#### **Variational Inference**

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#### **Outline**

#### Introduction

Variational Inference

Variational Bayes

Variational Bayes EM

#### Motivation

- ▶ Variational inference: deterministic approximate inference.
- ▶ Pick an approximation q(y) that are tractable family, and make this approximation close to the true posterior,  $p^*(y) = p(y|\mathcal{D})$ .
- ▶ This reduces inference to an optimization problem.
- ▶ By approximating the objective, we can trade accuracy for speed.

#### ► Pros:

- For small to medium problems, it is usually faster.
- It is deterministic.
- Is it easy to determine when to stop.
- It often provides a lower bound on the log likelihood.

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#### Variational calculus

Variational inference is based on variational calculus.

#### Standard Calculus

- ▶ Functions  $f: y \rightarrow f(y)$ .
- ▶ Derivatives  $\frac{df}{du}$ .

Example: maximize the likelihood expression  $p(y|\theta)$  w.r.t  $\theta$ .

#### Variational Calculus

- ▶ Functionals  $f : y \to F(f)$ .
- ▶ Derivatives  $\frac{dF}{df}$ .

Example: maximize the entropy H[p] w.r.t a probability p(y).

## Variational calculus and the free energy

By appropriate choice of  $q(\theta)$ , F(q, y) becomes tractable to compute and maximize. Hence we have both an analytical approximation  $q(\theta)$  for the posterior  $p(\theta|y)$  and a lower bound F(q, y) for the evidence  $\log p(y)$ .

## Computing the free energy

- ▶  $\mathsf{KL}[q||p]$  divergence is unknown and free energy  $F(q, \boldsymbol{y})$  is easy to evaluate for a given q.
- ▶ Maximizing F(q, y) is equivalent to minimizing  $\mathsf{KL}[q||p]$  and tightening F(q, y) as a lower bound to (1).

We can decompose the free energy  $F(q, \boldsymbol{y})$  as follows

$$F(q, \mathbf{y}) = \int q(\boldsymbol{\theta}) \ln \frac{p(\mathbf{y}, \boldsymbol{\theta})}{q(\boldsymbol{\theta})} d\boldsymbol{\theta}$$

$$= \int q(\boldsymbol{\theta}) \ln p(\mathbf{y}, \boldsymbol{\theta}) d\boldsymbol{\theta} - \int q(\boldsymbol{\theta}) \ln q(\boldsymbol{\theta}) d\boldsymbol{\theta}$$

$$= \underbrace{\langle \ln p(\mathbf{y}, \boldsymbol{\theta}) \rangle_q}_{\text{expected log-joint}} + \underbrace{H[q]}_{\text{Shannon entropy}}$$
(2)

#### Forward or reverse KL?

KL divergence is not symmetric in its arguments, minimizing  $\mathsf{KL}[q||p]$  wrt q will give different behavior than minimizing  $\mathsf{KL}[q||p]$ .

- ▶ Variational Bayes minimize  $\mathsf{KL}[q(\boldsymbol{\theta})||p(\boldsymbol{\theta}|\boldsymbol{y})]$ :  $q(\boldsymbol{\theta})$  will tend to be zero where  $p(\boldsymbol{\theta}|\boldsymbol{y})$  is zero.
- ▶ Expectation Propagation minimize  $KL[p(\theta|y)||q(\theta)]$ :  $q(\theta)$  will tend to be nonzero where  $p(\theta|y)$  is nonzero.

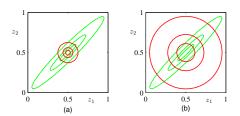


Figure: Comparison of the two alternative forms for the Kullback-Leibler divergence. (a) the Kullback-Leibler divergence  $\mathsf{KL}(q||p)$ , and (b) the reverse Kullback-Leibler divergence  $\mathsf{KL}(p||q)$ . Figure generated by KLpqGauss.

## Forward or reverse KL? (cont'd)

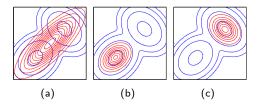


Figure: Another comparison of the two alternative forms for the Kullback-Leibler divergence. (a) Averaging across modes may lead to poor predictive performance. (b) (c) Variational Bayes may lead to local minimum. Figure generated by KLfwdReverseMixGauss.

## Mean field approximation

**Mean field approximation** assumes the posterior is a fully factorized approximation of the form

$$q(\boldsymbol{\theta}) = \prod_{i} q_i(\boldsymbol{\theta}_i) \tag{3}$$

## Derivation of the mean field update equations

$$F(q, \mathbf{y}) = \int q(\boldsymbol{\theta}) \ln \frac{p(\mathbf{y}, \boldsymbol{\theta})}{q(\boldsymbol{\theta})} d\boldsymbol{\theta}$$

$$= \int \prod_{i} q_{i} \times (\ln p(\mathbf{y}, \boldsymbol{\theta}) - \sum_{i} \ln q_{i}) d\boldsymbol{\theta} \qquad \stackrel{\text{mean field assumption: } q(\boldsymbol{\theta}) = \prod_{i} q_{i}(\boldsymbol{\theta}_{i})}{}$$

$$= \int q_{j} \prod_{\backslash j} q_{i} (\ln p(\mathbf{y}, \boldsymbol{\theta}) - \ln q_{i}) d\boldsymbol{\theta} - \int q_{j} \prod_{\backslash j} q_{i} \sum_{\backslash j} \ln q_{i} d\boldsymbol{\theta}$$

$$= \int q_{j} \left( \int \prod_{\backslash j} q_{i} \ln p(\mathbf{y}, \boldsymbol{\theta}) d\boldsymbol{\theta}_{\backslash j} - \ln q_{i} \right) d\boldsymbol{\theta}_{j} - \int q_{j} \int \prod_{\backslash j} q_{i} \ln \prod_{\backslash j} q_{i} d\boldsymbol{\theta}_{\backslash j} d\boldsymbol{\theta}_{j}$$

$$= \int q_{j} \ln \frac{\exp(<\ln p(\mathbf{y}, \boldsymbol{\theta}) >_{q \backslash j})}{q_{j}} d\boldsymbol{\theta}_{j} + c \qquad \stackrel{\exp(<\ln p(\mathbf{y}, \boldsymbol{\theta}) >_{q \backslash j}) = E_{\backslash j} [\ln p(\mathbf{y}, \boldsymbol{\theta})]}{}$$

$$= -KL[q_{j}|| \exp(<\ln p(\mathbf{y}, \boldsymbol{\theta}) >_{q \backslash j})] + c \qquad (4)$$

## Derivation of the mean field update equations(cont'd)

Suppose the densities  $q_{\backslash j}=q(\pmb{\theta}_{\backslash j})$  are kept fixed. Then the approximate posterior  $q(\pmb{\theta}_j)$  that maximizes  $F(q,\pmb{y})$  is given by

$$q_{j}^{*} = \max_{q_{j}} F(q, \boldsymbol{y})$$

$$= \frac{1}{Z} \exp(\langle \ln p(\boldsymbol{y}, \boldsymbol{\theta}) \rangle_{q \setminus j})$$
(5)

Therefore:

$$\ln q_j^* = \langle \ln p(\boldsymbol{y}, \boldsymbol{\theta}) \rangle_{q \setminus j} - \ln Z \tag{6}$$

where  $Z = \int \langle \ln p(\boldsymbol{y}, \boldsymbol{\theta}) \rangle_{q \setminus j} d\boldsymbol{\theta}_j$ .

This implies a straightforward algorithm for variational inference:

- 1. Initialize all approximate posteriors  $q(\boldsymbol{\theta}_i)$ , e.g., by setting them to their priors.
- 2. Cycle over the parameters, revising each given the current estimates of the others.
- 3. Loop until convergence.

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- ▶ So far we are inferring latent variables  $z_i$  assuming the parameters  $\theta$  of the model are known.
- ▶ Now infer the parameters themselves.
- ► Mean field approximation

$$p(\boldsymbol{\theta}|\mathcal{D}) \approx \prod_{i} q_i(\boldsymbol{\theta}_i)$$
 (7)

- ► This is variational Bayes or VB.
- ▶ If we want to infer both latent variables and parameters, then

$$p(\boldsymbol{\theta}, \boldsymbol{z}_{1:N} | \mathcal{D}) \approx q(\boldsymbol{\theta}) \prod_{i} q_{i}(\boldsymbol{z}_{i})$$
 (8)

### **Example: VB for a univariate Gaussian**

- ► Assuming there are no latent variables.
- ► Consider applying VB to infer the posterior over the parameters for a 1d Gaussian,  $p(\mu, \lambda | \mathcal{D})$ , where  $\lambda = 1/\sigma^2$  is the precision.
- ► For convenience, we will use a conjugate prior of the form.

$$p(\mu, \lambda) = p(\mu|\lambda)p(\lambda)$$

$$= N(\mu|\mu_0, (\kappa_0\lambda)^{-1})\mathsf{Ga}(\lambda|a_0, b_0)$$
(9)

Consider a factorized variational approximation

$$q(\mu, \lambda) = q_{\mu}(\mu)q_{\lambda}(\lambda) \tag{10}$$

### Target distribution

The unnormalized log posterior has the form

$$\log \widetilde{p}(\mu, \lambda) = \log p(\mu, \lambda, D) = \log p(D|\mu, \lambda) + \log p(\mu|\lambda) + \log p(\lambda)$$

$$= \frac{N}{2} \log \lambda - \frac{\lambda}{2} \sum_{i=1}^{N} (x_i - \mu)^2 - \frac{1}{2} \log(\kappa_0 \lambda)$$

$$+ \frac{\kappa_0 \lambda}{2} (\mu - \mu_0)^2 + (a_0 - 1) \log \lambda - b_0 \lambda + \text{const}$$
(11)

(11)

# Updating $q_{\mu}(\mu)$ (fix $q_{\lambda}(\lambda)$ )

The optimal form for  $q_{\mu}(\mu)$  is obtained by averaging over  $\lambda$ 

$$\begin{split} \log q_{\mu}(\mu) &= E_{q_{\lambda}}[\log p(D|\mu,\lambda) + \log p(\mu|\lambda)] + \text{const} \\ &= -\frac{E_{q_{\lambda}}[\lambda]}{2} \{ \kappa_0 (\mu - \mu_0)^2 + \sum_{i=1}^2 (x_i - \mu)^2 \} + \text{const} \end{split} \tag{12}$$

By completing the square one can show that  $q_{\mu}(\mu) = N(\mu|\mu_N, \kappa_N^{-1})$ , where

$$\mu_N = \frac{\kappa_0 \mu_0 + N\bar{x}}{\kappa_0 + N}$$

$$\kappa_N = (\kappa_0 + N) E_{q_{\lambda}}[\lambda]$$
(13)

At this stage we don't know what  $q_{\lambda}(\lambda)$  is, and hence we cannot compute  $E[\lambda]$ , but we will derive this below.

# Updating $q_{\lambda}(\lambda)$ (fix $q_{\mu}(\mu)$ )

The optimal form for  $q_{\lambda}(\lambda)$  is given by

$$\log q_{\lambda}(\lambda) = E_{q_{\mu}}[\log p(D|\mu, \lambda) + \log p(\mu|\lambda) + \log p(\lambda)] + \text{const}$$

$$= (a_0 - 1)\log \lambda - b_0\lambda + \frac{1}{2}\log \lambda + \frac{N}{2}\log \lambda$$

$$- \frac{\lambda}{2}E_{q_{\mu}}[\kappa_0(\mu - \mu_0)^2 + \sum_{i=1}^{N}(x_i - \mu)^2] + \text{const}$$
(14)

We recognize this as the log of a Gamma distribution, hence  $q_{\lambda}(\lambda) = \mathsf{Ga}(\lambda|a_N,b_N)$ , where

$$a_N = a_0 + \frac{N+1}{2}$$

$$b_N = b_0 + \frac{1}{2} E_{q_\mu} \left[ \kappa_0 (\mu - \mu_0)^2 + \sum_{i=1}^N (x_i - \mu)^2 \right]$$
(15)

## Computing the expectations

Since  $q(\mu) = N(\mu | \mu_N, \kappa_N^{-1})$ , we have

$$E_{q(\mu)}[\mu] = \mu_N$$
  
 $E_{q(\mu)}[\mu^2] = \frac{1}{\kappa_N} + \mu_N^2$  (16)

Since  $q(\lambda) = Ga(\lambda | a_N, b_N)$ , we have

$$E_q(\lambda)[\lambda] = \frac{a_N}{b_N} \tag{17}$$

Explicit forms for the update equations for  $q(\mu)$  we have

$$\mu_N = \frac{\kappa_0 \mu_0 + N\bar{x}}{\kappa_0 + N} \stackrel{\text{fixed!}}{\longleftarrow}$$

$$\kappa_N = (\kappa_0 + N) \frac{a_N}{b_N} \tag{18}$$

and for  $q(\lambda)$  we have

$$a_N = a_0 + \frac{N+1}{2} \xleftarrow{\text{fixed!}}$$

$$b_N = b_0 + \kappa_0 (E[\mu^2] + \mu_0^2 - 2E[\mu]\mu_0) + \frac{1}{2} \sum_{i=1}^{N} (x_i^2 + E[\mu^2] - 2E[\mu] - x_i)$$

(19)

#### Illustration

In the Figure, the green contours represent the exact posterior, which is Gaussian-Gamma. The dotted red contours represent the variational approximation over several iterations.

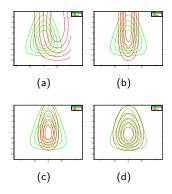


Figure: Factored variational approximation (red) to the Gaussian-Gamma distribution (green). (a) Initial guess. (b) After updating  $q_{\mu}$ . (c) After updating  $q_{\lambda}$ . (d) At convergence (after 5 iterations). Based on 10.4 of (Bishop 2006b). Figure generated by UnigaussVbDemo.

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- lacktriangle Now consider latent variable models of the form  $z_i o x_i \leftarrow heta$ .
- ▶ In EM,  $\theta$  are informed by all N data cases, whereas  $z_i$  is only informed by  $x_i$ .
- **Variational Bayes EM** or **VBEM**: model uncertainty in  $\theta$  and  $z_i$ .
- ► Computational cost is essentially the same as EM.
- ► Same idea

$$p(\boldsymbol{\theta}, \boldsymbol{z}_{1:N} | \mathcal{D}) \approx q(\boldsymbol{\theta}) \prod_{i} q_i(\boldsymbol{z}_i)$$
 (20)

▶ **Pros:** marginalizing out the parameters, we can compute a lower bound on the marginal likelihood (useful for model selection).

#### The variational posterior

▶ The conditional distribution of Z, given the mixing coefficients  $\pi$ :

$$p(\boldsymbol{Z}|\boldsymbol{\pi}) = \prod_{k=1}^{N} \prod_{k=1}^{K} \pi_{k}^{z_{nk}}$$
 (21)

► The likelihood:

$$p(\boldsymbol{X}|\boldsymbol{Z},\boldsymbol{\mu},\boldsymbol{\Lambda}) = \prod_{k=1}^{N} \prod_{k=1}^{K} N(\boldsymbol{X}_{n}|\boldsymbol{\mu}_{k},\boldsymbol{\Sigma}_{k}^{-1})^{z_{nk}}$$
(22)

- $\blacktriangleright$  Priors over the parameters  $\mu, \Sigma$  and  $\pi$ 
  - Pick a Dirichlet distribution over the mixing coefficients  $\pi$

$$p(\boldsymbol{\pi}) = \mathsf{Dir}(\boldsymbol{\pi}|\boldsymbol{\alpha}_0) = C(\boldsymbol{\alpha}_0) \prod_{k=1}^K \boldsymbol{\pi}_k^{\alpha_0 - 1}$$
 (23)

 Pick an independent Gaussian-Wishart prior for the mean and precision of each Gaussian component

$$p(\boldsymbol{\mu}, \boldsymbol{\Lambda}) = p(\boldsymbol{\mu}|\boldsymbol{\Lambda})p(\boldsymbol{\Lambda})$$

$$= \prod_{k=1}^{K} N(\boldsymbol{\mu}_{k}|\boldsymbol{m}_{0}, (\beta_{0}\boldsymbol{\Lambda}_{k})^{-1})W(\boldsymbol{\Lambda}_{k}|\boldsymbol{W}_{0}, \nu_{0})$$
(24)

### The variational posterior (cont'd)

► The joint distribution of all of the random variables

$$p(X, Z, \pi, \mu, \Lambda) = p(X|Z, \mu, \Lambda)p(Z|\pi)p(\pi)p(\mu|\Lambda)p(\Lambda)$$
 (25)

► Consider a variational distribution

$$q(\mathbf{Z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) = q(\mathbf{Z})q(\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda})$$
 (26)

Factors q(Z) and  $q(\pi, \mu, \Lambda)$  will be determined automatically by optimization of the variational distribution.

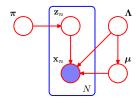


Figure: DAG of the Bayesian mixture of Gaussians model.

# Derivation of q(z) (variational E step)

Update for the factor  $q(\boldsymbol{Z})$ 

$$\ln q^*(\boldsymbol{Z}) = E_{\boldsymbol{\pi},\boldsymbol{\mu},\boldsymbol{\Lambda}}[\ln p(\boldsymbol{X},\boldsymbol{Z},\boldsymbol{\pi},\boldsymbol{\mu},\boldsymbol{\Lambda})] + \text{const}$$

$$= E_{\boldsymbol{\pi}}[\ln p(\boldsymbol{Z}|\boldsymbol{\pi})] + E_{\boldsymbol{\mu},\boldsymbol{\Lambda}}[\ln p(\boldsymbol{X}|\boldsymbol{Z},\boldsymbol{\mu},\boldsymbol{\Lambda})] + \text{const}$$

$$= \sum_{n=1}^{N} \sum_{k=1}^{K} z_{nk} \ln \rho_{nk} + \text{const}$$
(27)

where we have defined

$$\ln \rho_{nk} = E[\ln \pi_k] + \frac{1}{2} E[\ln |\mathbf{\Lambda}_k|] - \frac{D}{2} \ln(2\pi) - \frac{1}{2} E_{\boldsymbol{\mu}_k, \mathbf{\Lambda}_k} (\boldsymbol{x}_n - \boldsymbol{\mu}_k)^T \mathbf{\Lambda}_k (\boldsymbol{x}_n - \boldsymbol{\mu}_k)]$$
(28)

Taking the exponential of both sides, we obtain

$$q^*(\mathbf{Z}) \propto \prod_{k=1}^{N} \prod_{n=1}^{K} \rho_{nk}^{z_{nk}}$$
 (29)

# Derivation of q(z) (variational E step) (cont'd)

The factor q(Z)

► Requires be normalized

$$q^*(\mathbf{Z}) \propto \prod_{n=1}^{N} \prod_{n=1}^{K} r_{nk}^{z_{nk}} \tag{30}$$

where  $r_{nk} = \frac{\rho_{nk}}{\sum_{i=1}^{K} \rho_{ni}}$ .

- ▶ Takes the same functional form as the prior  $p(Z|\pi)$ .
- ▶ The discrete distribution q(Z) have  $E[z_{nk}] = r_{nk}$ .
- ▶ The quantities  $r_{nk}$  are playing the role of responsibilities.
- ▶ Three statistics evaluated with respect to the responsibilities

$$N_k = \sum_{n=1}^{N} r_{nk}$$

$$\bar{\boldsymbol{x}}_k = \frac{1}{N_k} \sum_{n=1}^{N} r_{nk} \boldsymbol{x}_n$$

$$\boldsymbol{S}_k = \frac{1}{N_k} \sum_{n=1}^{N} r_{nk} (\boldsymbol{x}_n - \bar{\boldsymbol{x}}_k) (\boldsymbol{x}_n - \bar{\boldsymbol{x}}_k)^T$$
(31)

## **Derivation of** $q(\theta)$ (variational M step)

Consider the factor  $q(\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda})$  in the variational posterior distribution

$$\ln q(\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) = \ln p(\boldsymbol{\pi}) + \sum_{k=1}^{K} \ln p(\boldsymbol{\mu}, \boldsymbol{\Lambda}) + E_{\boldsymbol{Z}}[\ln p(\boldsymbol{Z}|\boldsymbol{\pi})] + \sum_{k=1}^{N} \sum_{k=1}^{K} E[z_{nk}] \ln N(\boldsymbol{x}_{n}|\boldsymbol{\mu}_{k}, \boldsymbol{\Lambda}_{k}^{-1}) + \text{const}$$
(32)

This decomposes into terms involving only  $\pi$  with only  $\mu$  and  $\Lambda$ . Thus

$$q(\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) = q(\boldsymbol{\pi}) \prod_{k=1}^{K} q(\boldsymbol{\mu}_{k}, \boldsymbol{\Lambda}_{k})$$
(33)

Identifying the terms on the right-hand side of (32) that depend on  $\pi$ 

$$\ln q^*(\pi) = (\alpha_0 - 1) \sum_{k=1}^K \ln \pi_k + \sum_{k=1}^K \sum_{k=1}^N r_{nk} \ln \pi_k + \text{const}$$
 (34)

Taking the exponential of both sides,  $q^*(\pi)$  is a Dirichlet distribution

$$q^*(\boldsymbol{\pi}) = \mathsf{Dir}(\boldsymbol{\pi}|\alpha) \tag{35}$$

where  $\alpha$  has components  $\alpha_k$  given by  $\alpha_k = \alpha_0 + N_k$ .

# Derivation of $q(\theta)$ (variational M step) (cont'd)

Recall:  $q(\boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k) = q(\boldsymbol{\mu}_k | \boldsymbol{\Lambda}_k) q(\boldsymbol{\Lambda}_k)$ . Thus

$$q(\boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k) = N(\boldsymbol{\mu}_k | \boldsymbol{m}_k, (\beta_k \boldsymbol{\Lambda}_k)^{-1}) W(\boldsymbol{\Lambda}_k | \boldsymbol{W}_k, \nu_k)$$
(36)

where we defined

$$\beta_k = \beta_0 + N_k$$

$$\boldsymbol{m}_k = \frac{1}{\beta_k} (\beta_0 \boldsymbol{m}_0 + N_k \bar{\boldsymbol{x}}_k)$$

$$\boldsymbol{W}_k^{-1} = \boldsymbol{W}_0^{-1} + N_k S_k + \frac{\beta_0 N_k}{\beta_0 + N_k} (\bar{\boldsymbol{x}}_k - \boldsymbol{m}_0) (\bar{\boldsymbol{x}}_k - \boldsymbol{m}_0)^T$$

$$\nu_k = \nu_0 + N_k$$

$$(37)$$

Expectations of the variational distributions of the parameters

$$E_{\boldsymbol{\mu}_{k},\boldsymbol{\Lambda}_{k}}[(\boldsymbol{x}_{n}-\boldsymbol{\mu}_{k})^{T}\boldsymbol{\Lambda}_{k}(\boldsymbol{x}_{n}-\boldsymbol{\mu}_{k}) = D\boldsymbol{\beta}_{k}^{-1} + \nu_{k}(\boldsymbol{x}_{n}-\boldsymbol{m}_{k})^{T}\boldsymbol{W}_{k}(\boldsymbol{x}_{n}-\boldsymbol{m}_{k})]$$

$$\ln \tilde{\boldsymbol{\Lambda}}_{k} = E[\ln |\boldsymbol{\Lambda}_{k}|] = \sum_{i=1}^{D} \psi(\frac{\nu_{k}+1-i}{2}) + D\ln 2 + \ln |\boldsymbol{W}_{k}|$$

$$\ln \tilde{\boldsymbol{\pi}}_{k} = E[\ln \boldsymbol{\pi}_{k}] = \psi(\alpha_{k}) - \psi(\hat{\boldsymbol{\alpha}})$$
(38)

where we define  $\tilde{\Lambda}_k$  and  $\tilde{\pi}_k$ ,  $\psi(.)$  is a the diagram function,  $\hat{\alpha} = \sum_k \alpha_k$ .

## Derivation of $q(\theta)$ (variational M step) (cont'd)

If we substitute (38) into  $r_{nk} = \frac{\rho_{nk}}{\sum_{i=1}^K \rho_{nj}}$ 

$$r_{nk} \propto \tilde{\boldsymbol{\pi}}_k \tilde{\boldsymbol{\Lambda}}_k^{1/2} \exp\{-\frac{D}{2\beta_k} - \frac{\nu_k}{2} (\boldsymbol{x}_n - \boldsymbol{m}_k)^T \boldsymbol{W}_k (\boldsymbol{x}_n - \boldsymbol{m}_k)\}$$
 (39)

Notice the similarity to the responsibilities in maximum likelihood EM

$$r_{nk} \propto \boldsymbol{\pi}_k |\boldsymbol{\Lambda}_k|^{1/2} \exp\{-\frac{1}{2}(\boldsymbol{x}_n - \boldsymbol{\mu}_k)^T \boldsymbol{\Lambda}_k (\boldsymbol{x}_n - \boldsymbol{\mu}_k)\}$$
 (40)

### Lower bound on the marginal likelihood

In VB, we are maximizing a lower bound on the log marginal likelihood. Why?

- ▶ To assess convergence of the algorithm.
- ► To assess the correctness of one's code: as with EM, if the bound does not increase monotonically, there must be a bug.
- ► To approximate to the marginal likelihood, which can be used for Bayesian model selection.

The algorithm is trying to maximize the following lower bound (i.e.  ${\cal F}(q,y)$  free energy)

$$L = \sum_{\mathbf{Z}} \int \int \int q(\mathbf{Z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) \ln \left\{ \frac{p(\mathbf{X}, \mathbf{Z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda})}{(Z, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda})} \right\} d\boldsymbol{\pi} d\boldsymbol{\mu} d\boldsymbol{\Lambda} \le \ln p(\mathbf{X})$$
(41)

This quantity increases monotonically with each iteration, in Figure. (Exercise)

## Posterior predictive distribution

The predictive density is then given by

$$p(\boldsymbol{x}^*|\boldsymbol{X}) = \sum_{\boldsymbol{z}^*} \int \int \int p(\boldsymbol{x}^*|\boldsymbol{z}^*, \boldsymbol{\mu}, \boldsymbol{\Lambda}) p(\boldsymbol{z}^*|\boldsymbol{\pi}) p(\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}|\boldsymbol{X}) d\boldsymbol{\pi} d\boldsymbol{\mu} d\boldsymbol{\Lambda}$$
(42)

Using (21) and (22) we can first perform the summation over  $z^*$ 

$$p(\boldsymbol{x}^*|\boldsymbol{X}) = \sum_{k=1}^K \int \int \int \pi_k N(\boldsymbol{x}^*|\boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1}) p(\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}|\boldsymbol{X}) d\boldsymbol{\pi} d\boldsymbol{\mu} d\boldsymbol{\Lambda}$$
(43)

Because the remaining integrations are intractable, we approximate the predictive density with  $q(\pi)q(\mu,\Lambda)$ 

$$p(\boldsymbol{x}^*|\boldsymbol{X}) = \sum_{k=1}^K \int \int \int \pi_k N(\boldsymbol{x}^*|\boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1}) q(\boldsymbol{\pi}) q(\boldsymbol{\mu}, \boldsymbol{\Lambda}) d\boldsymbol{\pi} d\boldsymbol{\mu} d\boldsymbol{\Lambda}$$
(44)

where we have made use of the factorization (33).

## Posterior predictive distribution (cont'd)

The remaining integrations can now be evaluated analytically giving a mixture of Student's t-distributions

$$p(\boldsymbol{x}^*|\boldsymbol{X}) = \frac{1}{\hat{\alpha}} \sum_{k=1}^{K} \alpha_k \mathsf{St}(\boldsymbol{x}^*|\boldsymbol{m}_k, \boldsymbol{L}_k, \nu + 1 - D)$$
 (45)

in which the  $k^{\mathsf{th}}$  component has mean  $m{m}_k$ , and the precision is

$$L_k = \frac{(\nu_k + 1 - D)\beta_k}{1 + \beta_k} \mathbf{W}_k \tag{46}$$

in which  $\nu_k$  is given by (37). When the size N of the data set is large the predictive distribution (45) reduces to a mixture of Gaussians.