

# Coverage of credible intervals under multivariate monotonicity

Subhashis Ghoshal, North Carolina State University

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Australia

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# Preliminaries

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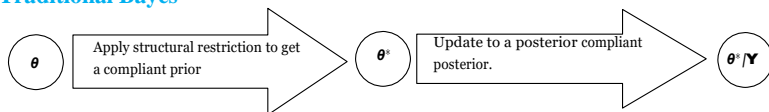
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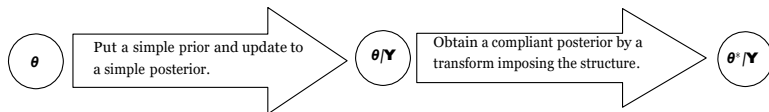
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- Consider a map that takes an element of  $\Theta$  to an element of  $\Theta_0$ . This may be used to induce a prior distribution on  $\Theta_0$ , but the corresponding posterior distribution is complicated.
- The key idea is to switch the order of a map  $\iota : \theta \mapsto \theta^*$  enforcing the desirable restriction, and the posterior updating, and use the induced posterior distribution to make an inference.

# Traditional Bayes vs the Off-beat Bayesian Idea

## Traditional Bayes



## Off-beat Bayes



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- An immersion map only needs to be defined on the support of the prior/posterior. Oftentimes, priors are put using basis expansion. Then the immersion map will typically be a finite-dimensional optimization.

# Univariate Monotone Regression

Chakraborty and G. (2021, EJS; 2021, AoS)

- A finite random series of step functions:  
$$f(x) = \sum_{j=1}^J \theta_j \mathbb{1}((j-1)/J < x \leq j/J], \theta_1, \dots, \theta_J \text{ are the coefficients}$$
given a prior distribution,  $J$  is the number of terms.



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- Monotone projection reduces to isotonization of the  $\theta$ -coefficients, for which efficient algorithms like the PAVA exist.
- Work with a deterministic choice of  $J$ , depending on the sample size  $n$ .

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- We shall obtain coverage of the monotone regression problem with the empirical  $\mathbb{L}_2$ -projection-posterior, which corresponds to the weighted isotonization problem of minimizing  $\sum_{j=1}^J N_j(\theta_j - \theta_j^*)^2$  subject to  $\theta_1^* \leq \dots \leq \theta_J^*$ , where  $N_j = \sum_{i=1}^n \mathbb{1}\{(j-1)/J < X_i \leq j/J\}$ .

## Limiting Coverage of a Credible interval

Let  $\Delta_f^* = \arg \min \{f(t) + t^2 : t \in \mathbb{R}\}$ ,  $W_1, W_2$  be independent two-sided Brownian motions,  $C_0 = 2b(a/b)^{2/3}$  with  $a = \sqrt{\sigma_0^2/g(x_0)}$ ,  $b = f'_0(x_0)/2$ ,  $g$  the density of  $X$ . Let  $\hat{f}_n$  be the sieve-MLE.  
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### Theorem

- (a) for every  $z \in \mathbb{R}$ ,  $\Pi(n^{1/3}(f^*(x_0) - f_0(x_0)) \leq z | \mathbb{D}_n) \rightsquigarrow F_{a,b}^*(z|W_1)$ ;
- (b) Limiting coverage of  $I_{n,\gamma}$ : with  $Z_B = P(\Delta_{W_1+W_2}^* \geq 0 | W_1)$ ,  
 $P_0(f_0(x_0) \in I_{n,\gamma}) \rightarrow P(\gamma/2 \leq Z_B \leq 1 - \gamma/2)$ .

Note that the nuisance parameters  $a, b$  magically vanish from the limit.

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- If the target coverage is  $(1 - \alpha)$ , starting with a  $(1 - \gamma)$ -credible interval, where  $A(\gamma/2) = \alpha/2$ , the **limiting coverage**  $(1 - \alpha)$  is **attained exactly**.

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- For instance, 93.2% equal-tailed credible interval has 95% limiting coverage.

# Multivariate Monotone Regression

# Prior and projection-posterior

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- $Y = f(\mathbf{X}) + \varepsilon$  with  $\mathbf{X} \sim G$  on  $[0, 1]^d$ ,  $f$  multivariate monotone, that is,  $f(\mathbf{x}_1) \leq f(\mathbf{x}_2)$  if  $\mathbf{x}_1 \preceq \mathbf{x}_2$ , where  $\mathbf{x}_1 \preceq \mathbf{x}_2$  means that  $x_{1,k} \leq x_{2,k}$ ,  $k = 1, \dots, d$ .

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- This also leads to a consistent Bayesian test as before.

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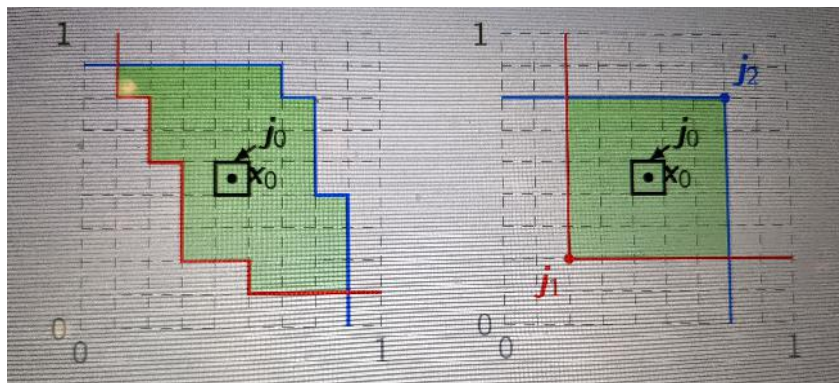
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- The clue comes from the operation used in the construction of the maxi-min estimator of Han and Zhang (2020, Ann Stat).
- A major difference with theirs is that the operation is in a discrete domain, and hence is also simpler, because of the binning through the hypercubes used in constructing the basis of step functions.





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$$\bar{l}(f)(\mathbf{x}_0) = \min_{j_0(\mathbf{x}_0) \preceq j_2} \max_{\substack{j_1 \preceq j_0(\mathbf{x}_0) \\ N_{[j_1:j_2]} > 0}} \frac{\sum_{j \in [j_1:j_2]} N_j \theta_j}{N_{[j_1:j_2]}}.$$

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- Both operations  $\underline{\iota}$  and  $\bar{\iota}$  are asymmetric in terms of the direction. A symmetric operation is obtained by averaging:  
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- Denote the images under the corresponding immersion maps by  $f_*(\mathbf{x}_0)$ ,  $f^*(\mathbf{x}_0)$ , and  $\tilde{f}(\mathbf{x}_0)$  respectively.
- In the univariate case, all three operations coincide and reduce to the empirical  $\mathbb{L}_2$ -projection on monotone functions for stepwise functions given by the standard isotonization procedure for the step-heights.

## Key assumptions

- Local smoothness: let  $\beta_k$  be the order of the first non-zero derivative of  $f$  at  $\mathbf{x}_0$  along the  $k$ th coordinate, that is,  
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- For a positive sequence  $\omega_n \downarrow 0$ , set  $\mathbf{r}_n = (\omega_n^{1/\beta_1}, \dots, \omega_n^{1/\beta_s}, 1, \dots, 1)^T$ . For any  $t > 0$ ,

$$\sup_{|\mathbf{x}_k - \mathbf{x}_{0,k}| \leq t \mathbf{r}_{n,k}} \left| f_0(\mathbf{x}) - f_0(\mathbf{x}_0) - \sum_{\mathbf{l} \in L} \frac{\partial^{\mathbf{l}} f_0(\mathbf{x}_0)}{\mathbf{l}!} (\mathbf{x} - \mathbf{x}_0)^{\mathbf{l}} \right| = o(\omega_n),$$

where

$$L = \{\mathbf{l} : 0 < \sum_{k=1}^s l_k / \beta_k \leq 1 \text{ and } l_k = 0, \text{ for } k = s+1, \dots, d\}.$$



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$$\beta_k = \min_{l \geq 1} \{l : \partial_k^l f(\mathbf{x}_0) \neq 0\}.$$
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- For a positive sequence  $\omega_n \downarrow 0$ , set  $\mathbf{r}_n = (\omega_n^{1/\beta_1}, \dots, \omega_n^{1/\beta_s}, 1, \dots, 1)^T$ . For any  $t > 0$ ,

$$\sup_{|\mathbf{x}_k - \mathbf{x}_{0,k}| \leq t r_{n,k}} \left| f_0(\mathbf{x}) - f_0(\mathbf{x}_0) - \sum_{l \in L} \frac{\partial^l f_0(\mathbf{x}_0)}{l!} (\mathbf{x} - \mathbf{x}_0)^l \right| = o(\omega_n),$$

where

$$L = \{l : 0 < \sum_{k=1}^s l_k / \beta_k \leq 1 \text{ and } l_k = 0, \text{ for } k = s+1, \dots, d\}.$$

- $\beta_k$  is odd,  $k \leq s$ ;  $\partial^l f_0(\mathbf{x}_0) = 0$  if  $\sum l_k / \beta_k < 1$ .

# Notations

Let  $H_1, H_2$  be independent centered Gaussian processes on  $\mathbb{R}_{\geq 0}^d \times \mathbb{R}_{\geq 0}^d$  with covariance kernel

$K(\mathbf{u}, \mathbf{v}) = \prod_{k=1}^s (u_k \wedge u'_k + v_k \wedge v'_k) D_s(\mathbf{u} \wedge \mathbf{u}', \mathbf{v} \wedge \mathbf{v}')$ , where

$$D_s(\mathbf{u} \wedge \mathbf{u}', \mathbf{v} \wedge \mathbf{v}') = \int_{\substack{\mathbf{x}_k \in [(\mathbf{x}_0 - \mathbf{u})_k, (\mathbf{x}_0 + \mathbf{v})_k] \cap [0, 1] \\ s+1 \leq k \leq d}} g(x_{0,1}, \dots, x_{0,s}, x_{s+1}, \dots, x_d) d\mathbf{x}$$

with  $D_d(\mathbf{u}, \mathbf{v}) = g(\mathbf{x}_0)$ , where  $g$  is the probability density function of  $\mathbf{X}$ .

Let

$$U(\mathbf{u}, \mathbf{v}) = \frac{\sigma_0 H_1(\mathbf{u}, \mathbf{v})}{\prod_{k=1}^s (u_k + v_k) D_s(\mathbf{u}, \mathbf{v})} + \frac{\sigma_0 H_2(\mathbf{u}, \mathbf{v})}{\prod_{k=1}^s (u_k + v_k) D_s(\mathbf{u}, \mathbf{v})} \\ + \sum_{l \in L^*} \frac{\partial^l f_0(x_0)}{(l+1)!} \prod_{k=1}^s \frac{v_k^{l_k+1} - (-u_k)^{l_k+1}}{u_k + v_k}.$$

$$Z_* = \sup_{\substack{\mathbf{u} \succeq \mathbf{0} \\ u_k \leq x_{0,k} \\ s+1 \leq k \leq d}} \inf_{\substack{\mathbf{v} \succeq \mathbf{0} \\ v_k \leq 1-x_{0,k} \\ s+1 \leq k \leq d}} U(\mathbf{u}, \mathbf{v}), \quad Z^* = \inf_{\substack{\mathbf{v} \succeq \mathbf{0} \\ v_k \leq 1-x_{0,k} \\ s+1 \leq k \leq d}} \sup_{\substack{\mathbf{u} \succeq \mathbf{0} \\ u_k \leq x_{0,k} \\ s+1 \leq k \leq d}} U(\mathbf{u}, \mathbf{v}).$$

# Weak limit

## Theorem

Let  $\omega_n = n^{-1/(2+\sum_{k=1}^s \beta_k^{-1})}$ . Let  $J_k \gg r_{n,k}^{-1}$ , for each  $k = 1, \dots, d$ , and  $\prod_{k=1}^d J_k \ll n\omega_n$ . For any  $z \in \mathbb{R}$ , we have

$$\Pi(\omega_n^{-1}(f_*(\mathbf{x}_0) - f_0(\mathbf{x}_0)) \leq z | \mathbb{D}_n) \rightsquigarrow P(Z_* \leq z | H_1);$$

$$\Pi(\omega_n^{-1}(f^*(\mathbf{x}_0) - f_0(\mathbf{x}_0)) \leq z | \mathbb{D}_n) \rightsquigarrow P(Z^* \leq z | H_1);$$

$$\Pi(\omega_n^{-1}(\tilde{f}(\mathbf{x}_0) - f_0(\mathbf{x}_0)) \leq z | \mathbb{D}_n) \rightsquigarrow P((Z_* + Z^*)/2 \leq z | H_1).$$

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- Tightness of the functional — max/min activity within a compact domain with high probability.

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  - the univariate case considered earlier.

# Coverage of a credible interval

- Consider the  $(1 - \gamma)$ -quantile of the  $\underline{\ell}$ -immersion posterior  $Q_{n,\gamma}^{(1)} = \inf\{z : \Pi(f_*(\mathbf{x}_0) \leq z | \mathbb{D}_n) \geq 1 - \gamma\}$ , and the corresponding one-sided credible interval  $(-\infty, Q_{n,\gamma}^{(1)}]$ .

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- Similar statements for the other two immersion maps with corresponding changes in the limiting process.

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- Using the numerical tables of the limiting distribution, we can reset the credibility level lower to obtain a targeted limiting coverage.
- Compared with the Han-Zhang procedure, the corrected intervals are significantly shorter (even the uncorrected ones are shorter), and have better coverage too, in most cases.

# Thank you