### Matrix Algebra

Ch.8

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#### Matrix

#### Definition (Matrix)

Matrix is a rectangular array of numbers (scalars)

Let  $a_{ij} \in \mathbb{R}$  or  $A_{ij} \in \mathbb{R}$  be the ith row and jth column element of matrix A

### Definition (Equal)

$$A = B \iff \begin{cases} \mathsf{same \ size} \\ a_{ij} = b_{ij} \quad \forall i, j \end{cases}$$

### Addition, Subtraction

Let A, B be  $n \times k$  matrices and  $r \in \mathbb{R}$ 

### Definition (Addition)

$$(A+B)_{ij} := a_{ij} + b_{ij} \quad \forall i, j$$

Important note: the first + and the second + are not same operators

#### Definition (Subtraction)

$$(A-B)_{ij} := a_{ij} - b_{ij} \quad \forall i, j$$

### Multiplications of Matrices

#### Definition (Scalar Multiplication)

$$(rA)_{ij} := rA_{ij} \quad \forall i, j$$

Let A be  $n \times k$  matrix and B be  $k \times m$  matrix. Then AB is  $n \times m$  matrix.

#### Definition (Matrix Multiplication)

$$(AB)_{ij} := A_{i1}B_{1j} + A_{i2}B_{2j} + \dots + A_{ik}B_{kj} = \sum_{r=1}^{k} A_{ir}B_{rj}$$

For  $n \times n$  matrices, identity matrix  $I_n$  is a multiplicative identity.

$$AI = IA = A$$



### Laws of Matrix Algebra

#### Laws of Matrix Algebra

$$(A+B)+C=A+(B+C)$$
 (Associative Law for Addition) 
$$(AB)C=A(BC)$$
 (Associative Law for Multiplication) 
$$A+B=B+A$$
 (Commutative Law for Addition) 
$$A(B+C)=AB+AC$$
 (Distributive Law) 
$$(A+B)C=AC+BC$$
 (Distributive Law)

Important Note:  $AB \neq BA$ 

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### Transpose

#### Definition (Transpose)

 $A^{\intercal}$   $(n \times m)$  is a transpose of A  $(m \times n)$  if:

$$(A^{\mathsf{T}})_{ij} := A_{ji} \quad \forall i, j$$

$$(A \pm B)^{\mathsf{T}} = A^{\mathsf{T}} \pm B^{\mathsf{T}}$$
$$(A^{\mathsf{T}})^{\mathsf{T}} = A$$
$$(rA)^{\mathsf{T}} = rA^{\mathsf{T}}$$
$$(AB)^{\mathsf{T}} = B^{\mathsf{T}}A^{\mathsf{T}}$$

(Theorem 8.1)

# Special Kinds of Matrices (1)

Suppose A is  $k \times n$  matrix. Then,

### Definition (Special Kinds of Matrices (1))

- A is a <u>square matrix</u> if k = n
- A is a column matrix if n=1
- A is a row matrix if k=1
- A is a <u>diagonal matrix</u> if k = n and  $a_{ij} = 0$   $\forall i \neq j$
- A is a scalar matrix if  $A = tI_n$
- A is an upper-triangular matrix if  $a_{ij} = 0 \quad \forall i > j$
- A is a lower-triangular matrix if  $a_{ij} = 0 \quad \forall i < j$

# Special Kinds of Matrices (2)

### Definition (Special Kinds of Matrices (2))

- A is a <u>symmetric matrix</u> if A is sugare matrix and  $a_{ij} = a_{ji} \quad \forall i, j$ .  $Or, A^{\intercal} = A$
- A is an <u>Idempotent matrix</u> if AA = A
- A is a permutation matrix if A is the result of  $I_n$  with  $ERO_1$  (row exchange)
- ullet A is a <u>nonsingular matrix</u> if rankA = #row = #column

If a coefficient matrix of a system of linear equations is nonsignular, this system has only one solution  ${\bf x}=A^{-1}{\bf b}$ 



### Elementary Matrix

Let E be an elementary matrix of some EROs. Then,

#### Theorem (8.3)

ERO with a matrix A is equivalent to EA

#### Theorem (8.2)

- Let  $E1_{ij}$  be the permutation matrix with interchanging  $R_i$  and  $R_j$  of  $I_n$ , then  $E1_{ij}$  is equivalent to  $ERO_1(i,j)$
- Let  $E2_{k,j,i}$  be the result of  $ERO_2(k,j,i)$  from  $I_n$ , then  $E2_{k,j,i}$  is equivalent to  $ERO_2(k,j,i)$
- Let  $E3_{k,i}$  be the result of  $ERO_3(k,i)$  from  $I_n$ , then  $E3_{k,i}$  is equivalent to  $ERO_3(k,i)$

### Elementary Matrix

#### Definition (Elementary Matrix)

E1, E2, E3 are elementary matrices corresponding to their EROs

#### Theorem (8.4)

Let  $A \in M_n$  (set of  $n \times n$  matrices),  $E_i \in EM$  (set of elementary matrices), and (R)REFM be the set of (R)REF matrices. Then:

$$\exists E_i \quad i = 1, 2, \cdots, m \quad s.t. \quad \prod_{i=m}^{1} E_i A \in (R) REFM$$

or

$$E_m E_{m-1} \cdots E_2 E_1 A \in (R) REFM$$

#### Inverse of Matrices

Suppose  $A, B \in M_n$ 

#### Definition (Inverse, Invertible)

B is (left, or right) inverse for A if:

$$\underbrace{AB}_{B: \ Right \ inverse} = \underbrace{B: \ Left \ inverse}_{B: \ Right \ inverse} = I$$

A is invertible if  $\exists B$ 

Notation:  $B = A^{-1}$ 

#### Theorem (8.5:Uniquenes of Inverse)

 $A \in M_n$  can have at most one inverse. (left inverse = right inverse)

### Inverse Matrices and the Solution of Linear Systems

### Theorem (8.6)

For  $A \in M_n$ ,

$$\exists A^{-1} \quad \Rightarrow \quad \begin{cases} A \text{ is nonsingular} \\ \text{Unique solution of } A\mathbf{x} = \mathbf{b} \quad \Rightarrow \quad \mathbf{x} = A^{-1}\mathbf{b} \end{cases}$$

Proof: easy

### Theorem (8.7: inverse of Th8.6)

$$A \in M_n$$
 is nonsignual  $\Rightarrow \exists A^{-1}$ 

Proof: difficult

#### Calculation of Inverse Matrix

#### Calculation of Inverse Matrix

$$[A|I] \xrightarrow{EROs} [I|A^{-1}]$$

If RREF is not  $I_n$ ,  $\nexists A^{-1}$ 

### Theorem (8.8)

Let 
$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in M_2$$
.  $A$  is nonsingular iff  $ad - bc \neq 0$ 

For general case  $(A \in M_n)$ , see Ch.9

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### Equivalent statements

#### Theorem (8.9)

For  $A \in M_n$ , the following statements are equivalent

- $\bullet$   $\exists A^{-1}$
- A has right inverse
- A has left inverse
- $\mathbf{0}$   $A\mathbf{x} = \mathbf{b}$  has at least one solution for every  $\mathbf{b}$
- $\mathbf{o}$   $A\mathbf{x} = \mathbf{b}$  has at most one solution for every  $\mathbf{b}$
- A is nonsingular
- o rankA = n

## Properties of Inverse Matrices and Their Exponentials

#### Theorem (8.10)

If  $A, B \in M_n$  and  $\exists A^{-1}, B^{-1}$ ,

- $(A^{-1})^{-1} = A$
- $(A^{\mathsf{T}})^{-1} = (A^{-1})^{\mathsf{T}}$
- $\exists (AB)^{-1} \wedge (AB)^{-1} = B^{-1}A^{-1}$

#### Definition (Matrix Exponential)

$$A^m := \prod_{i=1}^m A$$

$$A^{-m} := (A^{-1})^m$$

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### Expoenetial Properties of Invertible Matrices

### Theorem (8.11)

$$\exists A^{-1} \quad \Rightarrow \quad \begin{cases} \exists A^{-m} \quad \forall m \in \mathbb{N} \\ A^r A^s = A^{r+s} \quad \forall r, s \in \mathbb{N} \\ \forall r \in \mathbb{R} - \{0\}, \quad \exists (rA)^{-1} \wedge (rA)^{-1} = \frac{1}{r} A^{-1} \end{cases}$$

Important Note:  $(AB)^k \neq A^k B^k$ 

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#### Partitioned Matrices

Somtimes, matrix of matrices can be more convenient.

#### Definition (Submatrix, Partitioned matrix)

- ullet A  $\underline{\mathit{submatrix}}$  of matrix A is a matrix obtained by deleting some  $R_i$  or  $C_j$
- A <u>partitioned matrix</u> is a matrix partitioned into submatrices by horizontal and/or vertical lines which extended along entire rows or columns of a matrix A

#### Partitioned Matrices

#### Theorem (8.15)

Let A be a square matrix partitioned as

$$A = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix}$$

and  $A_{11}, A_{22} \in M_n$ . Then,

$$\exists A_{22}^{-1} \land \exists D^{-1} \land D = A_{11} - A_{12} A_{22}^{-1} A_{21}$$

$$\Rightarrow A^{-1} = \begin{pmatrix} D^{-1} & -D^{-1} A_{12} A_{22}^{P-1} \\ -A_{22}^{-1} A_{21} D^{-1} & A_{22}^{-1} (I + A_{21} D^{-1} A_{12} A_{22}^{-1}) \end{pmatrix}$$