

# GAUSSIANS & ASSIGNMENT 1 HANDOUT

PROBABILISTIC DECISION MAKING VU – PRACTICALS

(REINFORCEMENT LEARNING KU)

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A probability space is a triple

$$(\Omega, \mathcal{F}, \mathbb{P})$$

## $\sigma$ -Algebra

Let  $\Omega \neq \emptyset$  be a set and let  $\mathcal{F} \subseteq \mathcal{P}(\Omega)$ . Then  $\mathcal{F}$  is a  $\sigma$ -algebra over  $\Omega$  if

- $\Omega \in \mathcal{F}$
- $A \in \mathcal{F} \implies A^c := \Omega \setminus A \in \mathcal{F}$   
(closed under complement)
- $A_1, A_2, \dots \in \mathcal{F} \implies \bigcup_{i \geq 1} A_i \in \mathcal{F}$   
(closed under countable union)

## Probability Measure

Let  $(\Omega, \mathcal{F})$  be a measurable space. A map

$$\mathbb{P} : \mathcal{F} \rightarrow [0, 1]$$

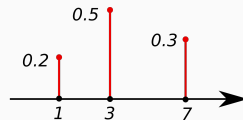
is a **probability measure** if

- $\mathbb{P}(\Omega) = 1$
- for pairwise disjoint  $A_1, A_2, \dots \in \mathcal{F}$ :  
 $\mathbb{P}\left(\bigcup_{i \geq 1} A_i\right) = \sum_{i \geq 1} \mathbb{P}(A_i)$

## Probability Mass Function (PMF)

Let  $X : \Omega \rightarrow \mathcal{X}$  be a **discrete** RV with countable state space  $\mathcal{X}$ . The **probability mass function** (PMF)  $p_X : \mathcal{X} \rightarrow [0, 1]$  is defined as

$$p_X(x) := \mathbb{P}_X(\{x\})$$

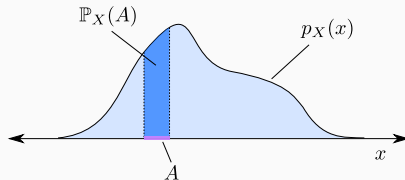


[https://commons.wikimedia.org/wiki/File:Discrete\\_probability\\_distrib.svg](https://commons.wikimedia.org/wiki/File:Discrete_probability_distrib.svg)

## Probability Density Function (PDF)

Let  $X : \Omega \rightarrow \mathcal{X}$  be a RV with state space  $\mathcal{X} = \mathbb{R}$ . If it exists, a function  $p_X : \mathbb{R} \rightarrow [0, \infty]$  is a **density** of  $X$  if for any event  $A$ ,

$$\int_A p_X(x) dx = \mathbb{P}_X(A).$$



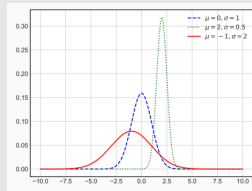
# GAUSSIAN DISTRIBUTION

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## Univariate Gaussian

Gaussian PDF with **mean**  $\mu \in \mathbb{R}$  and **variance**  $\sigma^2 > 0$ :

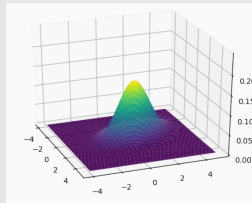
$$p_X(x) = \mathcal{N}(x; \mu, \sigma^2) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{1}{2} \frac{(x - \mu)^2}{\sigma^2}\right)$$



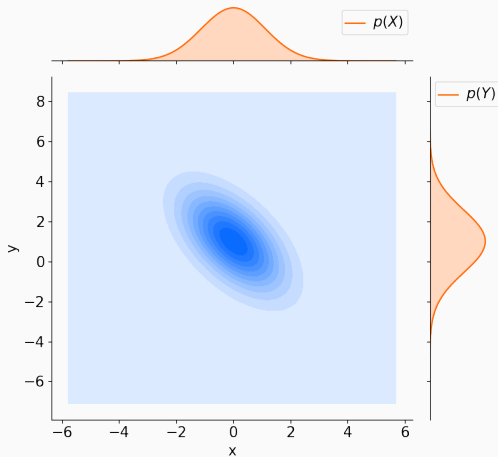
## Multivariate Gaussian

**Mean**  $\mu \in \mathbb{R}^D$ , **symm. pos. def. covariance**  $\Sigma \in \mathbb{R}^{D \times D}$ :

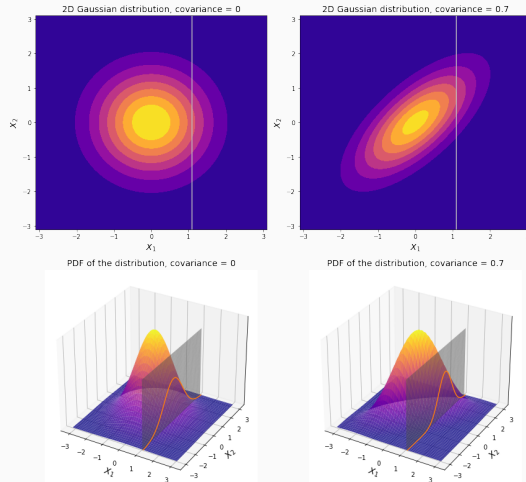
$$\mathcal{N}(x; \mu, \Sigma) = \frac{1}{\sqrt{(2\pi)^D |\Sigma|}} \exp\left(-\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu)\right)$$



- Marginals of Gaussians are again Gaussians !



- Conditionals of Gaussians are again Gaussians !

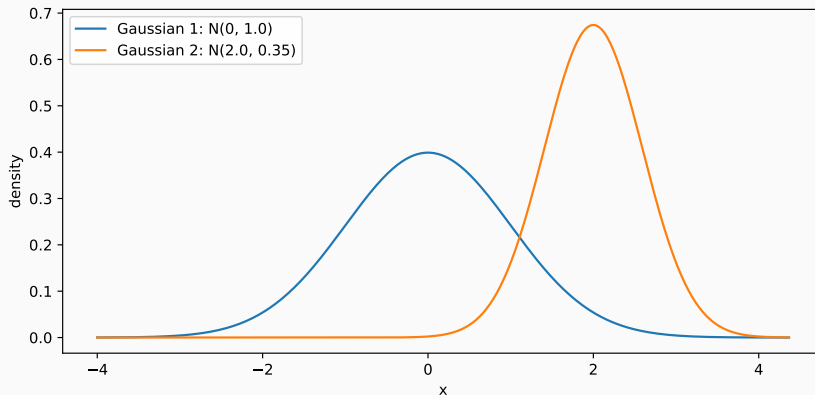


Source: <https://vzahorui.net/regression/gaussian-process/>

- Product of two Gaussian PDFs is again a (scaled) Gaussian PDF !

$$\mathcal{N}(\mathbf{x}; \mathbf{a}, A) \mathcal{N}(\mathbf{x}; \mathbf{b}, B) = Z \cdot \mathcal{N}(\mathbf{x}; \mathbf{c}, C)$$

where  $C := (A^{-1} + B^{-1})^{-1}$ ,  $\mathbf{c} := C(A^{-1}\mathbf{a} + B^{-1}\mathbf{b})$ , and  $Z := \mathcal{N}(\mathbf{a}; \mathbf{b}, A + B)$ .

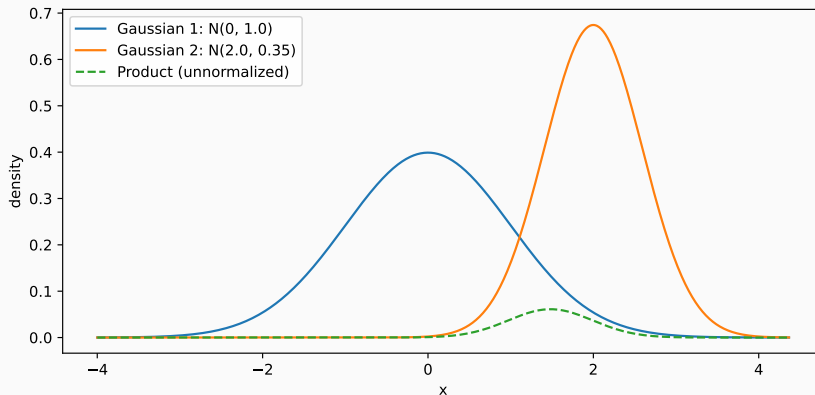




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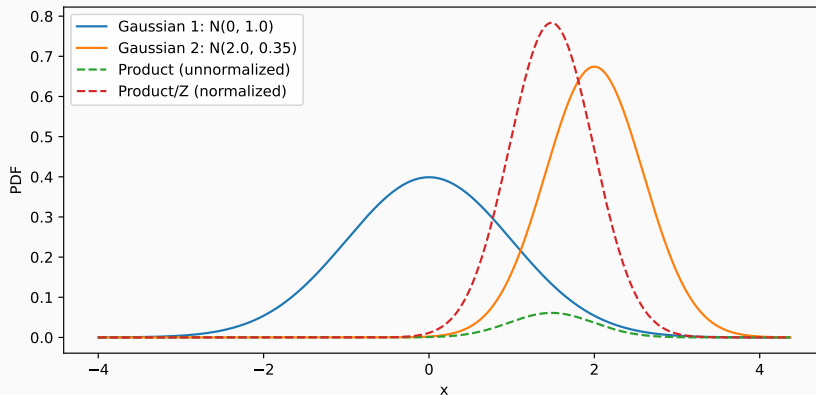
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- **Note:** Product of Gaussian **PDFs**  $\neq$  Product of Gaussian **RVs** !

# ASSIGNMENT 1 HANDOUT

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