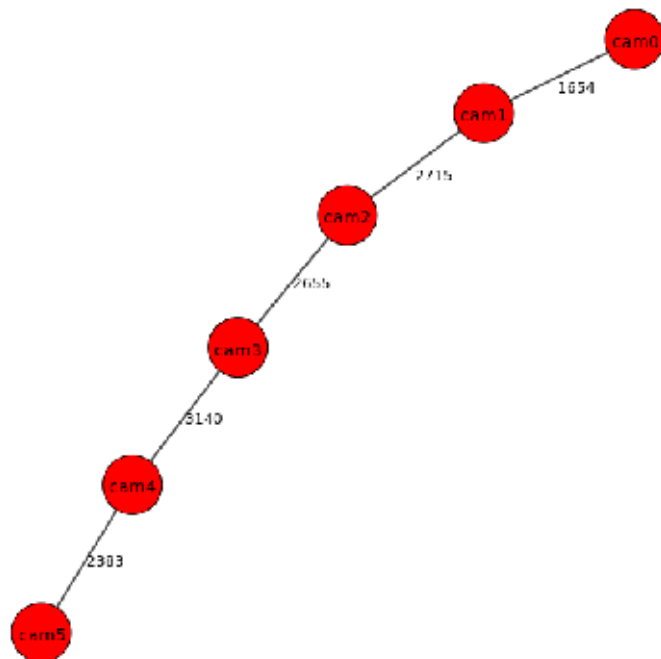
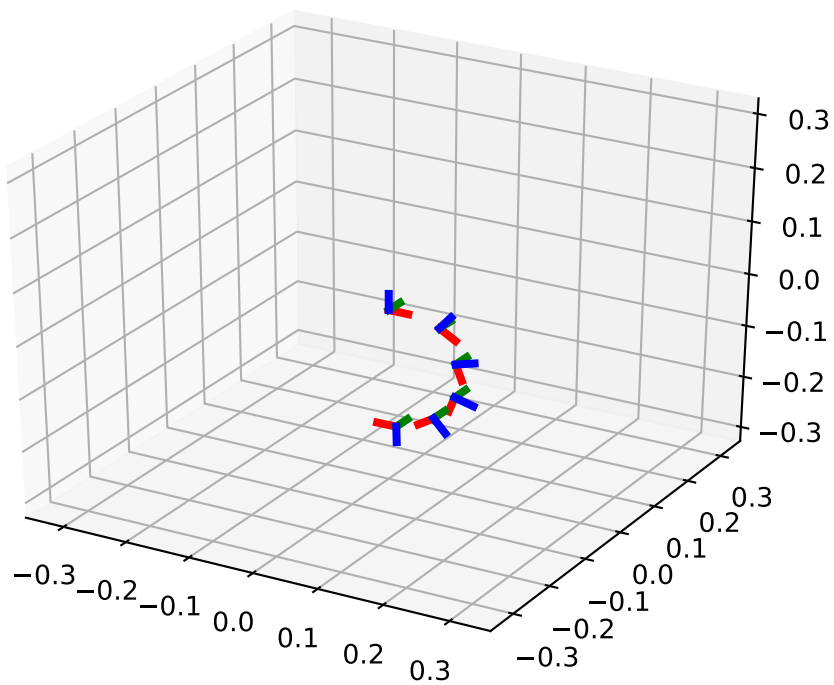


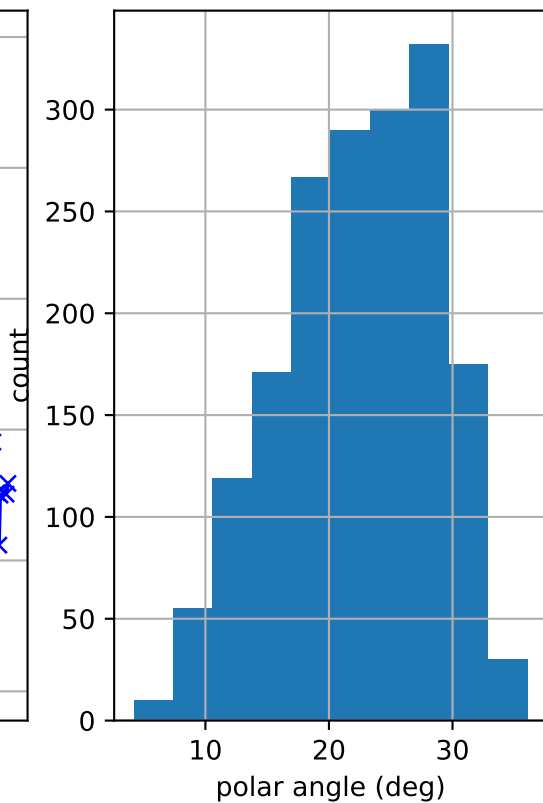
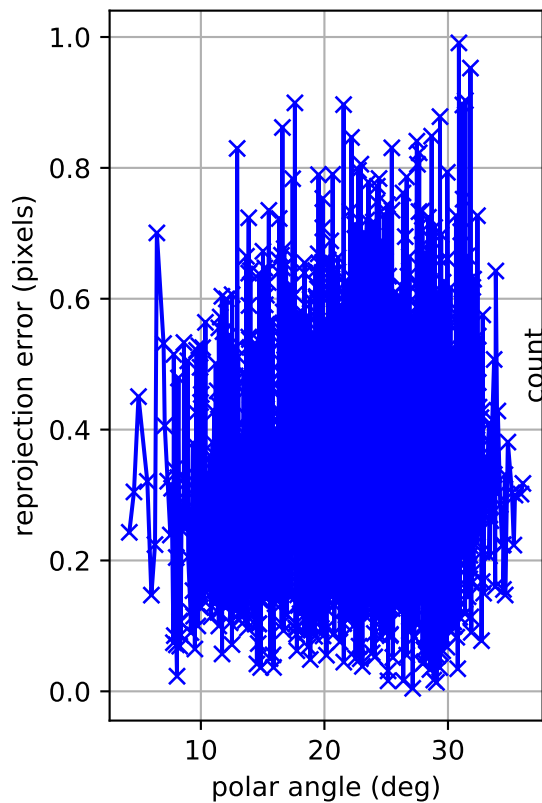
Inter-camera observations graph (edge weight=#mutual obs.)



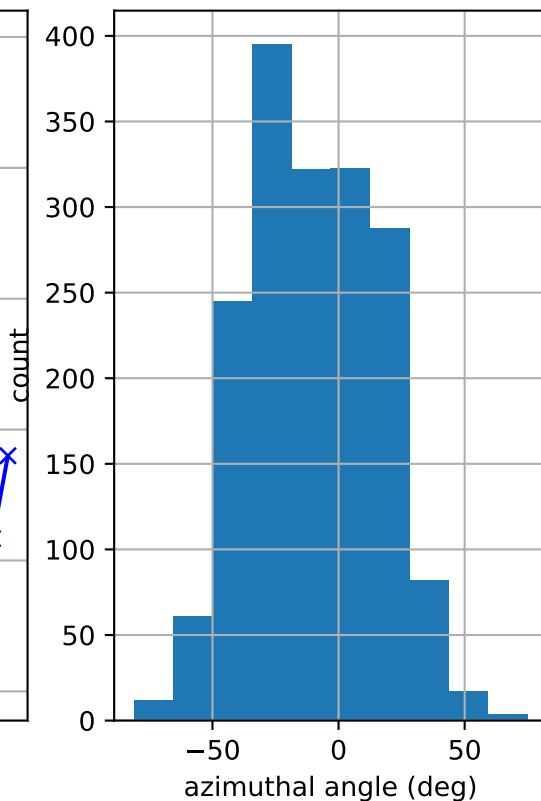
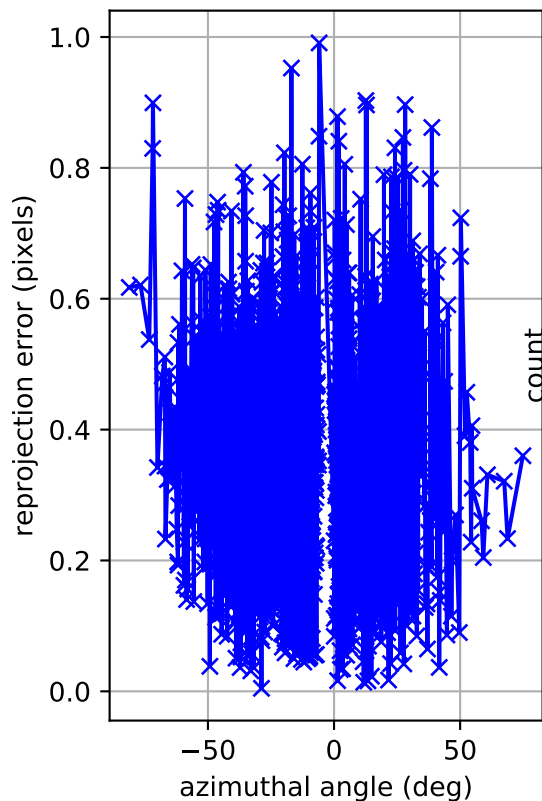
camera system



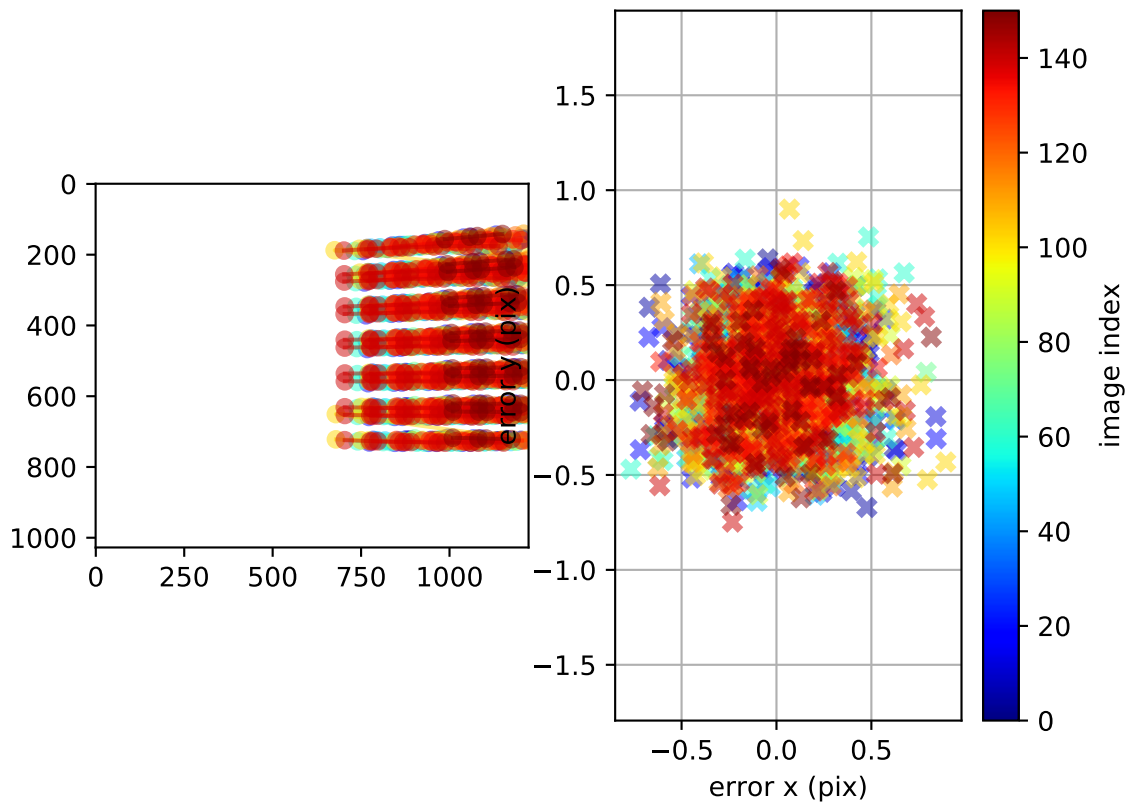
cam0: polar error



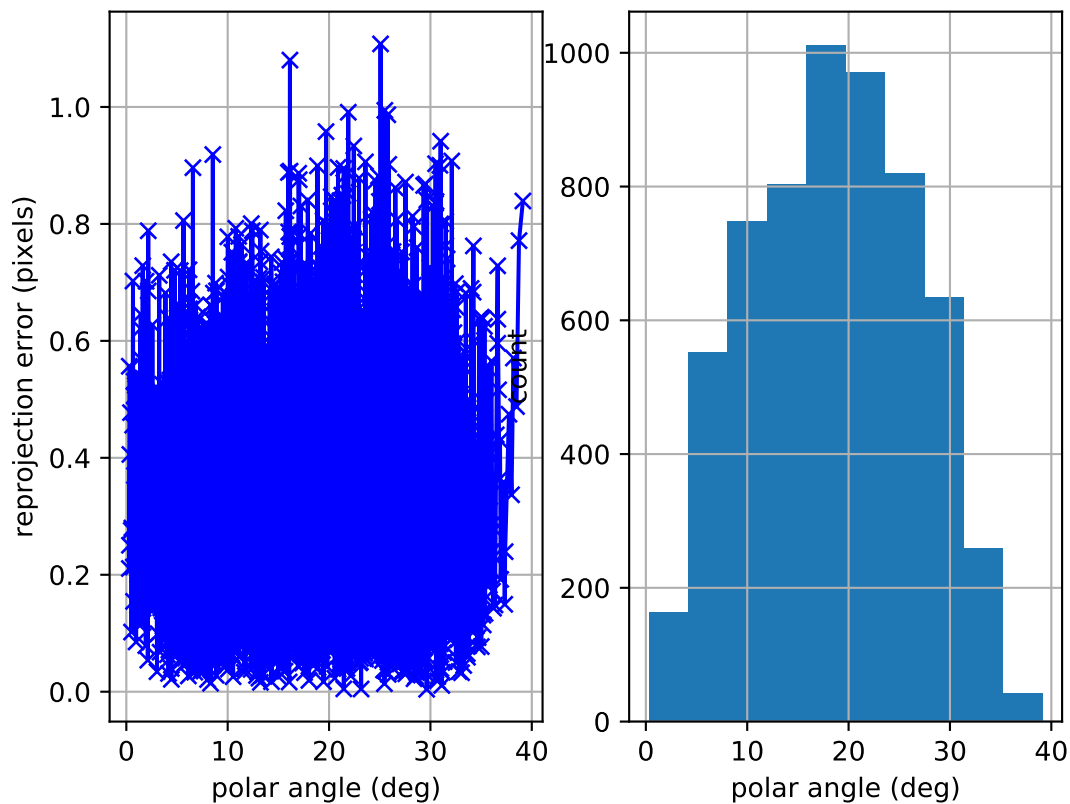
cam0: azimuthal error



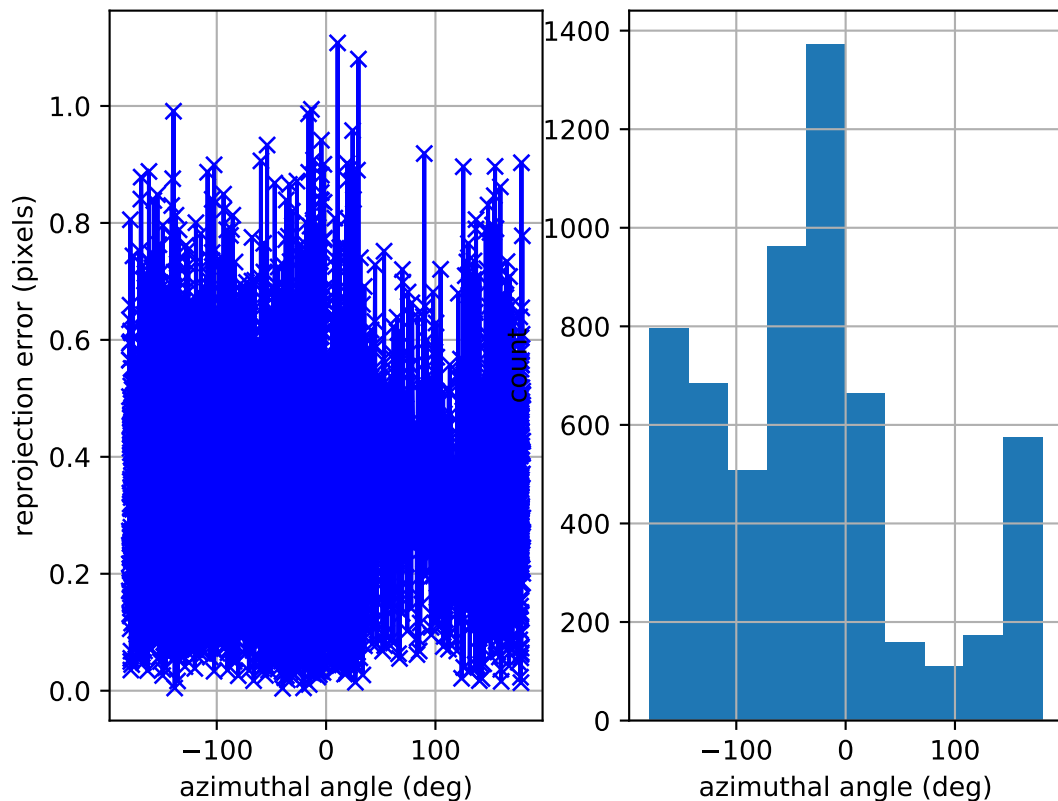
cam0: reprojection errors



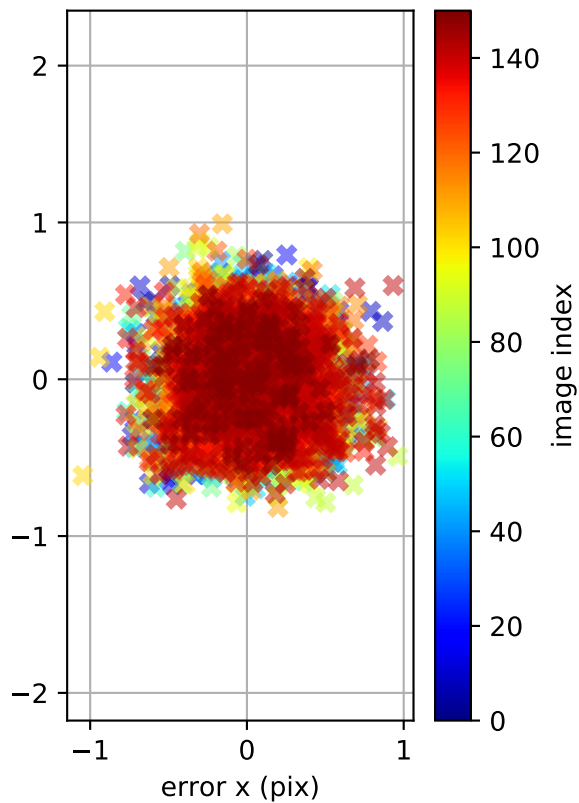
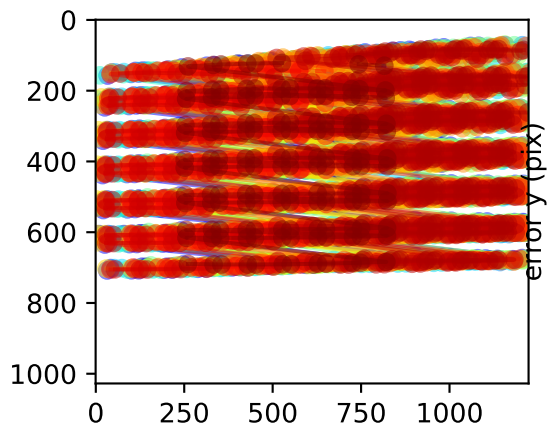
cam1: polar error



cam1: azimuthal error

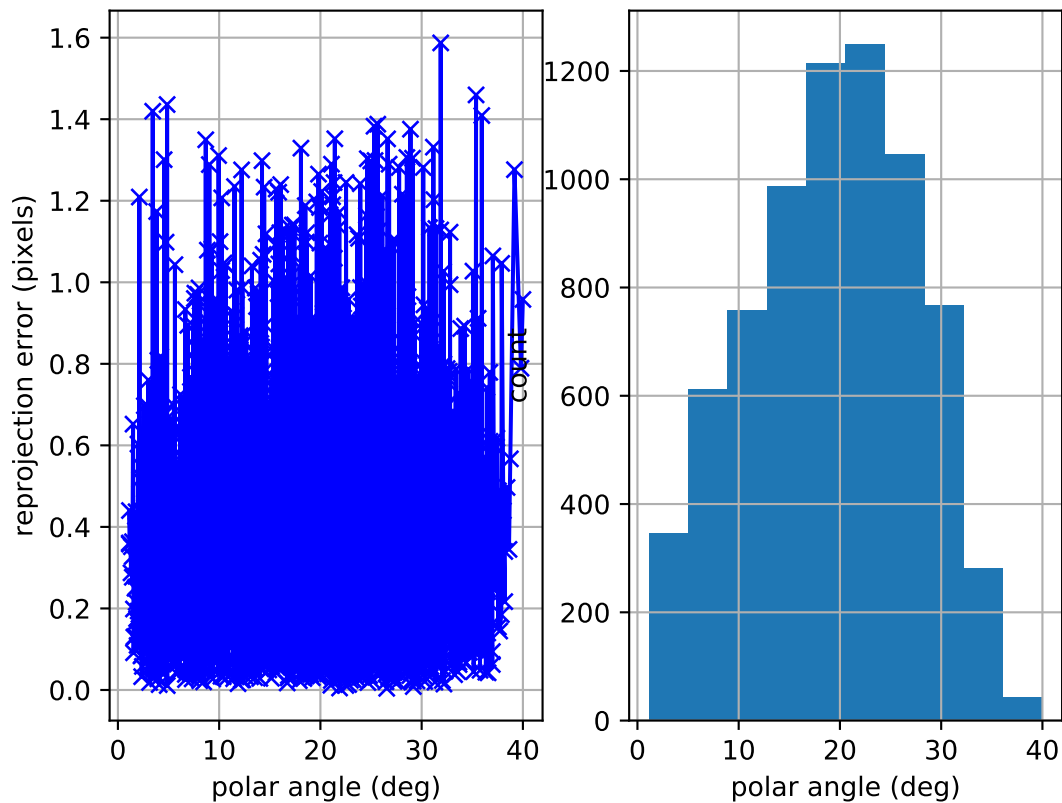


cam1: reprojection errors

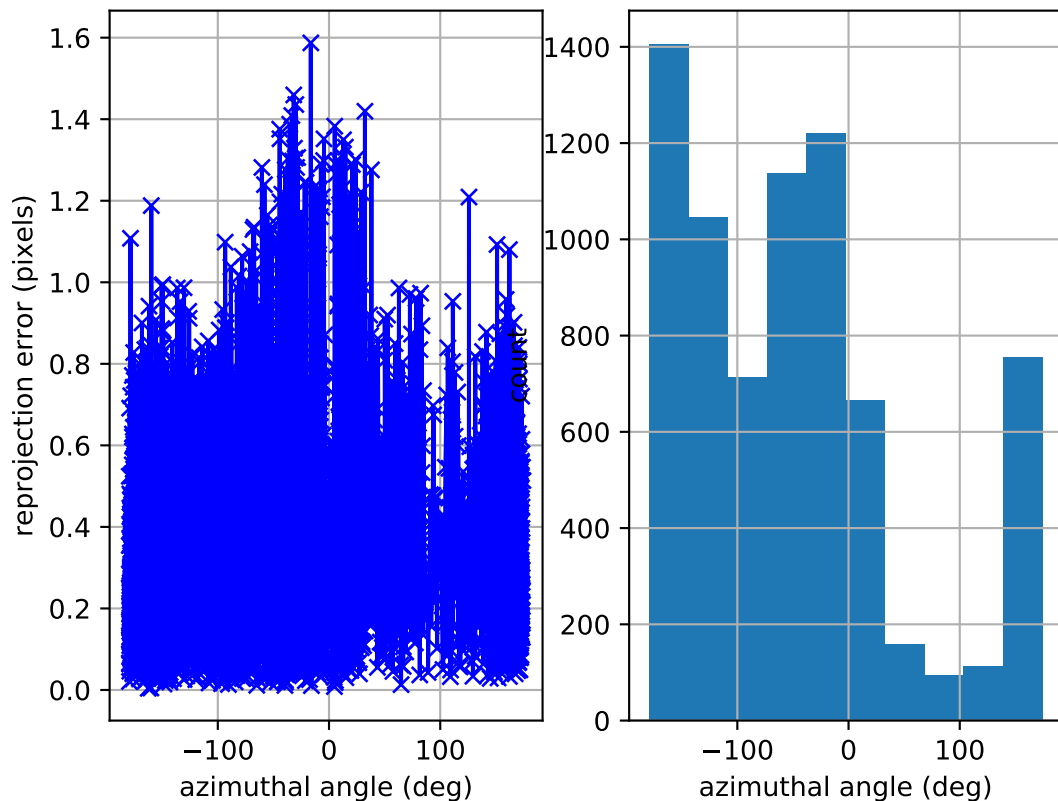




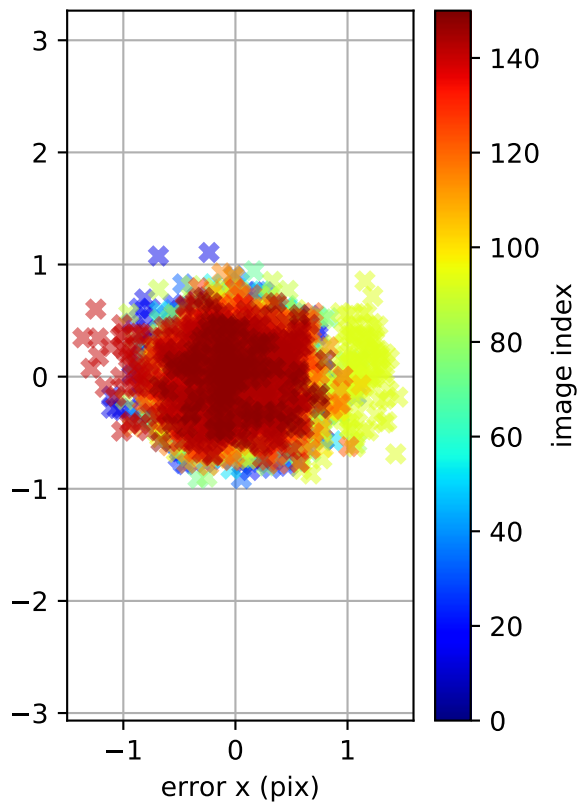
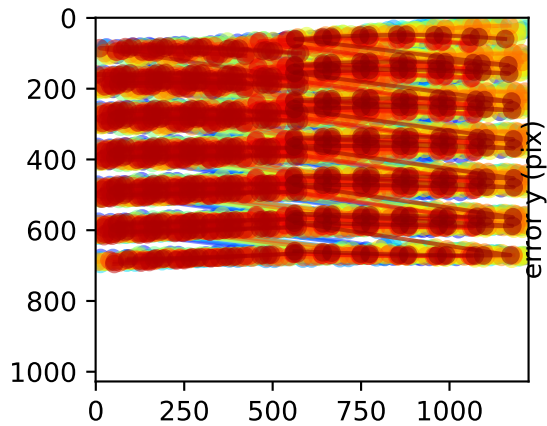
cam2: polar error



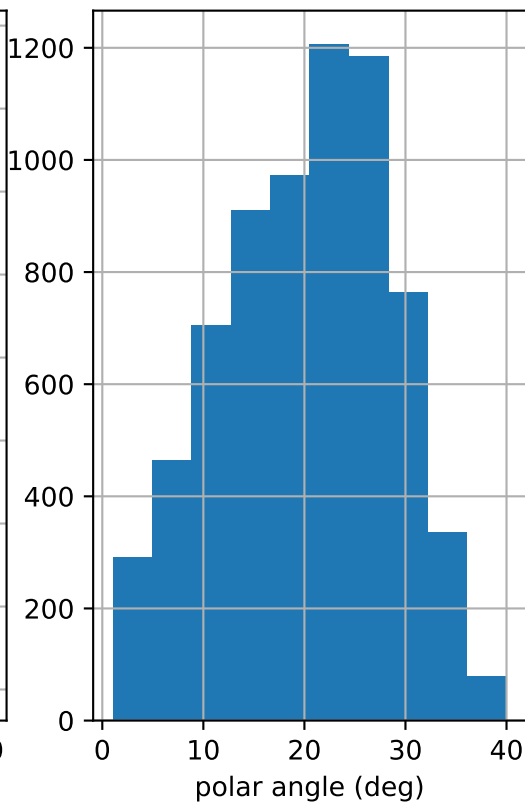
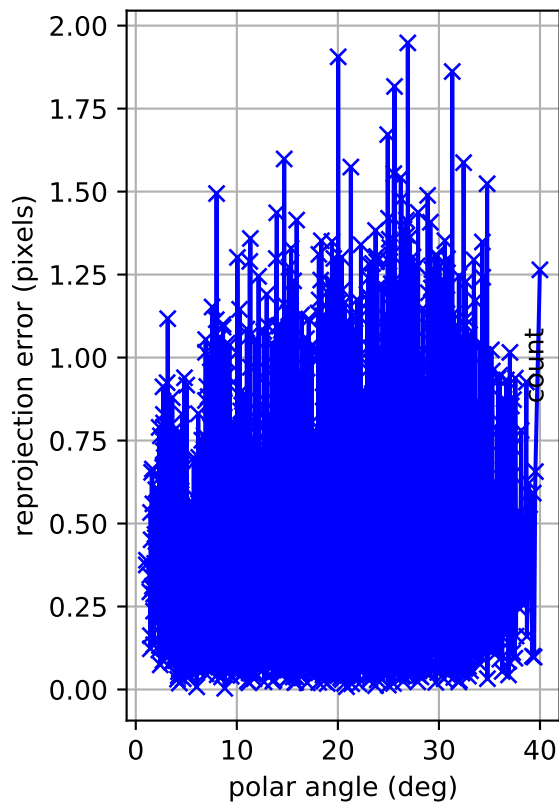
cam2: azimuthal error



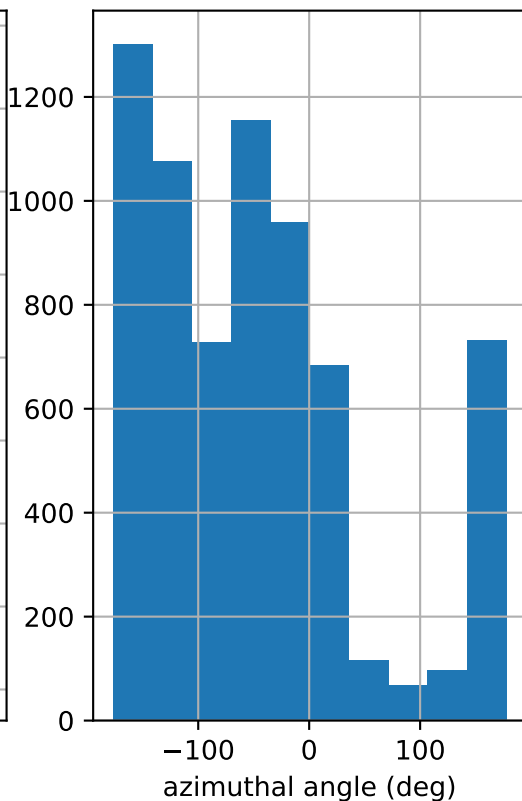
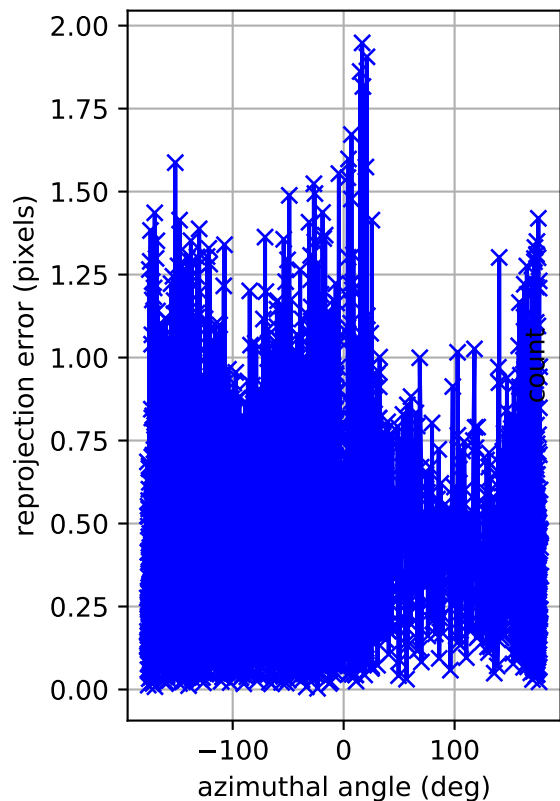
cam2: reprojection errors



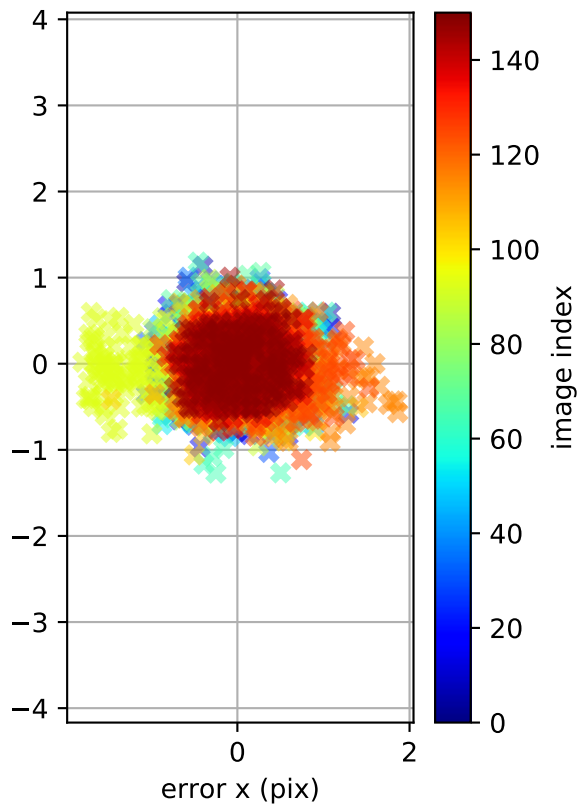
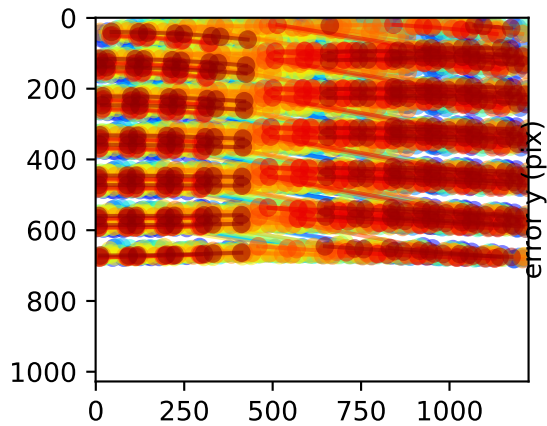
cam3: polar error



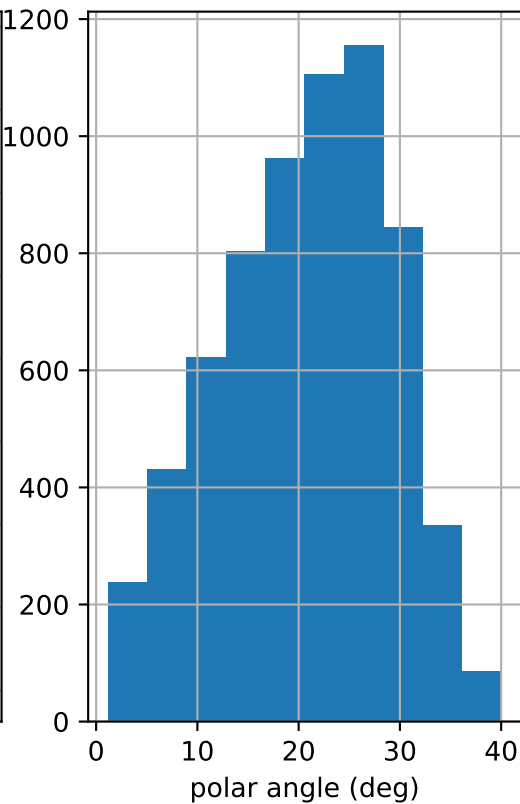
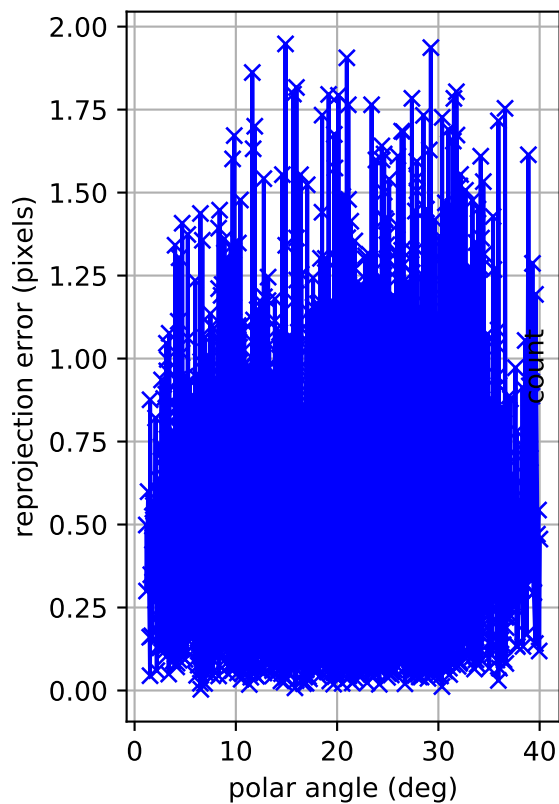
cam3: azimuthal error



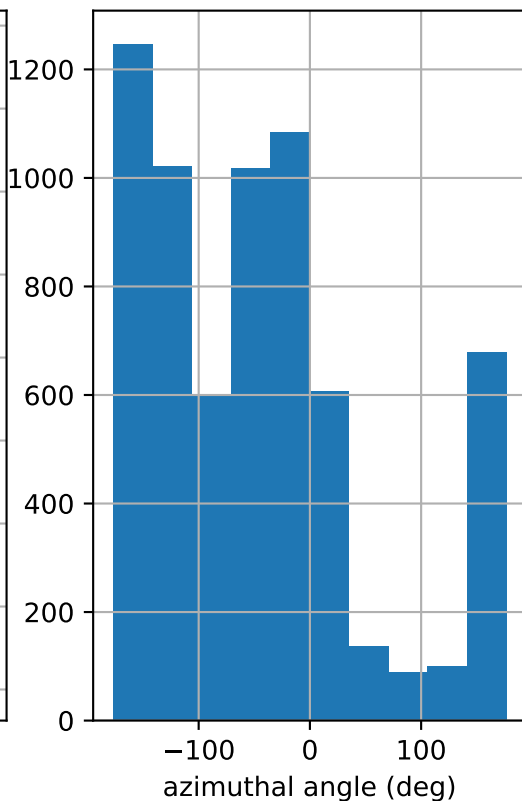
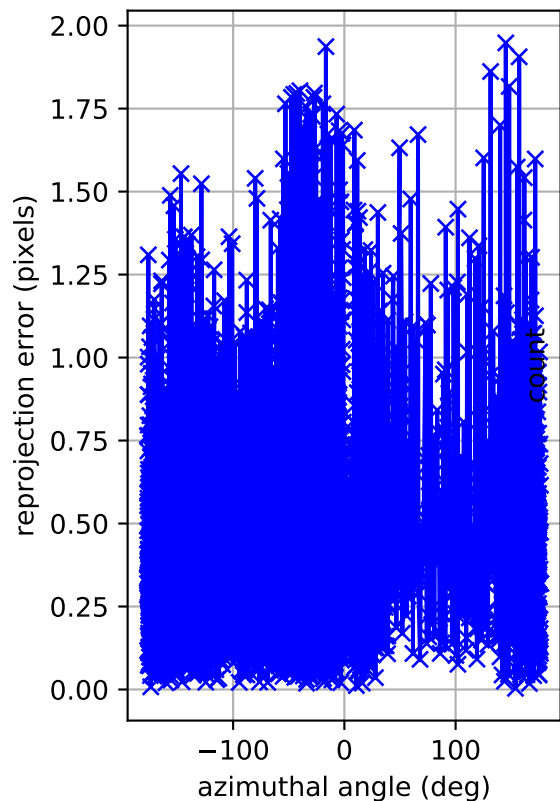
cam3: reprojection errors



cam4: polar error

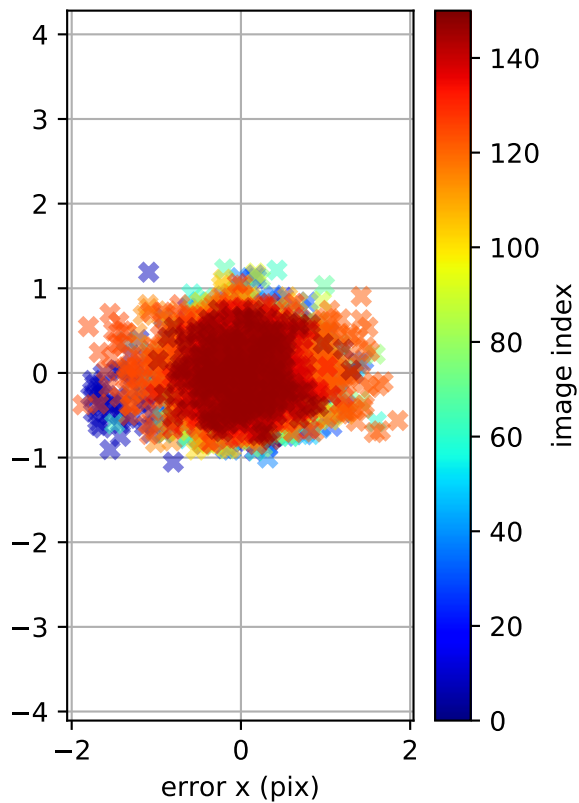
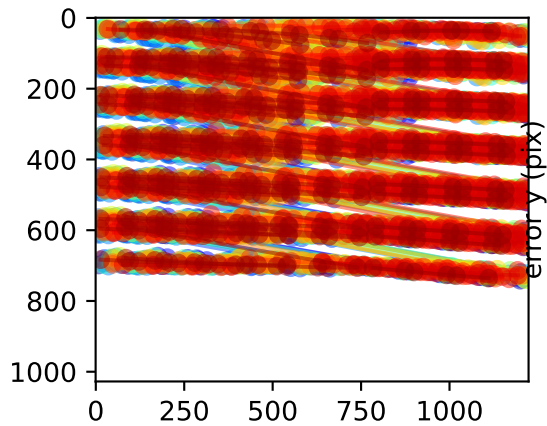


cam4: azimuthal error

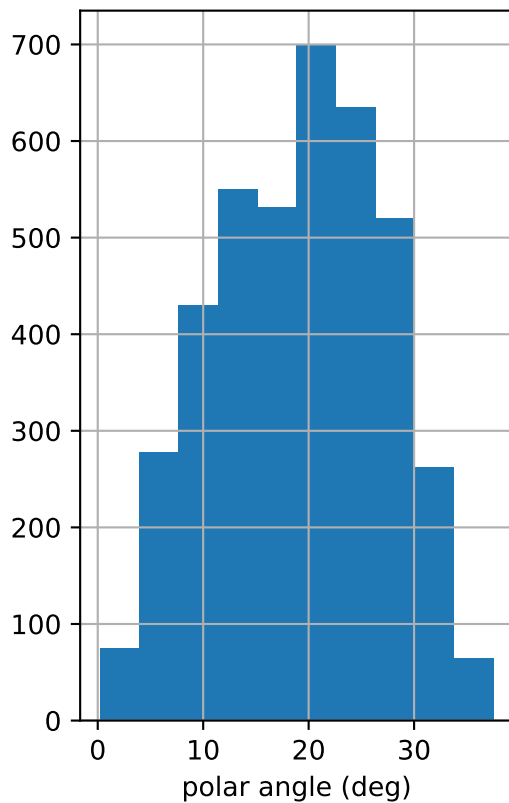
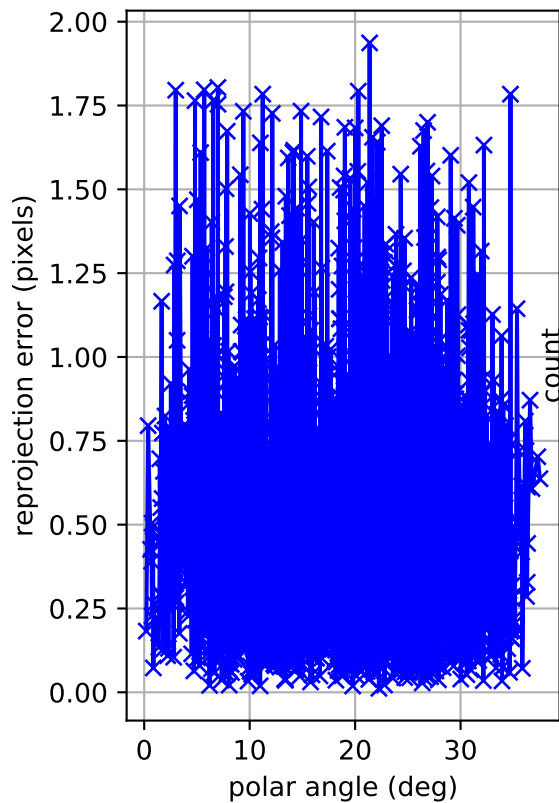




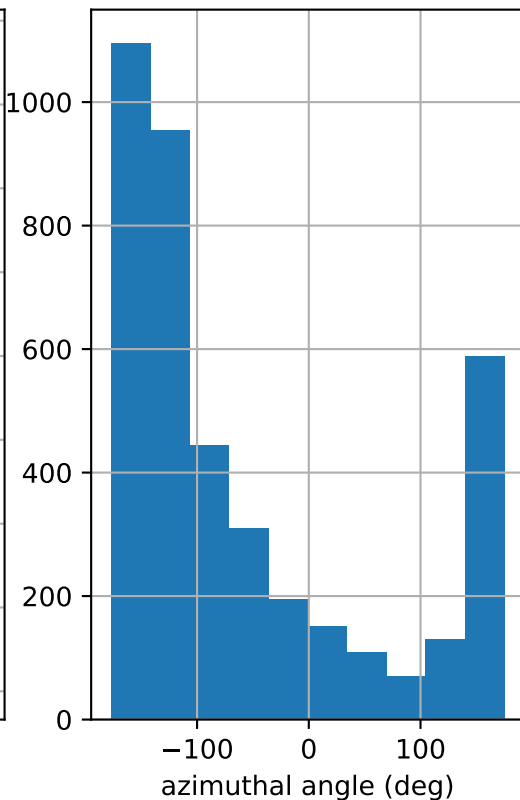
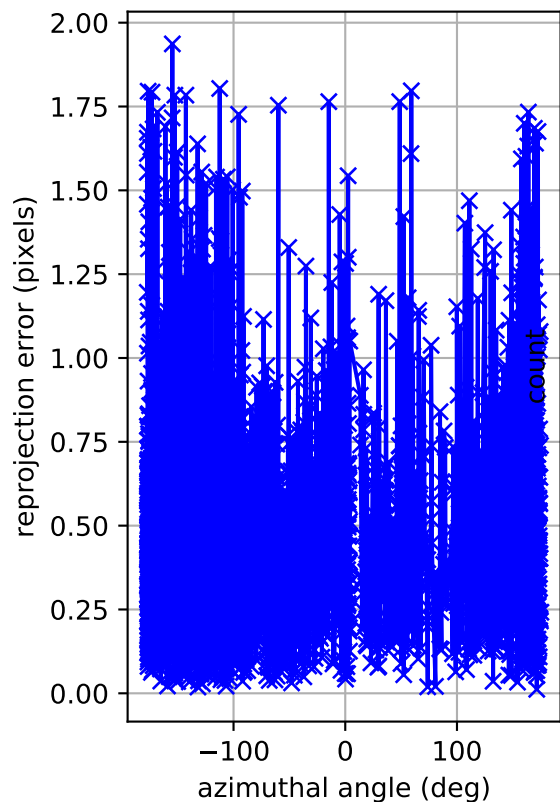
cam4: reprojection errors



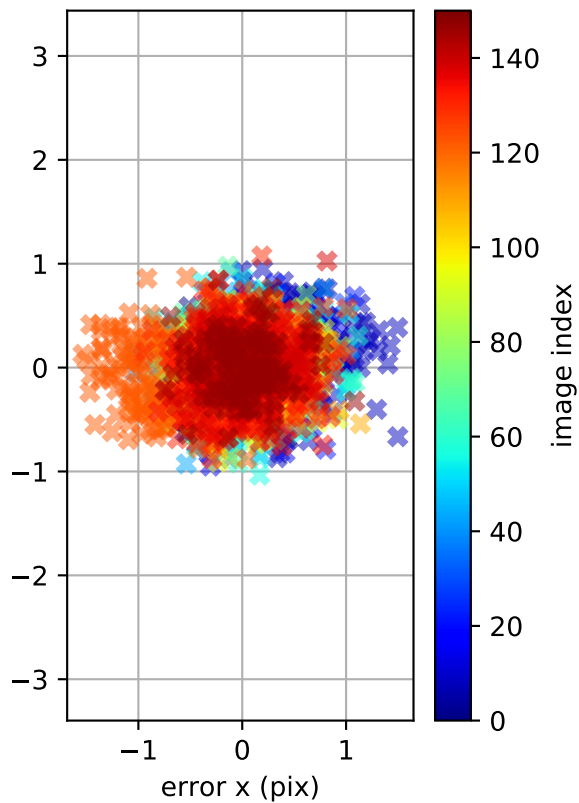
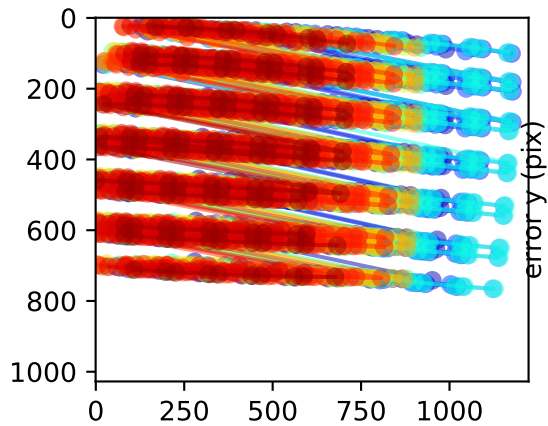
cam5: polar error



cam5: azimuthal error



cam5: reprojection errors



# Location of removed outlier corners

