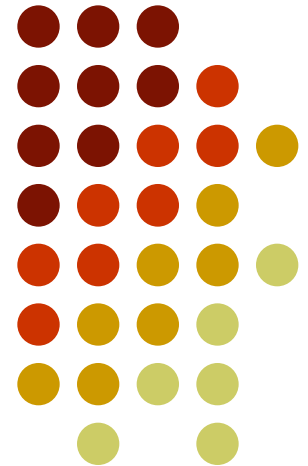


SISTEME DE CALCUL DEDICATE

Curs 3



Outline

- SystemC
 - Time
 - Concurrency
- Bibliography



Time



- three unique time measurements:
 - the simulation's wall-clock time
 - the time from the start of execution to completion, including time waiting on other system activities and applications.
 - the simulation's processor time
 - the actual time spent executing the simulation, which will always be less than the simulation's wall-clock time
 - the simulated time
 - the time being modeled by the simulation
 - it may be less than or greater than the simulation's wall-clock time



Time

- SystemC simulation performance is a combination of many factors:
 - the host system
 - system load
 - the C++ compiler
 - the SystemC simulator
 - the model being



Time

- data type `sc_time` – used by the simulation kernel
 - to track simulated time
 - to specify delays and timeouts
- `sc_time` is represented by a minimum of a 64-bit unsigned integer

```
sc_time name...; // no initialization
sc_time name(double, sc_time_unit)...;
sc_time name(const sc_time&)...;
```



Time

- time units
 - are defined by the enumeration **sc_time_unit**

enum	Units	Magnitude
SC_FS	femtoseconds	10^{-15}
SC_PS	picoseconds	10^{-12}
SC_NS	nanoseconds	10^{-9}
SC_US	microseconds	10^{-6}
SC_MS	milliseconds	10^{-3}
SC_SEC	seconds	10^0



Time

- all objects of **sc_time** use a single (global) time resolution
 - that has a default of 1 picosecond
 - the **sc_time** class provides get and set methods
 - **sc_set_time_resolution()**
 - may be used to change time resolution once and only once in a simulation
 - the change must occur before both creating objects of **sc_time** and starting the simulation.

```
//positive power of ten for resolution  
sc_set_time_resolution(double, sc_time_unit);
```

Time



- objects of `sc_time`
 - may be used as operands for assignment, arithmetic, and comparison operations
 - provides conversion methods to convert `sc_time` to a double (`to_double()`) or to a double scaled to seconds (`to_seconds()`)

```
sc_time t_PERIOD(5, SC_NS);  
sc_time t_TIMEOUT(100, SC_MS);  
sc_time t_MEASURE, t_CURRENT, t_LAST_CLOCK;  
t_MEASURE = (t_CURRENT - t_LAST_CLOCK);  
if (t_MEASURE > t_HOLD) { error("Setup violated") }
```




Time

- SystemC simulation kernel tracks simulated time using an `sc_time` object
 - **`sc_time_stamp()`** can be used to obtain the current simulated **`time_value`**

```
sc_time current_time = sc_time_stamp();
```

```
cout << "    The time is now "  
      << sc_time_stamp()  
      << "!" << endl;
```



Time

- method **sc_start()** is used to start simulation

```
//sim "forever"  
sc_start();  
//sim no more than max_sc_time  
sc_start(const sc_time& max_sc_time);  
//sim no more than max_time time_unit's  
sc_start(double max_time, sc_time_unit time_unit);
```

```
//FILE: main.cpp  
int sc_main(int argc, char* argv[]) { // args unused  
    basic_process_ex my_instance("my_instance");  
    sc_start(60.0, SC_SEC); // Limit sim to one minute  
    return 0;  
}
```



Time

- simulations use delays in simulated time to model
 - real world behaviors
 - mechanical actions
 - chemical reaction times
 - signal propagation
- **wait()** method provides a syntax to allow this delay in **SC_THREAD** processes

```
wait(delay_sc_time); // wait specified amount of
                     // time
```

Concurrency



- concurrency is fundamental to simulating with SystemC
- SystemC uses **simulation processes** to model concurrency
 - event-driven simulator
 - concurrency is not true concurrent execution
 - simulated concurrency works like cooperative multitasking
 - a simulation process runs: it is expected to execute a small segment of code and then return control to the simulation kernel

Concurrency



- SystemC simulation processes (**SC_THREAD**)
 - simply C++ function
 - designated by the programmer to be used as processes (**process registration**)
 - it can be used only within a SystemC module
 - the function must be a member function of the module class
 - must be used only during the elaboration stage
 - the member function must exist and the function can take no arguments and return no values

```
SC_THREAD (MEMBER_FUNCTION) ;
```



Concurrency

- processes must voluntarily yield control
 - executing a **return**
 - calling SystemC's **wait()** function
- processes typically begin execution at the start of simulation and continue in an endless loop until the simulation ends

```
//FILE: two_processes.h
SC_MODULE(two_processes) {
    void wiper_thread(void); // process
    void blinker_thread(void); // process
    SC_CTOR(two_processes) {
        SC_THREAD(wiper_thread); // register process
        SC_THREAD(blinker_thread); // register process
    }
};
```

Concurrency



```
//FILE: two_processes.cpp
void two_processes::wiper_thread(void) {
    while (true) {
        wipe_left();
        wait(500, SC_MS);
        wipe_right();
        wait(500, SC_MS);
    } //endwhile
}

void two_processes::blinker_thread(void) {
    while (true) {
        blinker = true;
        cout << "Blink ON" << endl;
        wait(300, SC_MS);
        cout << "Blink OFF" << endl;
        blinker = false;
        wait(300, SC_MS);
    } //endwhile
}
```



Concurrency

- **DEFINITION:** a SystemC event is the occurrence of an **sc_event** notification and happens at a single instant in time
- an event has no duration or value
- **RULE:** to observe an event, the observer must be watching for the event prior to its notification

```
sc_event event_name1[,event_namei]...;
```

```
event_name.notify(void);           // Immediate  
event_name.notify(SC_ZERO_TIME); // Delayed  
event_name.notify(sc_time);       // Timed (time>0)  
event_name.notify(double,units); // Convenience
```




Concurrency

- events are explicitly caused using the `notify()` method of an `sc_event` object
- invoking an immediate **`notify(void)`** causes any processes waiting for the event to be immediately moved from the waiting set into the runnable set for execution

```
sc_event A_event;  
A_event.notify(10, SC_NS);  
A_event.notify( 5, SC_NS); // only this one stays  
A_event.notify(15, SC_NS);
```



Concurrency

- thread processes rely on the **wait()** method to suspend their execution

```
wait(time);                // timeout is the event
wait(double,time_unit);    // convenience
wait(event);               // single event
wait(event1 | eventn...); // any of these
wait(event1 & eventn...); // all of these
wait(time,event);          // event or timeout
wait(time,event1 | eventn...); // any event or timeout
wait(time,event1 & eventn...); // all events or timeout
wait(); // static sensitivity - discussed later
```

Concurrency



```
....
sc_event ack_event, bus_error_event;

....
sc_time start_time(sc_time_stamp());
wait(t_MAX_DELAY, ack_event | bus_error_event);
if (sc_time_stamp()-start_time == t_MAX_DELAY) {
    break; // path for a time out
....
```

Concurrency



- SystemC has more than one type of process
 - The **SC_METHOD** process is in some ways simpler than the **SC_THREAD**
 - **SC_METHOD** processes never suspend internally (i.e., they can never invoke **wait()**)
 - **SC_METHOD** processes run completely and return

```
SC_METHOD(process_name) ; // Located INSIDE constructor
```



Concurrency

- **SC_METHOD** processes dynamically specify their sensitivity by means of the **next_trigger()** method

```
next_trigger(time);  
next_trigger(timeout,time_unit); //convenience  
next_trigger(event);  
next_trigger(event1 | eventi...); //any of these  
next_trigger(event1 & eventi...); //all of these  
                                //required  
next_trigger(timeout,event); //event with timeout  
next_trigger(timeout,event1 | eventi...); //any + timeout  
next_trigger(timeout,event1 & eventi...); //all + timeout  
next_trigger(void); //re-establish static sensitivity
```



Concurrency

- The concept of actively determining what will cause a process to resume is often called **dynamic sensitivity**
- **Static sensitivity** establishes the parameters for resumption during elaboration (i.e., before simulation begins).
- Once established, static sensitivity parameters cannot be changed (i.e., they're static).

```
// IMPORTANT: Must follow process registration  
sensitive << event [<< event]_; // streaming style
```



Concurrency

- the simulation engine description specifies that processes are executed at least once initially by placing processes in the runnable set during the initialization stage
- it may be necessary to specify that some processes should not be made runnable at initialization
 - SystemC provides the **dont_initialize()** method

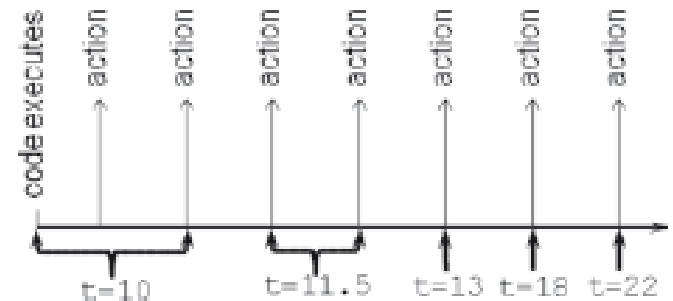
```
...  
SC_METHOD(attendant_method);  
    sensitive(fillup_request);  
    dont_initialize();  
...
```



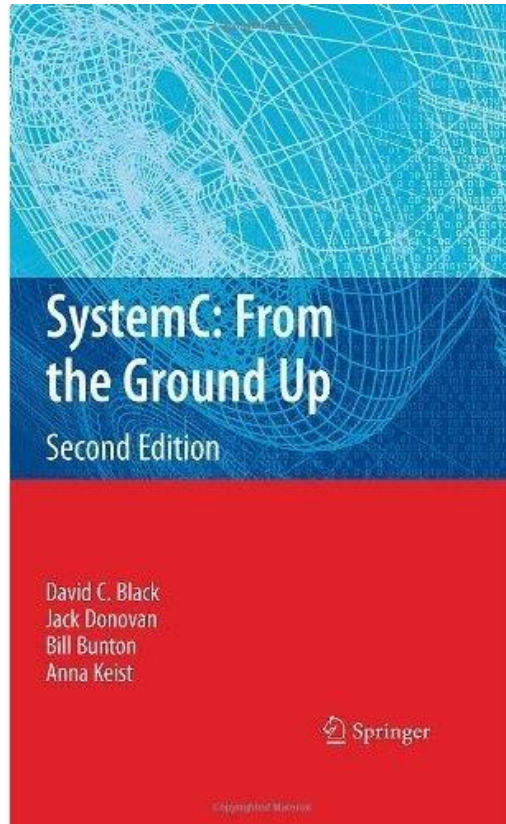
Concurrency

- **sc_event_queue**
 - allows a single event to be scheduled multiple times even for the same instant in time

```
sc_event_queue action;  
wait(10, SC_NS) // assert time=10ns  
sc_time now1(sc_time_stamp()); // observe current time  
action.notify(20, SC_NS); // schedule for 20ns from now  
action.notify(10, SC_NS); // schedule for 20ns from now  
action.cancel_all(); // cancel all actions entirely  
action.notify(8, SC_NS); // schedule for 8 ns from now  
action.notify(1.5, SC_NS); // 1.5 ns from now  
action.notify(1.5, SC_NS); // another identical action  
action.notify(3.0, SC_NS); // 3.0 ns from now  
action.notify(SC_ZERO_TIME); // after all runnable  
action.notify(SC_ZERO_TIME); // and yet another  
action.notify(12, SC_NS); // 12 ns from now  
sc_time now2(sc_time_stamp()); // observe current time
```



Bibliography



- David C. Black, Jack Donovan, Bill Bunton, Anna Keist, ***SystemC: From the Ground Up***, Springer Science+Business Media, LLC 2010
 - “The authors designed this book primarily for the student or engineer new to SystemC. This book’s structure is best appreciated by reading sequentially from beginning to end.”