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Abstract

Abstract

The accompanying source code for this thesis, including all deployment and automation scripts, is available in the **PowerStack**[1] repository on GitHub.

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Chapter 1

Introduction and Context

1.1 Introduction and Context

1.1.1 Cloud Computing and its impact on the global energy challenge

Global energy consumption is rising at an alarming pace, driven in part by the accelerating digital transformation of society. A significant share of this growth comes from data centers, which form the physical backbone of cloud computing. While the cloud offers substantial efficiency gains through resource sharing and dynamic scaling, its aggregate energy footprint is growing rapidly. While data center accounted for around 1.5% (around 415 TWh) of the worlds electricity consumption in 2024, they are set to more than double by 2030[2]. That is slightly more than Japans's current electricity consumption today.

This increase is fueled by the rising demand for compute-heavy workloads such as artificial intelligence, large-scale data processing, and real-time services. Meanwhile, traditional drivers of efficiency—such as Moore's law and Dennard scaling—are slowing down[3][4]. Improvements in data center infrastructure, like cooling and power delivery, have helped reduce energy intensity per operation[5], but these gains are approaching diminishing returns. As a result, total data center energy use is expected to grow faster than before, even as efficiency per unit of compute continues to improve more slowly[6].

1.1.2 Rise of the Container

Containers have become a core abstraction in modern computing, enabling lightweight, fast, and scalable deployment of applications. Compared to virtual machines, containers impose less overhead, start faster, and support finer-grained resource control. As such, they are widely used in microservice architectures and cloud-native environments[7].

This trend is amplified by the growing popularity of Container-as-a-Service (CaaS) platforms, where containerized workloads are scheduled and managed at high density on shared infrastructure. Kubernetes has become the de facto orchestration tool for managing such workloads at scale. While containers are inherently more energy-efficient than virtual machines in many scenarios[8], their widespread use presents a new challenge: understanding and attributing their energy consumption accurately.

1.1.3 Container Energy Consumption Measurement Challenges

Knowing the energy consumed by a container on a server is the essential elemenent to a container-level energy efficiency assessment of both the container itself, as well as the environment surrounding it. An accurate energy consumption estimation is therefore required to validate and improve any potential energy efficiency improvements of a container environment, from kubernetes system components (e.g. Kubernetes Schedulers) to the containers themselves.

Energy consumption in containerized systems is inherently hard to measure due to the abstraction layers involved. Tools like RAPL (Running Average Power Limit) expose component-level energy metrics on modern Intel and AMD CPUs, but this information is not accessible from within containers or virtual machines. In public cloud environments, such telemetry is either not exposed or aggregated at coarse granularity, making direct measurement infeasible.

Containers further complicate attribution: because they share the kernel and hard-ware resources, it is difficult to isolate the energy impact of one container from another. Only indirect metrics—such as CPU time, memory usage, or performance counters—are available, and even these may be incomplete or noisy depending on system configuration and workload behavior. Various tools exist that attempt to model container power usage based on these inputs, but rarely are their produced metrics transistent and verified.

1.1.4 Problem Definition

The growing importance of containers in cloud environments, combined with the difficulty of directly measuring their energy usage, motivates this work. In particular, this thesis investigates the questions:

Question 1: Which metrics and models allow for reliable container-level power estimation?

Question 2: How should a software-based container energy consumption estimation tool be implemented?

Question 3: How can exist g container energy consumption estimation tools be validated?

To answer these questions, this study explores methods of measuring server energy consumption, analyzes container workload metrics, and evaluates modeling techniques that aim to bridge the gap between raw energy data and container-level attribution. The focus is on bare-metal Kubernetes environments, where full system observability allows for deeper analysis and model validation, serving as a foundation for future energy-aware cloud architectures.

1.1.5 Context of this thesis

This thesis is part of the Master's program in Computer Science at the Zurich University of Applied Sciences (ZHAW) and represents the second of two specialization projects ("VTs"). The preceding project (VT1) focused on the practical implementation of a test environment for energy efficiency research in Kubernetes clusters. This

thesis (VT2) is meant to explore theoretical and methodolocical aspects of container energy consumption measurements in detail.

Furhtermore, this thesis builds upon prior works focused on performance optimization and energy measurement. EVA1 covered topics such as operating system tools, statistics, and eBPF, while EVA2 explored energy measurement in computer systems, covering hardware, firmware, and software aspects. These foundational topics provide the basis for the current thesis but will not be revisited in detail.

1.1.6 Use of AI Tools

During the writing of this thesis, *ChatGPT*[9] (Version 4o, OpenAI, 2025) was used as an auxiliary tool to enhance efficiency in documentation and technical writing. Specifically, it assisted in:

- Structuring and improving documentation clarity.
- Beautifying and formatting smaller code snippets.
- Assisting in LaTeX syntax corrections and debugging.

All AI-generated content was critically reviewed, edited, and adapted to fit the specific context of this thesis. **ChatGPT was not used for literature research, conceptual development, methodology design, or analytical reasoning.** The core ideas, analysis, and implementation details were developed independently.

1.1.7 Project Repository

All code, configurations, and automation scripts developed for this thesis are publicly available in the PowerStack[1] repository on GitHub. The repository contains Ansible playbooks for automated deployment, Kubernetes configurations, monitoring stack setups, and benchmarking scripts. This allows for full reproducibility of the test environment and facilitates further research or adaptation for similar projects.

Chapter 2

State of the Art and Related Research

2.1 Energy consumption measurement and efficiency on data center level

Energy consumption and efficiency on a data center level has been well-studied to the point where various Literature reviews were published[10][11]. The bigger part of this research is focused on the data center infrastructure (cooling and power), and with good reason, as the data center infrastructure is responsible for a large part of the energy consumption. While a large number of coarse-, medium- and fine-grained metrics for data center energy consumption exist, most data center operators have focused on improving coarse-grained metrics (especially the *Power Utilization Effectiveness*, *PUE*) with improvements to infrastructure. This has resulted in a PUE of 1.1 or lower in some cases[5]. Meanwhile, server energy efficiency has substantially improved, especially for parial load and idle power[12]. This has allowed data center operators to improve energy efficiency by simply installing more efficient cooling and power systems and servers. Fine-grained metrics such as server component utilization rates or speed were generally not used in the context of energy efficiency, but rather as performance metrics to ensure customer satisfaction.

2.2 Energy consumption measurement on a server level

As a result of the energy efficiency improvements of both data center infrastructure and server hardware mentioned in the previous section, a shift has started towards evaluating the actual server load energy efficiency. Efficiency gains on this level compound into further gains at the data center level. The method of resource-sharing of modern cloud computing (and especially the use of containers) have created great opportunities for server workload optimitation for energy efficiency, which in turn require power consumption measurements for evaluation. In the context of containers on multi-core processors, measuring the energy consumption of the entire server is insufficient, since it does not allow the attribution of consumped energy to specific containers or processes. While component-level power measurements provide finer measurements that could theoretically be modelled to display container energy consumption, they drastically raise the complexity for a number of reasons:

- Component-level energy consumption measurement without external tools is far from easy. While some components provide estimation models (e.g. Intel RAPL or Nvidia SMI), others can only be estimated using their performance metrics. This will invariably lead to large measurement uncertainties, especially with the component hardware differences between generations and manufacturers.
- The problem of attributing measured or estimated energy consumption to individual containers is in itself non-trivial: It not only requires a fine-grained time synchronization of energy consumption and used container resources due to the fast-switching nature most server components during any sort of multitasking.
- A deep understanding of dynamic or static energy consumption is required: Depending on the energy consumption attribution model, a container might not only account the energy it actively used, but potentially also account for a fraction of the energy consumed for any shared overhead such as shared hardware components, or system resources (such as the Kubernetes system architecure). This idea can be further extended: containers could potentially be penalized for any unused server resources, as these unused capacity still consume energy. These different attribution models lead to a larger debate about the goals of the measurements.
- Any server-level power models used to estimate the relation of individual component energy consumption suffers from the varity of different server configurations due to server specialization, such as Storage-, GPU-, or Memoryoptimized servers.

•

The following sections of this chapter aim to present the current state-of-the-art in the various fields of research of the problem domains listed above.

• Hardware components: CPU / RAM / SoC / GPU / ...

•

2.3 Overview of Power Data collection

In a systematic review cloud servers power models, Lin et al[13] categorize power collection methods into 4 categories:

| Key | Value | Description | Deployment Difficulty | Data Granularity | Data Credibil- ity |
|--------------------------------------|-------------------------------|-----------------------------------|--------------------------|--------------------------------------|-----------------------|
| Based on instruments | Installation of extra devices | Bare-metal machines | Easy | Machine Level | Very high |
| Based on dedicated aquisition system | Specialized systems | Specified models of ma- chines | Difficult | Machine or component-level | High |
| Based on software monitoring | Build-in power mod- els | Bare-metal and virtual servers | Moderate | Machine, compo- nent, or VM level | Fair |
| Based on simulation | System simulation | Machine, component or VM level | Easy | Machine, compo- nent or VM level | Low |

TABLE 2.1: Comparison of power collection methods for cloud servers

2.3.1 Instrument-based power data aquisition

Instrument-based Data collection aquisition produces the hightest data credibility at a low granularity: These devices, installed externally (measuring the power supplied to the PDU) or internally (measuring the power flow between the PDU and motherboard) have been the source of information for a number of studies. The approach to simply measure electric power at convenient hardware locations using dedicated equipment can of course be extended to provide additional granularity: For example, Desrocher et al[14] custom-created a DIMM extender custom-fitted with Hall-sensor resistors and a linux measurement utility to measure power consumed by a DIMM memory module at 1kHz sampling rate using a *WattsAppPro?* power meter and a *Measurment Computing USB.1208FS-Plus* data aquisition board.

This of course highlights a fundamental truth of instrument-based data collection: While it is possible to implement a measuring solution that provides high-granular and high-sampling rate power data, it is paired with an immense effort since solutions like this are not provided off-the-shelf. Unsuprisingly, this is most valuable for benchmarking or validation (Desrochers used this setup to validate Intel RAPL DRAM power estimations on three different systems). However, this methodology is (currently) unsuitable for deployment to data center servers due to its bad scalability and prohibitive costs. Hence, the primary role of instrument-based power data aquisiton is as a benchmarking and validation tool for research and development.

2.3.2 Dedicated Aquisition systems

2.3.2.1 BMC Devices, IPMI and Redfish

Some manufacturers have developed specialized power data aquisition systems for their own server products. The baseboard management controller (BMC) is a typical dedicated aquisition system usually integrated with the motherboard, usually as part of the intelligent platform management interface (IPMI)[13]. It can be connected to the system bus, sensors and a number of components to provide power and temparature information about the CPU, memory, LAN port, fan, and the BMC itself. Some comprehensive management systems such as Dell iDRAC or Lenovo xClarity have been further developed to provide high-quality, fine-grained power data due to their close interoperation between system software and underlying hardware. BMC devices on modern servers often offer IPMI- or Redfish interfaces. While these interfaces use the same physical servers, their implementation differ significantly, where Redfish generally offers higher accuracy (e.g through the use of higher-bit formats, whereas IPMI often uses 8-bit raw numbers).

In the context of container power consumption estimation, IPMI-implementations occupy an interesting role. In 2016, Kavanagh et al[15] found the accuracy of IMPI

power data to be relatively inaccurate when compared with an external power meter, mainly due to the large measurement window size of 120 to 180 seconds and the inaccurate assessment of the idle power. They concluded that IMPI power data was still useful when a longer averaging window was used, and the initial datapoints discounted. In a later study, they suggest combining the measurements of IPMI and Intel RAPL (which they find to underestimate the power consumption) for a reasonable approximation of true measurement[16]. Kavanagh's findings have been cited in various studies, often to negate the use of IPMI for power measurement. When used, it sometimes is chosed because it was the "simplest power metric to read"[17] in the context of entire data centers.

Redfish is a modern Out-of-band Management System, first released in 2015 explicitely to replace IPMI [18]. It uses a RESTful API and JSON data format, making queries with code easier. In 2019, Wang et al[19] directly compared IPMI and redfish power data to a reading of a high accuracy power analyzer, and found Redfish to be more accurate than IPMI, with a MAPE of 2.9%, while also finding a measurement latency of about 200ms. They also found measurements to be more accurate in higher power ranges, which they attribute to the improved latency.

In conclusion, BMC power data aquired over Redfish provides a simple simple and comparatively easy way to measure system power based on various physical system sensors. Its biggest strenght lies in easy implementation and general availability. In the context of container energy consumption, BMC power data lacks the short sampling rates necessary to measure a a highly dynamcic container setup, but can prove useful as a validation or cross-reference dataset for longer intervals exceeding 120 seconds. Unfortunately, the data quality of BMC power data depends on the actual system, and power models can be significantly improved by initial calibration with an external power measurement device [15].

2.3.3 Power Monitoring Counters: Intel RAPL

Intel Running Average Power Level (RAPL) is a Power Monitoring Counter (PMC)-based feature introduced by Intel and provides a way to monitor and control the energy consumption of various components within their processor package[20]. An adaptation of RAPL for AMD processors uses largely the same mechansms and the same interface[21], although it provides less information than Intel's RAPL, providing no DRAM energy consumption[22].

Intel RAPL has been used extensively in research to measure energy consumption[23] despite some objections about its accuracy, which will be discussed sections 2.3.3.2 and 2.3.3.3. The general concencus is that RAPL is *good enough* for most scientific work in the field of server energy consumption and efficiency. As Raffin et at[24] point out, it is mostly used *like a black box without deep knowledge of its behavior*, resulting in implementation mistakes. For this reason, the next section 2.3.3.1 presents an overview of the RAPL fundamentals. Finally, section 2.7.1 discusses the currently available RAPL-based tools.

2.3.3.1 RAPL measuerment methods

This subsection provides an overview of how RAPL works and is used. It is based on the Intel rchitectures Software Developer's Manual[25, Section 16.10] and the works of Raffin et al [24] (2024) and Schöne et al [26] (2024).

Running Average Power Limit (RAPL) is a power management interface in Intel CPUs. Apart from power limiting and thermal management, it also allows to measure the energy consumed by various components (or domains). These domains individual CPU cores, integrated graphics (in non-server CPUs) and DRAM, as well as package, referring to the whole CPU die. While it initially used models to estimate energy use[27], it now uses physical measurements. The processor is divided into different power domains or "planes", representing specific components, seen in figure 2.1. Notably, not all domains are present in all systems: Both client-grade systems feature the *Package* and *PP0 core* domains, server grade processors typically don't show the PP1 uncore-domain typically used for integrated GPUs, and clientgrade processors don't show the DRAM domain. The PSYS domain for the "whole machine" is ill defined and only exists on client-grade systems. In an experiment with recent Lenovo and Alienware laptops, Raffin et al found that the PSYS domain reported the total consumption of the laptop, including display, dedicated GPU and other domains. Regardless, this thesis will focus on the RAPL power domains available to server-grade processors.

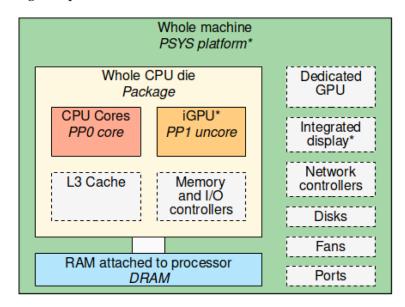


FIGURE 2.1: Hierarchy of possible RAPL domains and their corresponding hardware components. Domain names are in italic, and grayed items do not form a domain on their own, items with an asterisk are not present on servers[24].

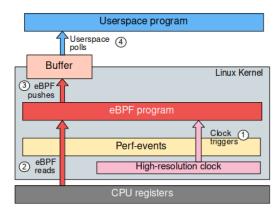
RAPL provides hardware counters to read the energy consumption (and set power limits) for each domain. The energy consumption is measured in terms of processor-specific "energy units" (e.g. 61μ J for Haswell and Skylake processors). The counters are exposed to the operating system through model-specific registers (MSRs) and are updated approximately every millisecond. The main advantages of RAPL are that no external powermeters are required, nor a privileged access to the BMC (which could be used to power off the server). RAPL is more accurate than any untuned statistical estimation model.

Various measurement methods can be used to extract RAPL measurements. In a detailed comparison, Raffin et al[24] outline their individual features and tradeoffs, which are summarize in figure 2.2b:

• The Model-Specific Register (MSR) interface provides low-level access to RAPL

energy counters but is complex and hardware-dependent. Developers must manually determine register offsets and unit conversions based on processor model and vendor documentation. This method lacks safeguards, requires deep processor knowledge, and is error-prone, with incorrect readings difficult to detect. Although read-only access poses no risk to system stability, MSRs expose sensitive data and are thus restricted to privileged users (e.g., root or CAP_SYS_RAWIO). Fine-grained access control is not supported natively, though the msr-safe module offers limited mitigation.

- The **Power Capping (powercap)** framework is a high-level Linux kernel interface that exposes RAPL energy data through the sysfs filesystem, making it accessible from userspace. It simplifies energy measurements by automatically handling unit conversions and domain discovery, requiring minimal hardware knowledge. Though domain hierarchy can be confusing (especially with DRAM domains appearing nested under the package domain) powercap remains user-friendly and scriptable. It supports fine-grained access control via file permissions and offers good adaptability to hardware changes, provided the measurement tool doesn't rely on hard-coded domain structures.
- The perf-events subsystem provides a higher-level Linux interface for accessing RAPL energy counters as counting events. It supports overflow correction and requires less hardware-specific knowledge than MSR. Each RAPL domain must be opened per CPU socket using perf_event_open, and values are polled from userspace. While it lacks a hierarchical structure like powercap and may be harder to use in certain languages or scripts, it remains adaptable and robust across different architectures. Fine-grained access control is possible via kernel capabilities or perf_event_paranoid settings.
- eBPF enables running custom programs in the Linux kernel, and in this context, it is used to directly read RAPL energy counters from within kernel space, potentially reducing measurement overhead by avoiding user-kernel context switches. The implementation attaches an eBPF program to a CPU clock event, using perf_event_open to access energy counters and buffering results for userspace polling (is visualized in figure 2.2a). While offering the same overflow protection as regular perf-events, this approach is significantly more complex, prone to low-level errors (especially in C), and requires elevated privileges (CAP_BPF or root). It also lacks portability, as it demands manual adaptation to kernel features and domain counts, limiting its maintainability across systems.



| mechanism MSR | technical diffi- culty medium | required knowl- edge CPU | safeguards | privileges SYS_RAWIO | resiliency |
|---------------------------|---|-----------------------------------|---|---|--|
| | | knowl- edge | | cap. + msr module | • |
| perf- events + eBPF | high (long, compli- cated code) | limited | overflows unlikely, many other possible mistakes | PERFMON and BPF capabili- ties | manual tweaks necessary for adap- tation |
| perf- events | low | limited | good, overflows unlikely | PERFMON capability | good |
| powercap | low | limited | beware of overflows | read access to one dir | good, very flexible |

(A) RAPL perf-event eBPF mechanism

(B) RAPL measurement mechanisms comparison

FIGURE 2.2: RAPL measurements: eBPF and comparison[24]

In their research, Raffin et al conclude that all four mechanisms have small or negligible impact on the running time of their benchmarks. Based on their findings, formulate the following recommendations:

- Measuring frequencies should be adapted to the state of the node, preventing high measurement overhead, due to a reduction in time spent in low-power states. Under heavy load, a highfrequencay can be used in order to capture more information.
- perf-events is the overall recommeded measurement method with good efficiency, latency and overflow protection. Powercap is less efficient, but provides a simpler sysfs API.
- Even though perf-events and eBPF-measurement method seems to be the most energy-efficient, it is not recommended in light of its complexity. For the same reason, the MSR method is not recommeded, as it raises complexity while counter-intuitively being slower than perf-events

2.3.3.2 Validation

Since its inception, RAPL has been subject of various validation studies, with the general concensus that it's accuracy could be considered "good enough"[24]. Notable works are Hackenberg et al, that in 2013 found RAPL accurate but missing timestamps[28], and in 2015 noticed a major improvement to RAPL accuracy, after Intel switched from a modeling approach to actual measurements for their Haswell architecture[27]. Desrochers et al concluded in a 2016 RAPL DRAM validation study[14] that DRAM power measurement was reasonably accurate, especially on server-grade CPUs. They also found measurement quality to drop when measuring and idling system.

A critical point in the RAPL validation was the introduction of the Alder Lake architecture, marking Intel's first heterogeneous processor, combining two different core architectures from the Core and Atom families (commonly referred to as P-Cores and E-cores) to improve performance and energy efficiency. While this heterogenity can improve performance and energy efficiency, it also increases complexity of scheduling decisions and power saving mechanisms, adding to the already complex

architecture, featuring per-core Dynamic Voltage and frequency Scaling (DVFS), Idle states and Power Limiting / Thermal Protection.

Schöne et al[26] found RAPL in the Alder Lake architecture to be generally consistent with external measurements, but exhibiting lower accuracy in low power scenarios. The following figure 2.3 shows these inaccuracies, albeit tested on a conusmer-grade Intel Core i9-12900K processor measured at the base frequency of 0.8GHz.

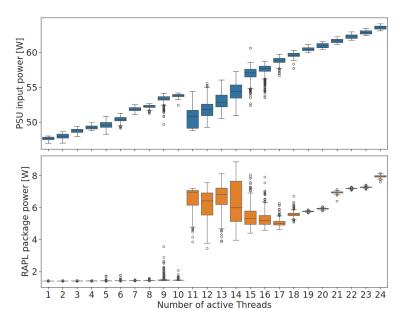


FIGURE 2.3: RAPL and reference power consumption sampled at 100 ms / 50 ms intervals respectively. Double precision matrix multiplication kernel at 0.8GHz running for 60s each at increasing number of active threads[26].

2.3.3.3 Limitations and issues

Several limitations of RAPL were noticed in various research works. Since RAPL is continually improved by Intel as new Processors are released, some of these issues have since been improved or entirely solved.

• **Register overflow:** The 32-bit register can experience an overflow error[24, 29]. This can be mitigated by sampling more frequently than the register takes to overflow. This interval can be calculated using the following equation:

$$t_{\text{overflow}} = \frac{2^{32} \cdot E_u}{P} \tag{2.1}$$

Here, E_u is the energy unit used (61 μ J for haswell), and P is the power consumption. On a Haswell processor consuming 84W, an overflow would occur every 52 minutes. Intel acknowledges this in the official documentation, stating that the register has a *wraparound time of around 60 seconds when power consumption is high*[25] This is solvable with a simple correction, provided that the measurement interfals are small enough: For two successive measurements

 m_{prev} and m_{current} , the actual measured difference is given by

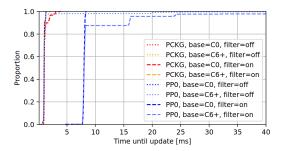
$$\Delta m = \begin{cases} m_{\text{current}} - m_{\text{prev}} + C & \text{if } m_{\text{current}} < m_{\text{prev}} \\ m_{\text{current}} - m_{\text{prev}} & \text{otherwise} \end{cases}$$
 (2.2)

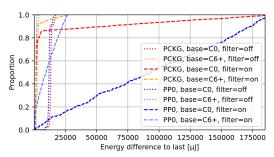
where C is a correction constant that depends on the chosen mechanism:

| mechanism | constant C |
|-----------------------|--|
| MSR | u32::MAX i.e. $2^{32}-1$ |
| perf-events | u64::MAX i.e. $2^{64} - 1$ |
| perf-events with eBPF | u64::MAX i.e. $2^{64} - 1$ |
| powercap | value give by the file max_energy_uj in the sysfs folder |
| | for the RAPL domain |

TABLE 2.2: RAPL overflow correction constant

- **DRAM Accuracy:** DRAM Accuracy can only reliably be used for the Haswell architecture[14, 29], and may still exibit a constant power offset.
- Unpredictable Timings: While the Intel documentation states that the RAPL time unit is 0.976ms, the actual intervals may vary. This is an issue since the measurements do not come with timestamps, making precise measurements difficult[29]. Several coping mechanisms have been used to mitigate this, notably busypolling (busypolling the counter for updates, significantly compromizing overhead in terms of time and energy[30]), supersampling (lowering the sampling interval, increasing overhead and occasionaly creating duplicates that need to be filtered[29]), or high frequency sampling (lowering the sampling rate when the resulting data is still sufficient[31]).
- **Lower idle power accuracy:** When measuring an idling server, RAPL tends to be less accurate[14, 26].
- **Side-channel attacks:** While the update rate of RAPL is usually 1ms, it can get as low as 50 μ s for the PP0 domain (processor cores) on desktop processors[26]. This can be used to retrieve processed data in a side channel attack[26, 32]. To mitigate this issue while retaining RAPL functionality, Intel implements a filtering technique via the ENERGY_FILTERING_ENABLE[33, Table 2-2] entry. This filter adds random noise to the reported values. For the PP0 domain, this raises the temporal granularity to about 8ms. While this does not affect the average power consumption, point measurement power consumption can be affected. Figure 2.4 shows the effect of the filter, clearly indicating the loss granularity resulting from the activation of the filter.





(A) Distribution of time between updates: With an enabled filter, the PP0 domain only provides updates every 8 ms, otherwise RAPL values are updated every 1 ms. If the load is too low, some updates might be skipped, e.g., the next update for PP0 and an enabled filter is at 16 ms.

(B) The minimal increase of a measurement is 1 energy unit of $61.035~\mu J$. Enabling the filter leads to a significant influence on measurements for the PP0 domain and a measurable influence on PCKG measurements.

FIGURE 2.4: Observable loss of granularity caused by the activation of ENERGY_FILTERING_ENABLE[26]

2.4 Server Power models

In the absence of actual power data, power consumption models can be formulated that essentially map variables (such as CPU, Memory utilization) related to a server's state to its power consumption. Due to the strong correlation between CPU uzilization and server power, a great number of models use CPU metrics as the only indicator of server power. Fan et al[34] proposed a linear interpolation between idle power and full power, which they further refine into a non-linear form, with a parameter γ to be fitted to minimize mean square error. Similar research was done to further reduce error by introducting more complex non-linear models, such as Hsu and Poole[35], who studied the SPECpower_ssj2008-dataset of systems released between December 2007 and August 2010, and suggested the adaptation of two non-linear terms:

$$P_{\text{server}} = \alpha_0 + \alpha_1 u_{\text{cpu}} + \alpha_2 (u_{\text{cpu}})^{\gamma_0} + \alpha_3 (1 - u_{\text{cpu}})^{\gamma_1}$$
 (2.3)

While models like these might work well when custom-fitted to specific, multipurpose servers, they have since been surpassed by the more common approach of modelling server power is to consider it an assembly of its components, such as Song et al[36] propose as:

$$P_{\text{server}} = P_{\text{cpu}} + P_{\text{memory}} + P_{\text{disk}} + P_{\text{NIC}} + C \tag{2.4}$$

, where C denotes the server's base power, which includes the power consumption of other components (regarded as static). This approach can easily be extended to include various other components such as GPUs, FPGAs or other connected components.

....

In a systematic review cloud servers power models, Lin et al[13] state that the common way

2.5 Power data collection

see Lin et al for overview -> instruments / dedicated aquisition system / software monitoring and calculation / simulation

- 2.5.1 CPU
- 2.5.2 Memory
- 2.5.3 Storage
- 2.5.4 Networking

2.6 Container energy estimation based on hardware power estimation

2.7 Tools

2.7.1 RAPL-based tools

- [37] An experimental comparison of software-based power meters (focus on CPU / GPU)
- [16] Rapid and accurate energy models through calibration with IPMI and RAPL
- [38] Scaphandre. Does not handle overflows correctly (https://github.com/hubbloorg/scaphandre/issues/280)
- [39] Smartwatts: Self-Calibrating Software-Defined Power Meter for containers
- [40] JoularJX: jaba-based agent for power monitoring at the code level
- [41]: KEPLER
- [42]: "AI power meter": Library to measure energy usage of machine learning programs, uses RAPL for CPU and nvidia-smi for GPU
- [43] CodeCarbon: Python package, estimates GPU + CPU + RAM: uses pynvml, ram RATIO (3W for 8G) and RAPL. According to Raffin2024, this tool does not account for the MSR overflow: https://github.com/mlco2/codecarbon/issues/322 -> apparently fixed now
- [44]: powertop
- [45]: Green metrics tool: measuring energy and CO2 consumption of software through a software life cycle anslysis (SLCA): Metric providers: RAPL, IPMI, PSU, Docker, Temperature, CPU, ... (sone external devices)

according to raffin2024: simplified versions of scaphandre and codecarbon have 3%, 0.5% overhead at 10Hz according to [37], the full versions have between 2 and 7% at 1Hz.

[46]: PowerAPI: Python framework for building software-defined power

2.8 "data fusion of power data and cpu metrics

- Estimating the consumption of a single function has been proven to be possible in 2012: M. Hähnel, B. Döbel, M. Völp, and H. Härtig, "Measuring energy consumption for short code paths using RAPL,", [30]

Appendix A

Appendix Title

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