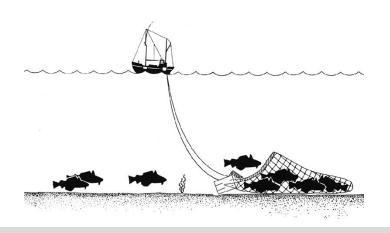
Detecting Fishing Activity in Trawling Vessels with Automatic Identification Systems (AIS) and Machine Learning

David Caspers

15 Sept 2024



Trawling & IUU



Trawling

- Drags funnel-shaped net (trawl)to catch fish
- Targets species near the ocean floor (bottom trawling) or in the water column (midwater trawling).

Effects of Trawling

- Seabed Destruction
- Water Chemistry Alteration
- Bycatch and Waste

Illegal, Unreported, & Unregulated (IUU) Fishing

- Economic Impact:
 - \$10-23B estimated annual cost
 - Undermines legitimate fisheries and threatens coastal communities
- Environment Degradation
- Biodiversity Loss

About the Data

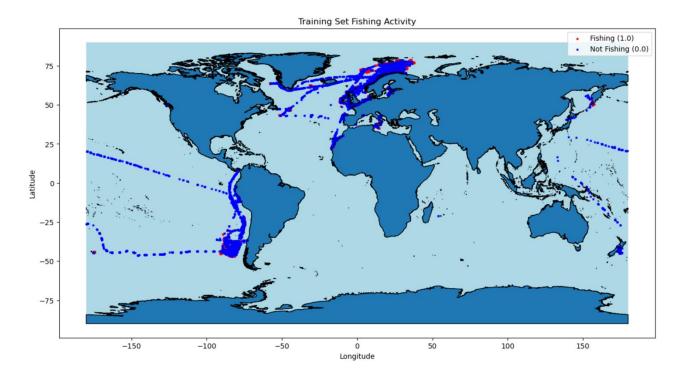
•Source: The dataset is sourced from Global Fishing Watch, an organization that provides open-access data on global fishing activity.

•Key Data Points:

- MMSI: Unique vessel identifier.
- **Timestamp:** Unix timestamp indicating the precise time of transmission.
- **Geolocation**: Latitude and longitude coordinates of the vessel at the time of transmission.
- **Speed and Course**: Vessel speed (in knots) and course (heading).
- **Distance from Shore/Port**: Additional geographic data indicating proximity to shorelines and ports.
- **Fishing Status**: Labels indicating whether a vessel was engaged in fishing at the time of transmission (e.g., 0 = not fishing, >0 = fishing, -1 = no data).

Observations:

4,369,101 labeled AIS signals taken from 49 trawling vessels across the word



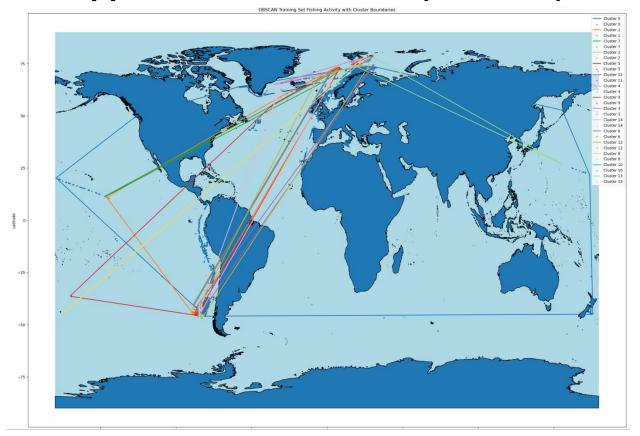
Project Goal

- **Objective:** develop a robust model for detecting fishing activities of trawling vessels using AIS data.
 - Contribute to detection of IUU Fishing detection models by refining fishing detection

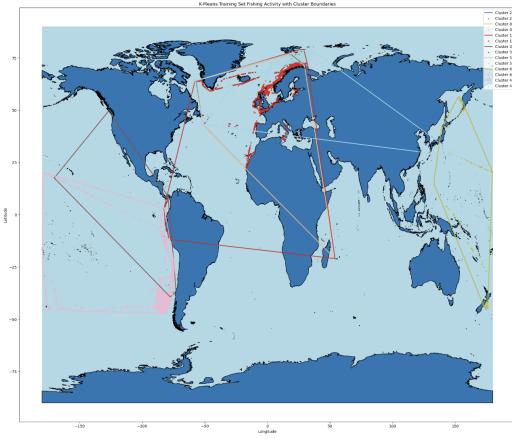


Clustering

Density-Based Spatial Clustering of Applications with Noise (DBSCAN)

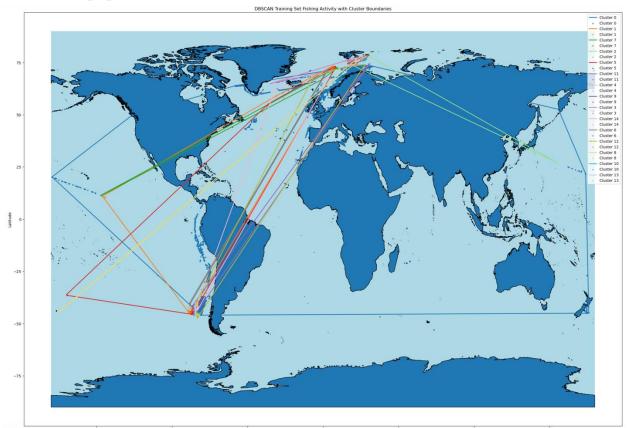


K-Means Clustering



Clustering

Density-Based Spatial Clustering of Applications with Noise (DBSCAN)



Cluster Distribution: 16 Distinct Clusters. Fishing activity concentrated in clusters 1, 2, 3, 4, and 7.

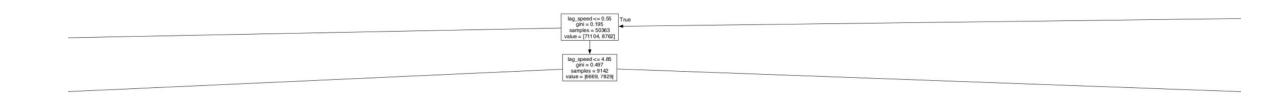
Cluster Characteristics: Clusters 2, 3, and 4 show high fishing percentages, with over 88% of the observations identified as fishing. Cluster 7 is unique with a 100% fishing rate, indicating a specialized area for fishing possibly supported by nearby resources or fish populations.

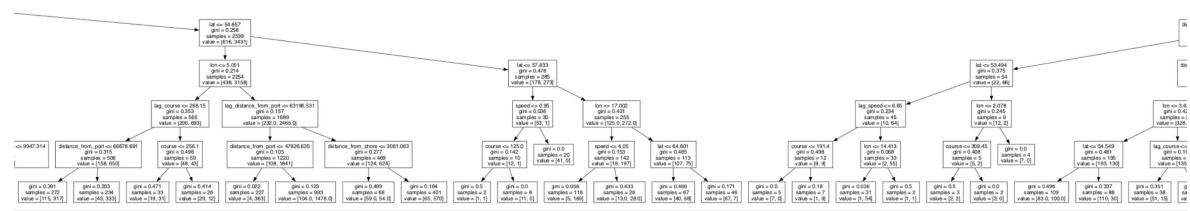
Noise Points: Cluster -1 (noise) accounts for 4,981 points, approximately 5% of the total dataset, with 53.6% of those points classified as fishing.

Geographical Spread: Clusters with high fishing activity (e.g., 2, 3, and 4) are located far from the port and shore, indicating deep-sea fishing operations.

Variability in Distance and Speed: Significant variations in average distances from port and shore across clusters highlight different fishing strategies and vessel capabilities.

Random Forest Classifier





Random Forest Classifier

Results Without Lag

• **Accuracy**: 84.88%

Precision:

Non-Fishing: 0.84

• Fishing: 0.86

Recall:

Non-Fishing: 0.92

• Fishing: 0.75

Top 5 Features:

• **Speed**: 37.57%

• Distance from Shore: 26.06%

• Distance from Port: 16.09%

Latitude: 11.95%Longitude: 6.60%

Results With Lag

• **Accuracy**: 87.69%

• Precision:

Non-Fishing: 0.88

• Fishing: 0.87

Recall:

Non-Fishing: 0.91

• Fishing: 0.80

Top 5 Features:

• Lag Speed: 31.00%

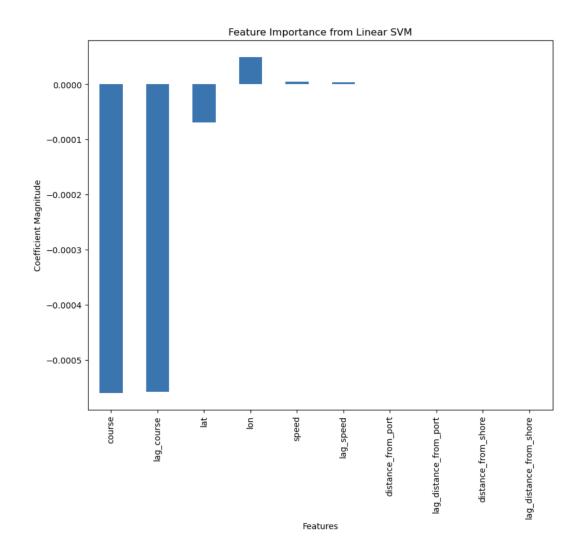
• **Speed**: 21.54%

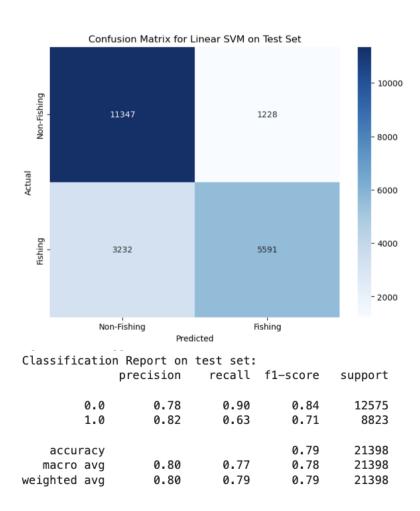
• Lag Distance from Shore: 16.94%

• Distance from Shore: 8.80%

• **Latitude**: 6.65%

Support Vector Machine (Linear Kernal)





Conclusion

Vessel activity is highly variable and noisy

• This introduces challenges in accurately identifying consistent fishing patterns, as vessel behavior is not uniform.

Time-series data is critical for detecting fishing activity

• Sequential changes in vessel behavior, such as speed and movement over time, are key for accurate classification.

Speed and distance from shore are the strongest predictors of fishing activity

• Speed variations and proximity to shore or deep-sea areas offer clear indicators for distinguishing fishing from non-fishing activities.

Future improvements should focus on handling sequential data

 Models that can account for the sequential nature of the data such as Long Short-Term Memory (LSTM) Networks or Recurrent Neural Networks (RNN)