

# Jin Cheng

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## EDUCATION

Doctoral student in Computer Science, ETH Zürich, Switzerland	since 10/2023
Advisor: <a href="#">Prof. Dr. Stelian Coros</a> (ETH Zürich), <a href="#">Prof. Dr. Guanya Shi</a> (Carnegie Mellon University)	
M.Sc. in Mechanical Engineering, ETH Zürich, Switzerland	09/2020 – 07/2023
B.E. in Vehicle Engineering, Tsinghua University, China	09/2016 – 07/2020

## RESEARCH EXPERIENCE

Scientific Assistant, ETH Zürich	since 10/2023
Computational Robotics Lab (CRL), supervised by <a href="#">Prof. Dr. Stelian Coros</a>	
Research Intern, Max Planck Institute for Intelligent Systems	04/2023 - 09/2023
Autonomous Learning Group, supervised by <a href="#">Prof. Dr. Georg Martius</a>	
Research Assistant, ETH Zürich	11/2022 - 03/2023
Computational Robotics Lab (CRL), supervised by <a href="#">Prof. Dr. Stelian Coros</a>	
Semester and Master Thesis, ETH Zürich	03/2022 - 11/2022
Robotic Systems Lab (RSL), supervised by <a href="#">Prof. Dr. Marco Hutter</a>	
Research Assistant and Bachelor Thesis, Tsinghua University	09/2019 - 05/2020
State Key Laboratory of Intelligent Green Vehicle and Mobility, supervised by <a href="#">Prof. Dr. Qing Zhou</a>	

## PUBLICATIONS

Whole-body Inverse Dynamics MPC for Legged Loco-manipulation (RA-L)	11/2025
<a href="#">Lukas Molnar</a> , <a href="#">Jin Cheng</a> , <a href="#">Gabriele Fadini</a> , <a href="#">Dongho kang</a> , <a href="#">Fateme Zargarbashi</a> , <a href="#">Stelian Coros</a>	
RAMBO: RL-Augmented Model-Based Whole-Body Control for Loco-Manipulation (RA-L)	07/2025
<a href="#">Jin Cheng</a> , <a href="#">Dongho Kang</a> , <a href="#">Gabriele Fadini</a> , <a href="#">Guanya Shi</a> , <a href="#">Stelian Coros</a>	
Spatio-Temporal Motion Retargeting for Quadruped Robots (T-RO)	07/2025
<a href="#">Taerim Yoon</a> , <a href="#">Dongho Kang</a> , <a href="#">Seungmin Kim</a> , <a href="#">Jin Cheng</a> , <a href="#">Minsung Ahn</a> , <a href="#">Stelian Coros</a> , <a href="#">Sungjoon Choi</a>	
SATA: Safe and Adaptive Torque-Based Locomotion Policies Inspired by Animal Learning (RSS 2025)	02/2025
<a href="#">Peizhuo Li</a> , <a href="#">Hongyi Li</a> , <a href="#">Ge Sun</a> , <a href="#">Jin Cheng</a> , <a href="#">Xinrong Yang</a> , <a href="#">Guillaume Bellegarda</a> , <a href="#">Milad Shafiee</a> , <a href="#">Yuhong Cao</a> , <a href="#">Auke Ijspeert</a> , <a href="#">Guillaume Sartoretti</a>	
DARE: Diffusion Policy for Autonomous Robot Exploration (ICRA 2025)	02/2025
<a href="#">Yuhong Cao</a> , <a href="#">Jeric Lew</a> , <a href="#">Jingsong Liang</a> , <a href="#">Jin Cheng</a> , <a href="#">Guillaume Sartoretti</a>	
RobotKeyframing: Learning Locomotion with High-Level Objectives via Mixture of Dense and Sparse Rewards (CoRL 2024)	09/2024
<a href="#">Fateme Zargarbashi</a> , <a href="#">Jin Cheng</a> , <a href="#">Dongho Kang</a> , <a href="#">Robert Sumner</a> , and <a href="#">Stelian Coros</a>	
Offline Diversity Maximization Under Imitation Constraints (RLC 2024)	05/2024
<a href="#">Marin Vlastelica</a> , <a href="#">Jin Cheng</a> , <a href="#">Georg Martius</a> , <a href="#">Pavel Kolev</a>	
Learning Diverse Skills for Local Navigation under Multi-constraint Optimality (ICRA 2024)	02/2024
<a href="#">Jin Cheng</a> , <a href="#">Marin Vlastelica</a> , <a href="#">Pavel Kolev</a> , <a href="#">Chenhao Li</a> , <a href="#">Georg Martius</a>	
RL + Model-based Control: Using On-demand Optimal Control to Learn Versatile Legged Locomotion (RA-L)	09/2023
<a href="#">Dongho Kang</a> , <a href="#">Jin Cheng</a> , <a href="#">Miguel Zamora</a> , <a href="#">Fateme Zargarbashi</a> , <a href="#">Stelian Coros</a>	
Haptic Teleoperation of High-dimensional Robotic Systems Using a Feedback MPC Framework (IROS 2022)	10/2022
<a href="#">Jin Cheng</a> , <a href="#">Firas Abi-Farraj</a> , <a href="#">Farbod Farshidian</a> , <a href="#">Marco Hutter</a>	

<b>Benchmarking Whole-Body Motion Tracking Policies via Just Dance: Using a Commercial Console Game for Embodied-AI Evaluation (Under Review)</b> <i>Jeonghwan Kim, Wontaek Kim, Yidan Lu, Jin Cheng, Fatemeh Zargarbashi, Zicheng Zeng, Zekun Qi, Zhiyang Dou, Nitish Sontakke, Donghoon Baek, Li Yi, Sehoon Ha, Tianyu Li</i>	11/2025
<b>APEX: Action Priors Enable Efficient Exploration for Robust Motion Tracking on Legged Robots (Under Review)</b> <i>Shivam Sood, Laukik Nakhwa, Ge Sun, Yuhong Cao, Jin Cheng, Fatemeh Zargarbashi, Taerim Yoon, Sungjoon Choi, Stelian Coros, Guillaume Sartoretti</i>	11/2025
<b>TARC: Time-Adaptive Robotic Control (Under Review)</b> <i>Arnav Sukhija, Lenart Treven, Jin Cheng, Florian Dörfler, Stelian Coros, Andreas Krause</i>	09/2025
<b>Learning Steerable Imitation Controllers from Unstructured Animal Motions (Under Review)</b> <i>Dongho Kang, Jin Cheng, Fatemeh Zargarbashi, Taerim Yoon, Sungjoon Choi, Stelian Coros</i>	07/2025
<b>CAIMAN: Causal Action Influence Detection for Sample-efficient Loco-manipulation (Under Review)</b> <i>Yuanchen Yuan, Jin Cheng, Núria Armengol Urpí, Stelian Coros</i>	07/2025
<b>Learning More With Less: Sample Efficient Dynamics Learning and Model-Based RL for Loco-Manipulation</b> <i>Benjamin Hoffman, Jin Cheng, Chenhao Li, Stelian Coros</i>	02/2025
<b>MetaLoco: Universal Quadrupedal Locomotion with Meta-Reinforcement Learning and Motion Imitation</b> <i>Fatemeh Zargarbashi, Fabrizio Di Giuro, Jin Cheng, Dongho Kang, Bhavya Sukhija, Stelian Coros</i>	09/2024

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INVITED TALKS

<b>Intelligent Motion Lab (IMO) @ Seoul National University (SNU)</b>	10/2025
<b>Frontier AI &amp; Robotics (FAR) @ Amazon</b>	05/2025
<b>Robotics and AI Institute (RAI) @ Zurich</b>	04/2025
<b>Biomimetic Robotics Laboratory @ Massachusetts Institute of Technology (MIT)</b>	11/2023

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TEACHING EXPERIENCE

<b>Probabilistic Artificial Intelligence (263-5210-00)</b> <i>Learning &amp; Adaptive Systems Group (LAS) at ETH Zürich, lectured by A. Krause</i>	08/2025 - 02/2026
<b>Computational Models of Motion (263-5807-00)</b> <i>Computational Robotics Lab (CRL) at ETH Zürich, lectured by S. Coros</i>	02/2025 - 07/2025
<b>Probabilistic Artificial Intelligence (263-5210-00)</b> <i>Learning &amp; Adaptive Systems Group (LAS) at ETH Zürich, lectured by A. Krause</i>	08/2024 - 02/2025
<b>Introduction to Machine Learning (252-0220-00)</b> <i>Learning &amp; Adaptive Systems Group (LAS) at ETH Zürich, lectured by F. Perez Cruz, F. Yang</i>	02/2024 - 08/2024
<b>Dynamic Programming and Optimal Control (151-0563-01)</b> <i>Institute for Dynamic Systems and Control (IDSC) at ETH Zürich, lectured by R. D'Andrea</i>	08/2022 - 02/2023
<b>Recursive Estimation (151-0566-00)</b> <i>Institute for Dynamic Systems and Control (IDSC) at ETH Zürich, lectured by R. D'Andrea</i>	02/2022 - 08/2022
<b>Dynamic Programming and Optimal Control (151-0563-01)</b> <i>Institute for Dynamic Systems and Control (IDSC) at ETH Zürich, lectured by R. D'Andrea</i>	08/2021 - 02/2022

## SKILLS AND SERVICES

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**Language:** Chinese (Native), English (C1), German (B2)

**Programming:** Python, C++, Git, Docker, L<sup>A</sup>T<sub>E</sub>X, PyTorch, ROS

**Journal Reviewer:** T-RO, RA-L

**Conference Reviewer:** CoRL, ICRA, IROS, RLC, SIGGRAPH

## SCHOLARSHIPS AND AWARDS

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<b>Outstanding Teaching Assistant Award</b> <i>ETH Zürich</i>	03/2022 <i>Zürich, Switzerland</i>
<b>Friends of Tsinghua Scholarship – German Scholarship</b> <i>Tsinghua University</i>	10/2019 <i>Beijing, China</i>
<b>Academic Excellence Scholarship</b> <i>Tsinghua University</i>	10/2018, 10/2019 <i>Beijing, China</i>
<b>Volunteer Public Service Scholarship</b> <i>Tsinghua University</i>	10/2018 <i>Beijing, China</i>
<b>Integrated Excellence Scholarship</b> <i>Tsinghua University</i>	10/2017 <i>Beijing, China</i>

13.11.2025