

## A NOTE ON ACTIVE LEARNING FOR SMOOTH PROBLEMS

SATYAKI MAHALANABIS  
SMAHALAN@CS.ROCHESTER.EDU

**ABSTRACT.** We show that the disagreement coefficient of certain smooth hypothesis classes is  $O(m)$ , where  $m$  is the dimension of the hypothesis space, thereby answering a question posed in [Fri09].

We answer a question posed in [Fri09] regarding the disagreement coefficient of certain smooth hypothesis classes. To be precise, we show that the limiting disagreement coefficient, defined in Lemma 3 of [Fri09], for hypotheses and distributions as specified in Theorem 4 of [Fri09] is at most  $2\sqrt{\frac{\pi}{2(1-\frac{1}{m})}}m \leq 2\sqrt{\pi}m$ , where  $m \geq 2$  is the dimension of the hypothesis space, thereby improving on the  $2m^{3/2}$  bound given there. Our proof is exactly the same as Theorem 4 of [Fri09], except that we need to use the following proposition.

**Proposition 1.** *Consider a set of vectors  $V \subseteq \mathbb{R}^m$  ( $m \geq 2$ ), and let  $K_m \subseteq \mathbb{R}^m$  be a symmetric, origin-centred and convex body. Then*

$$(1) \quad \frac{\sum_{v \in V} \sup_{h \in K_m} |v^t h|}{\sup_{h \in K_m} \sum_{v \in V} |v^t h|} \leq \sqrt{\frac{\pi}{2(1-\frac{1}{m})}} m.$$

The convex set  $K_m$  and the vectors  $V$  in Proposition 1 correspond respectively to the ball in  $\mathbb{R}^m$  w.r.t the distance  $\hat{d}$  and the vectors  $\{a_x\}$  as defined in the proof of Theorem 4 in [Fri09]. Roughly speaking,  $K_m$  is the version space. Note that the limiting disagreement coefficient is actually twice the l.h.s of (1).

**Proof :**

(Proposition 1) As in [Fri09], consider the John ellipsoid  $\mathcal{E} = \{x^t A^t A x \leq 1\}$  s.t.  $\mathcal{E} \subseteq K_m \subseteq \sqrt{m}\mathcal{E}$ . Then clearly we have

$$(2) \quad \frac{\sum_{v \in V} \sup_{h \in K_m} |v^t h|}{\sup_{h \in K_m} \sum_{v \in V} |v^t h|} \leq \sqrt{m} \frac{\sum_{v \in V} \sup_{h \in \mathcal{E}} |v^t h|}{\sup_{h \in \mathcal{E}} \sum_{v \in V} |v^t h|} = \sqrt{m} \frac{\sum_{v \in V} \sup_{h \in S_{m-1}} |(v^t A^{-1}) h|}{\sup_{h \in S_{m-1}} \sum_{v \in V} |(v^t A^{-1}) h|},$$

where  $S_{m-1}$  is the (surface of)  $m$ -dimensional unit sphere. Now if we choose  $h$  from the uniform distribution  $U_m$  on  $S_{m-1}$ , we have

$$(3) \quad \sup_{h \in S_{m-1}} \sum_{v \in V} |(v^t A^{-1}) h| \geq \mathbb{E}_{h \sim U_m} \left[ \sum_{v \in V} |(v^t A^{-1}) h| \right] = \sum_{v \in V} \mathbb{E}_{h \sim U_m} \left[ |(v^t A^{-1}) h| \right] \geq \sum_{v \in V} \frac{c_m}{\sqrt{m}} \|v^t A^{-1}\|,$$

where  $c_m = \sqrt{\frac{2}{\pi}(1-\frac{1}{m})}$  and where we have used the fact (see e.g. [Bau90]) that for any unit vector  $u$ ,  $\mathbb{E}_{h \sim U_m} [|u^t h|] \geq c_m / \sqrt{m}$ . Note also that for each  $v$ ,  $\sup_{h \in S_{m-1}} |(v^t A^{-1}) h| = \|v^t A^{-1}\|$ . Hence (1) follows by substituting (3) in (2).  $\blacksquare$

**Remark 2.** The l.h.s of (1) is  $m$  for the example of the origin-centred  $m$ -dimensional octagon (i.e. the convex hull of  $2m$  points  $\{[\pm 1 \ 0 \ \dots \ 0]^t, [0 \ \pm 1 \ \dots \ 0]^t, \dots, [0 \ 0 \ \dots \ \pm 1]^t\}$ ) and the set of  $m$  vectors  $\{[1 \ 0 \ \dots \ 0]^t, [0 \ 1 \ \dots \ 0]^t, \dots, [0 \ 0 \ \dots \ 1]^t\}$ . Tightening the bound in (1) to  $m$  would probably need more careful analysis.

#### REFERENCES

- [Bau90] Eric B. Baum. The perceptron algorithm is fast for nonmalicious distributions. *Neural Comput.*, 2:248–260, April 1990.
- [Fri09] Eric Friedman. Active learning for smooth problems. In *Conference on Learning Theory*, 2009.