

GAUSSIANS & ASSIGNMENT 1 HANDOUT

PROBABILISTIC DECISION MAKING VU – PRACTICALS
(REINFORCEMENT LEARNING KU)

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RECAP: PROBABILITY TRIPLES

A probability space is a triple

$$(\Omega, \mathcal{F}, \mathbb{P})$$

σ -Algebra

Let $\Omega \neq \emptyset$ be a set and let $\mathcal{F} \subseteq \mathcal{P}(\Omega)$. Then \mathcal{F} is a **σ -algebra** over Ω if

- $\Omega \in \mathcal{F}$
- $A \in \mathcal{F} \implies A^c := \Omega \setminus A \in \mathcal{F}$
(closed under complement)
- $A_1, A_2, \dots \in \mathcal{F} \implies \bigcup_{i \geq 1} A_i \in \mathcal{F}$
(closed under countable union)

Probability Measure

Let (Ω, \mathcal{F}) be a measurable space. A map

$$\mathbb{P} : \mathcal{F} \rightarrow [0, 1]$$

is a **probability measure** if

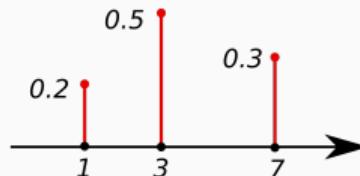
- $\mathbb{P}(\Omega) = 1$
- for pairwise disjoint $A_1, A_2, \dots \in \mathcal{F}$:
$$\mathbb{P}\left(\bigcup_{i \geq 1} A_i\right) = \sum_{i \geq 1} \mathbb{P}(A_i)$$

RECAP: DISTRIBUTION FUNCTIONS

Probability Mass Function (PMF)

Let $X : \Omega \rightarrow \mathcal{X}$ be a discrete RV with countable state space \mathcal{X} . The probability mass function (PMF) $p_X : \mathcal{X} \rightarrow [0, 1]$ is defined as

$$p_X(x) := \mathbb{P}_X(\{x\})$$

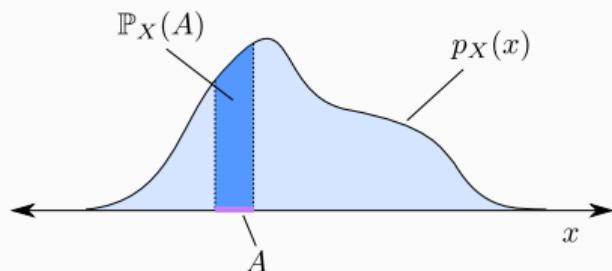


https://commons.wikimedia.org/wiki/File:Discrete_probability_distrib.svg

Probability Density Function (PDF)

Let $X : \Omega \rightarrow \mathcal{X}$ be a RV with state space $\mathcal{X} = \mathbb{R}$. If it exists, a function $p_X : \mathbb{R} \rightarrow [0, \infty]$ is a density of X if for any event A ,

$$\int_A p_X(x) dx = \mathbb{P}_X(A).$$

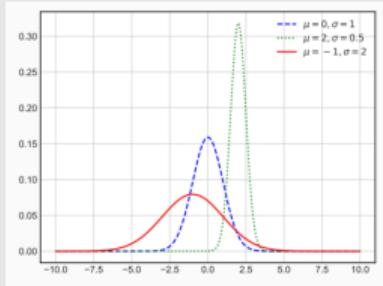


GAUSSIAN DISTRIBUTION

Univariate Gaussian

Gaussian PDF with **mean** $\mu \in \mathbb{R}$ and **variance** $\sigma^2 > 0$:

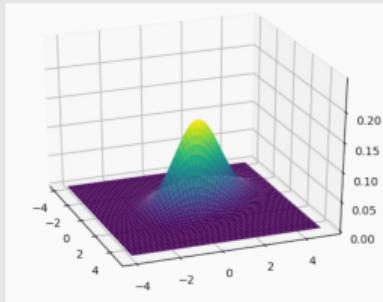
$$p_X(x) = \mathcal{N}(x; \mu, \sigma^2) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{1}{2} \frac{(x - \mu)^2}{\sigma^2}\right)$$



Multivariate Gaussian

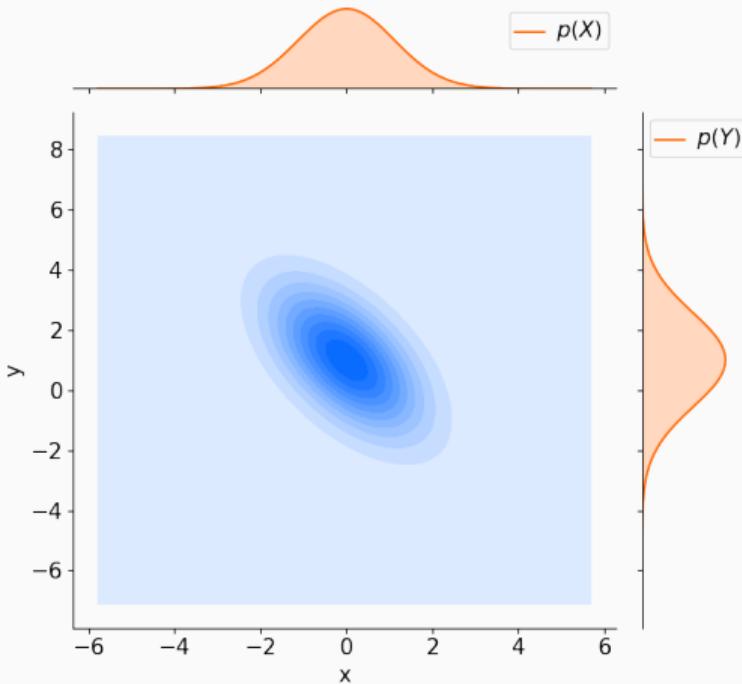
Mean $\mu \in \mathbb{R}^D$, symm. pos. def. covariance $\Sigma \in \mathbb{R}^{D \times D}$:

$$\mathcal{N}(\mathbf{x}; \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{\sqrt{(2\pi)^D |\boldsymbol{\Sigma}|}} \exp\left(-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})\right)$$



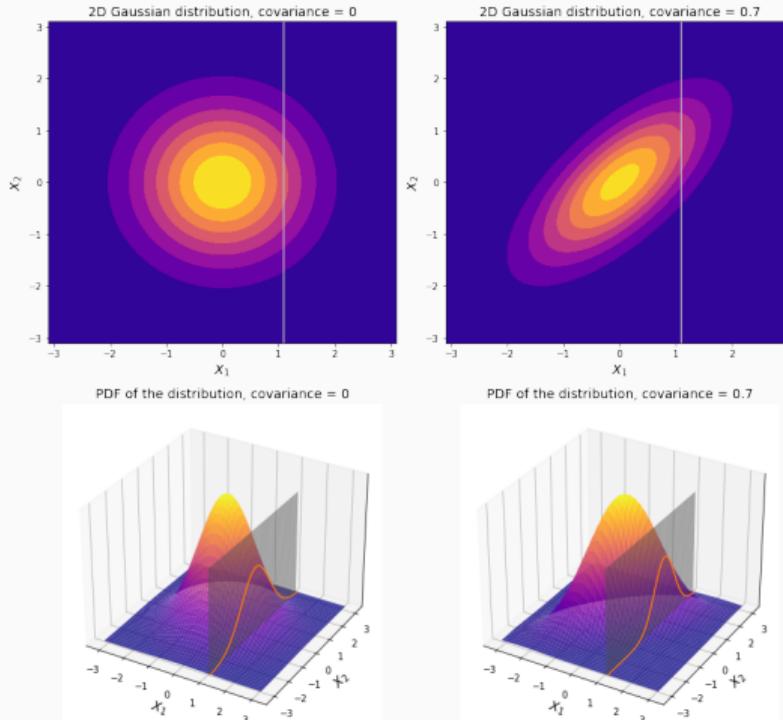
PROPERTIES OF GAUSSIANS

- Marginals of Gaussians are again Gaussians !



PROPERTIES OF GAUSSIANS – CONT.

- Conditionals of Gaussians are again Gaussians !



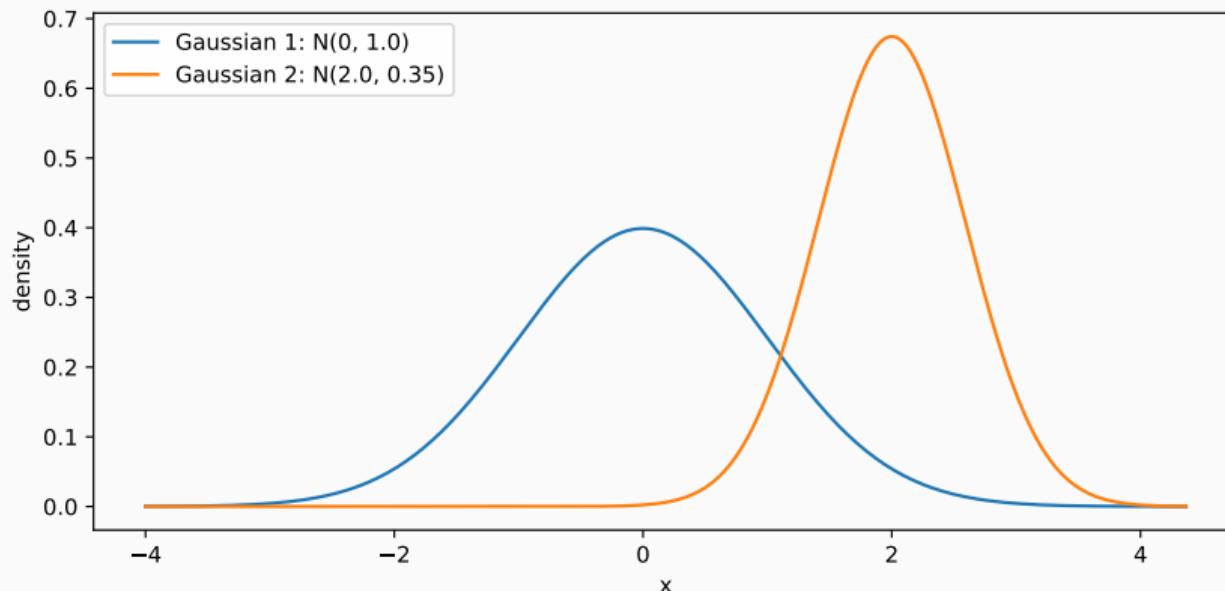
Source: <https://vzahorui.net/regression/gaussian-process/>

PROPERTIES OF GAUSSIANS – CONT.

- Product of two Gaussian PDFs is again a (scaled) Gaussian PDF !

$$\mathcal{N}(\mathbf{x}; \mathbf{a}, \mathbf{A}) \mathcal{N}(\mathbf{x}; \mathbf{b}, \mathbf{B}) = Z \cdot \mathcal{N}(\mathbf{x}; \mathbf{c}, \mathbf{C})$$

where $\mathbf{C} := (\mathbf{A}^{-1} + \mathbf{B}^{-1})^{-1}$, $\mathbf{c} := \mathbf{C}(\mathbf{A}^{-1}\mathbf{a} + \mathbf{B}^{-1}\mathbf{b})$, and $Z := \mathcal{N}(\mathbf{a}; \mathbf{b}, \mathbf{A} + \mathbf{B})$.

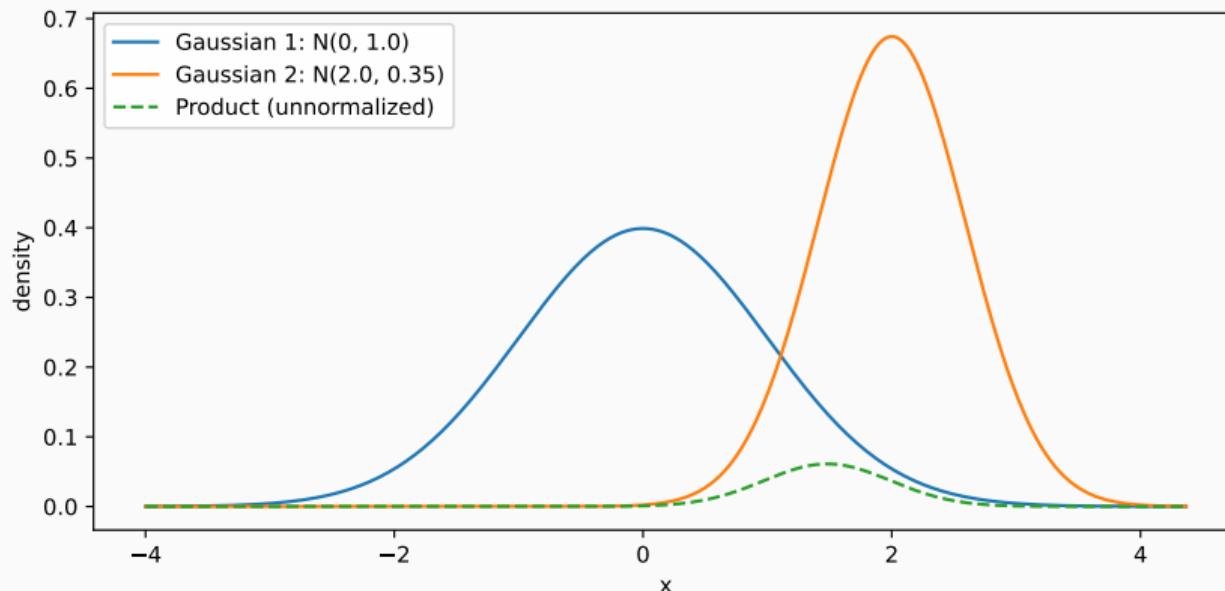


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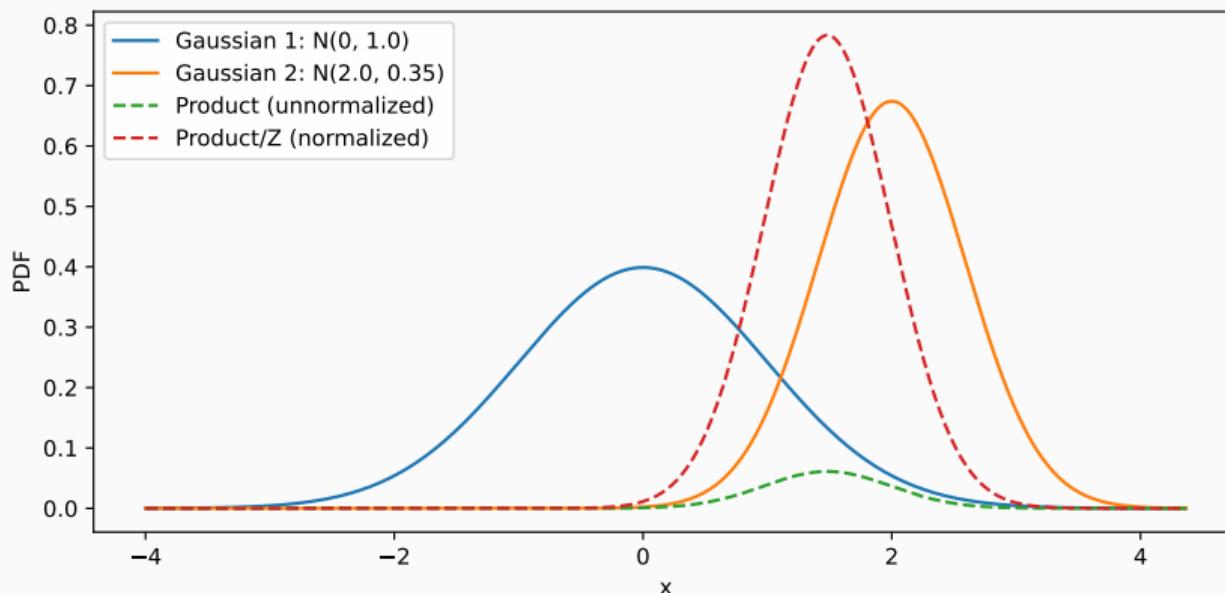


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- Note: Product of Gaussian PDFs \neq Product of Gaussian RVs !

ASSIGNMENT 1 HANDOUT
