

DPDA

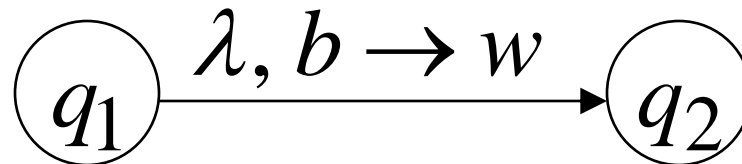
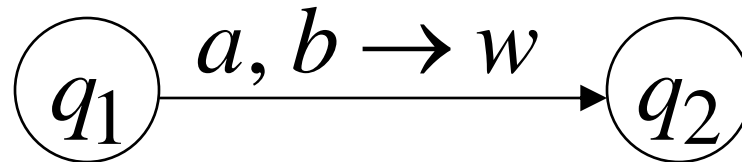
Deterministic PDA

Deterministic PDA's

- ▶ A PDA $M = (Q, \Sigma, \Gamma, \delta, q_0, z_0, F)$ is said to be deterministic if
 - $\delta(p, a, \beta) = (q, \gamma)$
 - ie. To be deterministic, there must be at most one choice of move for any state p , input symbol a , and stack symbol β .
 - $\delta(p, \epsilon, \beta)$ is not empty then $\delta(p, a, \beta)$ must be empty for every $a \in \Sigma, p \in Q, \beta \in \Gamma$.
 - ie. there must not be a choice between using input ϵ or real input.
 - Formally, $\delta(p, \epsilon, \beta)$ and $\delta(p, a, \beta)$ cannot both be nonempty.

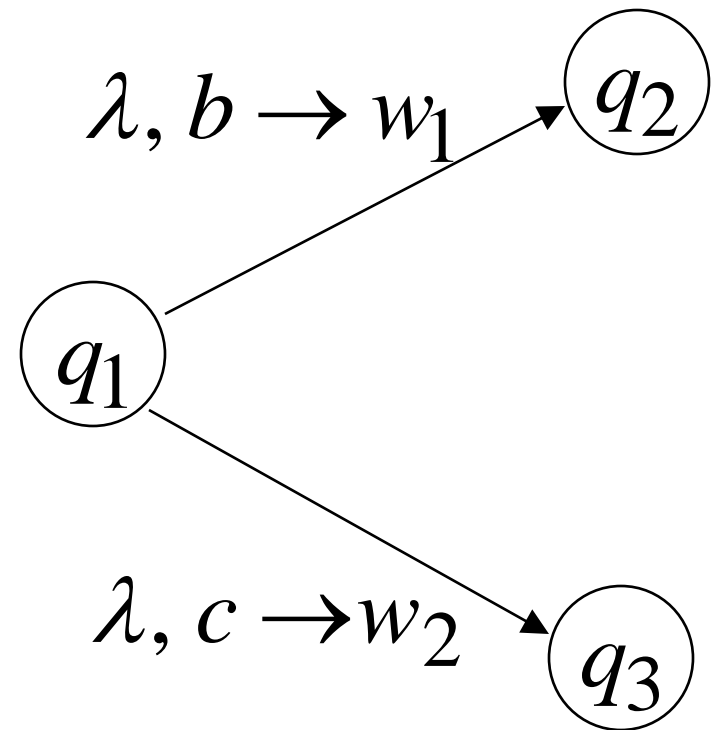
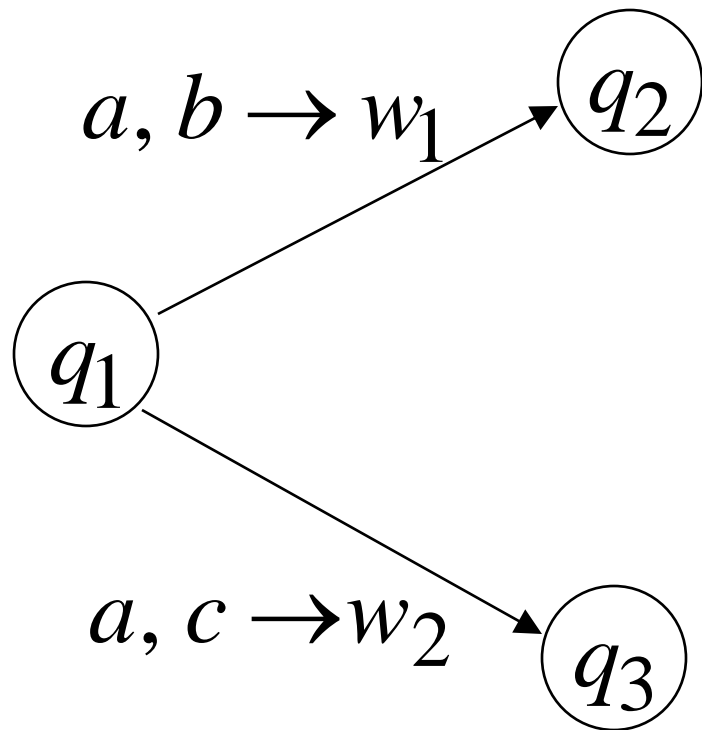
Deterministic PDA: DPDA

Allowed transitions:



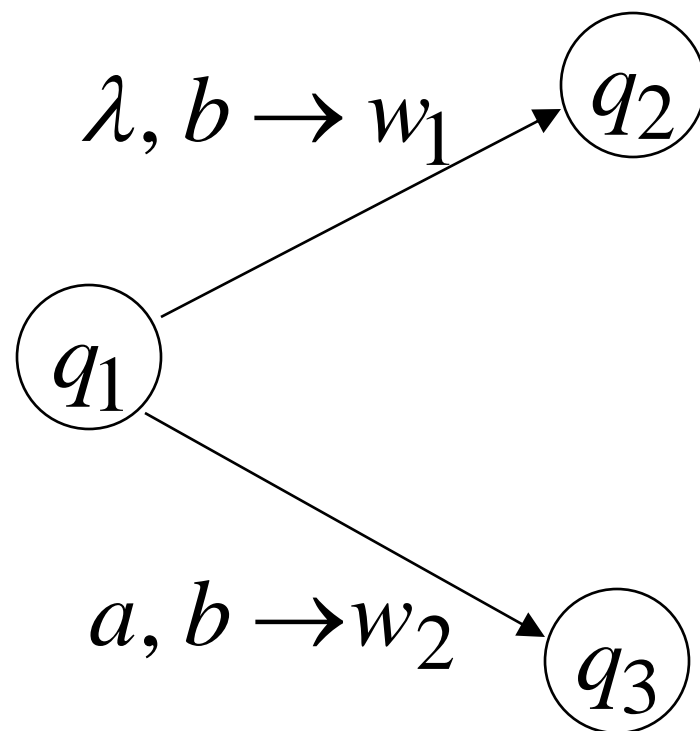
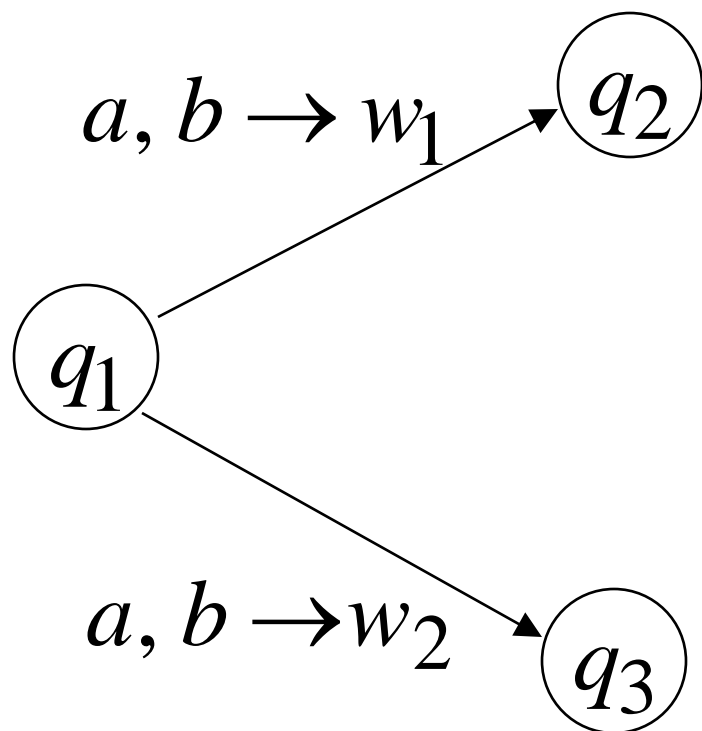
(deterministic choices)

Allowed transitions:



(deterministic choices)

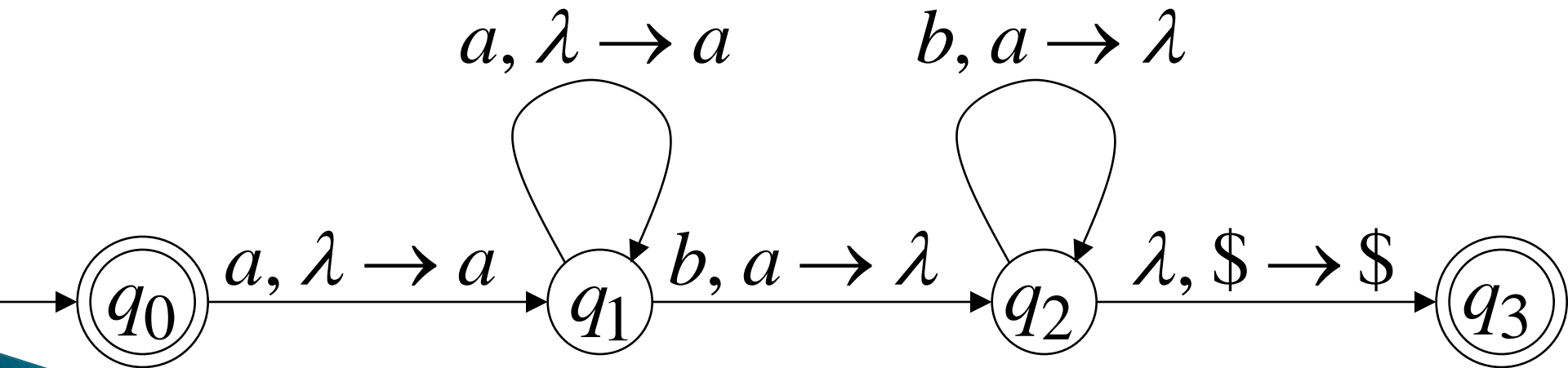
Not allowed:



(non deterministic choices)

DPDA example

$$L(M) = \{a^n b^n : n \geq 0\}$$



Definition:

A language L is **deterministic context-free** if there exists some DPDA that accepts it

Example:

The language $L(M) = \{a^n b^n : n \geq 0\}$

is deterministic context-free

Example of Non-DPDA (PDA)

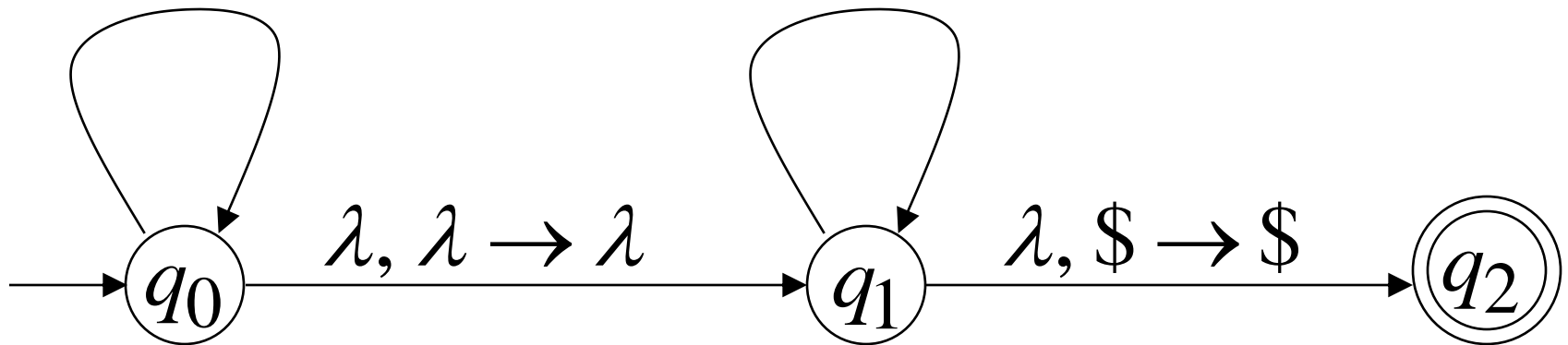
$$L(M) = \{vv^R : v \in \{a,b\}^*\}$$

$a, \lambda \rightarrow a$

$a, a \rightarrow \lambda$

$b, \lambda \rightarrow b$

$b, b \rightarrow \lambda$



Not allowed in DPDAs

