

EDUCATION EXPERIENCE

Korea Advanced Institute of Science and Technology (KAIST)
Ph.D. candidate in Industry and System Engineering
- Research student in KAIST SILab, supervised by Dr. Jinkyoo Park
- KAIST full scholarship & KAIST special scholarship

Daejeon, Republic of Korea
Sep. 2022 ~ Aug. 2025 (Expected)

Korea Advanced Institute of Science and Technology (KAIST)
M.E. in Industry and System Engineering
- Research student in KAIST SILab, supervised by Dr. Jinkyoo Park
- KAIST full scholarship. GPA: 3.9/4.3

Daejeon, Republic of Korea
Sep. 2020 ~ Jul. 2022

Pohang University of Science and Technology (POSTECH)
Exchange student in Computer Science Engineering
- Research intern in POSTECH CV Lab, supervised by Dr. Minsu Cho

Pohang, Republic of Korea
Sep. 2019 ~ Jan. 2020

Harbin Institute of Technology (HIT)
B.S. in Information and Computing Science, Mathematics
- People's scholarship. GPA: 3.4/4.0. Rank: 12/98

Harbin, People's Republic of China
Sep. 2016 ~ Jul. 2020

WORK EXPERIENCE

Omelet
AI scientist intern

Daejeon, Republic of Korea
June. 2024 ~ Present

Daewoong Foundation
Machine learning engineering intern

Seoul, Republic of Korea
Jan. 2023 ~ Feb. 2023

HUAWEI Technologies Research Center
Algorithm engineering intern

Nanjing, People's Republic of China
Jun. 2019 ~ Aug. 2019

China Huarong Asset Management
Data engineering intern

Beijing, People's Republic of China
Jun. 2018 ~ Sep. 2018

PUBLICATIONS

CAMP: Collaborative Attention Model with Profiles for Vehicle Routing Problems
C Hua, F Berto*, J Son, S Kang, C Kwon, and J Park*

AAMAS 2025
Conference Poster

AoP-SAM: Automation of Prompts for Efficient Segmentation
Y Chen, M Son, C Hua, and JY Kim

AAAI 2025
Conference Poster

Accelerating Chiplet Placement & Routing Optimization with Machine Learning
H Kim, F Berto, J Lee, H An, T Shin, C Hua, J Park, Y Kim, and J Kim

DesignCon 2025
Conference Best Paper

Large Language Models as Hyper-Heuristics for Combinatorial Optimization
H Ye, J Wang, Z Cao, F Berto, C Hua, H Kim, and J Park

NeruIPS 2024
Conference Poster

HiMAP: Learning Heuristics-Informed Policies for Large-Scale Multi-Agent Pathfinding
H Tang, F Berto, Z Ma, C Hua, K Ahn, and J Park

AAMAS 2024
Conference Poster

Learning Efficient Surrogate Dynamic Models with Graph Spline Networks
C Hua, F Berto*, M Poli, S Massaroli, and J Park*

NeurIPS 2023
Conference Poster

Coagulant dosage determination using deep learning-based graph attention multivariate time series forecasting model
S Lin, J Kim, C Hua, MH Park, and S Kang

Water Research
Journal

Deep learning-based coagulant dosage prediction for extreme events leveraging large-scale data
J Kim, C Hua, S Lin, S Kang, JH Kang, and MH Park

JWPE
Journal

Comparing artificial and deep neural network models for prediction of coagulant amount and settled water turbidity: lessons learned from big data in water treatment operations
S Lin, J Kim, C Hua, S Kang, and MH Park

JWPE
Journal

Optimizing coagulant dosage using deep learning models with large-scale data
J Kim, C Hua, K Kim, S Lin, G Oh, MH Park, and S Kang

Chemosphere
Journal

Under Review & Preprints

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| RL4CO: a Unified Reinforcement Learning for Combinatorial Optimization Library <i>F Berto*, C Hua*, J Park*, M Kim, H Kim, J Son, H Kim, J Kim, and J Park</i> | Under Review arXiv preprint |
| A Unified Learning Model for the Profiled Vehicle Routing Problem <i>C Hua*, F Berto*, Z Zhao, J Son, C Kwon, and J Park</i> | Under Review arXiv preprint |
| PARCO: Learning parallel autoregressive policies for efficient multi-agent combinatorial optimization <i>F Berto*, C Hua*, L Luttmann, J Son, J Park, K Ahn, C Kwon, L Xie, and J Park</i> | Under Review arXiv preprint |
| Routefinder: Towards foundation models for vehicle routing problems <i>F Berto*, C Hua*, NG Zepeda*, A Hottung, N Wouda, L Lan, K Tierney, and J Park</i> | Under Review arXiv preprint |
| Neural Combinatorial Optimization for Real-World Routing <i>J Son*, Z Zhao*, F Berto, C Hua, C Kwon, and J Park</i> | Under Review arXiv preprint |
| Multi-agent dynamic relational reasoning for social robot navigation <i>J Li*, C Hua*, H Ma, J Park, V Dax, and MJ Kochenderfer</i> | Under Review arXiv preprint |
| Evolvehypergraph: Group-aware dynamic relational reasoning for trajectory prediction <i>J Li*, C Hua*, J Park, H Ma, V Dax, and MJ Kochenderfer</i> | Under Review arXiv preprint |

Workshop

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| Routefinder: Towards foundation models for vehicle routing problems <i>F Berto*, C Hua*, NG Zepeda*, A Hottung, N Wouda, L Lan, K Tierney, and J Park</i> | ICML 2024 Workshop Oral |
| RL4CO: a Unified Reinforcement Learning for Combinatorial Optimization Library <i>F Berto*, C Hua*, J Park*, M Kim, H Kim, J Son, H Kim, J Kim, and J Park</i> | NeurIPS 2023 Workshop Oral |
| Efficient Continuous Spatio-Temporal Simulation with Graph Spline Networks <i>C Hua*, F Berto*, M Poli, S Massaroli, and J Park</i> | ICML 2022 Workshop Oral |

AWARDS

- 2023, Daewoong AI & Big Data Scholarship
- 2023, KAIST ISysE Research Day Excellent Paper Award
- 2022, Korea Advanced Institute of Science and Technology Special Scholarship
- 2021, **2nd Finalist**, Daewoong Foundation AI & Big Data Hackathon
- 2019, **Second Round Shortlisted**, The 5th Baidu Big Data Competition
- 2018, **Provincial Second Award**, China Undergraduate Mathematical Contest in Modeling (CUMCM)
- 2018, Harbin Institute of Technology Outstanding Student Leader, People's Scholarship

ACADEMIC SERVICE

Reviewer: ICML 2023, 2024, 2025; NeurIPS 2023, 2024, 2025; KDD 2024, 2025; ICLR 2024; AAMAS 2025; IJCAI 2024, RA-L.

ADDITIONAL

- GitHub Link: <https://github.com/cbhua>
- Personal Page: <https://cbhua.github.io>

SUMMARY

I am a third-year Ph.D. candidate in the *Industrial & Systems Engineering* (ISysE) department at *Korea Advanced Institute of Science and Technology* (KAIST). I am doing research with my colleagues at the *Systems Intelligence Laboratory* (SILab) supervised by Prof. Jinkyoo Park. I am a co-founder of the AI4CO open source group and working closely with the DiffEqML open source group.

The primary focus of my ongoing research is the development of *reinforcement learning* (RL) algorithms for the study of *combinatorial optimization* (CO) problems. We create an extensive open-source benchmark RL4CO to provide a unified framework for RL-based CO algorithms. I also explore machine learning methods for dynamical physical system simulation, scientific computing, and trajectory prediction. Recent interests include reinforcement learning for continuous dynamical system control, robot navigation and high efficient complex physical system simulation.