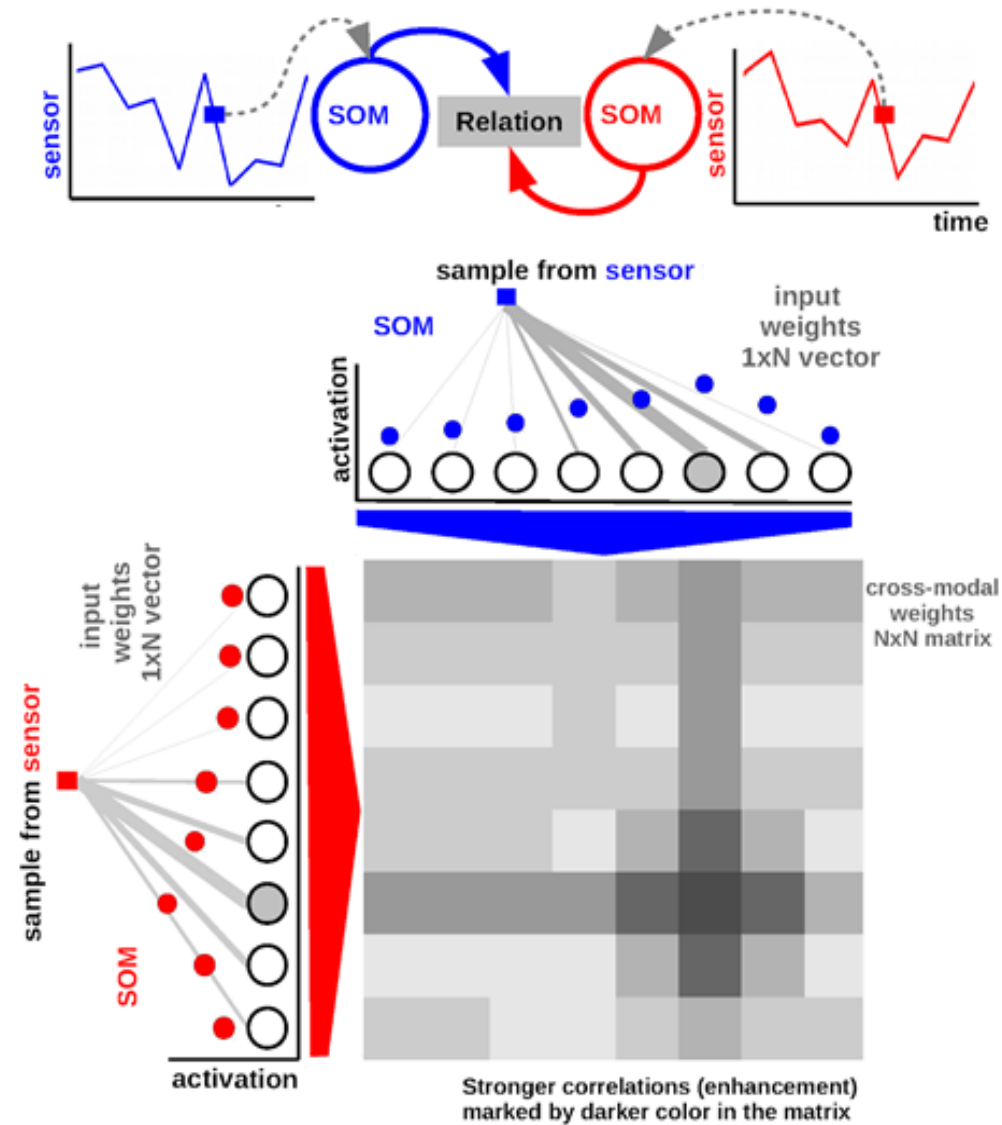




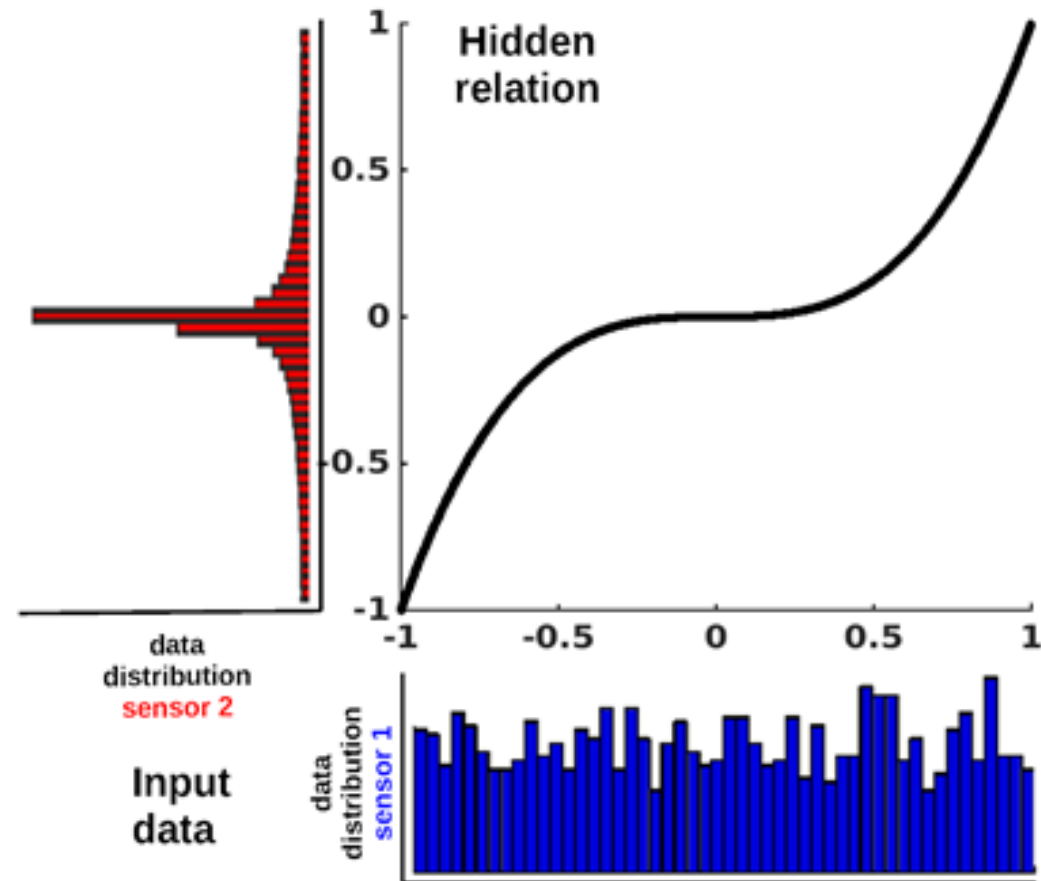
Dr. Cristian Axenie

# Basic Model

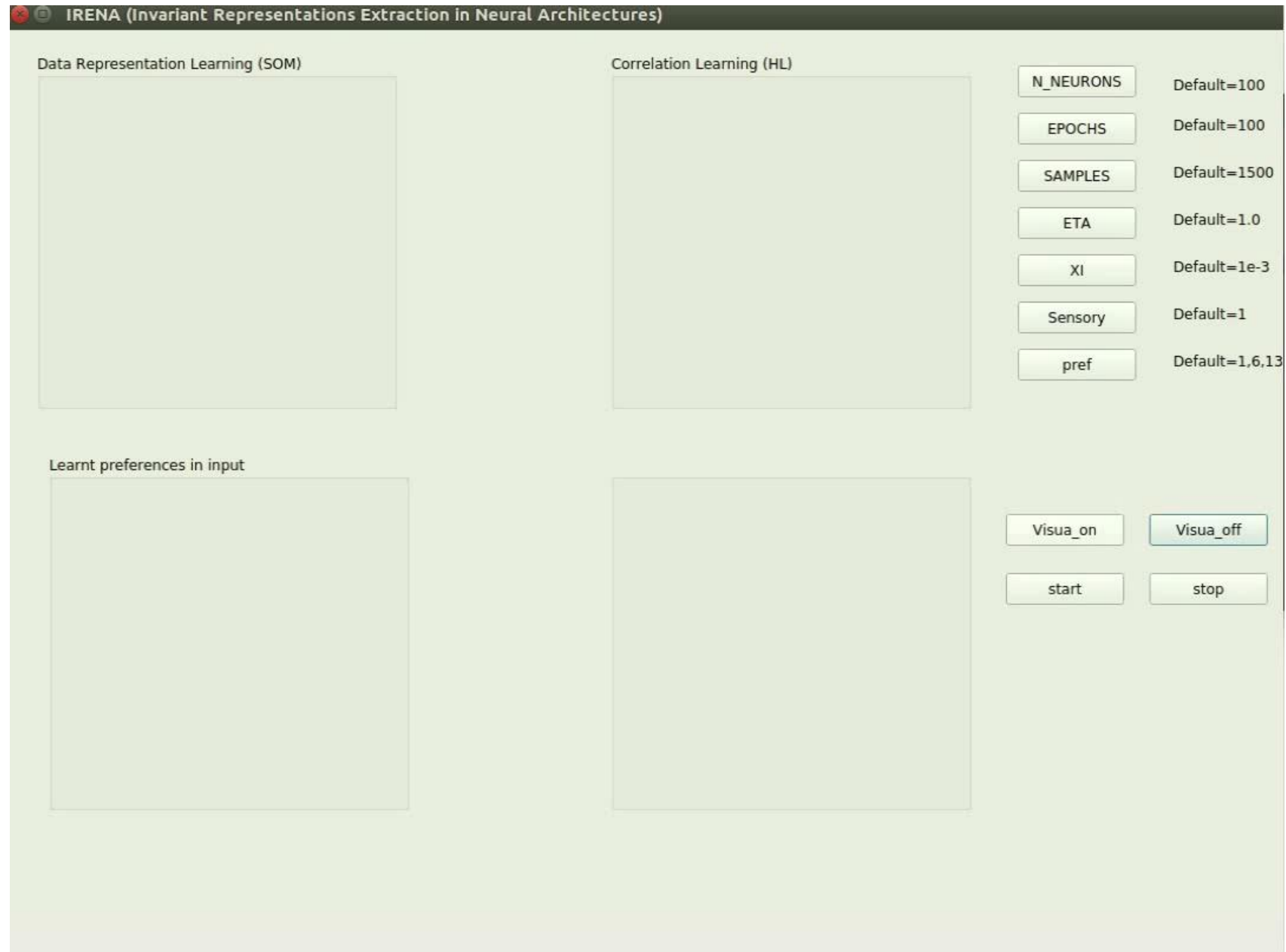


# Learning invariants in low-dimensional spaces

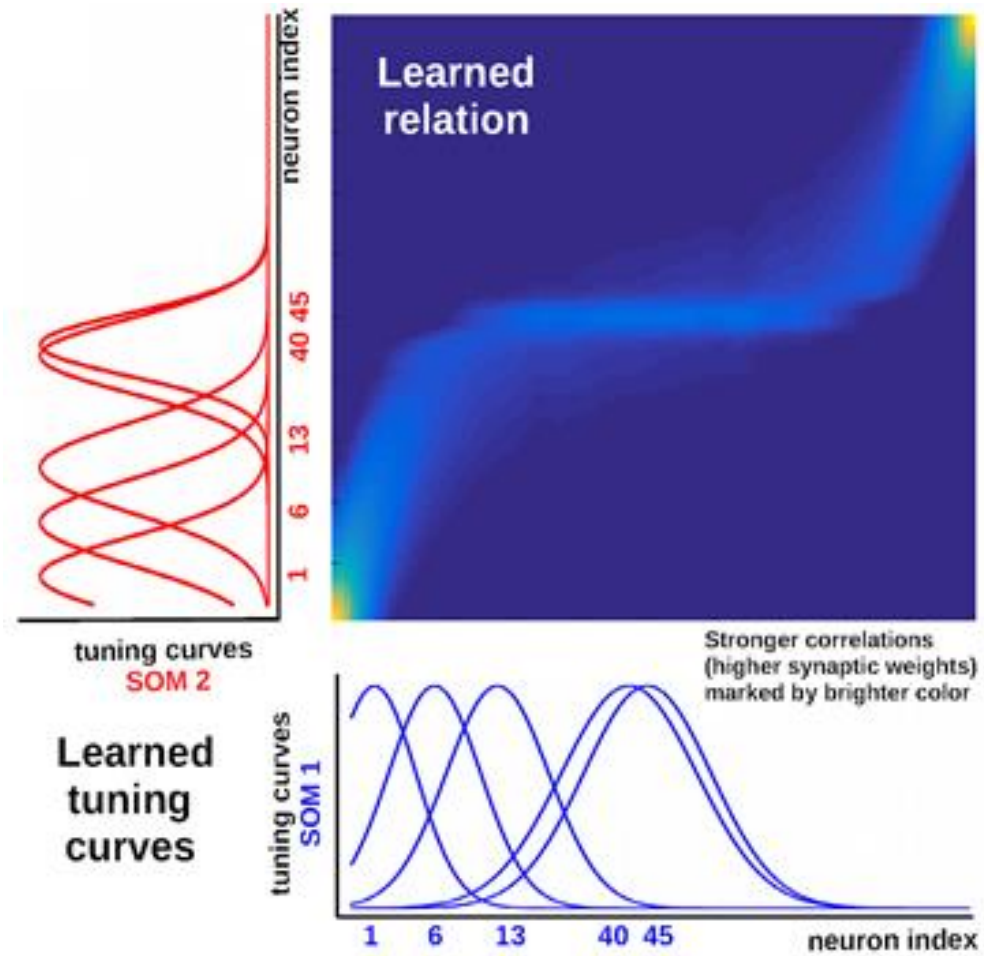
# Learning invariants in 1D



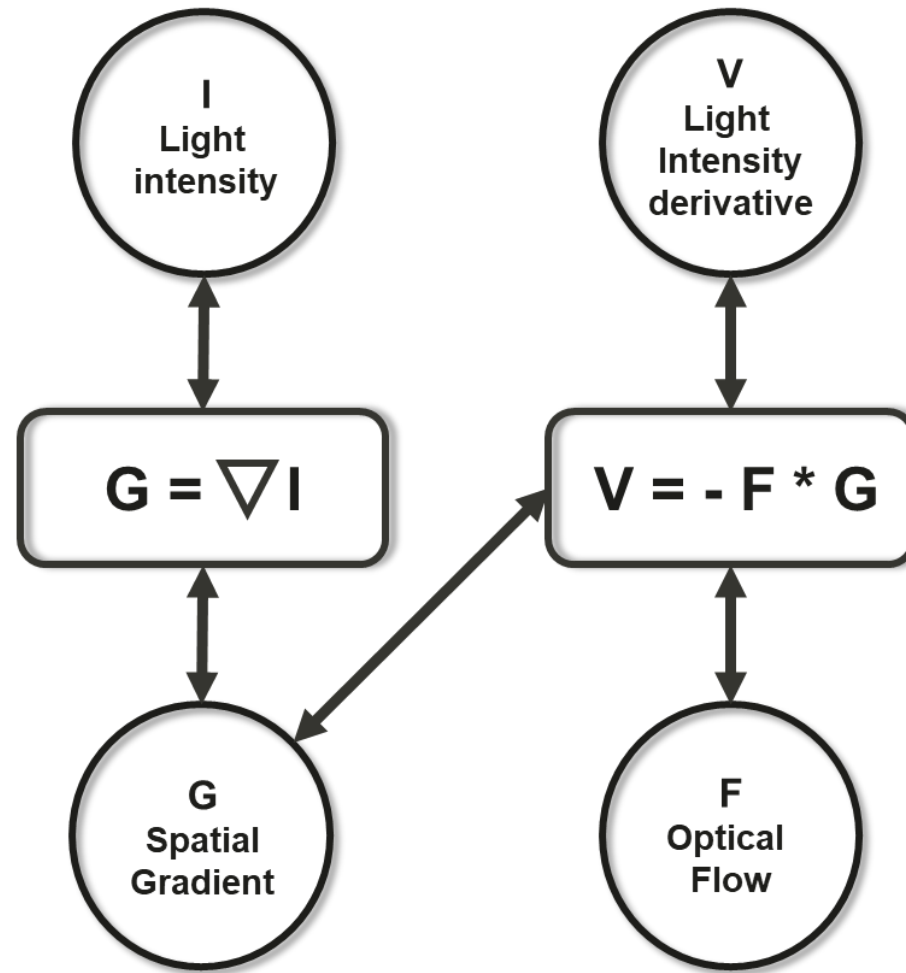
# Learning invariants in 1D



# Learning invariants in 1D

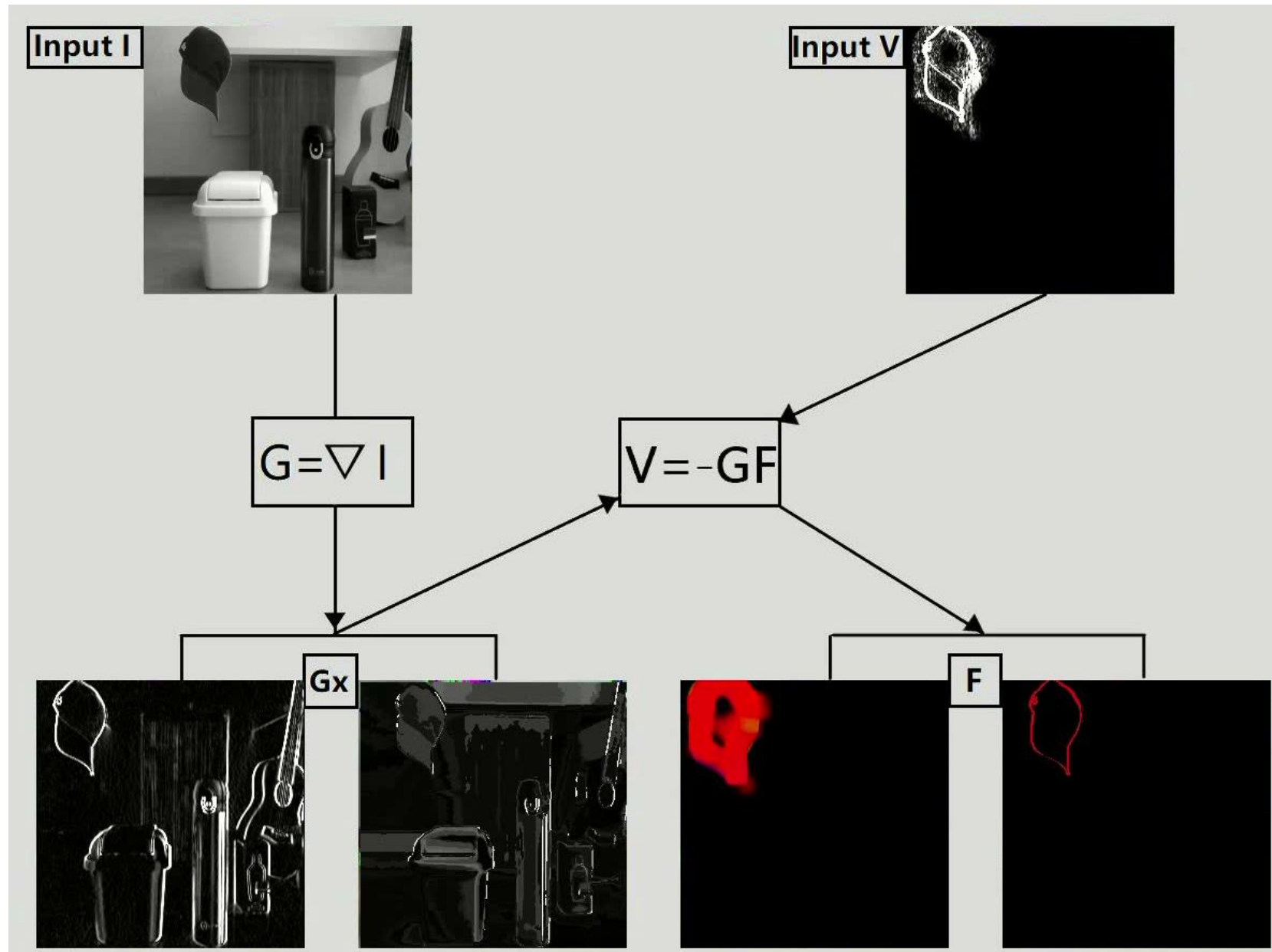


# Learning invariants in high-dimensional visual scenes



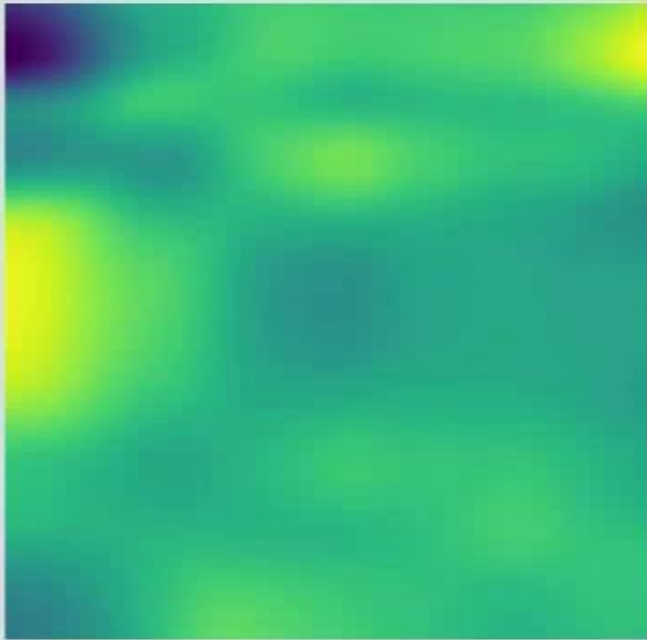


# Learning spatial gradient and optic flow

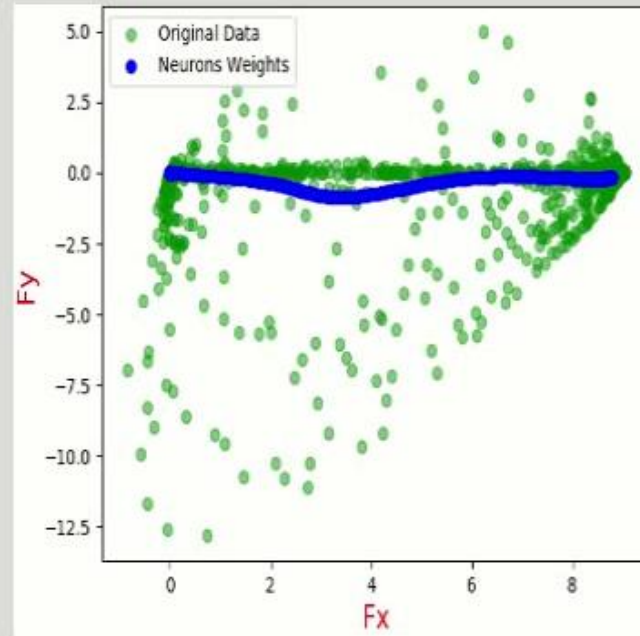


Training

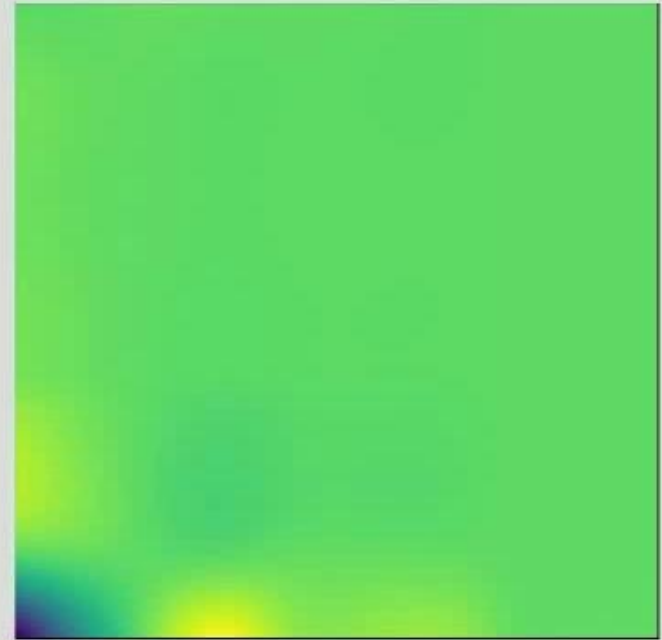
HL matrix (G&I)



SOM (Fx, Fy)

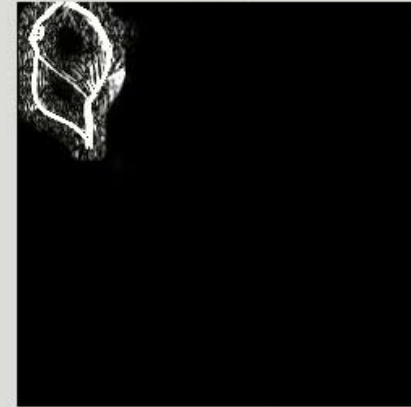


HL matrix ([V,G],[F])



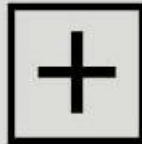


Input I

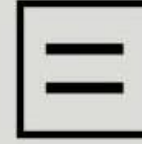


Input V

Start Position



Optical Flow Image

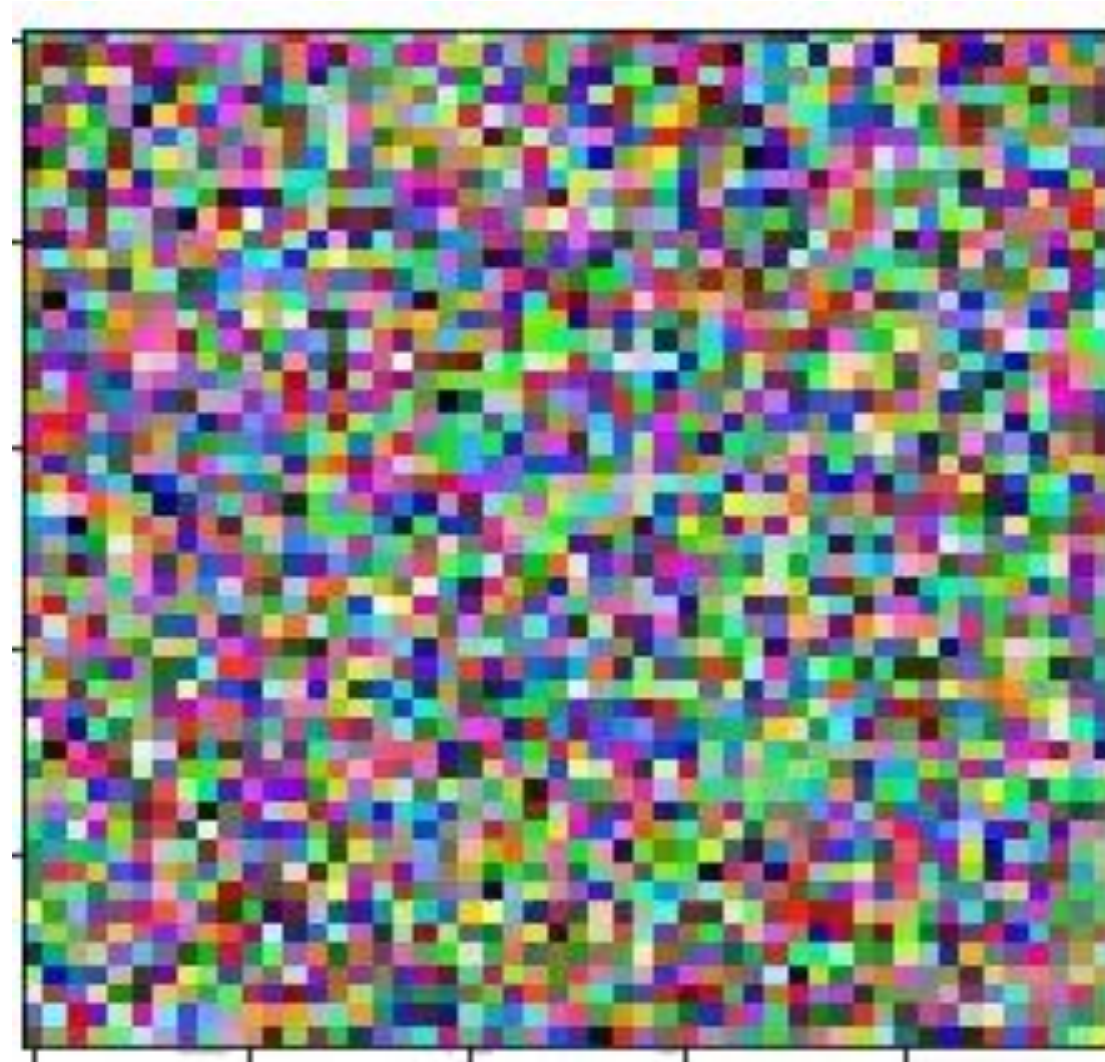


Predicted Position



# Learning semantics in the visual scene

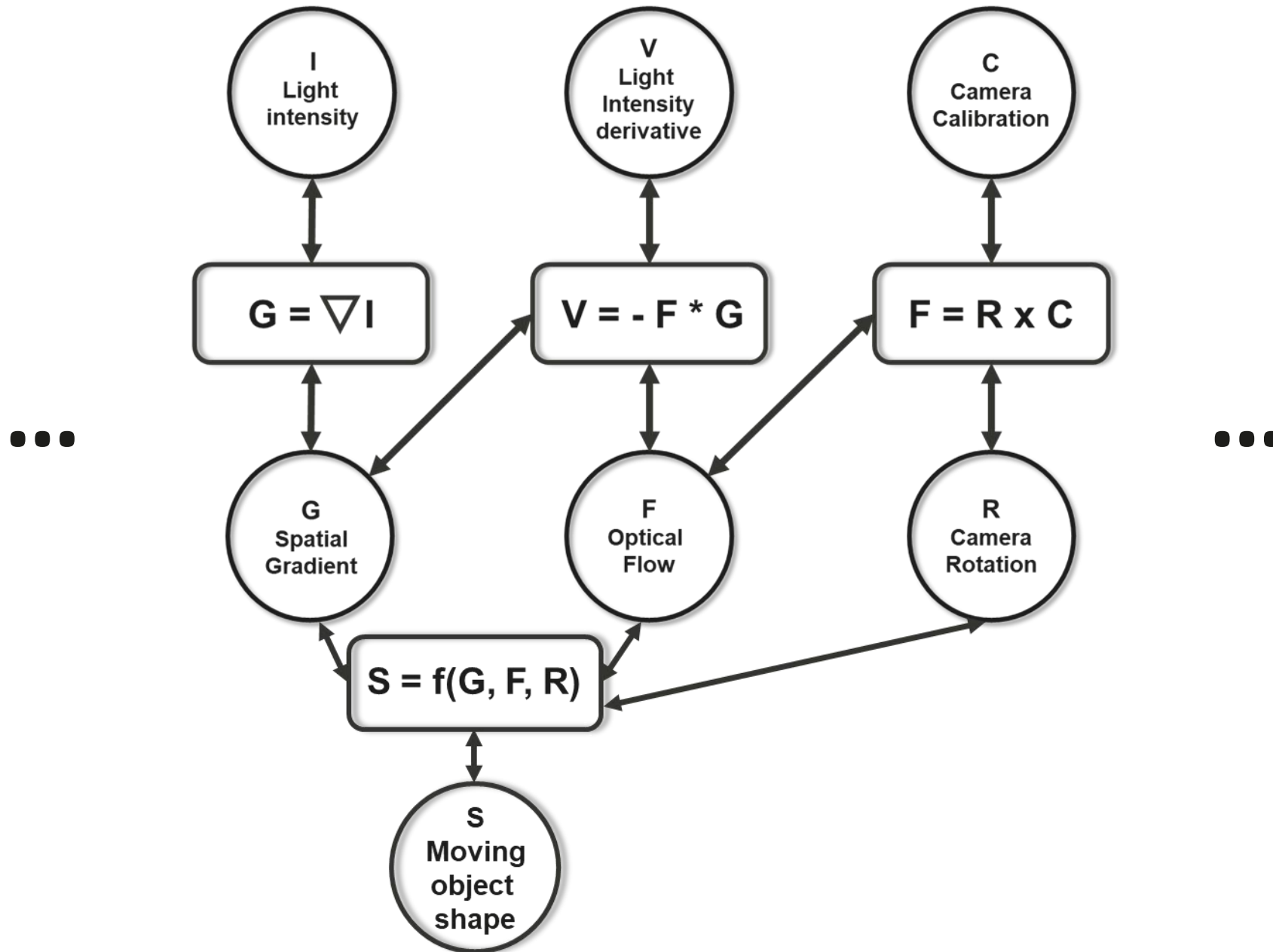
Clustering and classification intrinsically in the system (SOM clustering)



## NeuroTHix



# Next steps: Learning full rich 3D visual scenes





**IRENA**

Invariant Representations Extraction in  
Neural Architectures

Neuro**TH**x



**Du XIAORUI**



**Yavuzhan ERDEM**



**Cristian AXENIE**