Project 1: Canny's Edge Detector

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Requirements

- 1. Being able to compile Python code
- 2. Install Pillow and numpy, on some command line
 - a. pip install Pillow
 - b. pip install numpy
- 3. Change img_path in main.py

```
if __name__ == "__main__":
    img_path = "Barbara.bmp"
    smooth = gaussian_smooth(img_path)
```

Source Code

```
import PIL
from PIL import Image
import numpy as np
from matplotlib import pyplot as plt

def convolve(img, mask):
    # img and mask are both np arrays

mask_width, mask_height = mask.shape
result_width, result_height = img.shape
result = np.zeros(img.shape)

for row in range(result_width-mask_width):
    for col in range(result_height-mask_height):
    img_window = img[row:row+mask_width, col:col+mask_height]
    result[row,col] = np.sum(np.multiply(img_window, mask))

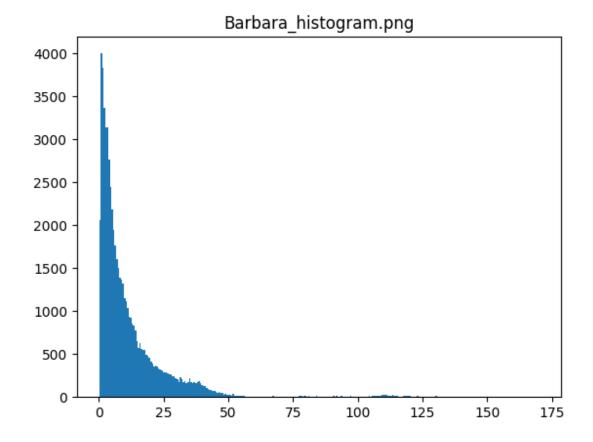
return result
```

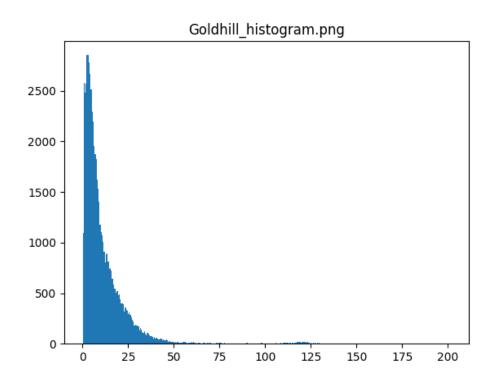
```
23 ▼ def gaussian_smooth(img_path):
         # perform gaussian smoothing
         gaussian_mask = [
                             [1,1,2,2,2,1,1],
                             [1,2,2,4,2,2,1],
                             [2,2,4,8,4,2,2],
                             [2,4,8,16,8,4,2],
                             [2,2,4,8,4,2,2],
                             [1,2,2,4,2,2,1],
                             [1,1,2,2,2,1,1]
                         ]
         mask = np.array(gaussian_mask)
         img = np.asarray(Image.open(img_path))
         result = convolve(img, mask)
         # normalize
         return result/np.sum(gaussian_mask)
```

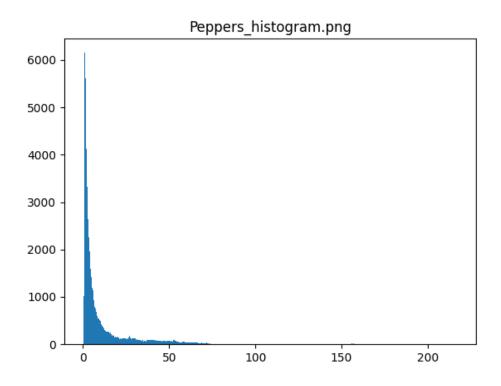
```
def get_gradients(img):
     # Four masks provided
     g0 = np.array([
         [-1, 0, 1],
[-2, 0, 2],
[-1, 0, 1]
     1)
     g1 = np.array([
         [0, 1, 2],
[-1, 0, 1],
[-2, -1, 0]
     1)
     g2 = np.array([
         [1, 2, 1],
[0, 0, 0],
[-1, -2, -1]
     g3 = np.array([
         [2, 1, 0],
[1, 0, -1],
[0, -1, -2]
     1)
     # get abs of responses from the four masks
     m0 = np.abs(convolve(img, g0))
     m1 = np.abs(convolve(img, g1))
    m2 = np.abs(convolve(img, g2))
m3 = np.abs(convolve(img, g3))
     # magnitude is the maximum of the four responses, divided by 4
     gradient magnitude = np.maximum.reduce([m0, m1, m2, m3])/4
     # quantized angle equals to the index of the mask that produces the maximum response
    quantized_angles = np.zeros(gradient_magnitude.shape)
quantized_angles_width, _ = quantized_angles.shape
     for row in range(quantized_angles_width):
          row_array = np.array([m0[row], m1[row], m2[row], m3[row]])
          quantized_angles[row] = np.argmax(row_array, axis=0)
     return gradient_magnitude, quantized_angles
```

```
def nms(magnitude, angles):
          # perform non-maxima suppression
          # indices of the two neighbors to do the comparison
          neighbors = {
              0: [(0,-1), (0,1)],
              1: [(1,-1), (-1,1)],
              2: [(-1,0), (1,0)],
              3: [(-1,-1), (1,1)]
          nms magnitude = np.zeros(magnitude.shape)
          width, height = magnitude.shape
          # get neighbors for each pixels and do nms comparison
          for row in range(width):
              for col in range(height):
110
                  try:
111
                      # neighbor 1
                      n1_row, n1_col = neighbors[angles[row][col]][0]
113
                      n1 mag = magnitude[row+n1 row][col+n1 col]
114
                      # neighbor 2
116
                      n2_row, n2_col = neighbors[angles[row][col]][1]
117
                      n2 mag = magnitude[row+n2 row][col+n2 col]
118
                      curr mag = magnitude[row][col]
120
                      if curr_mag < n1_mag or curr_mag < n2_mag:</pre>
121
                          nms magnitude[row][col] = 0
122
                      else:
123
                          nms_magnitude[row][col] = curr_mag
124
125
                  except IndexError:
126
                      # the pixel doesn't have two neighbors, do nothing
127
128
129
          return nms magnitude
130
```

```
132 ▼ def threshold(nms_magnitude):
133
134
          # perform simple thresholding for 25, 50, 75th percentile
135
          vals = [v for v in nms_magnitude.flatten() if v],
136
137
          t25, t50, t75 = np.percentile(vals, [25, 50, 75])
138
139
          edgemap25 = np.zeros(nms_magnitude.shape)
          edgemap50 = np.zeros(nms_magnitude.shape)
          edgemap75 = np.zeros(nms_magnitude.shape)
          width, height = nms_magnitude.shape
144 ▼
          for row in range(width):
145 ▼
              for col in range(height):
                  mag = nms_magnitude[row][col]
148 ▼
                  if mag >= t25:
                      edgemap25[row][col] = 255
150 ▼
                  if mag >= t50:
                      edgemap50[row][col] = 255
                  if mag >= t75:
                      edgemap75[row][col] = 255
154
          return edgemap25, edgemap50, edgemap75
156
157 ▼ def histogram(nms magnitude):
158
          vals = [v for v in nms_magnitude.flatten() if v]
            = plt.hist(vals, bins='auto')
          plt.show()
163 ▼ if <u>name</u> == "__main__":
          img path = "Peppers.bmp"
          smooth = gaussian smooth(img path)
          mag, angles = get_gradients(smooth)
          nms = nms(mag, angles)
          edgemap25, edgemap50, edgemap75 = threshold(nms)
170
          histogram(nms)
171
```







Barbara.bmp

After Gaussian smoothing



Normalized mag image



After nms



25th Percentile - 2.89



50th Percentile - 6.64



75th Percentile - 14.7



Goldhill.bmp

After Gaussian smoothing



Normalized mag image

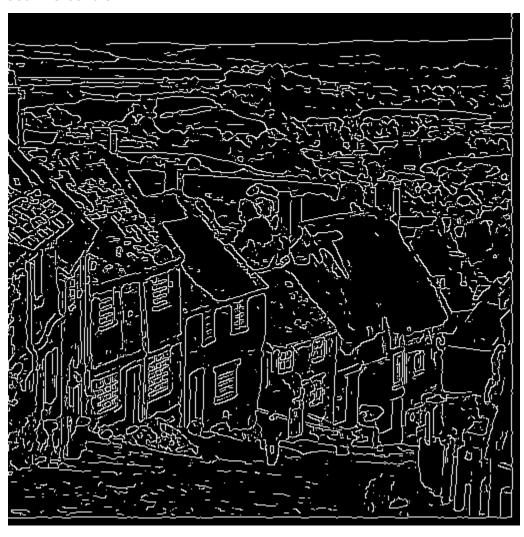


After nms





50th Percentile - 7.2



75th Percentile - 14.4



Peppers.bmp After Gaussian smoothing



Normalized mag image



After nms



25th Percentile - 1.69



50th Percentile - 3.59



75th Percentile - 10.56

