Tree-Structured Indexes (Brass Tacks)

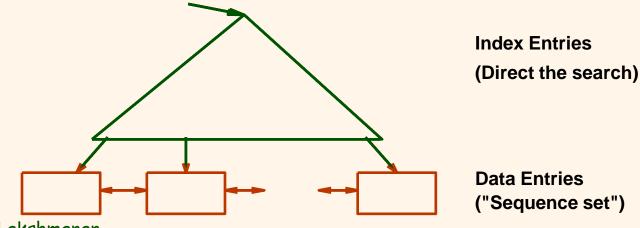
Chapter 10 Ramakrishnan and Gehrke (Sections 10.3-10.8)

What will I learn from this set of lectures?

- * How do B+trees work (for search)?
- * How can I tune B+trees for performance?
- * How can I maintain its balance against inserts and deletes?
- * How do I build a B+tree from scratch?
- How can I handle key values that are very long - e.g., long song names or long names of people?

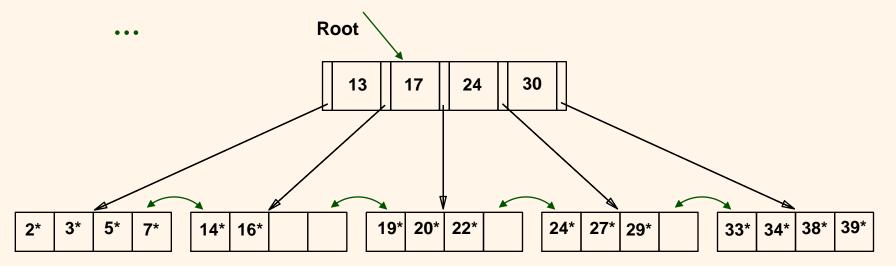
B+ Tree: The Most Widely Used Index

- Insert/delete at log FN cost; keep tree heightbalanced. (F = fanout, N = # leaf pages)
- * Minimum 50% occupancy (except for root). Each node contains $\mathbf{d} \leftarrow \underline{m} \leftarrow 2\mathbf{d}$ entries. The parameter \mathbf{d} is called the *order* of the tree.
- * Supports equality and range-searches efficiently.

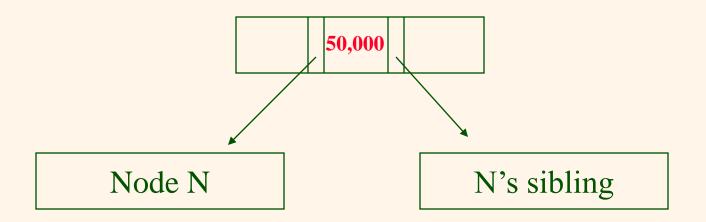


Example B+ Tree

- Search begins at root, and key comparisons direct it to a leaf (as in ISAM)
- * Binary search within a node
- Search for 5*, 15*, all data entries >= 28*



B+Trees basics



The key 50,000 separates or discriminates between N and its sibling. Plays a crucial role in search and update maintenance. Call 50,000 the separator/discriminator of N and its sibling.

B+ Trees in Practice

- * Typical order: 100. Typical fill-factor: In 2 = 66.5% (approx).
 - average fanout = $2 \times 100 \times 66.5\% = 133$
- Typical capacities:
 - Height 4: 133⁴ = 312,900,721 pages.
 - Height 3: 133³ = 2,352,637 pages
- * Can often hold top levels in buffer pool:
 - Level 1 = 1 page = 8 Kbytes
 - Level 2 = 133 pages = 1 MByte (approx.)
 - Level 3 = 17,689 pages = 133 MBytes (approx.)
 - Level 4 = 2,352,637 pages = 17.689 GBytes (approx.)
 - Level 5 = 312,900,721 pages = 2.352637 tera bytes! (approx.)
- * For typical orders (d ~ 100-200), a shallow B+tree can accommodate very large files. How tall a B+tree do we need to cover all of Canada's taxpayer records?

B+ Trees in practice

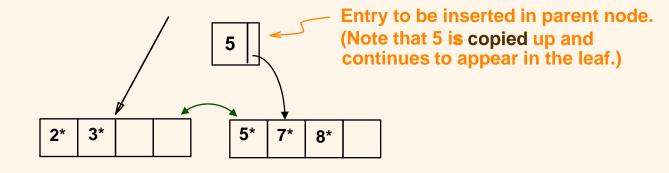
- Suppose a node is implemented as a block, a block is 4 K, a key is 12 bytes, whereas a pointer is 8 bytes.
 - For a file occupying b (logical) blocks, what is the min/max/avg height of a B+tree index?
 - If we have m bytes of RAM, how many levels of the B+tree can we prefetch to speed up performance?

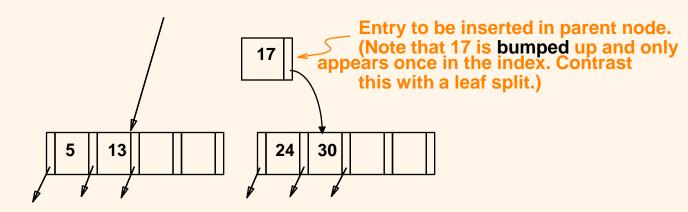
Inserting a Data Entry into a B+ Tree

- * Find correct leaf L.
- ❖ Put data entry onto L.
 - If L has enough space, done!
 - Else, must split L (into L and a new node L2)
 - * Redistribute entries evenly, copy up middle key.
 - Insert index entry pointing to L2 (i.e., the middle key copied up) into parent of L.
- * This can happen recursively
 - To split index node, redistribute entries evenly, but bump up middle key. (Contrast with leaf splits.)
- * Splits "grow" tree; root split increases height.
 - Tree growth: gets wider, maybe even one level taller.

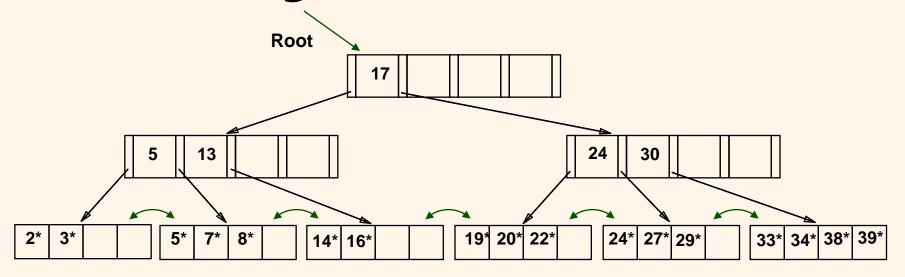
Inserting 8* into <u>Example B+</u> Tree

- Observe how minimum occupancy is guaranteed in both leaf and index pg splits.
- Note difference between copy-up and bump-up; Why do we handle leaf page split and index page split differently?





Example B+ Tree After Inserting 8*



- Notice that root was split, leading to increase in height.
- ❖ In this example, we can avoid split by re-distributing entries; however, this is usually not done in practice.

What would it look like?

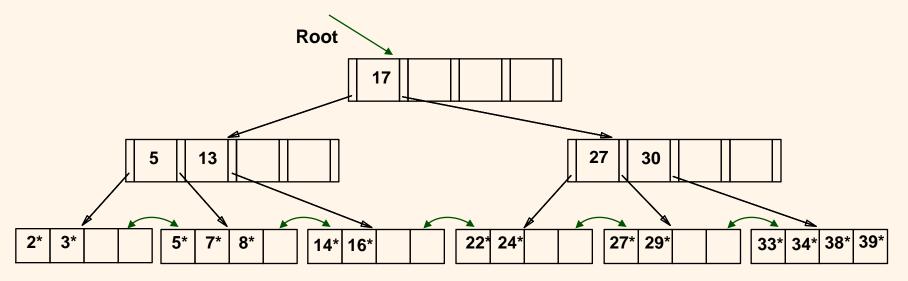
Deleting a Data Entry from a B+ Tree

- * Start at root, find leaf L where entry belongs.
- * Remove the entry.
 - If L is at least half-full, done!
 - If L has only d-1 entries,
 - ◆ Try to re-distribute, borrowing from sibling (adjacent node with same parent as L). Adjust the key that separates L and its sibling.
 - ◆ If re-distribution fails, merge L and sibling.
- * If merge occurred, must delete separator entry (discriminating L & its sibling) from parent of L.
- * Merge could propagate to root, decreasing height.

Question: Can L's occupancy ever drop below d-1?

Example Tree After (Inserting 8* Then) Deleting 19* and 20*

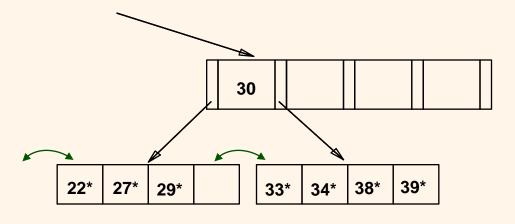
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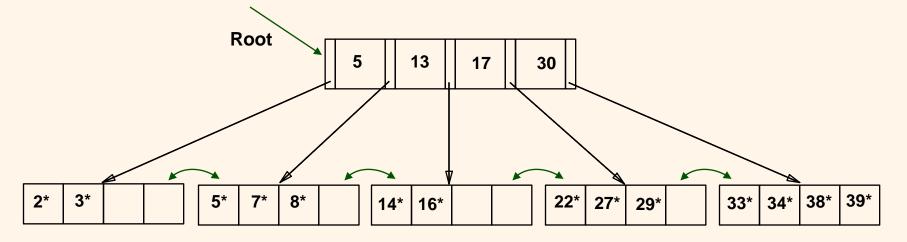


- ❖ Deleting 19* is easy.
- * Deleting 20* is done with re-distribution. Notice how new middle key is copied up.

... And Then Deleting 24*

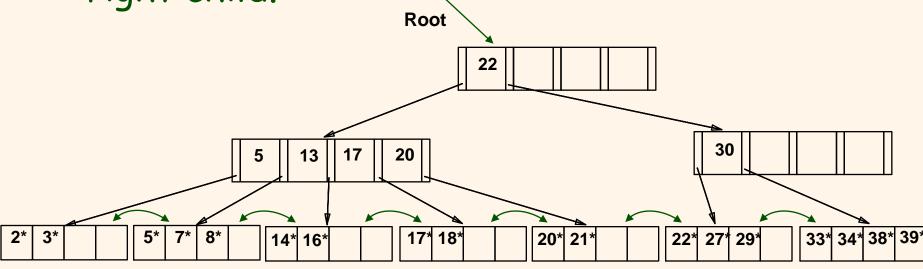
- * Must merge.
- Observe `toss' of index entry (on right), and `pull down' of index entry (below).





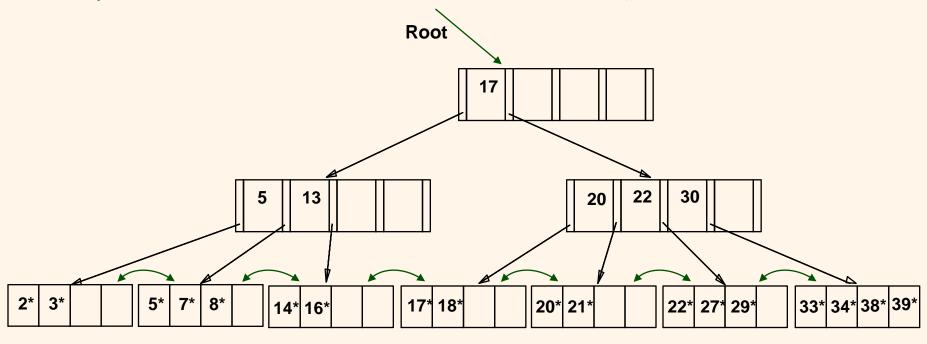
Example of Non-leaf Redistribution

- Tree is shown below during deletion of 24*.
 (What could be a possible initial tree?)
- * In contrast to previous example, can redistribute entry from left child of root to right child.



After Re-distribution

- * Intuitively, entries are re-distributed by "pushing through" the splitting entry (i.e., separator) in the parent node.
- * It suffices to re-distribute index entry with key 20; we've re-distributed 17 as well for illustration.



Optimization 1: Prefix Key Compression

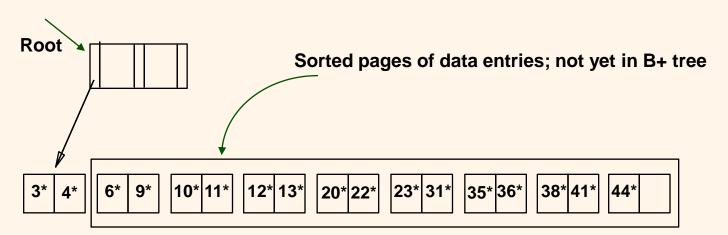
- * Important to increase fan-out. (Why?)
- * Key values in index entries only `direct traffic'; can often compress them.
 - E.g., If we have adjacent index entries with search key values Dannon Yogurt, David Smith and Devarakonda Murthy, we can abbreviate <u>David Smith</u> to Dav. (The other keys can be compressed too ...)
 - ◆ Is this correct? Not quite! What if there is a data entry Davey Jones? (Can only compress <u>David Smith</u> to <u>Davi</u>)
 - ♦ In general, while compressing, must leave each index entry greater than every key value (in any subtree) to its left.
- Insert/delete must be suitably modified.
- This idea works for any field/attribute whose data type is a long string: e.g., customer code, shipping tracking number, etc.

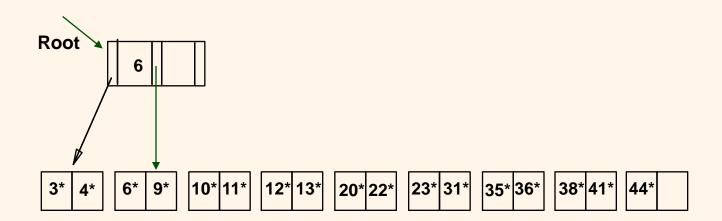
Analyzing insert/delete time.

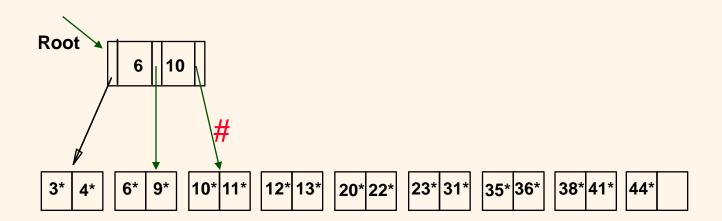
- ❖ Given a B+tree index with height h, what can you say about best case, average case, and worst case I/O?
- It must have something to do with h.
- But is it exactly h?
- What exactly constitutes best, averege, and worst case?

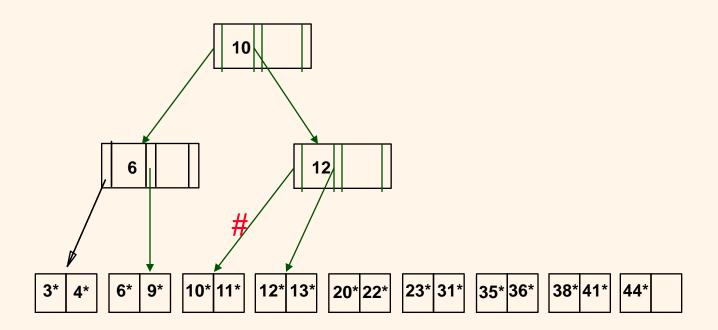
Optimization 2: Bulk Loading of a B+ Tree

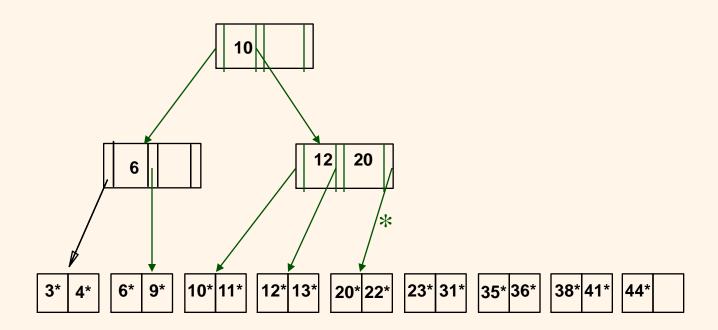
- * If we have a large collection of records, and we want to create a B+ tree on some field, doing so by repeatedly inserting records is very slow.
- * Bulk Loading can be done much more efficiently.
- * Initialization: Sort all data entries, insert pointer to first (leaf) page in a new (root) page.

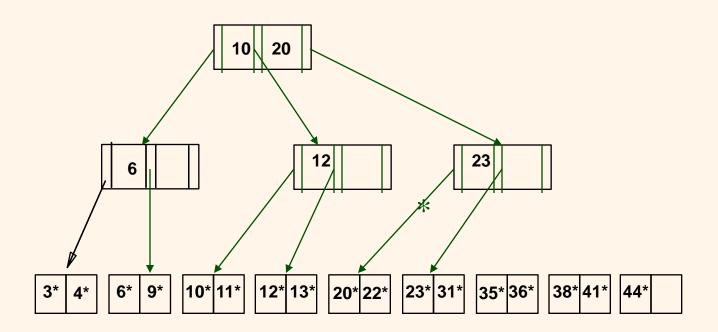








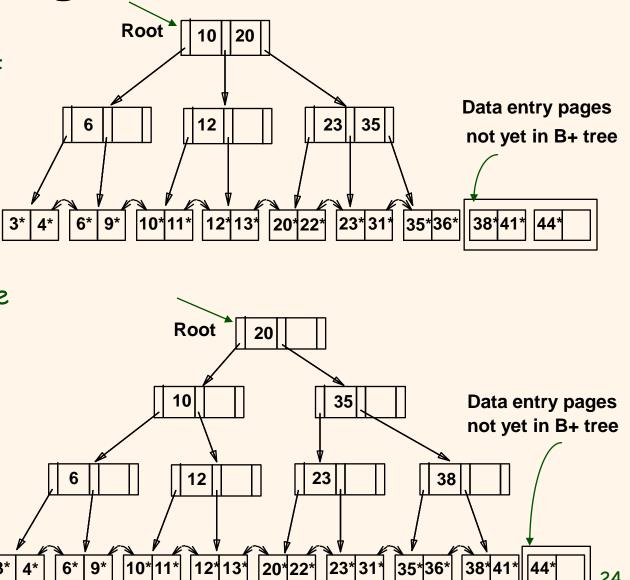




Index entries for leaf pages always entered into right-most index page just above leaf level. When this fills up, it splits.

(Split may go up right-most path to the root.)

 Much faster than repeated inserts, especially when one considers locking!



CPSC 404, Laks V.S. Lakshmanan

Bulk Loading

- How would you estimate time taken to build a B+tree index from scratch?
 - Naïve approach of repeated insertions.
 - Bulk loading.
- Naïve approach: each insert is potentially a random block seek; cannot read/insert next data block until after previous block has been inserted. Very slow.
- * Bulk loading: dominant factor sorting data (or data entries as appropriate). Followed by another sequential read (w/ proper buffer management).
 - Explored in exercises.

Summary of Bulk Loading

- Option 1: multiple inserts.
 - Slow.
 - Does not ensure sequential storage of leaves.
- Option 2: bulk loading
 - Has advantages for concurrency control.
 - Fewer I/Os during build.
 - Leaves will be stored sequentially (and linked, of course).
 - Can control "fill factor" on pages.

Summary

- Tree-structured indexes are ideal for range-searches, also good for equality searches.
- * ISAM is a static structure.
 - Only leaf pages modified; overflow pages needed.
 - Overflow chains can degrade performance unless size of data set and data distribution stay constant.
- * B+ tree is a dynamic structure.
 - Inserts/deletes leave tree height-balanced; log F N cost.
 - High fanout (F) means depth (i.e., height) rarely more than 3 or 4.
 - Almost always better than simply maintaining a sorted file.

Summary (Contd.)

- * Key compression increases fanout, reduces height.
- Bulk loading can be much faster than repeated inserts for creating a B+ tree on a large data set.
- * Most widely used index in database management systems because of its versatility. One of the most optimized components of a DBMS.