

四. 旋量场

1. Weyl 方程

考虑一阶偏微分的场方程

$$\partial_0 \psi = b^i \partial_i \psi + C \psi \xrightarrow{\partial_0} \partial_0^2 \psi = (b^i \partial_i + C) \partial_0 \psi = (b^i \partial_i + C)^2 \psi = \left[\frac{1}{2} (b^i b^j + b^j b^i) \partial_i \partial_j + 2C b^i \partial_i + C^2 \right] \psi$$

协变性要求: $[b_i, b_j] = -2g_{ij}, C=0$

$\downarrow C=0, [b^i, b^j] = -2g^{ij}$ (反对易)

每个 ψ 为 2 分量波函数 $\begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix}$

$$b_i = \pm \sigma_i, \quad \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad (\sigma^i)^2 = 1, [\sigma^i, \sigma^j] = 0$$

有协变性 $\rightarrow \partial^\mu \partial_\mu \psi = 0$ d'Alembert 方程

Weyl 方程: $\partial_0 \psi = \pm \sigma^i \partial_i \psi$ (2 个方程), 光速无质量粒子

角动量算符 $S^i = \frac{1}{2} \sigma^i, [S^i, S^j] = i \epsilon^{ijk} S^k, S^2 = \frac{3}{4} = \frac{1}{2} \left(\hbar \frac{1}{2} \right) \rightarrow$ 自旋为 $\frac{1}{2}$

描述 $m=0$, 自旋为 $\frac{1}{2}$ 的光速粒子

方程的解: $\psi = e^{ik^\mu x_\mu} \rightarrow \begin{cases} -k^0 = \pm \vec{\sigma} \cdot \vec{k} \\ k^0 = \pm \omega = \pm |\vec{k}| \end{cases} \rightarrow \xi \equiv \frac{\vec{\sigma} \cdot \vec{k}}{|\vec{k}|} = \pm 1$ 螺旋性

$\xi = +1 \rightarrow$ 自旋与动量同向 \rightarrow 右旋态

$\xi = -1 \rightarrow$ 反向 \rightarrow 左旋

空间变换:

这里注意, 逆变与协变的转动 $\partial_i x^j = \partial^j x_i = a^j_i \partial^k x^i = \partial^k x^j$

空间转动: $x'^i = a^i_j x^j$ ($a^i_j a^k_j = \delta^i_k$) 场变换 $\psi' = \Lambda \psi, \partial_i = a^j_i \partial_j$

方程: $\Lambda \partial_0 \psi = \Lambda \sigma^i \partial_i \Lambda^{-1} \psi' \rightarrow \partial_0 \psi' = \pm \Lambda \sigma^i \Lambda^{-1} a^j_i \partial_j \psi' \rightarrow a^j_i \Lambda \sigma^i \Lambda^{-1} = \sigma^j \rightarrow \Lambda^{-1} \sigma^i \Lambda = a^i_j \sigma^j$

\downarrow 转动变化

这里保证转动后方程不变

无穷小转动: $a^i_j = \delta^i_j + \epsilon^i_{jk} \theta^k \rightarrow$ 无限小转动矩阵: $\Lambda = 1 + i \epsilon_{ij} \sigma^i, \epsilon_i$ 为小量

$$\Lambda^{-1} \sigma^i \Lambda = \sigma^i + i \epsilon_j (\delta^i_j \sigma^k - \sigma^j \delta^i_k) + O(\epsilon^2) = \sigma^i - 2 \epsilon_j \epsilon^{ijk} \sigma^k = \sigma^i + \epsilon^{ijk} \sigma^j \theta^k$$

\downarrow 有限角度 $\vec{\theta} = \vec{n} \theta, \partial_n = \vec{n} \cdot \vec{\sigma}$

$$\epsilon_i = \frac{\theta}{2} \delta^i \rightarrow \Lambda = 1 - \frac{i}{2} \vec{\theta} \cdot \vec{\sigma}$$

$$\Lambda = e^{-\frac{i \vec{\theta} \cdot \vec{\sigma}}{2}} = e^{-\frac{i \vec{\theta} \cdot \vec{\sigma}}{2}} \quad \left(\frac{d\Lambda}{d\theta} = -\frac{i}{2} \sigma^i \partial_i \right) \rightarrow \Lambda = e^{-\frac{i \vec{\theta} \cdot \vec{\sigma}}{2}}$$

$= D^{\frac{1}{2}}(\vec{n}, \theta) \rightarrow$ 三维转动下, ψ 内部的二维空间同转 ($\dim SU(2) = 3$)

$\vec{S} = \frac{\hbar}{2}$ 为自旋角动量算符, σ 内部转 \rightarrow 旋量场

时空反演

空间反演 $P \quad a^\mu_\nu = \begin{pmatrix} 1 & & \\ & -1 & \\ & & -1 \end{pmatrix} \xrightarrow{\text{代入方程}} \partial_0 \psi' = \pm \Lambda \delta^i_\Lambda \underline{a^j_i} \partial_j \psi \quad \partial_0 \psi = \mp \Lambda \delta^i_\Lambda \partial_i \psi$
 反射不变条件 \downarrow

$\Lambda \delta^i_\Lambda = -\delta^i \rightarrow [\Lambda, \delta^i] = 0 \rightarrow$ 不存在酉的 Λ

时间 $a^\mu_\nu = \begin{pmatrix} -1 & & \\ & 1 & \\ & & 1 \end{pmatrix} \rightarrow \Lambda \delta^i_\Lambda = -\delta^i \rightarrow$ 同上 宇称不守恒

时空同时反演 \rightarrow 守恒

正反粒子变换 C Weyl 方程共轭 $\cdot \delta^2$: $\partial_0 \psi_c = \mp \delta^i \partial_i \psi_c$, $\psi_c = C\psi \equiv \eta_c \delta^2 \psi^\dagger \rightarrow \psi_c$ 与 ψ 为螺旋性相反的正反粒子
 $\delta^2 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \delta^2 \delta^2 = -\delta^2 \delta^2$
 $C+P \rightarrow \Lambda^i \delta^i_\Lambda = \delta^i \rightarrow CP$ 后 Weyl 方程不变 $\rightarrow CP$ 不变性

2. Dirac 方程: 自旋为 $\frac{1}{2}$, 有质量 $\xrightarrow{m=0}$ 简化为 Weyl

耦合: 1. 左旋态、右旋态可叠加 (相对观者 $\xrightarrow{v \xrightarrow{z} v} \xrightarrow{v} \xrightarrow{v}$)

$$\begin{cases} (\partial_0 + \delta^i \partial_i) \psi_R = -im \psi_L \\ (\partial_0 - \delta^i \partial_i) \psi_L = -im \psi_R \end{cases} \xrightarrow{\text{耦合}} (\partial_0 + \delta^i \partial_i)(\partial_0 - \delta^i \partial_i) = (\partial_0^2 + \underbrace{\delta^i \delta^i \partial_i \partial_i}_{\text{四维反对称}}) = \partial_\mu \partial^\mu$$

 $\partial_\mu \partial^\mu \psi_i = -m^2 \psi_i, \quad i=R, L$

Dirac 方程 $(\partial_0 + \alpha^i \partial_i + im\beta) \psi = 0$, $\alpha = \begin{pmatrix} \delta & 0 \\ 0 & -\delta \end{pmatrix}$, $\beta = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$. 可有: $\psi = \begin{pmatrix} \psi_R \\ \psi_L \end{pmatrix} \rightarrow$ 内部有自由度

表象: $p \gg mc \rightarrow$ 用 Weyl 表象 ψ_R, ψ_L
 低速/质量大 \rightarrow Dirac 表象 $\psi = \begin{pmatrix} \psi \\ \chi \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} \psi_R + \psi_L \\ \psi_R - \psi_L \end{pmatrix} \quad u = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$ 变换

各种表象出现的原因
 态矢有多少性质?

$\beta = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \alpha = \begin{pmatrix} 0 & \delta \\ \delta & 0 \end{pmatrix}$, $\begin{cases} \partial_0 \psi + \delta \cdot \nabla \chi + im\psi = 0 \\ \partial_0 \chi + \delta \cdot \nabla \psi - im\chi = 0 \end{cases} \xrightarrow{k \rightarrow 0 \text{ 时}} \psi \text{ 正频项}, \chi \text{ 负频项}$

Majorana 表象

4元数与3矩阵
(未发现有趣性质)

粒子态 ψ_P , 反粒子态 ψ_A , 变换: $\psi_A = \hat{C}\psi = \eta_C \delta^2 \psi_P^*$

书上为 $\frac{1}{\sqrt{2}}$?

$$\psi = \begin{pmatrix} \psi_A \\ \psi_P \end{pmatrix} = \begin{pmatrix} \eta_C \delta^2 \psi_P^* \\ \psi_P \end{pmatrix} \quad \text{取 } U = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & \delta^2 \\ \delta^2 & -1 \end{pmatrix}, \quad \psi_M = U\psi, \quad \psi_M = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & \delta^2 \\ \delta^2 & -1 \end{pmatrix} \begin{pmatrix} \eta_C \delta^2 \psi_P^* \\ \psi_P \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} i\delta^2 \text{Im}\psi_P \\ -\text{Re}\psi_P \end{pmatrix}$$

实结果 ψ_M , 有: $a_M^i = U a_P^i U^\dagger, \beta_M^i = U \beta_P^i U^\dagger \rightarrow a_M^i$ 为实, β_M^i 为虚 \rightarrow 全方程 $(\partial_0 + \alpha^i \partial_i + i m \beta) \psi_M = 0$ 全实数

$$a_M^1 = \begin{pmatrix} \delta^1 & 0 \\ 0 & \delta^1 \end{pmatrix}, a_M^2 = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}, a_M^3 = \begin{pmatrix} \delta^3 & 0 \\ 0 & -\delta^3 \end{pmatrix}, \beta_M = \begin{pmatrix} \delta^0 & 0 \\ 0 & -\delta^0 \end{pmatrix}$$

特征投影算符:

$$\text{定义 } P_L = \frac{1}{2} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}, P_R = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \rightarrow P_L \psi = \frac{1}{\sqrt{2}} \begin{pmatrix} \psi_L \\ -\psi_L \end{pmatrix}, P_R \psi = \frac{1}{\sqrt{2}} \begin{pmatrix} \psi_R \\ \psi_R \end{pmatrix}$$

$$P_L^2 = P_L, P_R^2 = P_R; P_R P_L = P_R P_L = 0, P_L + P_R = 1 \rightarrow P_L \psi \text{ 与 } P_R \psi \text{ 正交}$$

? 联系

协变形式: (Dirac表象)

γ^μ 是起何作用

? 联系

1. Dirac 矩阵为厄米矩阵: $[\alpha_i, \alpha_j] = 2\delta_{ij}, [\alpha_i, \beta] = 0, \beta^2 = 1$

2. γ 矩阵: $\gamma^0 = \beta, \gamma^i = \beta \alpha^i, \rightarrow (\gamma^0)^\dagger = \gamma^0; (\gamma^i)^\dagger = -\gamma^i$ ($\gamma^0 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \gamma^i = \begin{pmatrix} 0 & \delta^i \\ \delta^i & 0 \end{pmatrix}$)

$$\{\gamma^\mu, \gamma^\nu\} = 2g^{\mu\nu} \quad \text{相当于一个“体元” ?}$$

3. 定义 $\gamma^5 = \gamma^5 = i\gamma^0\gamma^1\gamma^2\gamma^3 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, [\gamma^5, \gamma^\mu] = 0, (\gamma^5)^2 = 1$

$$P_L = \frac{1}{2}(1 - \gamma^5), P_R = \frac{1}{2}(1 + \gamma^5) \quad P_L \psi \text{ 与 } P_R \psi \text{ 为 } \gamma^5 \text{ 本征态} \rightarrow \gamma^5 P_L \psi = -P_L \psi, \gamma^5 P_R \psi = P_R \psi \rightarrow \gamma^5 \text{ 称手征算符}$$

$$(i\gamma^\mu \partial_\mu - m)\psi = 0, \text{ 共轭: } i\partial_\mu \bar{\psi} \gamma^\mu + m\bar{\psi} = 0, \bar{\psi} = \psi^\dagger \gamma^0 \quad (\text{Dirac 共轭})$$

$$\text{Feynman 符号: } \gamma \text{ 与 4 维矢相乘: } \gamma^\mu \partial_\mu = \not{\partial}, \gamma^\mu k_\mu = \not{k}, \gamma^\mu p_\mu = \not{p}$$

$$(i\not{\partial} - m)\psi = 0$$

平面波解: Dirac 表象的 ψ 与 χ 形式同 k -G 方程 \rightarrow 设 $\psi(x) = W e^{-ik^\mu x_\mu}, k^0 = \sqrt{k^2 + m^2} = \omega, W = \begin{pmatrix} \xi \\ \eta \end{pmatrix}$

$$\text{代入: } (K - m)\psi = (\gamma^0 k_0 + \gamma^i k_i - m)W = 0 \rightarrow \begin{pmatrix} m - k_0 & \vec{\sigma} \cdot \vec{k} \\ -\vec{\sigma} \cdot \vec{k} & m + k_0 \end{pmatrix} \begin{pmatrix} \xi \\ \eta \end{pmatrix} = 0$$

当 W 为螺旋度 s 本征态 $\rightarrow \vec{\sigma} \cdot \vec{k} \Rightarrow s|\vec{k}|$

共轭

正频 $u(k, s) = W(\omega, k, s)$

负频 $v(k, s) = W(-\omega, -k, s)$

1. 形式上 使方程保持协变性

2. 每一个 γ^μ 对应着 ∂_μ

而 $\gamma^\mu A_\mu$ 的实际效果

空间转动:



$$D^{\frac{1}{2}}(n_z \rightarrow n_k) = D^{\frac{1}{2}}(n_z, \phi) D^{\frac{1}{2}}(n_y, \theta) = e^{-i\phi\sigma^3/2} \cdot e^{-i\theta\sigma^2/2}$$

$$= \begin{pmatrix} e^{-i\frac{\theta}{2}\cos\frac{\phi}{2}} & -e^{-i\frac{\theta}{2}\sin\frac{\phi}{2}} \\ e^{i\frac{\theta}{2}\sin\frac{\phi}{2}} & e^{i\frac{\theta}{2}\cos\frac{\phi}{2}} \end{pmatrix} \begin{pmatrix} e^{-i\frac{\theta}{2}\cos\frac{\phi}{2}} \\ e^{i\frac{\theta}{2}\sin\frac{\phi}{2}} \end{pmatrix}$$

$$\xi = \uparrow \text{本征态}: \xi_+ = D^{\frac{1}{2}}(n_k \rightarrow n_z)(0) = \begin{pmatrix} e^{i\frac{\theta}{2}\sin\frac{\phi}{2}} \\ e^{i\frac{\theta}{2}\cos\frac{\phi}{2}} \end{pmatrix}$$

$$\xi_- = D^{\frac{1}{2}}(0) = \begin{pmatrix} -e^{i\frac{\theta}{2}\sin\frac{\phi}{2}} \\ e^{i\frac{\theta}{2}\cos\frac{\phi}{2}} \end{pmatrix}$$

$$\downarrow (\gamma^i)^{\dagger} = -\gamma^i \rightarrow W^{\dagger}(\gamma^0 k_0 - \gamma^i k_i - m) = 0$$

$$W^{\dagger}(x)W + W^{\dagger}(x)W \rightarrow W^{\dagger}(\omega, k, \xi) \gamma^0 W(\omega, k, \xi') = \frac{m}{k_0} W^{\dagger}(\omega, k, \xi) W(\omega, k, \xi') \quad (\bar{W} = W^{\dagger} \gamma^0)$$

$$\text{分离正负频: } \bar{u}u = \frac{m}{k_0} u^{\dagger}u; \quad \bar{v}v = -\frac{m}{k_0} v^{\dagger}v \rightarrow u(k, \xi) = N \begin{pmatrix} \xi \\ \frac{\xi \cdot k}{\omega + m} \xi \end{pmatrix}; \quad v(k, \xi) = \begin{pmatrix} \frac{\xi \cdot k}{\omega + m} \eta \\ \eta \end{pmatrix}$$

$$\text{归一化: } u^{\dagger}(k, \xi) u(k, \xi') = 2\omega \cdot \delta_{\xi\xi'}, \quad v^{\dagger}(k, \xi) v(k, \xi') = 2\omega \delta_{\xi\xi'}$$

$$\downarrow N = \sqrt{\omega + m} \quad (\xi^{\dagger} \xi = \eta^{\dagger} \eta = 1 \text{ (归一化)})$$

正交归一关系

$$\bar{u}(k, \xi) u(k, \xi') = (\omega + m) \left(1 - \frac{\omega^2 - m^2}{(\omega + m)^2} \right) \delta_{\xi\xi'} = 2m \delta_{\xi\xi'}$$

$$\bar{v}(k, \xi) v(k, \xi') = (\omega + m) \left(\frac{\omega^2 - m^2}{(\omega + m)^2} - 1 \right) \delta_{\xi\xi'} = -2m \delta_{\xi\xi'}$$

$$\bar{u}v = \bar{v}u = 0$$

$$\text{投影算符: } P_+ = \frac{1}{2m} \sum_{\xi} u(k, \xi) \bar{u}(k, \xi), \quad P_- = -\frac{1}{2m} \sum_{\xi} v(k, \xi) \bar{v}(k, \xi) \Rightarrow \text{代入 } u, v \text{ 表达式: } P_+ = \frac{\omega + m}{2m} \sum \begin{pmatrix} \xi \\ \frac{\xi \cdot k}{\omega + m} \xi \end{pmatrix} \begin{pmatrix} \xi^{\dagger} & -\frac{\xi \cdot k}{\omega + m} \xi^{\dagger} \end{pmatrix}$$

$$P_+ u(s) = u(s), \quad P_- v(s) = v(s), \quad ebe = 0$$

$$(P_+)^2 = P_+, \quad (P_-)^2 = P_-, \quad P_+ P_- = P_- P_+ = 0, \quad \underline{P_+ + P_- = 1}$$

$$u, v \text{ 完备性: } \frac{1}{2m} \sum_{\xi} u \bar{u} - v \bar{v} = 1 \quad \leftarrow$$

$$= \frac{1}{2m} \sum \begin{pmatrix} \omega + m \xi \xi^{\dagger} & -\xi \xi^{\dagger} (k \cdot \xi) \\ 0 \cdot k \xi \xi^{\dagger} & -0 \cdot k \xi \xi^{\dagger} \frac{k \cdot \xi}{\omega + m} \end{pmatrix} = \frac{\gamma^{\mu} k_{\mu} + m}{2m} = \frac{k + m}{2m}$$

$$\sum \xi \xi^{\dagger} = \xi_+ \xi_+^{\dagger} + \xi_- \xi_-^{\dagger} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$P_- = \frac{-k + m}{2m}$$

? 内空间?

与 \mathbb{C}^2 实数内积空间

3. Dirac 方程变换性质

1. 相对论协变: Lorentz 变换: $x'^{\mu} = a^{\mu}_{\nu} x^{\nu}$, $\psi' = \Lambda \psi \Rightarrow \partial_{\mu} = a^{\nu}_{\mu} \partial'_{\nu}$

$$\downarrow \quad (i\hbar \gamma^{\mu} \Lambda^{\dagger} a'_{\mu} \partial'_{\nu} - m) \psi' = 0 \xrightarrow{\text{形式不变}} \underline{\underline{\Lambda \gamma^{\mu} \Lambda^{\dagger} a'_{\mu} = \gamma^{\nu}}}$$

无限小正规变换: $a^{\mu}_{\nu} = g^{\mu}_{\nu} + \varepsilon^{\mu}_{\nu}$, 正规: $\langle a^{\mu}_{\nu}, a^{\lambda}_{\rho} \rangle = \langle \nu, \rho \rangle$ $a^{\mu}_{\lambda} a^{\lambda}_{\nu} = g^{\mu}_{\nu} \rightarrow \varepsilon^{\mu\nu} = -\varepsilon^{\nu\mu}$

$$\text{设 } \Lambda = 1 + a \varepsilon_{\mu\nu} \gamma^{\mu} \gamma^{\nu} \rightarrow \text{代入: } a \varepsilon_{\mu\lambda} (\gamma^{\mu} \gamma^{\nu} \gamma^{\lambda} - \gamma^{\nu} \gamma^{\lambda} \gamma^{\mu}) = \varepsilon^{\mu}_{\nu} \gamma^{\nu}$$

$$\downarrow$$

$$\varepsilon_{\mu\nu} \text{ 反对称} + \gamma \text{ 反对易: } a \varepsilon_{\mu\lambda} (\underbrace{\gamma^{\mu} \gamma^{\nu} \gamma^{\lambda} - \gamma^{\nu} \gamma^{\lambda} \gamma^{\mu}}_{-\gamma^{\nu} [\gamma^{\mu}, \gamma^{\lambda}]} + (\gamma^{\mu} \gamma^{\nu}) \gamma^{\lambda}) = -2a \varepsilon_{\nu}^{\mu} \gamma^{\nu} + 2a \varepsilon^{\mu}_{\lambda} \gamma^{\lambda}$$

$$\overset{a = \frac{1}{4}}{\downarrow} \quad \quad \quad = 4a \varepsilon^{\mu}_{\nu} \gamma^{\nu} = \varepsilon^{\mu}_{\nu} \gamma^{\nu} \quad \quad \quad \overset{a = \frac{1}{4}}{\downarrow}$$

$$\Lambda = 1 + \frac{1}{8} \varepsilon_{\mu\nu} (\gamma^{\mu} \gamma^{\nu} - \gamma^{\nu} \gamma^{\mu}) \rightarrow$$

双线性协变: Dirac 共轭 $\bar{\psi} = \psi^{\dagger} \gamma^0$, $\Lambda^{\dagger} = \gamma^0 \Lambda^{\dagger} \gamma^0 \rightarrow \bar{\psi}' = \psi'^{\dagger} \gamma^0 = (\Lambda \psi)^{\dagger} \gamma^0 = \psi^{\dagger} \Lambda^{\dagger} \gamma^0 = \bar{\psi} \Lambda^{-1}$

γ 线性 + ψ 线性: \square

$\bar{\psi} \psi$	$\bar{\psi} \gamma^{\mu} \psi$	$\bar{\psi} \gamma^{\mu} \gamma^{\nu} \psi$	$\bar{\psi} \gamma^5 \psi$	$\bar{\psi} \gamma^5 \gamma^{\mu} \psi$
标量	矢量	反对称张量	赝标量	赝矢量

Pf: 1) $\bar{\psi}' \psi' = \bar{\psi} \Lambda^{\dagger} \Lambda \psi = \bar{\psi} \psi$ 2) $\bar{\psi}' \gamma^{\mu} \psi' = \bar{\psi} \Lambda^{\dagger} \gamma^{\mu} \Lambda \psi = a^{\mu}_{\nu} \bar{\psi} \gamma^{\nu} \psi$ 3) $\bar{\psi}' \gamma^{\mu} \gamma^{\nu} \psi' = \bar{\psi} \Lambda^{\dagger} \gamma^{\mu} \gamma^{\nu} \Lambda \psi = a^{\mu}_{\lambda} a^{\nu}_{\rho} \bar{\psi} \gamma^{\lambda} \gamma^{\rho} \psi$

4) $\bar{\psi}' \gamma^5 \psi' = \bar{\psi} \Lambda^{\dagger} \gamma^5 \Lambda \psi = \bar{\psi} \gamma^5 \psi$ 5) 同 2)

流矢量: $j^{\mu} = q \cdot \bar{\psi} \gamma^{\mu} \psi \rightarrow \partial_{\mu} j^{\mu} = 0$ 为标量, L 变换不变

$$j^0 = q \bar{\psi} \gamma^0 \psi = q \psi^{\dagger} \psi = q \quad ; \quad j^i = q \bar{\psi} \gamma^i \psi = q \psi^{\dagger} \gamma^0 \gamma^i \psi = q \psi^{\dagger} \beta \alpha^i \psi = q \psi^{\dagger} \alpha^i \psi$$

2. 时空对称性:

空间转动: $\varepsilon_{ij} = \varepsilon_{ijk} \theta^k$, 同前 $\rightarrow \Lambda = 1 - \frac{i}{2} \theta \cdot \Sigma$, $\Sigma^i = -\frac{1}{2} \varepsilon_{ijk} \gamma^j \gamma^k = \begin{pmatrix} \sigma^i & 0 \\ 0 & \sigma^i \end{pmatrix}$

$$[x^i, x^j] = -2g^{ij} \quad , \quad [s^i, s^j] = i \varepsilon^{ij}_k S^k$$

空间反射: $a^{\mu}_{\nu} = \begin{pmatrix} 1 & \\ & -1 \end{pmatrix}$, $\det(a^{\mu}_{\nu}) = -1 \rightarrow$ 非正规 L 变换

$$\Lambda^{\dagger} \gamma^0 \Lambda = \gamma^0; \Lambda^{\dagger} \gamma^i \Lambda = -\gamma^i \rightarrow P = \Lambda = \eta_P \gamma^0, \quad \eta_P^{\dagger} \eta_P = 1 \rightarrow \text{空间反射宇称守恒}$$

□内部空间与外部空间耦合?

$\bar{\psi}\psi$ 标量
 $\bar{\psi}\gamma^\mu\psi$ 矢量
 $\bar{\psi}\gamma^\mu\gamma^\nu\psi$ 反对称张量
 $\bar{\psi}\gamma^5\psi$ 赝标量
 $\bar{\psi}\gamma^5\gamma^\mu\psi$ 赝矢量

1) 略. 2) $\bar{\psi}\gamma^\mu\psi = \sum_{n=1}^{\infty} \psi_n^\dagger \psi_n$ 同上
 3) 同2)
 4) $\bar{\psi}\gamma^5\psi = \bar{\psi}\gamma^5\psi = -\bar{\psi}\gamma^5\psi$
 5) $\bar{\psi}\gamma^5\gamma^\mu\psi = \bar{\psi}\gamma^5\gamma^\mu\psi = \sum_{n=1}^{\infty} \psi_n^\dagger \psi_n$

时间反演: $\alpha = \begin{pmatrix} 1 & \\ & -1 \end{pmatrix}$, Dirac 方程复共轭: $(-i\gamma^\mu\partial_\mu - m)\psi^\dagger = 0$

η_c 的含义? □

$$[i(\gamma^0\partial_0 - \gamma^1\partial_1 - \gamma^2\partial_2 - \gamma^3\partial_3) - m]\psi^\dagger = 0 \rightarrow [i(\gamma^0\partial_0' - \gamma^1\partial_1' + \gamma^2\partial_2' - \gamma^3\partial_3') - m]\psi^\dagger = 0$$

$$\begin{aligned} \gamma^0\gamma^0 &= 1, \gamma^i\gamma^i = -1 \\ \gamma^0\gamma^i &= -\gamma^i\gamma^0, \gamma^i\gamma^j = -\gamma^j\gamma^i \end{aligned} \Rightarrow \Lambda = \eta_T \gamma^0 \gamma^3, \eta_T \eta_T = 1, T\psi = \Lambda\psi^\dagger$$

↪ 反么正

3. 正反粒子变换:

$$\psi_c = C\psi = \eta_c \gamma^2 \psi^*$$

$$\gamma^i = -\gamma^i, \text{ else } \gamma^i = \gamma^i$$

$$\text{引入规范场 } A_\mu \rightarrow \text{Dirac 方程: } [\gamma^\mu(i\partial_\mu - qA_\mu) - m]\psi = 0; \text{ 复共轭: } [\gamma^\mu(-i\partial_\mu - qA_\mu) - m]\psi = 0$$

$$\text{故 } \eta_c \gamma^2 \text{ 作用: } [\gamma^\mu(i\partial_\mu + qA_\mu) - m]\psi = 0 \Rightarrow \text{电荷反号 (电荷)}$$

Majorana 表示中为实场, 无规范变换 \Rightarrow 无规范场作用

↓
为中性粒子, $q = -q = 0$

↓
Dirac 方程正反粒子变换 = 电荷共轭变换

4. 旋量场量子化

1. 拉氏密度与观测量密度

为何? □ 拉氏密度 $\mathcal{L} = \bar{\psi}(i\gamma^\mu\partial_\mu - m)\psi \rightarrow \frac{\partial \mathcal{L}}{\partial \bar{\psi}} = 0 \rightarrow (i\partial - m)\psi = 0$

代入: $\mathcal{L} = \bar{\psi} \cdot 0 = 0$

$$\frac{\partial \mathcal{L}}{\partial \psi} - \partial_\mu \frac{\partial \mathcal{L}}{\partial \partial_\mu \psi} = 0 \rightarrow -m\bar{\psi} - i\partial_\mu \bar{\psi} \gamma^\mu = 0$$

旋量场的观测量密度:

★ 故以前所有 $\langle \psi^\dagger, \psi^\dagger \rangle = -1 \rightarrow \langle \psi^\dagger, i\psi^\dagger \rangle = 1$

正则动量: $\pi = \frac{\partial \mathcal{L}}{\partial \dot{\psi}} = i\bar{\psi}\gamma_0 = i\psi^\dagger \rightarrow \psi \text{ 与 } i\psi^\dagger \text{ 构成相空间 (当 } \omega \text{ 为 1 阶出现该现象)}$

猜想: Dirac方程 - 半自由度融入内部空间? \square

$$\mathcal{H} = \pi \dot{\psi} - \mathcal{L} = \psi^\dagger i \partial_0 \psi = \psi^\dagger (-i \alpha_0 \cdot \nabla + m \beta) \psi$$

$$\downarrow$$

$$\mathcal{P}^\mu = \pi \partial_\mu \psi - \mathcal{L} = \psi^\dagger i \partial^\mu \psi$$

$$j^\mu = q \bar{\psi} \gamma^\mu \psi \rightarrow Q = q \psi^\dagger \psi$$

2. Jordan-Wigner 量子化

\square 正则与反正则 - P 与 Q 是否独立?

问题: 正则量子化得到的对易关系为 Bose 子

\downarrow
Fermi 子 \rightarrow 应为反对易

动量空间: $\psi(x, t) = \sum_{\vec{k}} \int \frac{d^3k}{(2\pi)^3 2\omega} [U(k, \xi) c_{k\xi} e^{-i(\omega t - \vec{k} \cdot \vec{x})} + V(k, \eta) d_{k\eta}^\dagger e^{i(\omega t - \vec{k} \cdot \vec{x})}]$

$$\psi^\dagger(x, t) = \sum_{\vec{k}} \int \frac{d^3k}{(2\pi)^3 2\omega} [U^\dagger(k, \eta) c_{k\eta}^\dagger e^{i(\omega t - \vec{k} \cdot \vec{x})} + V^\dagger(k, \xi) d_{k\xi} e^{-i(\omega t - \vec{k} \cdot \vec{x})}]$$

\downarrow

$$H = \int d^3x \psi^\dagger i \partial_0 \psi = \sum_{\vec{k}} \int d^3k \omega (c_{k\xi}^\dagger c_{k\xi} - d_{k\xi} d_{k\xi}^\dagger)$$

Jordan-Wigner 量子化: $\{c_{k\xi}, c_{k'\xi'}^\dagger\} = \delta_{\xi\xi'} \delta(k-k')$ else = 0

\downarrow $\{d_{k\xi}, d_{k'\xi'}^\dagger\} = \delta_{\xi\xi'} \delta(k-k')$

\downarrow $H = \sum_{\vec{k}} \int d^3k \omega [c_{k\xi}^\dagger c_{k\xi} + d_{k\xi}^\dagger d_{k\xi} - \delta(0)]$

\uparrow 零点能

1) $\partial_x, \partial_y, \partial_z$ 的本征矢

ψ, ψ^\dagger 的反对易:

$$[\psi_\alpha(x), \psi_\beta^\dagger(x')]_{t=t'} = \sum_{\xi\xi'} \int d^3k d^3k' [U_\alpha(k, \xi) c_{k\xi} \psi_\beta(x) + V_\alpha(k, \xi) d_{k\xi}^\dagger \psi_\beta(x), U_\beta^\dagger(k', \xi') c_{k'\xi'}^\dagger \psi_\beta^\dagger(x') + V_\beta^\dagger(k', \xi') d_{k'\xi'} \psi_\beta^\dagger(x')]_{t=t'}$$

$$= \sum_{\xi\xi'} \int d^3k \delta_{\xi\xi'} U_\alpha(k, \xi) U_\beta^\dagger(k, \xi) \psi_\alpha(x) \psi_\beta^\dagger(x') - V_\alpha V_\beta^\dagger \psi_\alpha^\dagger(x) \psi_\beta(x')$$

$$= \int \frac{d^3k}{(2\pi)^3 2\omega} \delta_{\alpha\beta} \gamma^0 [(k+m) e^{-ik(x-x')} - (k-m) e^{ik(x-x')}] = \int \frac{d^3k}{(2\pi)^3 2\omega} 2\omega e^{ik(x-x')} \delta_{\alpha\beta} = \delta_{\alpha\beta} \delta(x-x')$$

\square 计算

协变反对易:

$$\begin{aligned} [\psi_\alpha(x), \bar{\psi}_\beta(x')] &= \int \frac{d^3k}{(2\pi)^3 2m} [(k+m)e^{-i(k-x')} + (k-m)e^{i(k-x)}]_{\alpha\beta} = (i\not{\partial}+m)_{\alpha\beta} \int \frac{d^3k}{(2\pi)^3 2m} (e^{-ik(x-x')} - e^{ik(x-x')}) \\ &= i \underbrace{(i\not{\partial}+m)_{\alpha\beta} \Delta(x-x')}_{S_{\alpha\beta}(x-x')} \\ \text{else} &= 0 \end{aligned}$$

箱归一化

$$\int d^3k \rightarrow \sum_k \frac{(2\pi)^3}{V} ; k \rightarrow \frac{2\pi}{L}(n, m, l) ; \delta(k-k') \rightarrow \frac{V}{(2\pi)^3} \delta_{kk'}$$

$$\downarrow \text{则: } c_k \rightarrow \sqrt{\frac{V}{(2\pi)^3}} c_k, dk \rightarrow \sqrt{\frac{V}{(2\pi)^3}} dk$$

$$\psi(x,t) = \sum_{k,s} \frac{1}{\sqrt{2mV}} [U(k,s) c_{ks} e^{-i(kx-Et)} + V(k,s) d_{ks}^\dagger e^{i(kx-Et)}]$$

\downarrow

粒子数表象 $N_{ks} = c_{ks}^\dagger c_{ks} \longrightarrow N_{ks} |n_{ks}\rangle = n_{ks} |n_{ks}\rangle$
 (对 d_{ks}, d_{ks}^\dagger 同样) $\hookrightarrow (c_{ks})^2 = \frac{1}{2} \{c_{ks}, c_{ks}\} = 0$, 同 c_{ks}^\dagger

$$c_{ks}^\dagger |n_{ks}\rangle = |n_{ks}+1\rangle \rightarrow c_{ks}^\dagger c_{ks} = 1 - n_{ks} \\ c = \sqrt{1-n_{ks}}$$

$$(N_{ks})^2 = c_{ks}^\dagger c_{ks} c_{ks}^\dagger c_{ks} = c_{ks}^\dagger (1 - c_{ks}^\dagger c_{ks}) c_{ks} = N_{ks} \rightarrow n_{ks} = 0, 1$$

$\left[\begin{array}{l} \\ \end{array} \right.$

$$\begin{aligned} [N_{ks}, c_{ks}^\dagger] &= c_{ks}^\dagger (1 - 2c_{ks}^\dagger c_{ks}) = c_{ks}^\dagger \\ [N_{ks}, c_{ks}] &= -c_{ks} \end{aligned}$$

$c_{ks}^\dagger |0\rangle = |1\rangle, c_{ks}^\dagger |1\rangle = 0$
 $c_{ks} |1\rangle = |0\rangle, c_{ks} |0\rangle = 0$

$$[N_{ks}, N_{k's'}] = c_{ks}^\dagger c_{ks} c_{k's'}^\dagger c_{k's'} - c_{k's'}^\dagger c_{k's'} c_{ks}^\dagger c_{ks} = 0$$

\downarrow

Pauli不相容: 反对易: $|1_{ks}, 1_{k's'}\rangle = c_{ks}^\dagger c_{k's'}^\dagger |0\rangle \rightarrow |1_{ks}, 1_{k's'}\rangle = -|1_{k's'}, 1_{ks}\rangle \rightarrow$ 同态不能有2个粒子

反粒子

$$P = \sum_k \int d^3k \cdot \vec{k} (c_{ks}^\dagger c_{ks} - d_{ks} d_{ks}^\dagger)$$

J-W量子化使得动量相反, 电性相同

$$Q = \sum_k \int d^3k \ q (c_{ks}^\dagger c_{ks} + d_{ks} d_{ks}^\dagger)$$

(正则 \rightarrow 动同荷反)

正则量子化 \leftarrow Heisenberg 不确定原理

J-W量子化 \leftarrow 微观因果性原理

5. 微观因果性原理 (对所有场的要求)

→ 类空间隔的两点无关 (即算子对易)

对于Dirac旋量, 仅反

对易满足微观因果

场的观测量为双线性 $\rightarrow O = \int d^3x \mathcal{O}(x, t)$

$\mathcal{O}(x) = \psi_r(x) \psi_s(x) \rightarrow$ 由 ψ 与 ψ^\dagger (或 ψ 与 ψ^\dagger 的分量) 线性组合而成

$$[\mathcal{O}(x), \mathcal{O}(x')] = 0 \text{ 对于 } (x-x')^2 < 0 \text{ (类空)}$$

↓ - 等价

$$[\psi_r(x), \psi_s(x')] = 0 \text{ 或 } [\psi_r(x), \psi_s(x')] = 0 \text{ 对 } (x-x')^2 < 0$$

实标量: $\phi^\dagger = \phi$, 则 $[\phi(x), \phi(x')] = 0 \text{ , } (x-x')^2 < 0$

复标量: 每个量同上

Dirac场: $[\psi_\alpha(x), \psi_\beta(x')] = [\bar{\psi}_\alpha(x), \bar{\psi}_\beta(x')] = 0 \text{ , } (x-x')^2 < 0$

$$[\psi_\alpha(x), \bar{\psi}_\beta(x')] = 0 \text{ , } (x-x')^2 < 0 \rightarrow S_{\alpha\beta}(x-x') = (i\not{\partial} + m)\Delta(x-x') = 0 \text{ 对 } (x-x')^2 < 0$$

$$\text{标量场: } [\phi(x), \phi(x')] = 0 \text{ , } [\phi(x), \phi^\dagger(x')] = i\Delta(x-x') \text{ , } [\phi(x), \phi^\dagger(x')] = \Delta_1(x-x')$$

$$\text{Dirac: } [\psi_\alpha(x), \psi_\beta(x')] = 0 \text{ , } [\psi_\alpha(x), \bar{\psi}_\beta(x')] = iS_{\alpha\beta}(x-x') \text{ , } [\psi_\alpha(x), \bar{\psi}_\beta(x')] = S_{1\alpha\beta}(x-x')$$

$$S_{1\alpha\beta}(x-x') = (i\not{\partial} + m)\Delta_1(x-x') \text{ , 类空时}$$

$$\Delta_1(x-x') \neq 0 \text{ 满足 } k\text{-G 方程}$$

解一下? →

$$|x-x'| > \lambda = \frac{1}{m} \text{ 时, } \Delta_1(x-x') \sim -\frac{1}{(x-x')^2} e^{-\sqrt{m(x-x')^2}}$$

→ 不满足微观因果

定域性: $\phi(x)$ 完全定域, 算符构成的观测量不一定定域

$$\text{eg: 实标的 } N_k = \int d^3x a_k^\dagger a_k \rightarrow \phi(x, t) = \phi^+(x, t) + \phi^-(x, t) = \int \frac{d^3k}{(2\pi)^3 2\omega} e^{-ikx} a_k + \int \frac{d^3k}{(2\pi)^3 2\omega} e^{ikx} a_k^\dagger$$

$$N_k = \phi^{-1} i \not{\partial}_0 \phi \rightarrow [N_k(x), N_k(x')] = \begin{cases} \infty & |x-x'| \rightarrow 0 \\ 0 & |x-x'| > \lambda \end{cases}$$

? 二次量子化 (Schrödinger 场)