MIT App Inventor Codi Bot: Complete



Level: advanced

This tutorial combines all the previous tutorials together, you can interact with all Codi Bot functions, including LEDs, wings and sounds.

source .ino / source .aia



Function description

This project will show you how to control all the Codi Bot functions with App Inventor through BLE communication.

Hardware

Please follow this building guide to assemble your Codi Bot.

App Inventor

Now log in to your App Inventor account and create a new project or directly import this aia file.

Since this app is the combination of the previous three, this tutorial will not describe everything in a very detailed way. But you are certainly can follow this tutorial to build the app step by step.

This app is composed of **four** different sections:

- 1. Connection (<u>Designer/Blocks</u>)
- 2. Wing (Designer/Blocks)
- 3. LED (<u>Designer/Blocks</u>)
- 4. Buzzer (**Designer/Blocks**)

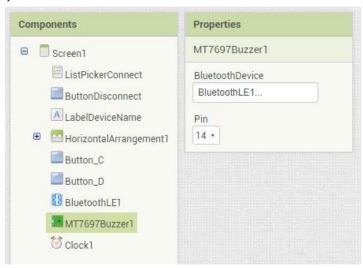
Designer

- 1. We need to import two extensions from this URL:
 - Bluetooth low energy: http://iot.appinventor.mit.edu/assets/resources/edu.mit.ap pinventor.ble.aix
 - MT7697pin: http://iot.appinventor.mit.edu/assets/resources/edu.mit.ap pinventor.iot.mt7697.aix
- 2. Add a **BluetoothLE** component to your project, we use it to send commands to Codi Bot through Bluetooth communication.

3. Add seven **MT7697Pin** components to your project. Set their BluetoothDevice properties to **BluetoothLE1** and rename them as table below:

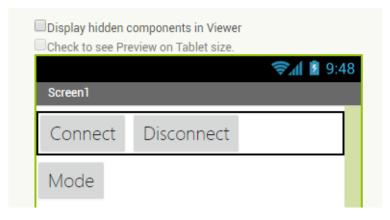
Rename as	Mode	Pin
MT7697_LeftWingServo	servo	2
MT7697_RightWingServo	servo	7
MT7697_LeftWingLED	analog output	3
MT7697_RightWingLED	analog output	9
MT7697_LED_R	analog output	15
MT7697_LED_G	analog output	16
MT7697_LED_B	analog output	11

- 4. Add a **MT7697Buzzer** component to your project, we use them to control the #14 pin of Linklt 7697, which is connected with Robot Shield onboard buzzer.
 - Set its BluetoothDevice property to BluetoothLE1 (Step 2.) and set Pin to 14.



Connection

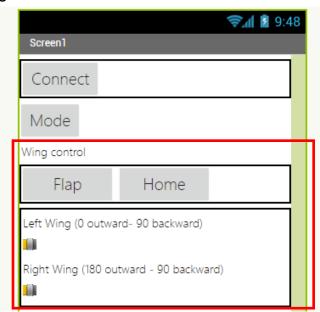
- Add a LiskPicker to select available Bluethooth devices nearby.
 Rename it as "ListPicker_Connect", set Text to "Connect" and FontSize to 20.
- Add a button to close Bluetooth connection between your Android phone and Linklt 7697. Rename it as "Button Disconnect" and set Text to "Disconnect".
- 7. Add a Label to show messages of connection. Rename it to "Label_Device" and clear Text to "".
- 8. Add a HorizontalArrangement component, set Width to **Fill parent**, the put components from Step 4 to 6 into it.
- Add another LiskPicker to select one of the three control mode: Wing, LED and Sound. Rename it as "ListPicker_Connect", Text to "Mode" and FontSize to 20.



Wing (Designer)

- Add a Label to show message, rename it as "Label_Wing" and set Text to "Wing control".
- 11. Add two Buttons for wing actions. Rename them as "Button_WingFlap" and "Button_Home". Set FontSize to 20 and Text to "Flap" and "Home".
- 12. Add a HorizontalArrangement component, set Width to **Fill parent**, then put components of Step 11 into it.

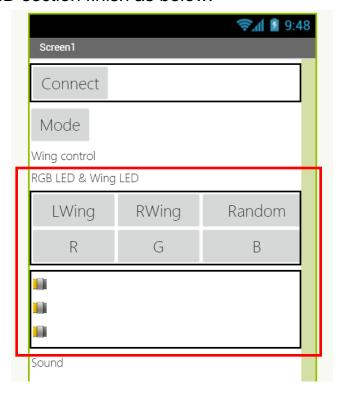
- 13. Add two labels to show messages. Rename them as "Label_LeftWing" and "Label_RightWing". Set their Text to "Left Wing (0 outward- 90 backward) " and "Right Wing (180 outward 90 backward) ".
- 14. Add a slider to control left wing position. Rename it as "Label_LeftWing". Set MinValue to 0, MaxValue to 90, Width to Fill parent and ColorLeft to Green.
- 15. Add a slider to control right wing position. Rename it as "Label_RightWing". Set MinValue to 90, MaxValue to 180, Width to Fill parent and ColorLeft to Purple.
- 16. Add a VerticalArrangement component, set Width to **Fill parent**, the put components from Step 13 to 15 into it.
- 17. Wing section finish as below:



LED (Designer)

- 18. Add a Label to show message, rename it as "Label_LED" and set Text to "RGB LED & Wing LED".
- 19. Add four buttons for RGB LED actions. Rename them as "Button_LED_R", "Button_LED_G", "Button_LED_B" and "Button_RGB_Random". Set Text to "R", "G", "B" and "Random", Width to 30 percent and FontSize to 20.

- 20. Add two more buttons for wing LEDs actions. Rename them as "Button_LED_LeftWin" and "Button_LED_RightWing". Set Text to "L" and "R", Width to 30 percent and FontSize to 20.
- 21. Add a TableArrangement component, set Width to **Fill parent**, Columns to **3** and Rows to **2**. Then put components from Step 19 to 20 into it.
- 22. Add three sliders to control red/green/blue light intensity of RGB LED. Rename them as "Slider_LED_R", "Slider_LED_G" and "Slider_LED_B". Set ColorLeft to Red, Green and Blue; Set MinValue to 0, MaxValue to 255 and Width to Fill parent.
- 23. Add a VerticalArrangement component, set Width to **Fill parent**, the put components of Step 22 into it.
- 24. LED section finish as below:



Sound (Designer)

- 25. Add a Label to show message, rename it as "Label_Sound" and set Text to "Sound".
- 26. Add eight buttons to make sounds. Rename them as "Button_C", "Button_D", "Button_E", "Button_F", "Button_G", "Button_A", "Button_B" and "Button_C2". Text to "C", "D", "E", "F", "G", "A", "B" and "C' ". Set Width to 25 percent and FontSize to 20.
- 27. Add a TableArrangement component, set Width to **Fill parent**, Columns to **4** and Rows to **2**. Then put components of Step 26 into it.
- 28. Sound section finish as below:



You should realize that not all the functions of previous tutorials are included here, for instance specifying sound frequency and time duration. However, you can always tinker this app and add as many App Inventor components as you like.

Blocks

Let's take a look at our blocks step by step. Notice this time we have

a different connect approach with previous projects. We use Listpicker to select available BluetoothLE device instead of a specified device.

Similar to Designer, we use the same structure to guide you finish the blocks needed for this project.

Connection (Blocks)

Initialize app and scan for nearby Bluetooth devices
 In Screen1.Initialize event, we ask BluetoothLE component to scan for BLE devices nearby (BluetoothLE1.StartScanning).

If any device is founded (**BluetoothLE1.DeviceFound** event), we put these devices into ListPicker.

```
when Screen1 · Initialize
do call BluetoothLE1 · StartScanning

when BluetoothLE1 · DeviceFound

do set ListPicker_Connect · ElementsFromString · to BluetoothLE1 · DeviceList ·
```

2. Choose device with ListPicker

In ListPicker.AfterPicking event, we use BluetoothLE.Connect method to connect with the device selected.

```
when ListPicker_Connect . AfterPicking
do call BluetoothLE1 . Connect
index (ListPicker_Connect . SelectionIndex .
```

3. BLE Connected

When connected successfully (**BluetoothLE.Connected** event), we will see related messages on several components, hide the ListPicker and show other components. This is because if we send Bluetooth commands without connecting to something first,

it may cause error.

```
when BluetoothLE1 .Connected
do set Screen1 . Title to
                               " Connected
    set ListPicker_Connect . Visible to false to
    set ListPicker_Mode . Enabled to to true .
    set Slider_LeftWing . ThumbEnabled to true .
    set Slider_RightWing v . ThumbEnabled v to
                                             true •
    set Slider_LED_R . ThumbEnabled to
    set Slider_LED_G . ThumbEnabled to
    set Slider_LED_B . ThumbEnabled to true .
    set Button_Disconnect . Visible to true
    set Label_Device v . Text v to ( join (
                                         BluetoothLE1 🔻
                                                         ConnectedDeviceName •
    call home •
```

4. Another ListPicker to choose one of the modes

To simplify the interface, we separate related components into three groups: Wing, LEd and Sound instead of displaying all the components at the same time In **ListPicker.BeforePicking** event, we set ListPicker elements to a list (Wing, LED, Sound). Next, in **ListPicker.AfterPicking** event, we set related components to be visible or not according the selection result.

```
when ListPicker_Mode v .BeforePicking
do set ListPicker_Mode v . Elements v to make a list v "Wing"

"LED"

"Sound"
```

5. Button to disconnect

When **Button_Disconnect** is pressed, we close the Bluetooth connection and hide all Layout components.

And when disconnect successfully (**BluetoothLE.Disconnected** event), we set all components to their initial status and wait for next connection.

```
when Button_Disconnect v .Click

do call BluetoothLE1 v .Disconnect

set HorizontalArrangement_Wing v . Visible v to false v

set VerticalArrangement_Wing v . Visible v to false v

set TableArrangement_LED v . Visible v to false v

set VerticalArrangement_LED v . Visible v to false v

set TableArrangement_Buzzer v . Visible v to false v
```

```
when BluetoothLE1 .Disconnected
    set Screen1 •
                   Title •
                                    Wait for connection
                             Visible v to
    set ListPicker_Mode •
                           Enabled v to
    set Slider_RightWing •
    set Slider_LED_R .
                        ThumbEnabled •
    set Slider_LED_G . ThumbEnabled .
                                               false 🔻
    set Slider LED B
    set Button_Disconnect •
                  TimerEnabled •
    call BluetoothLE1 .StartScanning
```

Wings (Blocks)

Here we are going to control the wings by buttons and sliders, which are exactly the same with **Codi Bot wing tutorial**.

6. Button to move wings to home position

We create a procedure (**home**) to move wings and sliders back to their home position, which is **45** for left wing and **135** for right wing.

7. Button to flap wings

This section is exactly the same with <u>Codi Bot wing tutorial</u>. We use **Button_WingFlap** to control the clock timer, which in turns make wings flapping.

For simplicity, we create two procedures (**forward**, **backward**) to control servo motor positions.

```
initialize global flap to false 🔻
when Button_WingFlap . Click
                         TimerEnabled •
    🗯 if
             Clock1 ▼
                          TimerEnabled •
           set Clock1 *
           set Button_WingFlap *
                                   Text ▼ to
                                                  " Flap "
           set Clock1 ▼ . TimerEnabled ▼
                                          to |
                                               true 🔻
           set Button_WingFlap *
                                   Text ▼
   when Clock1 .Timer
        📮 if
                      get global flap 🔻
                                                 true 🔻
               call forward *
               set global flap v to (false v
               call backward •
               set global flap ▼ to 📜 true ▼
             to forward

  call MT7697_LeftWingServo ▼

                                               .Write
                                                value
               call MT7697_RightWingServo ▼ .Write
                                                 value
                                                        180
          🔯 to (backward)
               call MT7697_LeftWingServo *
                                               .Write
                                               value
                                                       90

            call MT7697_RightWingServo ▼ .Write

                                                value
                                                        90
```

8. Sliders to move each wing

When you drag a slider, the corresponding servo motor will move to the specific position.

```
when Slider_LeftWing .PositionChanged
 thumbPosition
    set Label_LeftWing ▼ . Text ▼ to (
                                           round • get thumbPosition •
    ? call (MT7697_LeftWingServo • ).Write
                                    value
                                                90
                                                round get (thumbPosition
when Slider RightWing .PositionChanged
 thumbPosition
    set Label_RightWing ▼ . Text ▼ to (
                                            270
                                            round 🔻 🛴 get (thumbPosition 🔻
    ? call MT7697 RightWingServo . Write
                                                 270
                                                 round y get thumbPosition
```

LED (Blocks)

Here we are going to control the LEDs by buttons and sliders, which are exactly the same with **Codi Bot LED tutorial**.

9. Button to control RGB LED

These three buttons are used to control the red, green and blue color of RGB LED. For red light, we use MT7697_LED_R.Write method with value 255 to turn on the red light; and with value 0 to turn it off. Please finish other two button events in a same manner.

```
when Button_LED_G . Click
    🔯 if
                Button_LED_G . Text .
    then (2) call (MT7697_LED_G v .Write
                                           255
           set Button_LED_G *
                               Text ▼ to
           🕡 call (MT7697_LED_G 🔻
                                    value
                               Text ▼ to
           set Button_LED_G *
                                            " (G)
when Button_LED_B ▼ .Click
    🔯 if
                Button_LED_B . Text .

  call MT7697_LED_B ▼ .Write

                                   value
                                          255
           set Button LED B *
                              Text ▼ to
           ? call MT7697_LED_B v .Write
                                          0
                                   value
           set Button_LED_B *
```

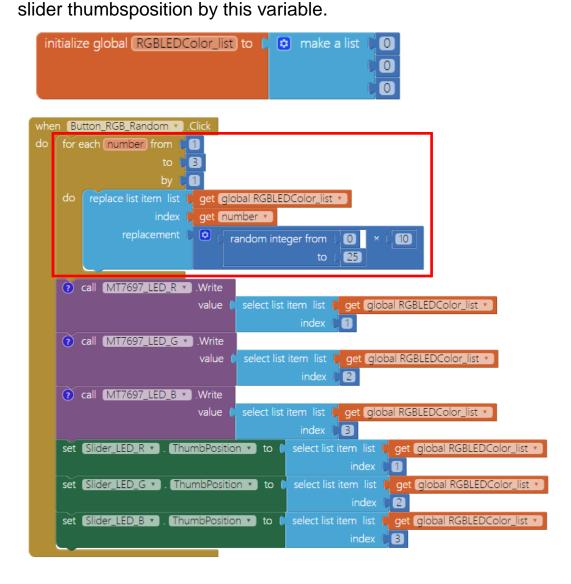
10. Button to control the green and purple wing LEDs

These two buttons are used to control the LED of both wings. The idea is same with the previous step.

```
when Button_LED_LeftWing . Click
                Button_LED_LeftWing ▼
                                      Text ▼
                                                       L_Wing
          7 call MT7697_LeftWingLED •
                                       .Write
                                               255
                                        value
          set Button_LED_LeftWing •
                                    Text ▼ to
          call (MT7697_LeftWingLED *)
                                       .Write
          set Button LED LeftWing v
                                    Text ▼ to
when Button_LED_RightWing . Click
                Button_LED_RightWing •
                                       Text ▼
                                                         R_Wing
    then (7) call (MT7697_RightWingLED v .Write
                                                255
                                         value
          set Button_LED_RightWing *
          call MT7697_RightWingLED .Write
                                         value 📗
                                                255
          set Button_LED_RightWing •
                                      Text ▼ to
```

11. Button to randomize RGB LED color

We can also randomize the RGB LED color. When Button_RGB_Random is pressed, we first use a for each loop to replace the RGBLEDColor_list variable content with random number from 0 to 250 and control the corresponding color and



12. Sliders to fine adjust RGB LED color

When slider is dragged, we simply control the corresponding color by slider thumbposition.

```
when Slider_LED_R .PositionChanged
 thumbPosition
   (2) call MT7697_LED_R ▼ .Write
                                    round *
                                               get (thumbPosition
                             value
when Slider_LED_G .PositionChanged
 thumbPosition
do ? call MT7697_LED_G v .Write
                                             get (thumbPosition 🔻
                             value (
                                    round *
when Slider LED B .PositionChanged
thumbPosition
do 🕡 call MT7697_LED_B 🔻 .Write
                             value (round v
                                              get (thumbPosition
```

Sound (Blocks)

Here we are going to control the wings by buttons and sliders, which are exactly the same with **Codi Bot Sound tutorial**.

13. Buttons to make sounds of different notes

We have eight buttons here, each of them will tell the buzzer inside Codi Bot to make a different note. For example, when **Button_C** is pressed (**Button_C.Click** event), we use a **MT7697Buzzer.Buzz** method to make a sound of Note C by specifying **frequency** as 262 and **duration** as 200 (milliseconds). Please finish other seven button events in a same manner.

```
when Button_D ▼ .Click
when Button_C .Click
                                              call MT7697Buzzer1 .Buzz
    call MT7697Buzzer1 ▼ .Buzz
                                                                frequency
                                                                           294
                      frequency
                                  262
                                                                 duration
                                                                           200
                                 200
                       duration
                                         when Button_F ▼ .Click
when Button_E .Click
                                              call MT7697Buzzer1 ▼ .Buzz
   call MT7697Buzzer1 ▼ .Buzz
                                                                           349
                                                                frequency
                      frequency
                                 330
                                                                           200
                                                                 duration
                                 200
                       duration
                                         when Button_A . Click
when Button_G .Click
                                              call MT7697Buzzer1 ▼ .Buzz
    call MT7697Buzzer1 ▼ .Buzz
                                                                frequency
                                                                           440
                      frequency
                                 392
                                                                 duration
                                                                           200
                       duration
                                 200
                                         when Button_C2 ▼ .Click
when Button_B .Click
                                              call MT7697Buzzer1 ▼ .Buzz
    call MT7697Buzzer1 ▼ .Buzz
                                                                frequency
                                                                           524
                      frequency
                                 493
                                                                 duration
                                                                           200
                       duration
                                  200
```

Arduino IDE and sketch

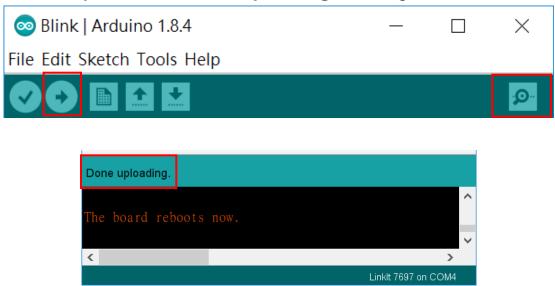
Make sure your computer has Arduino IDE installed and Linklt 7697 SDK/driver are ready. If not, please check <u>Codi Bot Standalone</u> <u>tutorial</u>.

Connect your computer and LinkIt 7697 with a microUSB cable.

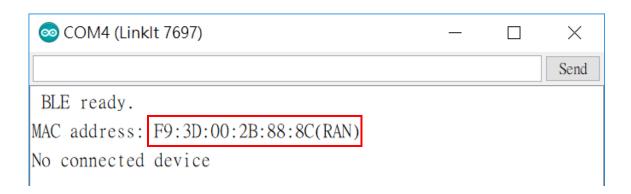


Please download the Arduino sketch from here and open in your Arduino IDE. This sketch can be used for all following Codi Bot projects, let you focus on building App Inventor projects.

Press the "**Upload**" right-arrow button of Arduino IDE, this will compile and upload the Arduino sketch to your Linklt 7697. Please make sure you see the "**done uploading**" message in the console.

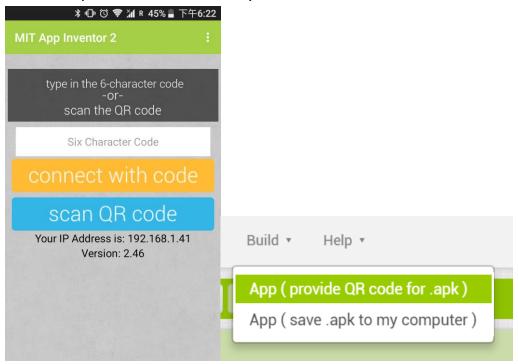


Click the magnifier icon at the up-right corner of Arduino IDE, you should see a message in the pop-up window. The [XX:XX:XX:XX:XX] 12-digit string is the Bluetooth address of your LinkIt 7697. We will choose the device of this address in our app.



Tips

Make sure your LinkIt 7697 is running correctly. And install App Inventor project on your Android phone by clicking Build / App (provide QR code for .apk), this will show a qrcode for .apk file. Use MIT Al2 Companion to scan this qrcode, download and install.



Open Codi Bot app (Fig 1.) and click **Connect** ListPicker, you'll see a list of available Bluetooth devices (Fig 2). In general, the first item is the Codi Bot where "**F9:3D:00:2B:88:8C**" is the Bluetooth address of my Codi Bot. Click it and your phone will try to connect with the Codi Bot, if connect successfully, you will see your app like Fig 3.

Click **Mode** ListPicker to choose which mode you want to play: **Wing**, **LED** and **Sound** (Fig. 4). Choose one to interact with your Codi Bot (Fig 5 to Fig 7). Remember to click **Disconnect** button when you finish with this project.

