

Differential Equations

A differential equation is a mathematical equation that relates a function to its derivatives.

$$\frac{1}{n^2}\frac{d}{dn}\left(\eta^2\frac{d\varphi}{dn}\right) + (\varphi^2 - C)^{3/2} = 0$$

$$\frac{\mathrm{d}[\mathrm{H}::]}{\mathrm{d}t}\bigg|_{\mathrm{form}} = \alpha(T) \, v_{\mathrm{th}} \, \langle n\sigma_{\mathrm{gr}} \rangle \, [\mathrm{H}] \, \exp\left(-\frac{T_1}{T}\right) \left(1 - \frac{[\mathrm{H}::]}{[\mathrm{H}::]_{\mathrm{max}}}\right)$$

Chandrasekhar White Dwarf equation

Eley-Rideal Mechanism

$$\frac{d}{dt} \{X\} = \{A\} + \{X\}^2 \{Y\} - \{B\} \{X\} - \{X\} \}$$

$$\frac{d}{dt} \{Y\} = \{B\} \{X\} - \{X\}^2 \{Y\} \}$$

$$I = C_m rac{{
m d} V_m}{{
m d} t} + g_K (V_m - V_K) + g_{Na} (V_m - V_{Na}) + g_l (V_m - V_l)$$

Autocatalytic Reactions

$$\frac{\mathrm{d}B}{\mathrm{d}t} = -\alpha A$$
 $\frac{\mathrm{d}B}{\mathrm{d}t} = -\alpha A$

 $rac{\partial V}{\partial t} + rac{1}{2}\sigma^2 S^2 rac{\partial^2 V}{\partial S^2} + r S rac{\partial V}{\partial S} - r V = 0$

Hodgkin-Huxley model

Lanchester's laws

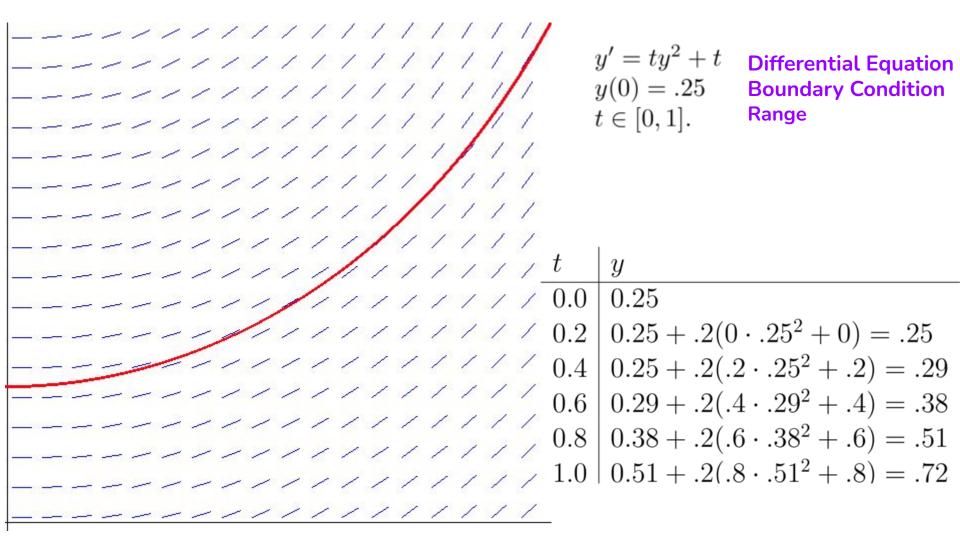
Black-Scholes equation

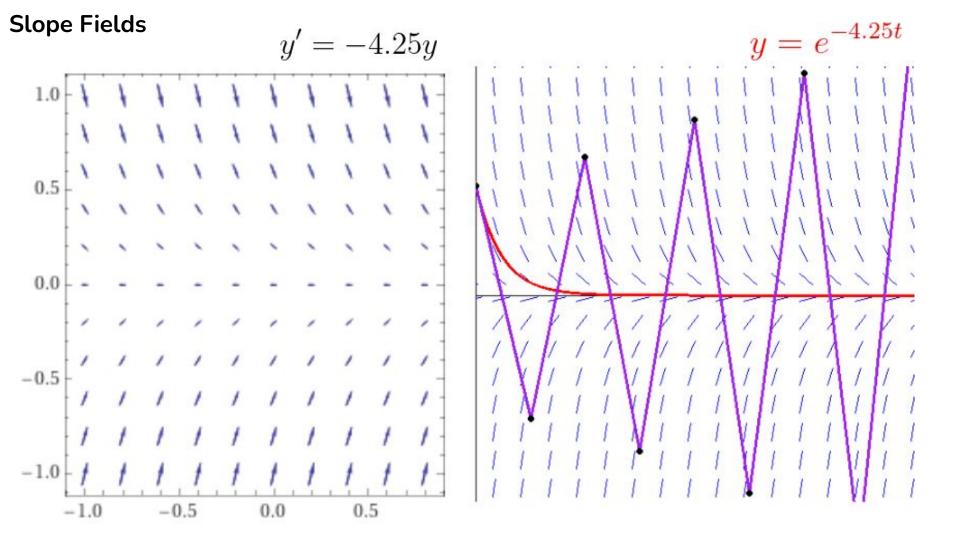
Ordinary Differential Equation: Euler Method

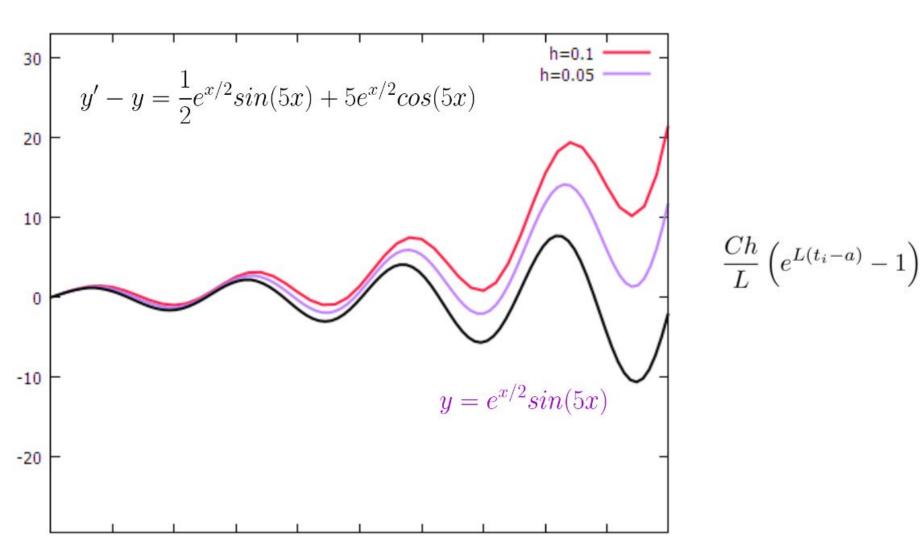
$$y(x+h) \approx y(x) + hy'(x) + \frac{h^2y''(x)}{2!} + \frac{h^3y'''(x)}{3!} + \cdots$$
$$y(x+h) \approx y(x) + hy'(x)$$

The integral can be thought of as the differential equation

$$y = \int f(x)dx$$
 $y' = f(x)$ $y' \equiv \frac{dy}{dx}$

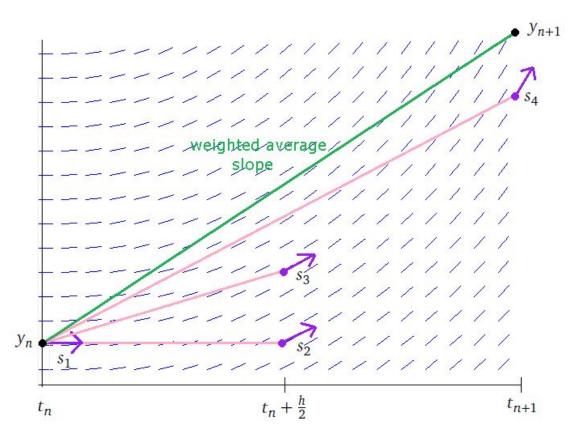






Ordinary Differential Equation: Runge Kutta-4

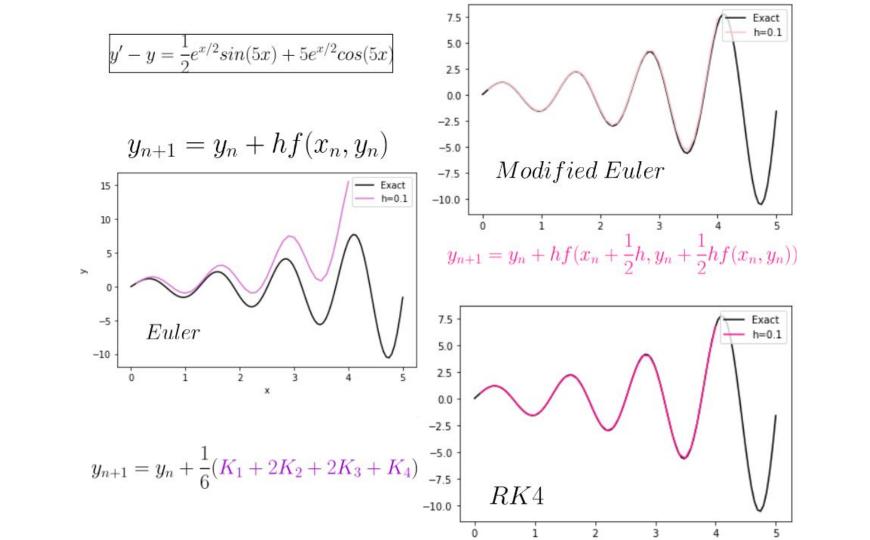
$$y_{n+1} = y_n + \frac{1}{6}(K_1 + 2K_2 + 2K_3 + K_4)$$



The RK4 method builds off of the RK2 methods (trapezoid, midpoint, etc.) by using four slopes instead of two.

- s_1 Euler's slope at the left endpoint
- s₂ Slope at midpoint from following Euler's slope
- s₃ Improved slope at midpoint,
 from following s₂ instead of s₁
- s₄ Slope at right endpoint, from following s₃

The new y_{n+1} is computed as a weighted average those four slopes.



Slaying the Dragon: Stiff differential equations

$$y' = -50(y - cos(t))$$

= $-50y + 50cos(t) = 50(cos(t) - y)$

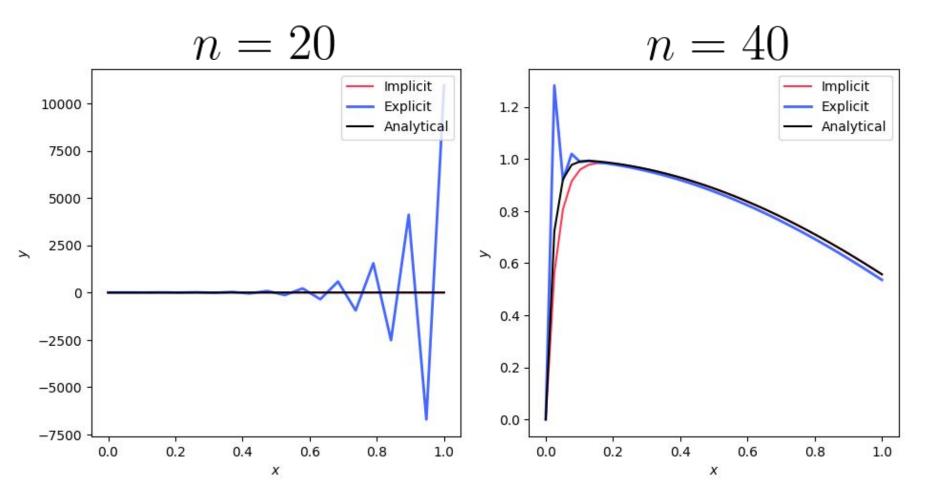
y(i + 1) = y(i) + 50[cos(t(i)) - y(i)]dt

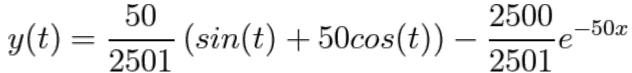
y(i+1) = y(i) + 50[cos(t(i+1)) - y(i+1)]dt

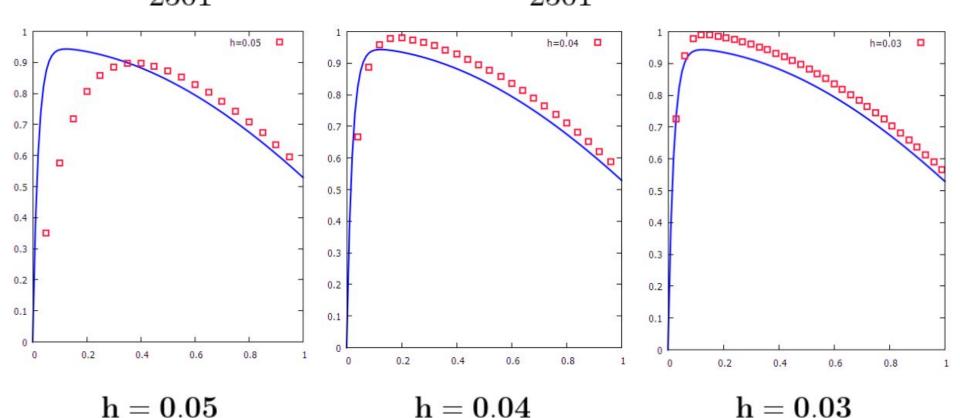
Explicit

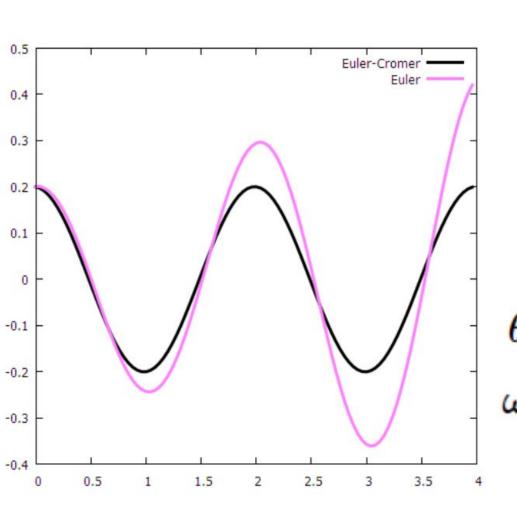
Implicit

$$y(i+1) = \frac{[y(i) + 50\cos(t(i+1))]dt}{1 + 50dt}$$









Simple Pendulum

$$egin{aligned} heta' &= \omega \ \omega' &= -rac{g}{L} heta \end{aligned}$$

$$egin{aligned} heta_k &= heta_{k-1} + \omega_{k-1} \delta t \ \omega_k &= \omega_{k-1} - rac{g}{L} \sin heta_{k-1} \delta t \end{aligned}$$

Equations of Stellar Structure

$$\frac{\mathrm{d}m(r)}{\mathrm{d}r} = 4\pi r^2 \rho(r). \qquad \qquad \rho = \frac{\overline{m}}{k} \frac{P}{T}$$

$$\rho = \frac{n}{k} \frac{1}{T}$$

mass continuity

$$\frac{\mathrm{d}P(r)}{\mathrm{d}r} = -\frac{G\,m(r)\,\rho(r)}{r^2}$$

Euler Method

hydrostatic equilibrium

$$\frac{\mathrm{d}L(r)}{\mathrm{d}r} = 4\pi r^2 \, \varepsilon(r)$$

energy generation

r(i+1) = r(i) + h;

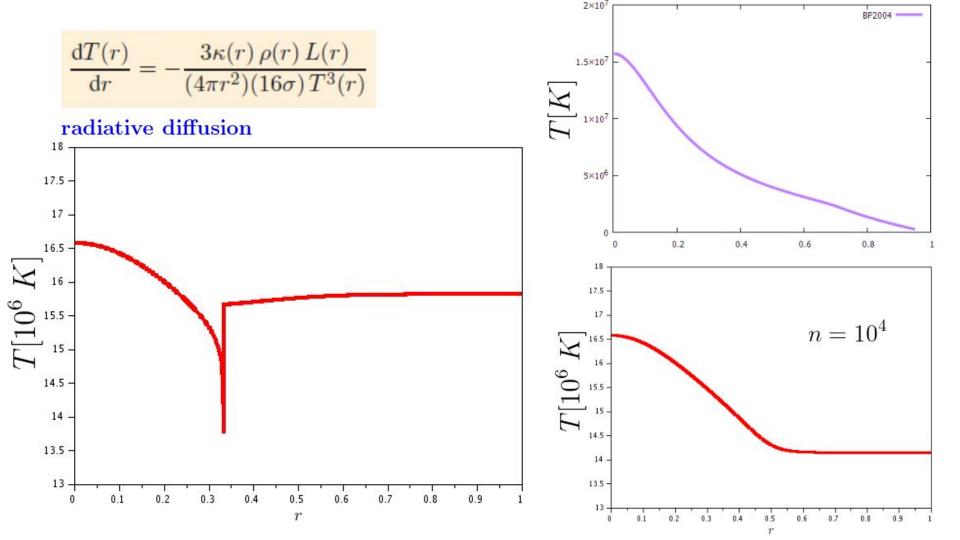
$$T(i+1) = T(i) - h*3*opa(i)*rho(i)*L(i)/(64*pi*sig*r(i)^2*T(i)^3);$$

 $L(i+1) = L(i) + h*4*pi*r(i)^2*rho(i)*con*T(i)^4;$

$$\frac{\mathrm{d}T(r)}{\mathrm{d}r} = -\frac{3\kappa(r)\,\rho(r)\,L(r)}{(4\pi r^2)(16\sigma)\,T^3(r)}$$

$$\frac{dT(r)}{dr} = -\frac{3\kappa(r)\rho(r)L(r)}{(4\pi r^2)(16\sigma)T^3(r)}$$

radiative diffusion



Partial Differential Equation: Heat Equation

$$abla^2 f(x,y) pprox rac{f(x-h,y)+f(x+h,y)+f(x,y-h)+f(x,y+h)-4f(x,y)}{h^2}.$$

 $\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial x^2} = 0 \qquad T_{i,j} = \frac{1}{4} \left(T_{i+1,j} + T_{i-1,j} + T_{i,j+1} + T_{i,j-1} \right)$

