

Automating Access Control Logics and Multimodal Logics in The Higher-Order Theorem Prover LEO-II¹

Christoph E. Benzmüller

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1 Higher-Order Logic (HOL)

The Good Thing: Expressivity

The Bad Thing: Automation is a Challenge

2 The LEO-II Prover

Motivation and Architecture

Solving Lightweight Problems: Sets

Less Lightweight Problems: Multimodal Logics

More Example Problems: Access Control Logics

Ongoing and Future Work

$$\frac{1}{L} \sum_{x=0}^{L-1} \sum_{y=0}^{L-1} s(x, y) \cos \left(\frac{\pi(2x+1)}{2L} \right) \cos \left(\frac{\pi(2y+1)}{2L} \right) = \frac{1}{L} \sum_{x=0}^{L-1} \sum_{y=0}^{L-1} s(x, y) \cos \left(\frac{\pi(2x+1)}{2L} \right) \cos \left(\frac{\pi(2y+1)}{2L} \right)$$



Church's Simple Type Theory

Higher-Order Logic (HOL)

Some folks say that HOL is like this:



I don't!

- ▶ Semantics (extensionality) [PhD-99, JSL-04]
- ▶ Proof theory [IJCAR-06, LMCS-08]
- ▶ ATPs LEO and LEO-II [CADE-98, IJCAR-08]

Higher-Order Logic (HOL)

- on one slide -

Property

FOL

HOL

Example

Quantification over

- individuals

✓

✓

$\forall x. P(F(x))$

- functions

—

✓

$\forall F. P(F(x))$

- predicates/sets/relations

—

✓

$\forall P. P(F(x))$

Unnamed

- functions

—

✓

$(\lambda x. x)$

- predicates/sets/relations

—

✓

$(\lambda x. x \neq 2)$

Statements about

- functions

—

✓

continuous $(\lambda x. x)$

- predicates/sets/relations

—

✓

reflexive $(=)$

Sets and Relations in HOL

$$A \cup B := \{x \mid x \in A \vee x \in B\}$$

$$A \cup B := (\lambda x. x \in A \vee x \in B)$$

$$\cup := \lambda A. \lambda B. (\lambda x. x \in A \vee x \in B)$$

$$\text{symmetric} := \lambda F. (\forall x, y. F(x, y) = F(y, x))$$

$$\text{Theorem : } \text{symmetric}(\cup)$$

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$$\text{symmetric} := \lambda F. (\forall x, y. F(x, y) = F(y, x))$$

Theorem : `symmetric(∪)`

Sets and Relations in HOL

\in	$:=$	$\lambda x. \lambda A. A(x)$
\emptyset	$:=$	$\lambda x. \perp$
\cap	$:=$	$\lambda A. \lambda B. (\lambda x. x \in A \wedge x \in B)$
\cup	$:=$	$\lambda A. \lambda B. (\lambda x. x \in A \vee x \in B)$
\setminus	$:=$	$\lambda A. \lambda B. (\lambda x. x \in A \wedge x \notin B)$
\dots		
\subseteq	$:=$	$\lambda A. \lambda B. (\forall x. x \in A \Rightarrow x \in B)$
\mathcal{P}	$:=$	$\lambda A. (\lambda B. B \subseteq A)$
\dots		
reflexive	$:=$	$\lambda R. (\forall x. R(x, x))$
transitive	$:=$	$\lambda R. (\forall x, y, z. (R(x, y) \wedge R(y, z)) \Rightarrow R(x, z))$
\dots		

Typed Sets and Relations in HOL

$$\begin{aligned}
 \in & \quad := \quad \lambda x_{\alpha} \cdot \lambda A_{\alpha \rightarrow o} \cdot A(x) \\
 \emptyset & \quad := \quad \lambda x_{\alpha} \cdot \perp \\
 \cap & \quad := \quad \lambda A_{\alpha \rightarrow o} \cdot \lambda B_{\alpha \rightarrow o} \cdot (\lambda x_{\alpha} \cdot x \in A \wedge x \in B) \\
 \cup & \quad := \quad \lambda A_{\alpha \rightarrow o} \cdot \lambda B_{\alpha \rightarrow o} \cdot (\lambda x_{\alpha} \cdot x \in A \vee x \in B) \\
 \backslash & \quad := \quad \lambda A_{\alpha \rightarrow o} \cdot \lambda B_{\alpha \rightarrow o} \cdot (\lambda x_{\alpha} \cdot x \in A \wedge x \notin B) \\
 \dots
 \end{aligned}$$

Polymorphism is a Challenge for Automation

- ▶ Another source of indeterminism / blind guessing

[TPHOLs-WP-07]

$$\frac{1}{L} \sum_{x=0}^{L-1} \sum_{y=0}^{L-1} s(x, y) \cos \left(\frac{\pi(2x+1)}{2L} \right) \cos \left(\frac{\pi(2y+1)}{2L} \right) = \frac{1}{L} \sum_{x=0}^{L-1} \sum_{y=0}^{L-1} s(x, y) \cos \left(\frac{\pi(2x+1)}{2L} \right) \cos \left(\frac{\pi(2y+1)}{2L} \right)$$



Automation is a Challenge

Automation of HOL: A Nightmare?

Undecidable and Infinitary Unification

$$\exists F_{\iota \rightarrow \iota}. F(g(x)) = g(F(x))$$

$$(1) F \leftarrow \lambda y_i. y$$

$$(2) F \leftarrow \lambda y_i. g(y)$$

$$(3) F \leftarrow \lambda y_i. g(g(y))$$

$$(4) \dots$$



Automation of HOL: A Nightmare?

Primitive Substitution

Example Theorem: $\exists S. \text{reflexive}(S)$

Negation and Expansion of Definitions:

$$\neg \exists S. (\forall x. S(x, x))$$

Clause Normalisation ($a(S)$ Skolem term):

$$\neg S(a(S), a(S))$$

Guess some suitable instances for S

$$S \leftarrow \lambda y. \lambda z. V(y, z) \vee W(y, z)$$

$$S \leftarrow \lambda y. \lambda z. \top$$

$$S \leftarrow \lambda y. \lambda z. V(y, z) = W(y, z)$$

$$S \leftarrow \dots$$

–
✓
✓



Automation of HOL: A Nightmare?

Cut rule

$$\frac{A \Rightarrow C \quad C \Rightarrow B}{A \Rightarrow B}$$

considered as bad in ATP

Calculi that avoid axioms

- ▶ Axiom of excluded middle ✓
- ▶ Comprehension axioms ✓
- ▶ Functional and Boolean extensionality ✓ [CADE-98, PhD-99]
- ▶ Leibniz and other definitions of equality ✓ [CADE-99, PhD-99]
- ▶ Axiom of induction ?
- ▶ Axiom of choice —
- ▶ Axiom of description —

Automation of HOL: A Nightmare?

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[IJCAR-06]: Axioms that imply Cut Calculi that avoid axioms

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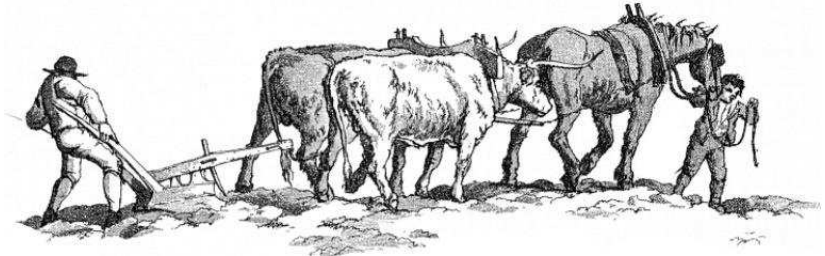
LEO-II – A Cooperative Automatic Higher-Order Theorem Prover

LEO-II

An Effective Higher-Order Theorem Prover

UNIVERSITY OF
CAMBRIDGE

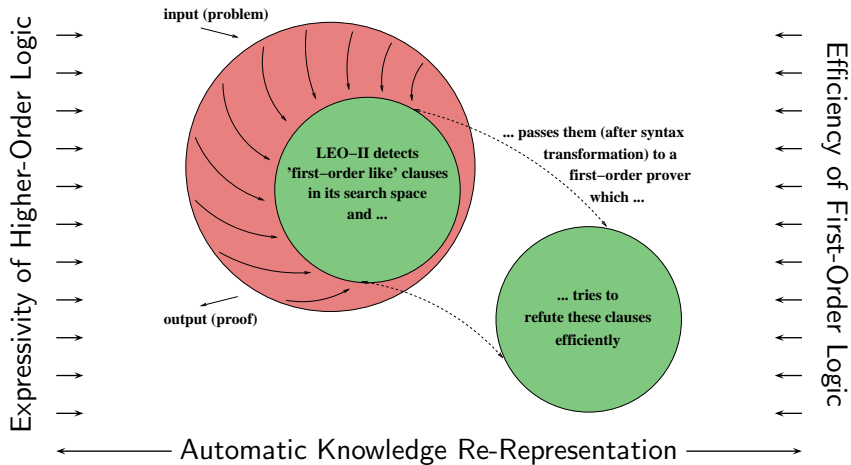
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DES
SAARLANDES



LEO-II employs FO-ATPs:

E, Spass, Vampire

Architecture of LEO-II



Solving Lightweight Problems



Example: TPTP Problem SET171+3

Axiomatization in FO Set Theory

Assumptions:

$$\forall B, C, x. (x \in (B \cup C) \Leftrightarrow x \in B \vee x \in C)$$

$$\forall B, C, x. (x \in (B \cap C) \Leftrightarrow x \in B \wedge x \in C)$$

$$\forall B, C. (B \subseteq C \Leftrightarrow \forall x. x \in B \Rightarrow x \in C)$$

$$\forall B, C. (B \cup C = C \cup B)$$

$$\forall B, C. (B \cap C = C \cap B)$$

$$\forall B, C. (B = C \Leftrightarrow B \subseteq C \wedge C \subseteq B)$$

$$\forall B, C. (B = C \Leftrightarrow \forall x. x \in B \Leftrightarrow x \in C)$$

Proof Goal:

$$\forall B, C, D.$$

$$B \cup (C \cap D) = (B \cup C) \cap (B \cup D)$$

Performance: FO-ATPs

```
% SPASS---3.0
% Problem : SET171+3
% SPASS beiseite: Ran out of time.

% E---0.999
% Problem : SET171+3
% Failure: Resource limit exceeded
(time)

% Vampire---9.0
% Problem : SET171+3
% Result : Theorem 68.6s
```

Performance: LEO-II + E

```
Eureka --- Thanks to Corina!
Total Reasoning Time: 0.03s
LEO-II (Proof Found!)
```

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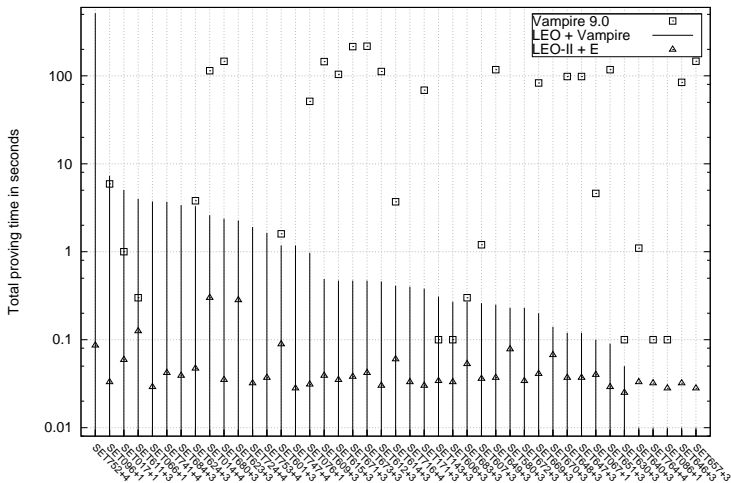
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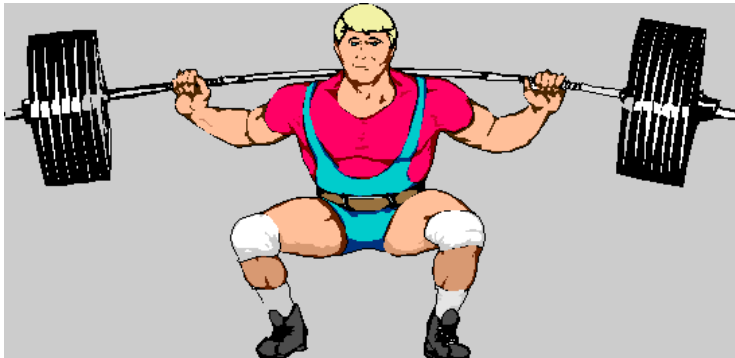


Results

Problem	Vamp. 9.0	LEO+Vamp.	LEO-II+E
014+4	114.5	2.60	0.300
017+1	1.0	5.05	0.059
066+1	–	3.73	0.029
067+1	4.6	0.10	0.040
076+1	51.3	0.97	0.031
086+1	0.1	0.01	0.028
096+1	5.9	7.29	0.033
143+3	0.1	0.31	0.034
171+3	68.6	0.38	0.030
580+3	0.0	0.23	0.078
601+3	1.6	1.18	0.089
606+3	0.1	0.27	0.033
607+3	1.2	0.26	0.036
609+3	145.2	0.49	0.039
611+3	0.3	4.00	0.125
612+3	111.9	0.46	0.030
614+3	3.7	0.41	0.060
615+3	103.9	0.47	0.035
623+3	–	2.27	0.282
624+3	3.8	3.29	0.047
630+3	0.1	0.05	0.025
640+3	1.1	0.01	0.033
646+3	84.4	0.01	0.032
647+3	98.2	0.12	0.037

Problem	Vamp. 9.0	LEO+Vamp.	LEO-II+E
648+3	98.2	0.12	0.037
649+3	117.5	0.25	0.037
651+3	117.5	0.09	0.029
657+3	146.6	0.01	0.028
669+3	83.1	0.20	0.041
670+3	–	0.14	0.067
671+3	214.9	0.47	0.038
672+3	–	0.23	0.034
673+3	217.1	0.47	0.042
680+3	146.3	2.38	0.035
683+3	0.3	0.27	0.053
684+3	–	3.39	0.039
716+4	–	0.40	0.033
724+4	–	1.91	0.032
741+4	–	3.70	0.042
747+4	–	1.18	0.028
752+4	–	516.00	0.086
753+4	–	1.64	0.037
764+4	0.1	0.01	0.032

Vamp. 9.0: 2.80GHz, 1GB memory, 600s time limit
LEO+Vamp.: 2.40GHz, 4GB memory, 120s time limit
LEO-II+E: 1.60GHz, 1GB memory, 60s time limit



Multimodal Logics

John Halleck (U Utah):
<http://www.cc.utah.edu/~nahaj/>
 \$100 Modal Logic Challenge:
www.tptp.org

	FO-ATPs [SutcliffeEtal-07]	LEO-II + E [BePa-08]
(1)	16min + 2710s	17.3s
(2)	???	2.4s

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Example

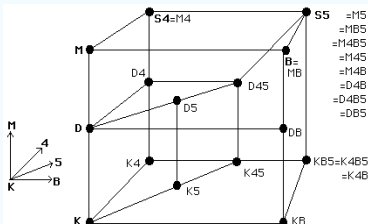
$$\begin{aligned} S4 &= K \\ &+ M(T): \quad \Box a \Rightarrow a \\ &+ 4: \quad \Box a \Rightarrow \Box \Box a \end{aligned}$$

Theorems:

$$S4 \not\subseteq K \quad (1)$$

$$(M \wedge 4) \Leftrightarrow (refl.(R) \wedge trans.(R)) \quad (2)$$

	FO-ATPs [SutcliffeEtal-07]	LEO-II + E [BePa-08]
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Example

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Experiments

	FO-ATPs [SutcliffeEtal-07]	LEO-II + E [BePa-08]
(1)	16min + 2710s	17.3s
(2)	???	2.4s

(Normal) Multimodal Logic in HOL

$$s, t ::= p \mid \neg s \mid s \vee t \mid \Box_r s$$

Simple, Straightforward Encoding

- ▶ base type ι : set of possible worlds
- ▶ (certain) terms of type $\iota \rightarrow o$: multimodal logic formulas

$$\begin{aligned} [p] &= p_{\iota \rightarrow o} \\ [r] &= r_{\iota \rightarrow \iota \rightarrow o} \\ [\neg s] &= \lambda w_{\iota}. \neg ([s] w) \\ [s \vee t] &= \lambda w_{\iota}. ([s] w) \vee ([t] w) \\ [\Box_r s] &= \lambda w_{\iota}. \forall y_{\iota}. ([r] w y) \Rightarrow ([s] y) \end{aligned}$$

(Normal) Multimodal Logic in HOL

$$s, t ::= p \mid \neg s \mid s \vee t \mid \Box_r s$$

Simple, Straightforward Encoding

- ▶ base type ι : set of possible worlds
- ▶ (certain) terms of type $\iota \rightarrow o$: multimodal logic formulas

$$\begin{aligned}
 |p| &= p_{\iota \rightarrow o} \\
 |r| &= r_{\iota \rightarrow \iota \rightarrow o} \\
 |\neg| &= \lambda s_{\iota \rightarrow o} . \lambda w_{\iota} . \neg(a \ w) \\
 |\vee| &= \lambda s_{\iota \rightarrow o} . \lambda t_{\iota \rightarrow o} . \lambda w_{\iota} . (s \ w) \vee (t \ w) \\
 |\Box| &= \lambda r_{\iota \rightarrow \iota \rightarrow o} . \lambda s_{\iota \rightarrow o} . \\
 &\quad \lambda w_{\iota} . \forall y_{\iota} . (r \ w \ y) \Rightarrow (s \ y)
 \end{aligned}$$

(Normal) Multimodal Logic in HOL

Encoding of Validity

$$\begin{aligned}\text{valid } s_{l \rightarrow o} &= (\forall w_{l \blacksquare} (s \ w)) \\ |\text{valid}| &= \lambda s_{l \rightarrow o} (\forall w_{l \blacksquare} (s \ w))\end{aligned}$$

Local Definition Expansion

$$\begin{aligned}|\text{valid } \Box_r \ T| &= |\text{valid}| |\Box| |r| |T| \\ &=^{\beta\eta} \forall w_{l \blacksquare} \forall y_{l \blacksquare} (r \ w \ y) \Rightarrow T\end{aligned}$$

(Normal) Multimodal Logic in HOL

Encoding of Validity

$$\begin{aligned}\text{valid } s_{\iota \rightarrow o} &= (\forall w_{\iota}. (s \ w)) \\ |\text{valid}| &= \lambda s_{\iota \rightarrow o}. (\forall w_{\iota}. (s \ w))\end{aligned}$$

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(Normal) Multimodal Logic in HOL

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Even simpler: Reasoning within Multimodal Logics

Problem	LEO-II + E
valid $\Box_r \top$	0.025s
valid $\Box_r a \Rightarrow \Box_r a$	0.026s
valid $\Box_r a \Rightarrow \Box_s a$	—
valid $\Box_s (\Box_r a \Rightarrow \Box_r a)$	0.026s
valid $\Box_r (a \wedge b) \Leftrightarrow (\Box_r a \wedge \Box_r b)$	0.044s
valid $\Diamond_r (a \Rightarrow b) \Rightarrow \Box_r a \Rightarrow \Diamond_r b$	0.030s
valid $\neg \Diamond_r a \Rightarrow \Box_r (a \Rightarrow b)$	0.029s
valid $\Box_r b \Rightarrow \Box_r (a \Rightarrow b)$	0.026s
valid $(\Diamond_r a \Rightarrow \Box_r b) \Rightarrow \Box_r (a \Rightarrow b)$	0.027s
valid $(\Diamond_r a \Rightarrow \Box_r b) \Rightarrow (\Box_r a \Rightarrow \Box_r b)$	0.029s
valid $(\Diamond_r a \Rightarrow \Box_r b) \Rightarrow (\Diamond_r a \Rightarrow \Diamond_r b)$	0.030s

Example Proof:

$$|\text{valid } \Box_s (\Box_r a \Rightarrow \Box_r a)|$$

Initialisation of problem

$$\neg |\text{valid } \Box_s (\Box_r a \Rightarrow \Box_r a)|$$

Definition expansion

$$\neg (\forall x_{\iota} \forall y_{\iota} \neg s(x, y) \vee ((\neg (\forall u_{\iota} \neg r(y, u) \vee a(u))) \vee (\forall v_{\iota} \neg r(y, v) \vee a(v)))$$

Normalisation (x, y, u are now Skolem constants, V is a free variable)

$$\begin{array}{ll} s(x, y) & \neg a(u) \\ r(y, u) & a(V) \vee \neg r(y, V) \end{array}$$

Translation to first-order logic [Kerber-94], [Hurd-02], [MengPaulson-04]

$$\begin{array}{ll} @_{(io) \perp} (@_{(i(io)) \perp} (s, x), y) & \neg @_{(lo) \perp} (a, u) \\ @_{(io) \perp} (@_{(i(io)) \perp} (r, y), u) & @_{(lo) \perp} (a, V) \vee \neg @_{(io) \perp} (@_{(i(io)) \perp} (r, y), V) \end{array}$$

Example Proof:

$$|\text{valid } \Box_s (\Box_r a \Rightarrow \Box_r a)|$$

Initialisation of problem

$$\neg |\text{valid } \Box_s (\Box_r a \Rightarrow \Box_r a)|$$

Definition expansion

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Normalisation (x, y, u are now Skolem constants, V is a free variable)

$$\begin{array}{ll} s(x, y) & \neg a(u) \\ r(y, u) & a(V) \vee \neg r(y, V) \end{array}$$

Translation to first-order logic [Kerber-94], [Hurd-02], [MengPaulson-04]

$$\begin{array}{ll} @_{(io)\perp} (@_{(i(io))\perp} (s, x), y) & \neg @_{(lo)\perp} (a, u) \\ @_{(io)\perp} (@_{(i(io))\perp} (r, y), u) & @_{(lo)\perp} (a, V) \vee \neg @_{(io)\perp} (@_{(i(io))\perp} (r, y), V) \end{array}$$

Example Proof:

$$|\text{valid } \Box_s (\Box_r a \Rightarrow \Box_r a)|$$

Initialisation of problem

$$\neg |\text{valid } \Box_s (\Box_r a \Rightarrow \Box_r a)|$$

Definition expansion

$$\neg (\forall x_{\iota}. \forall y_{\iota}. \neg s(x, y) \vee ((\neg (\forall u_{\iota}. \neg r(y, u) \vee a(u))) \vee (\forall v_{\iota}. \neg r(y, v) \vee a(v)))$$

Normalisation (x, y, u are now Skolem constants, V is a free variable)

$$\begin{array}{ll} s(x, y) & \neg a(u) \\ r(y, u) & a(V) \vee \neg r(y, V) \end{array}$$

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Example Proof:

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Definition expansion

$$\neg (\forall x_{\iota}. \forall y_{\iota}. \neg s(x, y) \vee ((\neg (\forall u_{\iota}. \neg r(y, u) \vee a(u))) \vee (\forall v_{\iota}. \neg r(y, v) \vee a(v)))$$

Normalisation (x, y, u are now Skolem constants, V is a free variable)

$$\begin{array}{ll} s(x, y) & \neg a(u) \\ r(y, u) & a(V) \vee \neg r(y, V) \end{array}$$

Translation to first-order logic [Kerber-94], [Hurd-02], [MengPaulson-04]

$$\begin{array}{ll} @_{(io)\neg} (@_{(i(io))\neg} (s, x), y) & \neg @_{(lo)\neg} (a, u) \\ @_{(io)\neg} (@_{(i(io))\neg} (r, y), u) & @_{(lo)\neg} (a, V) \vee \neg @_{(io)\neg} (@_{(i(io))\neg} (r, y), V) \end{array}$$

More Examples ...

A simple equation between modal logic formulas

$$\forall r. \forall a. \forall b. |\Box_r (a \vee b)| \doteq |\Box_r (b \vee a)|$$

where \doteq is defined as $\lambda u, v. \forall p. (p u) \Rightarrow (p v)$

- initialisation, definition expansion and normalisation:

$$\begin{aligned} & (p (\lambda W. \forall y. \neg ((r W) y) \vee (a y) \vee (b y))) \\ & \neg (p (\lambda W. \forall y. \neg ((r W) y) \vee (b y) \vee (a y))) \end{aligned}$$

More Examples ...

A simple equation between modal logic formulas

$$\forall r. \forall a. \forall b. |\Box_r (a \vee b)| \doteq |\Box_r (b \vee a)|$$

where \doteq is defined as $\lambda u, v. \forall p. (p u) \Rightarrow (p v)$

► resolution:

$$\begin{aligned} & (p (\lambda W. \forall y. \neg((r W) y) \vee (a y) \vee (b y))) \\ & \neq \\ & (p (\lambda W. \forall y. \neg((r W) y) \vee (b y) \vee (a y))) \end{aligned}$$

More Examples ...

A simple equation between modal logic formulas

$$\forall r. \forall a. \forall b. |\Box_r (a \vee b)| \doteq |\Box_r (b \vee a)|$$

where \doteq is defined as $\lambda u, v. \forall p. (p u) \Rightarrow (p v)$

► decomposition:

$$\begin{aligned} & (\lambda W_t. \forall y_t. \neg((r W) y) \vee (a y) \vee (b y)) \\ & \neq \\ & (\lambda W_t. \forall y_t. \neg((r W) y) \vee (b y) \vee (a y)) \end{aligned}$$

More Examples ...

A simple equation between modal logic formulas

$$\forall r. \forall a. \forall b. |\Box_r (a \vee b)| \doteq |\Box_r (b \vee a)|$$

where \doteq is defined as $\lambda u, v. \forall p. (p \ u) \Rightarrow (p \ v)$

- functional extensionality:

$$\begin{aligned} & (\forall y. \neg((r \ w) \ y) \vee (a \ y) \vee (b \ y)) \\ & \neq \\ & (\forall y. \neg((r \ w) \ y) \vee (b \ y) \vee (a \ y)) \end{aligned}$$

More Examples ...

A simple equation between modal logic formulas

$$\forall r. \forall a. \forall b. |\Box_r (a \vee b)| \doteq |\Box_r (b \vee a)|$$

where \doteq is defined as $\lambda u, v. \forall p. (p u) \Rightarrow (p v)$

► Boolean extensionality:

$$\begin{aligned} & \neg((\forall y. \neg((r w) y) \vee (a y) \vee (b y))) \\ & \Leftrightarrow \\ & (\forall y. \neg((r w) y) \vee (b y) \vee (a y))) \end{aligned}$$

More Examples ...

A simple equation between modal logic formulas

$$\forall r. \forall a. \forall b. |\Box_r (a \vee b)| \doteq |\Box_r (b \vee a)|$$

where \doteq is defined as $\lambda u. v. \forall p. (p u) \Rightarrow (p v)$

► normalisation:

40 : $(b \vee) \vee (a \vee) \vee \neg((r w) \vee) \vee \neg((r w) \vee) \vee (b \vee) \vee (a \vee)$

41 : $((r w) z) \vee ((r w) v)$

42 : $\neg(a z) \vee ((r w) v)$

43 : $\neg(b z) \vee ((r w) v)$

44 : $((r w) z) \vee \neg(a v)$

45 : $\neg(a z) \vee \neg(a v)$

46 : $\neg(b z) \vee \neg(a v)$

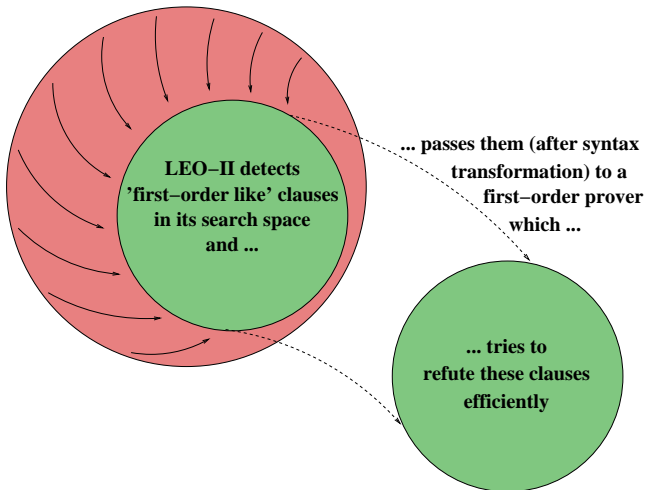
47 : $((r w) z) \vee \neg(b v)$

48 : $\neg(a z) \vee \neg(b v)$

49 : $\neg(b z) \vee \neg(b v)$

► total proving time is 0.166s

Architecture of LEO-II



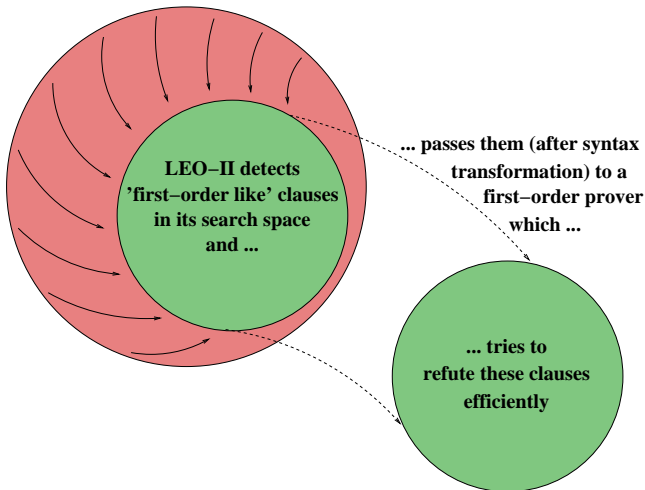
More Examples ...

In modal logic **K**, the axioms *T* and 4 are equivalent to reflexivity and transitivity of the accessibility relation *R*

$$\begin{aligned} & \forall r. (\forall a. |\text{valid } \Box_r a \Rightarrow a| \wedge |\text{valid } \Box_r a \Rightarrow \Box_r \Box_r a|) \\ & \Leftrightarrow ((\text{reflexive } r) \wedge (\text{transitive } r)) \end{aligned}$$

- ▶ processing in LEO-II analogous to previous example
- ▶ now 70 clauses are passed to E
- ▶ E generates **21769** clauses before finding the empty clause
- ▶ total proving time 2.4s
- ▶ this proof cannot be found in LEO-II alone

Architecture of LEO-II



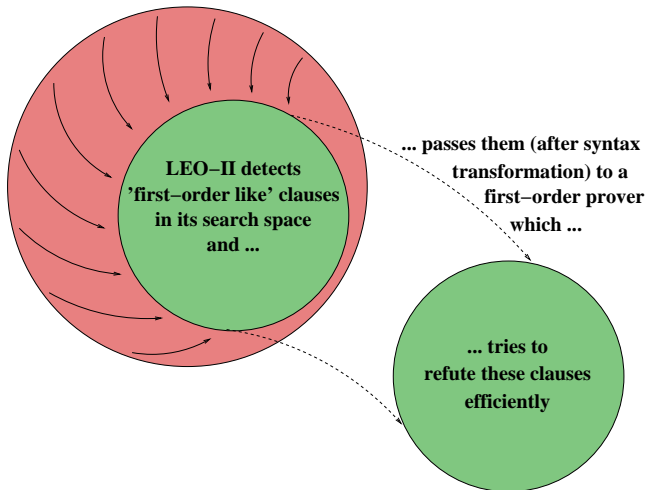
More Examples ...

$S4 \not\subseteq K$: Axioms T and 4 are not valid in modal logic K

$$\neg \forall r. \forall a. \forall b. | \text{valid } \Box_r a \Rightarrow a | \wedge | \text{valid } \Box_r b \Rightarrow \Box_r \Box_r b |$$

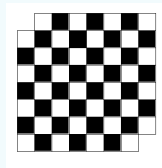
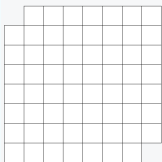
- ▶ LEO-II shows that axiom T is not valid
- ▶ R is instantiated with $\lambda x. \lambda y. (H \times y) \neq (H' \times y)$ via primitive substitution
- ▶ total proving time 17.3s

Architecture of LEO-II



Representation (and the right System Architecture) Matters!

A general lesson in AI ...

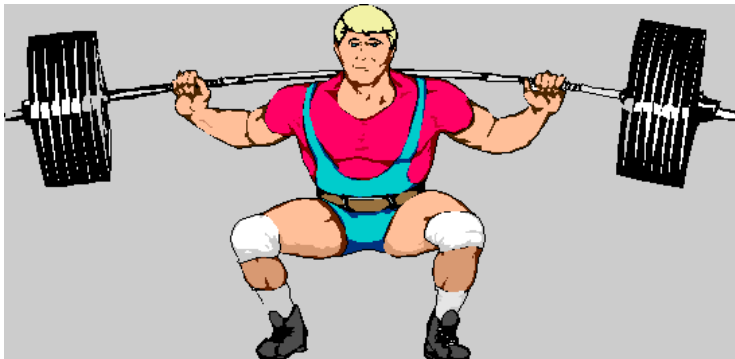


... and a specific lesson here

FOL
+
FO-ATP

HOL
+
LEO-II + FO-ATP

Access Control Logics



Access Control Logics

Example (from [GargAbadi08]): file-access scenario

- ▶ If admin says that file1 should be deleted, then this must be the case.

$(\text{admin says deletefile1}) \supset \text{deletefile1}$

- ▶ admin trusts Bob to decide whether file1 should be deleted.

$\text{admin says } ((\text{Bob says deletefile1}) \supset \text{deletefile1})$

- ▶ Bob wants to delete file1.

$\text{Bob says deletefile1}$

- ▶ Is deletion permitted?

deletefile1

Deepak Garg, Martín Abadi:

A Modal Deconstruction of Access Control Logics

FoSSaCS 2008: 216-230, LNCS 4962 ©Springer

- ▶ translation of a logic of access control with “says” operator into classical modal logic S4
- ▶ sound and complete
- ▶ extends to logics with
 - ▶ “speaks for” relation (ICL^{\Rightarrow})
 - ▶ Boolean combinations of principals (ICL^B)

So, let's combine this with our previous work ... and apply LEO-II

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So, let's combine this with our previous work ... and apply LEO-II

Access Control Logic translated to Modal Logic and HOL

$$s, t ::= p \mid s \wedge t \mid s \vee t \mid s \supset t \mid \perp \mid \top \mid A \text{ says } s$$

Translation $\lceil \cdot \rceil$ (of Garg and Abadi) into S4

$$\lceil p \rceil = \Box p$$

$$\lceil s \wedge t \rceil = \lceil s \rceil \wedge \lceil t \rceil$$

$$\lceil s \vee t \rceil = \lceil s \rceil \vee \lceil t \rceil$$

$$\lceil s \supset t \rceil = \Box(\lceil s \rceil \Rightarrow \lceil t \rceil) \text{ (fixed on 05.11.2008)}$$

$$\lceil \top \rceil = \top$$

$$\lceil \perp \rceil = \perp$$

$$\lceil A \text{ says } s \rceil = \Box(A \vee \lceil s \rceil)$$

Access Control Logic translated to Modal Logic and HOL

$$s, t ::= p \mid s \wedge t \mid s \vee t \mid s \supset t \mid \perp \mid \top \mid A \text{ says } s$$

Translation $\|\cdot\|$ to HOL

$$\begin{aligned}
 & \quad |r| \quad (\text{we fix one single } r!!!) \\
 \|p\| &= |\Box_r p| \\
 \|A\| &= |A| \\
 \|\wedge\| &= \lambda s. \lambda t. |s \wedge t| \\
 \|\vee\| &= \lambda s. \lambda t. |s \vee t| \\
 \|\supset\| &= \lambda s. \lambda t. |\Box_r (s \Rightarrow t)| \quad (\text{fixed on 05.11.2008}) \\
 \|\top\| &= |\top| \\
 \|\perp\| &= |\perp| \\
 \|\text{says}\| &= \lambda A. \lambda s. |\Box_r (A \vee s)|
 \end{aligned}$$

Access Control Logic translated to Modal Logic and HOL

$$s, t ::= p \mid s \wedge t \mid s \vee t \mid s \supset t \mid \perp \mid \top \mid A \text{ says } s$$

Translation $\|\cdot\|$ to HOL

$$\begin{aligned}
 & r_{l \rightarrow l \rightarrow o} \quad (\text{we fix one single } r!!!) \\
 \|p\| &= \lambda x_{l \rightarrow o} \cdot \forall y_{l \rightarrow o} \cdot r_{l \rightarrow l \rightarrow o} x y \Rightarrow p_{l \rightarrow o} Y \\
 \|A\| &= a_{l \rightarrow o} \quad ((\text{distinct from the } p_{l \rightarrow o})) \\
 \|\wedge\| &= \lambda s_{l \rightarrow o} \cdot \lambda t_{l \rightarrow o} \cdot \lambda w_{l \rightarrow o} \cdot s w \wedge t w \\
 \|\vee\| &= \lambda s_{l \rightarrow o} \cdot \lambda t_{l \rightarrow o} \cdot \lambda w_{l \rightarrow o} \cdot s w \vee t w \\
 \|\supset\| &= \lambda s_{l \rightarrow o} \cdot \lambda t_{l \rightarrow o} \cdot \lambda w_{l \rightarrow o} \cdot \forall y_{l \rightarrow o} \cdot r_{l \rightarrow l \rightarrow o} w y \Rightarrow (s y \Rightarrow t y) \quad (\text{fixed on } w) \\
 \|\top\| &= \lambda s_{l \rightarrow o} \cdot \top \\
 \|\perp\| &= \lambda s_{l \rightarrow o} \cdot \perp \\
 \|\text{says}\| &= \lambda A_{l \rightarrow o} \cdot \lambda s_{l \rightarrow o} \cdot \lambda w_{l \rightarrow o} \cdot \forall y_{l \rightarrow o} \cdot r_{l \rightarrow l \rightarrow o} w y \Rightarrow (A y \vee s y)
 \end{aligned}$$

Access Control Logic translated to Modal Logic and HOL

Notion of Validity

$$\text{iclval} = \text{valid}$$

Addition of Modal Logic Axioms for S4

$$\forall p_{l \rightarrow o}. |\text{valid } \Box_r p \Rightarrow p|$$

$$\forall p_{l \rightarrow o}. |\text{valid } \Box_r p \Rightarrow \Box_r \Box_r p|$$

Soundness of Embedding

see [SR-2008-01]: employs transformation from Kripke models into corresponding Henkin models

Access Control Logic translated to Modal Logic and HOL

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$$\text{iclval} = \text{valid}$$

Addition of Modal Logic Axioms for S4

$$\forall p_{\iota \rightarrow o}. |\text{valid } \Box_r p \Rightarrow p|$$

$$\forall p_{\iota \rightarrow o}. |\text{valid } \Box_r p \Rightarrow \Box_r \Box_r p|$$

Soundness of Embedding

see [SR-2008-01]: employs transformation from Kripke models into corresponding Henkin models

Access Control Logic translated to Modal Logic and HOL

Example (from [GargAbadi08]): file-access scenario

- ▶ If admin says that file1 should be deleted, then this must be the case.

$\| \text{iclval } (\text{adminsays deletefile1}) \supset \text{deletefile1} \|$

- ▶ admin trusts Bob to decide whether file1 should be deleted.

$\| \text{iclval adminsays}((\text{Bobsays deletefile1}) \supset \text{deletefile1}) \|$

- ▶ Bob wants to delete file1.

$\| \text{iclval Bobsays deletefile1} \|$

- ▶ Is deletion permitted?

$\| \text{iclval deletefile1} \|$

Access Control Logic translated to Modal Logic and HOL

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$\| \text{iclval adminsays}((\text{Bobsays deletefile1}) \supset \text{deletefile1}) \|$

- ▶ Bob wants to delete file1.

$|\text{valid } \Box_r (\text{Bob} \vee \Box_r \text{deletefile1})|$

- ▶ Is deletion permitted?

$\| \text{iclval deletefile1} \|$

Access Control Logic translated to Modal Logic and HOL

Example (from [GargAbadi08]): file-access scenario

- ▶ If admin says that file1 should be deleted, then this must be the case.

$\|\text{iclval } (\text{admin says deletefile1}) \supset \text{deletefile1}\|$

- ▶ admin trusts Bob to decide whether file1 should be deleted.

$\|\text{iclval admin says } ((\text{Bob says deletefile1}) \supset \text{deletefile1})\|$

- ▶ Bob wants to delete file1.

$\forall w. (\forall y. (r \ w \ y) \Rightarrow ((\text{Bob } y) \vee \forall u. (r \ w \ u) \Rightarrow (\text{deletefile1 } u)))$

- ▶ Is deletion permitted?

$\|\text{iclval deletefile1}\|$

LEO-II: 0.149 seconds

Exp.: Access Control Logic in HOL

Logic ICL:

Name	Problem	LEO (s)
unit	$\{R, T\} \vdash \ \text{ICLval } s \supset (A \text{ says } s)\ $	0.048
cuc	$\{R, T\} \vdash \ \text{ICLval } (A \text{ says } (s \supset t)) \supset (A \text{ says } s) \supset (A \text{ says } t)\ $	0.055
idem	$\{R, T\} \vdash \ \text{ICLval } (A \text{ says } A \text{ says } s) \supset (A \text{ says } s)\ $	0.048
Ex1	$\{R, T, \ \text{ICLval } (1.1)\ , \dots, \ \text{ICLval } (1.3)\ \} \vdash \ \text{ICLval } (1.4)\ $	0.149
unit^K	$\vdash \ \text{ICLval } s \supset (A \text{ says } s)\ $	—
cuc^K	$\vdash \ \text{ICLval } (A \text{ says } (s \supset t)) \supset (A \text{ says } s) \supset (A \text{ says } t)\ $	0.041
idem^K	$\vdash \ \text{ICLval } (A \text{ says } A \text{ says } s) \supset (A \text{ says } s)\ $	—
Ex1^K	$\{\ \text{ICLval } (1.1)\ , \dots, \ \text{ICLval } (1.3)\ \} \vdash \ \text{ICLval } (1.4)\ $	0.053

R, T : reflexivity and transitivity axioms as seen before

Exp.: Access Control Logic in HOL

Logic ICL \Rightarrow :

Name	Problem	LEO (s)
refl	$\{R, T\} \vdash \ \text{ICLval } A \Rightarrow A\ $	0.052
trans	$\{R, T\} \vdash \ \text{ICLval } (A \Rightarrow B) \supset (B \Rightarrow C) \supset (A \Rightarrow C)\ $	0.044
sp.-for	$\{R, T\} \vdash \ \text{ICLval } (A \Rightarrow B) \supset (A \text{ says } s) \supset (B \text{ says } s)\ $	0.052
handoff	$\{R, T\} \vdash \ \text{ICLval } (B \text{ says } (A \Rightarrow B)) \supset (A \Rightarrow B)\ $	0.044
Ex2	$\{R, T, \ \text{ICLval } (2.1)\ , \dots, \ \text{ICLval } (2.4)\ \} \vdash \ \text{ICLval } (2.5)\ $	0.251
refl ^K	$\vdash \ \text{ICLval } A \Rightarrow A\ $	0.034
trans ^K	$\vdash \ \text{ICLval } (A \Rightarrow B) \supset (B \Rightarrow C) \supset (A \Rightarrow C)\ $	0.043
sp.-for ^K	$\vdash \ \text{ICLval } (A \Rightarrow B) \supset (A \text{ says } s) \supset (B \text{ says } s)\ $	0.039
handoff ^K	$\vdash \ \text{ICLval } (B \text{ says } (A \Rightarrow B)) \supset (A \Rightarrow B)\ $	–
Ex2 ^K	$\{\ \text{ICLval } (2.1)\ , \dots, \ \text{ICLval } (2.4)\ \} \vdash \ \text{ICLval } (2.5)\ $	–

R, T : reflexivity and transitivity axioms as seen before

Exp.: Access Control Logic in HOL

Logic ICL^B :

Name	Problem	LEO (s)
trust	$\{R, T\} \vdash \ \text{ICLval } (\perp \text{ says } s) \supset s\ $	0.044
untrust	$\{R, T, \ \text{ICLval } A \equiv \top\ \} \vdash \ \text{ICLval } A \text{ says } \perp\ $	0.046
cuc'	$\{R, T\} \vdash \ \text{ICLval } ((A \supset B) \text{ says } s) \supset (A \text{ says } s) \supset (B \text{ says } s)\ $	0.048
Ex3	$\{R, T, \ \text{ICLval } (3.1)\ , \dots, \ \text{ICLval } (3.3)\ \} \vdash \ \text{ICLval } (3.4)\ $	0.060
trust ^K	$\vdash \ \text{ICLval } (\perp \text{ says } s) \supset s\ $	—
untrust ^K	$\{\ \text{ICLval } A \equiv \top\ \} \vdash \ \text{ICLval } A \text{ says } \perp\ $	0.035
cuc' ^K	$\vdash \ \text{ICLval } ((A \supset B) \text{ says } s) \supset (A \text{ says } s) \supset (B \text{ says } s)\ $	0.044
Ex3 ^K	$\{\ \text{ICLval } (3.1)\ , \dots, \ \text{ICLval } (3.3)\ \} \vdash \ \text{ICLval } (3.4)\ $	—

R, T : reflexivity and transitivity axioms as seen before

What makes LEO-II strong? The combination of

- ▶ expressive higher-order representations
- ▶ reduction to first-order representations
- ▶ cooperation with first-order ATPs
- ▶ higher-order termsharing and termindeixing techniques

Try LEO-II (running under Ocaml 3.10)

- ▶ Website: <http://www.ags.uni-sb.de/~leo>
 - ▶ download version, very easy to install
 - ▶ online demo
- ▶ Systems on TPTP:
<http://www.cs.miami.edu/~tptp/cgi-bin/SystemOnTPTP>

.... there is much left to be done!

LEO-II

- ▶ Equational Reasoning
- ▶ Termination
- ▶ Handling of Definitions

Cooperat. with Specialist Reasoners

- ▶ Monadic Second-Order Logic, Prop. Logic, Arithmetic, ...
- ▶ Logic Translations
- ▶ Feedback for LEO-II
- ▶ Proof Transf./Verification
- ▶ Agent-based Architecture

Integration into Proof Assistants

- ▶ Relevance of Axioms
- ▶ Proof Transf./Verification

International Infrastructure

- ▶ TPTP Language(s) for HOL
- ▶ Repository of Proof Problems
- ▶ HOL Prover Contest

Applications

Logic System Interrelationships,
Ontology Reasoning (SUMO, CYC),
Formal Methods, CL, ...

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More Information on LEO-II

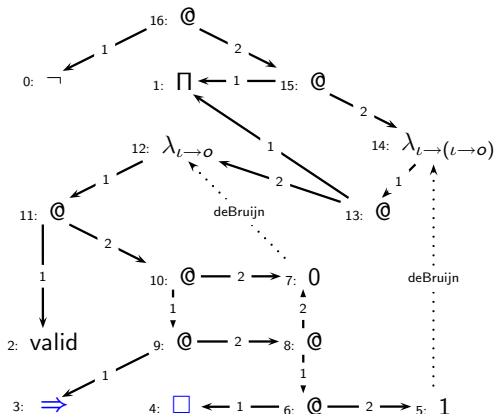
- ▶ Website with online version of LEO-II:

<http://www.ags.uni-sb.de/~leo>

- ▶ System description [IJCAR-08]
- ▶ TPTP THF input syntax [IJCAR-THF-08]
Higher-Order TPTP Infrastructure EU project THFTPTP
- ▶ Reasoning in and about multimodal logic [Festschrift-Andrews-08]

Term Graph for:

$$\neg \forall R. \forall A. (\text{valid}(\Box_R A \Rightarrow A))$$



Term graph videos: <http://www.ags.uni-sb.de/~leo/art>

Latest Application of LEO-II: Dancefloor Animation



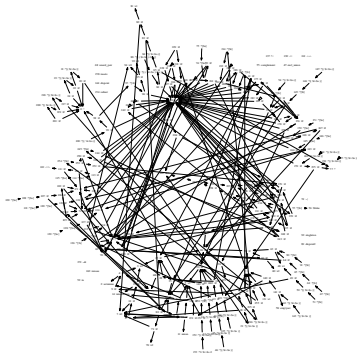
Grooving to an animation of LEO-II's dynamically growing termgraph (while LEO-II is proving Cantor's theorem)

In LEO-II:

- ▶ Terms as unique instances
- ▶ Perfect Term Sharing
- ▶ Shallow data structures

Features:

- ▶ β - η -normalization
- ▶ DeBruijn indices
- ▶ local contexts for polymorphic type variables



LEO-II cannot prove the following example:

Modal logic $K4$ (which adds only axiom 4 to K) is not entailed in K :

$$\neg \forall R. \forall B. (\text{valid}(\Box_R B \Rightarrow \Box_R \Box_R B))$$

LEO-II also cannot prove this related example:

$$\neg \forall R. \text{trans}(R)$$

- ▶ reason: not a theorem; domain of possible worlds may well just consist of a single world w .
- ▶ LEO-II can in fact prove the latter example under the additional assumption

$$\neg \forall X. \forall Y. X = Y$$

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