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condition

if condition is true, do this

if condition is false, do that

Note the indentation!

A **condition** is something that is either **True** or **False**.



```
if True:
    print "CS101 is my favorite course"
```




```
if True:
```

```
    print "CS101 is my favorite course"
```

```
if False:
```

```
    print "Every CS101 student will receive an A+"
```



```
if True:
```

```
    print "CS101 is my favorite course"
```

```
if False:
```

```
    print "Every CS101 student will receive an A+"
```

```
if 3 < 5:
```

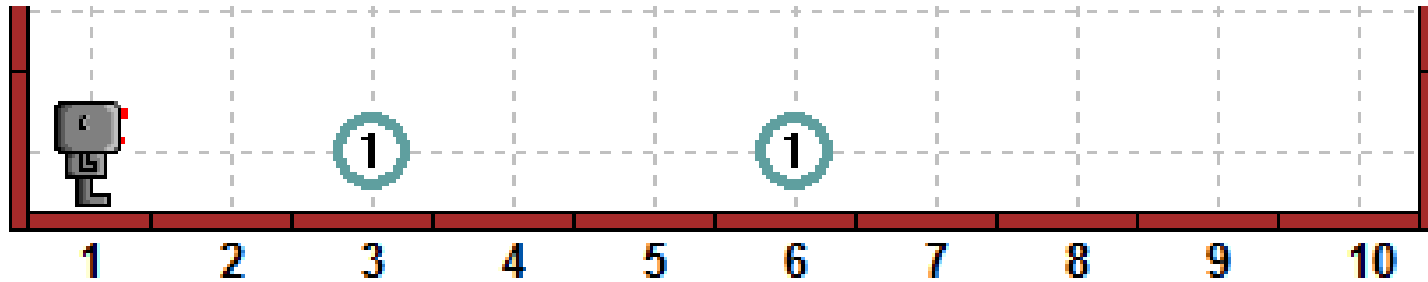
```
    print "3 is less than 5"
```

```
else:
```

```
    print "3 is larger than 5"
```

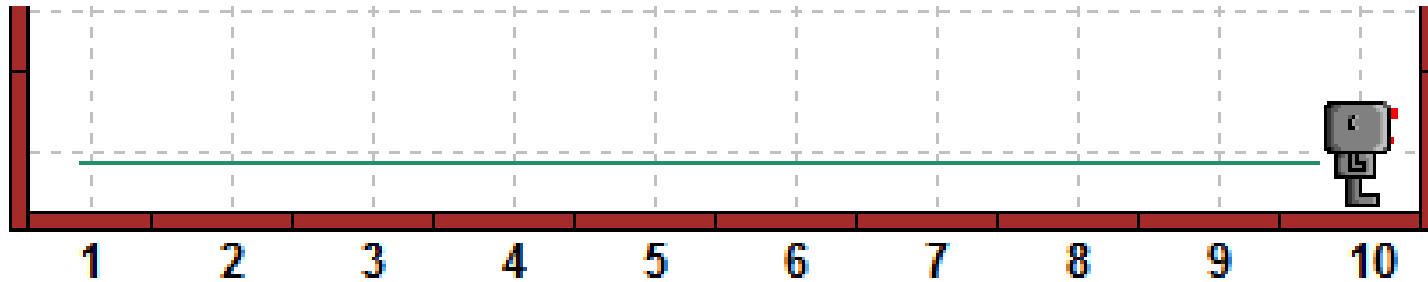


We want the robot to make 9 steps and pick up all beepers on the way.



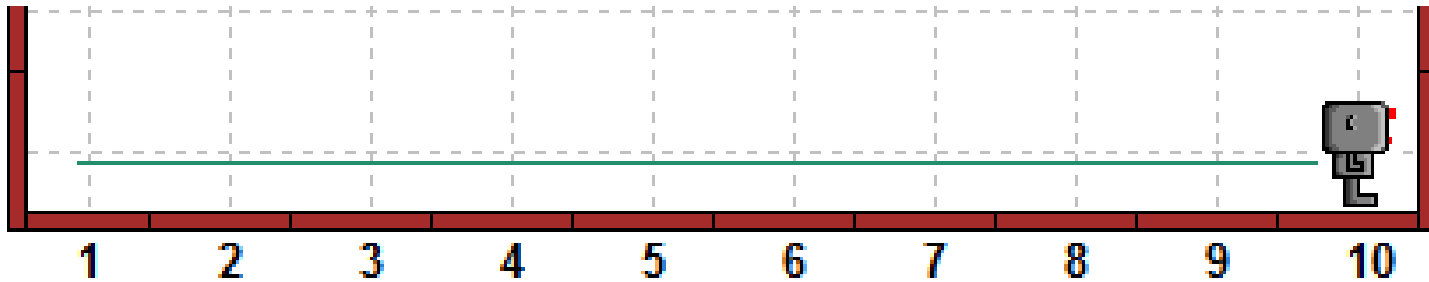


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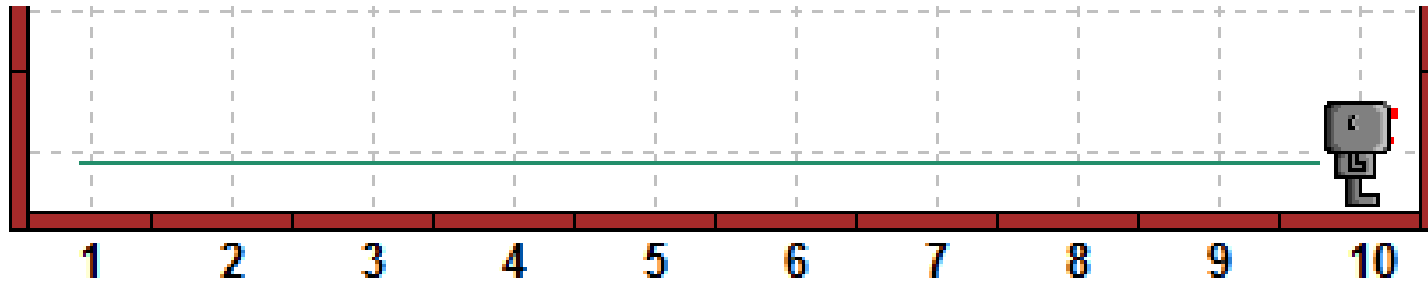
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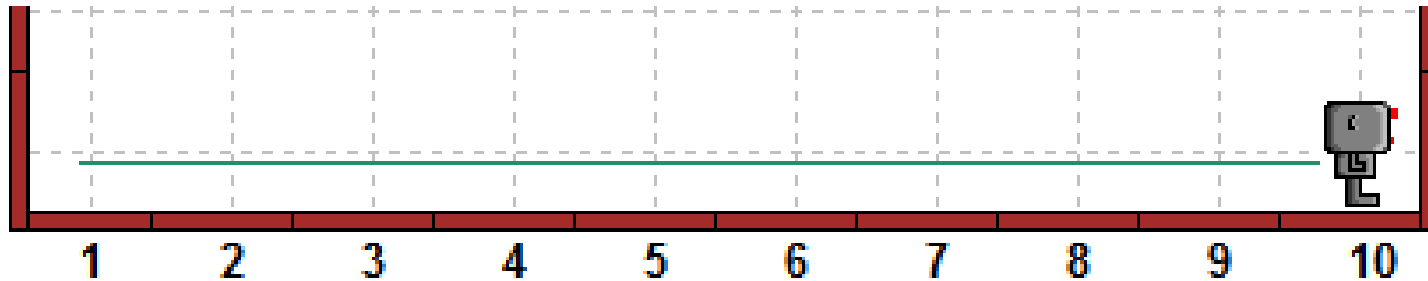
`hubo.pick_beeper()` causes an error if there is no beeper.

Repeat the following 9 times:

- Take a step forward.
- Check if there is a beeper.
- If yes, pick it up.



We want the robot to make 9 steps and pick up all beepers on the way.



`hubo.pick_beeper()` causes an error if there is no beeper.

Repeat the following 9 times:

- Take a step forward.
- Check if there is a beeper.
- If yes, pick it up.

```
def move_and_pick():  
    hubo.move()  
    if hubo.on_beeper():  
        hubo.pick_beeper()
```

```
for i in range(9):  
    move_and_pick()
```



Let's do the opposite: we want to drop a beeper, but only if there is **no** beeper at the current location.



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```
if not hubo.on_beeper():  
    hubo.drop_beeper()
```



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The keyword **not** inverts the sense of the condition: **not** true is false, and **not** false is true.



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if not hubo.on_beeper():  
    hubo.drop_beeper()
```

The keyword **not** inverts the sense of the condition: **not** true is false, and **not** false is true.

What is the output?

```
print not 3 < 5
```



Let's try to follow the boundary of the world: We move forward if there is no wall, otherwise turn to the left.



Let's try to follow the boundary of the world: We move forward if there is no wall, otherwise turn to the left.

```
def move_or_turn():  
    if hubo.front_is_clear():  
        hubo.move()  
    else:  
        hubo.turn_left()  
  
for i in range(20):  
    move_or_turn()
```



```
def dance():
    for i in range(4):
        hubo.turn_left()

def move_or_turn():
    if hubo.front_is_clear():
        dance()
        hubo.move()
    else:
        hubo.turn_left()
        hubo.drop_beeper()

for i in range(18):
    move_or_turn()
```



```
def dance():
    for i in range(4):
        hubo.turn_left()

def move_or_turn():
    if hubo.front_is_clear():
        dance()
        hubo.move()
    else:
        hubo.turn_left()
        hubo.drop_beeper()

for i in range(18):
    move_or_turn()
```

Note the indentation!



```
def dance():  
    for i in range(4):  
        hubo.turn_left()  
  
def move_or_turn():  
    if hubo.front_is_clear():  
        dance()  
        hubo.move()  
    else:  
        hubo.turn_left()  
        hubo.drop_beeper()  
  
for i in range(18):  
    move_or_turn()
```

What happens now?



```
def dance():
    for i in range(4):
        hubo.turn_left()

def move_or_turn():
    if hubo.front_is_clear():
        dance()
        hubo.move()
    else:
        hubo.turn_left()
hubo.drop_beeper()

for i in range(18):
    move_or_turn()
```

...and now?



```
if hubo.on_beeper():
    hubo.pick_beeper()
else:
    if hubo.front_is_clear():
        hubo.move()
    else:
        if hubo.left_is_clear():
            hubo.turn_left()
        else:
            if hubo.right_is_clear():
                turn_right()
            else:
                turn_around()
```



```
if hubo.on_beeper():
    hubo.pick_beeper()
else:
    if hubo.front_is_clear():
        hubo.move()
    else:
        if hubo.left_is_clear():
            hubo.turn_left()
        else:
            if hubo.right_is_clear():
                turn_right()
            else:
                turn_around()
```

This is not very readable!



```
if hubo.on_beeper():
    hubo.pick_beeper()
elif hubo.front_is_clear():
    hubo.move()
elif hubo.left_is_clear():
    hubo.turn_left()
elif hubo.right_is_clear():
    turn_right()
else:
    turn_around()
```



```
if hubo.on_beeper():
    hubo.pick_beeper()
elif hubo.front_is_clear():
    hubo.move()
elif hubo.left_is_clear():
    hubo.turn_left()
elif hubo.right_is_clear():
    turn_right()
else:
    turn_around()
```

`elif` combines `else` and `if` to express many alternatives without complicated indentation.



A **for**-loop repeats some instructions a fixed number of times.



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A **while**-loop repeats instructions as long as some condition is true.



A **for**-loop repeats some instructions a fixed number of times.

A **while**-loop repeats instructions as long as some condition is true.

Go forward until we reach a beeper:

```
while not hubo.on_beeper():  
    hubo.move()
```




Around the world in 80 days

Let's write a program to let the robot walk around the boundary of the world until he comes back to the starting point.



Let's write a program to let the robot walk around the boundary of the world until he comes back to the starting point.

Solution outline:

1. Put down a beeper to mark starting point
2. Move forward until facing wall
3. Turn left
4. Repeat steps 2 and 3 until we find the beeper
5. Finish when we found the beeper



Let's write a program to let the robot walk around the boundary of the world until he comes back to the starting point.

Solution outline:

1. Put down a beeper to mark starting point
2. Move forward until facing wall
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4. Repeat steps 2 and 3 until we find the beeper
5. Finish when we found the beeper

```
hubo.drop_beeper()  
while not hubo.on_beeper():  
    if hubo.front_is_clear():  
        hubo.move()  
    else:  
        hubo.turn_left()
```



Let's write a program to let the robot walk around the boundary of the world until he comes back to the starting point.

Solution outline:

1. Put down a beeper to mark starting point
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5. Finish when we found the beeper

```
hubo.drop_beeper()  
while not hubo.on_beeper():  
    if hubo.front_is_clear():  
        hubo.move()  
    else:  
        hubo.turn_left()
```

Doesn't work!



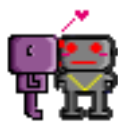
Let's write a program to let the robot walk around the boundary of the world until he comes back to the starting point.

Solution outline:

1. Put down a beeper to mark starting point
2. Move forward until facing wall
3. Turn left
4. Repeat steps 2 and 3 until we find the beeper
5. Finish when we found the beeper

```
hubo.drop_beeper()  
while not hubo.on_beeper():  
    if hubo.front_is_clear():  
        hubo.move()  
    else:  
        hubo.turn_left()
```

A red arrow points from the text `hubo.move()` to the `hubo.move()` line inside the `while` loop.



```
hubo.drop_beeper()
hubo.move()
while not hubo.on_beeper():
    if hubo.right_is_clear():
        turn_right()
    elif hubo.front_is_clear():
        hubo.move()
    else:
        hubo.turn_left()
```



```
hubo.drop_beeper()
hubo.move()
while not hubo.on_beeper():
    if hubo.right_is_clear():
        turn_right()
    elif hubo.front_is_clear():
        hubo.move()
    else:
        hubo.turn_left()
```

This can go into an infinite loop!



```
hubo.drop_beeper()
hubo.move()
while not hubo.on_beeper():
    if hubo.right_is_clear():
        turn_right()
    elif hubo.front_is_clear():
        hubo.move()
    else:
        hubo.turn_left()
```

A red arrow points from the text `hubo.move()` to the `turn_right()` line in the code block.

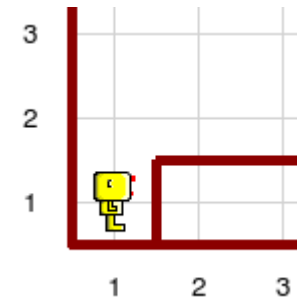
This can go into an infinite loop!



Sometimes we need right turns

```
hubo.drop_beeper()
hubo.move()
while not hubo.on_beeper():
    if hubo.right_is_clear():
        turn_right()
    elif hubo.front_is_clear():
        hubo.move()
    else:
        hubo.turn_left()
```

hubo.move()



This can go into an **infinite loop**!

Still does not work when there is a wall in front of the starting position!

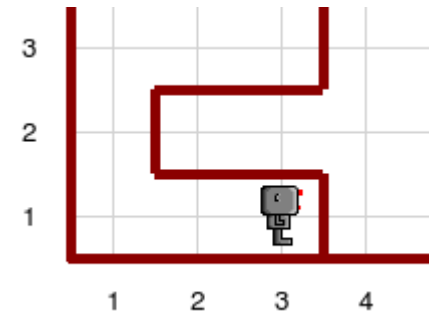


```
hubo.drop_beeper()
if not hubo.front_is_clear():
    hubo.turn_left()
hubo.move()
while not hubo.on_beeper():
    if hubo.right_is_clear():
        turn_right()
        hubo.move()
    elif hubo.front_is_clear():
        hubo.move()
    else:
        hubo.turn_left()
```



Getting out of the starting position

```
hubo.drop_beeper()
if not hubo.front_is_clear():
    hubo.turn_left()
hubo.move()
while not hubo.on_beeper():
    if hubo.right_is_clear():
        turn_right()
        hubo.move()
    elif hubo.front_is_clear():
        hubo.move()
    else:
        hubo.turn_left()
```

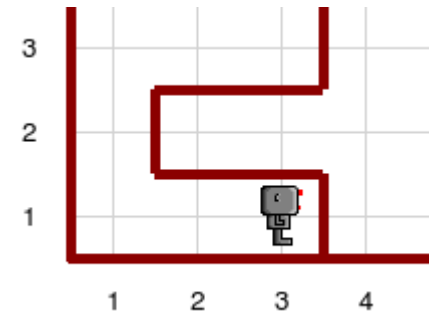


Still has a problem if not starting at position (1,1).



Getting out of the starting position

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hubo.drop_beeper()
while not hubo.front_is_clear():
    hubo.turn_left()
hubo.move()
while not hubo.on_beeper():
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        turn_right()
        hubo.move()
    elif hubo.front_is_clear():
        hubo.move()
    else:
        hubo.turn_left()
```



Still has a problem if not starting at position (1,1).



One of the secrets of writing good, correct, elegant programs is to write them as if you wrote them for a **human** reader, not a computer. Let's clean up our program:

```
# This program lets the robot go around his world counter-
# clockwise, stopping when he returns to the starting point.
from cs1robots import *
load_world()
hubo = Robot(b beepers = 1)

def turn_right():
    for i in range(3):
        hubo.turn_left()

def mark_starting_point_and_move():
    hubo.drop_beeper()
    while not hubo.front_is_clear():
        hubo.turn_left()
    hubo.move()
```



```
def follow_right_wall():
    if hubo.right_is_clear():
        # Keep to the right
        turn_right()
        hubo.move()
    elif hubo.front_is_clear():
        # move following the right wall
        hubo.move()
    else:
        # follow the wall
        hubo.turn_left()

# end of definitions, begin solution

mark_starting_point_and_move()

while not hubo.on_beeper():
    follow_right_wall()
```



Steps to follow when writing a program:

- start simple;
- introduce small changes, one at a time;
- **make sure** that each change does not invalidate the work you have done before;
- add appropriate comments (not just repeating what the instruction does);
- choose descriptive names.