

PID Exercise

20160204

2_wire_charLCD_0.1.f

PID_Exercise_-0.1.f

PID1 folder include Processing files. [Processing2.2.1]

I wrote PID-code to refer site below;

<http://brettbeauregard.com/blog/2011/04/improving-the-beginners-pid-introduction/>

I think Forth-code is easy. (Not using assembler word)

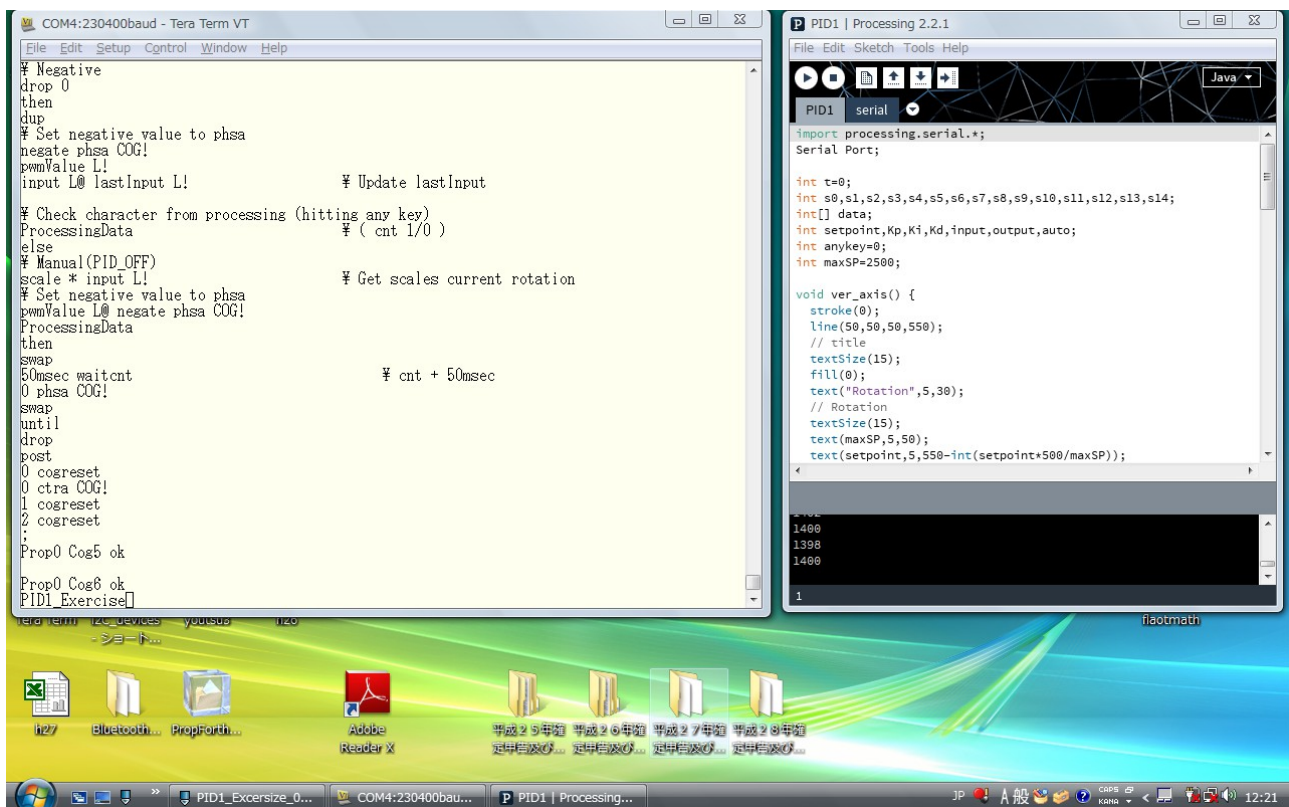
Important thing is only PID-code.

Used PropPlug for communication between PropForth and Processing.

Procedure

1 Loading 2_wire_charLCD_0.1.f and PID_Exercise_-0.1.f.

Start PID1.pde inside PID1 folder.



2 Execute PID1_Exercise

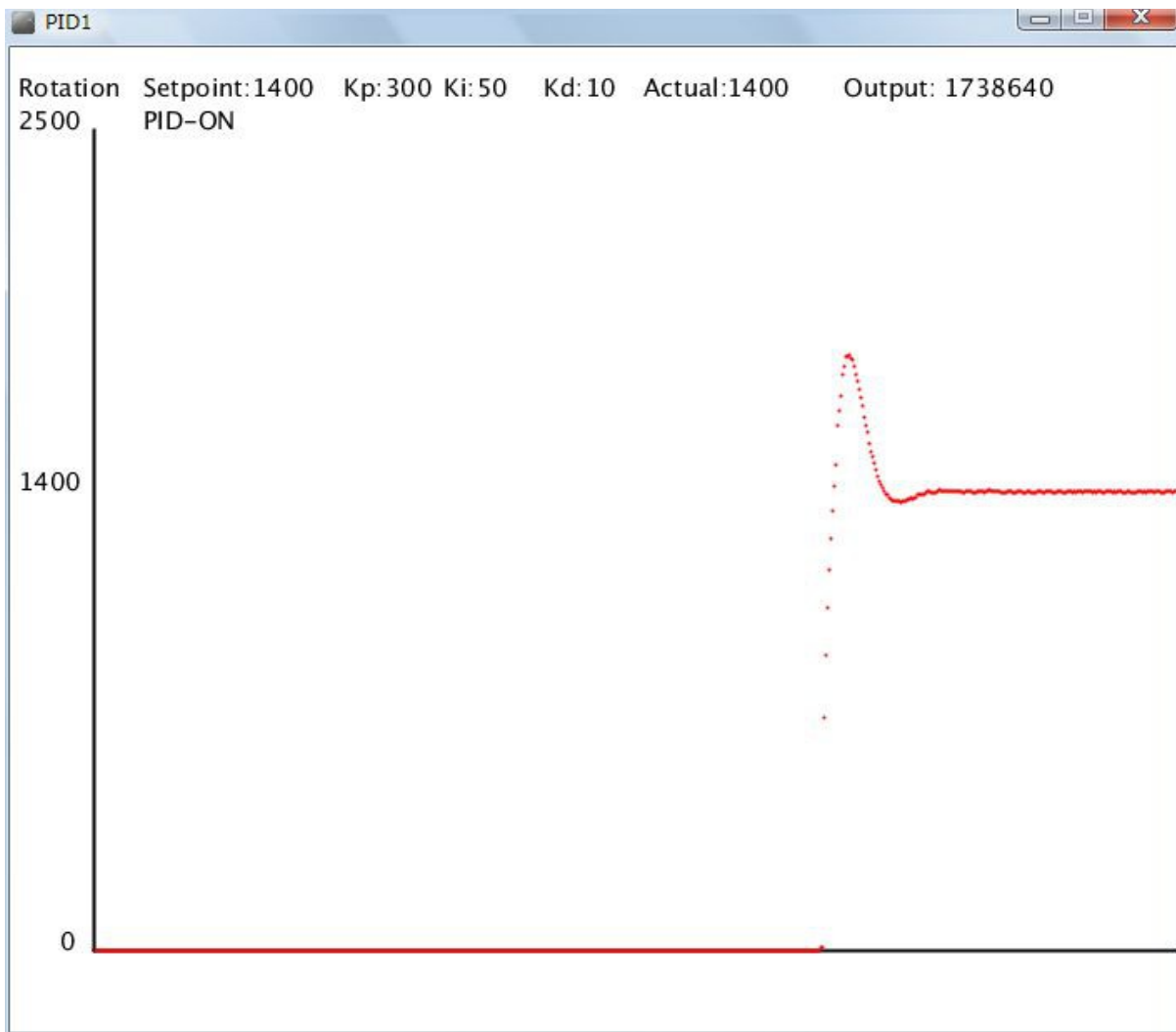
Start PID1.pde → Opened Processing-window

3 Click left-button inside Processing-window.

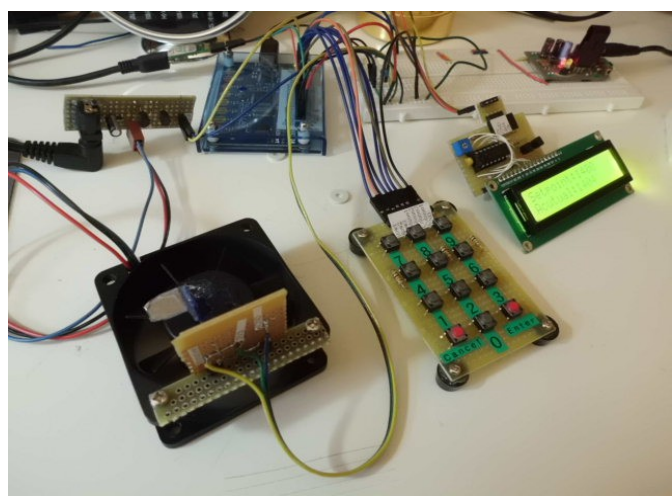
DC-Fan start to rotate.

Rotation-speed drawn inside Processing window.

Default PID-parameters are setpoint:1400, $K_p=300$, $K_i=50$, $K_d=10$.



PID-parameters can be changed by using 12-KeyPad.





Setpoint is from 0 to 2500

By pushing Enter-key, value is entered

By pushing Cancel-key, next item is displayed.



Kp is from 0 to 4095

By pushing Enter-key, value is entered

By pushing Cancel-key, next item is displayed.



Ki is from 0 to 4095

By pushing Enter-key, value is entered

By pushing Cancel-key, next item is displayed.



Kd is from 0 to 4095

By pushing Enter-key, value is entered

By pushing Cancel-key, next item is displayed.



In case of Auto(PID-ON), Output(PWM signal) merely display.

Output(PWM signal) can be changed under Manual (PID-OFF).

Value is from 0 to 100.

By pushing Enter-key, value is entered

By pushing Cancel-key, next item is displayed.



By pushing Enter-key, PID-parameters are adopted.

By pushing Enter-key, value is entered

By pushing Cancel-key, next item is displayed.



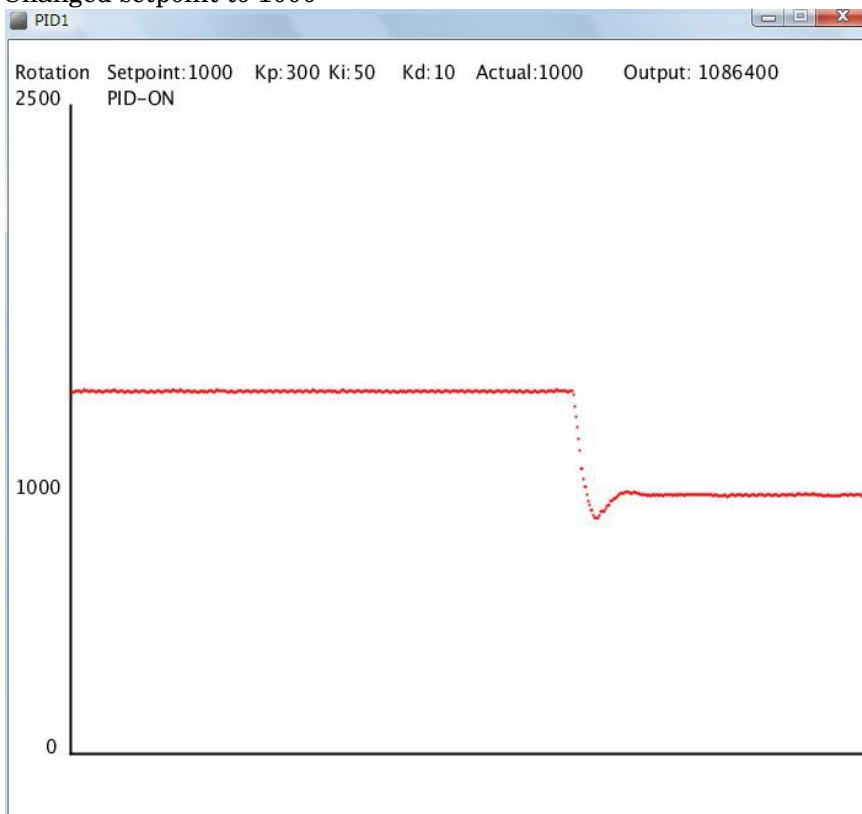
By pushing Enter-key, mode change to "Manual (PID-OFF)".

Displaying "AUTO(PID-ON)".

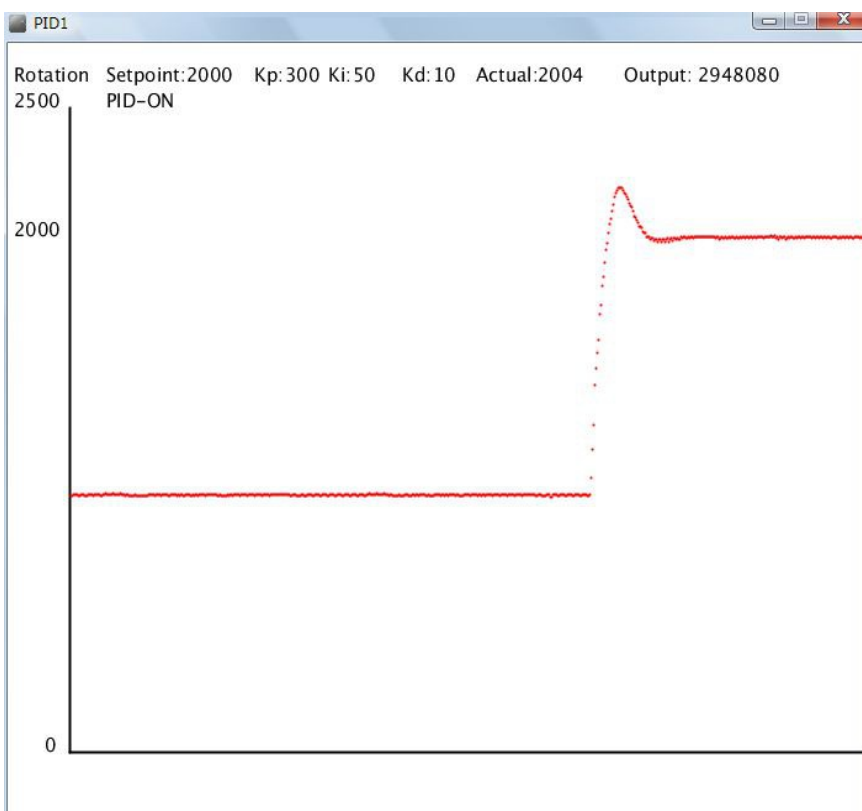
Alterneting "Manual(PID-OFF)" and "AUTO(PID-ON)"

By pushing Cancel-key, back to "Setpoint"

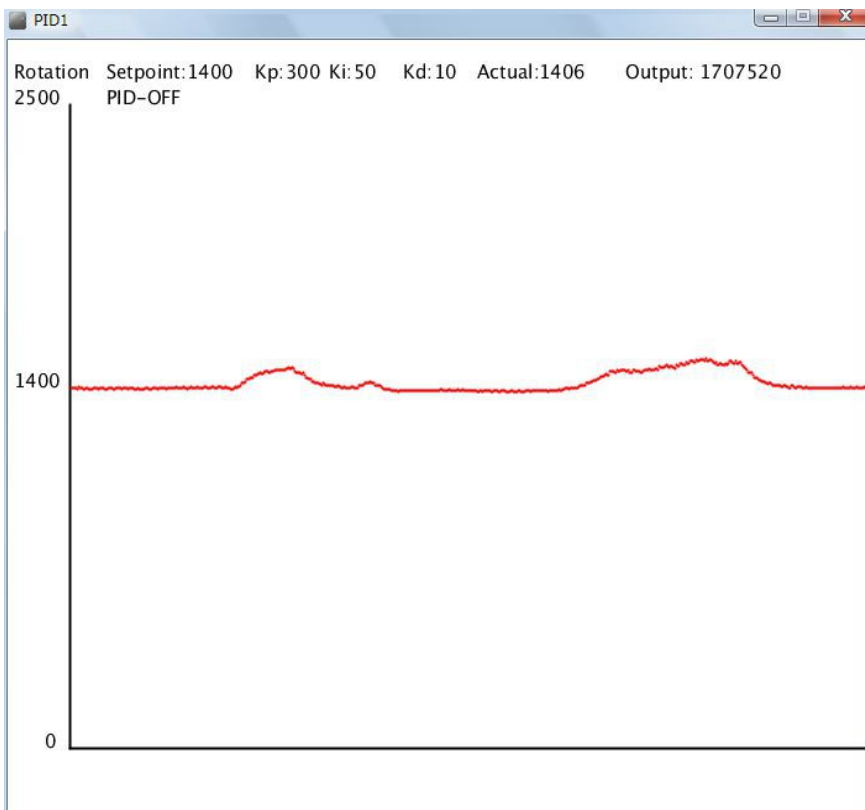
Changed setpoint to 1000



Changed setpoint to 2000



Changed to Manual(PID-OFF)



PID_test.f don't communicat between PropForth and Processing.
Messages are printed to TeraTerm.
So, this is used for debug.