

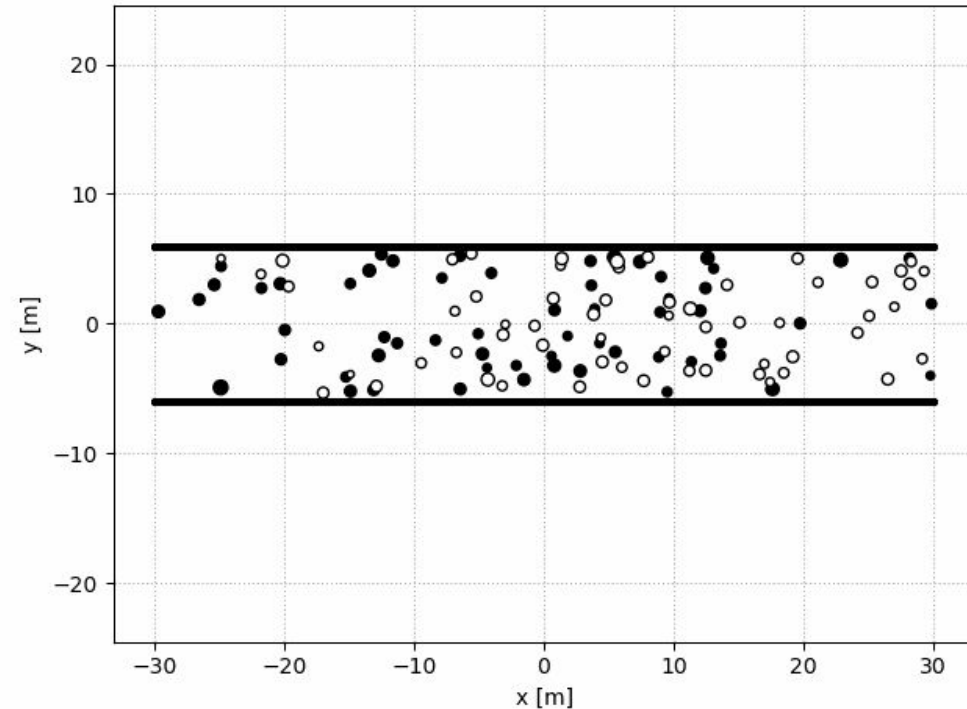
BIDIRECTIONAL CROWD FLOWS WITH INTRODUCTION OF OBSTACLES

Caterina Buranelli, Robbert van Koesveld, Marija Puljić & Iris Reitsma

Bidirectional crowd flow



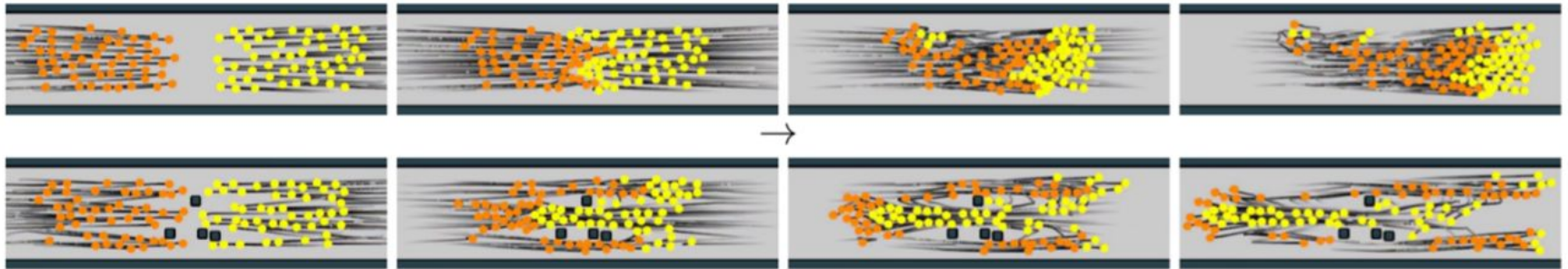
The social force model for pedestrian dynamics



- By Helbing & Molnár (1995)
- Motion of pedestrians can be described by “social forces”
- Focus on the formation of lanes of pedestrians with the same walking direction
- Bigger circle diameters mean higher velocity

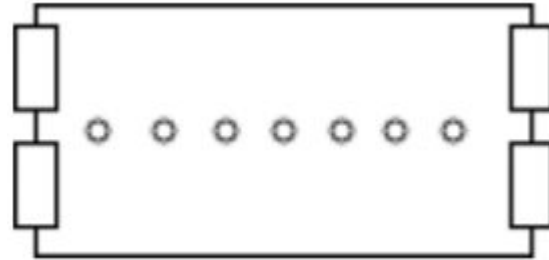
Environment optimization for crowd evacuation (2015)

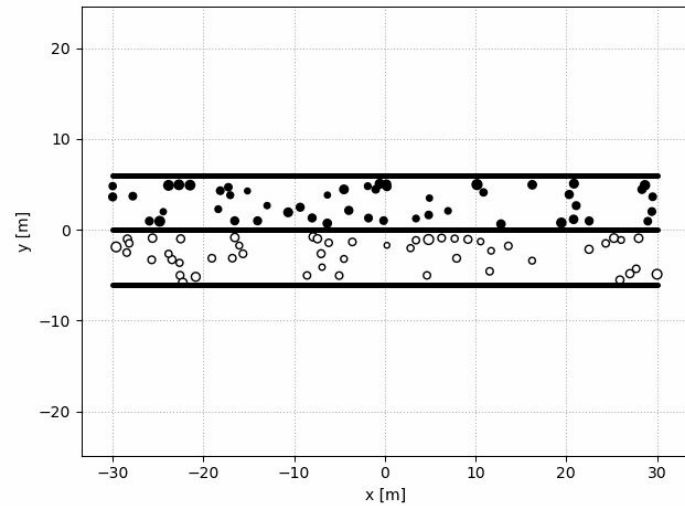
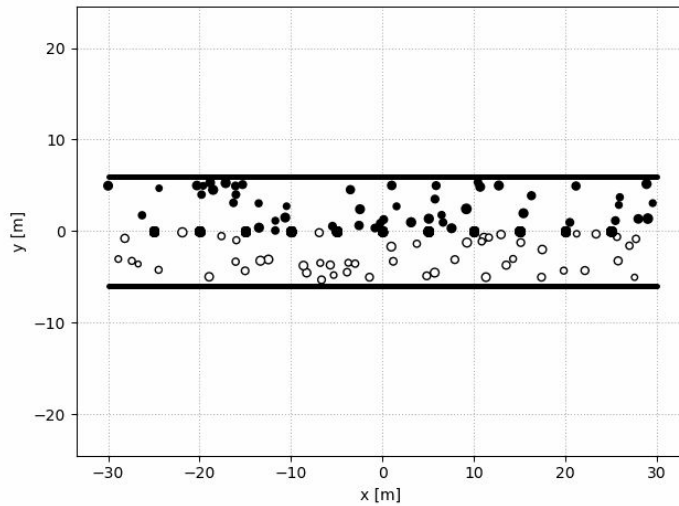
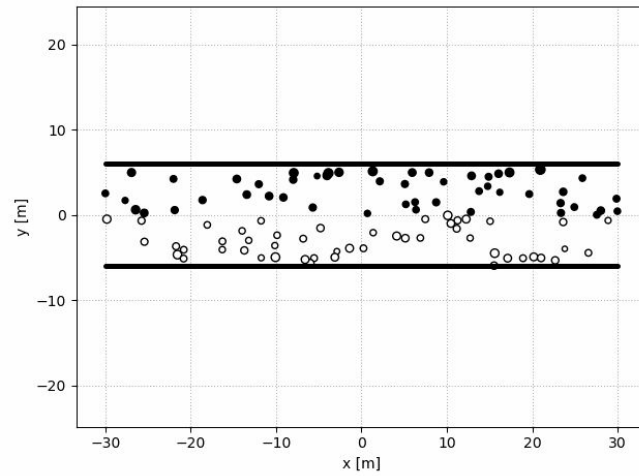
- strategically placed pillars can increase the throughput



The study of the influence of obstacles on crowd dynamics (2017)

- A straight line or column barrier increases average velocity of agents



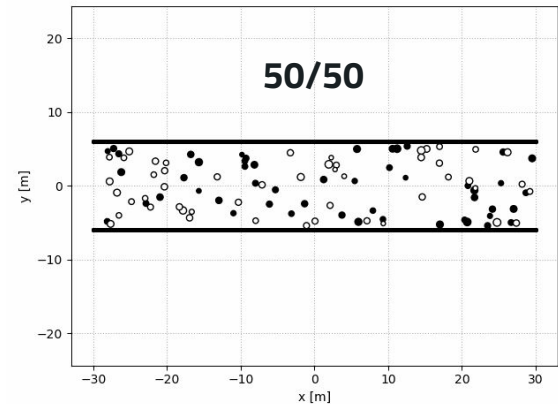
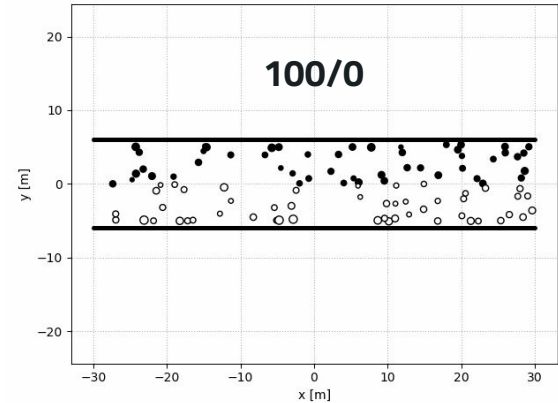


Research question

- ① Which obstacles in a corridor increase the average velocity of a bidirectional crowd flow?
- ② Is the result robust for different number of agents, N ?
- ③ Does the result change for different parameter settings?

Model settings and assumptions

- Corridor with bidirectional flow with different obstacles
- If agent exits corridor, new agent enters on other side
- Vary distribution of initial positions: 100/0, 80/20, 50/50
- 30 runs for 40 to 200 agents
- Measure the average velocity of agents



SOME FORMULAS THAT REGULATE THE MODEL

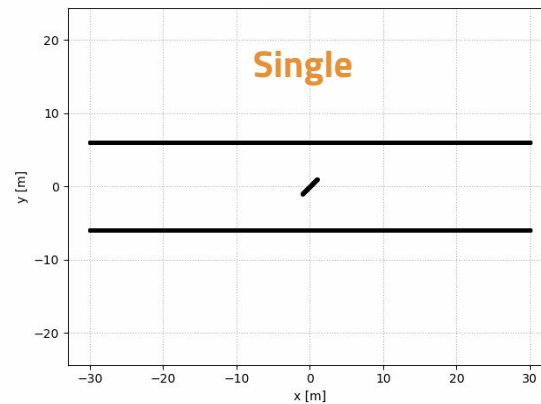
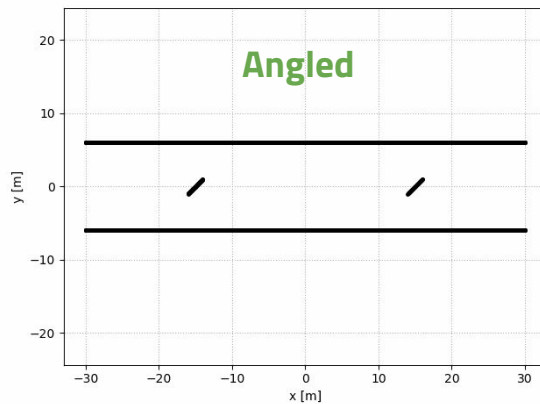
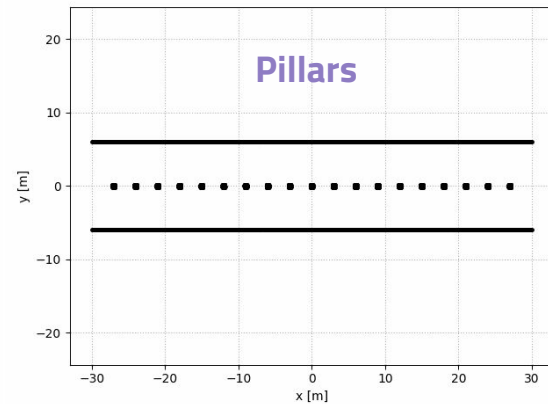
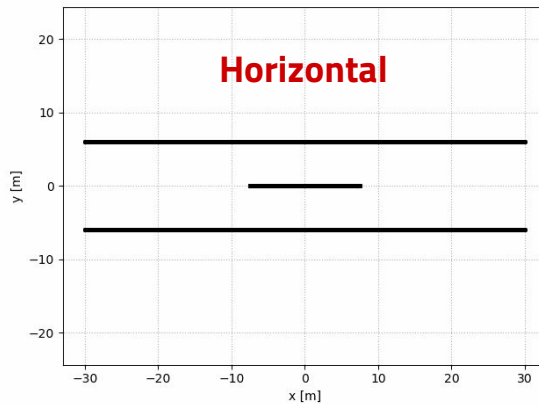
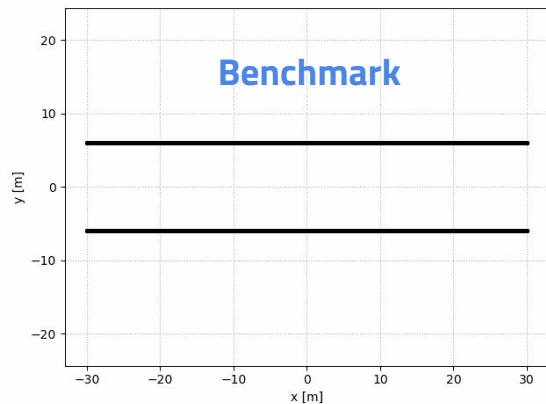
Desired direction $\vec{e}_\alpha(t) := \frac{\vec{r}_\alpha^k - \vec{r}_\alpha(t)}{\|\vec{r}_\alpha^k - \vec{r}_\alpha(t)\|}$

Acceleration term $\vec{F}_\alpha^0(\vec{v}_\alpha, v_\alpha^0 \vec{e}_\alpha) := \frac{1}{\tau_\alpha} (v_\alpha^0 \vec{e}_\alpha - \vec{v}_\alpha)$

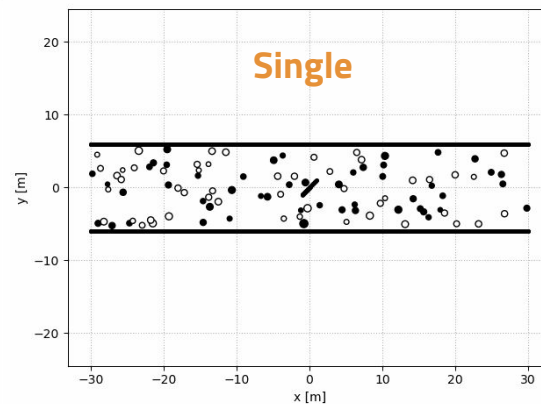
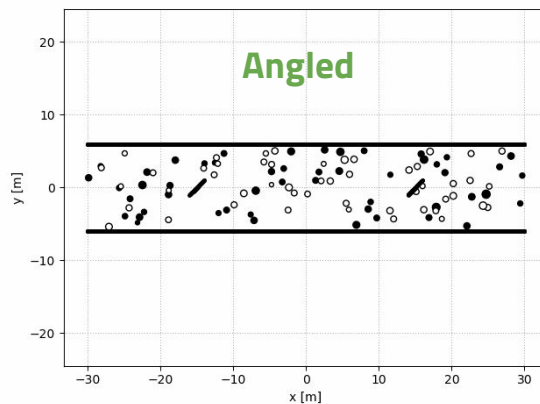
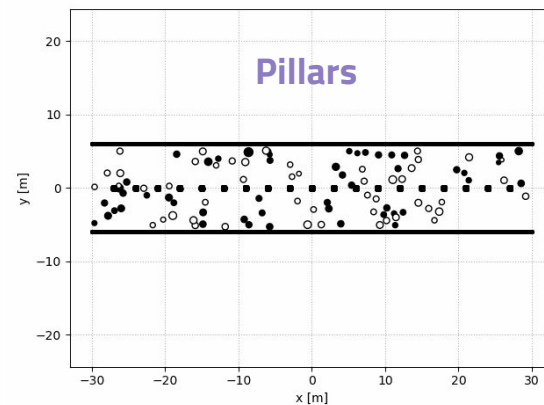
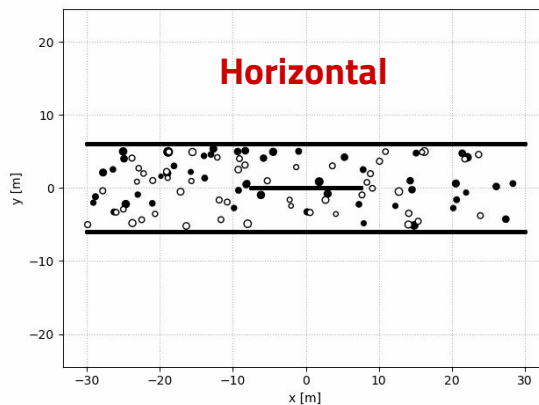
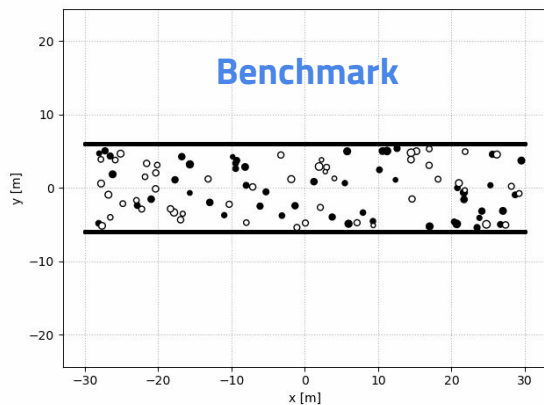
Pedestrians repulsive effect $\vec{f}_{\alpha\beta}(\vec{r}_{\alpha\beta}) := -\nabla_{\vec{r}_{\alpha\beta}} V_{\alpha\beta} [b(\vec{r}_{\alpha\beta})]$

Border/obstacle repulsive effect $\vec{F}_{\alpha B}(\vec{r}_{\alpha B}) := -\nabla_{\vec{r}_{\alpha B}} U_{\alpha B} (\|\vec{r}_{\alpha B}\|)$

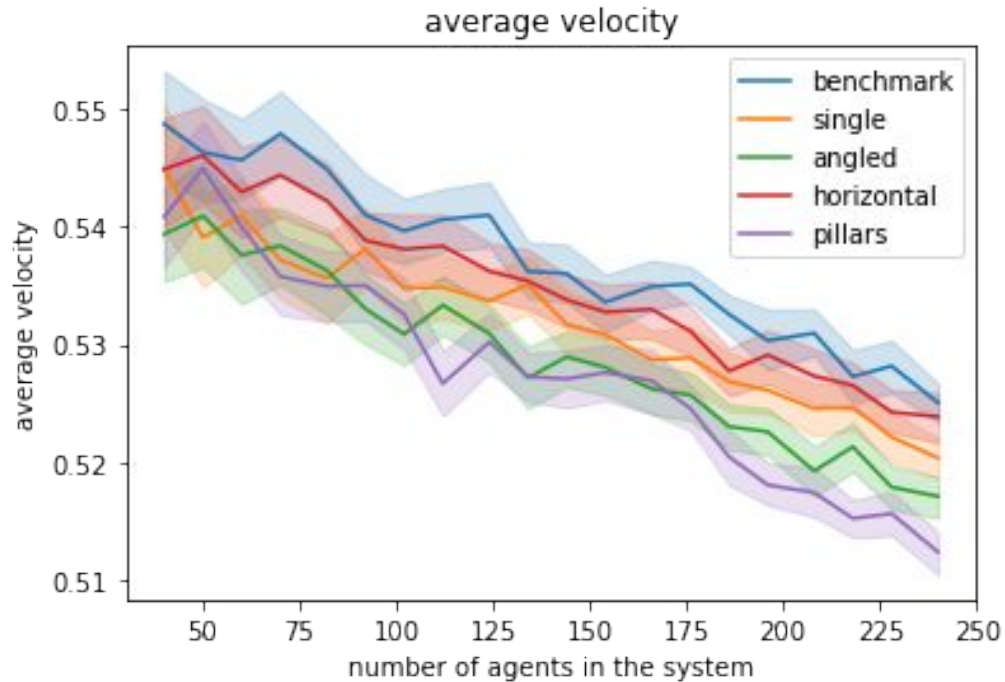
Obstacle modes



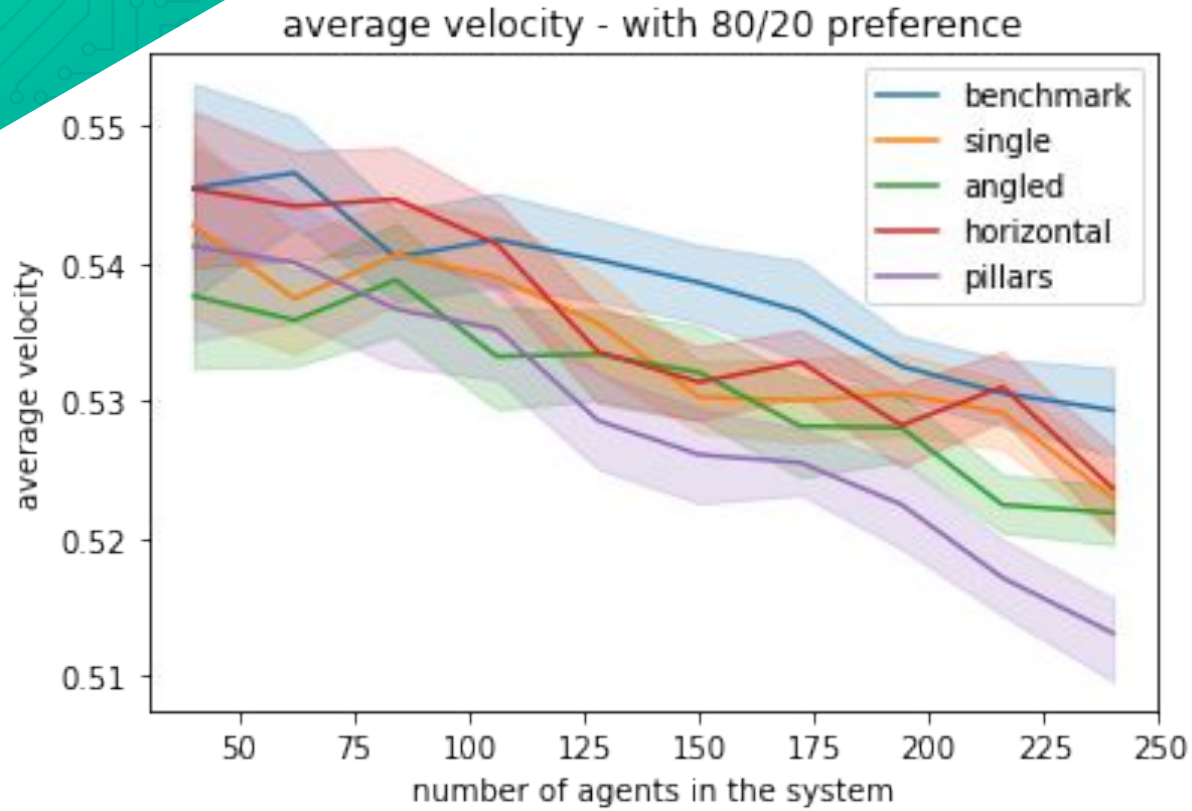
Obstacle modes with animation



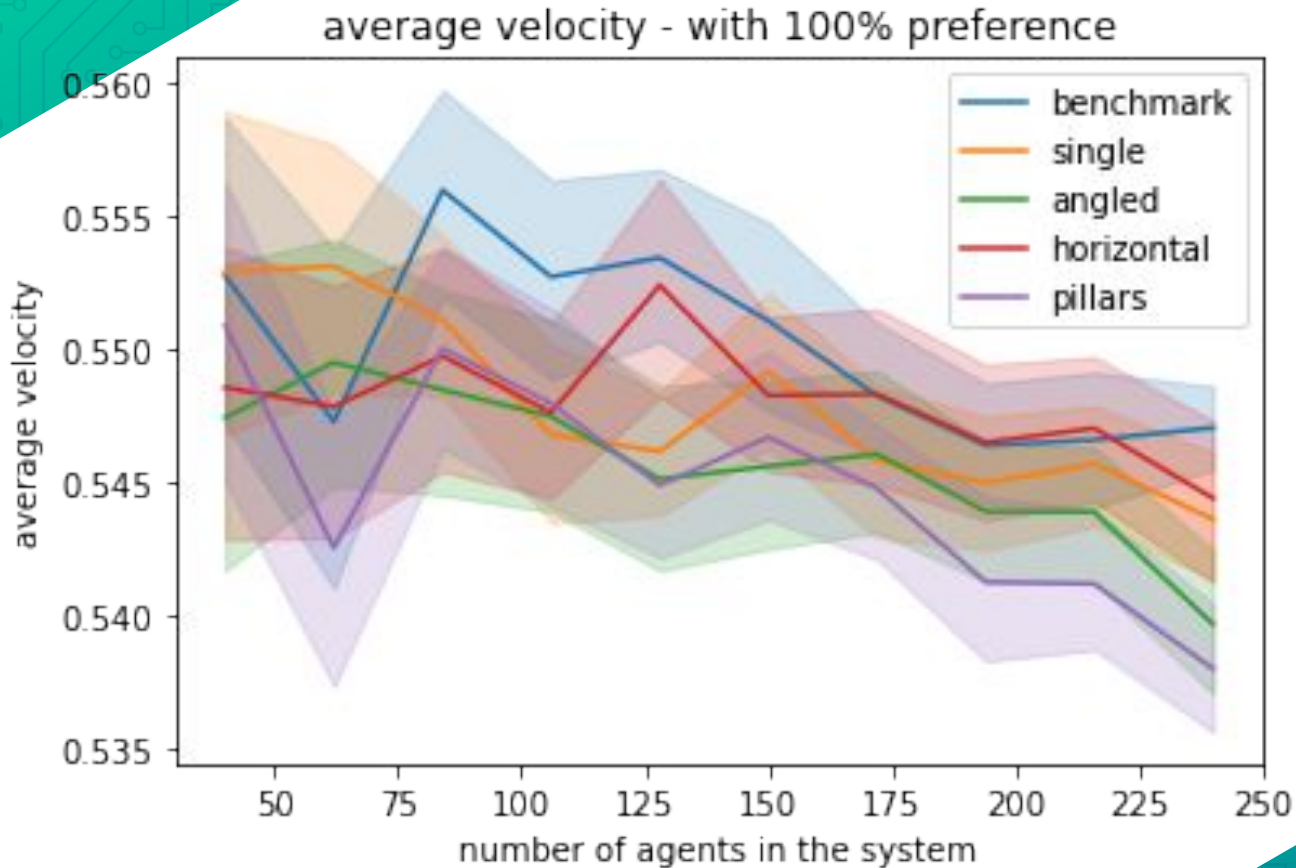
Results for 50/50



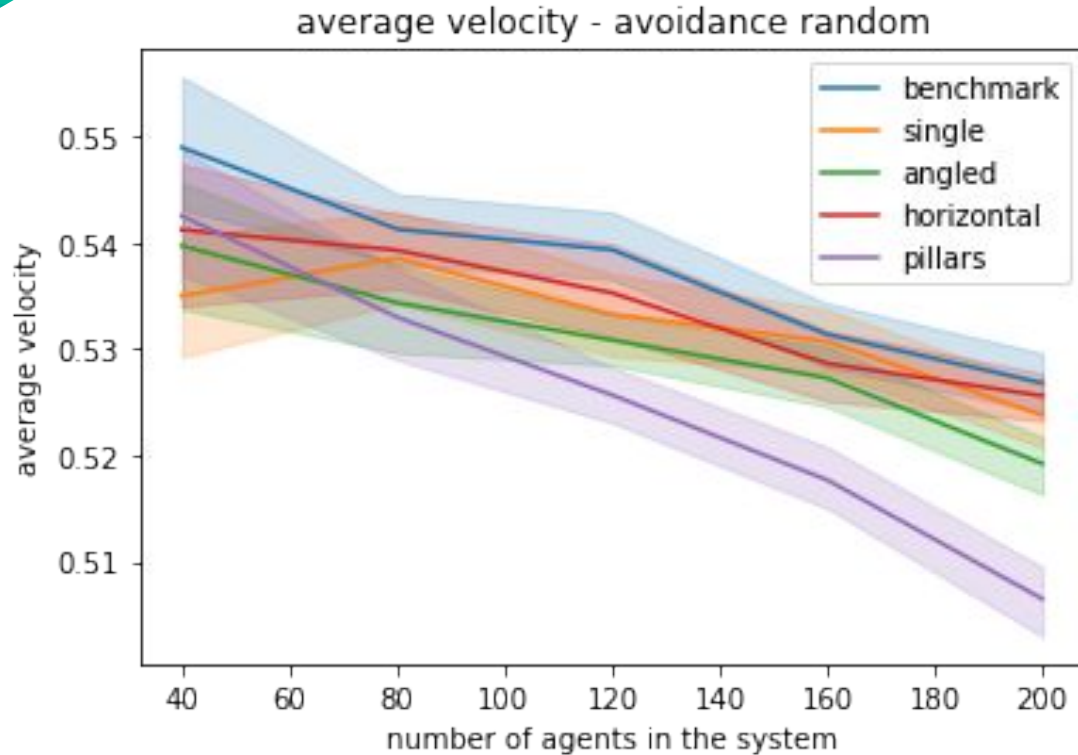
Results for 80/20



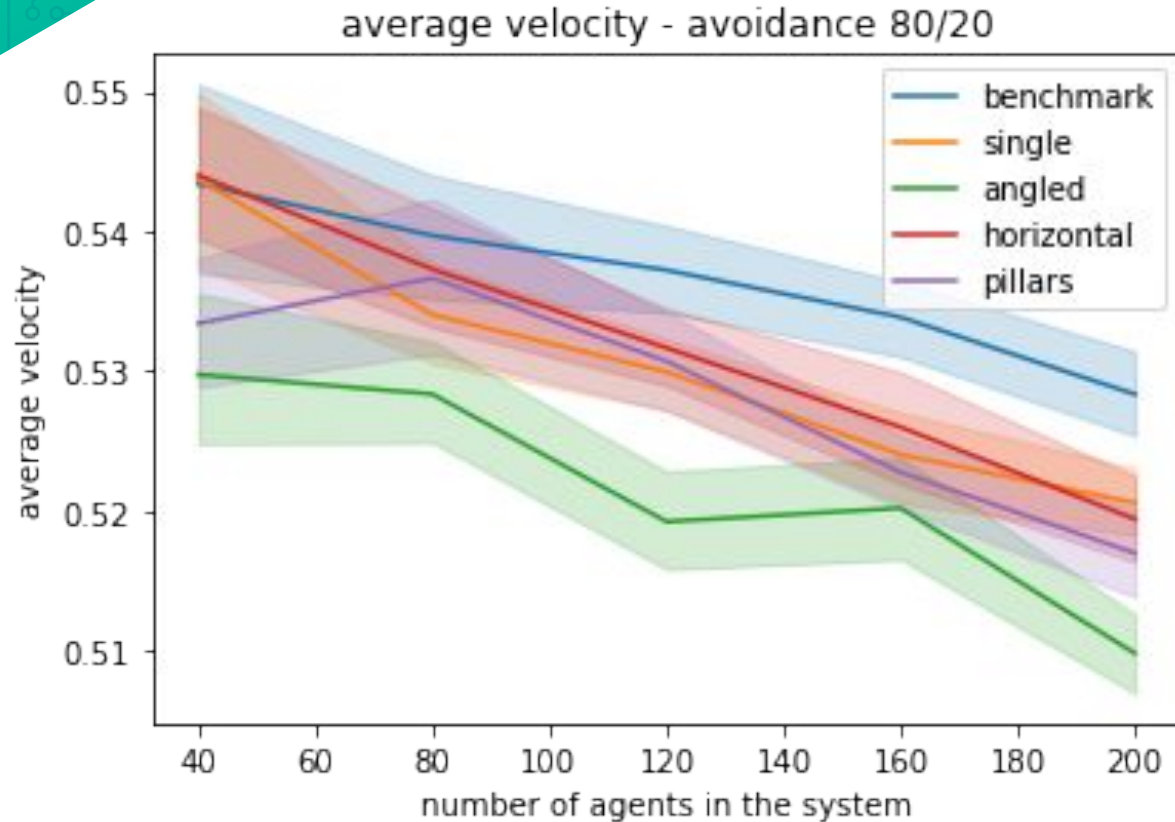
Results for 100/0



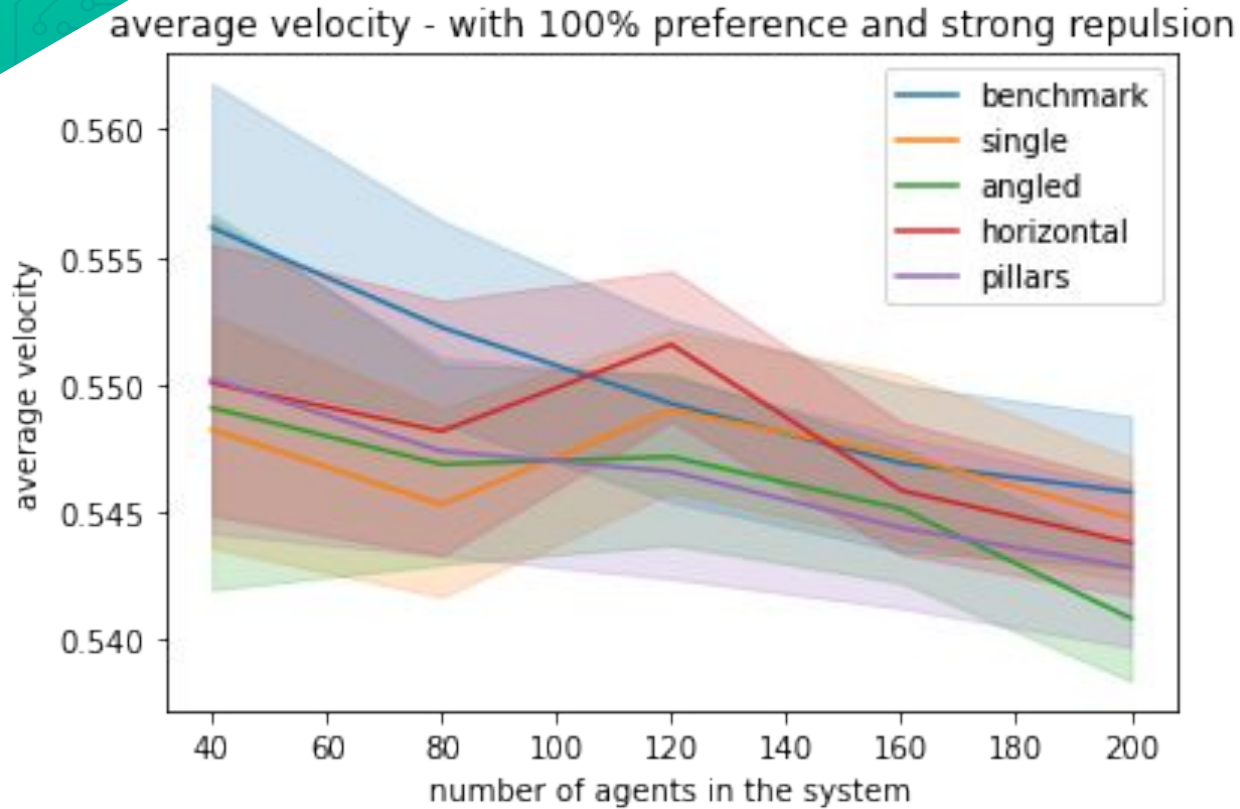
Results for 50/50 and stronger repulsion



Results for 80/20 and stronger repulsion



Results for 100/0 and stronger repulsion



Modification attempts

- ① Distribution of agents' initial position ✓
- ② Increased repulsion force towards obstacles ✓
- ③ Goal destination ✗
- ④ Width of the field of view ✗
- ⑤ Density and size of the pillars ✓

Conclusions

- Which obstacles in a corridor increase the average velocity of a bidirectional crowd flow?
 - Is the result robust for different number of agents, N ?
 - Does the result change for different parameter settings?

Deviations from the paper *'The study of the influence of obstacles on crowd dynamics'* (2017):

- Non-periodic movement
- Choice of obstacles
- Initial position of the agents



**THANK YOU FOR LISTENING,
ANY QUESTIONS?**

Bibliography

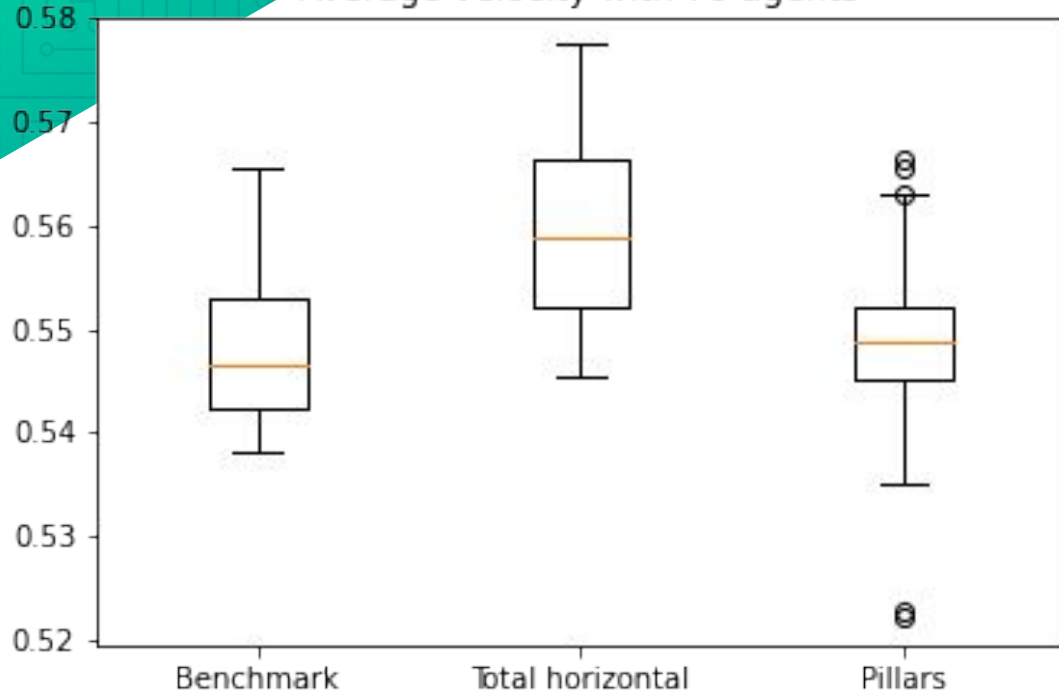
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The background is a teal color with a white circuit board pattern. A diagonal white line runs from the top-left corner to the bottom-right corner, dividing the image into two triangular sections. The word "APPENDIX" is written in white, bold, uppercase letters in the lower-left section.

APPENDIX

Appendix A

Average velocity with 70 agents



Validation of our model and algorithm with the one from the paper *The study of the influence of obstacles on crowd dynamics (2017)*.

With an horizontal obstacle for all the pathway, the crowd moves faster than with an empty corridor; adding pillars also seems to increase the average velocity, but the difference from the benchmark is not significant.