

Introduction to Programming CS101

Fall 2011

Lecture #2



Cheating is strongly forbidden.

Cheating on homework or exams will give an F.







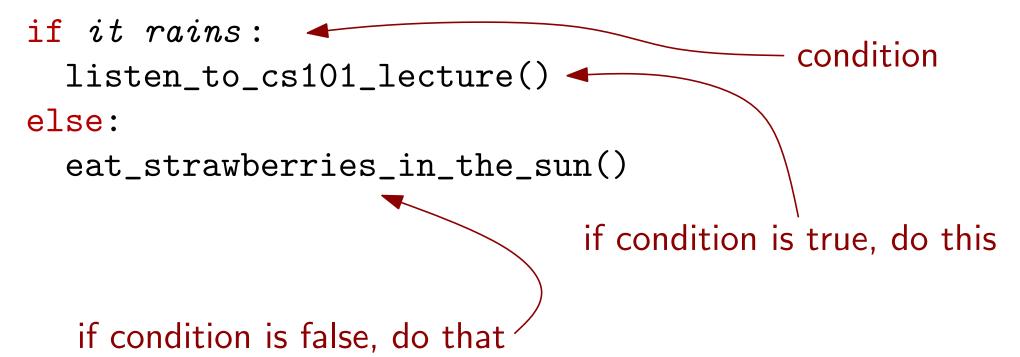
```
if it rains:
   listen_to_cs101_lecture()
else:
   eat_strawberries_in_the_sun()
```



```
if it rains:
    listen_to_cs101_lecture()
else:
    eat_strawberries_in_the_sun()
```









Note the indentation!

So far, our programs performed exactly the same steps every time the program is run.

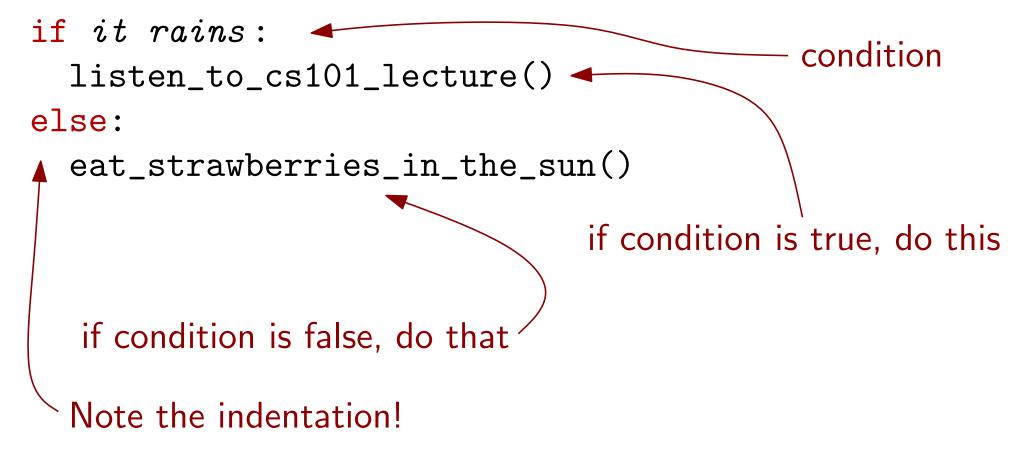
Often, what the robot does must depend on the environment:

if it rains:
 listen_to_cs101_lecture()
else:
 eat_strawberries_in_the_sun()
 if condition is true, do this

if condition is false, do that



Often, what the robot does must depend on the environment:



A condition is something that is either True or False.



if True:

print "CS101 is my favorite course"



if True:

print "CS101 is my favorite course"

if False:

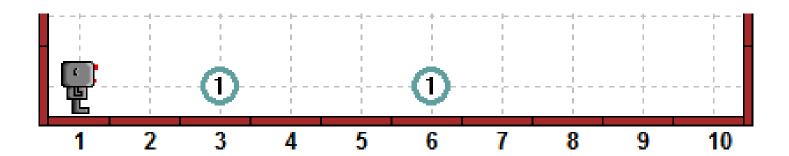
print "Every CS101 student will receive an A+"



```
if True:
 print "CS101 is my favorite course"
if False:
 print "Every CS101 student will receive an A+"
if 3 < 5:
 print "3 is less than 5"
else:
 print "3 is larger than 5"
```

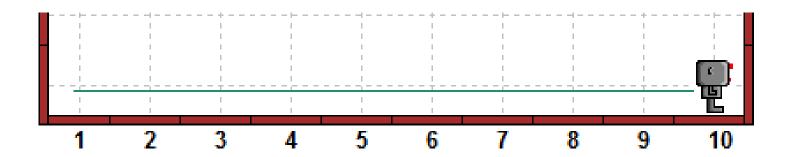




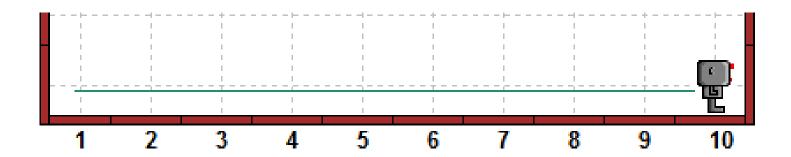






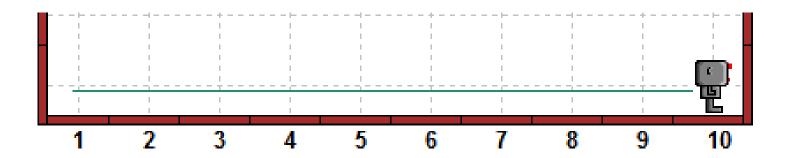






hubo.pick_beeper() causes an error if there is no beeper.



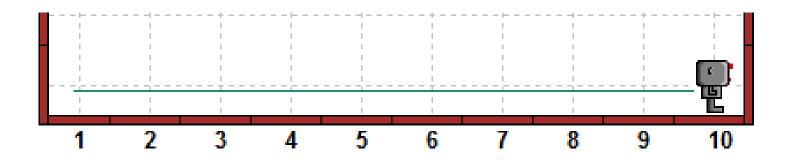


hubo.pick_beeper() causes an error if there is no beeper.

Repeat the following 9 times:

- Take a step forward.
- Check if there is a beeper.
- If yes, pick it up.





hubo.pick_beeper() causes an error if there is no beeper.

Repeat the following 9 times:

- Take a step forward.
- Check if there is a beeper.
- If yes, pick it up.

```
def move_and_pick():
   hubo.move()
   if hubo.on_beeper():
     hubo.pick_beeper()
```

```
for i in range(9):
   move_and_pick()
```





Let's do the opposite: we want to drop a beeper, but only if there is no beeper at the current location.





Let's do the opposite: we want to drop a beeper, but only if there is no beeper at the current location.

```
if not hubo.on_beeper():
   hubo.drop_beeper()
```





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if not hubo.on_beeper():
   hubo.drop_beeper()
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The keyword **not** inverts the sense of the condition: **not** true is false, and **not** false is true.





Let's do the opposite: we want to drop a beeper, but only if there is no beeper at the current location.

```
if not hubo.on_beeper():
   hubo.drop_beeper()
```

The keyword **not** inverts the sense of the condition: **not** true is false, and **not** false is true.

What is the output? print not 3 < 5



Let's try to follow the boundary of the world: We move forward if there is no wall, otherwise turn to the left.



Let's try to follow the boundary of the world: We move forward if there is no wall, otherwise turn to the left.

```
def move_or_turn():
    if hubo.front_is_clear():
       hubo.move()
    else:
       hubo.turn_left()

for i in range(20):
    move_or_turn()
```



```
def dance():
  for i in range(4):
    hubo.turn_left()
def move_or_turn():
  if hubo.front_is_clear():
    dance()
    hubo.move()
  else:
    hubo.turn_left()
    hubo.drop_beeper()
for i in range(18):
  move_or_turn()
```



```
def dance():
  for i in range(4):
    hubo.turn_left()
def move_or_turn():
  if hubo.front_is_clear():
    dance()
                                  Note the indentation!
    hubo.move()
  else:
    hubo.turn_left()
    hubo.drop_beeper()
for i in range(18):
  move_or_turn()
```



```
def dance():
  for i in range(4):
    hubo.turn_left()
def move_or_turn():
  if hubo.front_is_clear():
    dance()
    hubo.move()
  else:
    hubo.turn_left()
                               What happens now?
  hubo.drop_beeper()
for i in range(18):
  move_or_turn()
```



```
def dance():
  for i in range(4):
    hubo.turn_left()
def move_or_turn():
  if hubo.front_is_clear():
    dance()
    hubo.move()
  else:
    hubo.turn_left()
                                  ...and now?
hubo.drop_beeper()
for i in range(18):
  move_or_turn()
```



```
if hubo.on_beeper():
  hubo.pick_beeper()
else:
  if hubo.front_is_clear():
    hubo.move()
  else:
    if hubo.left_is_clear():
      hubo.turn_left()
    else:
      if hubo.right_is_clear():
        turn_right()
      else:
        turn_around()
```



```
if hubo.on_beeper():
  hubo.pick_beeper()
else:
  if hubo.front_is_clear():
    hubo.move()
                                This is not very readable!
  else:
    if hubo.left_is_clear():
      hubo.turn_left()
    else:
      if hubo.right_is_clear():
        turn_right()
      else:
        turn_around()
```



```
if hubo.on_beeper():
  hubo.pick_beeper()
elif hubo.front_is_clear():
  hubo.move()
elif hubo.left_is_clear():
  hubo.turn_left()
elif hubo.right_is_clear():
  turn_right()
else:
  turn_around()
```



```
if hubo.on_beeper():
  hubo.pick_beeper()
elif hubo.front_is_clear():
  hubo.move()
elif hubo.left_is_clear():
  hubo.turn_left()
elif hubo.right_is_clear():
  turn_right()
else:
  turn_around()
```

elif combines else and if to express many alternatives without complicated indentation.



A for-loop repeats some instructions a fixed number of times.



A for-loop repeats some instructions a fixed number of times.

A while-loop repeats instructions as long as some condition is true.



A for-loop repeats some instructions a fixed number of times.

A while-loop repeats instructions as long as some condition is true.

Go forward until we reach a beeper:
while not hubo.on_beeper():
 hubo.move()



Around the world in 80 days

Let's write a program to let the robot walk around the boundary of the world until he comes back to the starting point.



Around the world in 80 days

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Solution outline:

- 1. Put down a beeper to mark starting point
- 2. Move forward until facing wall
- 3. Turn left
- 4. Repeat steps 2 and 3 until we find the beeper
- 5. Finish when we found the beeper



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- 4. Repeat steps 2 and 3 until we find the beeper
- 5. Finish when we found the beeper

```
hubo.drop_beeper()
while not hubo.on_beeper():
   if hubo.front_is_clear():
     hubo.move()
   else:
   hubo.turn_left()
```



Around the world in 80 days

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- 3. Turn left
- 4. Repeat steps 2 and 3 until we find the beeper
- 5. Finish when we found the beeper

```
hubo.drop_beeper()
while not hubo.on_beeper():
                                    Doesn't work!
  if hubo.front_is_clear():
    hubo.move()
  else:
    hubo.turn_left()
```



Around the world in 80 days

Let's write a program to let the robot walk around the boundary of the world until he comes back to the starting point.

Solution outline:

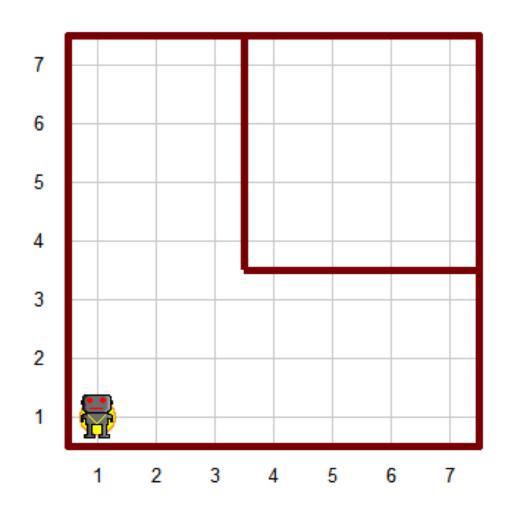
- 1. Put down a beeper to mark starting point
- 2. Move forward until facing wall
- 3. Turn left
- 4. Repeat steps 2 and 3 until we find the beeper
- 5. Finish when we found the beeper

```
hubo.drop_beeper()
                                   hubo.move()
while not hubo.on_beeper():
  if hubo.front_is_clear():
    hubo.move()
  else:
    hubo.turn_left()
```





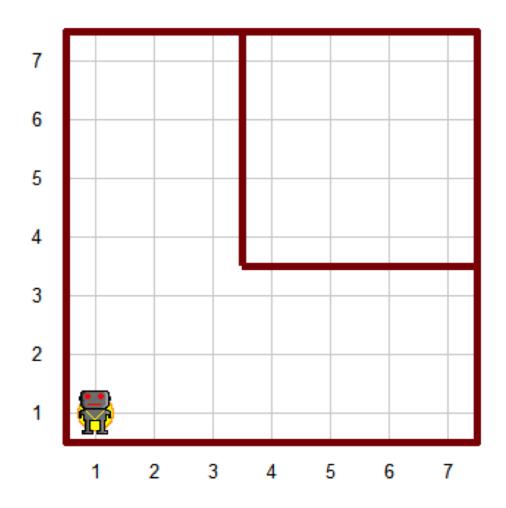
KAIST CS101 What if the world looks like below?







What if the world looks like below?



Try the code in the previous page with "amazing2.wld" and see if the previous code works.



```
hubo.drop_beeper()
hubo.move()
while not hubo.on_beeper():
    if hubo.right_is_clear():
        turn_right()
    elif hubo.front_is_clear():
        hubo.move()
    else:
        hubo.turn_left()
```



```
hubo.drop_beeper()
hubo.move()
while not hubo.on_beeper():
  if hubo.right_is_clear():
    turn_right()
  elif hubo.front_is_clear():
    hubo.move()
  else:
    hubo.turn_left()
```

This can go into an infinite loop!



```
hubo.drop_beeper()
hubo.move()
while not hubo.on_beeper():
  if hubo.right_is_clear():
    turn_right()
                                   hubo.move()
  elif hubo.front_is_clear():
    hubo.move()
  else:
    hubo.turn_left()
```

This can go into an infinite loop!



```
hubo.drop_beeper()
hubo.move()
while not hubo.on_beeper():
  if hubo.right_is_clear():
    turn_right()
                                    hubo.move()
  elif hubo.front_is_clear():
    hubo.move()
  else:
    hubo.turn_left()
This can go into an infinite loop!
```

Still does not work when there is a wall in front of the starting position!



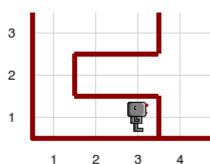
Getting out of the starting position

```
hubo.drop_beeper()
if not hubo.front_is_clear():
  hubo.turn_left()
hubo.move()
while not hubo.on_beeper():
  if hubo.right_is_clear():
    turn_right()
    hubo.move()
  elif hubo.front_is_clear():
    hubo.move()
  else:
    hubo.turn_left()
```



Getting out of the starting position

```
hubo.drop_beeper()
if not hubo.front_is_clear():
  hubo.turn_left()
hubo.move()
while not hubo.on_beeper():
  if hubo.right_is_clear():
    turn_right()
    hubo.move()
  elif hubo.front_is_clear():
    hubo.move()
  else:
    hubo.turn_left()
```



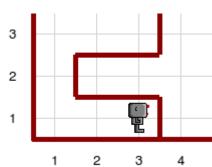
Still has a problem if not starting at position (1,1).





Getting out of the starting position

```
hubo.drop_beeper()
while not hubo.front_is_clear():
  hubo.turn_left()
hubo.move()
while not hubo.on_beeper():
  if hubo.right_is_clear():
    turn_right()
    hubo.move()
  elif hubo.front_is_clear():
    hubo.move()
  else:
    hubo.turn_left()
```



Still has a problem if not starting at position (1,1).



Write code for humans

One of the secrets of writing good, correct, elegant programs is to write them as if you wrote them for a human reader, not a computer. Let's clean up our program:

```
# This program lets the robot go around his world counter-
# clockwise, stopping when he returns to the starting point.
from cs1robots import *
load_world()
hubo = Robot(beepers = 1)
def turn_right():
  for i in range(3):
    hubo.turn_left()
def mark_starting_point_and_move():
  hubo.drop_beeper()
  while not hubo.front_is_clear():
    hubo.turn_left()
hubo.move()
```

KAIST CS101

```
def follow_right_wall():
  if hubo.right_is_clear():
    # Keep to the right
    turn_right()
    hubo.move()
  elif hubo.front_is_clear():
    # move following the right wall
    hubo.move()
  else:
    # follow the wall
    hubo.turn_left()
# end of definitions, begin solution
mark_starting_point_and_move()
while not hubo.on_beeper():
  follow_right_wall()
```





Steps to follow when writing a program:

- start simple;
- introduce small changes, one at a time;
- make sure that each change does not invalidate the work you have done before;
- add appropriate comments (not just repeating what the instruction does);
- choose descriptive names.