

```

In[ ]:= (* C3.AI COVID CHALLENGE *)

In[1127]:= Clear["Global`*"]

In[1765]:= type = "Cases_per_Million";
           policy = "C6_Policy";

In[1495]:= pD0 = 0.7609;
           pD1 = 0.0967;
           pD2 = 0.0266;
           pD3 = 0.0155;
           pD4 = 0.1003;
           pD0 + pD1 + pD2 + pD3 + pD4

In[ ]:= (* C0nditional Prob *)

In[1545]:= pD0C6l0 = 0.3349;
           pD1C6l0 = 0.0019;
           pD2C6l0 = 0.1458;
           pD3C6l0 = 0.0119;
           pD4C6l0 = 1 - pD0C6l0 - pD1C6l0 - pD2C6l0 - pD3C6l0;

In[1550]:= pD0C6l1 = 0.13603298639670133;
           pD1C6l1 = 0.23091590763363695;
           pD2C6l1 = 0.2847222847222847;
           pD3C6l1 = 0.011904804761921906;
           pD4C6l1 = 1 - pD0C6l1 - pD1C6l1 - pD2C6l1 - pD3C6l1;

In[1555]:= pD0C6l2 = 0.5095;
           pD1C6l2 = 0.3073;
           pD2C6l2 = 0.4236;
           pD3C6l2 = 0.7262;
           pD4C6l2 = 1 - pD0C6l2 - pD1C6l2 - pD2C6l2 - pD3C6l2;

In[1560]:= pD0C6l3 = 0.0196;
           pD1C6l3 = 0.4599;
           pD2C6l3 = 0.1458;
           pD3C6l3 = 0.2500;
           pD4C6l3 = 1 - pD0C6l3 - pD1C6l3 - pD2C6l3 - pD3C6l3;

In[ ]:= (* C6 - 1 *)

In[1567]:= prC6l0 = pD0 pD0C6l0 + pD1 pD1C6l0 + pD2 pD2C6l0 + pD3 pD3C6l0 + pD4 pD4C6l0
Out[ ]:= 0.309774

In[1568]:= prC6l1 = pD0 pD0C6l1 + pD1 pD1C6l1 + pD2 pD2C6l1 + pD3 pD3C6l1 + pD4 pD4C6l1
Out[ ]:= 0.167339

In[1569]:= prC6l2 = pD0 pD0C6l2 + pD1 pD1C6l2 + pD2 pD2C6l2 + pD3 pD3C6l2 + pD4 pD4C6l2
Out[ ]:= 0.342968

```

In[1570]:= $\text{prC6l3} = \text{pD0 pD0C6l3} + \text{pD1 pD1C6l3} + \text{pD2 pD2C6l3} + \text{pD3 pD3C6l3} + \text{pD4 pD4C6l3}$

Out[]:= 0.0796467

In[1774]:= $\text{prC6l0} + \text{prC6l1} + \text{prC6l2} + \text{prC6l3}$

Out[]:= 0.899727

In[]:= (* Quantum Prob *)

In[1571]:= $\text{interfC6l0} = \text{Sqrt}[\text{pD0 pD0C6l0 pD1 pD1C6l0}] \text{Cos}[\theta_{00} - \theta_{10}] +$
 $\text{Sqrt}[\text{pD0 pD0C6l0 pD2 pD2C6l0}] \text{Cos}[\theta_{00} - \theta_{20}] + \text{Sqrt}[\text{pD0 pD0C6l0 pD3 pD3C6l0}]$
 $\text{Cos}[\theta_{00} - \theta_{30}] + \text{Sqrt}[\text{pD0 pD0C6l0 pD4 pD4C6l0}] \text{Cos}[\theta_{00} - \theta_{40}] +$
 $\text{Sqrt}[\text{pD1 pD1C6l0 pD2 pD2C6l0}] \text{Cos}[\theta_{10} - \theta_{20}] + \text{Sqrt}[\text{pD1 pD1C6l0 pD3 pD3C6l0}]$
 $\text{Cos}[\theta_{10} - \theta_{30}] + \text{Sqrt}[\text{pD1 pD1C6l0 pD4 pD4C6l0}] \text{Cos}[\theta_{10} - \theta_{40}] +$
 $\text{Sqrt}[\text{pD2 pD2C6l0 pD3 pD3C6l0}] \text{Cos}[\theta_{20} - \theta_{30}] + \text{Sqrt}[\text{pD2 pD2C6l0 pD4 pD4C6l0}]$
 $\text{Cos}[\theta_{20} - \theta_{40}] + \text{Sqrt}[\text{pD3 pD3C6l0 pD4 pD4C6l0}] \text{Cos}[\theta_{30} - \theta_{40}];$

In[1572]:= $\text{interfC6l1} = \text{Sqrt}[\text{pD0 pD0C6l1 pD1 pD1C6l1}] \text{Cos}[\theta_{01} - \theta_{11}] +$
 $\text{Sqrt}[\text{pD0 pD0C6l1 pD2 pD2C6l1}] \text{Cos}[\theta_{01} - \theta_{21}] + \text{Sqrt}[\text{pD0 pD0C6l1 pD3 pD3C6l1}]$
 $\text{Cos}[\theta_{01} - \theta_{31}] + \text{Sqrt}[\text{pD0 pD0C6l1 pD4 pD4C6l1}] \text{Cos}[\theta_{01} - \theta_{41}] +$
 $\text{Sqrt}[\text{pD1 pD1C6l1 pD2 pD2C6l1}] \text{Cos}[\theta_{11} - \theta_{21}] + \text{Sqrt}[\text{pD1 pD1C6l1 pD3 pD3C6l1}]$
 $\text{Cos}[\theta_{11} - \theta_{31}] + \text{Sqrt}[\text{pD1 pD1C6l1 pD4 pD4C6l1}] \text{Cos}[\theta_{11} - \theta_{41}] +$
 $\text{Sqrt}[\text{pD2 pD2C6l1 pD3 pD3C6l1}] \text{Cos}[\theta_{21} - \theta_{31}] + \text{Sqrt}[\text{pD2 pD2C6l1 pD4 pD4C6l1}]$
 $\text{Cos}[\theta_{21} - \theta_{41}] + \text{Sqrt}[\text{pD3 pD3C6l1 pD4 pD4C6l1}] \text{Cos}[\theta_{31} - \theta_{41}];$

In[1573]:= $\text{interfC6l2} = \text{Sqrt}[\text{pD0 pD0C6l2 pD1 pD1C6l2}] \text{Cos}[\theta_{02} - \theta_{12}] +$
 $\text{Sqrt}[\text{pD0 pD0C6l2 pD2 pD2C6l2}] \text{Cos}[\theta_{02} - \theta_{22}] + \text{Sqrt}[\text{pD0 pD0C6l2 pD3 pD3C6l2}]$
 $\text{Cos}[\theta_{02} - \theta_{32}] + \text{Sqrt}[\text{pD0 pD0C6l2 pD4 pD4C6l2}] \text{Cos}[\theta_{02} - \theta_{42}] +$
 $\text{Sqrt}[\text{pD1 pD1C6l2 pD2 pD2C6l2}] \text{Cos}[\theta_{12} - \theta_{22}] + \text{Sqrt}[\text{pD1 pD1C6l2 pD3 pD3C6l2}]$
 $\text{Cos}[\theta_{12} - \theta_{32}] + \text{Sqrt}[\text{pD1 pD1C6l2 pD4 pD4C6l2}] \text{Cos}[\theta_{12} - \theta_{42}] +$
 $\text{Sqrt}[\text{pD2 pD2C6l2 pD3 pD3C6l2}] \text{Cos}[\theta_{22} - \theta_{32}] + \text{Sqrt}[\text{pD2 pD2C6l2 pD4 pD4C6l2}]$
 $\text{Cos}[\theta_{22} - \theta_{42}] + \text{Sqrt}[\text{pD3 pD3C6l2 pD4 pD4C6l2}] \text{Cos}[\theta_{32} - \theta_{42}];$

In[1574]:= $\text{interfC6l3} = \text{Sqrt}[\text{pD0 pD0C6l3 pD1 pD1C6l3}] \text{Cos}[\theta_{03} - \theta_{13}] +$
 $\text{Sqrt}[\text{pD0 pD0C6l3 pD2 pD2C6l3}] \text{Cos}[\theta_{03} - \theta_{23}] + \text{Sqrt}[\text{pD0 pD0C6l3 pD3 pD3C6l3}]$
 $\text{Cos}[\theta_{03} - \theta_{33}] + \text{Sqrt}[\text{pD0 pD0C6l3 pD4 pD4C6l3}] \text{Cos}[\theta_{03} - \theta_{43}] +$
 $\text{Sqrt}[\text{pD1 pD1C6l3 pD2 pD2C6l3}] \text{Cos}[\theta_{13} - \theta_{23}] + \text{Sqrt}[\text{pD1 pD1C6l3 pD3 pD3C6l3}]$
 $\text{Cos}[\theta_{13} - \theta_{33}] + \text{Sqrt}[\text{pD1 pD1C6l3 pD4 pD4C6l3}] \text{Cos}[\theta_{13} - \theta_{43}] +$
 $\text{Sqrt}[\text{pD2 pD2C6l3 pD3 pD3C6l3}] \text{Cos}[\theta_{23} - \theta_{33}] + \text{Sqrt}[\text{pD2 pD2C6l3 pD4 pD4C6l3}]$
 $\text{Cos}[\theta_{23} - \theta_{43}] + \text{Sqrt}[\text{pD3 pD3C6l3 pD4 pD4C6l3}] \text{Cos}[\theta_{33} - \theta_{43}];$

In[1575]:= $\text{qprC6l0} = \text{prC6l0} + 2 \text{interfC6l0};$

In[1576]:= $\text{qprC6l1} = \text{prC6l1} + 2 \text{interfC6l1};$

In[1577]:= $\text{qprC6l2} = \text{prC6l2} + 2 \text{interfC6l2};$

In[1578]:= $\text{qprC6l3} = \text{prC6l3} + 2 \text{interfC6l3};$

```

In[1594]:= qprC6l0Norm = FullSimplify[ $\frac{\text{qprC6l0}}{\text{qprC6l0} + \text{qprC6l1} + \text{qprC6l2} + \text{qprC6l3}}$ ];

In[1595]:= qprC6l1Norm = FullSimplify[ $\frac{\text{qprC6l1}}{\text{qprC6l0} + \text{qprC6l1} + \text{qprC6l2} + \text{qprC6l3}}$ ];

In[1596]:= qprC6l2Norm = FullSimplify[ $\frac{\text{qprC6l2}}{\text{qprC6l0} + \text{qprC6l1} + \text{qprC6l2} + \text{qprC6l3}}$ ];

In[1597]:= qprC6l3Norm = 1 - qprC6l2Norm - qprC6l1Norm - qprC6l0Norm;

In[1604]:= Clear[ $\theta_{00}, \theta_{10}, \theta_{20}, \theta_{30}, \theta_{40}, \theta_{01}, \theta_{11}, \theta_{21},$ 
 $\theta_{31}, \theta_{41}, \theta_{02}, \theta_{12}, \theta_{22}, \theta_{32}, \theta_{42}, \theta_{03}, \theta_{13}, \theta_{23}, \theta_{33}, \theta_{43}$ ];

In[ ]:=  $\theta_{20} = \pi;$ 
 $\theta_{31} = 0.1;$ 
 $\theta_{22} = \pi/2;$ 
 $\theta_{43} = \pi/2;$ 
 $\theta_{23} = \pi;$ 
 $\theta_{30} = \pi;$ 
 $\theta_{21} = \pi;$ 
 $\theta_{42} = \pi;$ 

In[1605]:= res = FindInstance[{qprC6l0Norm + qprC6l1Norm + qprC6l2Norm + qprC6l3Norm == 1},
{ $\theta_{00}, \theta_{10}, \theta_{20}, \theta_{30}, \theta_{40}, \theta_{01}, \theta_{11}, \theta_{21}, \theta_{31}, \theta_{41},$ 
 $\theta_{02}, \theta_{12}, \theta_{22}, \theta_{32}, \theta_{42}, \theta_{03}, \theta_{13}, \theta_{23}, \theta_{33}, \theta_{43}$ }, Reals]

Out[ ]:=  $\left\{ \left\{ \theta_{00} \rightarrow -\frac{12}{5}, \theta_{10} \rightarrow -\frac{1}{2}, \theta_{20} \rightarrow -\frac{9}{5}, \theta_{30} \rightarrow \frac{3}{5}, \theta_{40} \rightarrow -\frac{24}{5}, \theta_{01} \rightarrow -\frac{21}{5}, \theta_{11} \rightarrow \frac{11}{5}, \right. \right.$ 
 $\theta_{21} \rightarrow -\frac{3}{5}, \theta_{31} \rightarrow -\frac{6}{5}, \theta_{41} \rightarrow -\frac{14}{5}, \theta_{02} \rightarrow -\frac{19}{5}, \theta_{12} \rightarrow -\frac{14}{5}, \theta_{22} \rightarrow -\frac{41}{10}, \theta_{32} \rightarrow -\frac{3}{10},$ 
 $\left. \left. \theta_{42} \rightarrow -\frac{17}{10}, \theta_{03} \rightarrow \frac{18}{5}, \theta_{13} \rightarrow -\frac{37}{10}, \theta_{23} \rightarrow \frac{13}{5}, \theta_{33} \rightarrow -\frac{39}{10}, \theta_{43} \rightarrow -\frac{21}{10} \right\} \right\}$ 

In[ ]:= (* Params *)

```

```
In[1659]:=
 $\theta_{10} = \text{res}[[1]][[2]][[2]];$ 
 $\theta_{20} = \text{res}[[1]][[3]][[2]];$ 
 $\theta_{30} = \text{res}[[1]][[4]][[2]];$ 
 $\theta_{40} = \text{res}[[1]][[5]][[2]];$ 
 $\theta_{11} = \text{res}[[1]][[7]][[2]];$ 
 $\theta_{21} = \text{res}[[1]][[8]][[2]];$ 
 $\theta_{31} = \text{res}[[1]][[9]][[2]];$ 
 $\theta_{41} = \text{res}[[1]][[10]][[2]];$ 
 $\theta_{02} = \text{res}[[1]][[11]][[2]];$ 
 $\theta_{12} = \text{res}[[1]][[12]][[2]];$ 
 $\theta_{22} = \text{res}[[1]][[13]][[2]];$ 
 $\theta_{32} = \text{res}[[1]][[14]][[2]];$ 
 $\theta_{42} = \text{res}[[1]][[15]][[2]];$ 
 $\theta_{03} = \text{res}[[1]][[16]][[2]];$ 
 $\theta_{13} = \text{res}[[1]][[17]][[2]];$ 
 $\theta_{23} = \text{res}[[1]][[18]][[2]];$ 
 $\theta_{33} = \text{res}[[1]][[19]][[2]];$ 
 $\theta_{43} = \text{res}[[1]][[20]][[2]];$ 
```

```
In[ ]:=
```

```
In[ ]:= qprC6l0Norm = FullSimplify[ $\frac{\text{qprC6l0}}{\text{qprC6l0} + \text{qprC6l1} + \text{qprC6l2} + \text{qprC6l3}}$ ];
```

```
In[ ]:= qprC6l0Norm = (20.625876849732148` +
  2.110074299383087` Cos[ $\theta_{00}$ ] + 12.136563618945598` Sin[ $\theta_{00}$ ]) /
  ((91.03182491156085`) + 2.110074299383087` Cos[ $\theta_{00}$ ] - 8.647382932576596`
  Cos[ $\theta_{01}$ ] + 12.136563618945598` Sin[ $\theta_{00}$ ] - 0.11828274209686551` Sin[ $\theta_{01}$ ]);
```

```
In[ ]:= qprC6l1Norm = FullSimplify[ $\frac{\text{qprC6l1}}{\text{qprC6l0} + \text{qprC6l1} + \text{qprC6l2} + \text{qprC6l3}}$ ];
```

```
In[ ]:= qprC6l1Norm = (1.4297233187681255` -
  1.2331596774696156` Cos[ $\theta_{01}$ ] - 0.01686770543546845` Sin[ $\theta_{01}$ ]) /
  ((12.981589542486294`) + 0.3009070562449182` Cos[ $\theta_{00}$ ] - 1.2331596774696143`
  Cos[ $\theta_{01}$ ] + 1.7307341417189919` Sin[ $\theta_{00}$ ] - 0.01686770543546756` Sin[ $\theta_{01}$ ]);
```

```
In[ ]:= qprC6l2Norm = FullSimplify[ $\frac{\text{qprC6l2}}{\text{qprC6l0} + \text{qprC6l1} + \text{qprC6l2} + \text{qprC6l3}}$ ];
```

```
In[ ]:= qprC6l2Norm = (21.775708576757673` - 6.3792965325476665) /
  ((43.141525840192166`) + 1.` Cos[ $\theta_{00}$ ] - 4.098141442272811` Cos[ $\theta_{01}$ ] +
  5.7517233504497485` Sin[ $\theta_{00}$ ] - 0.056056197704245365` Sin[ $\theta_{01}$ ]);
```

```
In[ ]:= qprC6l3Norm = 1 - qprC6l2Norm - qprC6l1Norm - qprC6l0Norm;
```

```
In[ ]:= (* Updated probabilities *)
```

```
In[ ]:= {qprC6l0Norm, qprC6l1Norm, qprC6l2Norm, qprC6l3Norm}
```

```
Out[ ]:= {
  
$$\frac{20.6259 + 2.11007 \cos[\theta_{00}] + 12.1366 \sin[\theta_{00}]}{91.0318 + 2.11007 \cos[\theta_{00}] - 8.64738 \cos[\theta_{01}] + 12.1366 \sin[\theta_{00}] - 0.118283 \sin[\theta_{01}]},$$

  
$$\frac{(1.42972 - 1.23316 \cos[\theta_{01}] - 0.0168677 \sin[\theta_{01}])}{(12.9816 + 0.300907 \cos[\theta_{00}] - 1.23316 \cos[\theta_{01}] + 1.73073 \sin[\theta_{00}] - 0.0168677 \sin[\theta_{01}])},$$

  
$$\frac{15.3964}{43.1415 + 1. \cos[\theta_{00}] - 4.09814 \cos[\theta_{01}] + 5.75172 \sin[\theta_{00}] - 0.0560562 \sin[\theta_{01}]},$$

  
$$1 - \frac{(20.6259 + 2.11007 \cos[\theta_{00}] + 12.1366 \sin[\theta_{00}])}{(91.0318 + 2.11007 \cos[\theta_{00}] - 8.64738 \cos[\theta_{01}] + 12.1366 \sin[\theta_{00}] - 0.118283 \sin[\theta_{01}])} -$$

  
$$\frac{43.1415 + 1. \cos[\theta_{00}] - 4.09814 \cos[\theta_{01}] + 5.75172 \sin[\theta_{00}] - 0.0560562 \sin[\theta_{01}]}{(1.42972 - 1.23316 \cos[\theta_{01}] - 0.0168677 \sin[\theta_{01}])} \bigg/ \frac{(12.9816 + 0.300907 \cos[\theta_{00}] - 1.23316 \cos[\theta_{01}] + 1.73073 \sin[\theta_{00}] - 0.0168677 \sin[\theta_{01}])}{15.3964}$$

}
```

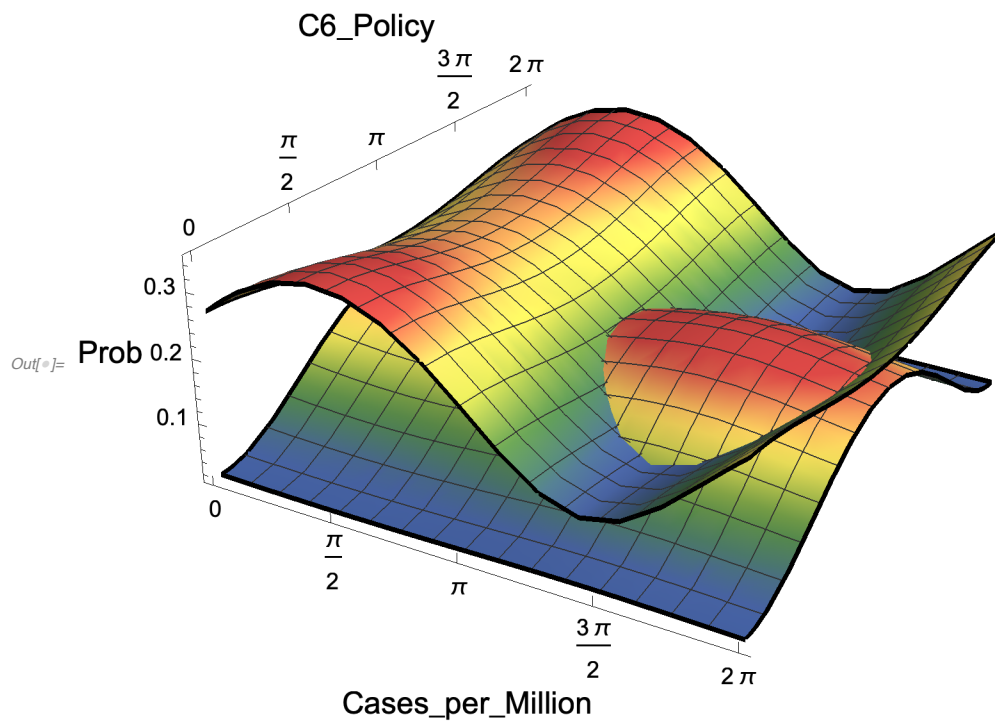
```
In[1767]:= p0 = Plot3D[qprC6l0Norm, {θ00, 0, 2 π},
  {θ01, 0, 2 π}, ColorFunction → (ColorData["DarkRainbow"][#3] &),
  AxesLabel → {Style[type, 16], Style[policy, 16], Style["Prob", 16]},
  BoundaryStyle → Thick, Boxed → False,
  Ticks → {{0, Pi/2, Pi, 3 Pi/2, 2 Pi}, {0, Pi/2, Pi, 3 Pi/2, 2 Pi}}, Automatic},
  TicksStyle → Directive[Black, 12]];
```

```
In[1768]:= p1 = Plot3D[qprC6l1Norm, {θ00, 0, 2 π},
  {θ01, 0, 2 π}, ColorFunction → (ColorData["DarkRainbow"][#3] &),
  AxesLabel → {Style[type, 16], Style[policy, 16], Style["Prob", 16]},
  BoundaryStyle → Thick, Boxed → False,
  Ticks → {{0, Pi/2, Pi, 3 Pi/2, 2 Pi}, {0, Pi/2, Pi, 3 Pi/2, 2 Pi}}, Automatic},
  TicksStyle → Directive[Black, 12]];
```

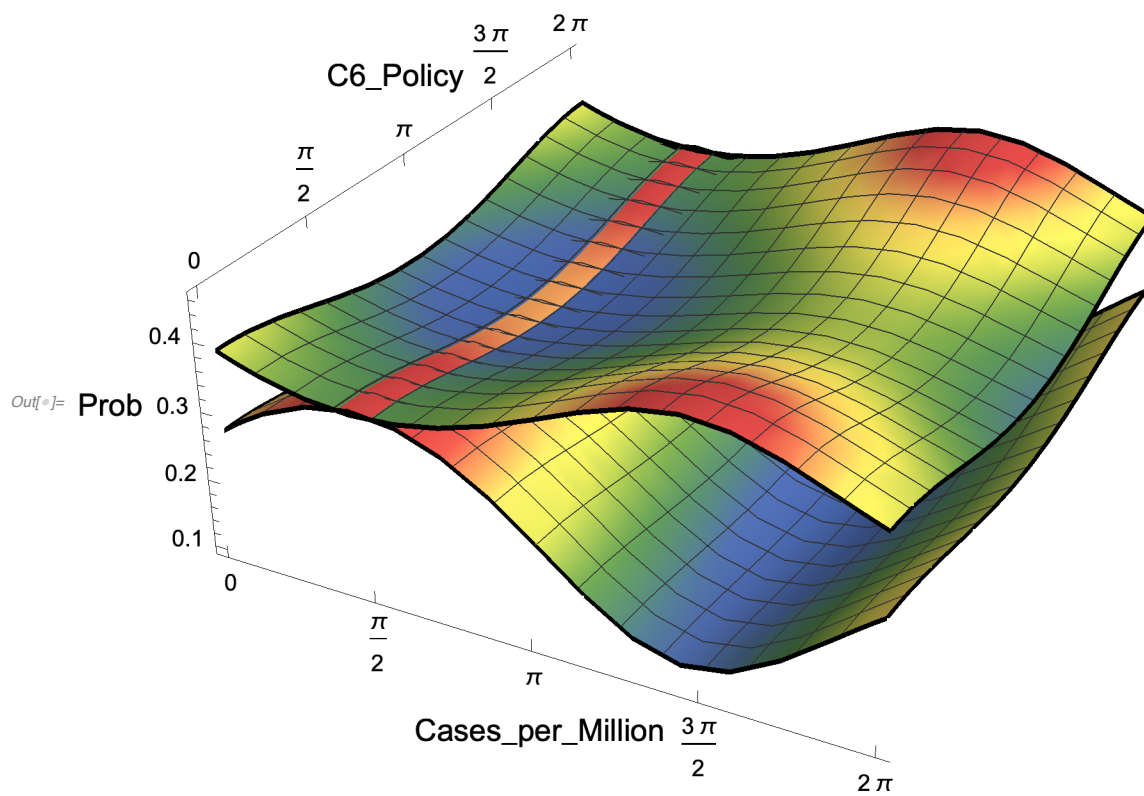
```
In[1769]:= p2 = Plot3D[qprC6l2Norm, {θ00, 0, 2 π},
  {θ01, 0, 2 π}, ColorFunction → (ColorData["DarkRainbow"][#3] &),
  AxesLabel → {Style[type, 16], Style[policy, 16], Style["Prob", 16]},
  BoundaryStyle → Thick, Boxed → False,
  Ticks → {{0, Pi/2, Pi, 3 Pi/2, 2 Pi}, {0, Pi/2, Pi, 3 Pi/2, 2 Pi}}, Automatic},
  TicksStyle → Directive[Black, 12]];
```

```
In[1770]:= p3 = Plot3D[qprC6l3Norm, {θ00, 0, 2 π},
  {θ01, 0, 2 π}, ColorFunction → (ColorData["DarkRainbow"][#3] &),
  AxesLabel → {Style[type, 16], Style[policy, 16], Style["Prob", 16]},
  BoundaryStyle → Thick, Boxed → False,
  Ticks → {{0, Pi/2, Pi, 3 Pi/2, 2 Pi}, {0, Pi/2, Pi, 3 Pi/2, 2 Pi}}, Automatic},
  TicksStyle → Directive[Black, 12]];
```

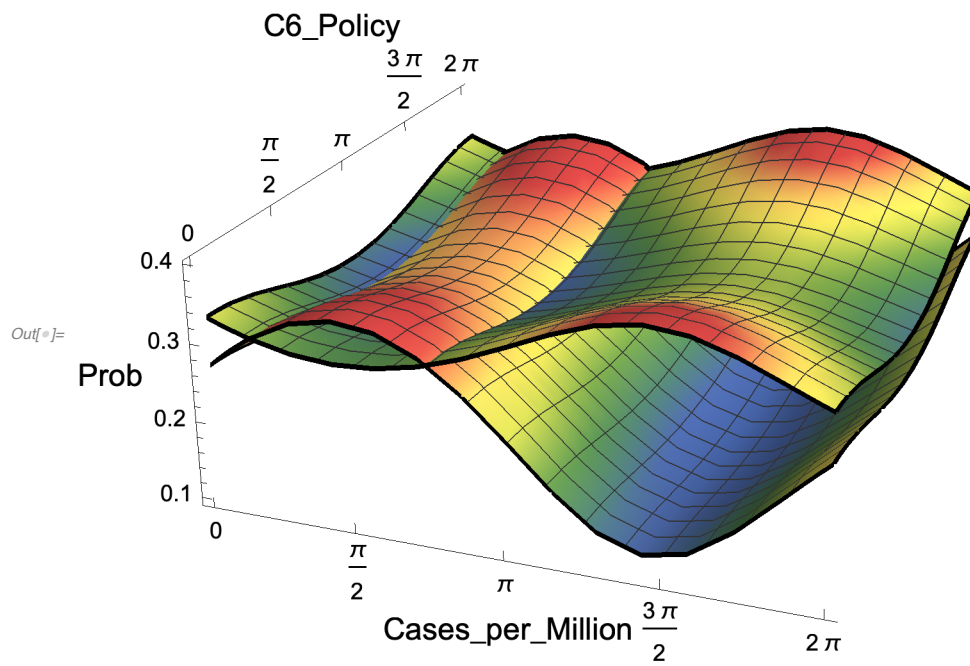
In[1771]:= Show[p0, p1]



In[1772]:= Show[p0, p2]

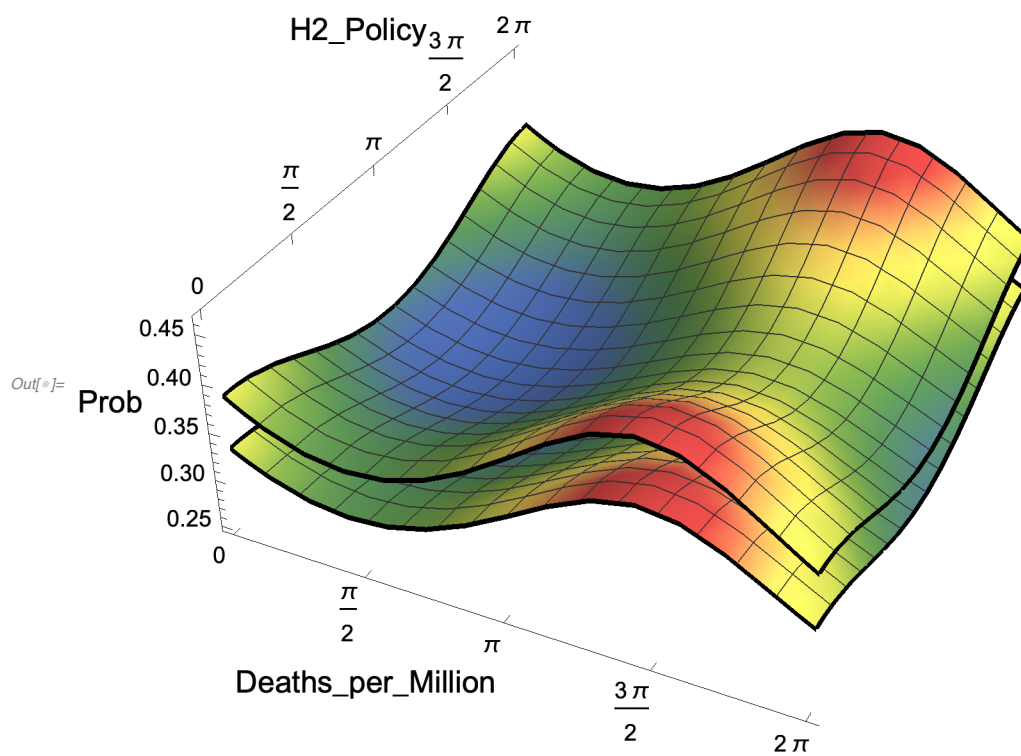


In[1773]:= Show[p0, p3]



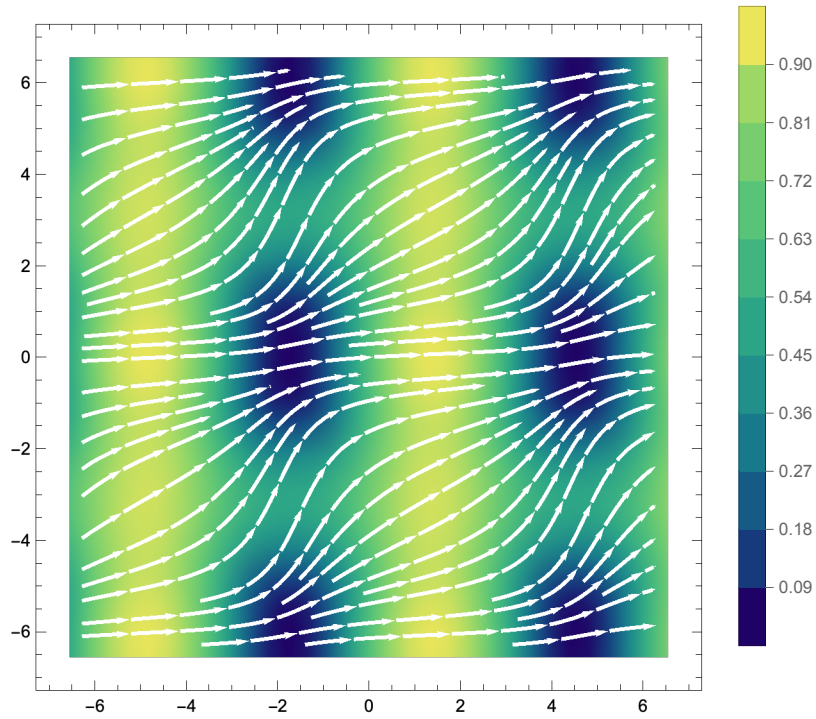
In[1761]:= Show[p1, p2]

In[1763]:= Show[p2, p3]

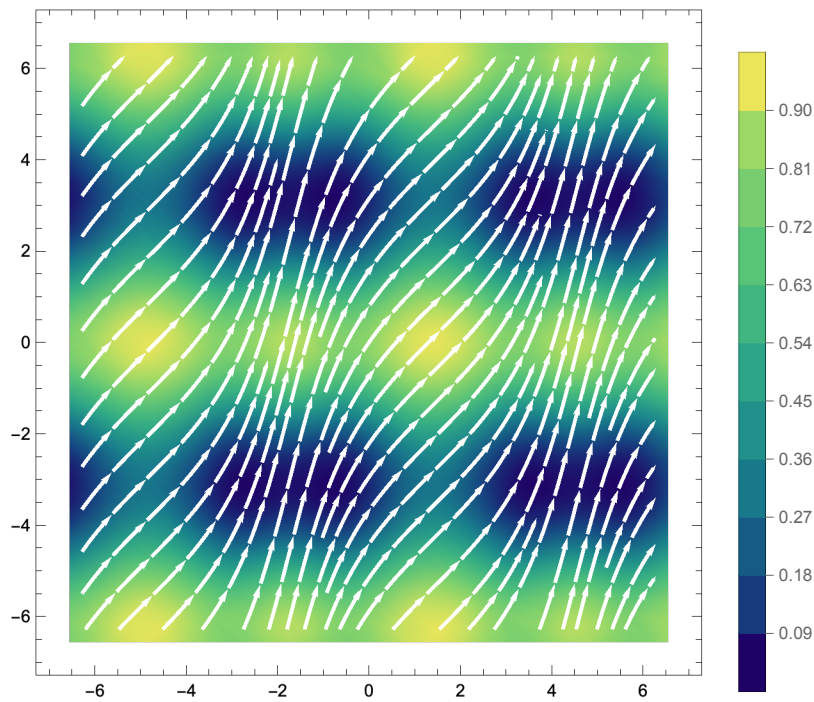


In[]:=

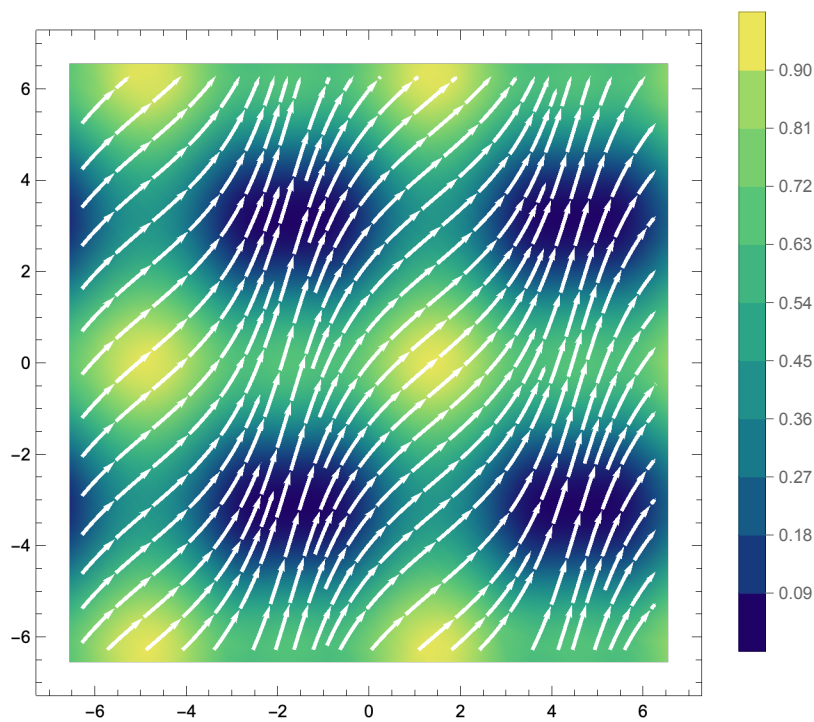
```
In[1758]:= fig = StreamDensityPlot[{qprC6l0Norm, qprC6l1Norm},
  {000, -2  $\pi$ , 2  $\pi$ }, {001, -2  $\pi$ , 2  $\pi$ }, ColorFunction -> "BlueGreenYellow",
  PlotLegends -> BarLegend[{"BlueGreenYellow", {0, 1}}, 10],
  AxesLabel -> Automatic, StreamStyle -> {White, Thick}]
```



```
In[1759]:= fig = StreamDensityPlot[{qprC6l0Norm, qprC6l2Norm},
  {000, -2  $\pi$ , 2  $\pi$ }, {001, -2  $\pi$ , 2  $\pi$ }, ColorFunction -> "BlueGreenYellow",
  PlotLegends -> BarLegend[{"BlueGreenYellow", {0, 1}}, 10],
  AxesLabel -> Automatic, StreamStyle -> {White, Thick}]
```

```
In[1760]:= fig = StreamDensityPlot[{qprC6l0Norm, qprC6l3Norm},
  {000, -2  $\pi$ , 2  $\pi$ }, {001, -2  $\pi$ , 2  $\pi$ }, ColorFunction -> "BlueGreenYellow",
  PlotLegends -> BarLegend[{"BlueGreenYellow", {0, 1}}, 10],
  AxesLabel -> Automatic, StreamStyle -> {White, Thick}]
```



```

In[1764]:= fig = StreamDensityPlot[{qprC6l2Norm, qprC6l3Norm},
  {000, -2  $\pi$ , 2  $\pi$ }, {001, -2  $\pi$ , 2  $\pi$ }, ColorFunction -> "BlueGreenYellow",
  PlotLegends -> BarLegend[{"BlueGreenYellow", {0, 1}}, 10],
  AxesLabel -> Automatic, StreamStyle -> {White, Thick}]

```

