

# Curtin University – Department of Computing

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Last name:	Beardsmore	Student ID:	15504319
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Unit name:	Artificial and Machine Intelligence	Unit ID:	COMP3006
Lecturer / unit coordinator:	Mihai Lazarescu	Tutor:	Stefan
Date of submission:	01/05/2017	Which assignment?	(Leave blank if the unit has only one assignment.)

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# **AMI300 Report**

Informed Beam and SMA\* Search Implementations

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# Informed Beam Search

## Design Decisions

The informed beam search is a non-complete and non-optimal search technique based on an admissible heuristic measure. The cost of each node is determined as  $f(n) = h(n)$ , thus the decision of which nodes to expand is based solely on heuristic cost. The algorithm tracks up to  $k$  beams or paths at each step. Each further step expands all children nodes from these beams and expands the best  $k$  choices. Informed beam searches sacrifices optimality and completeness for increased memory efficiency and speed (Winston 1993).

The algorithm implemented utilizes a priority queue for both the *beam* and the *frontier* data structures, sorted via heuristic cost. The *beam* represents the current nodes in the  $k$  beams while the *frontier* stores all children of every node in the beams. At each level the frontier is trimmed to  $k$  length to allow the best  $k$  choices to be chosen. After this stage, the beam is replaced by the frontier and the process repeats until a solution is found, or no valid paths can be explored.

The algorithm allows for the discovery of alternate paths after an initial solution is discovered. Once the goal node is discovered in the frontier, the path is stored and the goal removed from the frontier to allow the beams to continue as if the goal was never discovered.

## Problems and Bugs

Several issues were faced during the implementation and testing of the algorithm. However, these issues were effectively resolved and the algorithm currently has no known issues or bugs resulting in errors.

The beams in the search technique do not communicate, they progress independently. Initially, the beams were communicating via comparing successors as they were added to the frontier. This fault was simply resolved by not adding duplicate nodes to the frontier at any stage. Two beams can effectively converge at the same node whilst having different paths to reach that node. Initially, nodes were not being duplicated and paths were being overwritten and lost. To solve this problem, nodes were duplicated to save their specific individual paths to allow for beams to converge upon the same nodes.

Before improvements were applied, the list of partial paths stored when a solution is discovered was not being correctly stored. Similarly to other issues, this was resolved by creating a deep copy of the beam before it was modified to allow for partial paths to be displayed if required.

## Simplified Memory Limited A\* Search

### Design Decisions

The simplified memory limited A\* search (SMA\*) is an extensible to pure memory bounded A\* search, designed by Stuart Russell (Russell 1992). It provides a more memory efficient form of the regular A\* search by placing a cap on the number of nodes in memory at anytime. Like A\* search, the evaluation function for a given node is defined as  $f(n) = g(n) + h(n)$ , thus being the sum of accumulated path cost and heuristic cost. It will produce the optimal solution given an admissible and consistent heuristic (Russell and Norvig 2016).

### Problems and Bugs

bookkeeping, what data structures used, issues with looping, duplicate nodes, continuing etc, how bad the regular pseudocode is ( removing parent from memory etc)

## References

- Russell, Stuart. 1992. “Efficient Memory-bounded Search Methods”. In *Proceedings of the 10th European Conference on Artificial Intelligence*. ECAI '92. Vienna, Austria: John Wiley & Sons, Inc.
- Russell, Stuart, and Peter Norvig. 2016. *Artificial Intelligence: A Modern Approach*. 3rd ed. Pearson.
- Winston, Patrick. 1993. *Artificial Intelligence*. 3rd ed. Addison-Wesley.