Class Testing

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What Is Class Testing?

- Unit Testing for Object-Oriented Systems
 - Test all features of a class object
 - Units should be tested in isolation
 - Test sequences of methods
- Inheritance presents problems in testing
 - ► Flattened classes
- Units
 - The smallest chunk that can be compiled by itself
 - A single procedure/function
 - Something so small it would be developed by one person
- Classes and Methods = Units?

Functional or Structural?

- ► Functional Testing
 - ► Test methods as black boxes
 - ► Tests based on specification
- Structural Testing
 - 'Set' and 'Get' methods for attributes

When? Who? What?

- Unit Level
- Extreme Programming...
 - ► Test cases designed before coding begins
- More normally...
 - ► Test cases designed after coding is complete
- ightharpoonup Tester \neq Programmer

Goals

- Check attributes get set correctly
 - ▶ Initialised to the right value, eg: sizeIndex = [31, 28, 31, 30, 31, 30, 31, 30, 31, 30, 30]
- ▶ Find errors in calculation
 - + instead of *
- Wrong method calls
 - year.increment() instead of month.increment()
- Redundant code
- Incorrect boundary values
 - for (int i = 0; $i \le 5$; i++) VS for (int i = 0; i < 5; i++)
- Error Messages
- Program efficiency is not so important

Windshield Wiper Example

c2.Lever	OFF	INT	INT	INT	LOW	HIGH
c2.Dial	n/a	1	2	3	n/a	n/a
a1.Wiper	0	4	6	12	30	30

- Lever has four positions: OFF, INT, LOW and HIGH
- Dial is only relevant when lever is on INT

Windshield Wiper Pseudocode

```
class windshieldWiper
           private wiperSpeed
           private leverPosition
           private dialPosition
 7 8 9
           windshieldWiper(wiperSpeed,
                    leverPosition, dialPosition)
            getWiperSpeed()
            setWiperSpeed()
            getLeverPosition()
14
            setLeverPosition()
            getDialPosition()
            setDialPosition()
           senseLeverUp()
            senseLeverDown()
            senseDialUp()
           senseDialDown()
24
   End class windshieldWiper
```

- Maintain the state of lever and dial
- 'Sense' methods for lever and dial
- Get/Set operations for each variable

Windshield Wiper Pseudocode 2

```
29 senseLeverUp()
       Case leverPosition Of
           Case 1: Off
                leverPosition = Int
               Case dialPosition Of
                    Case 1: 1
                        wiperSpeed = 4
                    Case 2: 2
                        wiperSpeed = 6
                    Case 3: 3
                        wiperSpeed = 12
40
               EndCase 'dialPosition
41
           Case 2: Int.
42
               leverPosition = Low
43
               wiperSpeed = 30
44
           Case 3: Low
45
               leverPosition = High
46
               wiperSpeed = 60
47
           Case 4: High
48
                (impossible; error condition)
       EndCase 'leverPosition
49
```

Methods for testing Windshield Wiper

- ► Test the get/set methods
 - wiperSpeed
 - leverPosition
 - dialPosition
- Driver (main program)
- Test individual methods
- ► Test classes that don't rely on others first
- ▶ Then test classes that use the already tested classes
- Stubs
 - Dummy subprograms

Test senseLeverUp

```
52 class testSenseLeverUp
       wiperSpeed
54
   leverPos
      dialPos
       testResult 'boolean
57 main()
       testCase = instantiate windshieldWiper(0,Off,1)
       windshieldWiper.senseLeverUp()
       leverPos = windshieldWiper.getLeverPosition()
61 If leverPos = Int
           Then testResult = Pass
          Else testResult = Fail
64
      EndIf
65 End 'main
```

Test Case	Preconditions	Method	Expected Value of leverPos
1	windshieldWiper(0,Off,1)	senseLeverUp()	INT
2	windshieldWiper(0,Int,1)	senseLeverUp()	LOW
3	windshieldWiper(0,Low,1)	senseLeverUp()	HIGH
4	windshieldWiper(0,High,1)	senseLeverDown()	LOW
5	windshieldWiper(0,Low,1)	senseLeverDown()	INT
6	windshieldWiper(0,Int,1)	senseLeverDown()	OFF

Test windshieldWiper

Event Sequence	User Action	System Response	
1	move lever to INT	Wiper speed is 4	
2	move dial to 2	Wiper speed is 6	
3	move dial to 3	Wiper speed is 12	
4	move lever to LOW	Wiper speed is 20	
5	move lever to INT	Wiper speed is 12	
6	move lever to OFF	Wiper speed is 0	

Test windshieldWiper Sequences

If wiperSpeed = 12 Then step3OK = Pass Else step3OK = Fail

EndIf

```
85 class testScenario
                                                                  windshieldWiper.senseLeverUp()
                                                                  wiperSpeed = windshieldWiper.getWiperSpeed()
       wiperSpeed
       leverPos
                                                                  If wiperSpeed = 20
      dialPos
                                                                      Then step40K = Pass
      steplok 'boolean
                                                                      Else step40K = Fail
       step20K 'boolean
                                                                  EndIf
      step30K 'boolean
                                                                  windshieldWiper.senseLeverDown()
      step40K 'boolean
                                                                  wiperSpeed = windshieldWiper.getWiperSpeed()
       step50K 'boolean
       step60K 'boolean
                                                                  If wiperSpeed = 12
                                                                      Then step50K = Pass
                                                                      Else step50K = Fail
96 main()
       testCase = instantiate windshieldWiper(0,Off,1)
                                                                  EndIf
       windshieldWiper.senseLeverUp()
      wiperSpeed = windshieldWiper.getWiperSpeed()
                                                                  windshieldWiper.senseLeverDown()
      If wiperSpeed = 4
                                                                  wiperSpeed = windshieldWiper.getWiperSpeed()
                                                                  If wiperSpeed = 0
           Then step10K = Pass
           Else step10K = Fail
                                                                      Then step60K = Pass
                                                                      Else step60K = Fail
       EndIf
                                                                  EndIf
       windshieldWiper.senseDialUp()
                                                         139 End 'main
      wiperSpeed = windshieldWiper.getWiperSpeed()
      If wiperSpeed = 6
           Then step20K = Pass
           Else step20K = Fail
       EndIf
       windshieldWiper.senseDialUp()
      wiperSpeed = windshieldWiper.getWiperSpeed()
```

Pros/Cons of writing a test driver

- Automated testing
- Drivers and Stubs = Overhead
- Manual Testing

In Summary...

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Any Questions?