

Pseudo-code of optimized SNI refresh gadgets

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The input (resp., output) sharing is denoted as \mathbf{x} (resp., \mathbf{y}). All r_i variables are independent uniform random elements, and \mathbf{s}^i are vectors of d independent randoms elements. The $(\cdot \gg i)$ operator applied to a vector denotes a rotation of its elements: the 1st element becomes the $i + 1$ -th, etc. Registers are denoted as $R[\cdot]$.

$ \begin{aligned} & d = 2 \\ & y_0 \leftarrow R[x_0 + r_0] \\ & y_1 \leftarrow R[x_1 + r_0] \\ & d = 3 \\ & t_0 \leftarrow R[r_0 + r_1] \\ & y_0 \leftarrow R[x_0 + r_0] \\ & y_1 \leftarrow R[x_1 + r_1] \\ & y_2 \leftarrow R[x_2 + t_0] \\ & d = 4, 5 \\ & \mathbf{t}^0 \leftarrow R[\mathbf{s}^0 + (\mathbf{s}^0 \gg 1)] \\ & \mathbf{y} \leftarrow R[\mathbf{x} + \mathbf{t}^0] \\ & d = 6 \\ & \mathbf{t}^0 \leftarrow R[\mathbf{s}^0 + (\mathbf{s}^0 \gg 1)] \\ & t_0^0 \leftarrow R[t_0^0 + r_0] \\ & t_3^0 \leftarrow R[t_3^0 + r_0] \\ & \mathbf{y} \leftarrow R[\mathbf{x} + \mathbf{t}^0] \\ & d = 7 \\ & \mathbf{t}^0 \leftarrow R[\mathbf{s}^0 + (\mathbf{s}^0 \gg 1)] \\ & t_0^0 \leftarrow R[t_0^0 + r_0] \\ & t_2^0 \leftarrow R[t_2^0 + r_1] \\ & t_4^0 \leftarrow R[t_4^0 + r_0] \\ & t_6^0 \leftarrow R[t_6^0 + r_1] \\ & \mathbf{y} \leftarrow R[\mathbf{x} + \mathbf{t}^0] \\ & d = 8 \\ & \mathbf{t}^0 \leftarrow R[\mathbf{s}^0 + (\mathbf{s}^0 \gg 1)] \\ & t_0^0 \leftarrow R[t_0^0 + r_0] \\ & t_1^0 \leftarrow R[t_1^0 + r_1] \\ & t_2^0 \leftarrow R[t_2^0 + r_2] \\ & t_4^0 \leftarrow R[t_4^0 + r_0] \\ & t_5^0 \leftarrow R[t_5^0 + r_1] \end{aligned} $	$ \begin{aligned} & t_6^0 \leftarrow R[t_6^0 + r_2] \\ & \mathbf{y} \leftarrow R[\mathbf{x} + \mathbf{t}^0] \\ & d = 9 \\ & \mathbf{t}^0 \leftarrow R[\mathbf{s}^0 + (\mathbf{s}^0 \gg 1)] \\ & t_0^0 \leftarrow R[t_0^0 + r_0] \\ & t_1^0 \leftarrow R[t_1^0 + r_1] \\ & t_3^0 \leftarrow R[t_3^0 + r_2] \\ & t_4^0 \leftarrow R[t_4^0 + r_0] \\ & t_6^0 \leftarrow R[t_6^0 + r_1] \\ & t_7^0 \leftarrow R[t_7^0 + r_2] \\ & \mathbf{y} \leftarrow R[\mathbf{x} + \mathbf{t}^0] \\ & d = 10 \\ & \mathbf{t}^0 \leftarrow R[\mathbf{s}^0 + (\mathbf{s}^0 \gg 1)] \\ & t_0^0 \leftarrow R[t_0^0 + r_0] \\ & t_1^0 \leftarrow R[t_1^0 + r_1] \\ & t_2^0 \leftarrow R[t_2^0 + r_2] \\ & t_3^0 \leftarrow R[t_3^0 + r_3] \\ & t_4^0 \leftarrow R[t_4^0 + r_4] \\ & t_5^0 \leftarrow R[t_5^0 + r_0] \\ & t_6^0 \leftarrow R[t_6^0 + r_1] \\ & t_7^0 \leftarrow R[t_7^0 + r_2] \\ & t_8^0 \leftarrow R[t_8^0 + r_3] \\ & t_9^0 \leftarrow R[t_9^0 + r_4] \\ & \mathbf{y} \leftarrow R[\mathbf{x} + \mathbf{t}^0] \\ & d = 11 \\ & \mathbf{t}^0 \leftarrow R[\mathbf{s}^0 + (\mathbf{s}^0 \gg 1)] \\ & t_0^0 \leftarrow R[t_0^0 + r_0] \\ & t_1^0 \leftarrow R[t_1^0 + r_1] \\ & t_2^0 \leftarrow R[t_2^0 + r_2] \end{aligned} $	$ \begin{aligned} & t_3^0 \leftarrow R[t_3^0 + r_3] \\ & t_4^0 \leftarrow R[t_4^0 + r_4] \\ & t_5^0 \leftarrow R[t_5^0 + r_0] \\ & t_6^0 \leftarrow R[t_6^0 + r_1] \\ & t_7^0 \leftarrow R[t_7^0 + r_2 + r_5] \\ & t_8^0 \leftarrow R[t_8^0 + r_3] \\ & t_9^0 \leftarrow R[t_9^0 + r_4] \\ & t_{10}^0 \leftarrow R[t_{10}^0 + r_5] \\ & \mathbf{y} \leftarrow R[\mathbf{x} + \mathbf{t}^0] \\ & d = 12 \\ & \mathbf{t}^0 \leftarrow R[\mathbf{s}^0 + (\mathbf{s}^0 \gg 1)] \\ & t_0^0 \leftarrow R[t_0^0 + r_0] \\ & t_1^0 \leftarrow R[t_1^0 + r_1] \\ & t_2^0 \leftarrow R[t_2^0 + r_2 + r_6] \\ & t_3^0 \leftarrow R[t_3^0 + r_3] \\ & t_4^0 \leftarrow R[t_4^0 + r_4] \\ & t_5^0 \leftarrow R[t_5^0 + r_5 + r_6] \\ & t_6^0 \leftarrow R[t_6^0 + r_0] \\ & t_7^0 \leftarrow R[t_7^0 + r_1] \\ & t_8^0 \leftarrow R[t_8^0 + r_2 + r_7] \\ & t_9^0 \leftarrow R[t_9^0 + r_3] \\ & t_{10}^0 \leftarrow R[t_{10}^0 + r_4] \\ & t_{11}^0 \leftarrow R[t_{11}^0 + r_5 + r_7] \\ & \mathbf{y} \leftarrow R[\mathbf{x} + \mathbf{t}^0] \\ & d = 13, \dots, 16 \\ & \mathbf{t}^0 \leftarrow R[\mathbf{s}^0 + (\mathbf{s}^0 \gg 1)] \\ & \mathbf{t}^1 \leftarrow R[\mathbf{s}^1 + (\mathbf{s}^1 \gg 3)] \\ & \mathbf{t}^2 \leftarrow R[\mathbf{t}^0 + \mathbf{t}^1] \\ & \mathbf{y} \leftarrow R[\mathbf{x} + \mathbf{t}^2] \end{aligned} $
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