

# LEO-II - A Cooperative Automatic Theorem Prover for Higher-Order Logic

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<sup>1</sup>Thanks to EPSRC grant EP/D070511/1 at Cambridge University



Motivation and Project Hypothesis



LEO-II's Architecture



Reasoning within and about Multimodal Logics



Conclusion

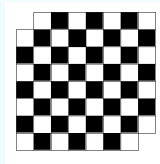
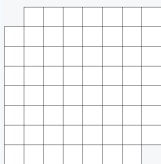
$$\frac{1}{L} \sum_{x=0}^{L-1} \sum_{y=0}^{L-1} s(x, y) \cos \left( \frac{\pi(2x+1)}{2L} \right) \cos \left( \frac{\pi(2y+1)}{2L} \right) = \frac{1}{L} \sum_{x=0}^{L-1} \sum_{y=0}^{L-1} s(x, y) \cos \left( \frac{\pi(2x+1)}{2L} \right) \cos \left( \frac{\pi(2y+1)}{2L} \right)$$



## Motivation and Project Hypothesis

# Representation (and the right System Architecture) Matters!

## A general lesson in AI ...

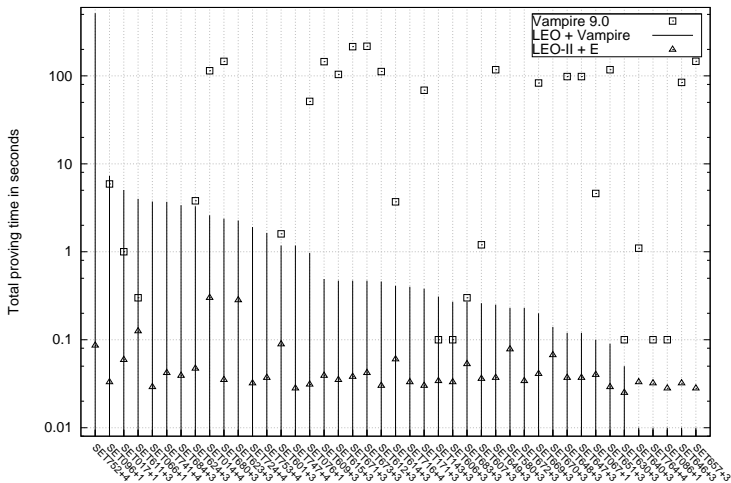


## ...and a specific research hypothesis here

FOL  
+  
FO-ATP

HOL  
+  
LEO-II + FO-ATP

# Reasoning about Sets, Relations, and Functions



$$\frac{1}{L} \sum_{x=0}^{L-1} \sum_{y=0}^{L-1} s(x, y) \cos \left( \frac{\pi(2x+1)}{2L} \right) \cos \left( \frac{\pi(2y+1)}{2L} \right) = \frac{1}{L} \sum_{x=0}^{L-1} \sum_{y=0}^{L-1} s(x, y) \cos \left( \frac{\pi(2x+1)}{2L} \right) \cos \left( \frac{\pi(2y+1)}{2L} \right)$$



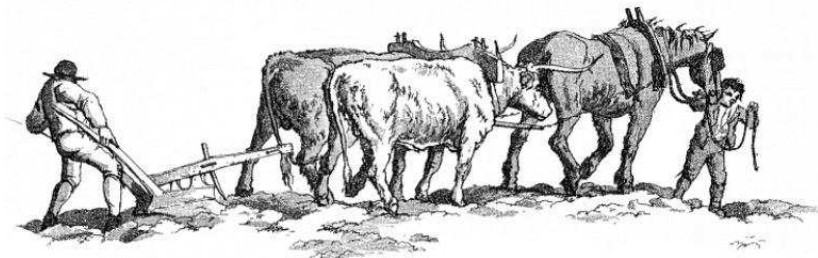
## LEO-II's Architecture

## LEO-II

An Effective Higher-Order Theorem Prover

UNIVERSITY OF  
CAMBRIDGE

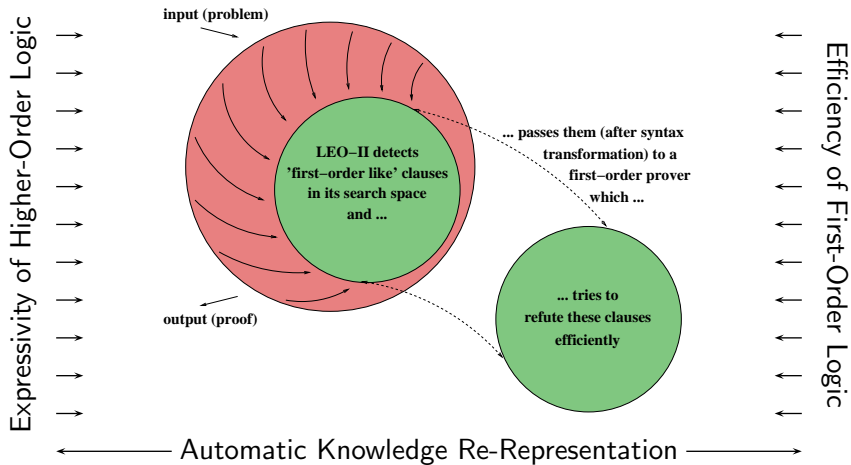
UNIVERSITÄT  
DES  
SAARLANDES



LEO-II employs FO-ATPs:

E, Spass, Vampire

# Architecture of LEO-II





# An Illustrating Example

$$\begin{aligned} & (p (\lambda X_{\iota \rightarrow \iota^*} ((q X) \Rightarrow (R X)))) \\ & \neg (p (\lambda Y_{\iota \rightarrow \iota^*} (\neg (q Y) \vee (r Y)))) \end{aligned}$$

# An Illustrating Example

$$(p (\lambda X_{\iota \rightarrow \iota}. ((q X) \Rightarrow (R X))))$$

$$\neg(p (\lambda Y_{\iota \rightarrow \iota}. (\neg(q Y) \vee (r Y))))$$

► resolution:

$$(p (\lambda X_{\iota \rightarrow \iota}. ((q X) \Rightarrow (R X)))) \neq (p (\lambda Y_{\iota \rightarrow \iota}. (\neg(q Y) \vee (r Y))))$$

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- resolution:

$$(p (\lambda X_{\iota \rightarrow \iota}. ((q X) \Rightarrow (R X)))) \neq (p (\lambda Y_{\iota \rightarrow \iota}. (\neg(q Y) \vee (r Y))))$$

- decomposition:

$$(\lambda X_{\iota \rightarrow \iota}. ((q X) \Rightarrow (R X))) \neq (\lambda Y_{\iota \rightarrow \iota}. (\neg(q Y) \vee (r Y)))$$

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- decomposition:

$$(\lambda X_{\iota \rightarrow \iota}. ((q X) \Rightarrow (R X))) \neq (\lambda Y_{\iota \rightarrow \iota}. (\neg (q Y) \vee (r Y)))$$

- functional and Boolean extensionality:

$$\neg \forall Z_{\iota \rightarrow \iota}. (((q Z) \Rightarrow (R Z)) \Leftrightarrow (\neg (q Z) \vee (r Z)))$$

# An Illustrating Example

$$(p (\lambda X_{\iota \rightarrow \iota} ((q X) \Rightarrow (R X))))$$

$$\neg(p (\lambda Y_{\iota \rightarrow \iota} (\neg(q Y) \vee (r Y))))$$

- clause normalisation

$$\neg(q s_{\iota \rightarrow \iota}) \vee (R s_{\iota \rightarrow \iota})$$

$$(q s_{\iota \rightarrow \iota}) \quad \neg(r s_{\iota \rightarrow \iota})$$

# An Illustrating Example

$$\begin{aligned} & (p (\lambda X_{\iota \rightarrow \iota} ((q X) \Rightarrow (R X)))) \\ & \neg(p (\lambda Y_{\iota \rightarrow \iota} (\neg(q Y) \vee (r Y)))) \end{aligned}$$

- clause normalisation

$$\neg(q s_{\iota \rightarrow \iota}) \vee (R s_{\iota \rightarrow \iota})$$

$$(q s_{\iota \rightarrow \iota}) \quad \neg(r s_{\iota \rightarrow \iota})$$

- mapping to first-order

$$\neg @_{((\iota \rightarrow \iota) \rightarrow o)_{-}(\iota \rightarrow \iota)}(q, s) \vee @_{((\iota \rightarrow \iota) \rightarrow o)_{-}(\iota \rightarrow \iota)}(R, s)$$

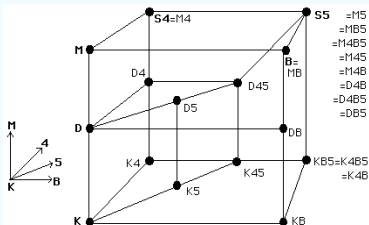
$$@_{((\iota \rightarrow \iota) \rightarrow o)_{-}(\iota \rightarrow \iota)}(q, s) \quad \neg @_{((\iota \rightarrow \iota) \rightarrow o)_{-}(\iota \rightarrow \iota)}(r, s)$$

$$\frac{1}{L-1} \sum_{x=0}^{L-1} \sum_{y=0}^{L-1} s(x, y) \cos \left( \frac{\pi(2x+1)}{2L} \right) \cos \left( \frac{\pi(2y+1)}{2L} \right) = \frac{1}{L-1} \sum_{x=0}^{L-1} \sum_{y=0}^{L-1} s(x, y) \cos \left( \frac{\pi(2x+1)}{2L} \right) \cos \left( \frac{\pi(2y+1)}{2L} \right)$$



## Reasoning within and about Multimodal Logics

## Modal Logics Challenge



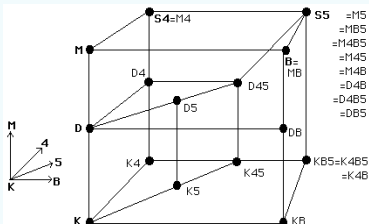
John Halleck (U Utah):

<http://www.cc.utah.edu/~nahaj/>

\$100 Modal Logic Challenge:

[www.tptp.org](http://www.tptp.org)





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### Example

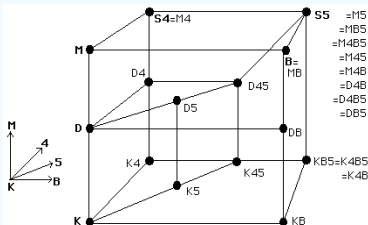
$$\begin{array}{lcl} S4 & = & K \\ & + & M : \quad \Box_R A \Rightarrow A \\ & + & 4 : \quad \Box_R A \Rightarrow \Box_R \Box_R A \end{array}$$

Theorems:

$$S4 \not\subseteq K \quad (1)$$

$$(M \wedge 4) \Leftrightarrow (refl.(R) \wedge trans.(R)) \quad (2)$$

## Modal Logics Challenge



John Halleck (U Utah):  
<http://www.cc.utah.edu/~nahaj/>  
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## Example

$$\begin{aligned}
 S4 &= K \\
 + \quad M &: \Box_R A \Rightarrow A \\
 + \quad 4 &: \Box_R A \Rightarrow \Box_R \Box_R A
 \end{aligned}$$

Theorems:

$$\begin{aligned}
 S4 &\not\subseteq K & (1) \\
 (M \wedge 4) &\Leftrightarrow (refl.(R) \wedge trans.(R)) & (2)
 \end{aligned}$$

## Experiments

	FO-ATPs [SutcliffeEtal-07]	LEO-II + E
(1)	16min + 2710s	17.3s
(2)	???	2.4s

# (Normal) Multimodal Logic in HOL

## – on one slide –

### Simple, Straightforward Encoding of Multimodal Logic

- ▶ base type  $\iota$ : set of possible worlds  
terms of type  $\iota \rightarrow o$ : multimodal logic formulas
- ▶ multimodal logic operators:

$$\begin{aligned}
 \neg (\iota \rightarrow o) \rightarrow (\iota \rightarrow o) &:= \lambda A_{\iota \rightarrow o}. (\lambda x_{\iota}. \neg A(x)) \\
 \forall (\iota \rightarrow o) \rightarrow (\iota \rightarrow o) \rightarrow (\iota \rightarrow o) &:= \lambda A_{\iota \rightarrow o}, B_{\iota \rightarrow o}. (\lambda x_{\iota}. A(x) \vee B(x)) \\
 \Box_R (\iota \rightarrow \iota \rightarrow o) \rightarrow (\iota \rightarrow o) \rightarrow (\iota \rightarrow o) &:= \lambda R_{\iota \rightarrow \iota \rightarrow o}, A_{\iota \rightarrow o}. \\
 &\quad (\lambda x_{\iota}. \forall y_{\iota}. R(x, y) \Rightarrow A(y))
 \end{aligned}$$

### Encoding of Validity

$$\text{valid} := \lambda A_{\iota \rightarrow o}. (\forall w_{\iota}. A(w))$$

# Even simpler: Reasoning within Multimodal Logics

Problem	LEO-II + E
$\text{valid}(\Box_r \top)$	0.025s
$\text{valid}(\Box_r a \Rightarrow \Box_r a)$	0.026s
$\text{valid}(\Box_r a \Rightarrow \Box_s a)$	—
$\text{valid}(\Box_s (\Box_r a \Rightarrow \Box_r a))$	0.026s
$\text{valid}(\Box_r (a \wedge b) \Leftrightarrow (\Box_r a \wedge \Box_r b))$	0.044s
$\text{valid}(\Diamond_r (a \Rightarrow b) \Rightarrow \Box_r a \Rightarrow \Diamond_r b)$	0.030s
$\text{valid}(\neg \Diamond_r a \Rightarrow \Box_r (a \Rightarrow b))$	0.029s
$\text{valid}(\Box_r b \Rightarrow \Box_r (a \Rightarrow b))$	0.026s
$\text{valid}((\Diamond_r a \Rightarrow \Box_r b) \Rightarrow \Box_r (a \Rightarrow b))$	0.027s
$\text{valid}((\Diamond_r a \Rightarrow \Box_r b) \Rightarrow (\Box_r a \Rightarrow \Box_r b))$	0.029s
$\text{valid}((\Diamond_r a \Rightarrow \Box_r b) \Rightarrow (\Diamond_r a \Rightarrow \Diamond_r b))$	0.030s

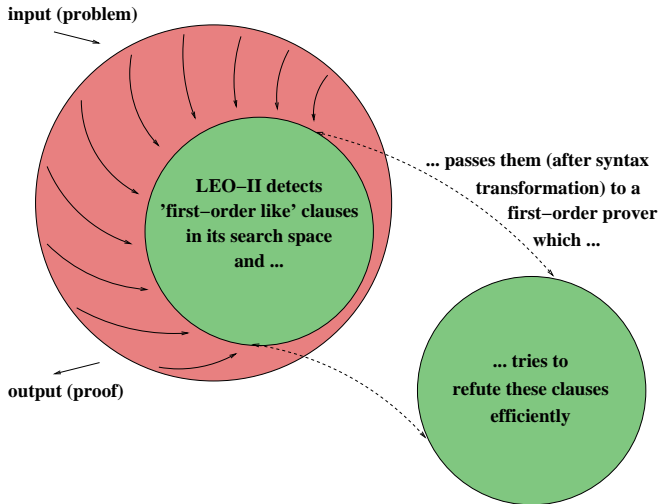
## Example (2)

In modal logic **K**, the axioms M and 4 are equivalent to reflexivity and transitivity of the accessibility relation  $R$

$$\begin{aligned} & \forall R. (\forall A. \text{valid}(\Box_R A \Rightarrow A) \wedge \text{valid}(\Box_R A \Rightarrow \Box_R \Box_R A)) \\ & \Leftrightarrow (\text{reflexive}(R) \wedge \text{transitive}(R)) \end{aligned}$$

- ▶ 70 clauses are passed to E
- ▶ E generates **21769** clauses before finding the empty clause
- ▶ total proving time 2.4sec (more than 2sec used by E)
- ▶ proof cannot be found in LEO-II alone

# Architecture of LEO-II



# More about Multimodal Logic in Higher-Order Logic

- ▶ C. Benzmüller, L. Paulson: **Exploring Properties of Normal Multimodal Logics in Simple Type Theory with LEO-II.** Festschrift in Honour of Peter B. Andrews 70th Birthday. To appear soon.
  - ▶ Interesting examples and limitations
  - ▶ + First-Order Multimodal Logic
  - ▶ + Higher-Order Multimodal Logic

## What makes LEO-II strong? The combination of

- ▶ expressive higher-order representations
- ▶ reduction to first-order representations
- ▶ cooperation with first-order ATPs
- ▶ higher-order termsharing and termindexing techniques

## Try LEO-II (running under Ocaml 3.10)

- ▶ Website: <http://www.ags.uni-sb.de/~leo>
  - ▶ download version, very easy to install
  - ▶ online demo
- ▶ Systems on TPTP:  
<http://www.cs.miami.edu/~tptp/cgi-bin/SystemOnTPTP>



# Latest Application of LEO-II: Dancefloor Animation



Grooving to an animation of LEO-II's dynamically growing termgraph (while LEO-II is proving Cantor's theorem)

## Example (1)

$S4 \not\subseteq K$ : Axioms M and 4 are not valid in modal logic **K**

$$\neg \forall R. \forall A. \forall B. (\text{valid}(\Box_R A \Rightarrow A)) \wedge (\text{valid}(\Box_R B \Rightarrow \Box_R \Box_R B))$$

- ▶ LEO-II shows that axiom M is not valid
- ▶ R is instantiated with  $\neq$  via primitive substitution
- ▶ total proving time 17.3s

# Architecture of LEO-II

