

Py-CoilGen

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1 README	1
1.0.1 Python Implementation	1
1.0.2 Testing with Pytest	1
1.0.3 Citation	1
2 Namespace Index	3
2.1 Package List	3
3 Hierarchical Index	5
3.1 Class Hierarchy	5
4 Class Index	7
4.1 Class List	7
5 File Index	9
5.1 File List	9
6 Namespace Documentation	11
6.1 calcContoursByTriangularPotentialCuts Namespace Reference	11
6.1.1 Function Documentation	11
6.1.1.1 calcContoursByTriangluarPotentialCuts()	11
6.1.1.2 checkIfPositionsElementIdenticalWithFirstList()	12
6.1.1.3 getCutDistancesToEdgeNodes()	12
6.1.1.4 getEdgeAttachedTriangles()	12
6.1.1.5 getEdgeOpposedNode()	12
6.1.1.6 getEdges()	13
6.1.1.7 getInnerEdegTriangleNodes()	13
6.1.1.8 getInnerEdges()	13
6.1.1.9 getNumAttachedTriangles()	13
6.1.1.10 getPotentialCutCriteria()	14
6.1.1.11 getPotentialSortedCutPoints()	14
6.1.1.12 getRawUnarrangedLoops()	14
6.1.1.13 getRawUnsortedPoints()	14
6.1.1.14 getuvCutPoints()	15
6.1.1.15 removeTwoElementsFromArray()	15
6.2 calcPotentialLevels Namespace Reference	15
6.2.1 Function Documentation	15
6.2.1.1 calcPotentialLevels()	15
6.3 defineTargetField Namespace Reference	16
6.3.1 Function Documentation	16
6.3.1.1 distanceBetweenPoints()	16
6.4 main Namespace Reference	16
6.4.1 Variable Documentation	17
6.4.1.1 bFieldGeneratedByOptSF	17

6.4.1.2 conductorThickness	17
6.4.1.3 contour	17
6.4.1.4 contourStep	17
6.4.1.5 gaussOrder	17
6.4.1.6 levelOffset	18
6.4.1.7 materialFactor	18
6.4.1.8 Mesh	18
6.4.1.9 meshFile	18
6.4.1.10 numLevels	18
6.4.1.11 potentialLevelList	18
6.4.1.12 resistanceMatrix	19
6.4.1.13 sensitivityMatrix	19
6.4.1.14 specificConductivityMaterial	19
6.4.1.15 streamFunction	19
6.4.1.16 targetMeshFile	19
6.4.1.17 TargetSphere	19
6.4.1.18 Test	20
6.4.1.19 tikonovFac	20
6.5 readMesh Namespace Reference	20
6.5.1 Function Documentation	20
6.5.1.1 calculateNormal()	20
6.5.1.2 checkIfVecInVecList()	21
6.5.1.3 getMeshFromSTL()	21
6.5.1.4 updateList()	21
6.6 resistanceMatrix Namespace Reference	21
6.6.1 Function Documentation	22
6.6.1.1 calculateArea()	22
6.6.1.2 calculateCurrent()	22
6.6.1.3 compareMultipleElementsBoolean()	22
6.6.1.4 compareMultipleElementsBooleanTest()	22
6.6.1.5 createPreviousResistanceMat()	23
6.6.1.6 elementInAandB()	23
6.6.1.7 elementInArray()	23
6.6.1.8 formFinalResistanceMat()	23
6.6.1.9 getMatElementShouldGetValue()	24
6.6.1.10 getNeighbourhoodMatrix()	24
6.6.1.11 getPartnerElement()	24
6.6.1.12 getResistanceMatrix()	24
6.6.1.13 getResistanceSumForDifferent()	25
6.6.1.14 getResistanceSumForSame()	25
6.6.1.15 getSpatialDistancesMatrix()	25
6.7 sensitivityMatrix Namespace Reference	25

6.7.1 Function Documentation	25
6.7.1.1 calcSensitivityMat()	26
6.7.1.2 calcWeightsGauss()	26
6.7.1.3 gaussLegendreIntegrationPointsTriangle()	26
6.7.1.4 getSensitivityMatrix()	26
6.8 showSTLMesh Namespace Reference	27
6.8.1 Function Documentation	27
6.8.1.1 getMesh()	27
6.8.2 Variable Documentation	27
6.8.2.1 axes	27
6.8.2.2 figure	27
6.8.2.3 givenMesh	28
6.8.2.4 scale	28
6.8.2.5 your_mesh	28
6.9 streamFunctionOptimization Namespace Reference	28
6.9.1 Function Documentation	28
6.9.1.1 applyTikonovRegularisation()	29
6.9.1.2 getBoundaryDetails()	29
6.9.1.3 getDimToRed()	29
6.9.1.4 getNotBoundaryNodes()	29
6.9.1.5 getNumNodesPerBoundary()	30
6.9.1.6 getReducedMat()	30
6.9.1.7 rearrangeReducedMat()	30
6.9.1.8 reduceMatricesForBoundaryNodes()	30
6.9.1.9 reexpandStreamFunctionForBoundaryNodes()	31
6.9.1.10 streamFunctionOptimization()	31
6.9.1.11 updateMeshCurrentDensityMeshFaces()	31
6.10 testCase Namespace Reference	31
6.10.1 Function Documentation	53
6.10.1.1 main()	53
6.10.1.2 test_bFieldGeneratedByOptSF()	53
6.10.1.3 test_finalSF()	53
6.10.1.4 test_gaußLegendre()	54
6.10.1.5 test_matElementsShouldGetValue()	54
6.10.1.6 test_reducedSF()	54
6.10.1.7 test_WeightsGauss()	54
6.10.2 Variable Documentation	54
6.10.2.1 BField	54
6.10.2.2 bFieldCorrectValue	55
6.10.2.3 calcWeightsGaussCorrect	63
6.10.2.4 conductorThickness	63
6.10.2.5 gaussOrder	63

6.10.2.6 gaußLegendreCorrect	64
6.10.2.7 matElementsShouldGetValueCorrect	64
6.10.2.8 materialFactor	74
6.10.2.9 Mesh	74
6.10.2.10 meshFile	74
6.10.2.11 reducedSFCorrect	74
6.10.2.12 resistanceMatrix	76
6.10.2.13 sensitivityMatrix	76
6.10.2.14 SFCorrectValue	76
6.10.2.15 SFOpt	77
6.10.2.16 specificConductivityMaterial	77
6.10.2.17 targetMeshFile	78
6.10.2.18 TargetSphere	78
6.10.2.19 Test	78
6.10.2.20 tikonovFac	78
6.11 Tester Namespace Reference	78
7 Class Documentation	79
7.1 readMesh.CylindricMesh Class Reference	79
7.1.1 Detailed Description	80
7.1.2 Constructor & Destructor Documentation	80
7.1.2.1 __init__()	80
7.1.3 Member Function Documentation	80
7.1.3.1 arrangeCircular()	81
7.1.3.2 calc3DRotMatByVec()	81
7.1.3.3 calcRotationVec()	81
7.1.3.4 checkIfBoundary()	81
7.1.3.5 checkStartTriangle()	82
7.1.3.6 createOneRingList()	82
7.1.3.7 ensureUniformOrientation()	82
7.1.3.8 findStartInBoundaryCase()	82
7.1.3.9 get2Dcoordinates()	83
7.1.3.10 getAreas()	83
7.1.3.11 getBoundaryEdges()	83
7.1.3.12 getBoundaryLoopNodes()	83
7.1.3.13 getCurrent()	84
7.1.3.14 getNeighbourAreas()	84
7.1.3.15 getNeighbourCurrents()	84
7.1.3.16 getNeighbourCurrentsUnsorted()	84
7.1.3.17 getNeighbourTriangleIndices()	85
7.1.3.18 getNormals()	85
7.1.3.19 getOneRingList()	85

7.1.3.20	getOpenBoundaries()	85
7.1.3.21	getRotatedCopy()	86
7.1.3.22	getRotatedVertices()	86
7.1.3.23	getVertexNormals()	86
7.1.3.24	orderElementsInCircularArrangement()	86
7.1.3.25	removeDoubleEdges()	87
7.1.3.26	turnAnsSortElements()	87
7.1.4	Member Data Documentation	87
7.1.4.1	areas	87
7.1.4.2	boundary	87
7.1.4.3	current	87
7.1.4.4	currentDensityFaces	88
7.1.4.5	faces	88
7.1.4.6	neighbourareas	88
7.1.4.7	neighbourcurrents	88
7.1.4.8	neighbourcurrentUnsorted	88
7.1.4.9	neighbours	88
7.1.4.10	normals	89
7.1.4.11	oneRingList	89
7.1.4.12	openBoundaries	89
7.1.4.13	rotatedCaylinder	89
7.1.4.14	v	89
7.1.4.15	vertexNormals	89
7.1.4.16	vertices	90
7.2	readMesh.CylindricMeshGiven Class Reference	90
7.2.1	Detailed Description	90
7.2.2	Constructor & Destructor Documentation	91
7.2.2.1	__init__()	91
7.2.3	Member Data Documentation	91
7.2.3.1	areas	91
7.2.3.2	boundary	91
7.2.3.3	current	91
7.2.3.4	currentDensityFaces	91
7.2.3.5	faces	92
7.2.3.6	neighbourareas	92
7.2.3.7	neighbourcurrents	92
7.2.3.8	neighbourcurrentUnsorted	92
7.2.3.9	neighbours	92
7.2.3.10	normals	92
7.2.3.11	oneRingList	93
7.2.3.12	openBoundaries	93
7.2.3.13	rotatedCaylinder	93

7.2.3.14 v	93
7.2.3.15 vertexNormals	93
7.2.3.16 vertices	93
7.3 showSTLMesh.CylindricMeshGiven Class Reference	94
7.3.1 Detailed Description	94
7.3.2 Constructor & Destructor Documentation	94
7.3.2.1 __init__()	94
7.3.3 Member Data Documentation	94
7.3.3.1 vertices	94
7.4 defineTargetField.TargetField Class Reference	95
7.4.1 Detailed Description	95
7.4.2 Constructor & Destructor Documentation	95
7.4.2.1 __init__()	95
7.4.3 Member Function Documentation	95
7.4.3.1 getMagneticFieldValues()	96
7.4.3.2 getTargetPoints()	96
7.4.4 Member Data Documentation	96
7.4.4.1 center	96
7.4.4.2 fieldValues	96
7.4.4.3 radius	96
7.4.4.4 vertices	97
7.5 defineTargetField.TargetFieldGiven Class Reference	97
7.5.1 Detailed Description	97
7.5.2 Constructor & Destructor Documentation	97
7.5.2.1 __init__()	97
7.5.3 Member Data Documentation	98
7.5.3.1 faces	98
7.5.3.2 fieldValues	98
7.6 Tester.Tester Class Reference	98
7.6.1 Detailed Description	98
7.6.2 Constructor & Destructor Documentation	98
7.6.2.1 __init__()	99
7.6.3 Member Data Documentation	99
7.6.3.1 calcWeightsGauss	99
7.6.3.2 gaußLegendre	99
7.6.3.3 matElementsShouldGetValue	99
7.6.3.4 reducedSF	99
8 File Documentation	101
8.1 main.py File Reference	101
8.2 main.py	102
8.3 README.md File Reference	102

8.4 showSTLMesh.py File Reference	102
8.5 showSTLMesh.py	103
8.6 subfunctions/calcContoursByTriangularPotentialCuts.py File Reference	103
8.7 calcContoursByTriangularPotentialCuts.py	104
8.8 subfunctions/calcPotentialLevels.py File Reference	107
8.9 calcPotentialLevels.py	107
8.10 subfunctions/defineTargetField.py File Reference	108
8.11 defineTargetField.py	108
8.12 subfunctions/readMesh.py File Reference	109
8.13 readMesh.py	109
8.14 subfunctions/resistanceMatrix.py File Reference	114
8.15 resistanceMatrix.py	114
8.16 subfunctions/sensitivityMatrix.py File Reference	116
8.17 sensitivityMatrix.py	116
8.18 subfunctions/streamFunctionOptimization.py File Reference	117
8.19 streamFunctionOptimization.py	118
8.20 subfunctions/testCase.py File Reference	120
8.21 testCase.py	141
8.22 subfunctions/Tester.py File Reference	156
8.23 Tester.py	156
Index	157

Chapter 1

README

1.0.1 Python Implementation

This project is the python implementation of the matlab project: [CoilGen \(https://github.com/Philipp-MR/CoilGen\)](https://github.com/Philipp-MR/CoilGen).

The python project reprogrammed the functionalitys starting in the Heard file: `CoilGen\CoilGen.m`. When the functionality is fine the stucture and the code itself was cleaned up and changes that do not change the results were made.

State 2022-11-07 working was stopped in `calcCountoursByTriangularPotentialCuts.py` (there is a TODO with further explaintation). Until there in a testcase the results are similar to the ones in the matlab implementation. The testcase in Matlab could be found in: `CoilGen\Examples\ygradient_coil.m`.

1.0.2 Testing with Pytest

There is a testcase implemented in [testCase.py](#), on which it could be evaluated if the program still does what it should do. The results there are checked against the ones of the same case in the matlab project. For testing pytest is used.

1. If not already installed run: `pip install -U pytest`
2. To run the tests, navigate to the `Py_Coilgen` folder and run: `pytest`

1.0.3 Citation

For citation of this work, please refer to the following publication: <https://onlinelibrary.wiley.com/doi/10.1002/mrm.29294> <https://doi.org/10.1002/mrm.29294>

([back to top](#))

Chapter 2

Namespace Index

2.1 Package List

Here are the packages with brief descriptions (if available):

calcContoursByTriangularPotentialCuts	11
calcPotentialLevels	15
defineTargetField	16
main	16
readMesh	20
resistanceMatrix	21
sensitivityMatrix	25
showSTLMesh	27
streamFunctionOptimization	28
testCase	31
Tester	78

Chapter 3

Hierarchical Index

3.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

readMesh.CylindricMesh	79
readMesh.CylindricMeshGiven	90
showSTLMesh.CylindricMeshGiven	94
defineTargetField.TargetField	95
defineTargetField.TargetFieldGiven	97
Tester.Tester	98

Chapter 4

Class Index

4.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

readMesh.CylindricMesh	79
readMesh.CylindricMeshGiven	90
showSTLMesh.CylindricMeshGiven	94
defineTargetField.TargetField	95
defineTargetField.TargetFieldGiven	97
Tester.Tester	98

Chapter 5

File Index

5.1 File List

Here is a list of all files with brief descriptions:

main.py	101
showSTLMesh.py	102
subfunctions/calcContoursByTriangularPotentialCuts.py	103
subfunctions/calcPotentialLevels.py	107
subfunctions/defineTargetField.py	108
subfunctions/readMesh.py	109
subfunctions/resistanceMatrix.py	114
subfunctions/sensitivityMatrix.py	116
subfunctions/streamFunctionOptimization.py	117
subfunctions/testCase.py	120
subfunctions/Tester.py	156

Chapter 6

Namespace Documentation

6.1 calcContoursByTriangularPotentialCuts Namespace Reference

Functions

- def [calcContoursByTriangularPotentialCuts](#) (mesh, potentialLevelList, streamFunction)
- def [getuvCutPoints](#) (mesh, innerEdges, edgeLength, potentialCutCriteria, cutPointDistanceToEdgeNode)
- def [getRawUnsortedPoints](#) (potentialLevelList, potentialSortedCutPoints)
- def [getPotentialSortedCutPoints](#) (potentialLevelList, uCutPoint, vCutPoint)
- def [getCutDistancesToEdgeNodes](#) (edgeNodePotentials, potentialLevelList, edgeLength)
- def [getPotentialCutCriteria](#) (edgeNodePotentials, potentialLevelList)
- def [getRawUnarrangedLoops](#) (rawUnsortedPoints, innerEdges, innerEdgeOpposedNode)
- def [checkIfPositionsElementIdenticalWithFirstList](#) (allCurrentEdges, allCurrentOpposedNodes, check↔Position)
- def [getEdgeOpposedNode](#) (mesh, innerEdgesTrianglesInds, innerEdges)
- def [removeTwoElementsFromArray](#) (array, Element1, Element2)
- def [getInnerEdegTriangleNodes](#) (innerEdgesTrianglesInds, mesh)
- def [getInnerEdges](#) (mesh)
- def [getNumAttachedTriangles](#) (edgeAttachedTriangles)
- def [getEdgeAttachedTriangles](#) (edges, mesh)
- def [getEdges](#) (mesh)

6.1.1 Function Documentation

6.1.1.1 calcContoursByTriangularPotentialCuts()

```
def calcContoursByTriangularPotentialCuts.calcContoursByTriangularPotentialCuts (
    mesh,
    potentialLevelList,
    streamFunction )
```

Definition at line 4 of file [calcContoursByTriangularPotentialCuts.py](#).

6.1.1.2 `checkIfPositionsElementIdenticalWithFirstList()`

```
def calcContoursByTriangularPotentialCuts.checkIfPositionsElementIdenticalWithFirstList (
    allCurrentEdges,
    allCurrentOpposedNodes,
    checkPosition )
```

returns lists of elements with booleans if checkPostions Element of first and secound Element are identical wi

Definition at line 142 of file [calcContoursByTriangularPotentialCuts.py](#).

6.1.1.3 `getCutDistancesToEdgeNodes()`

```
def calcContoursByTriangularPotentialCuts.getCutDistancesToEdgeNodes (
    edgeNodePotentials,
    potentialLevelList,
    edgeLength )
```

returns the cutPointDistanceToEdgeNode

Definition at line 57 of file [calcContoursByTriangularPotentialCuts.py](#).

6.1.1.4 `getEdgeAttachedTriangles()`

```
def calcContoursByTriangularPotentialCuts.getEdgeAttachedTriangles (
    edges,
    mesh )
```

returns the attached triangles for each edge.

Definition at line 198 of file [calcContoursByTriangularPotentialCuts.py](#).

6.1.1.5 `getEdgeOpposedNode()`

```
def calcContoursByTriangularPotentialCuts.getEdgeOpposedNode (
    mesh,
    innerEdgesTrianglesInds,
    innerEdges )
```

returns the to the edge opposed node for each attached triangle

Definition at line 156 of file [calcContoursByTriangularPotentialCuts.py](#).

6.1.1.6 getEdges()

```
def calcContoursByTriangularPotentialCuts.getEdges (  
    mesh )
```

returns all edges in the mesh.

Definition at line 209 of file [calcContoursByTriangularPotentialCuts.py](#).

6.1.1.7 getInnerEdegTriangleNodes()

```
def calcContoursByTriangularPotentialCuts.getInnerEdegTriangleNodes (  
    innerEdgesTrianglesInds,  
    mesh )
```

returns the Node Indices for the Triangles.

Definition at line 171 of file [calcContoursByTriangularPotentialCuts.py](#).

6.1.1.8 getInnerEdges()

```
def calcContoursByTriangularPotentialCuts.getInnerEdges (  
    mesh )
```

returns the inner edges an the corresponding triangleInds.

Definition at line 178 of file [calcContoursByTriangularPotentialCuts.py](#).

6.1.1.9 getNumAttachedTriangles()

```
def calcContoursByTriangularPotentialCuts.getNumAttachedTriangles (  
    edgeAttachedTriangles )
```

returns the number of attached triangles per edge.

Definition at line 191 of file [calcContoursByTriangularPotentialCuts.py](#).

6.1.1.10 `getPotentialCutCriteria()`

```
def calcContoursByTriangularPotentialCuts.getPotentialCutCriteria (
    edgeNodePotentials,
    potentialLevelList )
```

returns the PotentialCutCriteria

Definition at line 69 of file [calcContoursByTriangularPotentialCuts.py](#).

6.1.1.11 `getPotentialSortedCutPoints()`

```
def calcContoursByTriangularPotentialCuts.getPotentialSortedCutPoints (
    potentialLevelList,
    uCutPoint,
    vCutPoint )
```

returns potentialSortedCutPoints

Definition at line 46 of file [calcContoursByTriangularPotentialCuts.py](#).

6.1.1.12 `getRawUnarrangedLoops()`

```
def calcContoursByTriangularPotentialCuts.getRawUnarrangedLoops (
    rawUnsortedPoints,
    innerEdges,
    innerEdgeOpposedNode )
```

returns rawUnarrangedLoops

Definition at line 83 of file [calcContoursByTriangularPotentialCuts.py](#).

6.1.1.13 `getRawUnsortedPoints()`

```
def calcContoursByTriangularPotentialCuts.getRawUnsortedPoints (
    potentialLevelList,
    potentialSortedCutPoints )
```

returns rawUnsortedPoints

Definition at line 34 of file [calcContoursByTriangularPotentialCuts.py](#).

6.1.1.14 getuvCutPoints()

```
def calcContoursByTriangularPotentialCuts.getuvCutPoints (
    mesh,
    innerEdges,
    edgeLength,
    potentialCutCriteria,
    cutPointDistanceToEdgeNode )

returns ucutPoint and vCutPoint
```

Definition at line 24 of file [calcContoursByTriangularPotentialCuts.py](#).

6.1.1.15 removeTwoElementsFromArray()

```
def calcContoursByTriangularPotentialCuts.removeTwoElementsFromArray (
    array,
    Element1,
    Element2 )

returns the array without the two elements.
```

Definition at line 167 of file [calcContoursByTriangularPotentialCuts.py](#).

6.2 calcPotentialLevels Namespace Reference

Functions

- def [calcPotentialLevels](#) (streamFunction, numLevels, levelOffset)

6.2.1 Function Documentation

6.2.1.1 calcPotentialLevels()

```
def calcPotentialLevels.calcPotentialLevels (
    streamFunction,
    numLevels,
    levelOffset )
```

returns the contourStep and the potentialLevelList. more options need to be implemented, if there is more than

Definition at line 3 of file [calcPotentialLevels.py](#).

6.3 defineTargetField Namespace Reference

Classes

- class [TargetField](#)
- class [TargetFieldGiven](#)

Functions

- def [distanceBetweenPoints](#) (point1, point2)

6.3.1 Function Documentation

6.3.1.1 distanceBetweenPoints()

```
def defineTargetField.distanceBetweenPoints (
    point1,
    point2 )
```

returns the distance between two given points

Definition at line 43 of file [defineTargetField.py](#).

6.4 main Namespace Reference

Variables

- [Test](#) = Tester()
- string [meshFile](#) = "cylinder_radius500mm_length1500mm.stl"
Input #####
- string [targetMeshFile](#) = "sphere_radius150mm.stl"
- int [gaussOrder](#) = 2
- int [tikonovFac](#) = 100
- float [specificConductivityMaterial](#) = 1.8000*10**-8
- float [conductorThickness](#) = 0.005
- float [materialFactor](#) = [specificConductivityMaterial](#)/[conductorThickness](#)
- int [numLevels](#) = 20
- float [levelOffset](#) = 0.2500
- [Mesh](#) = CylindricMeshGiven([meshFile](#))
- [TargetSphere](#) = TargetFieldGiven([targetMeshFile](#),1)
- [sensitivityMatrix](#) = getSensitivityMatrix([Test](#),[Mesh](#),[TargetSphere](#),[gaussOrder](#))
- [resistanceMatrix](#) = getResistanceMatrix([Test](#),[Mesh](#),[materialFactor](#))
- [bFieldGeneratedByOptSF](#)
- [streamFunction](#)
- [contourStep](#)
- [potentialLevelList](#)
- [contour](#) = calcContoursByTriangluarPotentialCuts([Mesh](#),[potentialLevelList](#),[streamFunction](#))

6.4.1 Variable Documentation

6.4.1.1 bFieldGeneratedByOptSF

```
main.bFieldGeneratedByOptSF
```

Definition at line 43 of file [main.py](#).

6.4.1.2 conductorThickness

```
float main.conductorThickness = 0.005
```

Definition at line 17 of file [main.py](#).

6.4.1.3 contour

```
main.contour = calcContoursByTriangluarPotentialCuts(Mesh,potentialLevellist,streamFunction)
```

Definition at line 49 of file [main.py](#).

6.4.1.4 contourStep

```
main.contourStep
```

Definition at line 46 of file [main.py](#).

6.4.1.5 gaussOrder

```
int main.gaussOrder = 2
```

Definition at line 14 of file [main.py](#).

6.4.1.6 levelOffset

```
float main.levelOffset = 0.2500
```

Definition at line 20 of file [main.py](#).

6.4.1.7 materialFactor

```
float main.materialFactor = specificConductivityMaterial/conductorThickness
```

Definition at line 18 of file [main.py](#).

6.4.1.8 Mesh

```
main.Mesh = CylindricMeshGiven(meshFile)
```

Definition at line 26 of file [main.py](#).

6.4.1.9 meshFile

```
string main.meshFile = "cylinder_radius500mm_length1500mm.stl"
```

Input #####.

Definition at line 12 of file [main.py](#).

6.4.1.10 numLevels

```
int main.numLevels = 20
```

Definition at line 19 of file [main.py](#).

6.4.1.11 potentialLevelList

```
main.potentialLevelList
```

Definition at line 46 of file [main.py](#).

6.4.1.12 resistanceMatrix

```
main.resistanceMatrix = getResistanceMatrix(Test, Mesh, materialFactor)
```

Definition at line 38 of file [main.py](#).

6.4.1.13 sensitivityMatrix

```
main.sensitivityMatrix = getSensitivityMatrix(Test, Mesh, TargetSphere, gaussOrder)
```

Definition at line 35 of file [main.py](#).

6.4.1.14 specificConductivityMaterial

```
float main.specificConductivityMaterial = 1.8000*10**-8
```

Definition at line 16 of file [main.py](#).

6.4.1.15 streamFunction

```
main.streamFunction
```

Definition at line 43 of file [main.py](#).

6.4.1.16 targetMeshFile

```
string main.targetMeshFile = "sphere_radius150mm.stl"
```

Definition at line 13 of file [main.py](#).

6.4.1.17 TargetSphere

```
main.TargetSphere = TargetFieldGiven(targetMeshFile, 1)
```

Definition at line 31 of file [main.py](#).

6.4.1.18 Test

```
main.Test = Tester()
```

Definition at line 9 of file [main.py](#).

6.4.1.19 tikonovFac

```
int main.tikonovFac = 100
```

Definition at line 15 of file [main.py](#).

6.5 readMesh Namespace Reference

Classes

- class [CylindricMesh](#)
- class [CylindricMeshGiven](#)

Functions

- def [calculateNormal](#) (vec)
- def [updateList](#) (edgeList, otheredge)
- def [getMeshFromSTL](#) (filename)
- def [checkIfVecInVecList](#) (node, vecList)

6.5.1 Function Documentation

6.5.1.1 calculateNormal()

```
def readMesh.calculateNormal (  
    vec )
```

returns the norm for a given 3d vector

Definition at line 7 of file [readMesh.py](#).

6.5.1.2 checkIfVecInVecList()

```
def readMesh.checkIfVecInVecList (
    node,
    vecList )
```

returns Boolean if a 3 components vec is in a list of 3 component elements

Definition at line 359 of file [readMesh.py](#).

6.5.1.3 getMeshFromSTL()

```
def readMesh.getMeshFromSTL (
    filename )
```

returns vertices and faces from given stl file meshes

Definition at line 335 of file [readMesh.py](#).

6.5.1.4 updateList()

```
def readMesh.updateList (
    edgeList,
    otheredge )
```

returns the edgeList without otheredge

Definition at line 17 of file [readMesh.py](#).

6.6 resistanceMatrix Namespace Reference

Functions

- def [getResistanceMatrix](#) (test, mesh, materialFactor)
- def [formFinalResistanceMat](#) (resistanceMatrix, materialFactor)
- def [createPreviousResistanceMat](#) (mesh, matElementsShouldGetValue)
- def [getResistanceSumForDifferent](#) (mesh, trianglesWithBothNodes, nodeInd1, nodeInd2)
- def [getResistanceSumForSame](#) (mesh, nodeInd1)
- def [calculateArea](#) (Point1, Point2, Point3)
- def [calculateCurrent](#) (Point1, Point2, Point3)
- def [getMatElementShouldGetValue](#) (mesh)
- def [getPartnerElement](#) (triangle, trianglesWithBothNodes, nodeInd2)
- def [elementInArray](#) (array, value)
- def [elementInAandB](#) (a, b)
- def [compareMultipleElementsBoolean](#) (elements, testelements)
- def [getSpatialDistancesMatrix](#) (mesh)
- def [getNeighbourhoodMatrix](#) (mesh)
- def [compareMultipleElementsBooleanTest](#) ()

6.6.1 Function Documentation

6.6.1.1 calculateArea()

```
def resistanceMatrix.calculateArea (
    Point1,
    Point2,
    Point3 )
```

returns the area of a triangle with 3 given Points

Definition at line 52 of file [resistanceMatrix.py](#).

6.6.1.2 calculateCurrent()

```
def resistanceMatrix.calculateCurrent (
    Point1,
    Point2,
    Point3 )
```

returns the current of a triangle with 3 given Points

Definition at line 56 of file [resistanceMatrix.py](#).

6.6.1.3 compareMultipleElementsBoolean()

```
def resistanceMatrix.compareMultipleElementsBoolean (
    elements,
    testelements )
```

returns a array with boolean elements in the length of elements, True if the value is in testelements False otherwise

Definition at line 94 of file [resistanceMatrix.py](#).

6.6.1.4 compareMultipleElementsBooleanTest()

```
def resistanceMatrix.compareMultipleElementsBooleanTest ( )
```

Test function: should always be True

Definition at line 123 of file [resistanceMatrix.py](#).

6.6.1.5 createPreviousResistanceMat()

```
def resistanceMatrix.createPreviousResistanceMat (
    mesh,
    matElementsShouldGetValue )
```

returns resistanceMatrix mit entries in matElementsShouldGetValue

Definition at line 17 of file [resistanceMatrix.py](#).

6.6.1.6 elementInAandB()

```
def resistanceMatrix.elementInAandB (
    a,
    b )
```

returns a list with elements that are in a and b

Definition at line 87 of file [resistanceMatrix.py](#).

6.6.1.7 elementInArray()

```
def resistanceMatrix.elementInArray (
    array,
    value )
```

returns a list with the elements the contain "value"

Definition at line 79 of file [resistanceMatrix.py](#).

6.6.1.8 formFinalResistanceMat()

```
def resistanceMatrix.formFinalResistanceMat (
    resistanceMatrix,
    materialFactor )
```

returns resistanceMatrix in final form. added with its transposed and multiplied with materialFactor

Definition at line 12 of file [resistanceMatrix.py](#).

6.6.1.9 getMatElementShouldGetValue()

```
def resistanceMatrix.getMatElementShouldGetValue (
    mesh )
```

returns a list with positions in the matix that should get a value (diagonal elements == same nodes and neighbours)

Definition at line 60 of file [resistanceMatrix.py](#).

6.6.1.10 getNeighbourhoodMatrix()

```
def resistanceMatrix.getNeighbourhoodMatrix (
    mesh )
```

returns a boolean matrix with information if node i and node j are neighbours

Definition at line 112 of file [resistanceMatrix.py](#).

6.6.1.11 getPartnerElement()

```
def resistanceMatrix.getPartnerElement (
    triangle,
    trianglesWithBothNodes,
    nodeInd2 )
```

returns the specified triangle both nodes are in from the oneRingList of the other one node. Important because

Definition at line 68 of file [resistanceMatrix.py](#).

6.6.1.12 getResistanceMatrix()

```
def resistanceMatrix.getResistanceMatrix (
    test,
    mesh,
    materialFactor )
```

returns the resistance Matrix for the given mesh

Definition at line 4 of file [resistanceMatrix.py](#).

6.6.1.13 getResistanceSumForDifferent()

```
def resistanceMatrix.getResistanceSumForDifferent (
    mesh,
    trianglesWithBothNodes,
    nodeInd1,
    nodeInd2 )
```

returns resistanceSum for the Case node1 and node2 are different

Definition at line 32 of file [resistanceMatrix.py](#).

6.6.1.14 getResistanceSumForSame()

```
def resistanceMatrix.getResistanceSumForSame (
    mesh,
    nodeInd1 )
```

returns resistanceSum for the Case node1 and node2 are the same

Definition at line 43 of file [resistanceMatrix.py](#).

6.6.1.15 getSpatialDistancesMatrix()

```
def resistanceMatrix.getSpatialDistancesMatrix (
    mesh )
```

returns a matrix containing the spatial distance between node i and node j

Definition at line 104 of file [resistanceMatrix.py](#).

6.7 sensitivityMatrix Namespace Reference

Functions

- def [getSensitivityMatrix](#) (test, mesh, target, n)
- def [calcSensitivityMat](#) (mesh, biotSavatCoeff, target, u, v, gaussWeight)
- def [gaussLegendreIntegrationPointsTriangle](#) (test, n)
- def [calcWeightsGauss](#) (n)

6.7.1 Function Documentation

6.7.1.1 calcSensitivityMat()

```
def sensitivityMatrix.calcSensitivityMat (
    mesh,
    biotSavatCoeff,
    target,
    u,
    v,
    gaussWeight )
```

returns the calculated sensitivityMatrix

Definition at line 12 of file [sensitivityMatrix.py](#).

6.7.1.2 calcWeightsGauss()

```
def sensitivityMatrix.calcWeightsGauss (
    n )
```

returns the abscissa and the weights for a Gauss-Legendre quadrature

Definition at line 56 of file [sensitivityMatrix.py](#).

6.7.1.3 gaussLegendreIntegrationPointsTriangle()

```
def sensitivityMatrix.gaussLegendreIntegrationPointsTriangle (
    test,
    n )
```

returns the weights and the test point for the gauss legendre

Definition at line 43 of file [sensitivityMatrix.py](#).

6.7.1.4 getSensitivityMatrix()

```
def sensitivityMatrix.getSensitivityMatrix (
    test,
    mesh,
    target,
    n )
```

returns the sensitivity Matrix for the mesh

Definition at line 5 of file [sensitivityMatrix.py](#).

6.8 showSTLMesh Namespace Reference

Classes

- class [CylindricMeshGiven](#)

Functions

- def [getMesh](#) (filename)

Variables

- [givenMesh](#) = [CylindricMeshGiven](#)()
- [figure](#) = `pyplot.figure()`
- [axes](#) = `mplot3d.Axes3D(figure)`
- [your_mesh](#) = `mesh.Mesh.from_file('cylinder_radius500mm_length1500mm.stl')`
- [scale](#) = `your_mesh.points.flatten()`

6.8.1 Function Documentation

6.8.1.1 [getMesh\(\)](#)

```
def showSTLMesh.getMesh (  
    filename )
```

Definition at line 6 of file [showSTLMesh.py](#).

6.8.2 Variable Documentation

6.8.2.1 [axes](#)

```
showSTLMesh.axes = mplot3d.Axes3D(figure)
```

Definition at line 23 of file [showSTLMesh.py](#).

6.8.2.2 [figure](#)

```
showSTLMesh.figure = pyplot.figure()
```

Definition at line 22 of file [showSTLMesh.py](#).

6.8.2.3 givenMesh

```
showSTLMesh.givenMesh = CylindricMeshGiven()
```

Definition at line 17 of file [showSTLMesh.py](#).

6.8.2.4 scale

```
showSTLMesh.scale = your_mesh.points.flatten()
```

Definition at line 35 of file [showSTLMesh.py](#).

6.8.2.5 your_mesh

```
showSTLMesh.your_mesh = mesh.Mesh.from_file('cylinder_radius500mm_length1500mm.stl')
```

Definition at line 28 of file [showSTLMesh.py](#).

6.9 streamFunctionOptimization Namespace Reference

Functions

- def [streamFunctionOptimization](#) (test, mesh, target, sensitivityMatrix, resistanceMatrix, tikonovFactor)
- def [applyTikonovRegularisation](#) (tikonovFactor, redSenMat, redResMat, target)
- def [reduceMatricesForBoundaryNodes](#) (mesh, matToRed, zeroFlag)
- def [rearrangeReducedMat](#) (mesh, dimToRed, reducedMat)
- def [getBoundaryDetails](#) (mesh)
- def [getReducedMat](#) (mesh, dimToRed, reducedMat, zeroFlag)
- def [getNotBoundaryNodes](#) (mesh)
- def [getDimToRed](#) (matToRed)
- def [getNumNodesPerBoundary](#) (mesh)
- def [reexpandStreamFunctionForBoundaryNodes](#) (mesh, reducedSF, boundaryNodes, isNotBoundaryNode, zeroFlag)
- def [updateMeshCurrentDensityMeshFaces](#) (mesh, optStreamFkt)

6.9.1 Function Documentation

6.9.1.1 applyTikonovRegularisation()

```
def streamFunctionOptimization.applyTikonovRegularisation (
    tikonovFactor,
    redSenMat,
    redResMat,
    target )
```

returns the StreamFunction for the reduced Matrix with applied trikonov regularisation.

Definition at line 24 of file [streamFunctionOptimization.py](#).

6.9.1.2 getBoundaryDetails()

```
def streamFunctionOptimization.getBoundaryDetails (
    mesh )
```

returns numNodesPerBoundary, notBoundaryNodes, boundaryNodes for the given mesh.

Definition at line 66 of file [streamFunctionOptimization.py](#).

6.9.1.3 getDimToRed()

```
def streamFunctionOptimization.getDimToRed (
    matToRed )
```

returns boolean values which dimension should be reduced

Definition at line 101 of file [streamFunctionOptimization.py](#).

6.9.1.4 getNotBoundaryNodes()

```
def streamFunctionOptimization.getNotBoundaryNodes (
    mesh )
```

returns no-boundary nodes of a given mesh

Definition at line 92 of file [streamFunctionOptimization.py](#).

6.9.1.5 getNumNodesPerBoundary()

```
def streamFunctionOptimization.getNumNodesPerBoundary (
    mesh )
```

returns the number of nodes for every boundary

Definition at line 109 of file [streamFunctionOptimization.py](#).

6.9.1.6 getReducedMat()

```
def streamFunctionOptimization.getReducedMat (
    mesh,
    dimToRed,
    reducedMat,
    zeroFlag )
```

returns the reduced matrix

Definition at line 73 of file [streamFunctionOptimization.py](#).

6.9.1.7 rearrangeReducedMat()

```
def streamFunctionOptimization.rearrangeReducedMat (
    mesh,
    dimToRed,
    reducedMat )
```

rearranges the reduced matrix. returns: reducedMat,boundaryNodes,notBoundaryNodes

Definition at line 41 of file [streamFunctionOptimization.py](#).

6.9.1.8 reduceMatricesForBoundaryNodes()

```
def streamFunctionOptimization.reduceMatricesForBoundaryNodes (
    mesh,
    matToRed,
    zeroFlag )
```

returns the for the boundary nodes reduced matrix

Definition at line 31 of file [streamFunctionOptimization.py](#).

6.9.1.9 reexpandSteamFunctionForBoundaryNodes()

```
def streamFunctionOptimization.reexpandSteamFunctionForBoundaryNodes (
    mesh,
    reducedSF,
    boundaryNodes,
    isNotBoundaryNode,
    zeroFlag )
```

reexpand Streamfunction to all nodes, because the nodes of the first boundary have a potential of zero

Definition at line 116 of file [streamFunctionOptimization.py](#).

6.9.1.10 streamFunctionOptimization()

```
def streamFunctionOptimization.streamFunctionOptimization (
    test,
    mesh,
    target,
    sensitivityMatrix,
    resistanceMatrix,
    tikonovFactor )
```

returns the magnetic field generated by the optimized stream function. Version for only one coil part, else a

Definition at line 4 of file [streamFunctionOptimization.py](#).

6.9.1.11 updateMeshCurrentDensityMeshFaces()

```
def streamFunctionOptimization.updateMeshCurrentDensityMeshFaces (
    mesh,
    optStreamFkt )
```

updates the current density of the Faces in the mesh

Definition at line 128 of file [streamFunctionOptimization.py](#).

6.10 testCase Namespace Reference

Functions

- def [test_finalSF](#) ()
- def [test_bFieldGeneratedByOptSF](#) ()
- def [test_reducedSF](#) ()
- def [test_gaußLegendre](#) ()
- def [test_WeightsGauss](#) ()
- def [test_matElementsShouldGetValue](#) ()
- def [main](#) ()

Variables

- string `meshFile` = "cylinder_radius500mm_length1500mm.stl"
- string `targetMeshFile` = "sphere_radius150mm.stl"
- int `gaussOrder` = 2
- int `tikonovFac` = 100
- float `specificConductivityMaterial` = 1.8000×10^{-8}
- float `conductorThickness` = 0.005
- float `materialFactor` = `specificConductivityMaterial/conductorThickness`
- `Test` = `Tester()`
- `Mesh` = `CylindricMeshGiven(meshFile)`
- `TargetSphere` = `TargetFieldGiven(targetMeshFile,1)`
- `sensitivityMatrix` = `getSensitivityMatrix(Test,Mesh,TargetSphere,gaussOrder)`
- `resistanceMatrix` = `getResistanceMatrix(Test,Mesh,materialFactor)`
- `BField`
- `SFOpt`
- list `matElementsShouldGetValueCorrect` = [0.0000000000, 1.0000000000, 2.0000000000, 3.0000000000, 4.0000000000, 5.0000000000, 6.0000000000, 7.0000000000, 8.0000000000, 9.0000000000, 10.↵
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```

6.10.1 Function Documentation

6.10.1.1 main()

```
def testCase.main ( )
```

Definition at line 62 of file [testCase.py](#).

6.10.1.2 test_bFieldGeneratedByOptSF()

```
def testCase.test_bFieldGeneratedByOptSF ( )
```

Definition at line 30 of file [testCase.py](#).

6.10.1.3 test_finalSF()

```
def testCase.test_finalSF ( )
```

Definition at line 27 of file [testCase.py](#).

6.10.1.4 test_gaußLegendre()

```
def testCase.test_gaußLegendre ( )
```

Definition at line 38 of file [testCase.py](#).

6.10.1.5 test_matElementsShouldGetValue()

```
def testCase.test_matElementsShouldGetValue ( )
```

Definition at line 46 of file [testCase.py](#).

6.10.1.6 test_reducedSF()

```
def testCase.test_reducedSF ( )
```

Definition at line 33 of file [testCase.py](#).

6.10.1.7 test_WeightsGauss()

```
def testCase.test_WeightsGauss ( )
```

Definition at line 41 of file [testCase.py](#).

6.10.2 Variable Documentation

6.10.2.1 BField

```
testCase.BField
```

Definition at line 23 of file [testCase.py](#).

6.10.2.2 bFieldCorrectValue

```
list testCase.bFieldCorrectValue = [[-0.00000466916987661623140515657, -0.00000469774735703660250055961,
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0.00010950145260021515328328207]]
```

Definition at line 60 of file [testCase.py](#).

6.10.2.3 calcWeightsGaussCorrect

```
list testCase.calcWeightsGaussCorrect = [[-0.5773502691896257310588680, 0.5773502691896257310588680], [1.↵
0000000000000004440892099, 1.0000000000000004440892099]]
```

Definition at line 52 of file [testCase.py](#).

6.10.2.4 conductorThickness

```
float testCase.conductorThickness = 0.005
```

Definition at line 15 of file [testCase.py](#).

6.10.2.5 gaussOrder

```
int testCase.gaussOrder = 2
```

Definition at line 12 of file [testCase.py](#).

6.10.2.6 gaußLegendreCorrect

```
list testCase.gaußLegendreCorrect = [[0.21132486540518713, 0.21132486540518713, 0.7886751345948129,  
0.7886751345948129], [0.16666666666666669, 0.6220084679281462, 0.044658198738520456, 0.↵  
16666666666666669], [0.19716878364870338, 0.19716878364870338, 0.052831216351296825, 0.↵  
052831216351296825]]
```

Definition at line 54 of file [testCase.py](#).

6.10.2.7 matElementsShouldGetValueCorrect

```
list testCase.matElementsShouldGetValueCorrect = [0.0000000000, 1.0000000000, 2.0000000000,  
3.0000000000, 4.0000000000, 5.0000000000, 6.0000000000, 7.0000000000, 8.0000000000, 9.0000000000,  
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Generated by Doxygen

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Definition at line 50 of file [testCase.py](#).

6.10.2.8 materialFactor

```
float testCase.materialFactor = specificConductivityMaterial/conductorThickness
```

Definition at line 16 of file [testCase.py](#).

6.10.2.9 Mesh

```
testCase.Mesh = CylindricMeshGiven(meshFile)
```

Definition at line 19 of file [testCase.py](#).

6.10.2.10 meshFile

```
string testCase.meshFile = "cylinder_radius500mm_length1500mm.stl"
```

Definition at line 10 of file [testCase.py](#).

6.10.2.11 reducedSFCorrect

```
list testCase.reducedSFCorrect = [-0.27937980331459932870075136, -0.33966732733873783445233130,
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57.04436608707574407617357792, 157.96464661316298361271037720, 111.31922987220724508006242104]

Definition at line 56 of file [testCase.py](#).

6.10.2.12 resistanceMatrix

```
testCase.resistanceMatrix = getResistanceMatrix(Test,Mesh,materialFactor)
```

Definition at line 22 of file [testCase.py](#).

6.10.2.13 sensitivityMatrix

```
testCase.sensitivityMatrix = getSensitivityMatrix(Test,Mesh,TargetSphere,gaussOrder)
```

Definition at line 21 of file [testCase.py](#).

6.10.2.14 SFCorrectValue

```
list testCase.SFCorrectValue = [-0.27937980331459933, 158.30535989173870348, -0.27937980331459933,
111.95922396290268352, 58.10903859010657158, -0.27937980331459933, 193.39790162602255919,
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111.31922987220724508, -0.33966732733873783, -0.33966732733873783, -0.33966732733873783]
```

Definition at line 58 of file [testCase.py](#).

6.10.2.15 SFOpt

```
testCase.SFOpt
```

Definition at line 23 of file [testCase.py](#).

6.10.2.16 specificConductivityMaterial

```
float testCase.specificConductivityMaterial = 1.8000*10**-8
```

Definition at line 14 of file [testCase.py](#).

6.10.2.17 targetMeshFile

```
string testCase.targetMeshFile = "sphere_radius150mm.stl"
```

Definition at line 11 of file [testCase.py](#).

6.10.2.18 TargetSphere

```
testCase.TargetSphere = TargetFieldGiven(targetMeshFile,1)
```

Definition at line 20 of file [testCase.py](#).

6.10.2.19 Test

```
testCase.Test = Tester()
```

Definition at line 18 of file [testCase.py](#).

6.10.2.20 tikonovFac

```
int testCase.tikonovFac = 100
```

Definition at line 13 of file [testCase.py](#).

6.11 Tester Namespace Reference

Classes

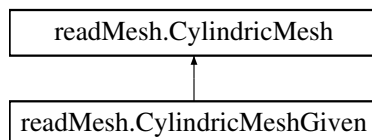
- class [Tester](#)

Chapter 7

Class Documentation

7.1 readMesh.CylindricMesh Class Reference

Inheritance diagram for readMesh.CylindricMesh:



Public Member Functions

- def `__init__` (self, coilLength, coilRadius, n)
- def `checkIfBoundary` (self)
- def `getVertexNormals` (self)
- def `getNormals` (self)
- def `getNeighbourAreas` (self)
- def `getNeighbourCurrents` (self)
- def `getNeighbourCurrentsUnsorted` (self)
- def `getCurrent` (self)
- def `getAreas` (self)
- def `getOpenBoundaries` (self)
- def `getBoundaryEdges` (self)
- def `removeDoubleEdges` (self, edgeList)
- def `getBoundaryLoopNodes` (self)
- def `getRotatedCopy` (self)
- def `getRotatedVertices` (self, rotMat)
- def `calcRotationVec` (self, boundaryLoopNodes)
- def `calc3DRotMatByVec` (self, rotationVec, angle)
- def `turnAnsSortElements` (self, boundaryEdges)
- def `get2Dcoordinates` (self)
- def `getNeighbourTriangleIndices` (self)
- def `getOneRingList` (self)
- def `orderElementsInCircularArangement` (self, oneRingList)
- def `arrangeCircular` (self, start, Elements)
- def `findStartInBoundaryCase` (self, oneRingList, nodeNumber)
- def `checkStartTriangle` (self, verticeTriangles, start)
- def `createOneRingList` (self)
- def `ensureUniformOrientation` (self, oneRingList)

Public Attributes

- [faces](#)
- [vertices](#)
- [normals](#)
- [openBoundaries](#)
- [areas](#)
- [current](#)
- [neighbours](#)
- [rotatedCylinder](#)
- [v](#)
- [neighbourareas](#)
- [currentDensityFaces](#)
- [vertexNormals](#)
- [boundary](#)
- [oneRingList](#)
- [neighbourcurrents](#)
- [neighbourcurrentUnsorted](#)

7.1.1 Detailed Description

Definition at line [22](#) of file [readMesh.py](#).

7.1.2 Constructor & Destructor Documentation

7.1.2.1 `__init__()`

```
def readMesh.CylindricMesh.__init__ (
    self,
    coilLength,
    coilRadius,
    n )
```

Reimplemented in [readMesh.CylindricMeshGiven](#).

Definition at line [23](#) of file [readMesh.py](#).

7.1.3 Member Function Documentation

7.1.3.1 arrangeCircular()

```
def readMesh.CylindricMesh.arrangeCircular (
    self,
    start,
    Elements )
```

returns the elements in a circular order beginning with start

Definition at line 273 of file [readMesh.py](#).

7.1.3.2 calc3DRotMatByVec()

```
def readMesh.CylindricMesh.calc3DRotMatByVec (
    self,
    rotationVec,
    angle )
```

returns the rotation matrix calculated from the rotationVector

Definition at line 191 of file [readMesh.py](#).

7.1.3.3 calcRotationVec()

```
def readMesh.CylindricMesh.calcRotationVec (
    self,
    boundaryLoopNodes )
```

returns the rotationVector and the angle based on the boundaryLoopNodes.

Definition at line 179 of file [readMesh.py](#).

7.1.3.4 checkIfBoundary()

```
def readMesh.CylindricMesh.checkIfBoundary (
    self )
```

returns a list of boolean if the vertice is a boundary vertice

Definition at line 41 of file [readMesh.py](#).

7.1.3.5 checkStartTriangle()

```
def readMesh.CylindricMesh.checkStartTriangle (
    self,
    verticeTriangles,
    start )
```

returns boolean if "start" is the correct startTriangle

Definition at line 295 of file [readMesh.py](#).

7.1.3.6 createOneRingList()

```
def readMesh.CylindricMesh.createOneRingList (
    self )
```

returns a list with the other two triangle Points for each triangle per node

Definition at line 302 of file [readMesh.py](#).

7.1.3.7 ensureUniformOrientation()

```
def readMesh.CylindricMesh.ensureUniformOrientation (
    self,
    oneRingList )
```

returns oneRingList with ensured uniform Orientation

Definition at line 317 of file [readMesh.py](#).

7.1.3.8 findStartInBoundaryCase()

```
def readMesh.CylindricMesh.findStartInBoundaryCase (
    self,
    oneRingList,
    nodeNumber )
```

returns the correct start triangle for ordering the triangles around a boundary vertice

Definition at line 284 of file [readMesh.py](#).

7.1.3.9 get2Dcoordinates()

```
def readMesh.CylindricMesh.get2Dcoordinates (
    self )
```

returns the from 3D to 2D converted vertices

Definition at line 231 of file [readMesh.py](#).

7.1.3.10 getAreas()

```
def readMesh.CylindricMesh.getAreas (
    self )
```

returns the areas of the triangles made with the points in faces

Definition at line 103 of file [readMesh.py](#).

7.1.3.11 getBoundaryEdges()

```
def readMesh.CylindricMesh.getBoundaryEdges (
    self )
```

returns the nodes for each boundary in the correct order

Definition at line 130 of file [readMesh.py](#).

7.1.3.12 getBoundaryLoopNodes()

```
def readMesh.CylindricMesh.getBoundaryLoopNodes (
    self )
```

returns the unsorted nodes for the boundaryLoop.

Definition at line 153 of file [readMesh.py](#).

7.1.3.13 `getCurrent()`

```
def readMesh.CylindricMesh.getCurrent (
    self )
```

returns the current for the triangles made with the points in faces
 $C = (c-b)/(2*Fläche)$

Definition at line 95 of file [readMesh.py](#).

7.1.3.14 `getNeighbourAreas()`

```
def readMesh.CylindricMesh.getNeighbourAreas (
    self )
```

returns the areas of the neighbour triangles for every node

Definition at line 65 of file [readMesh.py](#).

7.1.3.15 `getNeighbourCurrents()`

```
def readMesh.CylindricMesh.getNeighbourCurrents (
    self )
```

returns the currents of the neighbour triangles for every node

Definition at line 75 of file [readMesh.py](#).

7.1.3.16 `getNeighbourCurrentsUnsorted()`

```
def readMesh.CylindricMesh.getNeighbourCurrentsUnsorted (
    self )
```

returns the currents of the neighbour triangles for every node before sorting

Definition at line 85 of file [readMesh.py](#).

7.1.3.17 getNeighbourTriangleIndices()

```
def readMesh.CylindricMesh.getNeighbourTriangleIndices (
    self )
```

returns the indices of the neighbour triangles of every node

Definition at line 242 of file [readMesh.py](#).

7.1.3.18 getNormals()

```
def readMesh.CylindricMesh.getNormals (
    self )
```

returns the normals of the faces

Definition at line 58 of file [readMesh.py](#).

7.1.3.19 getOneRingList()

```
def readMesh.CylindricMesh.getOneRingList (
    self )
```

returns sorted list with nodes around every node

Definition at line 254 of file [readMesh.py](#).

7.1.3.20 getOpenBoundaries()

```
def readMesh.CylindricMesh.getOpenBoundaries (
    self )
```

returns indexes of the nodes at the edges of a cylinder extended in z-direction

Definition at line 110 of file [readMesh.py](#).

7.1.3.21 getRotatedCopy()

```
def readMesh.CylindricMesh.getRotatedCopy (
    self )
```

returns rotated copy of the vertices. If the cylinder is orientated along the z axis we need a rotated copy.

Definition at line 164 of file [readMesh.py](#).

7.1.3.22 getRotatedVertices()

```
def readMesh.CylindricMesh.getRotatedVertices (
    self,
    rotMat )
```

returns the rotated vertices (multiplication with rotMat).

Definition at line 172 of file [readMesh.py](#).

7.1.3.23 getVertexNormals()

```
def readMesh.CylindricMesh.getVertexNormals (
    self )
```

returns the normals of the vertices. These are calculated as average of the touching faces normals.

Definition at line 48 of file [readMesh.py](#).

7.1.3.24 orderElementsInCircularArrangement()

```
def readMesh.CylindricMesh.orderElementsInCircularArrangement (
    self,
    oneRingList )
```

returns the List in a circular arrangement

Definition at line 261 of file [readMesh.py](#).

7.1.3.25 removeDoubleEdges()

```
def readMesh.CylindricMesh.removeDoubleEdges (
    self,
    edgeList )
```

returns the edgeList with each edge just once.

Definition at line 144 of file [readMesh.py](#).

7.1.3.26 turnAnsSortElements()

```
def readMesh.CylindricMesh.turnAnsSortElements (
    self,
    boundaryEdges )
```

returns the given list in sorted. If needed single elements were turned to close the loop.

Definition at line 209 of file [readMesh.py](#).

7.1.4 Member Data Documentation

7.1.4.1 areas

`readMesh.CylindricMesh.areas`

Definition at line 28 of file [readMesh.py](#).

7.1.4.2 boundary

`readMesh.CylindricMesh.boundary`

Definition at line 36 of file [readMesh.py](#).

7.1.4.3 current

`readMesh.CylindricMesh.current`

Definition at line 29 of file [readMesh.py](#).

7.1.4.4 `currentDensityFaces`

`readMesh.CylindricMesh.currentDensityFaces`

Definition at line 34 of file [readMesh.py](#).

7.1.4.5 `faces`

`readMesh.CylindricMesh.faces`

Definition at line 24 of file [readMesh.py](#).

7.1.4.6 `neighbourareas`

`readMesh.CylindricMesh.neighbourareas`

Definition at line 33 of file [readMesh.py](#).

7.1.4.7 `neighbourcurrents`

`readMesh.CylindricMesh.neighbourcurrents`

Definition at line 38 of file [readMesh.py](#).

7.1.4.8 `neighbourcurrentUnsorted`

`readMesh.CylindricMesh.neighbourcurrentUnsorted`

Definition at line 39 of file [readMesh.py](#).

7.1.4.9 `neighbours`

`readMesh.CylindricMesh.neighbours`

Definition at line 30 of file [readMesh.py](#).

7.1.4.10 normals

`readMesh.CylindricMesh.normals`

Definition at line 26 of file [readMesh.py](#).

7.1.4.11 oneRingList

`readMesh.CylindricMesh.oneRingList`

Definition at line 37 of file [readMesh.py](#).

7.1.4.12 openBoundaries

`readMesh.CylindricMesh.openBoundaries`

Definition at line 27 of file [readMesh.py](#).

7.1.4.13 rotatedCaylinder

`readMesh.CylindricMesh.rotatedCaylinder`

Definition at line 31 of file [readMesh.py](#).

7.1.4.14 v

`readMesh.CylindricMesh.v`

Definition at line 32 of file [readMesh.py](#).

7.1.4.15 vertexNormals

`readMesh.CylindricMesh.vertexNormals`

Definition at line 35 of file [readMesh.py](#).

7.1.4.16 vertices

`readMesh.CylindricMesh.vertices`

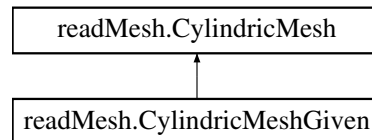
Definition at line 25 of file [readMesh.py](#).

The documentation for this class was generated from the following file:

- subfunctions/[readMesh.py](#)

7.2 readMesh.CylindricMeshGiven Class Reference

Inheritance diagram for `readMesh.CylindricMeshGiven`:



Public Member Functions

- `def __init__` (self, filename)

Public Attributes

- [faces](#)
- [vertices](#)
- [normals](#)
- [openBoundaries](#)
- [areas](#)
- [current](#)
- [neighbours](#)
- [rotatedCaylinder](#)
- [v](#)
- [neighbourareas](#)
- [currentDensityFaces](#)
- [vertexNormals](#)
- [boundary](#)
- [oneRingList](#)
- [neighbourcurrents](#)
- [neighbourcurrentUnsorted](#)

7.2.1 Detailed Description

Definition at line 340 of file [readMesh.py](#).

7.2.2 Constructor & Destructor Documentation

7.2.2.1 `__init__()`

```
def readMesh.CylindricMeshGiven.__init__ (
    self,
    filename )
```

Reimplemented from [readMesh.CylindricMesh](#).

Definition at line 341 of file [readMesh.py](#).

7.2.3 Member Data Documentation

7.2.3.1 `areas`

```
readMesh.CylindricMeshGiven.areas
```

Definition at line 346 of file [readMesh.py](#).

7.2.3.2 `boundary`

```
readMesh.CylindricMeshGiven.boundary
```

Definition at line 354 of file [readMesh.py](#).

7.2.3.3 `current`

```
readMesh.CylindricMeshGiven.current
```

Definition at line 347 of file [readMesh.py](#).

7.2.3.4 `currentDensityFaces`

```
readMesh.CylindricMeshGiven.currentDensityFaces
```

Definition at line 352 of file [readMesh.py](#).

7.2.3.5 faces

`readMesh.CylindricMeshGiven.faces`

Definition at line [342](#) of file [readMesh.py](#).

7.2.3.6 neighbourareas

`readMesh.CylindricMeshGiven.neighbourareas`

Definition at line [351](#) of file [readMesh.py](#).

7.2.3.7 neighbourcurrents

`readMesh.CylindricMeshGiven.neighbourcurrents`

Definition at line [356](#) of file [readMesh.py](#).

7.2.3.8 neighbourcurrentUnsorted

`readMesh.CylindricMeshGiven.neighbourcurrentUnsorted`

Definition at line [357](#) of file [readMesh.py](#).

7.2.3.9 neighbours

`readMesh.CylindricMeshGiven.neighbours`

Definition at line [348](#) of file [readMesh.py](#).

7.2.3.10 normals

`readMesh.CylindricMeshGiven.normals`

Definition at line [344](#) of file [readMesh.py](#).

7.2.3.11 oneRingList

`readMesh.CylindricMeshGiven.oneRingList`

Definition at line 355 of file [readMesh.py](#).

7.2.3.12 openBoundaries

`readMesh.CylindricMeshGiven.openBoundaries`

Definition at line 345 of file [readMesh.py](#).

7.2.3.13 rotatedCaylinder

`readMesh.CylindricMeshGiven.rotatedCaylinder`

Definition at line 349 of file [readMesh.py](#).

7.2.3.14 v

`readMesh.CylindricMeshGiven.v`

Definition at line 350 of file [readMesh.py](#).

7.2.3.15 vertexNormals

`readMesh.CylindricMeshGiven.vertexNormals`

Definition at line 353 of file [readMesh.py](#).

7.2.3.16 vertices

`readMesh.CylindricMeshGiven.vertices`

Definition at line 343 of file [readMesh.py](#).

The documentation for this class was generated from the following file:

- subfunctions/[readMesh.py](#)

7.3 showSTLMesh.CylindricMeshGiven Class Reference

Public Member Functions

- `def __init__(self)`

Public Attributes

- `vertices`

7.3.1 Detailed Description

Definition at line 12 of file [showSTLMesh.py](#).

7.3.2 Constructor & Destructor Documentation

7.3.2.1 `__init__()`

```
def showSTLMesh.CylindricMeshGiven.__init__ (
    self )
```

Definition at line 13 of file [showSTLMesh.py](#).

7.3.3 Member Data Documentation

7.3.3.1 `vertices`

```
showSTLMesh.CylindricMeshGiven.vertices
```

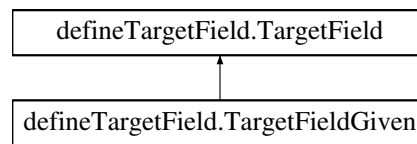
Definition at line 14 of file [showSTLMesh.py](#).

The documentation for this class was generated from the following file:

- [showSTLMesh.py](#)

7.4 `defineTargetField.TargetField` Class Reference

Inheritance diagram for `defineTargetField.TargetField`:



Public Member Functions

- `def __init__` (self, [center](#), [radius](#), direction)
- `def getTargetPoints` (self)
- `def getMagneticFieldValues` (self, direction)

Public Attributes

- [center](#)
- [radius](#)
- [vertices](#)
- [fieldValues](#)

7.4.1 Detailed Description

Definition at line 8 of file [defineTargetField.py](#).

7.4.2 Constructor & Destructor Documentation

7.4.2.1 `__init__()`

```
def defineTargetField.TargetField.__init__ (
    self,
    center,
    radius,
    direction )
```

Reimplemented in [defineTargetField.TargetFieldGiven](#).

Definition at line 9 of file [defineTargetField.py](#).

7.4.3 Member Function Documentation

7.4.3.1 `getMagneticFieldValues()`

```
def defineTargetField.TargetField.getMagneticFieldValues (
    self,
    direction )
```

returns magnetic field values analogous to matlab skript

Definition at line 30 of file [defineTargetField.py](#).

7.4.3.2 `getTargetPoints()`

```
def defineTargetField.TargetField.getTargetPoints (
    self )
```

generate Target Points within a circle with the given specifications

Definition at line 15 of file [defineTargetField.py](#).

7.4.4 Member Data Documentation

7.4.4.1 `center`

`defineTargetField.TargetField.center`

Definition at line 10 of file [defineTargetField.py](#).

7.4.4.2 `fieldValues`

`defineTargetField.TargetField.fieldValues`

Definition at line 13 of file [defineTargetField.py](#).

7.4.4.3 `radius`

`defineTargetField.TargetField.radius`

Definition at line 11 of file [defineTargetField.py](#).

7.4.4.4 vertices

`defineTargetField.TargetField.vertices`

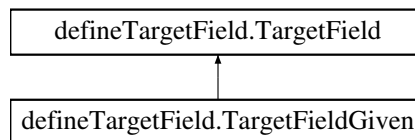
Definition at line 12 of file [defineTargetField.py](#).

The documentation for this class was generated from the following file:

- [subfunctions/defineTargetField.py](#)

7.5 defineTargetField.TargetFieldGiven Class Reference

Inheritance diagram for `defineTargetField.TargetFieldGiven`:



Public Member Functions

- `def __init__(self, filename, direction)`

Public Attributes

- [faces](#)
- [fieldValues](#)

7.5.1 Detailed Description

Definition at line 38 of file [defineTargetField.py](#).

7.5.2 Constructor & Destructor Documentation

7.5.2.1 `__init__()`

```
def defineTargetField.TargetFieldGiven.__init__ (
    self,
    filename,
    direction )
```

Reimplemented from [defineTargetField.TargetField](#).

Definition at line 39 of file [defineTargetField.py](#).

7.5.3 Member Data Documentation

7.5.3.1 faces

`defineTargetField.TargetFieldGiven.faces`

Definition at line 40 of file [defineTargetField.py](#).

7.5.3.2 fieldValues

`defineTargetField.TargetFieldGiven.fieldValues`

Definition at line 41 of file [defineTargetField.py](#).

The documentation for this class was generated from the following file:

- [subfunctions/defineTargetField.py](#)

7.6 Tester.Tester Class Reference

Public Member Functions

- `def __init__(self)`

Public Attributes

- [gaußLegendre](#)
- [reducedSF](#)
- [calcWeightsGauss](#)
- [matElementsShouldGetValue](#)

7.6.1 Detailed Description

Definition at line 1 of file [Tester.py](#).

7.6.2 Constructor & Destructor Documentation

7.6.2.1 `__init__()`

```
def Tester.Tester.__init__ (
    self )
```

Definition at line 2 of file [Tester.py](#).

7.6.3 Member Data Documentation

7.6.3.1 `calcWeightsGauss`

`Tester.Tester.calcWeightsGauss`

Definition at line 5 of file [Tester.py](#).

7.6.3.2 `gaußLegendre`

`Tester.Tester.gaußLegendre`

Definition at line 3 of file [Tester.py](#).

7.6.3.3 `matElementsShouldGetValue`

`Tester.Tester.matElementsShouldGetValue`

Definition at line 6 of file [Tester.py](#).

7.6.3.4 `reducedSF`

`Tester.Tester.reducedSF`

Definition at line 4 of file [Tester.py](#).

The documentation for this class was generated from the following file:

- subfunctions/[Tester.py](#)

Chapter 8

File Documentation

8.1 main.py File Reference

Namespaces

- namespace [main](#)

Variables

- [main.Test](#) = `Tester()`
- string [main.meshFile](#) = "cylinder_radius500mm_length1500mm.stl"
Input #####.
- string [main.targetMeshFile](#) = "sphere_radius150mm.stl"
- int [main.gaussOrder](#) = 2
- int [main.tikonovFac](#) = 100
- float [main.specificConductivityMaterial](#) = 1.8000×10^{-8}
- float [main.conductorThickness](#) = 0.005
- float [main.materialFactor](#) = `specificConductivityMaterial/conductorThickness`
- int [main.numLevels](#) = 20
- float [main.levelOffset](#) = 0.2500
- [main.Mesh](#) = `CylindricMeshGiven(meshFile)`
- [main.TargetSphere](#) = `TargetFieldGiven(targetMeshFile,1)`
- [main.sensitivityMatrix](#) = `getSensitivityMatrix(Test,Mesh,TargetSphere,gaussOrder)`
- [main.resistanceMatrix](#) = `getResistanceMatrix(Test,Mesh,materialFactor)`
- [main.bFieldGeneratedByOptSF](#)
- [main.streamFunction](#)
- [main.contourStep](#)
- [main.potentialLevelList](#)
- [main.contour](#) = `calcContoursByTriangluarPotentialCuts(Mesh,potentialLevelList,streamFunction)`

8.2 main.py

[Go to the documentation of this file.](#)

```

00001 import numpy as np
00002 from decimal import *
00003 import sys
00004 sys.path.append('subfunctions/')
00005
00006
00007
00008 from subfunctions.Tester import Tester
00009 Test = Tester()
00010
00011
00012 meshFile = "cylinder_radius500mm_length1500mm.stl" #insert Filename of stl mesh or False here
00013 targetMeshFile = "sphere_radius150mm.stl" #insert Filename of stl mesh or False here
00014 gaussOrder = 2
00015 tikonovFac = 100
00016 specificConductivityMaterial = 1.8000*10**-8
00017 conductorThickness = 0.005
00018 materialFactor = specificConductivityMaterial/conductorThickness
00019 numLevels = 20
00020 levelOffset = 0.2500
00021
00022
00023
00024 from subfunctions.readMesh import CylindricMesh,CylindricMeshGiven
00025 if meshFile:
00026     Mesh = CylindricMeshGiven(meshFile)
00027 else: Mesh = CylindricMesh(5.0,3.0,10)
00028
00029 from subfunctions.defineTargetField import TargetField,TargetFieldGiven
00030 if targetMeshFile:
00031     TargetSphere = TargetFieldGiven(targetMeshFile,1)
00032 else: TargetSphere = TargetField([0,0,0],4,1)
00033
00034 from subfunctions.sensitivityMatrix import getSensitivityMatrix
00035 sensitivityMatrix = getSensitivityMatrix(Test,Mesh,TargetSphere,gaussOrder)
00036
00037 from subfunctions.resistanceMatrix import getResistanceMatrix
00038 resistanceMatrix = getResistanceMatrix(Test,Mesh,materialFactor)
00039
00040
00041
00042 from subfunctions.streamFunctionOptimization import streamFunctionOptimization
00043 bFieldGeneratedByOptSF,streamFunction =
00044     streamFunctionOptimization(Test,Mesh,TargetSphere,sensitivityMatrix,resistanceMatrix,tikonovFac)
00045
00046 from subfunctions.calcPotentialLevels import calcPotentialLevels
00047 contourStep, potentialLevelList = calcPotentialLevels(streamFunction, numLevels, levelOffset)
00048
00049 from subfunctions.calcContoursByTriangularPotentialCuts import calcContoursByTriangularPotentialCuts
00050 contour = calcContoursByTriangularPotentialCuts(Mesh,potentialLevelList,streamFunction)
00051
00052 # topological contour sorting
00053
00054 # opening and interconnection wires
00055
00056
00057 # plots
00058
00059 # ouput for 3D

```

8.3 README.md File Reference

8.4 showSTLMesh.py File Reference

Classes

- class [showSTLMesh.CylindricMeshGiven](#)

Namespaces

- namespace [showSTLMesh](#)

Functions

- def [showSTLMesh.getMesh](#) (filename)

Variables

- [showSTLMesh.givenMesh](#) = CylindricMeshGiven()
- [showSTLMesh.figure](#) = pyplot.figure()
- [showSTLMesh.axes](#) = mplot3d.Axes3D(figure)
- [showSTLMesh.your_mesh](#) = mesh.Mesh.from_file('cylinder_radius500mm_length1500mm.stl')
- [showSTLMesh.scale](#) = your_mesh.points.flatten()

8.5 showSTLMesh.py

[Go to the documentation of this file.](#)

```
00001 import numpy as np
00002 from stl import mesh
00003 from mpl_toolkits import mplot3d
00004 from matplotlib import pyplot
00005
00006 def getMesh(filename):
00007     your_mesh = mesh.Mesh.from_file(filename)
00008     normals = your_mesh.normals
00009     vertices = [your_mesh.v0, your_mesh.v1, your_mesh.v2]
00010     return normals, vertices
00011
00012 class CylindricMeshGiven():
00013     def __init__(self):
00014         self.normals, self.vertices = getMesh('cylinder_radius500mm_length1500mm.stl')
00015
00016
00017 givenMesh = CylindricMeshGiven()
00018 print("mesh", givenMesh.normals)
00019
00020
00021 # Create a new plot
00022 figure = pyplot.figure()
00023 axes = mplot3d.Axes3D(figure)
00024
00025 # Using an existing stl file:
00026
00027
00028 your_mesh = mesh.Mesh.from_file('cylinder_radius500mm_length1500mm.stl')
00029
00030 print(your_mesh.normals)
00031 axes.add_collection3d(mplot3d.art3d.Poly3DCollection(your_mesh.vectors))
00032
00033
00034 # Auto scale to the mesh size
00035 scale = your_mesh.points.flatten()
00036 axes.auto_scale_xyz(scale, scale, scale)
00037
00038 # Show the plot to the screen
00039 pyplot.show()
```

8.6 subfunctions/calcContoursByTriangularPotentialCuts.py File Reference

Namespaces

- namespace [calcContoursByTriangularPotentialCuts](#)

Functions

- def [calcContoursByTriangularPotentialCuts.calcContoursByTriangularPotentialCuts](#) (mesh, potentialLevelList, streamFunction)
- def [calcContoursByTriangularPotentialCuts.getuvCutPoints](#) (mesh, innerEdges, edgeLength, potentialCutCriteria, cutPointDistanceToEdgeNode)
- def [calcContoursByTriangularPotentialCuts.getRawUnsortedPoints](#) (potentialLevelList, potentialSortedCutPoints)
- def [calcContoursByTriangularPotentialCuts.getPotentialSortedCutPoints](#) (potentialLevelList, uCutPoint, vCutPoint)
- def [calcContoursByTriangularPotentialCuts.getCutDistancesToEdgeNodes](#) (edgeNodePotentials, potentialLevelList, edgeLength)
- def [calcContoursByTriangularPotentialCuts.getPotentialCutCriteria](#) (edgeNodePotentials, potentialLevelList)
- def [calcContoursByTriangularPotentialCuts.getRawUnarrangedLoops](#) (rawUnsortedPoints, innerEdges, innerEdgeOpposedNode)
- def [calcContoursByTriangularPotentialCuts.checkIfPositionsElementIdenticalWithFirstList](#) (allCurrentEdges, allCurrentOpposedNodes, checkPosition)
- def [calcContoursByTriangularPotentialCuts.getEdgeOpposedNode](#) (mesh, innerEdgesTrianglesInds, innerEdges)
- def [calcContoursByTriangularPotentialCuts.removeTwoElementsFromArray](#) (array, Element1, Element2)
- def [calcContoursByTriangularPotentialCuts.getInnerEdgeTriangleNodes](#) (innerEdgesTrianglesInds, mesh)
- def [calcContoursByTriangularPotentialCuts.getInnerEdges](#) (mesh)
- def [calcContoursByTriangularPotentialCuts.getNumAttachedTriangles](#) (edgeAttachedTriangles)
- def [calcContoursByTriangularPotentialCuts.getEdgeAttachedTriangles](#) (edges, mesh)
- def [calcContoursByTriangularPotentialCuts.getEdges](#) (mesh)

8.7 calcContoursByTriangularPotentialCuts.py

[Go to the documentation of this file.](#)

```
00001 import numpy as np
00002 from readMesh import updateList
00003
00004 def calcContoursByTriangularPotentialCuts(mesh, potentialLevelList, streamFunction):
00005
00006     innerEdges, innerEdgesTrianglesInds = getInnerEdges(mesh)
00007     innerEdgeOpposedNode = getEdgeOpposedNode(mesh, innerEdgesTrianglesInds, innerEdges)
00008
00009     edgeNodePotentials = streamFunction[innerEdges]
00010     potentialCutCriteria = getPotentialCutCriteria(edgeNodePotentials, potentialLevelList)
00011     edgeLength = np.sqrt((mesh.u[innerEdges[:,0]]-mesh.u[innerEdges[:,1]])**2 +
00012                          (mesh.v[innerEdges[:,0]]-mesh.v[innerEdges[:,1]])**2)
00012
00013     cutPointDistanceToEdgeNode=getCutDistancesToEdgeNodes(edgeNodePotentials, potentialLevelList, edgeLength)
00014     uCutPoint, vCutPoint =
00015     getuvCutPoints(mesh, innerEdges, edgeLength, potentialCutCriteria, cutPointDistanceToEdgeNode)
00016
00017     potentialSortedCutPoints = getPotentialSortedCutPoints(potentialLevelList, uCutPoint, vCutPoint)
00018     rawUnsortedPoints = getRawUnsortedPoints(potentialLevelList, potentialSortedCutPoints)
00019     rawUnarrangedLoops = getRawUnarrangedLoops(rawUnsortedPoints, innerEdges, innerEdgeOpposedNode)
00020
00021     #TODO: next step Matlab calc_contours_by triangular_potential_cuts line 179 "evaluate for each loop
00022     the current orientation"
00023
00024     contours=0
00025     return contours
00026
00027 def getuvCutPoints(mesh, innerEdges, edgeLength, potentialCutCriteria, cutPointDistanceToEdgeNode):
00028     """returns uCutPoint and vCutPoint"""
00029     uKompEdgeVec = mesh.u[innerEdges[:,1]] - mesh.u[innerEdges[:,0]]
00030     vKompEdgeVec = mesh.v[innerEdges[:,1]] - mesh.v[innerEdges[:,0]]
00031     uCutPoint, vCutPoint=[[], []]
00032     for x in range(len(edgeLength)):
00033         uCutPoint.append(potentialCutCriteria[x] * (mesh.u[innerEdges[:,0]][x] +
00034               cutPointDistanceToEdgeNode[x]/edgeLength[x] *uKompEdgeVec[x]))
00035         vCutPoint.append(potentialCutCriteria[x] * (mesh.v[innerEdges[:,0]][x] +
00036               cutPointDistanceToEdgeNode[x]/edgeLength[x] *vKompEdgeVec[x]))
00037     return uCutPoint, vCutPoint
00038
00039
```

```

00034 def getRawUnsortedPoints(potentialLevelList, potentialSortedCutPoints):
00035     """ returns rawUnsortedPoints"""
00036     rawUnsortedPoints = []
00037     for i in range(len(potentialLevelList)):
00038         rawUnsortedPointsDict = {
00039             "potential": potentialLevelList[i],
00040             "edgeInd": np.array(potentialSortedCutPoints[i])[:,2].astype(int),
00041             "uv":
00042                 [np.array(potentialSortedCutPoints[i])[:,0], np.array(potentialSortedCutPoints[i])[:,1]],
00043                 }
00044         rawUnsortedPoints.append(rawUnsortedPointsDict)
00045     return rawUnsortedPoints
00046 def getPotentialSortedCutPoints(potentialLevelList, uCutPoint, vCutPoint):
00047     """ returns potentialSortedCutPoints"""
00048     potentialSortedCutPoints = []
00049     for potInd in range(len(potentialLevelList)):
00050         listelement = []
00051         for edgeInd in range(len(uCutPoint)):
00052             if uCutPoint[edgeInd][potInd] != 0:
00053                 listelement.append([uCutPoint[edgeInd][potInd], vCutPoint[edgeInd][potInd], int(edgeInd)])
00054         potentialSortedCutPoints.append(listelement)
00055     return potentialSortedCutPoints
00056
00057 def getCutDistancesToEdgeNodes(edgeNodePotentials, potentialLevelList, edgeLength):
00058     """ returns the cutPointDistanceToEdgeNode"""
00059     edgePotentialSpan = edgeNodePotentials[:,1]-edgeNodePotentials[:,0]
00060     cutPointDistanceToEdgeNode = []
00061     for x in range(len(edgeNodePotentials)):
00062         cutPointDistanceToEdgeNodePart = []
00063         for y in range(len(potentialLevelList)):
00064             cutPointDistanceToEdgeNodePart.append(np.abs(edgeLength[x]/edgePotentialSpan[x] *
00065                 (potentialLevelList[y]-edgeNodePotentials[x][0])))
00066         cutPointDistanceToEdgeNode.append(cutPointDistanceToEdgeNodePart)
00067     return cutPointDistanceToEdgeNode
00068
00069 def getPotentialCutCriteria(edgeNodePotentials, potentialLevelList):
00070     """ returns the PotentialCutCriteria"""
00071     minEdgePotential = []
00072     maxEdgePotential = []
00073     for x in range(len(edgeNodePotentials)):
00074         minEdgePotential.append(min(edgeNodePotentials[x]))
00075         maxEdgePotential.append(max(edgeNodePotentials[x]))
00076     triBelowPotStep = []
00077     triAbovePotStep = []
00078     for i in range(len(maxEdgePotential)):
00079         triBelowPotStep.append(maxEdgePotential[i]>potentialLevelList)
00080         triAbovePotStep.append(minEdgePotential[i]<potentialLevelList)
00081     return np.array(triBelowPotStep) & np.array(triAbovePotStep)
00082
00083 def getRawUnarrangedLoops(rawUnsortedPoints, innerEdges, innerEdgeOpposedNode):
00084     """ returns rawUnarrangedLoops"""
00085     rawUnarrangedLoopsTotal = []
00086     for potentialGroupInd in range(len(rawUnsortedPoints)):
00087         allCurrentEdges = innerEdges[rawUnsortedPoints[potentialGroupInd]['edgeInd']]
00088         allCurrentOpposedNodes =
00089             np.array(innerEdgeOpposedNode[rawUnsortedPoints[potentialGroupInd]['edgeInd']])
00090         allCurrentUVKcoords = rawUnsortedPoints[potentialGroupInd]['uv']
00091         setNewStart = True
00092         numBuildLoops = 0
00093         edgeAlreadyUsed = np.zeros(len(allCurrentEdges))
00094         rawUnarrangedLoops = []
00095         while not edgeAlreadyUsed.all():
00096             if setNewStart:
00097                 oneLoop = []
00098                 numBuildLoops += 1
00099                 startingEdge = min(np.argwhere(edgeAlreadyUsed== 0))
00100                 rawUnarrangedLoopsDict = {
00101                     "edgeInd": allCurrentEdges[startingEdge],
00102                     "uv": np.array(allCurrentUVKcoords[:,startingEdge])
00103                 }
00104                 oneLoop.append(rawUnarrangedLoopsDict)
00105                 edgeAlreadyUsed[startingEdge] = 1
00106                 currentEdge = startingEdge
00107             else:
00108                 neighbouringFreeNextEdges = np.argwhere(np.any(testElement, axis=1) &
00109                     np.any(testtestElement, axis=1))
00110                 if not neighbouringFreeNextEdges.any(): break
00111                 elif len(neighbouringFreeNextEdges) == 1:
00112                     setNewStart = False
00113                     nextEdge = neighbouringFreeNextEdges[0]

```

```

00114         else:
00115             setNewStart = False
00116             if not edgeAlreadyUsed[neighbouringFreeNextEdges[0]]: nextEdge =
neighbouringFreeNextEdges[0]
00117             else: nextEdge = neighbouringFreeNextEdges[1]
00118
00119         while not (nextEdge == startingEdge):
00120             rawUnarrangedLoopsDict = {
00121                 "edgeInd":allCurrentEdges[nextEdge],
00122                 "uv": np.array(allCurrentUVKcoords[:,nextEdge]
00123             )
00124             oneLoop.append(rawUnarrangedLoopsDict)
00125             edgeAlreadyUsed[nextEdge] = 1
00126             currentEdge = np.copy(nextEdge)
00127
00128     testElement, testtestElement=checkIfPositionsElementIdenticalWithFirstList (allCurrentEdges,allCurrentOpposedNodes,
currentEdge)
00129     possibleNextEdges = np.argwhere(np.any(testElement, axis=1) &
np.any(testtestElement, axis=1))
00130     possibleNextEdges = np.setdiff1d(possibleNextEdges,np.argwhere(edgeAlreadyUsed ==
1))
00131     if not possibleNextEdges.any():
00132         rawUnarrangedLoops.append(oneLoop)
00133         break
00134     elif len(possibleNextEdges) == 1: nextEdge = possibleNextEdges[0]
00135     else:
00136         if not edgeAlreadyUsed[possibleNextEdges[0]]: nextEdge = possibleNextEdges[0]
00137         else: nextEdge = possibleNextEdges[1]
00138         setNewStart = True
00139     rawUnarrangedLoopsTotal.append(rawUnarrangedLoops)
00140     return rawUnarrangedLoopsTotal
00141
00142 def checkIfPositionsElementIdenticalWithFirstList(allCurrentEdges, allCurrentOpposedNodes,
checkPosition):
00143     """returns lists of elements with booleans if checkPostions Element of first and second Element
are identical with allCurrentEdges"""
00144     testElement=[]
00145     testtestElement=[]
00146     for i in allCurrentEdges:
00147         testElement1=[]
00148         testElement2=[]
00149         for j in i:
00150             testElement1.append(np.any(j == allCurrentOpposedNodes[checkPosition]))
00151             testElement2.append(np.any(j == allCurrentEdges[checkPosition]))
00152         testElement.append(testElement1)
00153         testtestElement.append(testElement2)
00154     return testElement, testtestElement
00155
00156 def getEdgeOpposedNode(mesh, innerEdgesTrianglesInds, innerEdges):
00157     """returns the to the edge opposed node for each attached triangle"""
00158     innerEdgeTriangleNodes = getInnerEdegTriangleNodes (innerEdgesTrianglesInds, mesh)
00159     edgeOpposedNodes = []
00160     for edgeInd in range(len(innerEdges)):
00161         oneEdgeOpposedNodes= []
00162         for triangleInd in range(len(innerEdgeTriangleNodes[edgeInd])):
00163             oneEdgeOpposedNodes.append(removeTwoElementsFromArray (innerEdgeTriangleNodes[edgeInd][triangleInd], innerEdges[edgeInd])
00164             edgeOpposedNodes.append(oneEdgeOpposedNodes)
00165     return edgeOpposedNodes
00166
00167 def removeTwoElementsFromArray(array, Element1, Element2):
00168     """returns the array without the two elements."""
00169     return updateList(updateList(array, Element1), Element2)
00170
00171 def getInnerEdegTriangleNodes (innerEdgesTrianglesInds, mesh):
00172     """returns the Node Indices for the Triangles."""
00173     innerEdgeTriangleNodes = []
00174     for edgeInd in range(len(innerEdgesTrianglesInds)):
00175         innerEdgeTriangleNodes.append([np.array(mesh.faces[innerEdgesTrianglesInds[edgeInd][0]]), np.array(mesh.faces[innerEdgesTrianglesInds[edgeInd][1]])])
00176     return innerEdgeTriangleNodes
00177
00178 def getInnerEdges (mesh):
00179     """returns the inner edges an the corresponding triangleInds."""
00180     edges = getEdges (mesh)
00181     edgeAttachedTriangles = getEdgeAttachedTriangles (edges, mesh)
00182     numAttachedTriangles = getNumAttachedTriangles (edgeAttachedTriangles)
00183     innerEdges=[]
00184     innerEdgesTrianglesInds = []
00185     for index in range(len(edges)):
00186         if numAttachedTriangles[index] == 2:
00187             innerEdges.append(edges[index])
00188             innerEdgesTrianglesInds.append(edgeAttachedTriangles[index])
00189     return np.array(innerEdges), innerEdgesTrianglesInds
00190
00191 def getNumAttachedTriangles (edgeAttachedTriangles):

```

```

00192     """returns the number of attached triangles per edge."""
00193     numAttachedTriangles = []
00194     for edgeInd in range(len(edgeAttachedTriangles)):
00195         numAttachedTriangles.append(len(edgeAttachedTriangles[edgeInd]))
00196     return numAttachedTriangles
00197
00198 def getEdgeAttachedTriangles(edges, mesh):
00199     """returns the attached triangles for each edge."""
00200     allEdgesTriangles = []
00201     for edge in edges:
00202         edgeFaces = []
00203         for triangleIndex in range(len(mesh.faces)):
00204             if edge[0] in mesh.faces[triangleIndex] and edge[1] in mesh.faces[triangleIndex]:
00205                 edgeFaces.append(triangleIndex)
00206         allEdgesTriangles.append(edgeFaces)
00207     return allEdgesTriangles
00208
00209 def getEdges(mesh):
00210     """returns all edges in the mesh."""
00211     edges = []
00212     for node in range(len(mesh.vertices)):
00213         for triangle in mesh.faces:
00214             if node in triangle:
00215                 if node == triangle[0]:
00216                     if node < triangle[1] and [triangle[0], triangle[1]] not in edges:
00217                         edges.append([triangle[0], triangle[1]])
00218                     if node < triangle[2] and [triangle[0], triangle[2]] not in edges:
00219                         edges.append([triangle[0], triangle[2]])
00220                 elif node == triangle[1]:
00221                     if node < triangle[0] and [triangle[1], triangle[0]] not in edges:
00222                         edges.append([triangle[1], triangle[0]])
00223                     if node < triangle[2] and [triangle[1], triangle[2]] not in edges:
00224                         edges.append([triangle[1], triangle[2]])
00225                 elif node == triangle[2]:
00226                     if node < triangle[0] and [triangle[2], triangle[0]] not in edges:
00227                         edges.append([triangle[2], triangle[0]])
00228                     if node < triangle[1] and [triangle[2], triangle[1]] not in edges:
00229                         edges.append([triangle[2], triangle[1]])
00230
00231     return edges

```

8.8 subfunctions/calcPotentialLevels.py File Reference

Namespaces

- namespace [calcPotentialLevels](#)

Functions

- def [calcPotentialLevels.calcPotentialLevels](#) (streamFunction, numLevels, levelOffset)

8.9 calcPotentialLevels.py

[Go to the documentation of this file.](#)

```

00001 import numpy as np
00002
00003 def calcPotentialLevels(streamFunction, numLevels, levelOffset):
00004     """returns the contourStep and the potentialLevelList. more options need to be implemented, if
    there is more than one mesh."""
00005     SFRangePerMesh = np.max(streamFunction) - np.min(streamFunction)
00006     contourStep = SFRangePerMesh / (numLevels - 1 + 2 * levelOffset)
00007     potentialLevelList =
    np.arange(0, numLevels) * contourStep + (np.min(streamFunction) + levelOffset * contourStep)
00008
00009     return contourStep, potentialLevelList

```

8.10 subfunctions/defineTargetField.py File Reference

Classes

- class [defineTargetField.TargetField](#)
- class [defineTargetField.TargetFieldGiven](#)

Namespaces

- namespace [defineTargetField](#)

Functions

- def [defineTargetField.distanceBetweenPoints](#) (point1, point2)

8.11 defineTargetField.py

[Go to the documentation of this file.](#)

```
00001 #kugel in zylinder, gleichmäßig im Volumen verteilte Punkte, mit gewünschtem Feld
00002 import numpy as np
00003 import pandas as pd
00004 import matplotlib.pyplot as plt
00005 from readMesh import getMeshFromSTL
00006
00007
00008 class TargetField():
00009     def __init__(self,center,radius,direction):#direction: 0==x,1==y,2==z
00010         self.center = center
00011         self.radius = radius
00012         self.vertices = self.getTargetPoints()
00013         self.fieldValues = self.getMagneticFieldValues(direction)
00014
00015     def getTargetPoints(self):
00016         '''generate Target Points within a circle with the given specifications'''
00017         newX = np.linspace(self.center[0]-self.radius,self.center[0]+self.radius,25)
00018         newY = np.linspace(self.center[1]-self.radius,self.center[1]+self.radius,25)
00019         newZ = np.linspace(self.center[2]-self.radius,self.center[2]+self.radius,25)
00020         newX,newY,newZ = np.meshgrid(newX, newY, newZ, indexing='ij')
00021         targetVertices = []
00022         for i in range(len(newX)):
00023             for j in range(len(newY)):
00024                 for k in range(len(newZ)):
00025                     if distanceBetweenPoints(self.center,[newX[i][j][k],newY[i][j][k],newZ[i][j][k]])
<= self.radius:
00026                         targetVertices.append([newX[i][j][k],newY[i][j][k],newZ[i][j][k]])
00027                     else: continue
00028         return np.array(targetVertices)#array is important to be able to do[:,0]
00029
00030     def getMagneticFieldValues(self,direction):
00031         '''returns magnetic field values analogous to matlab skript'''
00032         targetStrength = 0.1
00033         targetField = np.zeros((3,len(self.vertices)))
00034         targetField[2] = self.vertices[:,direction]
00035         targetField = targetField*targetStrength
00036         return targetField
00037
00038 class TargetFieldGiven(TargetField):
00039     def __init__(self,filename,direction):
00040         self.vertices,self.faces = getMeshFromSTL(filename)
00041         self.fieldValuesfieldValues = self.getMagneticFieldValues(direction)
00042
00043     def distanceBetweenPoints(point1,point2):
00044         '''returns the distance between two given points'''
00045         result = 0
00046         for i in range(len(point1)):
00047             result += (point1[i]-point2[i])**2
00048         return np.sqrt(result)
00049
00050
00051
00052
00053
00054
00055
00056
00057 #ax.scatter3D(points[0],points[1],points[2])
00058 plt.show()
```

8.12 subfunctions/readMesh.py File Reference

Classes

- class [readMesh.CylindricMesh](#)
- class [readMesh.CylindricMeshGiven](#)

Namespaces

- namespace [readMesh](#)

Functions

- def [readMesh.calculateNormal](#) (vec)
- def [readMesh.updateList](#) (edgeList, otheredge)
- def [readMesh.getMeshFromSTL](#) (filename)
- def [readMesh.checkIfVecInVecList](#) (node, vecList)

8.13 readMesh.py

[Go to the documentation of this file.](#)

```
00001 import numpy as np
00002 import matplotlib.pyplot as plt
00003 import meshzoo
00004 import trimesh
00005 import scipy
00006
00007 def calculateNormal(vec):
00008     """returns the norm for a given 3d vector"""
00009     if len(vec) == 3:
00010         v1 = vec[1] - vec[0]
00011         v2 = vec[2] - vec[0]
00012         return
00013     np.cross(v1,v2)/np.sqrt(np.cross(v1,v2)[0]**2+np.cross(v1,v2)[1]**2+np.cross(v1,v2)[2]**2)
00014     else:
00015         print("Mesh-Generation is going wrong. Faces do not have 3 components")
00016         return False
00017
00018 def updateList(edgeList,otheredge):
00019     """returns the edgeList without otheredge"""
00020     return [a for a, skip in zip(edgeList, [np.allclose(a, otheredge) for a in edgeList]) if not skip]
00021
00022 #option 1: create mesh
00023 class CylindricMesh():
00024     def __init__(self,coilLength,coilRadius,n):
00025         self.vertices, self.faces = meshzoo.tube(length=coilLength, radius=coilRadius,
00026         n=int(n)) #points, cells(index of the points that close the cell)
00027         self.vertices = np.array(self.vertices)
00028         self.normals=self.getNormals()
00029         self.openBoundaries=self.getOpenBoundaries()
00030         self.areas = self.getAreas()
00031         self.current = self.getCurrent()
00032         self.neighbours=self.getNeighbourTriangleIndices()
00033         self.rotatedCaylinder=self.getRotatedCopy()
00034         self.u,self.v=self.get2Dcoordinates()
00035         self.neighbourareas = self.getNeighbourAreas()
00036         self.currentDensityFaces=[]
00037         self.vertexNormals=self.getVertexNormals()
00038         self.boundary = self.checkIfBoundary()
00039         self.oneRingList = self.getOneRingList()
00040         self.neighbourcurrents = self.getNeighbourCurrents()
00041         self.neighbourcurrentUnsorted = self.getNeighbourCurrentsUnsorted()
00042
00043     def checkIfBoundary(self):
00044         """returns a list of boolean if the vertice is a boundary vertice"""
00045         boundaryBooleans = []
00046         for nodeElements in range(len(self.vertices)):
00047             if len(self.faces[nodeElements]) < 3:
00048                 boundaryBooleans.append(True)
00049             else:
00050                 boundaryBooleans.append(False)
```

```

00045         boundaryBooleans.append((nodeElements in self.openBoundaries[0]) | (nodeElements in
self.openBoundaries[1]))
00046         return boundaryBooleans
00047
00048     def getVertexNormals(self):
00049         """returns the normals of the vertices. These are calculated as average of the touching faces
normals."""
00050         vertexNormals = []
00051         for vertex in range(len(self.vertices)):
00052             sum = 0
00053             for x in np.array(self.neighbours[vertex]):
00054                 sum+= self.normals[x]
00055             vertexNormals.append(sum/len(self.neighbours[vertex]))
00056         return vertexNormals
00057
00058     def getNormals(self):
00059         """returns the normals of the faces"""
00060         normals=[]
00061         for i in range(len(self.faces)):
00062             normals.append(calculateNormal(self.vertices[self.faces[i]]))
00063         return normals
00064
00065     def getNeighbourAreas(self):
00066         """returns the areas of the neighbour triangles for every node"""
00067         neighbourareas = []
00068         for i in range(len(self.vertices)):
00069             neighbourareasparts=[]
00070             for j in self.neighbours[i]:
00071                 neighbourareasparts.append(self.areas[j])
00072             neighbourareas.append(neighbourareasparts)
00073         return neighbourareas
00074
00075     def getNeighbourCurrents(self):
00076         """returns the currents of the neighbour triangles for every node"""
00077         neighbourcurrents = []
00078         for i in range(len(self.vertices)):
00079             neighbourcurrentparts=[]
00080             for j in self.oneRingList[i]:
00081                 neighbourcurrentparts.append((self.vertices[j][1] -
self.vertices[j][0])/ (scipy.linalg.norm(np.cross(self.vertices[j][1]-self.vertices[i],self.vertices[j][0]]
- self.vertices[i]))))
00082             neighbourcurrents.append(neighbourcurrentparts)
00083         return neighbourcurrents
00084
00085     def getNeighbourCurrentsUnsorted(self):
00086         """returns the currents of the neighbour triangles for every node before sorting"""
00087         neighbourcurrents = []
00088         for i in range(len(self.vertices)):
00089             neighbourcurrentparts=[]
00090             for j in self.neighbours[i]:
00091                 neighbourcurrentparts.append(self.current[j])
00092             neighbourcurrents.append(neighbourcurrentparts)
00093         return neighbourcurrents
00094
00095     def getCurrent(self):
00096         """returns the current for the triangles made with the points in faces
C = (c-b)/(2*Fläche)"""
00097         current =[]
00098         for i in range(len(self.areas)):
00099             current.append((self.vertices[self.faces[i][2]]-self.vertices[self.faces[i][1]])/(2*self.areas[i]))
00100
00101         return current
00102
00103     def getAreas(self):
00104         """returns the areas of the triangles made with the points in faces"""
00105         areas=[]
00106         for i in self.faces:
00107             areas.append(np.linalg.norm(np.cross((self.vertices[i][1]-self.vertices[i][0]), (self.vertices[i][2]-self.vertices[i][0]))))
00108         return areas
00109
00110     def getOpenBoundaries(self):
00111         """returns indexes of the nodes at the edges of a cylinder extended in z-direction"""
00112         max = 0
00113         upperopen=[]
00114         min = 0
00115         loweropen=[]
00116         for i in range(len(self.vertices)):
00117             if self.vertices[i][2]< min:
00118                 min = self.vertices[i][2]
00119                 loweropen = [i]
00120             elif self.vertices[i][2] == min:
00121                 loweropen.append(i)
00122             elif self.vertices[i][2]>max:
00123                 max = self.vertices[i][2]
00124                 upperopen = [i]
00125             elif self.vertices[i][2]==max:

```



```

00126         upperopen.append(i)
00127     else: continue
00128     return [upperopen,loweropen]#TODO tauschen
00129
00130 def getBoundaryEdges(self):
00131     """returns the nodes for each boundary in the correct order"""
00132     boundaryEdges=[]
00133     for boundary in self.openBoundaries:
00134         eachBoundaryEdges=[]
00135         for boundaryPoint in boundary:
00136             for neighbour in self.faces[self.neighbours[boundaryPoint]]:
00137                 for neighbournode in neighbour:
00138                     if neighbournode in boundary and neighbournode != boundaryPoint:
00139                         eachBoundaryEdges.append([boundaryPoint,neighbournode])
00140         eachBoundaryEdges = self.removeDoubleEdges(eachBoundaryEdges)
00141         boundaryEdges.append(eachBoundaryEdges)
00142     return boundaryEdges
00143
00144 def removeDoubleEdges(self,edgeList):
00145     """returns the edgeList with each edge just once."""
00146     newList=np.copy(edgeList)
00147     for edgeInd in range(len(newList)):
00148         for otheredgeInd in range(len(newList)):
00149             if (newList[edgeInd][::-1] == newList[otheredgeInd]).all() and edgeInd < otheredgeInd:
00150                 edgeList = updateList(edgeList,newList[otheredgeInd])
00151     return edgeList
00152
00153 def getBoundaryLoopNodes(self):
00154     """returns the unsorted nodes for the boundaryLoop."""
00155     boundaryEdges = self.getBoundaryEdges()
00156     boundaryEdges = self.turnAnsSortElements(boundaryEdges)
00157     boundaryEdges = [np.flip(boundaryEdges[1]),boundaryEdges[0]] #TODO welche Regelmäßigkeit,
    warum so?
00158     boundaryLoopNodes=[]
00159     for boundary in boundaryEdges:
00160         boundaryNodes = np.append(np.array(boundary)[:,0],boundary[0][0])
00161         boundaryLoopNodes.append(boundaryNodes)
00162     return boundaryLoopNodes
00163
00164 def getRotatedCopy(self):
00165     """returns rotated copy of the vertices. If the cylinder is orientated along the z axis we need
    a rotated copy."""
00166     boundaryLoopNodes = self.getBoundaryLoopNodes()
00167     rotationVec,angle = self.calcRotationVec(boundaryLoopNodes)
00168     rotMat = self.calc3DRotMatByVec(rotationVec,angle)
00169     rotatedVertices = self.getRotatedVertices(rotMat)
00170     return rotatedVertices
00171
00172 def getRotatedVertices(self,rotMat):
00173     """returns the rotated vertices (multiplication with rotMat)."""
00174     rotatedVertices = []
00175     for i in self.vertices:
00176         rotatedVertices.append(np.dot(rotMat,np.transpose(i)))
00177     return rotatedVertices
00178
00179 def calcRotationVec(self,boundaryLoopNodes):
00180     """returns the rotationVector and the angle based on the boundaryLoopNodes."""
00181     openingMean =
    [np.mean(self.vertices[boundaryLoopNodes[0]][::-1]),np.mean(self.vertices[boundaryLoopNodes[0]][::-1]),np.mean(self.vertices[boundaryLoopNodes[0]][::-1])]
00182     overallMean = np.mean(self.vertices)
00183     oldOrientationVec=(openingMean-overallMean)/np.linalg.norm(openingMean-overallMean)
00184     zVec = [0,0,1]
00185     sina =
    np.linalg.norm(np.cross(oldOrientationVec,zVec))/(np.linalg.norm(oldOrientationVec)*np.linalg.norm(zVec))
00186     cosa =
    np.linalg.norm(np.dot(oldOrientationVec,zVec))/(np.linalg.norm(oldOrientationVec)*np.linalg.norm(zVec))
00187     angle = np.arctan2(sina,cosa)
00188     rotationVec =
    np.cross(oldOrientationVec,zVec)/np.linalg.norm(np.cross(oldOrientationVec,zVec))
00189     return rotationVec,angle
00190
00191 def calc3DRotMatByVec(self,rotationVec,angle):
00192     """returns the rotation matrix calculated from the rotationVector"""
00193     uX,uY,uZ = rotationVec
00194     tmp1 = np.sin(angle)
00195     tmp2 = np.cos(angle)
00196     tmp3 = (1-np.cos(angle))
00197     rotMat = np.zeros((3,3))
00198     rotMat[0][0] = tmp2 + uX*uX*tmp3
00199     rotMat[0][1] = uX*uY*tmp3-uZ*tmp1
00200     rotMat[0][2] = uX*uZ*tmp3+uY*tmp1
00201     rotMat[1][0] = uY*uX*tmp3+uZ*tmp1
00202     rotMat[1][1] = tmp2+uY*uY*tmp3
00203     rotMat[1][2] = uY*uZ*tmp3-uX*tmp1
00204     rotMat[2][0] = uZ*uX*tmp3-uY*tmp1
00205     rotMat[2][1] = uZ*uY*tmp3+uX*tmp1
00206     rotMat[2][2] = tmp2+uZ*uZ*tmp3

```

```

00207         return rotMat
00208
00209 def turnAnsSortElements(self,boundaryEdges):
00210     '''returns the given list in sorted. If needed single elements were turned to close the loop.'''
00211     new=[]
00212     for boundary in boundaryEdges:
00213         start = boundary[0]
00214         newElement = [start]
00215         while len(newElement) < len(boundary):
00216             for element in boundary:
00217                 if start == element:
00218                     continue
00219                 elif start[1] == element[0]:
00220                     if element[1] is not start[0]:
00221                         newElement.append(element)
00222                         break
00223                 elif start[1] == element[1]:
00224                     if start[0] is not element[1]:
00225                         newElement.append([element[1],element[0]])
00226                         break
00227             start = newElement[-1]
00228         new.append(newElement)
00229     return new
00230
00231 def get2Dcoordinates(self):
00232     '''returns the from 3D to 2D converted vertices'''
00233     corods = np.array(self.rotatedCaylinder)
00234     minZCylinder = min(corods[:,2])
00235     corods[:,2] = corods[:,2]+minZCylinder
00236     phiCoord = np.arctan2(corods[:,1],corods[:,0])
00237     r = np.sqrt(corods[:,0]**2+corods[:,1]**2)
00238     u = (corods[:,2]-np.mean(r))*np.sin(phiCoord)
00239     v = (corods[:,2]- np.mean(r))*np.cos(phiCoord)
00240     return u,v
00241
00242 def getNeighbourTriangleIndices(self):
00243     '''returns the indices of the neighbour triangles of every node'''
00244     neighbourtrianglesIndices=[]
00245     for node in self.vertices:
00246         k=[]
00247         for i in range(len(self.faces)):
00248             vecList = self.vertices[self.faces[i]]
00249             if checkIfVecInVecList(node,vecList):
00250                 k.append(i)
00251         neighbourtrianglesIndices.append(k)
00252     return neighbourtrianglesIndices
00253
00254 def getOneRingList(self):
00255     '''returns sorted list with nodes around every node'''
00256     oneRingList = self.createOneRingList()
00257     oneRingList = self.ensureUniformOrientation(oneRingList)
00258     oneRingList = self.orderElementsInCircularArangement(oneRingList)
00259     return oneRingList
00260
00261 def orderElementsInCircularArangement(self,oneRingList):
00262     '''returns the List in a circular arrangement'''
00263     for nodeElements in range(len(oneRingList)):
00264         if self.boundary[nodeElements]:
00265             start = self.findStartInBoundaryCase(oneRingList,nodeElements)
00266         else:
00267             start = oneRingList[nodeElements][0]
00268
00269         new = self.arrangeCircular(start,oneRingList[nodeElements])
00270         oneRingList[nodeElements] = new
00271     return oneRingList
00272
00273 def arrangeCircular(self,start,Elements):
00274     '''returns the elements in a circular order beginning with start'''
00275     new = [start]
00276     while len(new) != len(Elements):
00277         for i in Elements:
00278             if len(new) == len(Elements):
00279                 break
00280             elif new[-1][1] == i[0]:
00281                 new.append(i)
00282     return new
00283
00284 def findStartInBoundaryCase(self,oneRingList,nodeNumber):
00285     '''returns the correct start triangle for ordering the triangles around a boundary vertice'''
00286     index = 0
00287     start = oneRingList[nodeNumber][0]
00288     correctstart = self.checkStartTriangle(oneRingList[nodeNumber],start)
00289     while not correctstart:
00290         start = oneRingList[nodeNumber][index+1]
00291         correctstart = self.checkStartTriangle(oneRingList[nodeNumber],start)
00292         index+=1
00293     return start

```

```

00294
00295     def checkStartTriangle(self, verticeTriangles, start):
00296         """returns boolean if "start" is the correct startTriangle"""
00297         test = []
00298         for i in range(len(verticeTriangles)):
00299             test.append(start[0]==verticeTriangles[i][1])
00300         return not np.any(test)
00301
00302     def createOneRingList(self):
00303         """returns a list with the other two triangle Points for each triangle per node"""
00304         indices = self.getNeighbourTriangleIndices()
00305         oneRingList=[]
00306         for i in range(len(indices)):
00307             eachnode=[]
00308             for k in range(len(indices[i])):
00309                 new=[]
00310                 for j in range(3):
00311                     if self.faces[indices[i][k]][j] != i:
00312                         new.append(self.faces[indices[i][k]][j])
00313                 eachnode.append(new)
00314             oneRingList.append(eachnode)
00315         return oneRingList
00316
00317     def ensureUniformOrientation(self, oneRingList):
00318         """returns oneRingList with ensured uniform Orientation"""
00319         for nodeelements in range(len(oneRingList)):
00320             for neighbournodes in oneRingList[nodeelements]:
00321                 b = self.vertices[neighbournodes[0]]
00322                 c = self.vertices[neighbournodes[1]]
00323                 a = self.vertices[nodeelements]
00324                 crossVec = np.cross(c-b,b-a)
00325
00326                 if np.sign(np.dot(self.vertexNormals[nodeelements],crossVec)) > 0:
00327                     before0 = neighbournodes[0]
00328                     before1 = neighbournodes[1]
00329                     neighbournodes[0] = before1
00330                     neighbournodes[1] = before0
00331             return oneRingList
00332
00333
00334 #option 2: create cylindric mesh
00335 def getMeshFromSTL(filename):
00336     """returns vertices and faces from given stl file meshes"""
00337     myobj = trimesh.load_mesh(filename, enable_post_processing=True, solid=True)
00338     return myobj.vertices, myobj.faces
00339
00340 class CylindricMeshGiven(CylindricMesh):
00341     def __init__(self, filename):
00342         self.vertices, self.faces = getMeshFromSTL(filename)
00343         self.vertices = np.array(self.vertices)
00344         self.normals = self.getNormals()
00345         self.openBoundaries = self.getOpenBoundaries()
00346         self.areas = self.getAreas()
00347         self.current = self.getCurrent()
00348         self.neighbours = self.getNeighbourTriangleIndices()
00349         self.rotatedCylinder = self.getRotatedCopy()
00350         self.u, self.v = self.get2Dcoordinates()
00351         self.neighbourareas = self.getNeighbourAreas()
00352         self.currentDensityFaces = self.getCurrentDensityFaces()
00353         self.vertexNormals = self.getVertexNormals()
00354         self.boundary = self.checkIfBoundary()
00355         self.oneRingList = self.getOneRingList()
00356         self.neighbourcurrents = self.getNeighbourCurrents()
00357         self.neighbourcurrentUnsorted = self.getNeighbourCurrentsUnsorted()
00358
00359     def checkIfVecInVecList(self, node, vecList):
00360         """returns Boolean if a 3 components vec is in a list of 3 component elements"""
00361         return (node == vecList[0]).all() or (node == vecList[1]).all() or (node == vecList[2]).all()
00362
00363
00364
00365
00366
00367
00368
00369
00370 #x,y = mesh.get2Dcoordinates()
00371 #plt.plot(x,y, '.')
00372 #plt.show()
00373
00374
00375
00376
00377
00378
00379 # X=[]
00380 # Y=[]
00381 # Z=[]
00382 # print(np.shape(mesh.vertices))
00383 # for i in range(len(mesh.vertices)):
00384 #     X.append(mesh.vertices[i][0])

```

```

00385 #     Y.append(mesh.vertices[i][1])
00386 #     Z.append(mesh.vertices[i][2])
00387 # ax.scatter3D(X,Y,Z)
00388 # plt.show()
00389

```

8.14 subfunctions/resistanceMatrix.py File Reference

Namespaces

- namespace [resistanceMatrix](#)

Functions

- def [resistanceMatrix.getResistanceMatrix](#) (test, mesh, materialFactor)
- def [resistanceMatrix.formFinalResistanceMat](#) (resistanceMatrix, materialFactor)
- def [resistanceMatrix.createPreviousResistanceMat](#) (mesh, matElementsShouldGetValue)
- def [resistanceMatrix.getResistanceSumForDifferent](#) (mesh, trianglesWithBothNodes, nodeInd1, nodeInd2)
- def [resistanceMatrix.getResistanceSumForSame](#) (mesh, nodeInd1)
- def [resistanceMatrix.calculateArea](#) (Point1, Point2, Point3)
- def [resistanceMatrix.calculateCurrent](#) (Point1, Point2, Point3)
- def [resistanceMatrix.getMatElementShouldGetValue](#) (mesh)
- def [resistanceMatrix.getPartnerElement](#) (triangle, trianglesWithBothNodes, nodeInd2)
- def [resistanceMatrix.elementInArray](#) (array, value)
- def [resistanceMatrix.elementInAandB](#) (a, b)
- def [resistanceMatrix.compareMultipleElementsBoolean](#) (elements, testelements)
- def [resistanceMatrix.getSpatialDistancesMatrix](#) (mesh)
- def [resistanceMatrix.getNeighbourhoodMatrix](#) (mesh)
- def [resistanceMatrix.compareMultipleElementsBooleanTest](#) ()

8.15 resistanceMatrix.py

[Go to the documentation of this file.](#)

```

00001 import numpy as np
00002 from defineTargetField import distanceBetweenPoints
00003
00004 def getResistanceMatrix(test,mesh,materialFactor):
00005     """returns the resistance Matrix for the given mesh"""
00006     matElementsShouldGetValue = getMatElementShouldGetValue(mesh)
00007     test.matElementsShouldGetValue = matElementsShouldGetValue
00008     resistanceMatrix = createPreviousResistanceMat(mesh,matElementsShouldGetValue)
00009     resistanceMatrix = formFinalResistanceMat(resistanceMatrix,materialFactor)
00010     return resistanceMatrix
00011
00012 def formFinalResistanceMat(resistanceMatrix,materialFactor):
00013     """returns resistanceMatrix in final form. added with its transposed and multiplied with
    materialFactor"""
00014     resistanceMatrix = (resistanceMatrix + np.transpose(resistanceMatrix))*materialFactor
00015     return resistanceMatrix
00016
00017 def createPreviousResistanceMat(mesh,matElementsShouldGetValue):
00018     """returns resistanceMatrix mit entries in matElementsShouldGetValue"""
00019     resistanceMatrix = np.zeros((len(mesh.vertices),len(mesh.vertices)),dtype=float)
00020     for elementIndex in range(len(matElementsShouldGetValue[0])):
00021         nodeInd1 = int(matElementsShouldGetValue[0][elementIndex])
00022         nodeInd2 = int(matElementsShouldGetValue[1][elementIndex])
00023         if nodeInd1 == nodeInd2:
00024             resistanceSum = getResistanceSumForSame(mesh,nodeInd1)
00025             resistanceMatrix[nodeInd1][nodeInd1] = resistanceSum
00026         else:

```

```

00027         trianglesWithBothNodes =
00028         [elementInArray(mesh.oneRingList[nodeInd1],nodeInd2),elementInArray(mesh.oneRingList[nodeInd2],nodeInd1)]
00029         resistanceSum =
00030         getResistanceSumForDifferent(mesh,trianglesWithBothNodes,nodeInd1,nodeInd2)
00031         resistanceMatrix[nodeInd1][nodeInd2] = resistanceSum
00032         return resistanceMatrix
00033
00034 def getResistanceSumForDifferent(mesh,trianglesWithBothNodes,nodeInd1,nodeInd2):
00035     """returns resistanceSum for the Case node1 and node2 are different"""
00036     resistanceSum = 0
00037     for triangle in trianglesWithBothNodes[0]:
00038         triangleArea =
00039         calculateArea(mesh.vertices[nodeInd1],mesh.vertices[triangle[0]],mesh.vertices[triangle[1]])
00040         primaryCurrent =
00041         calculateCurrent(mesh.vertices[nodeInd1],mesh.vertices[triangle[0]],mesh.vertices[triangle[1]])
00042         partnerElement = getPartnerElement(triangle,trianglesWithBothNodes,nodeInd2)
00043         secondaryCurrent =
00044         calculateCurrent(mesh.vertices[nodeInd2],mesh.vertices[partnerElement[0]],mesh.vertices[partnerElement[1]])
00045         resistanceSum = resistanceSum + np.dot(primaryCurrent,secondaryCurrent)*(triangleArea**2)
00046     return resistanceSum
00047
00048 def getResistanceSumForSame(mesh,nodeInd1):
00049     """returns resistanceSum for the Case node1 and node2 are the same"""
00050     resistanceSum = 0
00051     for triangle in mesh.oneRingList[nodeInd1]:
00052         triangleArea =
00053         calculateArea(mesh.vertices[nodeInd1],mesh.vertices[triangle[0]],mesh.vertices[triangle[1]])
00054         current =
00055         calculateCurrent(mesh.vertices[nodeInd1],mesh.vertices[triangle[0]],mesh.vertices[triangle[1]])
00056         resistanceSum = resistanceSum + np.dot(current,current)*triangleArea**2
00057     return resistanceSum
00058
00059 def calculateArea(Point1,Point2,Point3):
00060     """returns the area of a triangle with 3 given Points"""
00061     return np.linalg.norm(np.cross((Point2-Point1),(Point3-Point1)))/2
00062
00063 def calculateCurrent(Point1, Point2, Point3):
00064     """returns the current of a triangle with 3 given Points"""
00065     return (Point3-Point2)/(np.linalg.norm(np.cross((Point2-Point1),(Point3-Point1))))
00066
00067 def getMatElementShouldGetValue(mesh):
00068     """returns a list with positions in the matrix that should get a value (diagonal elements == same
00069     nodes and neighbouring nodes)"""
00070     nodeAdjacencyMatrix = getNeighbourhoodMatrix(mesh)
00071     neighbourPairs = np.array(np.where(nodeAdjacencyMatrix))
00072     neighbourPairs = neighbourPairs[:,neighbourPairs[1].argsort()]
00073     matElementsShouldGetValue = [np.concatenate([np.linspace(0,263,264),neighbourPairs[0]])
00074     ,np.concatenate([np.linspace(0,263,264),neighbourPairs[1]])]
00075     return matElementsShouldGetValue
00076
00077 def getPartnerElement(triangle,trianglesWithBothNodes,nodeInd2):
00078     """returns the specified triangle both nodes are in from the oneRingList of the other one node.
00079     Important because different Point-orders cause different currents."""
00080     partnerElement = 0
00081     for i in triangle:
00082         if i != nodeInd2:
00083             differentElement = i
00084     for j in trianglesWithBothNodes[1]:
00085         if differentElement in j:
00086             partnerElement = j
00087     return partnerElement
00088
00089 def elementInArray(array,value):
00090     """returns a list with the elements the contain "value""""
00091     solution = []
00092     for element in array:
00093         if value in element:
00094             solution.append(element)
00095     return solution
00096
00097 def elementInAandB(a, b):
00098     """returns a list with elements that are in a and b"""
00099     solution = []
00100     for i in a:
00101         if i in b: solution.append(i)
00102     return solution
00103
00104 def compareMultipleElementsBoolean(elements,testelements):
00105     """returns a array with boolean elements in the length of elements, True if the value is in
00106     testelements False otherwise"""
00107     comparisonResult=[]
00108     for i in elements:
00109         if i == testelements:
00110             comparisonResult.append(True)
00111         else:
00112             comparisonResult.append(False)
00113     return comparisonResult

```

```

00103
00104 def getSpatialDistancesMatrix(mesh):
00105     """returns a matrix containing the spatial distance between node i and node j"""
00106     nodalNeighbourMatrix = np.full((len(mesh.vertices),len(mesh.vertices)), 0,dtype=float)
00107     for i in range(len(mesh.vertices)):
00108         for j in range(len(mesh.vertices)):
00109             nodalNeighbourMatrix[i][j] = distanceBetweenPoints(mesh.vertices[i],mesh.vertices[j])
00110     return nodalNeighbourMatrix
00111
00112 def getNeighbourhoodMatrix(mesh):
00113     """returns a boolean matrix with information if node i and node j are neighbours"""
00114     nodeAdjacencyMatrix = np.full((len(mesh.vertices),len(mesh.vertices) ), False)
00115     for i in range(len(mesh.faces)):
00116         nodeAdjacencyMatrix[mesh.faces[i][0]][mesh.faces[i][1]]=True
00117         nodeAdjacencyMatrix[mesh.faces[i][1]][mesh.faces[i][2]]=True
00118         nodeAdjacencyMatrix[mesh.faces[i][2]][mesh.faces[i][0]]=True
00119     return nodeAdjacencyMatrix
00120
00121
00122
00123 def compareMultipleElementsBooleanTest():
00124     """Test function: should always be True"""
00125     return len(np.where(compareMultipleElementsBoolean()))==1

```

8.16 subfunctions/sensitivityMatrix.py File Reference

Namespaces

- namespace [sensitivityMatrix](#)

Functions

- def [sensitivityMatrix.getSensitivityMatrix](#) (test, mesh, target, n)
- def [sensitivityMatrix.calcSensitivityMat](#) (mesh, biotSavatCoeff, target, u, v, gaussWeight)
- def [sensitivityMatrix.gaussLegendreIntegrationPointsTriangle](#) (test, n)
- def [sensitivityMatrix.calcWeightsGauss](#) (n)

8.17 sensitivityMatrix.py

[Go to the documentation of this file.](#)

```

00001 #Flächenströme der Dreieck um jeden Knoten aufintegrieren
00002 import numpy as np
00003 import scipy
00004
00005 def getSensitivityMatrix(test,mesh,target,n):
00006     """returns the sensitivity Matrix for the mesh"""
00007     biotSavatCoeff = 10**(-7)
00008     [u,v,gaussWeight] = gaussLegendreIntegrationPointsTriangle(test,n)
00009     sensitivityMatrix = calcSensitivityMat(mesh,biotSavatCoeff,target,u,v,gaussWeight)
00010     return sensitivityMatrix
00011
00012 def calcSensitivityMat(mesh,biotSavatCoeff,target,u,v,gaussWeight):
00013     """returns the calculated sensitivityMatrix"""
00014     trianglesPerNode = [len(mesh.neighbours[x]) for x in range(len(mesh.neighbours))]
00015     xTarget,yTarget,zTarget = target.vertices[:,0],target.vertices[:,1],target.vertices[:,2]
00016     xAll,yAll,zAll=[],[],[]
00017     for nodeIndex in range(len(mesh.vertices)):
00018         dCx,dCy,dCz = np.zeros(len(xTarget)),np.zeros(len(xTarget)),np.zeros(len(xTarget))
00019         for triangleIndex in range(trianglesPerNode[nodeIndex]):
00020             nodePoint = mesh.vertices[nodeIndex]
00021             pointB = mesh.vertices[mesh.oneRingList[nodeIndex][triangleIndex][0]]
00022             pointC = mesh.vertices[mesh.oneRingList[nodeIndex][triangleIndex][1]]
00023             nodeX,nodeY,nodeZ = nodePoint
00024             bX,bY,bZ = pointB
00025             cX,cY,cZ = pointC
00026             vX,vY,vZ = (pointC -
pointB)/(scipy.linalg.norm(np.cross(pointC-nodePoint,pointB-nodePoint)))
00027             for gaussIndex in range(len(gaussWeight)):

```

```

00028         xGaussInUV =
nodeX*u[gaussIndex]+bX*v[gaussIndex]+cX*(1-u[gaussIndex]-v[gaussIndex]) #scalar
00029         yGaussInUV =
nodeY*u[gaussIndex]+bY*v[gaussIndex]+cY*(1-u[gaussIndex]-v[gaussIndex]) #scalar
00030         zGaussInUV =
nodeZ*u[gaussIndex]+bZ*v[gaussIndex]+cZ*(1-u[gaussIndex]-v[gaussIndex]) #scalar
00031         distanceNorm =
(np.square(xGaussInUV-xTarget)+np.square(yGaussInUV-yTarget)+np.square(zGaussInUV-zTarget))*(-3/2) #for
biot savat #len of target
00032         dCx = dCx + ((-1)*vZ*(yTarget-yGaussInUV) + vY*(zTarget-zGaussInUV))*distanceNorm *2
*mesh.areas[mesh.neighbours[nodeIndex][triangleIndex]]* gaussWeight[gaussIndex]
00033         dCy = dCy + ((-1)*vX*(zTarget-zGaussInUV) + vZ*(xTarget-xGaussInUV))*distanceNorm *2
*mesh.areas[mesh.neighbours[nodeIndex][triangleIndex]]* gaussWeight[gaussIndex]
00034         dCz = dCz + ((-1)*vY*(xTarget-xGaussInUV) + vX*(yTarget-yGaussInUV))*distanceNorm *2
*mesh.areas[mesh.neighbours[nodeIndex][triangleIndex]]* gaussWeight[gaussIndex]
00035         dCx *= biotSavatCoeff
00036         dCy *= biotSavatCoeff
00037         dCz *= biotSavatCoeff
00038         xAll.append(dCx)
00039         yAll.append(dCy)
00040         zAll.append(dCz)
00041         return [xAll,yAll,zAll]
00042
00043 def gaussLegendreIntegrationPointsTriangle(test,n):
00044     '''returns the weights and the test point for the gauss legendre'''
00045     u,v,ck=[],[],[]
00046     eta,w = calcWeightsGauss(n)
00047     test.calcWeightsGauss = eta,w
00048     for i in range(len(eta)):
00049         for j in range(len(eta)):
00050             u.append((1+eta[i])/2)
00051             v.append((1-eta[i])*(1+eta[j])/4)
00052             ck.append((1-eta[i])/8)*w[i]*w[j])
00053     test.gaußLegendre = [u,v,ck]
00054     return [u,v,ck]
00055
00056 def calcWeightsGauss(n):
00057     '''returns the abscissa and the weights for a Gauss-Legendre quadrature'''
00058     abscissa = np.zeros(n)
00059     weights = np.copy(abscissa)
00060     m = (n+1)/2
00061     for i in np.arange(1,m).reshape(-1):
00062         z = np.cos(np.pi*(i-0.25)/(n+0.5))
00063         z1 = z+1
00064         while abs(z-z1)>(2.2204*10**(-16)): #distance from 1.0 to the next larger double precision
00065             number
00066             p1 = 1
00067             p2 = 0
00068             for j in range(n):
00069                 p3 = np.copy(p2)
00070                 p2 = np.copy(p1)
00071                 p1 = ((2*(j+1)-1)*z*p2-((j+1)-1)*p3)/(j+1)
00072                 pp = n*(z*p1-p2)/(z**2-1)
00073                 z1 = np.copy(z)
00074                 z = z1-p1/pp
00075                 abscissa[int(i-1)] = -z
00076                 abscissa[int(n+1-i-1)] = z
00077                 weights[int(i-1)] = 2/((1-z**2)*pp**2)
00078                 weights[int(n+1-i-1)] = weights[int(i-1)]
00079     return abscissa,weights

```

8.18 subfunctions/streamFunctionOptimization.py File Reference

Namespaces

- namespace [streamFunctionOptimization](#)

Functions

- def [streamFunctionOptimization.streamFunctionOptimization](#) (test, mesh, target, sensitivityMatrix, resistanceMatrix, tikonovFactor)
- def [streamFunctionOptimization.applyTikonovRegularisation](#) (tikonovFactor, redSenMat, redResMat, target)
- def [streamFunctionOptimization.reduceMatricesForBoundaryNodes](#) (mesh, matToRed, zeroFlag)
- def [streamFunctionOptimization.rearrangeReducedMat](#) (mesh, dimToRed, reducedMat)

- `def streamFunctionOptimization.getBoundaryDetails (mesh)`
- `def streamFunctionOptimization.getReducedMat (mesh, dimToRed, reducedMat, zeroFlag)`
- `def streamFunctionOptimization.getNotBoundaryNodes (mesh)`
- `def streamFunctionOptimization.getDimToRed (matToRed)`
- `def streamFunctionOptimization.getNumNodesPerBoundary (mesh)`
- `def streamFunctionOptimization.reexpandSteamFunctionForBoundaryNodes (mesh, reducedSF, boundaryNodes, isNotBoundaryNode, zeroFlag)`
- `def streamFunctionOptimization.updateMeshCurrentDensityMeshFaces (mesh, optStreamFkt)`

8.19 streamFunctionOptimization.py

Go to the documentation of this file.

```
00001 import numpy as np
00002 import scipy.linalg as sc
00003
00004 def streamFunctionOptimization(test,mesh,target,sensitivityMatrix,resistanceMatrix,tikonovFactor):
00005     """returns the magnetic field generated by the optimized stream function. Version for only one coil
00006     part, else a combined mesh is needed"""
00007     PotentialZeroAtBoundaryNodes = False
00008     sensitivityMatrixSingleZKomp=np.transpose(np.array(sensitivityMatrix) [2])
00009     redResMat,boundaryNodes,isNotBoundaryNode =
00010     reduceMatricesForBoundaryNodes(mesh,resistanceMatrix,PotentialZeroAtBoundaryNodes)
00011     redSenMat,boundaryNodes,isNotBoundaryNode =
00012     reduceMatricesForBoundaryNodes(mesh,sensitivityMatrixSingleZKomp,PotentialZeroAtBoundaryNodes)
00013     reducedSF = applyTikonovRegularisation(tikonovFactor,redSenMat,redResMat, target)
00014     test.reducedSF = reducedSF
00015     if not PotentialZeroAtBoundaryNodes:
00016         optStreamFkt =
00017     reexpandSteamFunctionForBoundaryNodes(mesh,reducedSF,boundaryNodes,isNotBoundaryNode,PotentialZeroAtBoundaryNodes)
00018     else: optStreamFkt = reducedSF
00019     bFieldGeneratedByOptSF = [np.dot(np.transpose(sensitivityMatrix[0]),optStreamFkt),
00020     np.dot(np.transpose(sensitivityMatrix[1]),optStreamFkt),
00021     np.dot(np.transpose(sensitivityMatrix[2]),optStreamFkt)]
00022
00023     updateMeshCurrentDensityMeshFaces(mesh,optStreamFkt)
00024     return bFieldGeneratedByOptSF,optStreamFkt
00025
00026 def applyTikonovRegularisation(tikonovFactor,redSenMat,redResMat, target):
00027     """returns the StreamFunction for the reduced Matrix with applied trikonov regularisation."""
00028     tikonovFactor = tikonovFactor*np.shape(redSenMat) [0]/np.shape(redSenMat) [1]
00029     tikRegMat = tikonovFactor * redResMat
00030     reducedSF = np.dot(sc.pinv(np.dot(np.transpose(np.array(redSenMat)),redSenMat) +
00031     np.dot(np.transpose(np.array(tikRegMat)),tikRegMat)),np.dot(np.transpose(np.array(redSenMat)),np.transpose(target.field)))
00032     return reducedSF
00033
00034 def reduceMatricesForBoundaryNodes(mesh, matToRed,zeroFlag):
00035     """returns the for the boundary nodes reduced matrix"""
00036     dimToRed = getDimToRed(matToRed)
00037     if True in dimToRed:
00038         reducedMat = getReducedMat(mesh,dimToRed,matToRed,zeroFlag)
00039         reducedMat,boundaryNodes,notBoundaryNodes = rearrangeReducedMat(mesh,dimToRed,reducedMat)
00040     else:
00041         print("nothing to reduce")
00042     return [reducedMat,boundaryNodes,notBoundaryNodes]
00043
00044 def rearrangeReducedMat(mesh,dimToRed,reducedMat):
00045     """rearranges the reduced matrix. returns: reducedMat,boundaryNodes,notBoundaryNodes"""
00046     numNodesPerBoundary,notBoundaryNodes,boundaryNodes = getBoundaryDetails(mesh)
00047     boundaryNodesFirstInds = [boundaryNodes[i][0] for i in range(len(mesh.openBoundaries))]
00048     for dimToRedInd in np.nonzero(dimToRed) [0]:
00049         prevReducedMat = np.copy(reducedMat)
00050         index1=np.array([':']*np.ndim(prevReducedMat),dtype=object)
00051         index2,index3,index4,index5 = np.copy(index1),np.copy(index1),np.copy(index1),np.copy(index1)
00052         index1[dimToRedInd] = [i for i in range(len(mesh.openBoundaries))]
00053         index2[dimToRedInd] = [x for x in boundaryNodesFirstInds]
00054         index3[dimToRedInd] =
00055         np.arange((len(mesh.openBoundaries)),(len(notBoundaryNodes)+len(mesh.openBoundaries)))
00056         index4[dimToRedInd] = np.transpose(notBoundaryNodes)
00057         index5[dimToRedInd] =
00058         np.arange(((len(prevReducedMat [0])-(sum(numNodesPerBoundary)-len(mesh.openBoundaries))))),
00059         len(prevReducedMat [0]))
00060
00061
00062
00063
00064
00065
```



```

00056         if index1[0] == ':' and index2[0]==':' and index3[0] == ':' and index4[0]==':' and index5[0]
== ':':
00057             reducedMat[:,index1[1]] = prevReducedMat[:,index2[1]]
00058             reducedMat[:,index3[1]] = prevReducedMat[:,index4[1]]
00059             reducedMat=np.delete(reducedMat,index5[1],1)
00060         else:
00061             reducedMat[index1[0]] = prevReducedMat[index2[0]]
00062             reducedMat[index3[0]] = prevReducedMat[index4[0]]
00063             reducedMat=np.delete(reducedMat,index5[0],0)
00064         return reducedMat,boundaryNodes,notBoundaryNodes
00065
00066 def getBoundaryDetails(mesh):
00067     """returns numNodesPerBoundary,notBoundaryNodes,boundaryNodes for the given mesh."""
00068     numNodesPerBoundary = getNumNodesPerBoundary(mesh)
00069     notBoundaryNodes = getNotBoundaryNodes(mesh)
00070     boundaryNodes = [mesh.openBoundaries[1],mesh.openBoundaries[0]]
00071     return numNodesPerBoundary,notBoundaryNodes,boundaryNodes
00072
00073 def getReducedMat(mesh,dimToRed,reducedMat,zeroFlag):
00074     """returns the reduced matrix"""
00075     boundaryNodes = [mesh.openBoundaries[1],mesh.openBoundaries[0]]
00076     for dimToRedInd in np.nonzero(dimToRed)[0]:
00077         index1=np.array([':']*np.ndim(reducedMat),dtype=object)
00078         index2=np.copy(index1)
00079         for boundaryInd in range(len(mesh.openBoundaries)):
00080             if zeroFlag:
00081                 index1[dimToRedInd] = boundaryNodes[boundaryInd][0]
00082                 reducedMat[index1[0:None]]=0
00083             else:
00084                 index1[dimToRedInd] = boundaryNodes[boundaryInd][0]
00085                 index2[dimToRedInd] = np.array(boundaryNodes[boundaryInd][0:None],dtype=int)
00086                 if dimToRedInd:#(==1)
00087                     reducedMat[:,index1[1]] =
np.sum(np.array(reducedMat[:,index2[1]],dimToRedInd)#spalte ersetzen
00088                     else:
00089                         reducedMat[index1[0]] = np.sum(np.array(reducedMat)[index2[0]],dimToRedInd)
00090         return reducedMat
00091
00092 def getNotBoundaryNodes(mesh):
00093     """returns no-boundary nodes of a given mesh"""
00094     isNotBoundaryNode = []
00095     for i in range(len(mesh.vertices[:,0])):
00096         if mesh.boundary[i]:
00097             continue
00098         else: isNotBoundaryNode.append(i)
00099     return isNotBoundaryNode
00100
00101 def getDimToRed(matToRed):
00102     """returns boolean values which dimension should be reduced"""
00103     dimToRed=[]
00104     for i in np.shape(matToRed):
00105         if i == len(matToRed[0]): dimToRed.append(True)
00106         else: dimToRed.append(False)
00107     return dimToRed
00108
00109 def getNumNodesPerBoundary(mesh):
00110     """returns the number of nodes for every boundary"""
00111     numNodesPerBoundary=[]
00112     for i in range(len(mesh.openBoundaries)):
00113         numNodesPerBoundary.append(len(mesh.openBoundaries[i]))
00114     return numNodesPerBoundary
00115
00116 def reexpandStreamFunctionForBoundaryNodes(mesh,reducedSF,boundaryNodes,isNotBoundaryNode,zeroFlag):
00117     """reexpand Streamfunction to all nodes, because the nodes of the first boundary have a potential
of zero"""
00118     streamFunction = np.zeros(len(mesh.vertices))
00119     for boundaryInd in range(len(boundaryNodes)):
00120         if zeroFlag:
00121             streamFunction[boundaryNodes[boundaryInd]]=0
00122         else:
00123             streamFunction[boundaryNodes[boundaryInd]]=reducedSF[boundaryInd]
00124
00125     streamFunction[isNotBoundaryNode]=reducedSF[len(boundaryNodes):]
00126     return streamFunction
00127
00128 def updateMeshCurrentDensityMeshFaces(mesh,optStreamFkt):
00129     """updates the current density of the Faces in the mesh"""
00130     pot1 =
np.transpose(np.array([optStreamFkt[mesh.faces[:,2]]-optStreamFkt[mesh.faces[:,0]],optStreamFkt[mesh.faces[:,2]]-optSt
00131     pot2 =
np.transpose(np.array([optStreamFkt[mesh.faces[:,1]]-optStreamFkt[mesh.faces[:,0]],optStreamFkt[mesh.faces[:,1]]-optSt
00132     pot3 =
np.transpose(np.array([optStreamFkt[mesh.faces[:,2]]-optStreamFkt[mesh.faces[:,1]],optStreamFkt[mesh.faces[:,2]]-optSt
00133     edge1 = mesh.vertices[mesh.faces[:,2]]-mesh.vertices[mesh.faces[:,0]]
00134     edge2 = mesh.vertices[mesh.faces[:,1]]-mesh.vertices[mesh.faces[:,0]]
00135     edge3 = mesh.vertices[mesh.faces[:,2]]-mesh.vertices[mesh.faces[:,1]]
00136     mesh.currentDensityFaces = edge1*pot1+edge2*pot2+edge3*pot3

```

00137

8.20 subfunctions/testCase.py File Reference

Namespaces

- namespace [testCase](#)

Functions

- def [testCase.test_finalSF](#) ()
- def [testCase.test_bFieldGeneratedByOptSF](#) ()
- def [testCase.test_reducedSF](#) ()
- def [testCase.test_gaußLegendre](#) ()
- def [testCase.test_WeightsGauss](#) ()
- def [testCase.test_matElementsShouldGetValue](#) ()
- def [testCase.main](#) ()

Variables

- string [testCase.meshFile](#) = "cylinder_radius500mm_length1500mm.stl"
- string [testCase.targetMeshFile](#) = "sphere_radius150mm.stl"
- int [testCase.gaussOrder](#) = 2
- int [testCase.tikonovFac](#) = 100
- float [testCase.specificConductivityMaterial](#) = 1.8000*10**-8
- float [testCase.conductorThickness](#) = 0.005
- float [testCase.materialFactor](#) = specificConductivityMaterial/conductorThickness
- [testCase.Test](#) = Tester()
- [testCase.Mesh](#) = CylindricMeshGiven(meshFile)
- [testCase.TargetSphere](#) = TargetFieldGiven(targetMeshFile,1)
- [testCase.sensitivityMatrix](#) = getSensitivityMatrix(Test,Mesh,TargetSphere,gaussOrder)
- [testCase.resistanceMatrix](#) = getResistanceMatrix(Test,Mesh,materialFactor)
- [testCase.BField](#)
- [testCase.SFOpt](#)
- list [testCase.matElementsShouldGetValueCorrect](#) = [0.0000000000, 1.0000000000, 2.0000000000, 3.↵
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Generated by Doxygen

[illegible]

- list `testCase.calcWeightsGaussCorrect` = `[[-0.5773502691896257310588680, 0.5773502691896257310588680], [1.↵
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```

8.21 testCase.py

[Go to the documentation of this file.](#)

```
00001
00002 from readMesh import CylindricMeshGiven
00003 from defineTargetField import TargetFieldGiven
00004 from sensitivityMatrix import getSensitivityMatrix
```

```

00005 from resistanceMatrix import getResistanceMatrix
00006 from streamFunctionOptimization import streamFunctionOptimization
00007 from Tester import Tester
00008 import numpy as np
00009
00010 meshFile = "cylinder_radius500mm_length1500mm.stl"
00011 targetMeshFile = "sphere_radius150mm.stl"
00012 gaussOrder = 2
00013 tikonovFac = 100
00014 specificConductivityMaterial = 1.8000*10**-8
00015 conductorThickness = 0.005
00016 materialFactor = specificConductivityMaterial/conductorThickness
00017
00018 Test = Tester()
00019 Mesh = CylindricMeshGiven(meshFile)
00020 TargetSphere = TargetFieldGiven(targetMeshFile,1)
00021 sensitivityMatrix = getSensitivityMatrix(Test,Mesh,TargetSphere,gaussOrder)
00022 resistanceMatrix = getResistanceMatrix(Test,Mesh,materialFactor)
00023 BField,SFOpt =
    streamFunctionOptimization(Test,Mesh,TargetSphere,sensitivityMatrix,resistanceMatrix,tikonovFac)
00024
00025 # SF Optimization
00026
00027 def test_finalSF():
00028     assert np.array_equal(np.array(SFOpt),np.array(SFCorrectValue))
00029
00030 def test_bFieldGeneratedByOptSF():
00031     assert np.array_equal(BField,np.array(bFieldCorrectValue))
00032
00033 def test_reducedSF():
00034     assert np.array_equal(Test.reducedSF,np.array(reducedSFCorrect))
00035
00036 # Sensitivity Matrix
00037
00038 def test_gaußLegendre():
00039     assert np.array_equal(Test.gaußLegendre,np.array(gaußLegendreCorrect))
00040
00041 def test_WeightsGauss():
00042     assert np.array_equal(Test.calcWeightsGauss,np.array(calcWeightsGaussCorrect))
00043
00044 # Resistance Matrix
00045
00046 def test_matElementsShouldGetValue():
00047     assert np.array_equal(Test.matElementsShouldGetValue,np.array(matElementsShouldGetValueCorrect))
00048
00049
00050 matElementsShouldGetValueCorrect = [0.0000000000, 1.0000000000, 2.0000000000, 3.0000000000,
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00062 def main():
00063     test_finalSF()
00064     test_bFieldGeneratedByOptSF()
00065
00066 if __name__ == "__main__":
00067     main()

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8.22 subfunctions/Tester.py File Reference

Classes

- class [Tester.Tester](#)

Namespaces

- namespace [Tester](#)

8.23 Tester.py

[Go to the documentation of this file.](#)

```

00001 class Tester():
00002     def __init__(self):
00003         self.gaußLegendre = []
00004         self.reducedSF = []
00005         self.calcWeightsGauss = []
00006         self.matElementsShouldGetValue = []

```

Index

- `__init__`
 - `defineTargetField.TargetField`, 95
 - `defineTargetField.TargetFieldGiven`, 97
 - `readMesh.CylindricMesh`, 80
 - `readMesh.CylindricMeshGiven`, 91
 - `showSTLMesh.CylindricMeshGiven`, 94
 - `Tester.Tester`, 98
- `applyTikonovRegularisation`
 - `streamFunctionOptimization`, 28
- `areas`
 - `readMesh.CylindricMesh`, 87
 - `readMesh.CylindricMeshGiven`, 91
- `arrangeCircular`
 - `readMesh.CylindricMesh`, 80
- `axes`
 - `showSTLMesh`, 27
- `BField`
 - `testCase`, 54
- `bFieldCorrectValue`
 - `testCase`, 54
- `bFieldGeneratedByOptSF`
 - `main`, 17
- `boundary`
 - `readMesh.CylindricMesh`, 87
 - `readMesh.CylindricMeshGiven`, 91
- `calc3DRotMatByVec`
 - `readMesh.CylindricMesh`, 81
- `calcContoursByTriangluarPotentialCuts`
 - `calcContoursByTriangularPotentialCuts`, 11
- `calcContoursByTriangularPotentialCuts`, 11
 - `calcContoursByTriangluarPotentialCuts`, 11
 - `checkIfPositionsElementIdenticalWithFirstList`, 11
 - `getCutDistancesToEdgeNodes`, 12
 - `getEdgeAttachedTriangles`, 12
 - `getEdgeOpposedNode`, 12
 - `getEdges`, 12
 - `getInnerEdegTriangleNodes`, 13
 - `getInnerEdges`, 13
 - `getNumAttachedTriangles`, 13
 - `getPotentialCutCriteria`, 13
 - `getPotentialSortedCutPoints`, 14
 - `getRawUnarrangedLoops`, 14
 - `getRawUnsortedPoints`, 14
 - `getuvCutPoints`, 14
 - `removeTwoElementsFromArray`, 15
- `calcPotentialLevels`, 15
 - `calcPotentialLevels`, 15
- `calcRotationVec`
 - `readMesh.CylindricMesh`, 81
- `calcSensitivityMat`
 - `sensitivityMatrix`, 25
- `calculateArea`
 - `resistanceMatrix`, 22
- `calculateCurrent`
 - `resistanceMatrix`, 22
- `calculateNormal`
 - `readMesh`, 20
- `calcWeightsGauss`
 - `sensitivityMatrix`, 26
 - `Tester.Tester`, 99
- `calcWeightsGaussCorrect`
 - `testCase`, 63
- `center`
 - `defineTargetField.TargetField`, 96
- `checkIfBoundary`
 - `readMesh.CylindricMesh`, 81
- `checkIfPositionsElementIdenticalWithFirstList`
 - `calcContoursByTriangularPotentialCuts`, 11
- `checkIfVecInVecList`
 - `readMesh`, 20
- `checkStartTriangle`
 - `readMesh.CylindricMesh`, 81
- `compareMultipleElementsBoolean`
 - `resistanceMatrix`, 22
- `compareMultipleElementsBooleanTest`
 - `resistanceMatrix`, 22
- `conductorThickness`
 - `main`, 17
 - `testCase`, 63
- `contour`
 - `main`, 17
- `contourStep`
 - `main`, 17
- `createOneRingList`
 - `readMesh.CylindricMesh`, 82
- `createPreviousResistanceMat`
 - `resistanceMatrix`, 22
- `current`
 - `readMesh.CylindricMesh`, 87
 - `readMesh.CylindricMeshGiven`, 91
- `currentDensityFaces`
 - `readMesh.CylindricMesh`, 87
 - `readMesh.CylindricMeshGiven`, 91
- `defineTargetField`, 16
 - `distanceBetweenPoints`, 16
- `defineTargetField.TargetField`, 95

- `__init__`, 95
 - `center`, 96
 - `fieldValues`, 96
 - `getMagneticFieldValues`, 95
 - `getTargetPoints`, 96
 - `radius`, 96
 - `vertices`, 96
- `defineTargetField.TargetFieldGiven`, 97
 - `__init__`, 97
 - `faces`, 98
 - `fieldValues`, 98
- `distanceBetweenPoints`
 - `defineTargetField`, 16
- `elementInAandB`
 - `resistanceMatrix`, 23
- `elementInArray`
 - `resistanceMatrix`, 23
- `ensureUniformOrientation`
 - `readMesh.CylindricMesh`, 82
- `faces`
 - `defineTargetField.TargetFieldGiven`, 98
 - `readMesh.CylindricMesh`, 88
 - `readMesh.CylindricMeshGiven`, 91
- `fieldValues`
 - `defineTargetField.TargetField`, 96
 - `defineTargetField.TargetFieldGiven`, 98
- `figure`
 - `showSTLMesh`, 27
- `findStartInBoundaryCase`
 - `readMesh.CylindricMesh`, 82
- `formFinalResistanceMat`
 - `resistanceMatrix`, 23
- `gaussLegendreIntegrationPointsTriangle`
 - `sensitivityMatrix`, 26
- `gaussOrder`
 - `main`, 17
 - `testCase`, 63
- `gaußLegendre`
 - `Tester.Tester`, 99
- `gaußLegendreCorrect`
 - `testCase`, 63
- `get2Dcoordinates`
 - `readMesh.CylindricMesh`, 82
- `getAreas`
 - `readMesh.CylindricMesh`, 83
- `getBoundaryDetails`
 - `streamFunctionOptimization`, 29
- `getBoundaryEdges`
 - `readMesh.CylindricMesh`, 83
- `getBoundaryLoopNodes`
 - `readMesh.CylindricMesh`, 83
- `getCurrent`
 - `readMesh.CylindricMesh`, 83
- `getCutDistancesToEdgeNodes`
 - `calcContoursByTriangularPotentialCuts`, 12
- `getDimToRed`
 - `streamFunctionOptimization`, 29
- `getEdgeAttachedTriangles`
 - `calcContoursByTriangularPotentialCuts`, 12
- `getEdgeOpposedNode`
 - `calcContoursByTriangularPotentialCuts`, 12
- `getEdges`
 - `calcContoursByTriangularPotentialCuts`, 12
- `getInnerEdegTriangleNodes`
 - `calcContoursByTriangularPotentialCuts`, 13
- `getInnerEdges`
 - `calcContoursByTriangularPotentialCuts`, 13
- `getMagneticFieldValues`
 - `defineTargetField.TargetField`, 95
- `getMatElementShouldGetValue`
 - `resistanceMatrix`, 23
- `getMesh`
 - `showSTLMesh`, 27
- `getMeshFromSTL`
 - `readMesh`, 21
- `getNeighbourAreas`
 - `readMesh.CylindricMesh`, 84
- `getNeighbourCurrents`
 - `readMesh.CylindricMesh`, 84
- `getNeighbourCurrentsUnsorted`
 - `readMesh.CylindricMesh`, 84
- `getNeighbourhoodMatrix`
 - `resistanceMatrix`, 24
- `getNeighbourTriangleIndices`
 - `readMesh.CylindricMesh`, 84
- `getNormals`
 - `readMesh.CylindricMesh`, 85
- `getNotBoundaryNodes`
 - `streamFunctionOptimization`, 29
- `getNumAttachedTriangles`
 - `calcContoursByTriangularPotentialCuts`, 13
- `getNumNodesPerBoundary`
 - `streamFunctionOptimization`, 29
- `getOneRingList`
 - `readMesh.CylindricMesh`, 85
- `getOpenBoundaries`
 - `readMesh.CylindricMesh`, 85
- `getPartnerElement`
 - `resistanceMatrix`, 24
- `getPotentialCutCriteria`
 - `calcContoursByTriangularPotentialCuts`, 13
- `getPotentialSortedCutPoints`
 - `calcContoursByTriangularPotentialCuts`, 14
- `getRawUnarrangedLoops`
 - `calcContoursByTriangularPotentialCuts`, 14
- `getRawUnsortedPoints`
 - `calcContoursByTriangularPotentialCuts`, 14
- `getReducedMat`
 - `streamFunctionOptimization`, 30
- `getResistanceMatrix`
 - `resistanceMatrix`, 24
- `getResistanceSumForDifferent`
 - `resistanceMatrix`, 24
- `getResistanceSumForSame`

- resistanceMatrix, 25
- getRotatedCopy
 - readMesh.CylindricMesh, 85
- getRotatedVertices
 - readMesh.CylindricMesh, 86
- getSensitivityMatrix
 - sensitivityMatrix, 26
- getSpatialDistancesMatrix
 - resistanceMatrix, 25
- getTargetPoints
 - defineTargetField.TargetField, 96
- getuvCutPoints
 - calcContoursByTriangularPotentialCuts, 14
- getVertexNormals
 - readMesh.CylindricMesh, 86
- givenMesh
 - showSTLMesh, 27
- levelOffset
 - main, 17
- main, 16
 - bFieldGeneratedByOptSF, 17
 - conductorThickness, 17
 - contour, 17
 - contourStep, 17
 - gaussOrder, 17
 - levelOffset, 17
 - materialFactor, 18
 - Mesh, 18
 - meshFile, 18
 - numLevels, 18
 - potentialLevelList, 18
 - resistanceMatrix, 18
 - sensitivityMatrix, 19
 - specificConductivityMaterial, 19
 - streamFunction, 19
 - targetMeshFile, 19
 - TargetSphere, 19
 - Test, 19
 - testCase, 53
 - tikonovFac, 20
- main.py, 101
- matElementsShouldGetValue
 - Tester.Tester, 99
- matElementsShouldGetValueCorrect
 - testCase, 64
- materialFactor
 - main, 18
 - testCase, 74
- Mesh
 - main, 18
 - testCase, 74
- meshFile
 - main, 18
 - testCase, 74
- neighbourareas
 - readMesh.CylindricMesh, 88
- readMesh.CylindricMeshGiven, 92
- neighbourcurrents
 - readMesh.CylindricMesh, 88
 - readMesh.CylindricMeshGiven, 92
- neighbourcurrentUnsorted
 - readMesh.CylindricMesh, 88
 - readMesh.CylindricMeshGiven, 92
- neighbours
 - readMesh.CylindricMesh, 88
 - readMesh.CylindricMeshGiven, 92
- normals
 - readMesh.CylindricMesh, 88
 - readMesh.CylindricMeshGiven, 92
- numLevels
 - main, 18
- oneRingList
 - readMesh.CylindricMesh, 89
 - readMesh.CylindricMeshGiven, 92
- openBoundaries
 - readMesh.CylindricMesh, 89
 - readMesh.CylindricMeshGiven, 93
- orderElementsInCircularArrangement
 - readMesh.CylindricMesh, 86
- potentialLevelList
 - main, 18
- radius
 - defineTargetField.TargetField, 96
- README.md, 102
- readMesh, 20
 - calculateNormal, 20
 - checkIfVecInVecList, 20
 - getMeshFromSTL, 21
 - updateList, 21
- readMesh.CylindricMesh, 79
 - __init__, 80
 - areas, 87
 - arrangeCircular, 80
 - boundary, 87
 - calc3DRotMatByVec, 81
 - calcRotationVec, 81
 - checkIfBoundary, 81
 - checkStartTriangle, 81
 - createOneRingList, 82
 - current, 87
 - currentDensityFaces, 87
 - ensureUniformOrientation, 82
 - faces, 88
 - findStartInBoundaryCase, 82
 - get2Dcoordinates, 82
 - getAreas, 83
 - getBoundaryEdges, 83
 - getBoundaryLoopNodes, 83
 - getCurrent, 83
 - getNeighbourAreas, 84
 - getNeighbourCurrents, 84
 - getNeighbourCurrentsUnsorted, 84

- getNeighbourTriangleIndices, 84
- getNormals, 85
- getOneRingList, 85
- getOpenBoundaries, 85
- getRotatedCopy, 85
- getRotatedVertices, 86
- getVertexNormals, 86
- neighbourareas, 88
- neighbourcurrents, 88
- neighbourcurrentUnsorted, 88
- neighbours, 88
- normals, 88
- oneRingList, 89
- openBoundaries, 89
- orderElementsInCircularArrangement, 86
- removeDoubleEdges, 86
- rotatedCaylinder, 89
- turnAnsSortElements, 87
- v, 89
- vertexNormals, 89
- vertices, 89
- readMesh.CylindricMeshGiven, 90
 - __init__, 91
 - areas, 91
 - boundary, 91
 - current, 91
 - currentDensityFaces, 91
 - faces, 91
 - neighbourareas, 92
 - neighbourcurrents, 92
 - neighbourcurrentUnsorted, 92
 - neighbours, 92
 - normals, 92
 - oneRingList, 92
 - openBoundaries, 93
 - rotatedCaylinder, 93
 - v, 93
 - vertexNormals, 93
 - vertices, 93
- rearrangeReducedMat
 - streamFunctionOptimization, 30
- reducedSF
 - Tester.Tester, 99
- reducedSFCorrect
 - testCase, 74
- reduceMatricesForBoundaryNodes
 - streamFunctionOptimization, 30
- reexpandSteamFunctionForBoundaryNodes
 - streamFunctionOptimization, 30
- removeDoubleEdges
 - readMesh.CylindricMesh, 86
- removeTwoElementsFromArray
 - calcContoursByTriangularPotentialCuts, 15
- resistanceMatrix, 21
 - calculateArea, 22
 - calculateCurrent, 22
 - compareMultipleElementsBoolean, 22
 - compareMultipleElementsBooleanTest, 22
 - createPreviousResistanceMat, 22
 - elementInAandB, 23
 - elementInArray, 23
 - formFinalResistanceMat, 23
 - getMatElementShouldGetValue, 23
 - getNeighbourhoodMatrix, 24
 - getPartnerElement, 24
 - getResistanceMatrix, 24
 - getResistanceSumForDifferent, 24
 - getResistanceSumForSame, 25
 - getSpatialDistancesMatrix, 25
 - main, 18
 - testCase, 75
- rotatedCaylinder
 - readMesh.CylindricMesh, 89
 - readMesh.CylindricMeshGiven, 93
- scale
 - showSTLMesh, 28
- sensitivityMatrix, 25
 - calcSensitivityMat, 25
 - calcWeightsGauss, 26
 - gaussLegendreIntegrationPointsTriangle, 26
 - getSensitivityMatrix, 26
 - main, 19
 - testCase, 76
- SFCorrectValue
 - testCase, 76
- SFOpt
 - testCase, 77
- showSTLMesh, 27
 - axes, 27
 - figure, 27
 - getMesh, 27
 - givenMesh, 27
 - scale, 28
 - your_mesh, 28
- showSTLMesh.CylindricMeshGiven, 94
 - __init__, 94
 - vertices, 94
- showSTLMesh.py, 102
- specificConductivityMaterial
 - main, 19
 - testCase, 77
- streamFunction
 - main, 19
- streamFunctionOptimization, 28
 - applyTikonovRegularisation, 28
 - getBoundaryDetails, 29
 - getDimToRed, 29
 - getNotBoundaryNodes, 29
 - getNumNodesPerBoundary, 29
 - getReducedMat, 30
 - rearrangeReducedMat, 30
 - reduceMatricesForBoundaryNodes, 30
 - reexpandSteamFunctionForBoundaryNodes, 30
 - streamFunctionOptimization, 31
 - updateMeshCurrentDensityMeshFaces, 31

- subfunctions/calcContoursByTriangularPotentialCuts.py,
103, 104
- subfunctions/calcPotentialLevels.py, 107
- subfunctions/defineTargetField.py, 108
- subfunctions/readMesh.py, 109
- subfunctions/resistanceMatrix.py, 114
- subfunctions/sensitivityMatrix.py, 116
- subfunctions/streamFunctionOptimization.py, 117, 118
- subfunctions/testCase.py, 120, 141
- subfunctions/Tester.py, 156
- targetMeshFile
 - main, 19
 - testCase, 77
- TargetSphere
 - main, 19
 - testCase, 78
- Test
 - main, 19
 - testCase, 78
- test_bFieldGeneratedByOptSF
 - testCase, 53
- test_finalSF
 - testCase, 53
- test_gaußLegendre
 - testCase, 53
- test_matElementsShouldGetValue
 - testCase, 54
- test_reducedSF
 - testCase, 54
- test_WeightsGauss
 - testCase, 54
- testCase, 31
 - BField, 54
 - bFieldCorrectValue, 54
 - calcWeightsGaussCorrect, 63
 - conductorThickness, 63
 - gaussOrder, 63
 - gaußLegendreCorrect, 63
 - main, 53
 - matElementsShouldGetValueCorrect, 64
 - materialFactor, 74
 - Mesh, 74
 - meshFile, 74
 - reducedSFCorrect, 74
 - resistanceMatrix, 75
 - sensitivityMatrix, 76
 - SFCorrectValue, 76
 - SFOpt, 77
 - specificConductivityMaterial, 77
 - targetMeshFile, 77
 - TargetSphere, 78
 - Test, 78
 - test_bFieldGeneratedByOptSF, 53
 - test_finalSF, 53
 - test_gaußLegendre, 53
 - test_matElementsShouldGetValue, 54
 - test_reducedSF, 54
 - test_WeightsGauss, 54
 - tikonovFac, 78
 - Tester, 78
 - Tester.Tester, 98
 - __init__, 98
 - calcWeightsGauss, 99
 - gaußLegendre, 99
 - matElementsShouldGetValue, 99
 - reducedSF, 99
 - tikonovFac
 - main, 20
 - testCase, 78
 - turnAnsSortElements
 - readMesh.CylindricMesh, 87
 - updateList
 - readMesh, 21
 - updateMeshCurrentDensityMeshFaces
 - streamFunctionOptimization, 31
- v
 - readMesh.CylindricMesh, 89
 - readMesh.CylindricMeshGiven, 93
- vertexNormals
 - readMesh.CylindricMesh, 89
 - readMesh.CylindricMeshGiven, 93
- vertices
 - defineTargetField.TargetField, 96
 - readMesh.CylindricMesh, 89
 - readMesh.CylindricMeshGiven, 93
 - showSTLMesh.CylindricMeshGiven, 94
- your_mesh
 - showSTLMesh, 28