Quadratic Forms and Definite Matrices

Ch.16

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1 Quadratic Forms

Quadratic Forms

Definition 1 (Quadratic Form). A quadratic form on \mathbb{R}^n is a real-valued function of the form

$$Q(\mathbf{x}) = \mathbf{x}^T A \mathbf{x}, \quad \mathbf{x} \in \mathbb{R}^n, \quad A^T = A$$

For more detailed description, see Ch13 (section 3).

2 Definiteness of Quadratic Forms

Definiteness

Definiteness: Overview

When $Q = \mathbf{x}^T A \mathbf{x}$ and A is a diagonal matrix

$$A = \begin{pmatrix} a_{11} & 0 & 0 & \cdots & 0 \\ 0 & a_{22} & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & a_{nn} \end{pmatrix}$$

- Positive Definite (PD): $a_{ii} > 0 \quad \forall i$
- Positive Semi Definite (PSD): $a_{ii} \ge 0 \quad \forall i$
- Negative Definite (ND): $a_{ii} < 0 \quad \forall i$
- Negative Semi Definite (NSD): $a_{ii} \leq 0 \quad \forall i$
- Indefinite (ID): $a_{ii} < 0$ for some i, and $a_{ii} > 0$ for some i

Definite Symmetric Matrices

Definition 2 (PD,PSD,ND,NSD,ID). Let A be an $n \times n$ symmetric matrix and $Q = \mathbf{x}^T A \mathbf{x}$, then A is:

- 1. PD if $Q > 0 \ \forall \mathbf{x} \neq \mathbf{0}$ in \mathbb{R}^n
- 2. PSD if $Q \ge 0 \ \forall \mathbf{x} \ne \mathbf{0}$ in \mathbb{R}^n
- 3. ND if $Q < 0 \ \forall \mathbf{x} \neq \mathbf{0}$ in \mathbb{R}^n
- 4. NSD if $Q \leq 0 \ \forall \mathbf{x} \neq \mathbf{0}$ in \mathbb{R}^n
- 5. ID if Q > 0 for some $\mathbf{x} \in \mathbb{R}^n$ and Q < 0 for some $\mathbf{x} \in \mathbb{R}^n$

Principal Minors of a Matrix

Definition 3 (Principal Submatrix (PS), Principal Minor (PM)). Let A be an $n \times n$ symmetric matrix. kth order <u>principal submatrix</u> of A is $k \times k$ submatrix of A obtained by deleting n - k columns C_1, \dots, C_{n-k} and same n - k rows R_1, \dots, R_{n-k} .

kth order principal minor of A is the determinant of kth order principal submatrix.

Note: the number of kth order principal submatrix can be nCk. We will denote kth order principal minor by $PM_k(A)$.

Definition 4 (Leading PS, Leading PM). kth order <u>leading principal submatrix</u> of A is an unique kth order submatrix obtained by deleting the last n-k rows and columns from A. kth order <u>leading principal minor</u> of A ($LPM_k(A)$ or $|A_k|$) is the determinant of kth order leading principal submatrix of A

Test for Definiteness

Theorem 1 (16.1,2). Let A be an $n \times n$ symmetric matrix. Then,

- 1. A is PD iff $LPM_k(A) > 0 \ \forall k$
- 2. A is PSD iff $PM_k(A) > 0 \ \forall k$
- 3. A is ND iff $sign(LPM_k(A)) = sign((-1)^k) \quad \forall k$
- 4. A is NSD iff $sign(PM_k(A)) = sign((-1)^k) \quad \forall k$
- 5. Otherwise, A is ID

Note: We can find more elegant criteria using eigenvalues (Ch.23). To check all PM, $\sum_{i=1}^{n} nCi$ determinants should be calculated.

3 Linear Constraints and Bordered Matrices

Bordered Matrix

Finding global max/min of $Q(x_1, x_2)$ with one linear constraint

$$Q(x_1, x_2) = \mathbf{x}^T H \mathbf{x} = (x_1 x_2) \begin{pmatrix} a & b \\ b & c \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = ax_1^2 + 2bx_1x_2 + cx_2^2$$

on

$$\begin{pmatrix} A & B \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = G\mathbf{x} = 0$$

Substitute x_1 to $-Bx_2/A$ and we can get one variable function \tilde{Q} in terms of x_2

$$\tilde{Q}(x_2) = Q(-Bx_2/A, x_2) = \frac{aB^2 - 2bAB + cA^2}{A^2}x_2^2$$

$$aB^{2} - 2bAB + cA^{2} = -\det\begin{pmatrix} 0 & A & B \\ A & a & b \\ B & b & c \end{pmatrix} = -\det\begin{pmatrix} 0 & G \\ G^{T} & H \end{pmatrix}$$

Definiteness of Bordered Matrix

Theorem 2 (16.3). $Q(\mathbf{x})$ is PD[ND] on the constraint set $G\mathbf{x} = 0$ iff

$$\det \begin{pmatrix} 0 & A & B \\ A & a & b \\ B & b & c \end{pmatrix} = \det \begin{pmatrix} 0 & G \\ G^T & H \end{pmatrix}$$

is negative/positive/

Note: sign of determinant is dependent on both n (size of \mathbf{x}) and m (number of restriction)

General Bordered Matrix

Consider general bordered matrix

$$Q(\mathbf{x}) = \mathbf{x}^T A \mathbf{x} = \begin{pmatrix} x_1 & \cdots & x_n \end{pmatrix} \begin{pmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \vdots & \vdots \\ a_{n1} & \cdots & a_{nn} \end{pmatrix} \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$$

with linear constraint set

$$B\mathbf{x} = \begin{pmatrix} b_{11} & \cdots & b_{1n} \\ \vdots & \vdots & \vdots \\ b_{m1} & \cdots & b_{mn} \end{pmatrix} \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix}$$

We can make $(n+m) \times (n+m)$ symmetric matrix (general bordered matrix)

$$H = \begin{pmatrix} \mathbf{0} & B \\ B^T & A \end{pmatrix}$$

Definiteness of General Bordered Matrix

Theorem 3 (16.4). To deterimne the definiteness of general bordered matrix, Check the signs of the last n-m LPMs of H, starting with LPM_{n+m}(H) (i.e., the determinant of H itself). This means you should check the sign of

$$\underbrace{LPM_{n+m}(H), LPM_{n+m-1}(H), \cdots, LPM_{n+m-(n-m-1)}}_{n-m \ LPMs}$$

- (a) If $sign(\det H) = sign((-1)^m)$ and all n-m LPMs have same sign, Q is \underline{PD} on the constraint set $B\mathbf{x} = \mathbf{0}$ and $\mathbf{x} = 0$ is strict global min of Q on the costraint set
- (b) If $sign(\det H) = sign((-1)^n)$ and following n m LPMs alternates in sign, Q is \underline{ND} on the constraint set $B\mathbf{x} = \mathbf{0}$ and $\mathbf{x} = 0$ is strict global max of Q on the costraint set

Definiteness of General Bordered Matrix

Continued

(c) if (a),(b) is violated by nonzero LPMs, Q is \underline{ID} on the constraint set $B\mathbf{x} = \mathbf{0}$ and $\mathbf{x} = 0$ is neigher a max nor a min of Q on the constraint set

Note: Test for NSD, PSD is much more tedious and trivial in economics \rightarrow SKIP