

ARTIFICIAL INTELLIGENCE

KNOWLEDGE REPRESENTATION USING
OTHER LOGIC

Ch6: Knowledge Representation Using Rules

Procedural vs. Declarative Knowledge

Logic Programming

Forward vs. backward reasoning

Matching

Control knowledge

Procedural vs. Declarative Knowledge

Declarative representation

- Knowledge is specified but the use is not given.
 - Need a program that specifies what is to be done to the knowledge and how.
 - Example:
 - Logical assertions and Resolution theorem prover
 - A different way: Logical assertions can be viewed as a program, rather than as data to a program.
- => Logical assertions = Procedural representations of knowledge

Procedural vs. Declarative Knowledge

Procedural representation

- The control information that is necessary to use the knowledge is considered to be embedded in the knowledge itself.
- Need an interpreter that follows the instructions given in the knowledge.
- The real difference between the declarative and the procedural views of knowledge lies in where control information resides.
 - Kowalski's equation: $\text{Algorithm} = \text{Logic} + \text{Control}$

Procedural vs. Declarative Knowledge

man(Marcus)

man(Caesar)

$\forall x: \text{man}(x) \rightarrow \text{person}(x)$

person(Cleopatra)

person(x)?

Logic Programming

Logical assertions are viewed as programs

Most popular programming system: PROLOG

Prolog program = {Horn Clauses}

- Horn clause: disjunction of literals of which at most one is positive literal

$$\neg P_1 \vee \neg P_2 \vee \dots \vee \neg P_n \vee Q$$

$$P_1 \wedge P_2 \wedge \dots \wedge P_n \Rightarrow Q$$

=> Prolog program is decidable

- Control structure: Prolog interpreter = backward reasoning + depth-first with backtracking

Logic Programming

Logic:

$\forall X: \text{pet}(X) \wedge \text{small}(X) \rightarrow \text{apartmentpet}(X)$

$\forall X: \text{cat}(X) \vee \text{dog}(X) \rightarrow \text{pet}(X)$

$\forall X: \text{poodle}(X) \rightarrow \text{dog}(X) \wedge \text{small}(X)$

$\text{poodle}(\text{fluffy})$

Prolog:

$\text{apartmentpet}(X) \text{ :- } \text{pet}(X) , \text{small}(X).$

$\text{pet}(X) \text{ :- } \text{cat}(X).$

$\text{pet}(X) \text{ :- } \text{dog}(X).$

$\text{dog}(X) \text{ :- } \text{poodle}(X).$

$\text{small}(X) \text{ :- } \text{poodle}(X).$ $\text{poodle}(\text{fluffy}).$

Logic Programming

Prolog vs. Logic

- Quantification is provided implicitly by the way the variables are interpreted.
 - Variables: begin with UPPERCASE letter
 - Constants: begin with lowercase letters or number
- There is an explicit symbol for AND (,), but there's none for OR. Instead, disjunction must be represented as a list of alternative statements
- “p implies q” is written as $q \text{ :- } p$.

Logic Programming

Prolog: How to find a solution?

?- apartmentpet(X)

Logical negation \neg cannot be represented explicitly in pure Prolog.

- Example: $\forall x: \text{dog}(x) \rightarrow \neg \text{cat}(x)$

=> problem-solving strategy: **NEGATION AS FAILURE**

?- cat(fluffy). => false b/c it's unable to prove Fluffy is a cat.

Negation as failure requires: **CLOSED WORLD**

ASSUMPTION

- True assertions are contained in our knowledge base or derivable from assertions that are so contained

Logic Programming

The **occur-check** is omitted from the unification: **unsound**

test:- p(X, X).

p(Y, f(Y)).

?- test => yes

Backward chaining with depth-first search: **incomplete**

p(X, X).

p(X, Y):- q(X, Y).

q(X, Y):- q(Y, X).

?- p(2, 2) => yes

p(X, Y):- q(X, Y).

p(X, X).

q(X, Y):- q(Y, X).

?- p(2, 2) => loop

Unsafe **cut**: **incomplete**

Forward vs. Backward Reasoning

Forward: from the start states.

Backward: from the goal states.

Forward or Backward?

=> The **topology** of the problem space

Forward vs. Backward Reasoning

Forward or Backward?

- Move from the smaller set of states to the larger set of states
- Proceed in the direction with the lower branching factor
- Proceed in the direction that corresponds more closely with the way the user will think
- Proceed in the direction that corresponds more closely with the way the problem-solving episodes will be triggered

Forward vs. Backward Reasoning

Bidirectional search (hybrid reasoning)

- Search both forward from the start state and backward from the goal simultaneously until two paths meet somewhere in between.
- Combining Forward and Backward Reasoning

← $A_1, \dots, A_{k-1}, A_k, A_{k+1}, \dots, A_n$

achieved by
forward reasoning

achieved by
backward reasoning

Forward vs. Backward Reasoning

To encode the knowledge for reasoning, we need 2 kinds of rules:

- **Forward rules:** to encode knowledge about **how to respond to certain input.**
- **Backward rules:** to encode knowledge about **how to achieve particular goals.**

Matching

How to extract from the entire collection of rules that can be applied at a given point?

=> Matching between current state and the precondition of the rules

Matching

Indexing

- A large number of rules => too slow to find a rule
- Indexing: Use the current state as an index into rules and select the matching ones immediately
- Only works when preconditions of rules match exact board configuration
- It's not always obvious whether a rule's preconditions are satisfied by a particular state.
- There's a trade-off between the ease of writing rules (high-level descriptions) and the simplicity of the matching process

Matching

Matching with variables

- Generality in the statements of the rules
- ⇒ Need a search process to discover a match between a particular state and the preconditions of a given rule
- Backward-chaining systems:
 - One-one matching algorithm:
 - Unification procedure + Depth-first backtracking to select individual rules
- Forward-chaining systems:
 - Many-many matching algorithm: RETE

Matching

RETE network (Forgy, 1982)

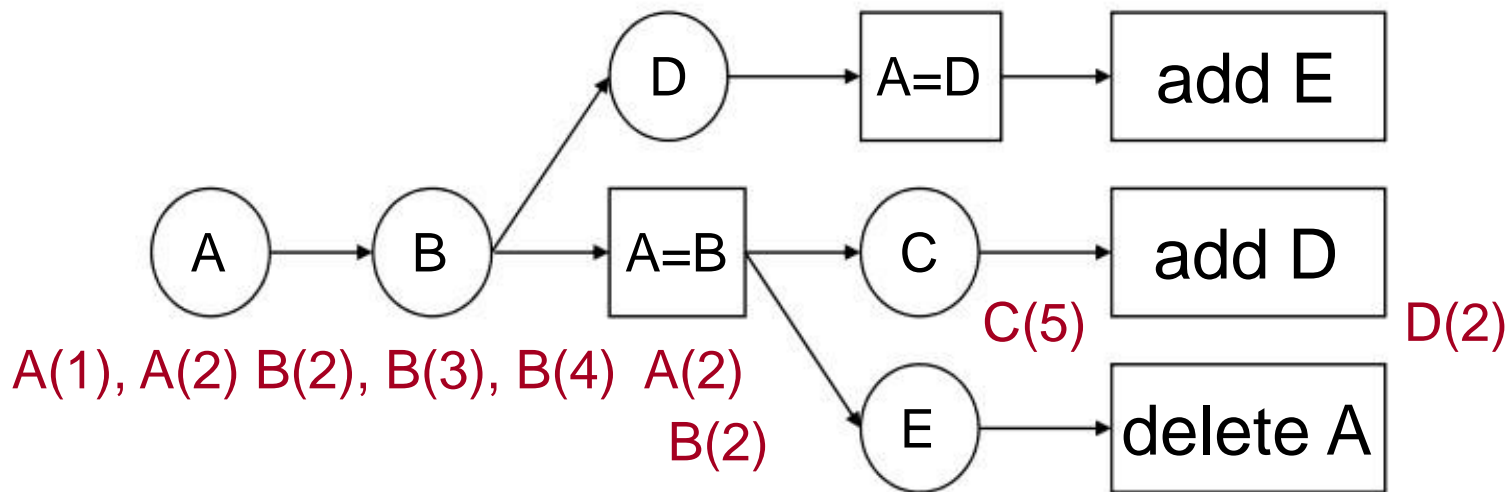
Working memory: $\{A(1), A(2), B(2), B(3), B(4), C(5)\}$

Rule memory:

$A(x) \wedge B(x) \wedge C(y) \Rightarrow \text{add } D(x)$

$A(x) \wedge B(y) \wedge D(x) \Rightarrow \text{add } E(x)$

$A(x) \wedge B(x) \wedge E(y) \Rightarrow \text{delete } A(x)$



Matching

Approximate matching

- Rules should be applied if their preconditions approximately match the current situation
- Example: A speech-understanding program
 - Rules: A description of a physical waveform to phones (a, e, ...)
 - Physical signal: differences in the way individuals speak, result of background noise, ...

Matching

ELIZA (Weizenbaum, 1966):

Person: It's true. I am unhappy.

ELIZA: Do you think coming here will help you not to be unhappy?

Person: I need some help, that much seems certain.

ELIZA: What would it mean to you if you got some help?

Person: Perhaps I could learn to get along with my brother.

ELIZA: Tell me more about your family.

Matching

ELIZA (Weizenbaum, 1966):

(X me Y) → (X you Y)

(I remember X) → (Why do you remember X just now?)

(My {family-member} is Y) → (Who else in your family is Y?)

(X {family-member} Y) → (Tell me more about your family)

Person: My brother is mean to me.

ELIZA: Who else in your family is mean to you?

Matching

Conflict resolution:

- Preferences based on rules:
 - Specificity of rules
 - Physical order of rules
- Preferences based on objects:
 - Importance of objects
 - Position of objects
- Preferences based on states:
 - Evaluation of states

Control Knowledge

Search control knowledge: Knowledge about which paths are most likely to lead quickly to a goal state.

- Which states are more preferable to others.
- Which rule to apply in a given situation.
- The order in which to pursue subgoals
- Useful sequences of rules to apply.

Search control knowledge = Meta knowledge

SUMMARY

- LOGIC
- MATCHING
- CONFLICTS