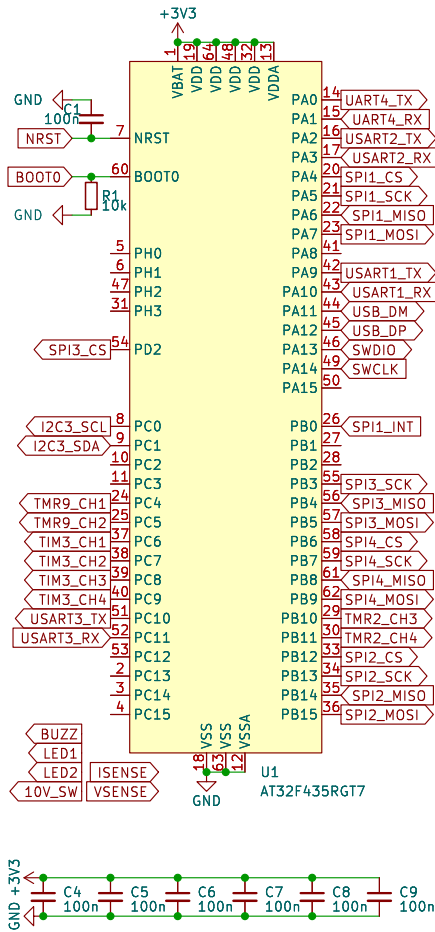
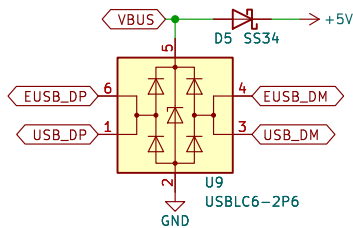


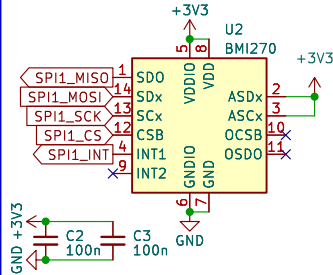
AT32 Microcontroller



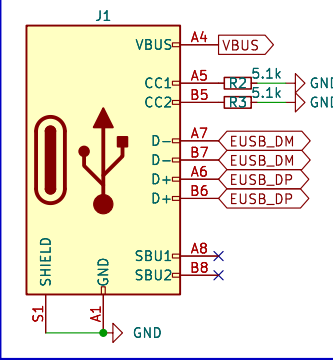
USB ESD



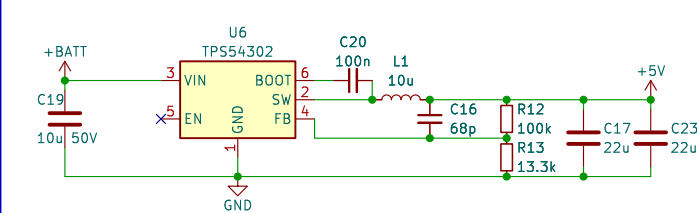
Gyro + Accelerometer



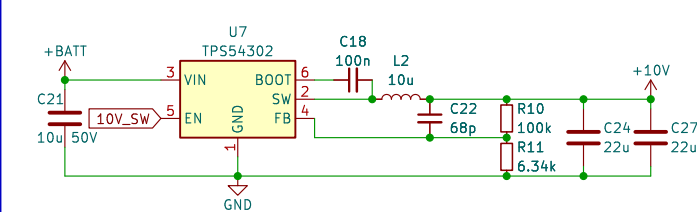
USB C 2.0 Connector



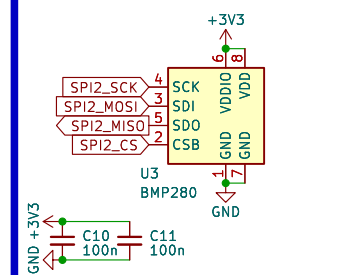
5V Supply



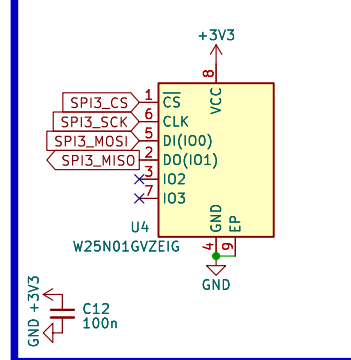
10V Supply



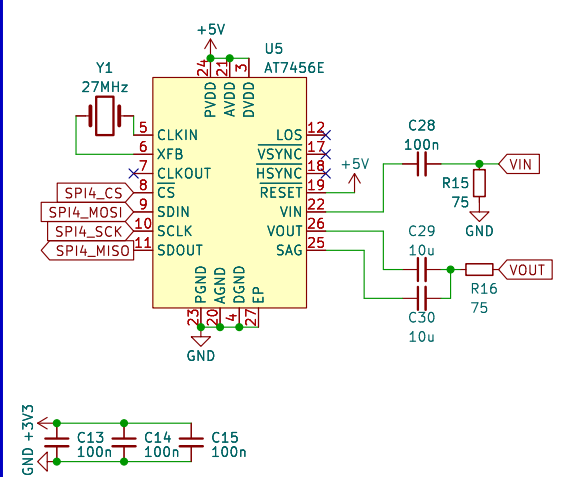
Barometer



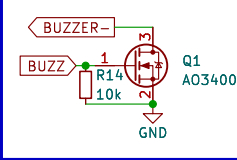
Flash Memory



Analog Video OSD



Buzzer



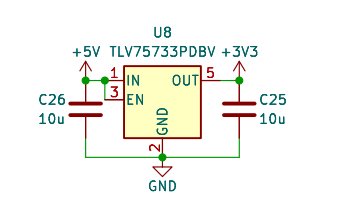
NOTES

- * TMR3 pins are for primary motors.
- * TMR3 pins could be mapped to TMR8.
- * TMR2/TMR9 are for servos.
- * Confirm that crystal is not needed for USB.
- * Check we can interrupt on PB0
- * LED supplies can be 5V as long as LED pins on MCU are FT.
- * Consider TagConnect for SWD

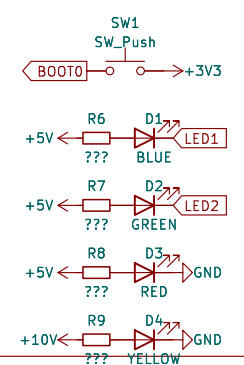
TODD

- * Voltage sense
- * Current sense
- * Pads
- * Connectors

3.3V Supply



Buttons and LEDs



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File: flight-controller.kicad_sch

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