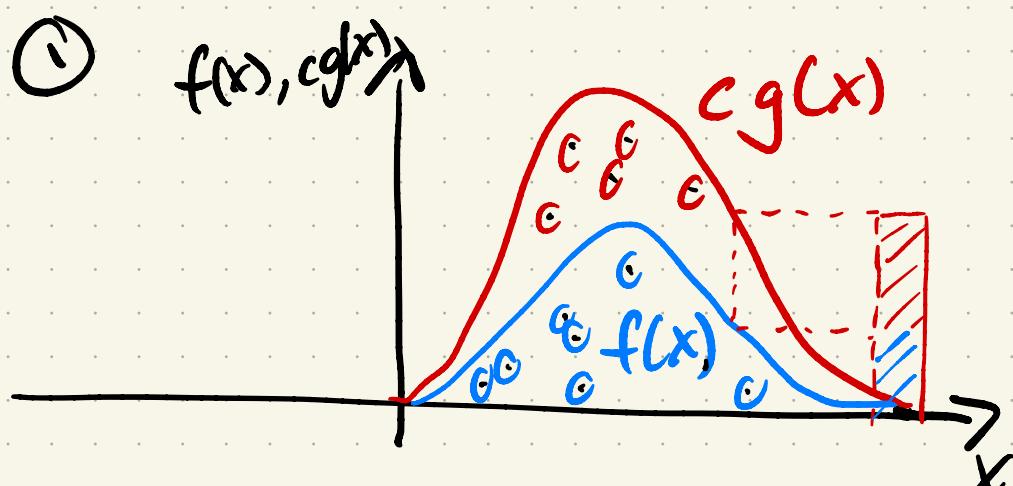


# Oral Exam Prep

# Random Number Generation

## Rejection Sampling



Proposal Distr.  $g(x)$

Target Distr.  $f(x)$

form

$$cg(x) \geq f(x)$$

$$\boxed{c \geq 1} \text{ ex: } g \in N(0, 1)$$

② Draw  $Y \sim g$  (accept prob)

c scale param

③ Draw  $U \sim \mathbb{I}_{(0,1)}$

④ Reject  $Y$  if  $Ucg(Y) > f(Y)$  and return ②

⑤ Else, set  $X = Y$  and save it as  $X \sim f$   
and return ①

No bias

- Obtains random draws  $X_i$  from target distr  $f(x)$
- Sample candidates from an easier distr and correct the sample probability with the help of rejecting candidates.

### Pros

- Unbiased i.i.d  $X_i \sim f$
- Enables sampling from unknown CDF's
- Flexible, can handle any distributions really

### Cons

- Risks being inefficient if diff  $|cg(x) - f(x)|$  is large and many rejects, large  $K$ . can be hard
- Modeling prop. distr.  $cg(x)$

## Rejection sampling

$$P(X \leq Y) = P(Y \leq y | \text{accepted})$$

$$P(X \leq y) \stackrel{\text{assert}}{=} P(Y \leq y | \text{accepted sample})$$

$$= P\left(Y \leq y \mid U \leq \frac{f(y)}{cg(y)}\right)$$

$$= P\left(Y \leq y \cap U \leq \frac{f(y)}{cg(y)}\right)$$

$$= \int_{-\infty}^y \int_0^{f(z)/cg(z)} du dz$$

Cond. Prob.  $P\left(Y \leq y \cap U \leq \frac{f(y)}{cg(y)}\right)$

Def. =

$$P\left(U \leq \frac{f(y)}{cg(y)}\right)$$

$$(P(Y \leq y) = \int_{-\infty}^y f_y(z) dz)$$

CDF def

=

$$\frac{\int_{-\infty}^y \int_0^{f(z)/cg(z)} du g(z) dz}{\int_{-\infty}^{\infty} \int_0^{f(z)/cg(z)} du g(z) dz}$$

density def  
(= 1)

the same but  
 $\int_{-\infty}^y$  on denominator

=

$$\int_{-\infty}^y f(z) dz \quad Q.E.D.$$

unbiased i.i.d f

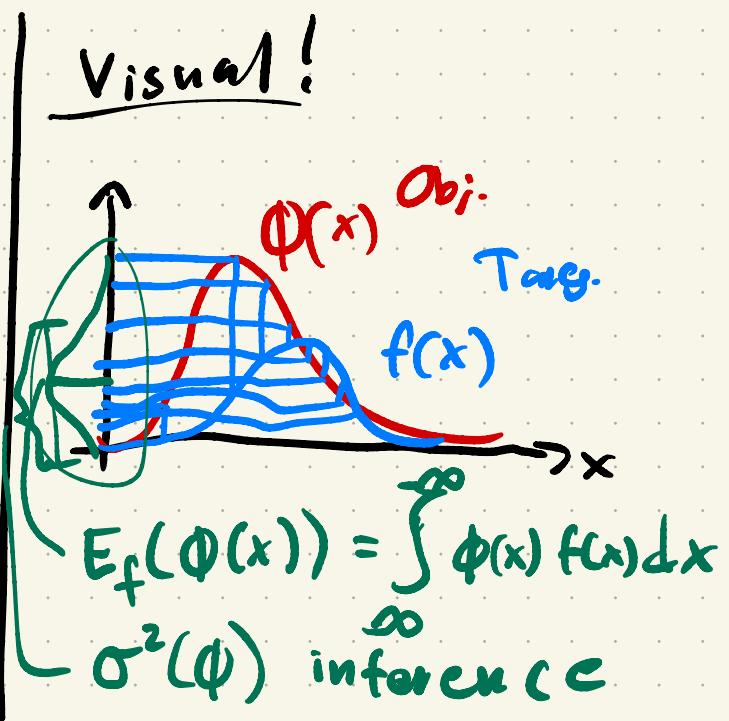
# Monte Carlo integration

## Explainer

(A) Basic Monte Carlo Sampler

(B) Importance Sampling

(C) Self-normalized Importance Sampling

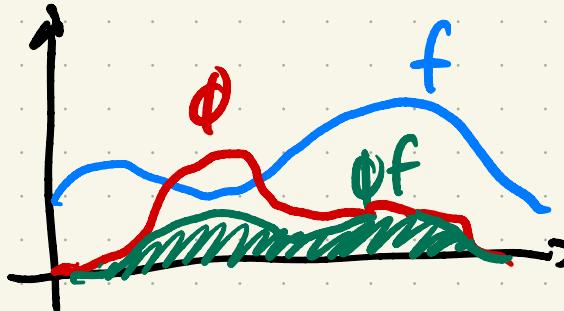


Intro: Random sampling to estimate integrand  $\Phi(x)$  useful

for problems that have difficult analytical solutions (or has no analytical solution).

Curse of dimensionality makes integrals vry diff as  $d \rightarrow \infty$ .

We seek



- (A) The foundation of basic MC sampling is the law of large numbers with  $\Phi(X_i)$  over  $n$  i.i.d  $X_i \sim f(x)$  converges to  $\rightarrow E_f(\Phi(x))$  as  $n \rightarrow \infty$

## Analytical Problem

$$\tau \equiv E_f(\Phi(x)) = \int_A \Phi(x) f(x) dx, A \subseteq \mathbb{R}^d$$

## Numerical Solution MC sampler

$$\tilde{\tau}_N \equiv \frac{1}{N} \sum_{i=1}^N \Phi(X_i) \approx \tau, \text{ as } N \text{ is large}$$

Assuming  $N \rightarrow \infty$ , then  $\tilde{\tau}_N = \tau$

# Monte Carlo integration

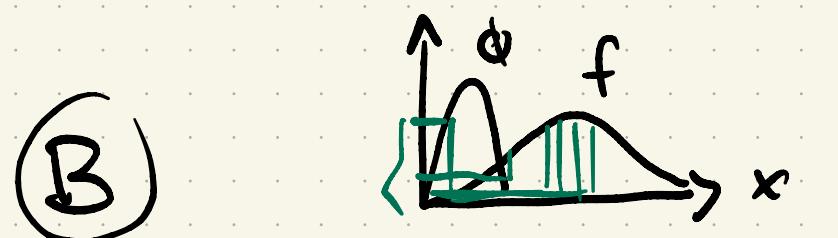
## Problem

$$\tau \equiv E(\phi(x)) = \int_A \phi(x) f(x) dx$$

$X$ : rand var within  $A \subseteq \mathbb{R}^d$  (where  $d \in \mathbb{N}$  may be large)

$f: A \rightarrow \mathbb{R}_+$  is density of  $X$  (target)

$\phi: A \rightarrow \mathbb{R}$  objective function



(B) MC effectiveness (i.e.  $\sigma(\phi)$ ) diminishes

when  $\phi_{\text{obj}}$  and  $f_{\text{target}}$  are dissimilar and  
many draws at small  $\phi(x)$  not contr. to estimate.

Importance sampling is introducing instrumental density

$g$ -instrumental density,  $g(x) = 0 \Rightarrow f(x) = 0$

To make them more similar.

$$\Rightarrow \tau = E(\phi(x)) = \int_{f(x) > 0} \phi(x) f(x) dx = \int_{f(x) > 0} \phi(x) \frac{f(x)}{g(x)} g(x) dx =$$

$$= \int_{g(x) > 0} \phi(x) w(x) g(x) dx = E_g(\phi(x) w(x))$$

$w$ -Imp weight function

# Monte Carlo integration

(B)

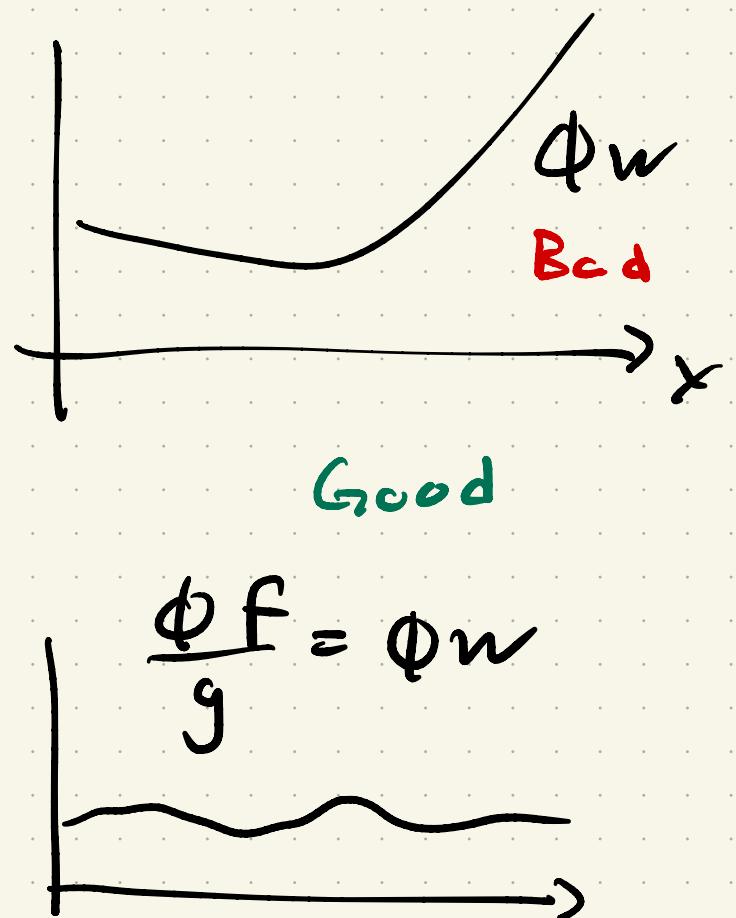
## Algorithm

$$① \quad x_i \sim g$$

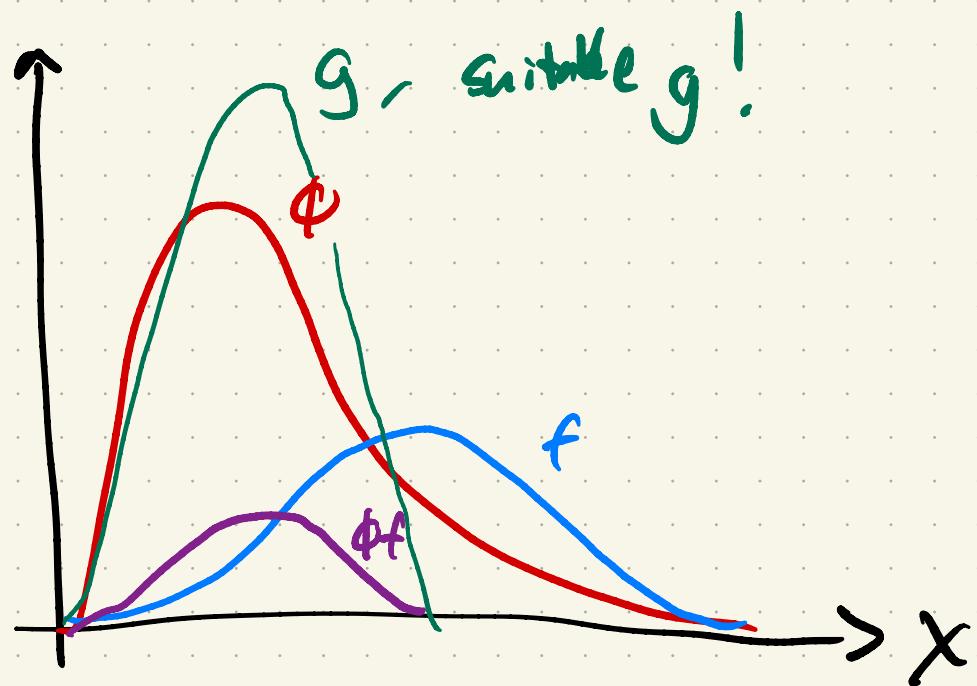
$$\left( \frac{f(x)}{g(x)} \right)$$

$$② \quad T_N = \frac{1}{N} \sum_i^N \phi(x_i) w(x_i)$$

$$V(\tilde{T}_N) = \frac{1}{N} V_g (\phi(x) w(x))$$



- $\phi(x) w$  should be close to constant in support of  $g$ .
- $g$  should be chosen by scale-location-transformation.



## Monte Carlo integration

### (c) Self Normalized IS

$z(x) = cf(x)$ , we do not know normalizing const  $c$ ,  
 we can sample

$$\tilde{\tau} = E_f(\phi(x)) \stackrel{\text{def}}{=} \int_X \phi(x) f(x) dx = \frac{c \int_{f>0} \phi(x) f(x) dx}{c \int_{f>0} f(x) dx} (= 1)$$

$$= \frac{\int_{g>0} \phi(x) c \frac{f(x)}{g(x)} g(x) dx}{\int_{g>0} c \frac{f(x)}{g(x)} g(x) dx}$$

$$= \frac{\int_{g>0} \phi(x) \frac{z(x)}{g(x)} g(x) dx}{\int_{g>0} \frac{z(x)}{g(x)} g(x) dx}$$

$$w(x) = \frac{z(x)}{g(x)}$$

$$= \frac{\int_{g>0} \phi(x) w(x) g(x) dx}{\int_{g>0} w(x) g(x) dx} = \frac{E_g(\phi(X) w(X))}{E_g(w(X))}$$

## Monte Carlo integration

(c) with

$$x_i \sim g \in \mathcal{N}(\mu, \sigma)$$

$E_g(\phi(x) w(x))$ ,  $E_g(w(x))$  may be estimated

$$\gamma = \frac{E_g(\phi(x) w(x))}{E_g(w(x))} \approx \frac{\frac{1}{N} \sum_i^N \phi(x_i) w(x_i)}{\frac{1}{N} \sum_j^N w(x_j)} =$$

$$= \frac{\sum_i^N w(x_i)}{\sum_j^N w(x_j)}$$

$\phi(x_i)$  SIS

$c = E_g(w(x))$   
 Normalized constant

$$\sum_i^N \frac{w(x_i)}{\sum_j^N w(x_j)} \phi(x_i)$$

## Monte Carlo integration

- (A) Prove the MC sampler satisfies CLT and provide asymptotic variance expression (B) Relation to Imp. Samp.?
  - (C) How is this useful for CI? (D) How can this be used for designing the instrumental distributions for a Imp. Samp. problem?
- 

(A) As  $N$  increases, the distr of the scaled deviation of the MC estimate  $\bar{\gamma}_N$  from the true  $\bar{\gamma}$ ,  $\bar{\gamma}_N - \bar{\gamma} \xrightarrow{d} N(0, \sigma^2(\phi))$

CLT def gives

$$\sqrt{N}(\bar{\gamma}_N - \bar{\gamma}) \xrightarrow{\text{converge}} N(0, V(\phi(x)))$$

$\sqrt{N}(\bar{\gamma}_N - \bar{\gamma})$  is asymptotically normal.

CLT requires:

- rand var " $\gamma_i$ " are i.i.d. **OK**
- $V(\phi(x)) < \infty$  **OK**

## Monte Carlo integration

- Asymptotic variance of MC estimator  $\bar{\tau}_N$

Rate of convergence gives for large  $N$

$$V(\sqrt{N}(\bar{\tau}_N - \tau)) = NV(\bar{\tau}_N - \tau) = V(\phi(x))$$

Implying

$$\begin{aligned} D(\bar{\tau}_N - \tau) &= \sqrt{V(\bar{\tau}_N - \tau)} = \sqrt{\frac{V(\phi(x))}{N}} \\ &= \frac{D(\phi(x))}{\sqrt{N}} = \frac{\sigma(\phi)}{\sqrt{N}} \end{aligned}$$

Convergence Rate

$O(\frac{1}{\sqrt{N}})$ , invariant of  $d$ !

$\Phi(\tau)$  has CLT if  $\Phi \in \mathcal{C}$ ,

$$\sqrt{N}(\Phi(\bar{\tau}_N) - \Phi(\tau)) \xrightarrow{d} N(0, \Phi'(\tau)^2 \sigma^2(\phi))$$

$\Phi(\bar{\tau}_N)$  is O.K but not unbiased estimator

B This relates to LS by

$$\bar{\tau}_N = E_g(\phi(x) w(x))$$

$$V(\sqrt{N}(\bar{\tau}_N - \tau)) = NV(\bar{\tau}_N - \tau) = V(\phi(x) w(x))$$

$$\begin{aligned} z(x) &\sim \\ \bar{\tau}_N &\Rightarrow D(\bar{\tau}_N - \tau) = \frac{D(\phi(x) w(x))}{\sqrt{N}} \end{aligned}$$

$$\begin{aligned} c = E(c) &= \int c f(x) dx = E_g(w(x)) = \int \frac{z(x)}{g(x)} g(x) dx = \int w(x) g(x) dx \\ &\approx \frac{1}{N} \sum_j^N w(x_j) \end{aligned}$$

## Monte Carlo integration

- ③ With inference of  $(\bar{x}_N - \bar{x}) \xrightarrow{d} N(0, \sigma^2(\phi))$  - you can construct CI of  $\phi(x)$  by

$$I_\alpha = \left( \bar{x}_N - \lambda_{\alpha/2} \frac{\sigma(\phi)}{\sqrt{N}}, \bar{x}_N + \lambda_{\alpha/2} \frac{\sigma(\phi)}{\sqrt{N}} \right)$$

- Where  $\sigma^2(\phi)$  is estimated

Var. def.

$$\sigma^2(\phi) = E(\phi^2(x)) - E(\phi(x))^2$$

$$\approx E(\phi(x)) - \bar{x}_N^2$$

Var. Def.

$$= \frac{1}{N} \sum_i^N \left( \phi(x_i) - \frac{1}{N} \sum_{j=1}^N \phi(x_j) \right)^2$$

Bias corr.

estimator

$$\Rightarrow \frac{1}{N-1} \sum_i^N \left( \phi(x_i) - \frac{1}{N} \sum_{j=1}^N \phi(x_j) \right)^2$$

- ④ For IS, this can be used for designing the instrumental distribution.

$$I_{\alpha/2} = \left( \bar{x}_N - \lambda_{\alpha/2} \frac{\sigma(\phi_w)}{\sqrt{N}}, \bar{x}_N + \lambda_{\alpha/2} \frac{\sigma(\phi_w)}{\sqrt{N}} \right)$$

Choose  $w$  so that CI is minimized.

## Var. Reduction for MC methods

$$E_f(\phi(x)) = E_{\tilde{f}}(\tilde{\phi}(x)), \quad \sigma^2(\tilde{\phi}) < \sigma^2(\phi)$$

- Explain how  $\sigma^2(\phi(x))$  can be reduced using control variates.

$E(Y)$  is known

$$\textcircled{1} \text{ Construct } z = \phi(x) + \beta(y - E(y)) \\ = \phi(x) + \beta(y - m)$$

$$\textcircled{2} \text{ Verify } E(z) = E(\phi(x)) + E(y) - E(x) \\ = E(\phi(x)) = z$$

$$V(\phi(x)) = \sigma^2(\phi)$$

$$V(z) = V(\phi(x) + \beta y)$$

$$= V(\phi(x)) + \beta^2 V(y)$$

$$+ 2\beta C(\phi(x), y)$$

$$\textcircled{3} \text{ Find } \beta^* \quad \frac{\partial V(z)}{\partial \beta} = 2\beta V(y) \\ + 2C(\phi(x), y) = 0$$

$$\Leftrightarrow \beta^* = -\frac{C(\phi(x), y)}{V(y)}$$