view_frames Result Recorded at time: 1464113173.831 base_footprint Broadcaster: /robot_state_publisher Average rate: 20.202 Hz Most recent transform: 1464113173.794 (0.038 sec old) Buffer length: 4.950 sec base_link Broadcaster: /robot_state_publisher Average rate: 20.202 Hz Most recent transform: 1464113173.794 (0.038 sec old) Buffer length: 4.950 sec torso_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 20.202 Hz Average rate: 16.868 Hz Average rate: 20.202 Hz Average rate: 20.202 Hz Most recent transform: 1464113173.827 (0.005 sec old) Most recent transform: 1464113173.794 (0.038 sec old) Most recent transform: 1464113173.794 (0.038 sec old) Most recent transform: 1464113173.794 (0.038 sec old) Buffer length: 4.950 sec Buffer length: 4.980 sec Buffer length: 4.950 sec Buffer length: 4.950 sec head_tele_link right_arm_base_link head_col_link left_arm_base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 20.202 Hz Average rate: 16.868 Hz Average rate: 16.868 Hz Most recent transform: 1464113173.794 (0.038 sec old) Most recent transform: 1464113173.827 (0.005 sec old) Most recent transform: 1464113173.827 (0.005 sec old) Buffer length: 4.950 sec Buffer length: 4.980 sec Buffer length: 4.980 sec right_arm_shouldera_link left_arm_shouldera_link head_neck_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 16.868 Hz Average rate: 16.868 Hz Average rate: 16.868 Hz Most recent transform: 1464113173.827 (0.005 sec old) Most recent transform: 1464113173.827 (0.005 sec old) Most recent transform: 1464113173.827 (0.005 sec old) Buffer length: 4.980 sec Buffer length: 4.980 sec Buffer length: 4.980 sec left_arm_shoulderb_link right_arm_shoulderb_link head_pan_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 16.868 Hz Average rate: 16.868 Hz Average rate: 16.868 Hz Most recent transform: 1464113173.827 (0.005 sec old) Most recent transform: 1464113173.827 (0.005 sec old) Most recent transform: 1464113173.827 (0.005 sec old) Buffer length: 4.980 sec Buffer length: 4.980 sec Buffer length: 4.980 sec head_tilt_link right_arm_biceps_link left_arm_biceps_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 20.202 Hz Average rate: 16.868 Hz Average rate: 16.868 Hz Most recent transform: 1464113173.794 (0.038 sec old) Most recent transform: 1464113173.827 (0.005 sec old) Most recent transform: 1464113173.827 (0.005 sec old) Buffer length: 4.950 sec Buffer length: 4.980 sec Buffer length: 4.980 sec right_arm_forearm_link left_arm_forearm_link realsense_link Broadcaster: /robot state publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot state publisher Average rate: 16.868 Hz Average rate: 20.202 Hz Average rate: 20.202 Hz Average rate: 16.868 Hz Most recent transform: 1464113173.794 (0.038 sec old) Most recent transform: 1464113173.794 (0.038 sec old) Most recent transform: 1464113173.827 (0.005 sec old) Most recent transform: 1464113173.827 (0.005 sec old) Buffer length: 4.950 sec Buffer length: 4.950 sec Buffer length: 4.980 sec Buffer length: 4.980 sec realsense_frame head_tracker_A_link right_arm_wrist_link left_arm_wrist_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 20.202 Hz Most recent transform: 1464113173.794 (0.038 sec old) Most recent transform: 1464113173.794 (0.038 sec old) Most recent transform: 1464113173.794 (0.038 sec old) Most recent transform: 1464113173.794 (0.038 sec old) / Most recent transform: 1464113173.794 (0.038 sec old) Buffer length: 4.950 sec left_gripper_base_link head_tracker_B_link camera_depth_optical_frame camera_color_optical_frame right_gripper_base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 16.868 Hz Average rate: 16.868 Hz Average rate: 16.868 Hz Average rate: 16.868 Hz Average rate: 20.202 Hz Average rate: 20.202 Hz Most recent transform: 1464113173.794 (0.038 sec old) Most recent transform: 1464113173.794 (0.038 sec old) Most recent transform: 1464113173.827 (0.005 sec old) Buffer length: 4.950 sec Buffer length: 4.980 sec Buffer length: 4.980 sec Buffer length: 4.950 sec Buffer length: 4.980 sec Buffer length: 4.980 sec left_gripper_link right_gripper_link right_gripper_thumb_link left_gripper_index_link left_gripper_thumb_link right_gripper_index_link