = \frac{\pi m}{2}$ [mm]

Design for Meshing:

$$m = 0.5$$

$$P = \frac{N}{D_p}$$

$$a = m = \frac{1}{P} = \frac{D_p}{N}$$

$$\therefore D_p = 0.5N$$

$$D_{p1} = 20$$

$$D_{p2} = 5$$

$$D_{p3} = 14$$

$$D_{p4} = 5$$

$$D_{p5} = 8$$

$$D_{p6} = 5$$

$$\begin{aligned} D_{p1} + \frac{D_{p2}}{2} + \frac{D_{p3}}{2} + \frac{D_{p4}}{2} + \frac{D_{p5}}{2} &= 20 + \frac{1}{2}(5+14+5+8+5) \quad \text{bigger!} \\ &= 20 + 37 = 57 \text{ [mm]} \end{aligned}$$

