

Expressing the cone radius in the relational calculus with real polynomial constraints

Floris Geerts
 University of Limburg (LUC)
 Dept. WNI
 B-3590 Diepenbeek, Belgium
 floris.geerts@luc.ac.be

Abstract

We show that there is a query expressible in first-order logic over the reals that returns, on any given semi-algebraic set A , for every point a radius around which A is conical. We obtain this result by combining famous results from calculus and real algebraic geometry, notably Sard's theorem and Thom's first isotopy lemma, with recent algorithmic results by Rannou.

1 Introduction

The framework of constraint databases, introduced by Kanellakis, Kuper and Revesz [8], provides a nice theoretical model for spatial databases [11]. A spatial dataset is modeled using real polynomial inequality constraints; such sets are also known as semi-algebraic sets [1, 3]. The relational calculus (first-order logic) with real polynomial constraints then serves as a basic query language, denoted here as FO.

The study of the expressive power of query languages for constraint databases is an active domain of research [10]. One of the problems in particular that received attention in recent years is that of determining the exact power of FO in expressing topological properties of spatial databases [2, 5, 7, 9, 13]. One such property, which is central in this research, is that locally around each point, a semi-algebraic set has the topology of a cone. A radius at which this behavior shows is called a *cone radius* around the point for the set.

Accordingly, a cone radius query is a query that returns, for a semi-algebraic set A , a set of pairs (\vec{p}, r) giving for every point \vec{p} a cone radius r in \vec{p} for A . In this paper, we show that there exists an FO formula expressing a cone radius query. So

far, this was only known in two dimensions [5]. Expressibility of the cone radius, apart from being a natural question in itself, has also applications: for example, it has been linked to the expressibility of piecewise linear approximations [4].

2 Preliminaries

2.1 Spatial databases and Queries

A *semi-algebraic set* in \mathbb{R}^n is a finite union of sets definable by conditions of the form

$$f_1(\vec{x}) = f_2(\vec{x}) = \dots = f_k(\vec{x}) = 0, g_1(\vec{x}) > 0, g_2(\vec{x}) > 0, \dots, g_\ell(\vec{x}) > 0,$$

with $\vec{x} = (x_1, \dots, x_n) \in \mathbb{R}^n$, and where $f_1(\vec{x}), \dots, f_k(\vec{x}), g_1(\vec{x}), \dots, g_\ell(\vec{x})$ are multi-variate polynomials in the variables x_1, \dots, x_n with real coefficients. A *database schema* \mathcal{S} is a finite set of relation names, each with a given arity. A *database* over \mathcal{S} assigns to each $S \in \mathcal{S}$ a semi-algebraic set S^D in \mathbb{R}^n , if n is the arity of S . A *k-ary query over \mathcal{S}* is a function mapping each database over \mathcal{S} to a semi-algebraic set in \mathbb{R}^k .

As query language we use *first-order logic* (FO) over the vocabulary $(+, \cdot, 0, 1, <)$ expanded with the relation names in \mathcal{S} . A formula $\varphi(x_1, \dots, x_k)$ expresses the *k-ary query* defined by

$$\varphi(D) := \{(a_1, \dots, a_k) \in \mathbb{R}^k \mid \langle \mathbb{R}, D \rangle \models \varphi(a_1, \dots, a_k)\},$$

for any database D . Note that $\varphi(D)$ is always semi-algebraic because all relations in D are; indeed, by Tarski's theorem [15], the relations that are first-order definable on the real ordered field are precisely the semi-algebraic sets.

An example of a query expressed in FO is the following: Let \mathcal{S} be a schema containing the relation name S . Consider the FO-formula

$$\varphi_{\text{int}}(\vec{x}) := (\exists \varepsilon > 0)(\forall x'_1) \dots (\forall x'_n)(\|\vec{x} - \vec{x}'\| < \varepsilon \rightarrow S(x'_1, \dots, x'_n)).$$

For any database D , $\varphi_{\text{int}}(D)$ equals the interior of S^D . However, not every query is first-order expressible: the query which asks whether a set is connected is not expressible in FO. This result and other results related to constraint databases have recently been collected in a single volume [10].

2.2 Cones

Let $A \subseteq \mathbb{R}^n$ be a semi-algebraic set and $\vec{p} \in \mathbb{R}^n$ a point not in A . We define the *cone with base A and top \vec{p}* as the union of all closed line segments between \vec{p} and points in A . We denote this set with $\text{Cone}(A, \vec{p}) := \{t\vec{b} + (1-t)\vec{p} \mid \vec{b} \in A, 0 \leq t \leq 1\}$. For a point $\vec{p} \in \mathbb{R}^n$ and $\varepsilon > 0$, denote the closed ball centered at

\vec{p} with radius ε by $B^n(\vec{p}, \varepsilon)$, and denote the sphere centered at \vec{p} with radius ε , by $S^{n-1}(\vec{p}, \varepsilon)$. The following well-known theorem says that, locally around each point, a semi-algebraic set has the topology of a cone.

Theorem ([1, 3]). *Let $A \subseteq \mathbb{R}^n$ be a semi-algebraic set and \vec{p} a point of A . Then there is a real number $\varepsilon > 0$ such that the intersection $A \cap B^n(\vec{p}, \varepsilon)$ is homeomorphic to the set $\text{Cone}(A \cap S^{n-1}(\vec{p}, \varepsilon), \vec{p})$.*

Any real number $\varepsilon > 0$ as in the lemma is called a *cone radius* of A in \vec{p} .

Let \mathcal{S} be a schema containing a relation name S of arity n . A *cone radius query* Q_{radius} is a query which maps any database D over \mathcal{S} to a set of pairs $(\vec{p}, r) \in \mathbb{R}^n \times \mathbb{R}$ such that for every point $\vec{p} \in S^D$ there exists at least one pair $(\vec{p}, r) \in Q_{\text{radius}}(D)$, and for every $(\vec{p}, r) \in Q_{\text{radius}}(D)$, r is a cone radius in \vec{p} for S^D .

We will use the following notation: Let $A \subseteq B \subseteq \mathbb{R}^n$, the closure of A in B is denoted by $\text{cl}_B(A)$, and $\text{int}_B(A)$ indicates the interior of A in B . When the ambient space B is \mathbb{R}^n , we omit the subscript B . We denote $\text{cl}(A) - A$ (the frontier of A) with ∂A .

2.3 Whitney stratification

Every semi-algebraic set $A \subseteq \mathbb{R}^n$ can be “nicely” decomposed in a finite sequence \mathcal{Z} of $n + 1$ semi-algebraic sets Z_0, \dots, Z_n , called *strata*, with the following properties. For each $i = 0, \dots, n$:

1. Z_i is either a C^1 semi-algebraic set in \mathbb{R}^n of dimension i , or an empty set; and
2. each triple (Z_i, \vec{p}, Z_j) for $i < j$ and $\vec{p} \in Z_i$ has the *Whitney property*.

Such a decomposition is called a C^1 -*Whitney stratification* of A . We will not need the precise definitions of when a set is C^1 and of the Whitney property. We refer to the paper of Rannou [12] for more details.

We remark that in this paper we do not require the *frontier condition*, which says that the frontier of a stratum is the union of lower dimensional strata, and also do not suppose strata to be connected. Both properties are not necessary for Thom’s first isotopy lemma [6, 14], which we will use in our proof in Section 4.

3 Constructing a Whitney stratification

Let A be a semi-algebraic set in \mathbb{R}^n . We shall construct a C^1 -Whitney stratification \mathcal{Z} of the closure $\text{cl}(A)$ such that A is the union of connected components of strata of \mathcal{Z} . We then say that \mathcal{Z} is *compatible with A* . This construction will be expressible in FO.

Our construction is an adaptation of the construction given by Shiota [14, Lemma I.2.2].

We define Z_n as the subset of A where A is locally C^1 and of dimension n . Now suppose that the strata Z_n, \dots, Z_{k+1} have already been constructed. Then the stratum Z_k is constructed as follows. Define $A_0 = A$ and $A_1 = \partial A$. For $i = 0, 1$ construct

$$R_k^i := \{\vec{p} \in A_i - \bigcup_{j=k+1}^n Z_j \mid A_i \text{ is } C^1 \text{ and of dimension } k \text{ in a neighborhood of } \vec{p}\} \quad (1)$$

$$W_k^i := \bigcap_{j=k+1}^n \text{int}_{R_k^i}(\{\vec{p} \in R_k^i \mid (R_k^i, \vec{p}, Z_j) \text{ has the Whitney property}\}) \quad (2)$$

$$Z_k^i := W_k^i - \text{cl}(R_k^{1-i}). \quad (3)$$

Then we define $Z_k := Z_k^0 \cup Z_k^1$.

The stratum Z_k has indeed the desired properties: By (1) it is C^1 and of dimension k , (2) guarantees that for all points in Z_k , and for any $j > k$, the triples (Z_k, \vec{p}, Z_j) have the Whitney property, and (3) ensures that the connected components of Z_k lie either completely in A or completely in ∂A .

It is well known [17, 14] that the dimension of $A_i - \bigcup_{j=k}^n Z_j$ is strictly less than the dimension of $A_i - \bigcup_{j=k+1}^n Z_j$ for $i = 0, 1$. Hence, the stratification \mathcal{Z} will consist of exactly $n + 1$ strata Z_k , some of which may be empty.

We now show that the above construction is in FO.

Theorem 1. *Let \mathcal{S} be a database schema containing a relation name S of arity n . The n -ary query $Q_{k\text{-stratum}}$, which takes as input a database D over \mathcal{S} , and returns the k th stratum Z_k of the stratification \mathcal{Z} constructed above for $A = S^D$, is expressible in FO.*

In order to prove FO-expressibility of these queries, it is sufficient to show that the sets R_k^i , W_k^i , and Z_k^i occurring in the construction are FO-expressible. But this follows immediately from the work of Rannou [12]. Indeed, from that work we can deduce the following lemma, which immediately implies Theorem 1:

Lemma 1. *(i) Let \mathcal{S} be a database schema containing a relation name S of arity n . The $n + 1$ queries of arity n , defined as*

$$Q_{k\text{-reg}}(D) := \{\vec{x} \in \mathbb{R}^n \mid \vec{x} \in S^D \wedge (S^D \text{ is } C^1 \text{ and of dimension } k \text{ in an open neighborhood of } \vec{x})\},$$

for any database D over \mathcal{S} , are all expressible in FO.

(ii) Let \mathcal{S} be a database schema containing two relation names S_1 and S_2 of arity

n . The n -ary query, defined as

$$Q_{\text{Whitney}}(D) := \{\vec{x} \in \mathbb{R}^n \mid S_1^D, S_2^D \text{ are } C^1 \text{ and } (S_1^D, \vec{x}, S_2^D) \text{ has the Whitney property}\},$$

for any database D over \mathcal{S} , is expressible in FO.

4 Expressing the cone radius in FO

We are now ready to prove the main result of this paper.

Theorem 2. *There exists an FO-expressible cone radius query.*

Proof. Consider a semi-algebraic set A in \mathbb{R}^n , and let \mathcal{Z} be the C^1 -Whitney stratification of $\text{cl}(A)$ compatible with A . Let $\vec{p} \in \text{cl}(A)$ and define the C^1 -map

$$f_{\vec{p}} : \text{cl}(A) \rightarrow \mathbb{R} : \vec{x} \mapsto \|\vec{x} - \vec{p}\|^2.$$

We will need Thom's First Isotopy Lemma [14]. Applied to the C^1 -map $f_{\vec{p}}$ and the C^1 -Whitney stratification \mathcal{Z} , this lemma can be stated as follows: For any $a < b$,

- (a) If $f_{\vec{p}}$ is proper, i.e., $f_{\vec{p}}^{-1}([a, b])$ is compact, and
- (b) if for each stratum $Z \in \mathcal{Z}$, the restriction

$$f_{\vec{p}}|_{(Z \cap \text{int}(B^n(\vec{p}, b) - B^n(\vec{p}, a)))} \rightarrow (a, b) \subseteq \mathbb{R}$$

has no critical points (this will be explained later),

then for any $c \in (a, b)$, there exists a homeomorphism

$$h : \text{cl}(A) \cap \text{int}(B^n(\vec{p}, b) - B^n(\vec{p}, a)) \rightarrow (\text{cl}(A) \cap S^{n-1}(\vec{p}, c)) \times (a, b).$$

Moreover, this homeomorphism satisfies the following two properties:

- (i) For each $d \in (a, b)$, $h(\text{cl}(A) \cap S^{n-1}(\vec{p}, d)) = (\text{cl}(A) \cap S^{n-1}(\vec{p}, c)) \times \{d\}$, and
- (ii) $h(Z \cap \text{int}(B^n(\vec{p}, b) - B^n(\vec{p}, a))) = (Z \cap S^{n-1}(\vec{p}, c)) \times (a, b)$ is a homeomorphism for every connected component Z of a stratum of \mathcal{Z} .

This statement of Thom's First Isotopy Lemma is a specialized form of Theorem II.6.2 in Shiota [14].

Remark that condition (a) is automatically satisfied. Indeed, the inverse image by $f_{\vec{p}}$ of any interval $[a, b] \subset \mathbb{R}$ is equal to $\text{cl}(A) \cap (B^n(\vec{p}, b) - \text{int}(B^n(\vec{p}, a)))$ which is closed and bounded in \mathbb{R}^n .

Claim 1. *If condition (b) is satisfied for $0 < b$ (so $a = 0$), then every $c \in (0, b)$ is a cone radius of A in \vec{p} .*

Proof of Claim. Take an arbitrary real number $c \in (0, b)$. The lemma gives a homeomorphism

$$h_0 : \text{cl}(A) \cap \text{int}(B^n(\vec{p}, b) - \{\vec{p}\}) \rightarrow (\text{cl}(A) \cap S^{n-1}(\vec{p}, c)) \times (0, b).$$

By property (i), we obtain a homeomorphism

$$h_1 : \text{cl}(A) \cap (B^n(\vec{p}, c) - \{\vec{p}\}) \rightarrow (\text{cl}(A) \cap S^{n-1}(\vec{p}, c)) \times (0, c],$$

which equals the restriction $h_0|_{\text{cl}(A) \cap (B^n(\vec{p}, c) - \{\vec{p}\})}$. Since the cylinder $(\text{cl}(A) \cap S^{n-1}(\vec{p}, c)) \times (0, c]$ is clearly homeomorphic to the cone $\text{Cone}(\text{cl}(A) \cap S^{n-1}(\vec{p}, c), \vec{p}) - \{\vec{p}\}$, e.g., by the homeomorphism

$$h_2(\vec{x}, t) := (1 - \frac{t}{c})\vec{p} + (\frac{t}{c})\vec{x} \quad \text{for } t \in (0, c],$$

we obtain a homeomorphism

$$h_3 := h_2 \circ h_1 : \text{cl}(A) \cap (B^n(\vec{p}, c) - \{\vec{p}\}) \rightarrow \text{Cone}(\text{cl}(A) \cap S^{n-1}(\vec{p}, c), \vec{p}) - \{\vec{p}\}.$$

It is easily verified that $h_2 : (Z \cap S^{n-1}(\vec{p}, c)) \times (0, c] \rightarrow \text{Cone}(Z \cap S^{n-1}(\vec{p}, c), \vec{p}) - \{\vec{p}\}$ is a homeomorphism for each connected component Z of a stratum of \mathcal{Z} . Since h_1 also satisfies property (ii), we have that $h_3 : (Z \cap (B^n(\vec{p}, c) - \{\vec{p}\})) \rightarrow \text{Cone}(Z \cap S^{n-1}(\vec{p}, c), \vec{p}) - \{\vec{p}\}$ is a homeomorphism for each connected component Z of a stratum of \mathcal{Z} .

This implies that the restriction $h = h_3|_{A \cap (B^n(\vec{p}, c) - \{\vec{p}\})}$ is a homeomorphism from $h(A \cap (B^n(\vec{p}, c) - \{\vec{p}\}))$ to $\text{Cone}(A \cap S^{n-1}(\vec{p}, c), \vec{p}) - \{\vec{p}\}$, because A is the union of connected components of strata of \mathcal{Z} .

The homeomorphism h can easily be extended to the point \vec{p} , hence c is indeed a cone radius as desired. \square

Let \mathcal{S} be a schema containing a relation name S of arity n , and let D be a database over \mathcal{S} . By Claim 1, we can define the following cone radius query

$$Q_{\text{radius}}(D) := \{(\vec{p}, r) \in \mathbb{R}^n \times \mathbb{R} \mid \vec{p} \in S^D \text{ and } r \in (0, b)\},$$

where the interval $(0, b)$ satisfies condition (b) for the map $f_{\vec{p}}$ and semi-algebraic set $A = S^D$. Let us express this query in FO.

We define the critical point query as

$$Q_{\text{crit}}(D) := \{(\vec{p}, \vec{x}) \in \mathbb{R}^n \times \mathbb{R}^n \mid \vec{p} \in S^D \text{ and } \vec{x} \in Q_{k\text{-stratum}}(D) \text{ for a certain } k \\ \text{and } \vec{x} \text{ is a critical point of } f_{\vec{p}} \text{ restricted to } Q_{k\text{-stratum}}(D)\}.$$

The *critical points* of $f_{\vec{p}}$ restricted to a stratum Z , are the points $\vec{x} \in Z$ where the differential map $d_{\vec{x}}(f_{\vec{p}}|_Z)$ is not surjective.

Claim 2. A point $\vec{x} \in \mathbb{R}^n$ is a critical point of $f_{\vec{p}}|Z$ if and only if the tangent space of Z in \vec{x} is orthogonal to the vector $\vec{x} - \vec{p}$.

Proof of Claim. We compute the differential $d_{\vec{x}}(f_{\vec{p}}|Z)$ as follows: Locally around \vec{x} , we may assume that the projection on the first k coordinates $\Pi : Z \rightarrow U \subset \mathbb{R}^k$, is a homeomorphism, where k is the dimension of Z in \vec{x} . By definition of the differential, $d_{\vec{x}}(f_{\vec{p}}|Z) = (d_{(x_1, \dots, x_k)}g)(d_{(x_1, \dots, x_k)}\Pi^{-1})^{-1}$, where $g = (f|Z) \circ \Pi^{-1}$. By the C^1 Inverse Function Theorem, we may assume that $\Pi^{-1} : U \rightarrow Z : (x_1, \dots, x_k) \mapsto (x_1, \dots, x_k, \varphi_{k+1}, \dots, \varphi_n)$, where $\varphi_i(x_1, \dots, x_k)$ are C^1 -maps, and hence $g : U \mapsto \mathbb{R} : (x_1, \dots, x_k) = \sum_{i=1}^k (x_i - p_i)^2 + \sum_{j=k+1}^n (\varphi_j(x_1, \dots, x_k) - p_j)^2$. An elementary calculation shows that the differential of $f_{\vec{p}}|Z$ in \vec{x} is the vector

$$d_{\vec{x}}(f_{\vec{p}}|Z) = 2 \left(\left((x_i - p_i) + \sum_{j=k+1}^n (x_j - p_j) \frac{\partial \varphi_j}{\partial x_i}(x_1, \dots, x_k) \right)_{i=1, \dots, k}, \underbrace{0, \dots, 0}_{n-k \text{ times}} \right).$$

Since $d_{(x_1, \dots, x_k)}\Pi^{-1}$ is an isomorphism between the tangent space $T_{(x_1, \dots, x_k)}U$ of U in the projection $\Pi(\vec{x})$, and the tangent space $T_{\vec{x}}Z$ of Z in \vec{x} , any tangent vector $(v_1, \dots, v_n) \in T_{\vec{x}}Z$ is of the form $(d_{(x_1, \dots, x_k)}\Pi^{-1})(v_1, \dots, v_k)$. More specifically, any tangent vector $\vec{v} \in T_{\vec{x}}Z$ can be written as

$$(v_1, \dots, v_n) = (v_1, \dots, v_k, \sum_{i=1}^k \frac{\partial \varphi_{k+1}}{\partial x_i}(x_1, \dots, x_k)v_i, \dots, \sum_{i=1}^k \frac{\partial \varphi_n}{\partial x_i}(x_1, \dots, x_k)v_i).$$

Hence, the product

$$d_{\vec{x}}(f_{\vec{p}}|Z) \cdot \vec{v} = 2 \sum_{i=1}^k (x_i - p_i)v_i + 2 \sum_{j=k+1}^n (x_j - p_j) \left(\sum_{i=1}^k \frac{\partial \varphi_j}{\partial x_i}(x_1, \dots, x_k)v_i \right),$$

is equal to $2 \sum_{i=1}^n (x_i - p_i)v_i$. This implies that the differential map $d_{\vec{x}}(f_{\vec{p}}|Z)$ is not surjective if and only if $2 \sum_{i=1}^n (x_i - p_i)v_i = 0$ for all tangent vectors $\vec{v} \in T_{\vec{x}}Z$. This proves the Claim. \square

The proof of the theorem now continues as follows. The tangent space query

$$Q_{\text{tangent}}(D) := \{(\vec{x}, \vec{v}) \in \mathbb{R}^n \times \mathbb{R}^n \mid S^D \text{ is } C^1, \vec{x} \in S^D \text{ and } \vec{v} \in T_{\vec{x}}S^D\},$$

is expressible in FO [12, Lemma 2]. Because the orthogonality of two vectors can be easily expressed in FO, the formula

$$\varphi_{\text{crit}}(\vec{p}, \vec{x}) := S(\vec{p}) \wedge \bigvee_{j=0}^n \forall \vec{v} (\varphi_{\text{tangent}}(\varphi_{j\text{-stratum}}(S))(\vec{x}, \vec{v}) \rightarrow (\vec{x} - \vec{p}) \cdot \vec{v} = 0)$$

expresses Q_{crit} correctly by Claim 2. Here, $\varphi_{j\text{-stratum}}$ denotes an FO-formula expressing $Q_{j\text{-stratum}}$ for $j = 0, \dots, n$, and φ_{tangent} is an FO formula expressing Q_{tangent} .

A *critical value* of $f_{\vec{p}}$ is the image by $f_{\vec{p}}$ of a critical point. The query which returns the set of critical values is expressible in FO by the formula

$$\varphi_{\text{val}}(\vec{p}, r) := \exists \vec{x} (\varphi_{\text{crit}}(\vec{p}, \vec{x}) \wedge r = f_{\vec{p}}(\vec{x})).$$

We now observe that $\{r \in \mathbb{R} \mid \varphi_{\text{val}}(\vec{p}, r)\}$ is finite for each \vec{p} . Indeed, the set of critical points $\{\vec{x} \in \mathbb{R}^n \mid \varphi_{\text{crit}}(\vec{p}, \vec{x})\}$ is semi-algebraic and hence admits a C^1 -cell decomposition $\mathcal{C} = \{C_1, \dots, C_m\}$ such that $f|_{C_i}$ is C^1 [16]. Sard's Theorem for C^1 -maps [18] implies that each $f_{\vec{p}}|_{C_i}$ attains only a finite number of values. Hence the image by $f_{\vec{p}}$ of the set of critical points is finite.

This implies that either there are no critical values, or there exists a minimal critical value. By Claim 1, any value smaller than this minimal value is a cone radius. We therefore conclude that the query expressed in FO as

$$\varphi_{\text{radius}}(\vec{p}, r) := (\forall r') (\varphi_{\text{val}}(\vec{p}, r') \rightarrow r < r'),$$

is a cone radius query, as desired. \square

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