view_frames Result

Recorded at time: 1461904289.931

realsense_frame

odom

Broadcaster: /standalone_nodelet
Average rate: 60.303 Hz
Most recent transform: 1461904289.923 (0.008 sec old)
Buffer length: 4.975 sec

Broadcaster: /standalone_nodelet
Average rate: 60.303 Hz
Most recent transform: 1461904289.923 (0.008 sec old)
Buffer length: 4.975 sec

Broadcaster: /virtual_joint_broadcaster_0
Average rate: 10.196 Hz
Most recent transform: 1461904289.973 (-0.042 sec old)
Buffer length: 4.904 sec

camera_depth_optical_frame

camera_color_optical_frame

base_footprint

Broadcaster: /robot_state_publisher
Average rate: 50.200 Hz
Most recent transform: 1461904289.902 (0.028 sec old)
Buffer length: 4.940 sec

base_link

Broadcaster: /robot_state_publisher
Average rate: 50.200 Hz
Most recent transform: 1461904289.902 (0.028 sec old)
Buffer length: 4.940 sec

torso_link

Broadcaster: /robot_state_publisher
Average rate: 50.200 Hz
Most recent transform: 1461904289.902 (0.028 sec old)
Buffer length: 4.940 sec

Broadcaster: /robot_state_publisher
Average rate: 50.200 Hz
Most recent transform: 1461904289.902 (0.028 sec old)
Buffer length: 4.940 sec

Broadcaster: /robot_state_publisher
Average rate: 50.200 Hz
Most recent transform: 1461904289.902 (0.028 sec old)
Buffer length: 4.940 sec

head_base_link

left_arm_base_link

right_arm_base_link

Broadcaster: /robot_state_publisher
Average rate: 50.200 Hz
Most recent transform: 1461904289.902 (0.028 sec old)
Buffer length: 4.940 sec

Broadcaster: /robot_state_publisher
Average rate: 50.200 Hz
Most recent transform: 1461904289.902 (0.028 sec old)
Buffer length: 4.940 sec

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1461904289.906 (0.025 sec old)
Buffer length: 4.900 sec

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1461904289.906 (0.025 sec old)
Buffer length: 4.900 sec

head_base_depth_frame

head_base_rgb_frame

left_arm_shouldera_link

right_arm_shouldera_link

Broadcaster: /robot_state_publisher
Average rate: 50.200 Hz
Most recent transform: 1461904289.902 (0.028 sec old)
Buffer length: 4.940 sec

Broadcaster: /robot_state_publisher
Average rate: 50.200 Hz
Most recent transform: 1461904289.902 (0.028 sec old)
Buffer length: 4.940 sec

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1461904289.906 (0.025 sec old)
Buffer length: 4.900 sec

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1461904289.906 (0.025 sec old)
Buffer length: 4.900 sec

head_base_depth_optical_frame

head_base_rgb_optical_frame

left_arm_shoulderb_link

right_arm_shoulderb_link

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1461904289.906 (0.025 sec old)
Buffer length: 4.900 sec

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1461904289.906 (0.025 sec old)
Buffer length: 4.900 sec

left_arm_biceps_link

right_arm_biceps_link

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1461904289.906 (0.025 sec old)
Buffer length: 4.900 sec

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1461904289.906 (0.025 sec old)
Buffer length: 4.900 sec

left_arm_forearm_link

right_arm_forearm_link

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1461904289.906 (0.025 sec old)
Buffer length: 4.900 sec

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1461904289.906 (0.025 sec old)
Buffer length: 4.900 sec

left_arm_wrist_link

right_arm_wrist_link

Broadcaster: /robot_state_publisher
Average rate: 50.200 Hz
Most recent transform: 1461904289.902 (0.028 sec old)
Buffer length: 4.940 sec

Broadcaster: /robot_state_publisher
Average rate: 50.200 Hz
Most recent transform: 1461904289.902 (0.028 sec old)
Buffer length: 4.940 sec

left_gripper_base_link

right_gripper_base_link

Broadcaster: /robot_state_publisher
Average rate: 50.200 Hz
Most recent transform: 1461904289.902 (0.028 sec old)
Buffer length: 4.940 sec

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1461904289.906 (0.025 sec old)
Buffer length: 4.900 sec

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1461904289.906 (0.025 sec old)
Buffer length: 4.900 sec

Broadcaster: /robot_state_publisher
Average rate: 50.200 Hz
Most recent transform: 1461904289.902 (0.028 sec old)
Buffer length: 4.940 sec

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1461904289.906 (0.025 sec old)
Buffer length: 4.900 sec

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1461904289.906 (0.025 sec old)
Buffer length: 4.900 sec

left_gripper_link

left_gripper_index_link

left_gripper_thumb_link

right_gripper_link

right_gripper_index_link

right_gripper_thumb_link