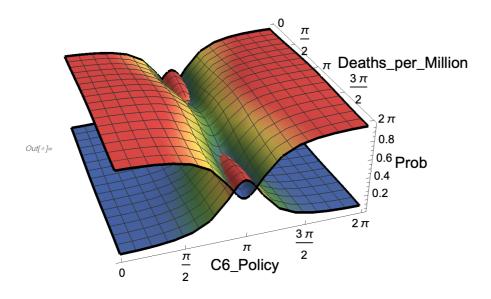
```
In[*]:= (* C3.AI COVID CHALLENGE *)
    In[●]:= (* Sweden *)
In[1191]:= Clear["Global`*"]
    In[*]:= type = "Deaths_per_Million";
                 policy = "C6_Policy";
ln[1194]:= pD0 = 0.6649;
                 pD1 = 0.1373;
                 pD2 = 0.0598;
                 pD3 = 0.1188;
                 pD4 = 0.0192;
     In[*]:= (* COnditional Prob *)
ln[1200] = pD0C6l1 = 0.7830;
                 pD1C6l1 = 0.9973;
                 pD2C6l1 = 0.9938;
                 pD3C6l1 = 0.9969;
                 pD4C6l1 = 0.9808;
In[1205]:= pD0C6l0 = 1 - pD0C6l1;
                 pD1C6l0 = 1 - pD1C6l1;
                  pD2C6l0 = 1 - pD2C6l1;
                  pD3C6l0 = 1 - pD3C6l1;
                 pD4C6l0 = 1 - pD4C6l1;
    In[*]:= (* C6 - 1 *)
In[1211]:= prC6l0 = pD0 pD0C6l0 + pD1 pD1C6l0 + pD2 pD2C6l0 + pD3 pD3C6l0 + pD4 pD4C6l0
   Out[\bullet] = 0.145762
In[1212]:= prC6l1 = pD0 pD0C6l1 + pD1 pD1C6l1 + pD2 pD2C6l1 + pD3 pD3C6l1 + pD4 pD4C6l1
   Out[*]= 0.854238
    In[*]:= (* Quantum Prob *)
ln[1214] = interfC6l0 = Sqrt[pD0 pD0C6l0 pD1 pD1C6l0] Cos[\theta00 - \theta10] + ln[1214] = interfC6l0 = Sqrt[pD0 pD0C6l0 pD1 pD1C6l0] Cos[\theta00 - \theta10] + ln[1214] = interfC6l0 = Sqrt[pD0 pD0C6l0 pD1 pD1C6l0] Cos[\theta00 - \theta10] + ln[1214] = interfC6l0 = Sqrt[pD0 pD0C6l0 pD1 pD1C6l0] Cos[\theta00 - \theta10] + ln[1214] = interfC6l0 = Sqrt[pD0 pD0C6l0 pD1 pD1C6l0] Cos[\theta00 - \theta10] + ln[1214] = interfC6l0 = Sqrt[pD0 pD0C6l0 pD1 pD1C6l0] Cos[\theta00 - \theta10] + ln[1214] = interfC6l0 = Sqrt[pD0 pD0C6l0 pD1 pD1C6l0] Cos[\theta00 - \theta10] + ln[1214] = interfC6l0 = Sqrt[pD0 pD0C6l0 pD1 pD1C6l0] Cos[\theta00 - \theta10] + ln[1214] = interfC6l0 = Sqrt[pD0 pD0C6l0 pD1 pD1C6l0] Cos[\theta00 - \theta10] + ln[1214] = ln[1214]
                            Sqrt[pD0 pD0C6l0 pD2 pD2C6l0] Cos[000 - 020] + Sqrt[pD0 pD0C6l0 pD3 pD3C6l0]
                              Cos[θ00 - θ30] + Sqrt[ pD0 pD0C6l0 pD4 pD4C6l0] Cos[θ00 - θ40] +
                            Sqrt[pD1 pD1C6l0 pD2 pD2C6l0 ] Cos[010 - 020] + Sqrt[pD1 pD1C6l0 pD3 pD3C6l0]
                              Cos[\theta 10 - \theta 30] + Sqrt[pD1 pD1C6l0 pD4 pD4C6l0] Cos[\theta 10 - \theta 40] +
                            Sqrt[pD2 pD2C6l0 pD3 pD3C6l0] Cos[\text{\text{o}}20 - \text{\text{\text{o}}30]} + Sqrt[pD2 pD2C6l0 pD4 pD4C6l0]
                              Cos[\theta 20 - \theta 40] + Sqrt[pD3 pD3C6l0 pD4 pD4C6l0] Cos[\theta 30 - \theta 40];
```

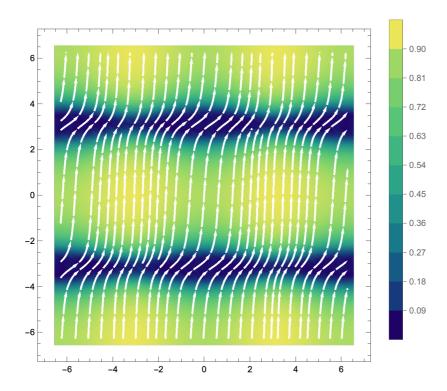
```
||f||_{1215} = interfC6l1 = Sqrt[pD0 pD0C6l1 pD1 pD1C6l1] Cos[\theta01 - \theta11] +
                                                        Sqrt[pD0 pD0C6l1 pD2 pD2C6l1] Cos[001 - 021] + Sqrt[pD0 pD0C6l1 pD3 pD3C6l1]
                                                               Cos[θ01 - θ31] + Sqrt[ pD0 pD0C6l1 pD4 pD4C6l1] Cos[θ01 - θ41] +
                                                        Sqrt[pD1 pD1C6l1 pD2 pD2C6l1 | Cos[011 - 021] + Sqrt[pD1 pD1C6l1 pD3 pD3C6l1]
                                                              Cos[\theta 11 - \theta 31] + Sqrt[pD1 pD1C6l1 pD4 pD4C6l1] Cos[\theta 11 - \theta 41] +
                                                        Sqrt[pD2 pD2C6l1 pD3 pD3C6l1] Cos[021 - 031] + Sqrt[pD2 pD2C6l1 pD4 pD4C6l1]
                                                               Cos[\theta 21 - \theta 41] + Sqrt[pD3 pD3C6l1 pD4 pD4C6l1] Cos[\theta 30 - \theta 41];
In[1216]:= qprC6l0 = prC6l0 + 2 interfC6l0;
In[1217]:= qprC6l1 = prC6l1 + 2 interfC6l1;
In[1218]:=
ln[1219] = qprC6l0Norm = FullSimplify \left[ \frac{qprC6l0}{qprC6l0 + qprC6l1} \right];
In[1220]:= qprC6l1Norm = 1 - qprC6l0Norm;
                                    (*FullSimplify[\frac{qprC6l1}{qprC6l0+qprC6l1}]; *)
In[1221]:= res = Minimize[{qprC6l0Norm, qprC6l0Norm+qprC6l1Norm == 1},
                                                 \{\theta00, \theta01, \theta10, \theta20, \theta30, \theta40, \theta11, \theta21, \theta31, \theta41\}
      Outf = \{0.0270547, \{000 \rightarrow 3.12584, 001 \rightarrow -0.0157531, 010 \rightarrow -0.0157536, 010 \rightarrow -0.0157536, 010 \rightarrow -0.0157536, 010 \rightarrow -0.0157531, 010 \rightarrow -0.0157536, 010 \rightarrow -0.0157531, 010 \rightarrow -0.0157511, 010 \rightarrow -0.01
                                                 \theta20 \rightarrow -0.0157537, \theta30 \rightarrow -0.0157535, \theta40 \rightarrow -0.0157536, \theta11 \rightarrow -0.0157531,
                                                 \theta21 \rightarrow -0.0157531, \theta31 \rightarrow -0.0157531, \theta41 \rightarrow -0.0157532}}
         In[*]:= (* Params *)
ln[1223] = \theta 10 = res[[2]][[3]][[2]];
                                      \theta20 = res[[2]][[4]][[2]];
                                     \theta30 = res[[2]][[5]][[2]];
                                   \theta40 = res[[2]][[6]][[2]];
                                   \theta11 = res[[2]][[7]][[2]];
                                   \theta21 = res[[2]][[8]][[2]];
                                  \theta31 = res[[2]][[9]][[2]];
                                  \theta41 = res[[2]][[10]][[2]];
          In[•]:=
          In[*]:= qprC6l0Norm = FullSimplify[ qprC6l0 + qprC6l1];
          In[@]:= qprC6l1Norm = 1 - qprC6l0Norm;
          In[*]:= (* Updated probabilities *)
          In[*]:= {qprC6l0Norm, qprC6l1Norm}
       Out = \{ (10.3023 + 4.00665 \cos [\theta 00] - 0.0631243 \sin [\theta 00]) / (128.284 + 0.00631243 \sin [\theta 00]) / (128.284 + 0.0063143 + 0.00631243 \sin [\theta 00]) / (128.284 + 0.00631243 + 0.00631243 + 0.0063144 + 0.0063144 + 0.0063144 + 0.0063144 + 0.0063144 + 0.0063144 + 0.0063144 + 0.0063144 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0
                                                               4.00665 \cos [\theta 00] + 108.392 \cos [\theta 01] - 0.0631243 \sin [\theta 00] - 1.70765 \sin [\theta 01]
                                           1 - (10.3023 + 4.00665 \cos [\theta 00] - 0.0631243 \sin [\theta 00]) / (128.284 + 0.00631243 + 0.00631243 \sin [\theta 00]) / (128.284 + 0.00631243 + 0.00631443 + 0.0063144 + 0.0063144 + 0.0063144 + 0.0063144 + 0.00631444 + 0.0063144 + 0.0063144 + 0.0063144 + 0.0063144 + 0.0063144 + 0.0063144 + 0.0063144 + 0.0063144 + 0.0063144 + 0.0063144 + 0.0063144 + 0.0063144 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.00644 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.0064 + 0.006
                                                                      4.00665 \cos [\theta 00] + 108.392 \cos [\theta 01] - 0.0631243 \sin [\theta 00] - 1.70765 \sin [\theta 01])
```

```
ln[1236] = p0 = Plot3D[qprC6l0Norm, {\theta00, 0, 2\pi},
          \{\theta 01, 0, 2\pi\}, ColorFunction \rightarrow (ColorData["DarkRainbow"][#3] &),
          AxesLabel → {Style[type, 16], Style[policy, 16], Style["Prob", 16]},
          BoundaryStyle → Thick, Boxed → False,
          Ticks \rightarrow {{0, Pi/2, Pi, 3 Pi/2, 2 Pi}, {0, Pi/2, Pi, 3 Pi/2, 2 Pi}, Automatic},
          TicksStyle → Directive[Black, 12]];
ln[1237] = p1 = Plot3D[qprC6l1Norm, {\theta00, 0, 2\pi},
          \{\theta 01, 0, 2\pi\}, ColorFunction \rightarrow (ColorData["DarkRainbow"][#3] &),
          AxesLabel → {Style[type, 16], Style[policy, 16], Style["Prob", 16]},
          BoundaryStyle → Thick, Boxed → False,
          Ticks → {\{0, Pi/2, Pi, 3Pi/2, 2Pi\}, \{0, Pi/2, Pi, 3Pi/2, 2Pi\}, Automatic},
          TicksStyle → Directive[Black, 12]];
```

In[1238]:= **Show[p0, p1]** 

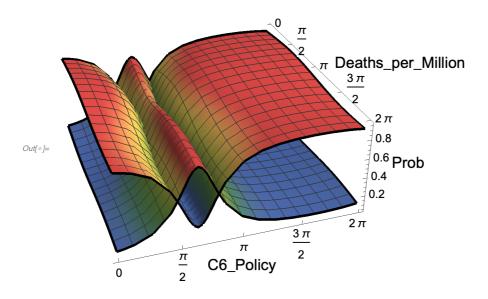


In[\*]:= fig = StreamDensityPlot[{qprC6l0Norm, qprC6l1Norm},  $\{\theta00, -2\pi, 2\pi\}, \{\theta01, -2\pi, 2\pi\}, \text{ColorFunction} \rightarrow \text{"BlueGreenYellow"},$ PlotLegends → BarLegend[{"BlueGreenYellow", {0, 1}}, 10], AxesLabel → Automatic, StreamStyle → {White, Thick}]



```
log[a] := Clear[\theta 10, \theta 20, \theta 30, \theta 40, \theta 11, \theta 21, \theta 31, \theta 41]
  ln[*]: res = Maximize[{qprC6l0Norm, qprC6l0Norm + qprC6l1Norm == 1},
                                               \{\theta00, \theta01, \theta10, \theta20, \theta30, \theta40, \theta11, \theta21, \theta31, \theta41\}
Out[\ \circ\ ]=\ \{\ 0.599076\ ,
                                       \{\theta00 \rightarrow -0.0157536, \ \theta01 \rightarrow -3.15735, \ \theta10 \rightarrow -1.04233, \ \theta20 \rightarrow -1.18342, \ \theta30 \rightarrow -1.33467, \ \theta40 \rightarrow -1.04233, \ \theta40 \rightarrow -
                                             \emptyset40 \rightarrow -1.14213, \emptyset11 \rightarrow -1.55531, \emptyset21 \rightarrow 0.112742, \emptyset31 \rightarrow -1.76147, \emptyset41 \rightarrow 0.183178}}
 In[*]:= (* Params *)
 ln[@]:= \Theta 10 = res[[2]][[3]][[2]];
                                 \theta20 = res[[2]][[4]][[2]];
                                 \theta30 = res[[2]][[5]][[2]];
                              \theta40 = res[[2]][[6]][[2]];
                              \theta11 = res[[2]][[7]][[2]];
                              \theta21 = res[[2]][[8]][[2]];
                              \theta31 = res[[2]][[9]][[2]];
                               \theta41 = res[[2]][[10]][[2]];
   In[ • ]:=
  In[*]:= qprC6l0Norm = FullSimplify[\frac{qprC6l0 + qprC6l1}{}];
  In[@]:= qprC6l1Norm = 1 - qprC6l0Norm;
 In[*]:= (* Updated probabilities *)
```

```
Infol:= {qprC6l0Norm, qprC6l1Norm}
                            10.264 + 1.52967 \cos [\theta 00] - 3.66558 \sin [\theta 00]
      84.8298 + 1.52967 \cos[\theta 00] + 31.3413 \cos[\theta 01] - 3.66558 \sin[\theta 00] - 64.6681 \sin[\theta 01]
      1 -
                              10.264 + 1.52967 \cos [\theta 00] - 3.66558 \sin [\theta 00]
        84.8298 + 1.52967 \cos[\theta 00] + 31.3413 \cos[\theta 01] - 3.66558 \sin[\theta 00] - 64.6681 \sin[\theta 01]
ln[\bullet]:= p0 = Plot3D[qprC6l0Norm, {\theta00, 0, 2\pi},
         \{\theta 01, 0, 2\pi\}, ColorFunction \rightarrow (ColorData["DarkRainbow"][#3] &),
         AxesLabel → {Style[type, 16], Style[policy, 16], Style["Prob", 16]},
         BoundaryStyle → Thick, Boxed → False,
         Ticks → {{0, Pi/2, Pi, 3 Pi/2, 2 Pi}, {0, Pi/2, Pi, 3 Pi/2, 2 Pi}, Automatic},
         TicksStyle → Directive[Black, 12]];
ln[\bullet]:= p1 = Plot3D[qprC6l1Norm, {\theta00, 0, 2\pi},
         \{\theta 01, 0, 2\pi\}, ColorFunction \rightarrow (ColorData["DarkRainbow"][#3] &),
         AxesLabel → {Style[type, 16], Style[policy, 16], Style["Prob", 16]},
         BoundaryStyle → Thick, Boxed → False,
         Ticks → {\{0, Pi/2, Pi, 3Pi/2, 2Pi\}, \{0, Pi/2, Pi, 3Pi/2, 2Pi\}, Automatic},
         TicksStyle → Directive[Black, 12]];
```



In[\*]:= Show[p0, p1]

```
ln[*]:= fig = StreamDensityPlot[{qprC6l0Norm, qprC6l1Norm},
       \{\theta00, -2\pi, 2\pi\}, \{\theta01, -2\pi, 2\pi\}, \text{ColorFunction} \rightarrow \text{"BlueGreenYellow"},
       PlotLegends → BarLegend[{"BlueGreenYellow", {0, 1}}, 10],
       AxesLabel → Automatic, StreamStyle → {White, Thick}]
```

