

Disjoint sets

```

#define REP(i, a, b) \ // all codes involving REP uses this macro
for (int i = int(a); i <= int(b); i++)
vector<int> pset(1000); // 1000 is just an initial number, it is user-adjustable.
void initSet(int _size) { pset.resize(_size); REP (i, 0, _size - 1) pset[i] = i; }
int findSet(int i) { return (pset[i] == i) ? i : (pset[i] = findSet(pset[i])); }
void unionSet(int i, int j) { pset[findSet(i)] = findSet(j); }
bool isSameSet(int i, int j) { return findSet(i) == findSet(j); }

```

Shortcuts

```

// Shortcuts for "common" data types in contests
typedef long long ll; // comments that are mixed in with code
typedef pair<int, int> ii; // are aligned to the right like this
typedef vector<ii> vii;
typedef vector<int> vi;
#define INF 1000000000 // 1 billion, safer than 2B for Floyd Warshall's
// Common memset settings
memset(memo, -1, sizeof memo); // initialize DP memoization table with -1
memset(arr, 0, sizeof arr); // to clear array of integers
// We have abandoned the use of "REP" and "TRvii" since the second edition
// in order to reduce the confusion encountered by new programmers
// The following shortcuts are frequently used in both our C/C++ and Java code:
ans = a ? b : c; // to simplify: if (a) ans = b; else ans = c;
ans += val; // to simplify: ans = ans + val; and its variants
index = (index + 1) % n; // index++; if (index >= n) index = 0;
index = (index + n - 1) % n; // index--; if (index < 0) index = n - 1;
int ans = (int)((double)d + 0.5); // for rounding to nearest integer
ans = min(ans, new_computation); // min/max shortcut
// alternative form but not used in this book: ans <?= new_computation;
some code use short circuit && (AND) and || (OR)

```

Libraries

```

#include <bits/stdc++.h>
std::sync_with_stdio(false);
$ g++ -std=c++11 myC.cc -o myC
$ ./myC <a.in >a.out
##### I/O

```

C/C++ Source Code	Sample Input	Sample Output
-------------------	--------------	---------------

int TC, a, b;	3	3
scanf("%d", &TC); // number of test cases	1 2	12
while (TC--) { // shortcut to repeat until 0	5 7	9
scanf("%d %d", &a, &b); // compute answer	6 3	-----
printf("%d\n", a + b); // on the fly	-----	
}		

int a, b;	1 2	3
// stop when both integers are 0	5 7	12
while (scanf("%d %d", &a, &b), (a b))	6 3	9
printf("%d\n", a + b);	0 0	-----

int a, b;	1 2	3
// scanf returns the number of items read	5 7	12
while (scanf("%d %d", &a, &b) == 2)	6 3	9
// or you can check for EOF, i.e.	-----	-----
while (scanf("%d %d", &a, &b) != EOF)		
printf("%d\n", a + b);		

int a, b, c = 1;	1 2	Case 1: 3
while (scanf("%d %d", &a, &b) != EOF)	5 7	
// notice the two '\n'	6 3	Case 2: 12
printf("Case %d: %d\n\n", c++, a + b);	-----	
		Case 3: 9

int a, b, c = 1;	1 2	Case 1: 3
while (scanf("%d %d", &a, &b) != EOF) {	5 7	

```

if (c > 1) printf("\n"); // 2nd/more cases
    printf("Case %d: %d\n", c++, a + b);
}

-----

int k, ans, v;
while (scanf("%d", &k) != EOF) {
    ans = 0;
    while (k--) { scanf("%d", &v); ans += v; }
    printf("%d\n", ans);
}

-----

##### DFS
typedef pair<int, int> ii; // In this chapter, we will frequently use these
typedef vector<ii> vii; // three data type shortcuts. They may look cryptic
typedef vector<int> vi; // but they are useful in competitive programming
vi dfs_num; // global variable, initially all values are set to UNVISITED
void dfs(int u) { // DFS for normal usage: as graph traversal algorithm
    dfs_num[u] = VISITED; // important: we mark this vertex as visited
    for (int j = 0; j < (int)AdjList[u].size(); j++) { // default DS: AdjList
        ii v = AdjList[u][j]; // v is a (neighbor, weight) pair
        if (dfs_num[v.first] == UNVISITED) // important check to avoid cycle
            dfs(v.first); // recursively visits unvisited neighbors of vertex u
    } // for simple graph traversal, we ignore the weight stored at v.second
}

##### BFS

// inside int main()---no recursion
vi d(V, INF); d[s] = 0; // distance from source s to s is 0
queue<int> q; q.push(s); // start from source
while (!q.empty()) {
    int u = q.front(); q.pop(); // queue: layer by layer!
    for (int j = 0; j < (int)AdjList[u].size(); j++) {
        ii v = AdjList[u][j]; // for each neighbor of u
        if (d[v.first] == INF) { // if v.first is unvisited + reachable
            d[v.first] = d[u] + 1; // make d[v.first] != INF to flag it
            q.push(v.first); // enqueue v.first for the next iteration
        }
    }
}

##### Flood Fill
int dr[] = {1,1,0,-1,-1,-1, 0, 1}; // trick to explore an implicit 2D grid
int dc[] = {0,1,1, 1, 0,-1,-1,-1}; // S,SE,E,NE,N,NW,W,SW neighbors
int floodfill(int r, int c, char c1, char c2) { // returns the size of CC
    if (r < 0 || r >= R || c < 0 || c >= C) return 0; // outside grid
    if (grid[r][c] != c1) return 0; // does not have color c1
    int ans = 1; // adds 1 to ans because vertex (r, c) has c1 as its color
    grid[r][c] = c2; // now recolors vertex (r, c) to c2 to avoid cycling!
    for (int d = 0; d < 8; d++)
        ans += floodfill(r + dr[d], c + dc[d], c1, c2);
    return ans; // the code is neat due to dr[] and dc[]
}

##### Kruskall

// inside int main()
vector< pair<int, ii> > EdgeList; // (weight, two vertices) of the edge
for (int i = 0; i < E; i++) {
    scanf("%d %d %d", &u, &v, &w); // read the triple: (u, v, w)
    EdgeList.push_back(make_pair(w, ii(u, v))); } // (w, u, v)
sort(EdgeList.begin(), EdgeList.end()); // sort by edge weight O(E log E)
// note: pair object has built-in comparison function
int mst_cost = 0;
UnionFind UF(V); // all V are disjoint sets initially
for (int i = 0; i < E; i++) { // for each edge, O(E)
    pair<int, ii> front = EdgeList[i];
    if (!UF.isSameSet(front.second.first, front.second.second)) { // check
        mst_cost += front.first; // add the weight of e to MST
        UF.unionSet(front.second.first, front.second.second); // link them
    } // note: the runtime cost of UFDS is very light
} // note: the number of disjoint sets must eventually be 1 for a valid MST
printf("MST cost = %d (Kruskal's)\n", mst_cost);

```

```
##### Dijkstra
vector<int> dist(V, INF); dist[s] = 0; // INF = 2.10^9 not MAX_INT to avoid overflow
priority_queue<ii, vector<ii>, greater<ii> > pq; pq.push(ii(0, s)); // sort by distance
while (!pq.empty()) { // main loop
    ii top = pq.top(); pq.pop(); // greedy: pick shortest unvisited vertex
    int d = top.first, u = top.second;
    if (d == dist[u]) // This check is important! We want to process vertex u only once but
    we can
        // actually enqueue u several times in priority_queue... Fortunately, other
        occurrences of u
        // in priority_queue will have greater distances and can be ignored (the overhead is
        small) :)
    TRvii (AdjList[u], it) { // all outgoing edges from u
        int v = it->first, weight_u_v = it->second;
        if (dist[u] + weight_u_v < dist[v]) { // if can relax
            dist[v] = dist[u] + weight_u_v; // relax
            pq.push(ii(dist[v], v)); // enqueue this neighbor
        }
    }
}
```

```
##### LIS
#include <algorithm>
#include <cstdio>
#include <stack>
using namespace std;
```

```
#define MAX_N 100000
```

```
void print_array(const char *s, int a[], int n) {
    for (int i = 0; i < n; ++i) {
        if (i) printf(", ");
        else printf("%s: [", s);
        printf("%d", a[i]);
    }
    printf("]\n");
}

void reconstruct_print(int end, int a[], int p[]) {
    int x = end;
    stack<int> s;
    for (; p[x] >= 0; x = p[x]) s.push(a[x]);
    printf("[%d", a[x]);
    for (; !s.empty(); s.pop()) printf(", %d", s.top());
    printf("]\n");
}
```

```
int main() {
    int n = 11, A[] = {-7, 10, 9, 2, 3, 8, 8, 1, 2, 3, 4};
    int L[MAX_N], L_id[MAX_N], P[MAX_N];

    int lis = 0, lis_end = 0;
    for (int i = 0; i < n; ++i) {
        int pos = lower_bound(L, L + lis, A[i]) - L;
        L[pos] = A[i];
        L_id[pos] = i;
        P[i] = pos ? L_id[pos - 1] : -1;
        if (pos + 1 > lis) {
            lis = pos + 1;
            lis_end = i;
        }

        printf("Considering element A[%d] = %d\n", i, A[i]);
        printf("LIS ending at A[%d] is of length %d: ", i, pos + 1);
        reconstruct_print(i, A, P);
        print_array("L is now", L, lis);
        printf("\n");
    }

    printf("Final LIS is of length %d: ", lis);
    reconstruct_print(lis_end, A, P);
    return 0;
}
```

Algorithm

Non-modifying sequence operations:

```

all_of      Test condition on all elements in range (function template )
any_of      Test if any element in range fulfills condition (function template )
none_of     Test if no elements fulfill condition (function template )
for_each    Apply function to range (function template )
find        Find value in range (function template )
find_if     Find element in range (function template )
find_if_not Find element in range (negative condition) (function template )
find_end    Find last subsequence in range (function template )
find_first_of Find element from set in range (function template )
adjacent_find Find equal adjacent elements in range (function template )
count       Count appearances of value in range (function template )
count_if    Return number of elements in range satisfying condition (function template )
mismatch    Return first position where two ranges differ (function template )
equal       Test whether the elements in two ranges are equal (function template )
is_permutation Test whether range is permutation of another (function template )
search      Search range for subsequence (function template )
search_n    Search range for elements (function template )

```

Modifying sequence operations:

```

copy        Copy range of elements (function template )
copy_n      Copy elements (function template )
copy_if     Copy certain elements of range (function template )
copy_backward Copy range of elements backward (function template )
move        Move range of elements (function template )
move_backward Move range of elements backward (function template )
swap        Exchange values of two objects (function template )
swap_ranges Exchange values of two ranges (function template )
iter_swap   Exchange values of objects pointed to by two iterators (function template )
transform   Transform range (function template )
replace     Replace value in range (function template )
replace_if  Replace values in range (function template )
replace_copy Copy range replacing value (function template )
replace_copy_if Copy range replacing value (function template )
fill        Fill range with value (function template )
fill_n      Fill sequence with value (function template )
generate    Generate values for range with function (function template )
generate_n  Generate values for sequence with function (function template )
remove      Remove value from range (function template )
remove_if   Remove elements from range (function template )
remove_copy Copy range removing value (function template )
remove_copy_if Copy range removing values (function template )
unique      Remove consecutive duplicates in range (function template )
unique_copy Copy range removing duplicates (function template )
reverse     Reverse range (function template )
reverse_copy Copy range reversed (function template )
rotate      Rotate left the elements in range (function template )
rotate_copy Copy range rotated left (function template )
random_shuffle Randomly rearrange elements in range (function template )
shuffle     Randomly rearrange elements in range using generator (function template )

```

Partitions:

```

is_partitioned Test whether range is partitioned (function template )
partition      Partition range in two (function template )
stable_partition Partition range in two - stable ordering (function template )
partition_copy Partition range into two (function template )
partition_point Get partition point (function template )

```

Sorting:

```

sort          Sort elements in range (function template )
stable_sort    Sort elements preserving order of equivalents (function template )
partial_sort   Partially sort elements in range (function template )
partial_sort_copy Copy and partially sort range (function template )
is_sorted      Check whether range is sorted (function template )

```

`is_sorted_until` Find first unsorted element in range (function `template`)
`nth_element` Sort element in range (function `template`)

Binary search (operating on partitioned/sorted ranges):

`lower_bound` Return iterator to lower bound (function `template`)
`upper_bound` Return iterator to upper bound (function `template`)
`equal_range` Get subrange of equal elements (function `template`)
`binary_search` Test `if` value exists in sorted sequence (function `template`)

Merge (operating on sorted ranges):

`merge` Merge sorted ranges (function `template`)
`inplace_merge` Merge consecutive sorted ranges (function `template`)
`includes` Test whether sorted range includes another sorted range (function `template`)
`set_union` Union of two sorted ranges (function `template`)
`set_intersection` Intersection of two sorted ranges (function `template`)
`set_difference` Difference of two sorted ranges (function `template`)
`set_symmetric_difference` Symmetric difference of two sorted ranges (function `template`)

Heap:

`push_heap` Push element into heap range (function `template`)
`pop_heap` Pop element from heap range (function `template`)
`make_heap` Make heap from range (function `template`)
`sort_heap` Sort elements of heap (function `template`)
`is_heap` Test `if` range is heap (function `template`)
`is_heap_until` Find first element `not` in heap order (function `template`)

Min/max:

`min` Return the smallest (function `template`)
`max` Return the largest (function `template`)
`minmax` Return smallest `and` largest elements (function `template`)
`min_element` Return smallest element in range (function `template`)
`max_element` Return largest element in range (function `template`)
`minmax_element` Return smallest `and` largest elements in range (function `template`)

Other:

`lexicographical_compare` Lexicographical less-than comparison (function `template`)
`next_permutation` Transform range to next permutation (function `template`)
`prev_permutation` Transform range to previous permutation (function `template`)