X Lecciones

3 min

10 min

3 min

3 min

Q

Siguiente

Anterior

Classification and Representation

✓ Volver a la semana 3

Logistic Regression Model

Multiclass Classification

Review

Solving the Problem of Overfitting

- The Problem of Overfitting 9 min
- The Problem of Overfitting 3 min
- Cost Function 10 min
- Cost Function

Regularized Linear Regression

Regularized Linear Regression

Regularized Logistic Regression 8 min

Regularized Logistic Regression

Review

Regularized Logistic Regression

We can regularize logistic regression in a similar way that we regularize linear regression. As a result, we can avoid overfitting. The following image shows how the regularized function, displayed by the pink line, is less likely to overfit than the non-regularized function represented by the blue line:

Regularized logistic regression. Cost function:

Recall that our cost function for logistic regression was:

$$J(\theta) = -\frac{1}{m} \sum_{i=1}^m \left[y^{(i)} \log(h_{\theta}(x^{(i)})) + (1-y^{(i)}) \log(1-h_{\theta}(x^{(i)})) \right]$$

We can regularize this equation by adding a term to the end:

$$J(\theta) = -\tfrac{1}{m} \textstyle \sum_{i=1}^m \big[y^{(i)} \log(h_\theta(x^{(i)})) + (1-y^{(i)}) \log(1-h_\theta(x^{(i)})) \big] + \frac{\lambda}{2m} \textstyle \sum_{j=1}^n \theta_j^2$$

The second sum, $\sum_{j=1}^{n} \theta_j^2$ means to explicitly exclude the bias term, θ_0 . I.e. the θ vector is indexed from 0 to n (holding n+1 values, θ_0 through θ_n), and this sum explicitly skips θ_0 , by running from 1 to n, skipping 0. Thus, when computing the equation, we should continuously update the two following equations:

Gradient descent

Repeat {
$$\Rightarrow \quad \theta_0 := \theta_0 - \alpha \frac{1}{m} \sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)}) x_0^{(i)}$$

$$\Rightarrow \quad \theta_j := \theta_j - \alpha \underbrace{\left[\frac{1}{m} \sum_{i=1}^m (h_\theta(x^{(i)}) - y^{(i)}) x_j^{(i)} + \frac{\lambda}{m} \odot_j \right]}_{(j = \mathbf{X}, 1, 2, 3, \dots, n)}$$
 }
$$\underbrace{\left[\frac{\lambda}{\partial \Theta_j} \underbrace{J(\Theta)}_{i, \dots, \Theta_n} \right]}_{h_{\Theta}(\mathbf{x})^{\circ}} \underbrace{\left[\frac{1}{\mathbf{y}} \underbrace{e^{-\Theta^*} \mathbf{x}}_{i} \right]}_{h_{\Theta}(\mathbf{x})^{\bullet}} \underbrace{\left[\frac{1}{\mathbf{y}} \underbrace{e^{-\Theta^*} \mathbf{x}}_{i} \right]}_{h_{\Theta}(\mathbf{x})^{\bullet}}$$

Marcar como completo



