

Study Notes

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Contents

	1.2	Maximum A Posteriori Estimation . .	13
	1.3	Gaussian Distribution	14
	II	Algorithm and Data Structure	15
	2	Algorithm	17
	2.1	Graph	17
	III	Programming	19
	3	C++	21
	4	Rust	23
	IV	Research	25
	5	Paper Reading	27
		Appendices	29
		Appendix A Formulas	29
	A.1	Gaussian distribution	29
		Bibliography	31
		Alphabetical Index	33
Acronyms	7		
Preface	9		
0.1	Features of this template	9	
0.1.1	crossref	9	
0.1.2	ToC (Table of Content)	9	
0.1.3	header and footer	9	
0.1.4	bib	10	
0.1.5	preface, index, quote (epi- graph) and appendix	10	
I Machine Learning	11		
1 Probability	13		
1.1	Maximum Likelihood Estimation . . .	13	

List of Figures

List of Theorems

A.1 Theorem (Central limit theorem) . . . 29

List of Definitions

A.1 Definition (Gaussian distribution) . . 29

Acronyms

MAP	Maximum A Posteriori Estimation 13
MLE	Maximum Likelihood Estimation 13 , 14
pdf	Probability Density Function 14

Preface

Contents

0.1 Features of this template	9
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0.1 Features of this template

TeX, stylized within the system as $\text{\texttt{L}^A\text{T}_{\text{\scriptsize E}}\text{\texttt{X}}$, is a typesetting system which was designed and written by Donald Knuth and first released in 1978. TeX is a popular means of typesetting complex mathematical formulae; it has been noted as one of the most sophisticated digital typographical systems.

- [Wikipedia](#)

0.1.1 crossref

different styles of clickable definitions and theorems

- nameref: [Gaussian distribution](#)
- autoref: [Definition A.1](#), ??
- cref: Definition [A.1](#),
- hyperref: [Gaussian](#),

0.1.2 ToC (Table of Content)

- mini toc of sections at the beginning of each chapter
- list of theorems, definitions, figures
- the chapter titles are bi-directional linked

0.1.3 header and footer

fancyhdr

- right header: section name and link to the beginning of the section
- left header: chapter title and link to the beginning of the chapter
- footer: page number linked to ToC of the whole document

0.1.4 **bib**

- titles of reference is linked to the publisher webpage e.g., [Kit+02]
- backref (go to the page where the reference is cited) e.g., [Chi09]
- customized video entry in reference like in [Bab16]

0.1.5 **preface, index, quote (epigraph) and appendix**

index page at the end of this document...

Part I

Machine Learning

Chapter 1

Probability

Contents

1.1 Maximum Likelihood Estimation	13
1.2 Maximum A Posteriori Estimation	13
1.3 Gaussian Distribution	14

1.1 Maximum Likelihood Estimation

$$\mathbf{X} = (\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N)^T, \mathbf{x}_i = (x_{i1}, x_{i2}, \dots, x_{ip})^T \quad (1.1)$$

in which N is the number of samples, p is the number of features. The data is sampled from a distribution $p(\mathbf{x} | \theta)$, where θ is the parameter of the distribution.

For N i.i.d. samples, the likelihood function is $p(\mathbf{X} | \theta) = \prod_{i=1}^N p(\mathbf{x}_i | \theta)$

In order to get θ , we use [Maximum Likelihood Estimation \(MLE\)](#) to maximize the likelihood function.

$$\theta_{\text{MLE}} = \underset{\theta}{\operatorname{argmax}} \log p(\mathbf{X} | \theta) = \underset{\theta}{\operatorname{argmax}} \sum_{i=1}^N \log p(\mathbf{x}_i | \theta) \quad (1.2)$$

1.2 Maximum A Posteriori Estimation

In Bayes' theorem, the θ is not a constant value, but $\theta \sim p(\theta)$. Hence,

$$p(\theta | \mathbf{X}) = \frac{p(\mathbf{X} | \theta)p(\theta)}{p(\mathbf{X})} = \frac{p(\mathbf{X} | \theta)p(\theta)}{\int_{\theta} p(\mathbf{X} | \theta)p(\theta)d\theta} \quad (1.3)$$

In order to get θ , we use [Maximum A Posteriori Estimation \(MAP\)](#) to maximize the posterior function.

$$\theta_{\text{MAP}} = \underset{\theta}{\operatorname{argmax}} p(\theta | \mathbf{X}) = \underset{\theta}{\operatorname{argmax}} \frac{p(\mathbf{X} | \theta)p(\theta)}{p(\mathbf{X})} \quad (1.4)$$

After θ is estimated, then calculating $\frac{p(\mathbf{X} | \theta)p(\theta)}{\int_{\theta} p(\mathbf{X} | \theta)p(\theta)d\theta}$ to get the posterior distribution. We can use the posterior distribution to predict the probability of a new sample \mathbf{x} .

$$p(x_{\text{new}} | \mathbf{X}) = \int_{\theta} p(x_{\text{new}} | \theta) \cdot p(\theta | \mathbf{X})d\theta \quad (1.5)$$

1.3 Gaussian Distribution

Gaussian distribution is also called normal distribution.

$$\theta = (\mu, \sigma^2), \quad \mu = \frac{1}{N} \sum_{i=1}^N x_i, \quad \sigma^2 = \frac{1}{N} \sum_{i=1}^N (x_i - \mu)^2 \quad (1.6)$$

For MLE,

$$\theta = (\mu, \Sigma) = (\mu, \sigma^2), \quad \theta_{\text{MLE}} = \underset{\theta}{\operatorname{argmax}} \log p(\mathbf{X} \mid \theta) = \underset{\theta}{\operatorname{argmax}} \sum_{i=1}^N \log p(x_i \mid \theta) \quad (1.7)$$

Generally, the **Probability Density Function (pdf)** of a Gaussian distribution is:

$$p(x \mid \mu, \Sigma) = \frac{1}{\sqrt{(2\pi)^p \det(\Sigma)}} \exp \left(-\frac{1}{2} (\mathbf{x} - \mu)^T \Sigma^{-1} (\mathbf{x} - \mu) \right) \quad (1.8)$$

in which μ is the mean vector, Σ is the covariance matrix, \det is the determinant of matrix. \det is the product of all eigenvalues of a matrix.

Hence,

$$\log p(\mathbf{X} \mid \theta) = \sum_{i=1}^N \log p(x_i \mid \theta) = \sum_{i=1}^N \log \frac{1}{\sqrt{(2\pi)^p \det(\Sigma)}} \exp \left(-\frac{1}{2} (\mathbf{x} - \mu)^T \Sigma^{-1} (\mathbf{x} - \mu) \right) \quad (1.9)$$

Let's only consider 1 dimension case for brevity, then

$$\log p(\mathbf{X} \mid \theta) = \sum_{i=1}^N \log p(x_i \mid \theta) = \sum_{i=1}^N \log \frac{1}{\sqrt{2\pi\sigma^2}} \exp \left(-\frac{1}{2} \frac{(x_i - \mu)^2}{\sigma^2} \right) \quad (1.10)$$

Let's get the optimal value for μ ,

$$\mu_{\text{MLE}} = \underset{\mu}{\operatorname{argmax}} \log p(\mathbf{X} \mid \theta) = \underset{\mu}{\operatorname{argmax}} \sum_{i=1}^N (x_i - \mu)^2 \quad (1.11)$$

So,

$$\frac{\partial \log p(\mathbf{X} \mid \theta)}{\partial \mu} = \sum_{i=1}^N -2(x_i - \mu) = 0 \rightarrow \mu_{\text{MLE}} = \frac{1}{N} \sum_{i=1}^N x_i \quad (1.12)$$

Part II

Algorithm and Data Structure

Chapter 2

Algorithm

Contents

2.1 Graph	17
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2.1 Graph

Part III

Programming

Chapter 3

C++

Chapter 4

Rust

Part IV

Research

Chapter 5

Paper Reading

Appendix A

Formulas

A.1 Gaussian distribution

Definition A.1 (Gaussian distribution). *Gaussian distribution*

Theorem A.1 (Central limit theorem).

Bibliography

- [Bab16] László Babai. “Graph Isomorphism in Quasipolynomial Time”. Jan. 19, 2016. arXiv: [1512.03547 \[cs, math\]](#) (cit. on p. 10). [ONLINE VIDEO](#)
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- [Kit+02] Alexei Yu Kitaev et al. *Classical and quantum computation*. 47. American Mathematical Soc., 2002 (cit. on p. 10).

Alphabetical Index

G	
Gaussian distribution	29
I	
index	10