

Carlos Bentes

I am an electronic engineer with experience in software development and neural networks. My objective is to work as a software developer in machine learning and data analysis.

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Technical Skills

- Experience with Deep Neural Networks, SVMs, Ensembling.
- Development of image processing and data analysis algorithms.
- Dataset management with NoSQL and Python.

Tools: Python (Numpy, Pandas, Scikit-learn, Theano, Keras, Matplotlib) R, C/C++, Java, IDL, HTML, JavaScript, MySQL, MongoDB, KML, Git, PHP, Bootstrap, Linux.

Experience

STACC
Data Scientist
Tartu, Estonia

Text mining, Natural Language Processing
Machine learning with Deep Neural Networks.

April 2016 - Present Environment: Python (Numpy, Pandas, Scikit-learn, Matplotlib), Elasticsearch, Conda.

German Aerospace Center (DLR) Improvement of ship detection algorithms in SAR images.

Research Assistant Target classification with Deep Neural Networks.

Bremen, Germany Data fusion and contextual analysis for maritime applications.

April 2013 - April 2016 Environment: Python (Numpy, Pandas, Scikit-learn, Theano, Keras, Matplotlib), MongoDB.

Touch TecnologiaDeveloped software for on-line booking, medical procedure auto-scheduling, and resource

Software Developer
Sao Jose dos Campos, Brazil

management of hospital/health-care centers.

2011 - 2012 Environment: Java, JavaScript, JQuery, HTML, Eclipse, MySQL.

Orbisat da Amazonia Implemented and optimized image processing algorithms in Synthetic Aperture Radar (SAR)

Software Developer images.

Sao Jose dos Campos, Brazil Developed web applications to support operational field campaigns.

2009 - 2010 Environment: C/C++, IDL, Java, JavaScript, JBoss Seam, Eclipse, MySQL, Linux.

Google IT residency with focus on project and analysis of algorithms, computer architecture, and C++

Intern programming.

Belo Horizonte, Brazil

Developed a web search engine prototype composed of three basic modules: Crawler, Indexer,

2008 - 2008 Search.

Environment: C/C++, Linux, Eclipse.

Orbisat da Amazonia

Developed and implemented Hardware Interfaces in VHDL to optimize Synthetic-Aperture

Intern Radar (SAR) image processing.

Developed Linux Device Driver for PCI hardware communication on FPGA.

Performed Software-Hardware integration, debugging and profiling analysis.

Environment: C/C++, VHDL, FPGA.

Education

• Master of Science in Electronics and Computer Engineering

Technological Institute of Aeronautics (ITA) - SP, Brazil 2009 - 2012

Thesis: "Dynamic Formation and UAV Swarm Navigation with Artificial Potential Fields".

Bachelor in Electronic Engineering

Technological Institute of Aeronautics (ITA) - SP, Brazil 01/2003 - 12/2007

Final project: "Development of a vector co-processor in VHDL".

Languages

• Native Language: Portuguese

• Other Languages:	Interaction	Reading	Listening	Writing	Usage
English	C1	C1	C1	C1	Every Day
German	A2	B1	B1	A2	Every Day
Estonian	A1	A1	A1	A1	Every Day

Awards and Certificates

- DAAD Scholarship Award Deutscher Akademischer Austausch Dienst (DAAD) 2013/2016
- SCJP Java SE 6 Programmer Oracle 2010

Publications



• www.cbentes.com/publications.html

Carlos Bentes, Anja Frost, Domenico Velotto, Bjorn Tings, "Ship-Iceberg Discrimination with Convolutional Neural Networks in High Resolution SAR Images", European Conference on Synthetic Aperture Radar (EUSAR), Hamburg, Germany, 2016 (accepted).

Carlos Bentes, Domenico Velotto, Susanne Lehner, "Target Classification in Oceanographic SAR Images with Deep Neural Networks: Architecture and Initial Results", International Geoscience and Remote Sensing Symposium (IGARSS), Milan, Italy, 2015.

Carlos Bentes, Bjorn Tings, Susanne Lehner, "Ship Detection on Wide ScanSAR TerraSAR-X Images", European Conference on Synthetic Aperture Radar (EUSAR), Berlin, Germany, 2014.

Carlos Bentes, Domenico Velotto, Susanne Lehner, "Analysis of ship size detectability over different TerraSAR-X modes", International Geoscience and Remote Sensing Symposium (IGARSS), Quebec City, Canada, 2014.

Carlos Bentes, Osamu Saotome, "Dynamic Swarm Formation with Potential Fields and A* Path Planning in 3D Environment", Robotics Symposium and Latin American Robotics Symposium (SBR-LARS), Fortaleza, Brazil, 2012.

Interests

In my free time I like to explore on-line courses on different subjects (at Coursera and Udacity), and to have fun with Kaggle competitions. I also dedicate my time to my family and hobbies: photography, music, dance, cook, swim.