# Assignment 3: A Faster IDIOT Implementor's Notes

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Abstract—The goal of this assignment involved implementing the pipelined version of the IDIOT instruction set using the AIK assembler, the Verilog Hardware Design Language and detailed test plan to exhaustively test the different components and logic of the design.

#### I. GENERAL APPROACH

Following the approach of previous assignments, the implementation of this assignment closely followed a heavily modulated design. Both the data and instruction memories where treated as modules along with the ALU incrementor, ALU module (for ALU instructions), the dependency detection module, the register file and the processor itself.

Similar to the previous assignment, global constants were declared both to represent common data structures (like 'WORD) and the different Opcode signals that could be received by the processor (like 'OpAdd or any of the instructions specified by the IDIOT ISA). Also, the AIK specification IDIOT\_SPEC provided by Dr. Dietz following the submission of Assignment 2 was used for the sake of consistency.

The main point of difference for this assignment is the addition of the three buffer modules that are used to share information between modules of the different cycles (Instruction Fetch, Register Read, ALU/Memory, Register Write). These buffers are used to implement the pipelined design and their implementations are described in the next section.

While there are still some incomplete aspects of this assignment (these issues are discussed in the **Issues** section of these notes), the most recent diagram is shown in **Appendix A** at the end of these notes.

# A. Key Notes

Currently every buffer uses an LI register that interacts with the Dependency Detector module to implement value forwarding

Also, the ALU uses an additional operation to directly store values into memory. This is slightly different than what was suggested during class and is detailed in the **Implementation: Stage 3** section of these notes.

## II. IMPLEMENTATION

This section describes how each module was implemented.

## A. Dependency Detector

Module that is used to handle value forwarding/interlock. Basically it checks the LI register in each of the buffers and enables that buffer (allowing it to continue) as long as a dependency issue has not arisen

# B. Stage 0: Instruction Fetch

- 1) Instruction Memory: Memory that interacts with the program counter and instruction buffer, the IR assigns the values of the opcode, destination and source to different values that are sent to the instruction register. These instructions are instantiated on reset by the "inst.txt" file located in the ReaFiles directory.
- 2) Instruction Buffer: Taking signals from the Instruction memory, the Instruction buffer checks it's NOP register to determine if a squash/jump has taken place. If so, it sets it's output signals to zero. It holds values and sends them to the register file if not squashed.
- 3) Incrementor: Small module that is used to account for li instructions after a squash by checking for an enable signal and incrementing based on input.

## C. Stage 1: Register Read

- 1) Register File: Used to store information in desired registers, the register file (known as **registers** in the source) defines the memory used by processor, assign source and destination addresses, transfers it's values to the Register Buffer and ensures that that four special purpose registers will not be overwritten.
- 2) Register Buffer: Taking its input signals from the Register File and the Instruction Buffer, the Register Buffer checks the NOP register like the previous buffer and reacts in the same way as the Instruction Buffer.

# D. Stage 2: ALU/Memory

Important to note here, is that this is primarily where the JZ/SZ/SYZ/FP operations are accounted for. After instantiating the three modules below, the *li2ndWord* variable is used to determine in the current instruction is the second word of li instruction. After making this check, the ALU operation is accounted for by checking the signal associated with *AluOp* and then setting the squashEnable or *jumpEnable* if those cases are met, or a sys call if necessary.

- 1) ALU: Handled similarly to ALU in some of the team member's Assignment 2 solutions, the ALU module takes an opcode and two number inputs, and preforms the operation using a case statement and the Verilog compiler.
- 2) Data Memory: Memory that communicates between the Register Buffer and ALU/Write Buffer, the Data Memory sends the ALU/Write Buffer the readAddr signal passed from the Register Buffer and then writes the result into memory if the right enable received from the Register Buffer is equal to 1.
- 3) ALU/Write Buffer: Again, the ALU/Write buffer is is essentially the same as the previous two buffers except that it takes inputs from the Data Memory, ALU and Register Buffer modules. It checks the buffer's NOP register and then resets values accordingly.

## E. Stage 3: Register Write

This section is important to note as it is where the load/store operations are implemented.

## F. Processor

Used to instantiate all of the previously defined modules, the processor initializes all of the necessary variables that will be used and then calls these modules in succession.

First, Dependency Detection is created after initializing each of the li flags for the buffers, and the processor reset is defined. Then the processor looks to account for NOPS and li flags before going through each of the pipeline cycles detailed above.

## III. TESTING

# A. Utilization of GTKWave

The primary source of testing for this assignment included extensive debugging using the GTKWave application after compiling the source using iVerilog. Simple test files were written using the ISA instructions formed into assembly using the AIK specification provided by Dr. Dietz (aikspec in the IDIOTSource Directory) and tested using GTKWave.

# B. Included Test Files

Currently there are two files that were used to test written code:

- 1) test1Src.txt/inst.txt: This is same example provided by Dr. Dietz in the assignment 3 prompt, it goes through each of the operations and ensures that it is working correctly. This was used as our main test file as it seemed to provide good coverage over the different cases that we hoped to test
- 2) *lijmptest.txt/inst1.txt:* This is simple assembly file that was created while debugging the code using GTKwave. It essentially preforms a simple test that looks at load immediate and jump operations.

## C. Test Coverage

## IV. ISSUES

## A. Features Not implemented

Currently all instructions in the IDIOT ISA seem to implemented as designed. Some issues may lie with with limited ability of the provided testbench as it primarily consists of two separate test files inst.txt and inst2.txt. While these two files are able to test the majority of the necessary instructions used, there are still

#### B. Notable workarounds

- 1) LI Register: As mentioned in the General Approach section of this report, currently every buffer contains a li register that is used to interface the dependency detector to determine if a buffer should be paused or not.
- 2) Load/Store: To account for the Load or Store instructions, the stored opcode opOut is used to determine if a load or store is occurring and then enable the write enable value in memory.

## C. Known Errors

As it currently stands there are no known issues, but this might just involve issues created by the limited test files (as detailed above). All aspects of the assignment seemed to be functional in the debugging process but things might be incorrect due to

# D. Possible Errors

While everything appears to be functional there might be some issues with load/store operations as they are essentially implemented as a separate opcode for the ALU.

## V. APPENDIX

## A. Top Level Design

The high level diagram for the processor is shown on the following page. A larger copy can be found in this directory as well.

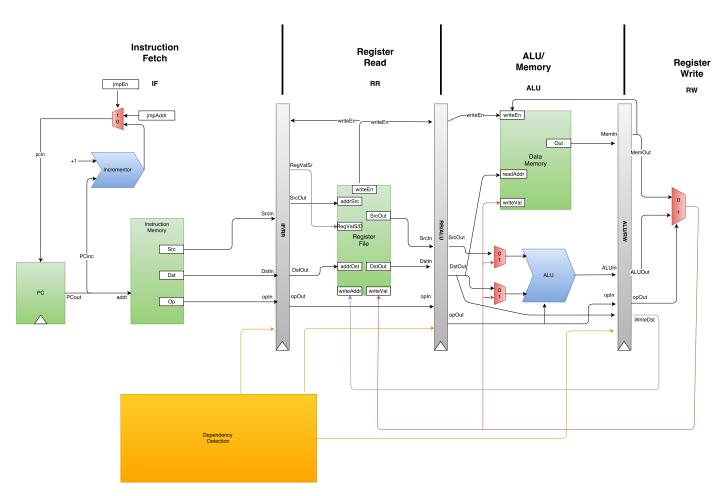


Fig. 1. Initial