$$\frac{1}{(\alpha)} \frac{1}{100 - 105} = \frac{1}{2} \text{ kn } \text{ Vov}^2$$

 $\Rightarrow \frac{5-1}{R0} = \frac{1}{2} \times 10^{-2} \times 0.2^{2}$

(b)
$$\frac{1}{2}$$
 km. $(V_{65} - V_{4})^{2} = \frac{V_{50} - (V_{65} - V_{4})}{R_{0}}$
=) $\frac{1}{2} \times 10^{-2} \cdot (V_{65} - V_{4})^{2} = \frac{5 - (V_{65} - V_{4})}{20 \times 10^{3}}$

(c)
$$I_0 = \frac{5-1}{20k} = 200 \mu H$$

 $g_m = \frac{2J_0}{V_{0V}} = \frac{400 m}{0.2} = 2 mS$
 $A_V = -g_m R_0 = -40 \%$

(d)
$$V_{DS, B} = 0.219 V$$

 $V_{DS, Q} = 1 V$

=) negative signal swing:
$$1 - 0.219 = 0.781 V$$
#

$$\Rightarrow$$
 peak input signal = $\frac{V_0}{AV} = \frac{19.525 \text{ mV}}{4}$

(a)
$$V_{DS} + 0.5 \le V_{DD}$$
, $V_{DS} - 0.5 \ge V_{DV}$
 $\Rightarrow V_{DS} \le 4.5V$ $\Rightarrow V_{DS} \ge 0.7V$

(b)
$$A_{V} = -g_{m} R_{D} = -\frac{2I_{D}R_{D}}{V_{OV}} = \frac{-2(5-0.7)}{V_{OV}} = \frac{-2(5-0.7)}{0.7} = \frac{-43 \text{ /v}}{43} = \frac{0.5}{V_{95}} = V_{95} = 11.628 \text{ mV}$$

(d)
$$I_D = \frac{1}{2} kn' \frac{W}{L} V_{ov}^2 \Rightarrow \frac{W}{L} = \frac{25}{4}$$

or
 $-43 = -kn' \frac{W}{L} V_{ov} \cdot R_D \Rightarrow \frac{W}{L} = \frac{25}{4}$

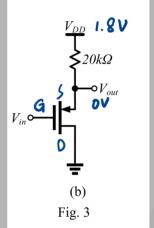


Fig. 3

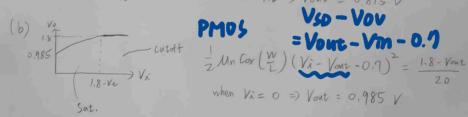
Fig. 3

$$V_{0.815}$$
 $V_{1.8}$

When $V_{i} = 1.8 \Rightarrow V_{0.00}$

Fig. 3

 $V_{0.815}$
 $V_{0.815}$



(a)
$$I_D = \frac{1}{2} kn \left(V_{QS} - V_{ER} \right)^2 = 7.5 \times 10^{-3} \left(0.6 - 0.4 \right)^2 = 0.1 \text{ mA}_{\frac{11}{4}}$$

 $V_{DS} = V_{DD} - I_D R_D = 0.8 V_{\frac{11}{4}}$

(d)
$$r_0 = \frac{1}{\lambda I_0} = 100 \text{ k}$$

 $Av = -9m (Ro // r_0) = -9.09 7_{VA}$

(a)
$$Av = -g_m Rb = -10$$

=) $g_m = 0.5 \text{ m/s} \neq 1$

(b)
$$I_D = \frac{V_{DD} - V_{peak}}{R_D} = \frac{1.8 - 0.2}{20 \, \text{k}} = 80 \, \text{mA}$$

$$f_M = \frac{2I_D}{V_{oV}} = V_{oV} = 0.32 \, V_{\#}$$

(c)
$$I_0 = \frac{1}{2} u_n Cox \frac{W}{L} v_{ov}^2$$

=) $\frac{W}{L} = 7.81 \pm 1$

(d)
$$V_{0V} = 0.32 = V_{95} - V_{th}$$

=) $V_{95} = 0.72 V_{#}$