# Implicit Functions and Their Derivatives

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## 1 Implicit Functions

### **Explicit Function, Implicit Function**

### **Explicit Function**

$$x_{n+1} = x_{n+1}(\mathbf{x})$$

In explicit functions, all input  $\mathbf{x} = (x_1, \dots, x_n)$  are free (or exogenous) variables. In this form, endogenous variables and exogenous variable  $(x_{n+1})$  can be distinguished easily.

### **Implicit Function**

Let  $x_{n+1} = x_{n+1}(\mathbf{x})$ . Then, we can find alternative representation

$$G = G(\mathbf{x}, x_{n+1}) = 0$$

G is not a function but an equation (implicit equation). In this representation,  $x_{n+1}$  is an implicit function of the exogeneous variables  $\mathbf{x} = (x_1, \dots, x_n)$ . In this form, we can not distinguish easily between exogenous and endogenous variables.

### Implicit Functions: Example

# Representing Implicit Function by Explicit Function(s)

$$G(x,y) = x^2 + y^2 - 1 = 0$$

y can be an implicit function of x. On the other hand, x also can be an implicit function of y.

$$y = \begin{cases} \sqrt{1 - x^2}, & y \ge 0\\ -\sqrt{1 - x^2}, & y < 0 \end{cases}$$

$$x = \begin{cases} \sqrt{1 - y^2}, & x \ge 0\\ -\sqrt{1 - y^2}, & x < 0 \end{cases}$$

We cannot find well-defined functional relationship on the boundary of these explicit functions.

### The Implicit Function Theorem (IFT) for $\mathbb{R}^2$

### **Main Question**

1. Does  $G(x, y) = \overline{c}$  determine y as a well-defined continuous function of x for around  $\overline{x}_0$  and  $\overline{y}_0$ ?

2. If (1) is true,  $y' = \frac{\partial y}{\partial x} = ?$ 

We can get IFT on  $\mathbb{R}^2$  by differentiate  $G(x,y(x))=\overline{c}$  wrt x at  $\overline{x}_0$  (Use Chain Rule I: Th14.1)

### Chain Rule I

Let  $g(t) = f(\mathbf{x}(t)), g : \mathbb{R} \to \mathbb{R}, f : \mathbb{R}^n \to \mathbb{R}, \mathbf{x} : \mathbb{R} \to \mathbb{R}^n$ . Then,

$$\frac{dg}{dt} = Df_{\mathbf{x}}(\mathbf{x})\frac{\mathbf{x}(t)}{dt} = \frac{\partial f}{\partial x_1}\frac{dx_1}{dt} + \dots + \frac{\partial f}{\partial x_n}\frac{dx_n}{dt}$$

IFT  $(\mathbb{R}^2)$ 

**Theorem 1** (15.1 (IFT)). Let G(x,y) be a  $C^1$  function on  $B_{\epsilon}(\overline{x}_0,\overline{y}_0)$  in  $\mathbb{R}^2$ . Suppose that  $G(\overline{x}_0,\overline{y}_0) = \overline{c}$  and consider the implicit equation

$$G(x,y) = \overline{c}$$

If  $\frac{\partial G}{\partial y}(\overline{x}_0, \overline{y}_0) \neq 0$ , (i.e., tangent line is not vertical) then  $\exists y = y(x) \in C^1$  on  $I = I_{\epsilon}(\overline{x}_0)$  s.t.,

- 1.  $G(x, y(x)) \equiv \overline{c} \quad \forall x \in I$
- 2.  $y(\overline{x}_0) = \overline{y}_0$
- 3. and

$$y'(\overline{x}_0) = -\frac{\frac{\partial G}{\partial x}(\overline{x}_0, \overline{y}_0)}{\frac{\partial G}{\partial y}(\overline{x}_0, \overline{y}_0)}$$

We can extend IFT on  $\mathbb{R}^n$ 

IFT on  $\mathbb{R}^n$ 

**Theorem 2** (15.2). Let  $G(\mathbf{x}, f)$  be a  $C^1$  function on  $B_{\epsilon}(\overline{\mathbf{x}_0}, \overline{f}_0)$  in  $\mathbb{R}^n$ . Suppose that  $G(\overline{\mathbf{x}_0}, \overline{f}_0) = \overline{c}$  and consider the implicit equation

$$G(\mathbf{x}, f) = \overline{c}$$

If  $\frac{\partial G}{\partial f}(\overline{\mathbf{x}_0}, \overline{f}_0) \neq 0$  (i.e., tangent hyperplane is not vertical), then  $\exists f = f(\mathbf{x}) \in C^1$  on  $B = B_{\epsilon}(\overline{\mathbf{x}_0})$  s.t.,

- 1.  $G(\mathbf{x}, f(\mathbf{x})) \equiv \overline{c} \quad \forall \mathbf{x} \in B$
- 2.  $f(\overline{\mathbf{x}_0}) = \overline{f}_0$
- 3. and

$$\frac{\partial f}{\partial x_i}(\overline{\mathbf{x}_0}) = -\frac{\frac{\partial G}{\partial x_i}(\overline{\mathbf{x}_0}, \overline{f}_0)}{\frac{\partial G}{\partial f}(\overline{\mathbf{x}_0}, \overline{f}_0)} \quad \forall i$$

# 2 Level Curves and Their Tangents

### **IFT:** Geometric Implication

**Theorem 3** (15.3). Let  $(x_0, y_0)$  is on the  $G(x, y) = \bar{c}$  in the plane and  $G \in C^1$ .

Case 1 If  $\frac{\partial G}{\partial y}(x_0, y_0) \neq 0$ ,  $\exists y = y(x) \in C^1$  around  $x = x_0$  with slope

$$-\frac{\frac{\partial G}{\partial x}(\overline{x}_0,\overline{y}_0)}{\frac{\partial G}{\partial y}(\overline{x}_0,\overline{y}_0)}$$

Case 2 If  $\frac{\partial G}{\partial y}(x_0, y_0) = 0$ ,

Case 2-1 If  $\frac{\partial G}{\partial x}(x_0, y_0) \neq 0$ ,  $\exists x = x(y) \in C^1$  around  $y = y_0$  with slope

$$-\frac{\frac{\partial G}{\partial y}(\overline{x}_0,\overline{y}_0)}{\frac{\partial G}{\partial x}(\overline{x}_0,\overline{y}_0)}$$

Case 2-2 If  $\frac{\partial G}{\partial x}(x_0, y_0) = 0$ , there is no well-defined function around  $(x_0, y_0)$  (irregular point)

### Regular on $\mathbb{R}^2$

**Definition 1** (Regular Point).  $(x_0, y_0)$  is a regular point of the  $G(x, y) \in C^1$  if:

$$DG_{(x,y)}(x_0,y_0) = \left(\frac{\partial G}{\partial x}(x_0,y_0), \frac{\partial G}{\partial y}(x_0,y_0)\right) \neq \mathbf{0} = (0,0)$$

We can find well-defined explicit function form around regular point. Geometrically, this implies smooth curve (or 1d manifold, 1d object) in  $\mathbb{R}^2$ 

**Theorem 4** (15.4). Let  $G \in C^1$  around  $(x_0, y_0)$  and this point is regular. Then,  $\nabla G(x_0, y_0)$  is perpendicular to the level set of G at  $(x_0, y_0)$ 

$$\nabla G(x_0, y_0) \bullet \left( 1, -\frac{\frac{\partial G}{\partial x}(\overline{x}_0, \overline{y}_0)}{\frac{\partial G}{\partial y}(\overline{x}_0, \overline{y}_0)} \right) = 0$$

### Extention to $\mathbb{R}^n$ Space

**Definition 2** (Regular Point on  $\mathbb{R}^n$ ).  $\mathbf{x}_0$  is a regular point of the  $G(\mathbf{x}) \in C^1$  if:

$$\nabla G(\mathbf{x}_0) = DG_{\mathbf{x}}(\mathbf{x}_0) \neq \mathbf{0}$$

We can find well-defined explicit function form around regular point. Geometrically, this implies smooth hypersurface (or n-1 dimensional manifold, n-1 dimensional object) in  $\mathbb{R}^n$ 

**Theorem 5** (15.6). If  $f: \mathbb{R}^n \to \mathbb{R} \in C^1$ ,  $\mathbf{x}^* \in \mathbb{R}^n$ , and  $\nabla f(\mathbf{x}^*) \neq \mathbf{0}$ , Then:

1. The level set of f through  $\mathbf{x}^*$ ,

$$\mathcal{F}_{f(\mathbf{x}^*)} \equiv {\{\mathbf{x} : f(\mathbf{x}) = f(\mathbf{x}^*)\}}$$

can be viewed as the graph of real-valued  $C^1$  function of (n-1) variables in a neighborhood of  $\mathbf{x}^*$ 

- 2.  $\nabla f(\mathbf{x}^*)$  is perpendicular to the tangent hyperplane of  $\mathcal{F}_{f(\mathbf{x}^*)}$  at  $\mathbf{x}^*$
- 3.  $\mathbf{v}$  is a tangent vector of  $\mathcal{F}_{f(\mathbf{x}^*)}$  at  $\mathbf{x}^*$  iff  $Df_{\mathbf{x}}(\mathbf{x}^*) \bullet \mathbf{v} = 0$

### 3 Systems of Implicit Functions

### Systems of Implicit Functions

**Definition 3** (System of implicit functions). A set of m equations in m + n unknowns

$$\mathbf{f}(x_1,\cdots,x_{m+n}) = \mathbf{c} \in \mathbb{R}^m$$

is called a <u>system of implicit functions</u> if there is a parition of the variables into n exogenous variables and m endogenous variables, so that if exogenous variables are given, the resulting system can be solved uniquely.

By linearization, we can solve  $df_1, \dots, df_m$  from given  $dx_1, \dots, dx_n$  around  $(\mathbf{f}, \mathbf{x}) = (\mathbf{f}^*, \mathbf{x}^*)$ 

#### Linearization

### Linearized System

We can get linearize system from nonlinear system

$$F_1(f_1, \dots, f_m, x_1, \dots, x_n) = \bar{c}_1$$

$$F_2(f_1, \dots, f_m, x_1, \dots, x_n) = \bar{c}_2$$

$$\dots$$

$$F_m(f_1, \dots, f_m, x_1, \dots, x_n) = \bar{c}_m$$

by taking derivative on a given point  $(\mathbf{f}, \mathbf{x}) = (\mathbf{f}^*, \mathbf{x}^*)$ ,

$$\frac{\partial F_1}{\partial f_1} df_1 + \dots + \frac{\partial F_1}{\partial f_m} df_m + \frac{\partial F_1}{\partial x_1} dx_1 + \dots + \frac{\partial F_1}{\partial x_n} dx_n = 0$$

$$\vdots \qquad \qquad \vdots$$

$$\frac{\partial F_m}{\partial f_1} df_1 + \dots + \frac{\partial F_m}{\partial f_m} df_m + \frac{\partial F_m}{\partial x_1} dx_1 + \dots + \frac{\partial F_m}{\partial x_n} dx_n = 0$$

### Solving Linearized System

#### Solving Prodecure

$$\frac{\partial F_1}{\partial f_1} df_1 + \dots + \frac{\partial F_1}{\partial f_m} df_m = -\left(\frac{\partial F_1}{\partial x_1} dx_1 + \dots + \frac{\partial F_1}{\partial x_n} dx_n\right)$$

$$\vdots$$

$$\frac{\partial F_m}{\partial f_1} df_1 + \dots + \frac{\partial F_m}{\partial f_m} df_m = -\left(\frac{\partial F_m}{\partial x_1} dx_1 + \dots + \frac{\partial F_m}{\partial x_n} dx_n\right)$$

In this system,  $d\mathbf{f}$  is unknown and others are given explicitly. Therefore,

$$d\mathbf{f} = -(D\mathbf{F}_{\mathbf{f}}(\mathbf{f}^*, \mathbf{x}^*))^{-1} \cdot D\mathbf{F}_{\mathbf{x}}(\mathbf{f}^*, \mathbf{x}^*) d\mathbf{x}$$

and when  $d\mathbf{x} = d\mathbf{x}^*$ ,  $\mathbf{f} = \mathbf{f}^* + d\mathbf{f}$