

Optimization and Prediction in Natural Gas Networks Using Graph Neural Networks and MPCC-Based Models

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Acknowledgments

Abstract

This thesis explores novel approaches to modeling and optimizing natural gas network systems, focusing on integrating Graph Neural Networks (GNNs) and Mathematical Programs with Complementarity Constraints (MPCCs). The increasing complexity of natural gas networks and energy systems demands predictive models that capture detailed system behaviors while adhering to physical laws. Traditional models often need help to account for intricate network dynamics and interconnected pipelines under diverse operating conditions. This research addresses these limitations through a multi-chapter progression, with each chapter advancing the modeling framework based on the unique strengths of GNNs and MPCCs.

In the second chapter, a GNN-based model was developed to learn the system responses obtained from a linear optimization model of the natural gas network, which modeled flow conditions without incorporating pressures. The GNN demonstrated the ability to approximate these responses effectively and generalize to cases not seen in the training phase, highlighting its potential for rapid, approximate solutions when computational efficiency is a priority.

The third chapter introduces an MPCC-based optimization model tailored for natural gas systems. It extends the modeling framework to include the Weymouth equation, which governs pressure-flow relationships in interconnected networks. This MPCC model provides a highly accurate solution by embedding non-linear pressure constraints directly into the optimization process, improving accuracy compared to traditional approaches.

Building on these advancements, the fourth chapter integrates the strengths of both approaches by using the MPCC-based model to generate accurate training data for a new, enhanced GNN-based model that incorporates pressure considerations. This hybrid model benefits from the robust physical fidelity of the MPCC-based approach, enabling the GNN to learn pressure-related responses effectively. As a result, this GNN-based model can generate predictions for scenarios not previously encountered in

training, a feature it shares with the initial GNN model from the second chapter but now with greater accuracy due to the inclusion of pressure constraints.

The results demonstrate that, while the GNN-based model may offer slightly lower accuracy than the MPCC model, it achieves predictions with a significant reduction in computational time, making it valuable for applications requiring rapid response. The MPCC-based optimization model, in contrast, provides the lowest error response, with superior accuracy in modeling non-linear pressure dynamics.

This thesis establishes that combining MPCC and GNN-based modeling, particularly with physics-informed loss functions, offers a scalable and computationally efficient framework for optimizing natural gas networks. Future research could extend this approach to incorporate transient dynamics, implement high-complexity Weymouth loss functions, and adopt a fully physics-informed neural network (PINN) approach, advancing predictive capabilities for resilient energy system operations under variable conditions.

Contents

1	Introduction	1
1.1	Justification	1
1.2	Problem statement	3
1.2.1	Objectives	4
1.2.2	General Objective	4
1.2.3	Specific Objectives	5
2	Natural Gas System Prediction Using Graph Neural Networks	6
2.1	Mathematical framework	6
2.1.1	Graph definition	6
2.1.2	Multi-Layered Perceptrons	8
2.1.3	Graph Neural Networks	10
2.1.4	Convolution with Edge-Node Switching (Cens Block)	12
2.1.5	Gas flow estimation through CensNet	16
2.1.6	Task-Dependent Loss Functions	18
2.2	Experimental Setup and Results	19
2.2.1	Results	21
2.2.2	Case Study I: 8-node Network	22
2.2.3	Case Study II: 63-node Network (Colombia)	25
2.3	Discussion and conclusions	29
3	Optimization Using Mathematical Programs with Complementarity Constraints	32
3.1	Formulation of Interconnected Power and Gas Systems	32
3.2	Mathematical Programming with Complementarity Constraints for Weymouth Approximation	35
3.2.1	Linear Independence Constraint Qualification (LICQ)	36

CONTENTS

3.2.2	Mangasarian-Fromovitz Constraint Qualification (MFCQ)	37
3.3	Case studies	38
3.3.1	Case Study I: 9/8 System	39
3.3.2	Case II: 118/48 System	42
3.3.3	Case Study III: 96/63 System	43
3.4	Conclusions	47
4	Enhanced Natural Gas Flow Predictions Using Physics-Guided Neural Networks	49
4.1	Methodology	50
4.2	Results	51
4.2.1	Case Study I: 8-node Network	52
4.2.2	Case Study II: 63-node Network (Colombia)	74
4.3	Discussion and conclusions	78
5	Conclusions and future work	83
5.1	Conclusions	83
5.2	Future Work	85

List of Figures

2.1	Types of graphs	7
2.2	General diagram of a multilayer perceptron, showing the input layers in green, the hidden layers in blue and the outputs in red.	9
2.3	General outline of the CensNet-based model used.	21
2.4	Model results using only the loss associated with nodal flow predictions in the 8-node network.	22
2.5	Model results using the losses associated with the flows in nodes and edges predictions in the 8-node network.	24
2.6	Model results using only the loss associated with nodal flow predictions in the colombian 63-node network.	26
2.7	Model results using the losses associated with the predicted flows injected at the nodes and transported by the pipelines and compressors in the colombian 63-node network.	27
3.1	Integrated system 9/8 used in Case Study I, modified from the MPNG software.	40
3.2	Cost function histogram for the Taylor, SOC, and MPCC Weymouth approximation approaches in the 9-bus 8-node system.	41
3.3	Boxplot of Weymouth error distribution for each pipeline in the 9/8 system attained by contrasted approximation approaches.	41
3.4	Histogram depicting the relative frequencies of cost differences obtained between MPCC and the other approaches in the 48-node 118-bus system.	42
3.5	Weymouth approximation errors for each pipeline p reached by the contrasted approaches in the 118/48 study case.	43
3.6	Daily operating cost obtained with each of the approaches in the 63-node 96-bus system.	44

LIST OF FIGURES

3.7	Weymouth error density on the Colombian case versus the gas flow and operation day.	45
3.8	Output-to-input pressure ratio at the compressor in the 96/63 system.	46
3.9	Outlying connection of well-compressor-pipeline on the system 96/63 used in Case Study III.	47
4.1	General outline of the CensNet-based model used.	52
4.2	Model results using only the loss associated with nodal flow predictions in the 8-node network.	53
4.3	Model results using only the loss associated with nodal flow predictions in the 8-node network.	54
4.4	Model results using only the loss associated with nodal flow predictions in the 8-node network.	55
4.5	Model results using only the loss associated with nodal flow predictions in the 8-node network.	55
4.6	Model results using only the loss associated with nodal flow predictions in the 8-node network.	56
4.7	Joint PDFs between the inputs used in the 8-node network, which have two modes.	58
4.8	Joint PDFs between the inputs used in the 8-node network, which do not appear to have a defined mode.	60
4.9	Joint PDFs between the inputs used in the 8-node network, which have a considerably wide mode with respect to the entire distribution	61
4.10	Joint PDFs between the outputs used in the 8-node network, which have a behavior quite similar to that of a Gaussian distribution.	62
4.11	Joint PDFs between the outputs used in the 8-node network, which have a negative flow.	63
4.12	Joint PDFs between the outputs used in the 8-node network, which...	64
4.13	Joint PDFs between the inputs and outputs used in the 8-node network, which present a wide dispersion along second variable.	66
4.14	Joint PDFs between the inputs and outputs used in the 8-node network, which present a linear behavior, although with different dispersions among them.	67
4.15	Joint PDFs between the entries used in the 8-node network, which have two modes in the KDE sampled variables	69
4.16	Joint PDFs between the inputs used in the 8-node network, which do not appear to have a defined mode in the KDE sampled variables.	70

LIST OF FIGURES

4.17	Joint PDFs between the outputs used in the 8-node network, which have a negative flow in the KDE sampled variables.	71
4.18	Joint PDFs between the inputs and outputs used in the 8-node network, which present a wide dispersion along second variable.	72
4.19	Joint PDFs between the inputs and outputs used in the 8-node network, which present a linear behavior, although with different dispersions among them.	73
4.20	Model results using only the loss associated with nodal flow predictions in the 8-node network.	75
4.21	Model results using only the loss associated with nodal flow predictions in the 8-node network.	76
4.22	Model results using only the loss associated with nodal flow predictions in the 8-node network.	77

Chapter 1

Introduction

1.1 Justification

Natural gas is an energy source that has gained great relevance worldwide, due to two fundamental causes. Firstly, it has been observed that a country's economic growth is closely related to its energy consumption [1]. Therefore, as nations develop and grow economically, it is expected that they will seek energy security to meet their own demand and continue their progress without interruptions. The second major motivation for the use of natural gas is its lower greenhouse gas emissions compared to other fuels, making it an attractive choice, especially in a context where there is a growing interest in environmental care. Natural gas emits fewer greenhouse gases compared to other fossil fuels, making it a favorable option for climate change mitigation [2]. In this context, the natural gas constitutes an energy source more efficient and less polluting than coal and oil [3], that supports heating and electricity for the intensive demand of houses and industry [4].

According to the U.S. Energy Information Administration (EIA), global demand for natural gas is projected to increase steadily through 2050, driven by population growth, rising incomes, and industrial expansion in emerging regions. In most modeled scenarios, demand for natural gas rises by between 2% and 10% by 2030 and between 11% and 57% by 2050, relative to 2022 levels. Despite significant gains in renewables and efficiency, natural gas continues to play a critical role in meeting the world's growing energy needs.[5].

In Colombia, natural gas remains a cornerstone of national energy planning, with its importance reaffirmed by the *Plan de Abastecimiento de Gas Natural (PAGN)*. This

CHAPTER 1. INTRODUCTION

plan incorporates the technical recommendations made by the Unidad de Planeación Minero-Energética (UPME) in the 2019–2028 study and continues to guide infrastructure priorities. According to the updated projections from UPME (June 2021), natural gas demand is expected to grow by 17% between April 2021 and December 2035, reflecting an average annual growth rate of approximately 1.18%. This demand projection includes aggregated consumption from sectors such as residential, industrial, tertiary, transportation, petrochemical, and compression. Notably, more than 75% of the aggregated demand is concentrated in the industrial and residential sub-sectors, reinforcing the seasonal nature of consumption patterns, with increased usage in the latter months of each year aligned with economic activity trends. While demand from the oil and thermoelectric sectors has been revised downward in medium and low scenarios—due to increased energy efficiency and favorable hydrological forecasts—potential deficits in supply between 2021 and 2030 have been identified. These gaps are expected to be addressed primarily through imported and regasified LNG from facilities like SPEC in Cartagena. Natural gas remains a key energy source for Colombia, balancing reliability, lower environmental impact compared to other fossil fuels, and its strategic role in enabling a gradual transition toward cleaner energy sources [6].

Although most of the country's electricity demand is commonly met by hydroelectric plants [7], this type of generation presents a significant source of uncertainty in the energy system since its effectiveness and generation capacity are directly linked to the country's climatic and meteorological conditions, especially in extreme cases such as the El Niño phenomenon [8]. Variations in precipitation, droughts, or floods can have a significant impact on the availability of water for hydroelectric power production, affecting the balance between supply and demand in the electrical system [9]. Additionally, the increase in energy demand and the transition to renewable energy sources pose significant challenges in the efficient and reliable transportation of gas. Optimizing the natural gas transportation system, considering the uncertainty associated with renewable energy generation and demand variability, is essential to ensure a reliable, sustainable, and environmentally friendly energy supply [10].

Therefore, it is necessary for the country not only to have a national gas transportation system, but also to ensure that it is operated as efficiently as possible, in order to make the best use of available natural resources. In the Colombian context, natural gas is a very important energy source as it is used in various sectors such as residential, commercial, industrial, and thermal [11]. It is especially in the latter sector that this fuel becomes more relevant during dry seasons, as it is when reservoir levels drop and thus hydroelectric power generation decreases. This problem is exacerbated in years

when the El Niño phenomenon occurs [12], making it of great interest to have tools that allow for the optimal injection and transportation of natural gas to fully meet demand.

1.2 Problem statement

Natural gas transportation is an integral part of the natural gas industry, relying on a pipeline network to transfer natural gas from various sources to consumers, fulfilling their demand. In general, natural gas transmission systems are composed of four fundamental elements: injection fields, responsible for injecting the hydrocarbon from extraction fields or regasification plants into the system; pipelines, which transport the gas from a sending node to a receiving node; compressors, which are responsible for raising the pressure at the outlet node relative to the inlet node; and end user, which are the main consumers of natural gas [13]. Ensuring gas flow to meet end-user demand, minimizing network operating costs, and maintaining system elements within appropriate technical operating limits are critical factors in natural gas transportation. Coordinating these factors requires efficient solutions of optimization problems with a large number of variables and different nature constraints [14].

The optimization problem consists on finding the best operational configurations to meet consumer demand while ensuring the technical and physical constraints of the natural gas transportation system. It must also be considered that these transportation systems are usually interconnected with electricity systems since the latters usually require natural gas as fuel for the thermal power plants. These power plants are significant natural gas consumers, relying on a steady gas supply to generate electricity [15]. In Colombia, despite holding 70% of hydroelectric plants, the remainder consists primarily of thermoelectric plants [16]. These thermoelectric plants are key to complementing the hydro plants to meet energy demand, especially during periods of drought, e.g., during El Niño phenomenon when reduced water availability limits hydroelectric generation [17]. As other studies have shown, variations in rainfall, droughts, or floods in countries with significant hydroelectric power plants can significantly affect water availability for hydropower production [18].

The above situation necessitates solving the optimization problem multiple times to ensure the system's correct operation across various scenarios. Consequently, this process takes considerable time and is both resource-intensive and time-consuming. Despite the high computational cost of each model execution, the resulting solutions are not utilized in subsequent optimization processes, even in similar operational scenarios. Therefore, there is a pressing need to develop a machine learning strategy that leverages

historical solutions to provide faster responses to different operational scenarios by learning from past optimization outcomes. However, the effectiveness of such a strategy also depends on how accurately the underlying physical components of the system are modeled—particularly the transmission pipelines, which pose significant challenges due to their nonlinear behavior.

Although production fields, compressors, and end users of natural gas are well-represented, modeling transmission pipelines remains complex due to the nonlinear relationship between flow and pressures at its ending nodes. This complexity arises from the Weymouth equation, which includes a nonconvex and discontinuous sign function that determines flow direction based on differential pressure. These nonconvexities introduce discontinuities lead to numerical issues and optimization instability [19, 20]. Various authors have approached the challenge posed by the Weymouth equation differently. One of the most widely accepted methods involves approximating this equation due to its inherent complexity and nonconvex nature. However, since it is an approximation, this solution introduces errors that impact the accuracy of optimization outcomes. Mitigating these errors remains critical for further research and development in natural gas transportation systems [13].

This research seeks to address these challenges by developing a machine learning-based strategy that leverages solutions from past optimizations to provide rapid, reliable predictions for various operational scenarios. Specifically, this thesis explores using Graph Neural Network (GNN) models and MPCC-based optimization formulations as complementary tools. The GNN model, by learning the structure and patterns from historical optimization outcomes, enables faster scenario evaluations while maintaining acceptable error margins. Furthermore, the Mathematical Programs with Complementarity Constraints (MPCC) approach introduces an accurate modeling of the Weymouth equation, enhancing the fidelity of flow and pressure calculations without compromising computational efficiency.

1.2.1 Objectives

1.2.2 General Objective

To develop an optimization tool that integrates knowledge of the gas transportation network topology, a suitable approximation of the Weymouth equation and stochastic optimization techniques to address the gas transportation task taking into account the uncertainties related to hydroelectric generation and the growth of alternative energy sources.

1.2.3 Specific Objectives

- Design a Graph Neural Networks-based approach of regression that integrates knowledge of natural gas network topology to reduce computational time for operation estimation.
- Develop an optimization model for natural gas transportation systems that takes into account the Weymouth equation for reducing that reduces the approximation error in pipeline gas flow calculations.
- Develop a stochastic gas flow dispatch optimization strategy that quantifies the uncertainty in the objective variables and decision variables associated with the operation of the gas system taking into account the constraints of the transportation problem.

Chapter 2

Natural Gas System Prediction Using Graph Neural Networks

2.1 Mathematical framework

2.1.1 Graph definition

A graph G is a mathematical structure that represents a set of interconnected objects. These objects are known as vertices (or nodes), denoted by the set V , and the connections between them are called edges (or arcs), denoted by the set E . Formally, a graph is defined as an ordered pair $G = (V, E)$, where V is a non-empty set of vertices, and $E \subseteq \{(u, v) \mid u, v \in V(G), u \neq v\}$ is the set of edges, where each edge connects two distinct vertices [21].

Graphs can be categorized based on the properties of their edges. An undirected graph has edges that do not have a direction, so the pair $(u, v) = (v, u)$ represents an edge that simply connects vertices u and v . In contrast, in a directed graph (or digraph), each edge $(u, v) \in E$ has a direction, meaning it goes from vertex u to vertex v . This implies that $(u, v) \neq (v, u)$ unless $u = v$ [22].

In Figure 2.1, two graphs are represented, each composed of four nodes labeled 1, 2, 3, and 4, and six edges labeled A , B , C , D , E , and F . The difference between them lies in the type of graph they represent. For example, in Figure 2.1a, the edge C connects nodes 2 and 4. However, in Figure 2.1b, this connection provides additional information: a direction, which, in the context of this study, could represent the direction of a specific element, such as electric power or gas flow.

A graph can be represented in various ways using matrices, each capturing different

**CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH
NEURAL NETWORKS**

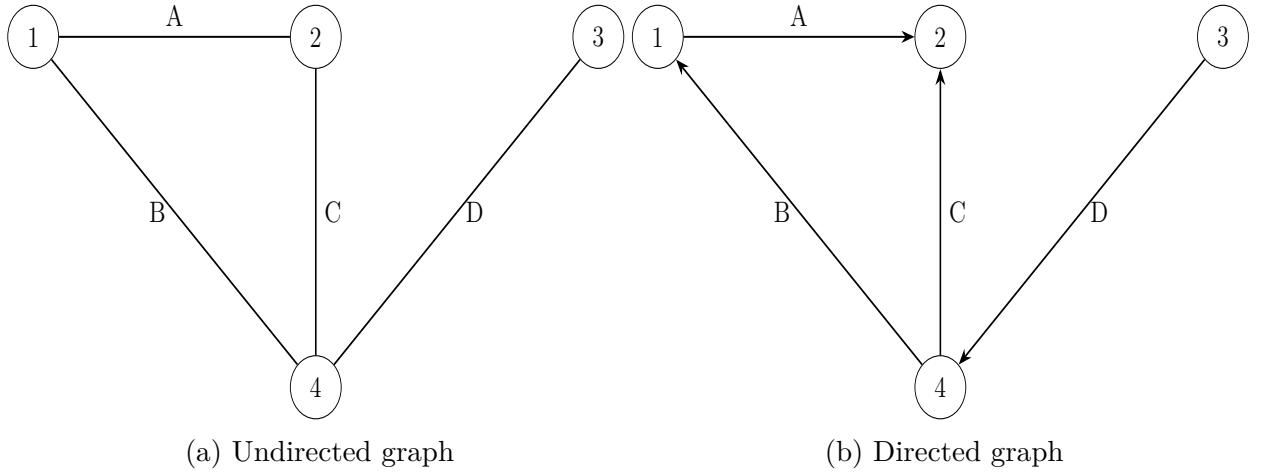


Figure 2.1: Types of graphs

aspects of the graph structure. The two most common matrix representations are the adjacency matrix and the incidence matrix.

The adjacency matrix of a graph is a square matrix used to represent the connections between vertices [23]. For a graph G with n vertices, the adjacency matrix A is an $n \times n$ matrix where the entry a_{ij} is defined as follows:

$$a_{ij} = \begin{cases} 1 & \text{if there is an edge from vertex } u \text{ to vertex } v, \\ 0 & \text{otherwise.} \end{cases} \quad (2.1)$$

For a directed graph, the adjacency matrix captures the direction of the edges. Below is the adjacency matrix for the directed graph shown earlier:

$$\mathbf{A} = \begin{pmatrix} 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{pmatrix}$$

The incidence matrix of a graph represents the relationship between vertices and edges [23]. For a graph G with n vertices and m edges, the incidence matrix I is an $n \times m$ matrix where the entry i_{ij} is defined as follows:

$$b_{ij} = \begin{cases} 1 & \text{if vertex } i \text{ is the starting point of edge } j \text{ in a directed graph,} \\ -1 & \text{if vertex } i \text{ is the endpoint of edge } j \text{ in a directed graph,} \\ 0 & \text{if vertex } i \text{ is not connected to edge } j. \end{cases} \quad (2.2)$$

For the directed graph previously described, the incidence matrix is given by:

$$\mathbf{B} = \begin{pmatrix} 1 & -1 & 0 & 0 \\ -1 & 0 & -1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 1 & -1 \end{pmatrix}$$

2.1.2 Multi-Layered Perceptrons

A Multilayer Perceptron (MLP) is a fundamental type of artificial neural network, often regarded as one of the building blocks of deep learning. At its core, an MLP consists of multiple layers of nodes, or neurons, where each layer is fully connected to the next one. The architecture typically includes an input layer, one or more hidden layers, and an output layer, as can be seen in the Figure 2.2.

The neurons in each layer are connected to the neurons in the subsequent layer through weighted connections, the key parameters learned during the training process [24]. One of the most significant properties of an MLP is its ability to work as a universal approximator. Given sufficient neurons in the hidden layers, an MLP can approximate any continuous function to an arbitrary degree of accuracy, provided the network is correctly trained [25].

Mathematically, an MLP can be defined as follows. Let $\mathbf{x} \in \mathbb{R}^n$ the input vector, where n is the number of features. The output of each neuron in the first hidden layer is calculated as:

$$\mathbf{z}^{(1)} = \sigma(\mathbf{W}^{(1)}\mathbf{x} + \mathbf{b}^{(1)}) \quad (2.3)$$

where $\mathbf{W}^{(1)} \in \mathbb{R}^{m_1 \times n}$ is the weighting matrix for the first hidden layer, with m_1 being the number of neurons in this layer, $\mathbf{b}^{(1)} \in \mathbb{R}^{m_1}$ is the bias vector, and $\sigma(\cdot)$ is the activation function, typically a non-linear function such as a ReLU (Rectified Linear Unit) or sigmoid function.

This process is repeated for each subsequent hidden layer k , where the output of the k -th layer is given by:

CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH NEURAL NETWORKS

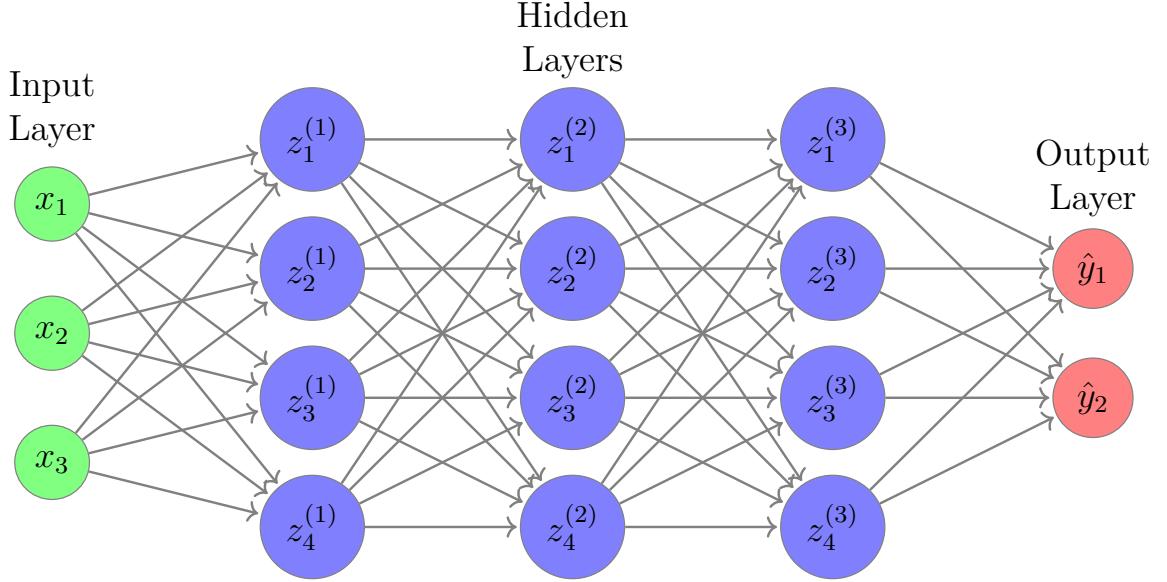


Figure 2.2: General diagram of a multilayer perceptron, showing the input layers in green, the hidden layers in blue and the outputs in red.

$$\mathbf{z}^{(k)} = \sigma(\mathbf{W}^{(k)}\mathbf{z}^{(k-1)} + \mathbf{b}^{(k)}) \quad \forall i \in \{2, \dots, L-1\} \quad (2.4)$$

Here, $\mathbf{W}^{(k)} \in \mathbb{R}^{m_k \times m_{k-1}}$ represents the weight matrix connecting layer $k-1$ to layer k , $\mathbf{b}^{(k)} \in \mathbb{R}^{m_k}$ is the bias vector for layer k , and $\mathbf{z}^{(k-1)}$ is the output of the previous layer.

Finally, the output layer produces the final prediction $\hat{\mathbf{y}}$:

$$\hat{\mathbf{y}} = \sigma(\mathbf{W}^{(L)}\mathbf{z}^{(L-1)} + \mathbf{b}^{(L)}) \quad (2.5)$$

where L denotes the number of layers in the network, including the input and output layers. Depending on the nature of the problem (e.g., classification or regression), the activation function $\sigma(\cdot)$ used in the output layer can vary, with softmax being common in multi-class classification problems, and a linear activation for regression tasks. The entire MLP is trained using a process called backpropagation, combined with an optimization algorithm like gradient descent, to minimize a loss function $\mathcal{L}(\mathbf{y}, \hat{\mathbf{y}})$, which compares the true outputs \mathbf{y} and the predicted outputs $\hat{\mathbf{y}}$.

CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH NEURAL NETWORKS

2.1.3 Graph Neural Networks

In recent years, Graph Neural Networks (GNNs) have emerged as a powerful tool in machine learning, particularly for tasks involving data that can be naturally represented as graphs. Graphs are a universal data structure that can model various systems in numerous fields, including social networks, biological networks, knowledge graphs, and physical systems. Because of their ability to represent relationships and interactions between entities, graphs are used extensively to model complex structures where the data points are not independent but interconnected [26].

GNNs are important because they can directly operate on graph-structured data, extending neural networks' success from grid-like data structures, such as images and sequences, to more general and irregular structures [27]. Traditional neural networks, like Convolutional Neural Networks (CNNs) or Recurrent Neural Networks (RNNs), are designed to work with data that has a fixed structure. However, many real-world problems involve data that can be better described by graphs, where nodes represent entities and edges represent relationships between those entities [28].

Graph Neural Networks can be broadly defined as a class of neural networks designed to perform inference on data described by graphs. Formally, let $G = (V, E)$ represent a graph, where V is the set of nodes (or vertices) and E is the set of edges. Each node $v \in V$ can be associated with a feature vector $\mathbf{x}_v \in \mathbb{R}^{D_v}$, where D_v is the number of features per node, and each edge $(u, v) \in E$ may have an associated weighting or feature vector $\mathbf{e}_{uv} \in \mathbb{R}^{D_e}$, where D_e is the number of features per edge. The goal of a GNN is to learn a representation for each node (or sometimes for the entire graph) by aggregating and transforming the feature information from the node's local neighborhood in the graph.

To move from the abstract concept to a practical implementation, the specific functions used for updating and aggregating node features must be defined [29]. In the GNN framework, message passing is understood as a series of iterations in which each node updates its representation by exchanging information with its neighbors.

The basic message passing operation, which simplifies the original GNN model proposed by [30], is expressed by the following equation:

$$\mathbf{h}_u^{(k)} = \sigma \left(\mathbf{W}_{\text{self}}^{(k)} \mathbf{h}_u^{(k-1)} + \mathbf{W}_{\text{neigh}}^{(k)} \sum_{v \in \mathcal{N}(u)} \mathbf{h}_v^{(k-1)} + \mathbf{b}^{(k)} \right) \quad (2.6)$$

In this equation:

CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH NEURAL NETWORKS

- $\mathbf{h}_u^{(k)} \in \mathbb{R}^{D_h^{(k)}}$ represents the updated feature vector of node u at layer k , where $D_h^{(k)}$ is the dimensionality of the hidden representation at that layer.
- The term $\mathbf{W}_{\text{self}}^{(k)} \mathbf{h}_u^{(k-1)}$, where $\mathbf{W}_{\text{self}}^{(k)} \in \mathbb{R}^{D_h^{(k)} \times D_h^{(k-1)}}$ and $\mathbf{h}_u^{(k-1)} \in \mathbb{R}^{D_h^{(k-1)}}$, transforms the node's own feature vector from the previous layer, enabling the node to retain and modify its own information.
- The term $\mathbf{W}_{\text{neigh}}^{(k)} \sum_{v \in \mathcal{N}(u)} \mathbf{h}_v^{(k-1)}$, where $\mathbf{W}_{\text{neigh}}^{(k)} \in \mathbb{R}^{D_h^{(k)} \times D_h^{(k-1)}}$, aggregates the feature vectors of the neighboring nodes v in the set $\mathcal{N}(u)$, and then applies a transformation via the weighting matrix.
- $\mathbf{b}^{(k)} \in \mathbb{R}^{D_h^{(k)}}$ is a bias term that can be added to the weighted sum, though it is sometimes omitted for simplicity.
- The non-linear function $\sigma(\cdot)$ is elementwise applied to introduce non-linearity into the model, which is essential for capturing complex patterns in the data.

In the context of Graph Neural Networks (GNNs), a Graph Convolutional Network (GCN) is a specialized model that applies the concept of convolution, widely used in image processing, to graphs. First introduced by [31], GCNs offer a method to perform deep learning on graph-structured data by extending traditional convolution operations to the irregular domain of graphs.

Specifically, the adjacency matrix $\tilde{\mathbf{A}}$ is defined as:

$$\tilde{\mathbf{A}} = \mathbf{A} + \mathbf{I} \quad (2.7)$$

with \mathbf{A} is the original adjacency matrix, and \mathbf{I} is the identity matrix. The identity matrix \mathbf{I} ensures that each node considers its own features when aggregating information from its neighbors.

The degree matrix $\tilde{\mathbf{D}}$ is defined as:

$$\tilde{D}_{vv} = \sum_{v' \in V} \tilde{A}_{vv'} \quad (2.8)$$

where V represents the set of all nodes in the graph. The diagonal entries of $\tilde{\mathbf{D}}$ correspond to the degree of each node, adjusted to account for the added self-loops.

The fundamental idea behind GCNs is to create a spectral filter that operates on graph data. The filter's purpose is to combine features from a node's local neighborhood, taking into account the graph's structure. This process is mathematically formalized in the following way:

$$\mathbf{H} = \sigma \left(\tilde{\mathbf{D}}^{-\frac{1}{2}} \tilde{\mathbf{A}} \tilde{\mathbf{D}}^{-\frac{1}{2}} \mathbf{X} \Theta \right) \quad (2.9)$$

Here:

- $\mathbf{H} \in \mathbb{R}^{N_v \times D_h}$ represents the matrix of node representations after applying the GCN layer. Each row $\mathbf{h}_u \in \mathbb{R}^{D_h}$ in \mathbf{H} corresponds to the updated feature vector for node u .
- $\mathbf{X} \in \mathbb{R}^{N_v \times D_v}$ is the matrix of input node features, where each row $\mathbf{x}_u \in \mathbb{R}^{D_v}$ corresponds to the feature vector for node u before applying the GCN layer.
- $\sigma(\cdot)$ denotes a non-linear activation function elementwise applied to introduce non-linearity into the model.
- $\tilde{\mathbf{A}} \in \mathbb{R}^{N_v \times N_v}$ is the adjacency matrix of the graph, with added self-loops to account for the node itself in the aggregation.
- $\tilde{\mathbf{D}} \in \mathbb{R}^{N_v \times N_v}$ is the degree matrix of the graph, modified to include the self-loops. The degree matrix is diagonal, with each diagonal entry $\tilde{D}_{ii} \in \mathbb{R}$ representing the degree of node i in the graph.
- $\Theta \in \mathbb{R}^{D_v \times D_h}$ is a matrix of trainable parameters, which is learned during the training process to optimize the model's performance.

The expression $\tilde{\mathbf{D}}^{-\frac{1}{2}} \tilde{\mathbf{A}} \tilde{\mathbf{D}}^{-\frac{1}{2}}$ is a normalized version of the adjacency matrix, ensuring that the eigenvalues of the operation are bounded between 0 and 1. This normalization step is crucial as it prevents issues such as exploding or vanishing gradients during the training of deep networks.

2.1.4 Convolution with Edge-Node Switching (Cens Block)

Graph Convolutional Networks (GCNs) have demonstrated considerable success in various graph-based machine learning tasks, particularly in their ability to generalize convolution operations to non-Euclidean data structures like graphs [32]. GCNs operate by aggregating features from a node's neighbors, thereby capturing local neighborhood information and propagating it through the network layers. Despite their effectiveness, GCNs possess certain limitations that hinder their performance in more complex scenarios.

CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH NEURAL NETWORKS

One notable limitation of GCNs is their reliance on node features during the convolution process, which overlooks the information encoded in edge features. This limitation prevents the model from fully capturing the complexity of the graph structure and may reduce its overall effectiveness [33]. Furthermore, GCNs typically aggregate information from immediate neighbors only, which can limit their ability to capture long-range dependencies in large or densely connected graphs. This restriction can lead to an oversimplified representation of the graph structure, particularly in cases where the graph contains intricate patterns that require deeper and more nuanced analysis [34].

To overcome the limitations of traditional GCNs, which focus primarily on node features, CensNet introduces a novel approach that integrates both node and edge features into the graph convolution process. The CensNet framework consists of two primary types of layers: the *node layer* and the *edge layer*. These layers work in concert to update node and edge embeddings alternately, leveraging the information from both nodes and edges in the graph [35].

The propagation rules in CensNet are designed to incorporate edge features into the convolution process, enabling a more comprehensive feature propagation across the graph. We define the normalized node adjacency matrix with self-loops as follows:

$$\tilde{\mathbf{A}}_v = \mathbf{D}_v^{-\frac{1}{2}} (\mathbf{A}_v + \mathbf{I}_{N_v}) \mathbf{D}_v^{-\frac{1}{2}}, \quad (2.10)$$

In this expression $\mathbf{A}_v \in \mathbb{R}^{N_v \times N_v}$ is the adjacency matrix for the nodes, and $\mathbf{I}_{N_v} \in \mathbb{R}^{N_v \times N_v}$ is the identity matrix that introduces self-loops. The matrix $\mathbf{D}_v \in \mathbb{R}^{N_v \times N_v}$ is the diagonal degree matrix of $\mathbf{A}_v + \mathbf{I}_{N_v}$, where each diagonal entry corresponds to the degree of a node (i.e., the number of neighbors, including itself). The term N_v denotes the number of nodes in the graph. Consequently, the sum $\mathbf{A}_v + \mathbf{I}_{N_v}$ is a matrix of size $N_v \times N_v$, and so is \mathbf{D}_v .

Node Layer Propagation: In the $(l+1)$ -th layer, the node features are updated using the following propagation rule:

$$\mathbf{H}_v^{(l+1)} = \sigma \left(\mathbf{T} \Phi \left(\mathbf{H}_e^{(l)} \mathbf{p}_e \right) \mathbf{T}^\top \odot \tilde{\mathbf{A}}_v \mathbf{H}_v^{(l)} \mathbf{W}_v \right) \quad (2.11)$$

With,

- $\mathbf{T} \in \{0, 1\}^{N_v \times N_e}$ is an incidence matrix that represents the connections between nodes and edges. Each element $T_{v,e}$ indicates whether edge e connects to node v . Specifically, if edge e is connected to node v , then $T_{v,e} = 1$; otherwise, $T_{v,e} = 0$. Given that each edge is formed by two nodes, every column of the matrix \mathbf{T} will

CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH NEURAL NETWORKS

have exactly two elements equal to 1, corresponding to the two nodes that the edge connects.

- $\mathbf{H}_e^{(l)} \in \mathbb{R}^{N_e \times D_e}$ is the edge feature matrix from the l -th layer, where D_e is the dimensionality of the edge features. $\mathbf{p}_e \in \mathbb{R}^{D_e}$ is a learnable vector of weights that projects the edge features into a scalar value per edge. The matrix-vector product $\mathbf{H}_e^{(l)} \mathbf{p}_e \in \mathbb{R}^{N_e}$ results in a vector with one scalar value per edge. The operation $\text{diag}(\mathbf{H}_e^{(l)} \mathbf{p}_e) \in \mathbb{R}^{N_e \times N_e}$ converts this vector into a diagonal matrix where each element of the vector is placed on the diagonal.
- The Hadamard product, denoted by \odot , represents element-wise multiplication between matrices. In this context, it combines the transformed edge features with the node adjacency matrix, integrating information from both the original graph and its line graph.
- $\tilde{\mathbf{A}}_v \in \mathbb{R}^{N_v \times N_v}$ is the normalized adjacency matrix for nodes, as shown in eq. (2.10), where $\mathbf{A}_v \in \mathbb{R}^{N_v \times N_v}$ is the original node adjacency matrix and $\mathbf{I}_{N_v} \in \mathbb{R}^{N_v \times N_v}$ is the identity matrix that introduces self-loops. This normalization ensures that the contributions from each node's neighbors are appropriately scaled.
- $\mathbf{H}_v^{(l)} \in \mathbb{R}^{N_v \times D_v}$ represents the node feature matrix from the l -th layer. $\mathbf{W}_v \in \mathbb{R}^{D_v \times D'_v}$ is a learnable weight matrix that is applied to the node features during the propagation process.
- The activation function σ (typically a non-linear function such as ReLU) is applied element-wise to the resulting matrix to introduce non-linearity into the model.

This expression can be understood as a mechanism for integrating node and edge information. The matrix \mathbf{T} is responsible for transferring edge features into the node domain, allowing these edge-derived features to be merged with the normalized node adjacency matrix $\tilde{\mathbf{A}}_v$.

Edge Layer Propagation: Similarly, the normalized edge adjacency matrix is defined as:

$$\tilde{\mathbf{A}}_e = \mathbf{D}_e^{-\frac{1}{2}} (\mathbf{A}_e + \mathbf{I}_{N_e}) \mathbf{D}_e^{-\frac{1}{2}}, \quad (2.12)$$

where $\mathbf{D}_e \in \mathbb{R}^{N_e \times N_e}$ is the degree matrix corresponding to the edge adjacency matrix $\mathbf{A}_e + \mathbf{I}_{N_e}$, with $\mathbf{A}_e \in \mathbb{R}^{N_e \times N_e}$ and $\mathbf{I}_{N_e} \in \mathbb{R}^{N_e \times N_e}$. The matrix $\tilde{\mathbf{A}}_e \in \mathbb{R}^{N_e \times N_e}$ serves as

CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH NEURAL NETWORKS

the normalized version of the edge adjacency matrix, similarly to the node adjacency normalization. This normalization ensures that the influence of each edge is scaled appropriately, which is crucial for the stability of the propagation process.

The propagation rule for edge features is defined as follows:

$$\mathbf{H}_e^{(l+1)} = \sigma \left(\mathbf{T}^\top \Phi \left(\mathbf{H}_v^{(l)} \mathbf{P}_v \right) \mathbf{T} \odot \tilde{\mathbf{A}}_e \mathbf{H}_e^{(l)} \mathbf{W}_e \right), \quad (2.13)$$

In this expression, the following components are involved:

- $\mathbf{T}^\top \in \{0, 1\}^{N_e \times N_v}$ is the transpose of the binary transformation matrix $\mathbf{T} \in \{0, 1\}^{N_v \times N_e}$ used in the node layer propagation. The matrix \mathbf{T}^\top maps the node features back into the edge domain, allowing the edge features to be updated based on the node information.
- $\mathbf{H}_v^{(l)} \in \mathbb{R}^{N_v \times D_v}$ is the node feature matrix from the l -th layer, and $\mathbf{p}_v \in \mathbb{R}^{D_v}$ is a learnable vector that projects each node's features to a scalar. The operation $\mathbf{H}_v^{(l)} \mathbf{p}_v \in \mathbb{R}^{N_v}$ results in a scalar per node. The function $\Phi(\cdot)$ produces the diagonal matrix $\Phi \left(\mathbf{H}_v^{(l)} \mathbf{p}_v \right) \in \mathbb{R}^{N_v \times N_v}$, which is used to scale each node's influence in the projection.
- The matrix product $\mathbf{T}^\top \Phi \left(\mathbf{H}_v^{(l)} \mathbf{p}_v \right) \mathbf{T} \in \mathbb{R}^{N_e \times N_e}$ maps this node-level scalar information into the edge domain. This matrix has the same dimensions as the normalized edge adjacency matrix $\tilde{\mathbf{A}}_e \in \mathbb{R}^{N_e \times N_e}$, which ensures the Hadamard product is dimensionally valid.
- $\mathbf{H}_e^{(l)} \in \mathbb{R}^{N_e \times D_e}$ represents the edge feature matrix from the l -th layer, while $\mathbf{W}_e \in \mathbb{R}^{D_e \times D'_e}$ is a learnable weight matrix. Their product $\mathbf{H}_e^{(l)} \mathbf{W}_e \in \mathbb{R}^{N_e \times D'_e}$ results in the updated edge features before aggregation, where D'_e denotes the dimensionality of the edge features in the $l + 1$ -th layer.
- The Hadamard product \odot element-wise multiplies the matrix $\mathbf{T}^\top \Phi \left(\mathbf{H}_v^{(l)} \mathbf{p}_v \right) \mathbf{T} \in \mathbb{R}^{N_e \times N_e}$ with $\tilde{\mathbf{A}}_e \in \mathbb{R}^{N_e \times N_e}$, producing a filtered adjacency matrix in the edge domain.
- The resulting matrix (after Hadamard product) multiplies the transformed edge features $\mathbf{H}_e^{(l)} \mathbf{W}_e \in \mathbb{R}^{N_e \times D'_e}$, resulting in an output matrix in $\mathbb{R}^{N_e \times D'_e}$, consistent with the desired shape of $\mathbf{H}_e^{(l+1)}$.

CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH NEURAL NETWORKS

- As in the node layer propagation, the activation function σ is applied element-wise to introduce non-linearity.

This propagation rule updates the edge embeddings by integrating information from the node features and the edge structure, thereby enhancing the expressiveness of the edge representations. The alternating updates between node and edge embeddings allow the model to effectively bridge signals across nodes and edges, resulting in more informative graph embeddings compared to other neural network approaches.

2.1.5 Gas flow estimation through CensNet

The natural gas system consists of a network of production centers, pipelines, compressor stations, storage facilities, and distribution points that ensure reliable gas delivery from producers to consumers. Mathematically, this system can be represented as a directed graph defined as $G = (V, E)$ where V is the set of units within the gas system, and E is the set of different elements linking them. This set of units includes gas supply nodes or wells $\mathcal{W} \subset V$, gas demand nodes or users $\mathcal{U} \subset V$, and gas storage facilities $\mathcal{S} \subset V$. Similarly, the set of directed gas adjacency edges $\mathcal{A} = \{(n, m) \mid n, m \in V\} \subset E$ delineates the network structure through two kinds of transmission elements: transport pipelines $\mathcal{P} = \{p = (n, m) \mid n, m \in V\}$ and compressing stations $\mathcal{C} = \{c = (n, m) \mid n, m \in V\}$, so that $\mathcal{P} \cup \mathcal{C} = \mathcal{A}$ and $\mathcal{P} \cap \mathcal{C} = \emptyset$.

Natural gas transportation requires coordination to manage the flow through the different elements to maintain safe operating ranges. In optimizing this network, mathematical models minimize overall operating costs associated with the various stages of natural gas transportation, compression, storage, and handling unsupplied demand, ensuring compliance with technical and physical constraints. The cost function to minimize is expressed as:

$$\min_{\mathcal{P}, \mathcal{F}} \quad \sum_{t \in \mathcal{T}} \sum_{w \in \mathcal{W}} C_w^t f_w^t + \sum_{p \in \mathcal{P}} C_p^t f_p^t + \sum_{c \in \mathcal{C}} C_c^t f_c^t + \sum_{u \in \mathcal{U}} C_u^t f_u^t \quad (2.14)$$

Here, \mathcal{T} denotes the set of discrete time periods considered in the optimization model. The term $\sum_{w \in \mathcal{W}} C_w^t f_w^t$ represents the total cost of gas production at the wells, where C_w^t denotes the cost per unit flow of gas at a specific well w during time period t , and f_w^t corresponds to the flow of gas from well w . Similarly, the transportation of gas through pipelines is captured by the term $\sum_{p \in \mathcal{P}} C_p^t f_p^t$, where C_p^t is the cost per unit flow through pipeline p during time period t , and f_p^t represents the flow of gas through

CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH NEURAL NETWORKS

pipeline p . In addition, the total cost associated with gas compression at compressor stations is accounted for by $\sum_{c \in \mathcal{C}} C_c^t f_c^t$, where C_c^t is the cost per unit flow at compressor station c during time period t , and f_c^t is the flow of gas through compressor station c . Beyond production, transportation, and compression, the model also considers the costs related to unmet gas demand. The term $\sum_{u \in \mathcal{U}} C_u^t f_u^t$ reflects the penalty cost associated with unsupplied gas demand, where C_u^t is the penalty cost per unit of unsupplied gas at location u during time period t , and f_u^t represents the volume of unmet demand.

The constraint set models the gas architecture of the transportation system and its technical limits: Equation (2.15) forces each production well to inject the flow $f_w^t \in \mathbb{R}^{N_v}$ over the technical minimum $\underline{f}_w^t \in \mathbb{R}^{N_v}$ and under the maximum capacity $\overline{f}_w^t \in \mathbb{R}^{N_v}$. Equation (2.16) upper-bounds the gas flow through pipelines $f_p^t \in \mathbb{R}^{N_e}$ to the structural capacity $\overline{f}_p^t \in \mathbb{R}^{N_e}$. Equation (2.17) ensures that the unsupplied demand $f_u^t \in \mathbb{R}^{N_v}$ is lower than the corresponding user demand $\overline{f}_u^t \in \mathbb{R}^{N_v}$. The nodal gas balance in Equation (2.18) guarantees that the gas entering the node n equals the gas leaving it.

$$\underline{f}_w^t \leq f_w^t \leq \overline{f}_w^t \quad \forall w \in \mathcal{W} \quad (2.15)$$

$$-\overline{f}_p^t \leq f_p^t \leq \overline{f}_p^t \quad \forall p \in \mathcal{P} \quad (2.16)$$

$$0 \leq f_u^t \leq \overline{f}_u^t \quad \forall u \in \mathcal{U} \quad (2.17)$$

$$\sum_{m:(m,n) \in \mathcal{A}} f_m^t = \sum_{m':(n,m') \in \mathcal{A}} f_{m'}^t \quad \forall n \in \mathcal{N}_f \quad (2.18)$$

The optimization model described above is used to generate flow scenarios across the network. These scenarios serve as supervised training data for a CensNet-based model that approximates the mapping between the structural and technical parameters of the network and the resulting gas flows. The CensNet architecture is designed to learn these mappings by taking as input a set of graph-based features and predicting the flow behavior directly through a regression task. Specifically, the network receives the following input data:

- **Node Features:** A matrix $\in \mathbb{R}^{N_v \times 3}$. Each node feature includes the lower and upper limits for injected flow, as well as demanded flow.
- **Node Laplacian:** An adjacency matrix of size $N_e \times N_e$ encoding the graph structure of the nodes.
- **Edge Laplacian:** A matrix of size $N_e \times N_e$ encoding the connections between edges.

CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH NEURAL NETWORKS

- **Incidence Matrix:** A matrix of size $N_v \times N_e$ representing the node-edge incidence relationship, mapping the flow of gas between nodes through edges.
- **Edge Features:** A matrix $\in \mathbb{R}^{N_e \times 5}$ that includes the features of pipelines and compressors in the gas network. Each edge feature includes the K constant, the maximum compression ratio β , and the upper and lower flow limits.

The model outputs include node-level predictions corresponding to the injected flow at each node and edge-level predictions representing the transported flow across the network edges.

2.1.6 Task-Dependent Loss Functions

The output layer and corresponding loss functions in CensNet are designed to be task-dependent. For regression tasks, the loss function can be formalized as a regularized mean square error (MSE) loss. The MSE loss measures the difference between the predicted outcomes and the actual values, providing a natural fit for regression problems.

We define the loss function for graph regression as follows:

$$\mathcal{L}(\Theta) = \sum_{r=1}^R \|Y_r - \hat{Y}_r\|_2^2 + \lambda \|\Theta\|_p, \quad (2.19)$$

where:

- $Y_r \in \mathbb{R}$ is the ground-truth value for the r -th regression target.
- $\hat{Y}_r \in \mathbb{R}$ is the predicted value for the same feature, computed from the final node representation of the graph.
- $\|Y_f - \hat{Y}_r\|_2^2$ is the squared error for feature r , and the sum is taken over all R output features.
- $\Theta \in \mathbb{R}^P$ is the set of learnable parameters in the model, and $\|\Theta\|_p$ denotes the L_p norm regularization term.
- $\lambda \in \mathbb{R}_+$ is a regularization coefficient that penalizes overly complex models to reduce overfitting.

*CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH
NEURAL NETWORKS*

2.2 Experimental Setup and Results

The generated samples served as training data for a GNN-based model to solve the natural gas transportation problem, which was designed as a faster alternative to the optimization-based model. This GNN model is built to focus on predicting node and edge-level characteristics, incorporating the structure of the network and its connectivity into the learning process.

In this experimental setup, different network operation scenarios were generated by perturbing the users' consumption values with added noise and subsequently solving each scenario using the linear constrained optimization model presented in the previous section. The noise levels range from 5% to 25%, applied to the parameters of the networks to simulate diverse operating conditions. The first network is a small-scale test network consisting of 8 nodes, while the second represents the Colombian natural gas transportation system, a more extensive and complex network consisting of 63 nodes. These networks were used to evaluate the performance of the proposed model under varying scenarios.

The model explicitly penalizes deviations in node and edge losses, which directly impact gas flow efficiency through the system. To achieve this, the architecture is structured as a CensNet-based neural networks, with customizable depth (number of layers), channels, and dense layers, ensuring flexibility in adapting to small-scale and large-scale networks, such as the Colombian system.

A general outline of the model can be seen in fig. 2.3 and the basic components of the model are explained below:

- **Normalization and Predense Layers:** The node and edge inputs receive feature-wise normalization to standardize the data. Following this, the inputs are passed through two dense layers, each with N channels. The purpose of these pre-dense layers is to transform the feature space before applying the convolutional layers, enabling the network to project the raw input data into a higher-dimensional latent space that facilitates more expressive and effective learning in the subsequent convolutional stages.
- **CensNet Blocks Layers:** The main body of the network consists of N convolutional blocks. Each block applies a CensNet convolution, which updates both node and edge features by considering the structural relationships encoded in the node and edge Laplacians, as well as the incidence matrix. Batch normalization follows each convolution to stabilize learning. This structure allows the model to

CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH NEURAL NETWORKS

capture complex interactions between nodes and edges and propagate information across the graph, learning how local features influence the broader system.

- **Post-dense Layer:** After passing through the convolutional blocks, the node and edge features are further processed by a series of dense layers. The number of dense layers N_{dense} is adjustable. These layers further refine the learned features, enabling the model to output node and edge-level predictions.
- **Losses and Outputs:** The final outputs of the network are the node-level and edge-level predictions. The node predictions correspond to the estimated flow at each node, while the edge predictions represent the flow along the edges. Both outputs are penalized based on their respective losses, which are calculated by comparing the predicted values to ground truth values and evaluating how well the physical constraints are respected.

The loss functions ensure that the model accurately predicts the node and edge flows while satisfying the physical constraints of the system. These constraints are essential for ensuring that the predicted flows are feasible within the operational limitations of the network.

- **Model Optimization:** The model is trained using backpropagation with the Adam optimizer. The training process involves minimizing the node and edge loss functions, which penalize incorrect flow predictions and deviations from the expected behavior of the network.

The network training was done under the following conditions: data was partitioned into training, validation, and test sets, with percentages of 60%, 20%, and 20% using 2000 samples for the 8-node network and 2400 for the 63-node network. The learning rate schedule followed an Exponential Decay approach, with an initial learning rate of 1×10^{-2} decay steps of 1000, and a decay rate of 0.9. The model was trained over 1500 epochs, ensuring the parameters had sufficient time to converge for both node- and edge-level predictions using a Leaky Relu activation function with an alpha parameter of 0.2.

The model utilized several key hyperparameters: $N_{channels}$, which corresponds to the units in the pre-dense and convolutional layers (CensNet), N_{Dense} , representing the number of post-dense layers, and N_{layers} , denoting the number of convolutional layers. Additionally, the model penalizes deviations in the network's response, specifically targeting MSE between the actual flow and the predicted flow at both the nodes and pipelines. Two tests were performed to determine the optimal set of hyperparameters.

CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH NEURAL NETWORKS

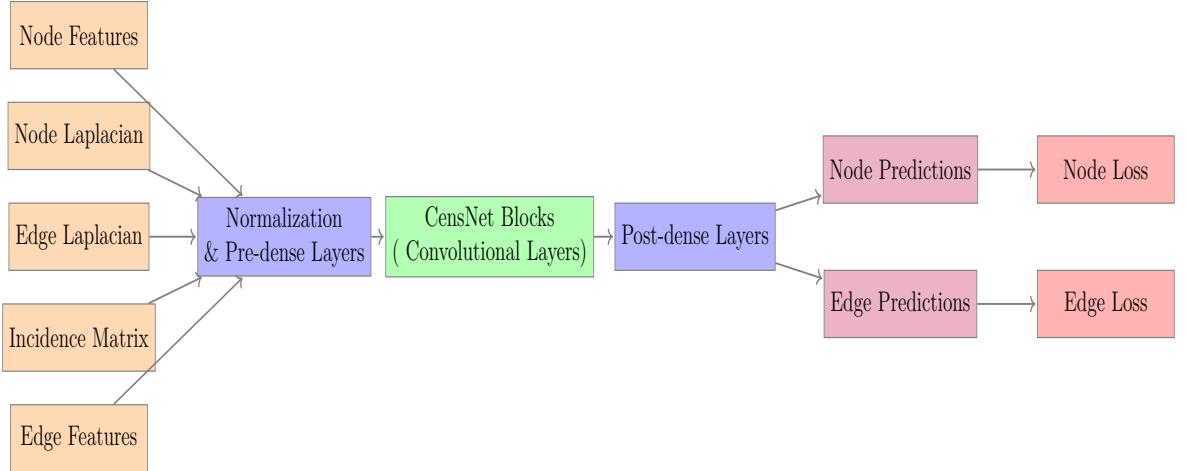


Figure 2.3: General outline of the CensNet-based model used.

The objective was to compare the effect of using different combinations of loss functions during training. In the first test, only the weight associated with the nodal flow loss was considered, while in the second test, both nodal and edge flow losses were included. A test using only the edge loss was not conducted, as it was considered inappropriate to disregard the nodal flow loss. This is because the nodal flows represent the injection and demand values, which are essential for the physical consistency of the system and are directly associated with the behavior of the network at each node. In each test, the hyperparameters were optimized using the open-source Optuna framework [36], with the following search space: N channels ranged from 16 to 64, N layers from 1 to 5, and N dense from 2 to 32.

2.2.1 Results

In this section, we present the results of the proposed GNN model, focusing on the relationship between the predicted outputs and the actual observed values in the natural gas transportation networks. The evaluation includes both the 8-node test network and the Colombian natural gas system, with the goal of assessing the model's ability to predict key parameters under varying operational conditions.

CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH NEURAL NETWORKS

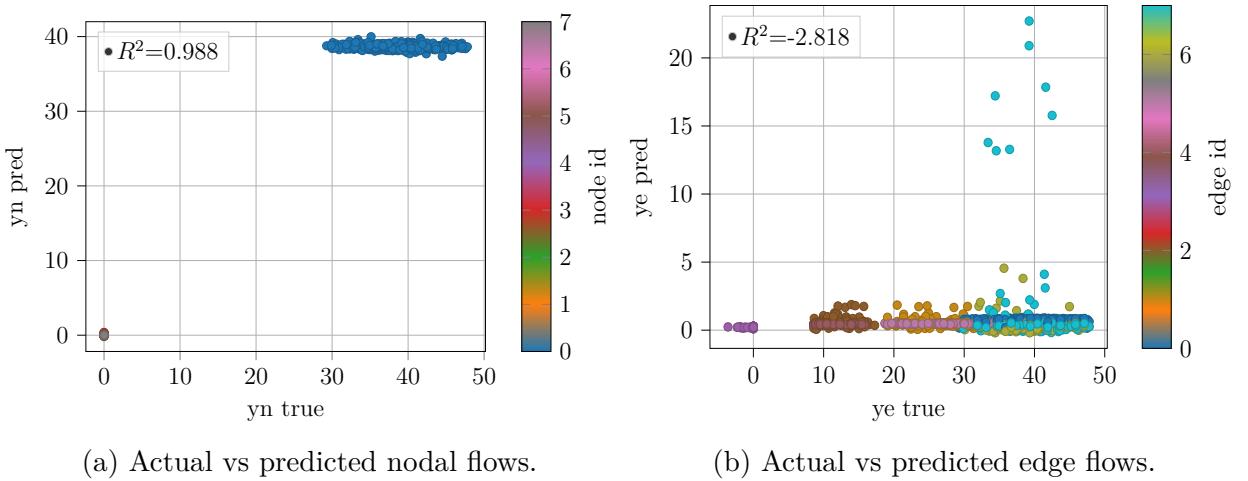


Figure 2.4: Model results using only the loss associated with nodal flow predictions in the 8-node network.

2.2.2 Case Study I: 8-node Network

As a result of the optimization process for this first test, the following hyperparameters were obtained: $N \text{ channels} = 21$, $N \text{ layers} = 5$, and $N \text{ dense} = 4$. With these optimized values, the model achieved an MSE of 1.98. In Figure 2.4a, a scatter plot illustrates the relationship between the actual values of gas generation at the nodes and the corresponding values predicted by the trained neural network, considering only the losses at the nodes. The plot highlights how effectively the network captures the fact that only one of the nodes in the system has gas generation. However, while the network successfully identifies the generating node, the predicted values exhibit less dispersion than the actual values, indicating that the model's predictions are more concentrated around a certain point.

Figure 2.4b displays the relationship between the actual gas flows through the edges and the predictions made by the neural network. In this case, the model struggled to predict the flow values accurately, demonstrating a significant deviation from the actual data. This result is not unexpected, as the model used in this experiment focused solely on the losses related to gas flows at the injection nodes without accounting for the gas transported through the edges. As such, the absence of edge-related loss consideration likely contributed to the poor prediction performance for edge flows.

To evaluate the performance of the optimization model and the GNN-based model, a t-test was performed, comparing the time each took to generate 100 predictions for

CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH NEURAL NETWORKS

new, unseen cases. The results showed a T-statistic of 14.94, 198 degrees of freedom and a p-value of 1.32e-34, indicating that the optimization model took significantly longer than the GNN-based model, confirming its higher computational cost.

In the next stage of the experiment, the model was updated to account for the loss associated with edge flow predictions. This allowed the network to better capture the dynamics of gas transportation across the entire network, not just at the nodes. In this case, the hyperparameter tuning revealed that the best combination was $N_{channels} = 44$, $N_{Layers} = 4$, and $N_{Dense} = 4$, with a test data loss of 2.02, where 1.996 corresponds to the loss associated with the prediction of flows injected at the nodes, and 0.207 corresponds to the loss related to the prediction of flows through the edges. Additionally, the MSE between the gas balance based on actual flows and predicted flows was calculated, resulting in a loss of 1.719. It is essential to highlight that, in the previous experiment, this same loss was 284.764. This loss was computed outside the training stage, so it did not influence the optimization of parameters or hyperparameters.

Figure 2.5a shows the relationship between the actual injection values at the nodes and the corresponding predictions. As in the previous experiment, the model successfully recognizes that gas injection occurs only at a single node, although the predicted values differ slightly from the actual data. However, a significant improvement is observed when analyzing the flows through the edges. Figure 2.5b highlights this, where the network's predictions for edge flows are almost perfectly aligned with the actual test data, as evidenced by an R^2 of 0.999. The near-perfect scatter plot in fig. 2.5b demonstrates the network's ability to make highly accurate predictions for gas flows through the edges in this updated experiment.

To evaluate the computational performance when considering the loss associated with pipelines and compressor flows, a t-test was performed comparing the computation times of the optimization model and the GNN-based model. The results showed a T-statistic of 14.81, 198 degrees of freedom and a p-value of $3.47e-34$, indicating that the optimization model took significantly longer to compute than the GNN-based model. This confirms the consistently higher computational cost of the optimization model, even when additional complexities, such as pipeline flows, are included in the network.

The table 2.1 presents a combined comparison of the optimization model (APOPT) and the GNN-based model across four experiments. Each experiment has three degrees of freedom: the model method (APOPT or GNN), whether nodal loss (N) was included, and whether edge loss (E) was included. The table focuses on four key metrics: nodal flows, edge flows, nodal balance, and prediction time. Mean and standard deviation

CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH NEURAL NETWORKS

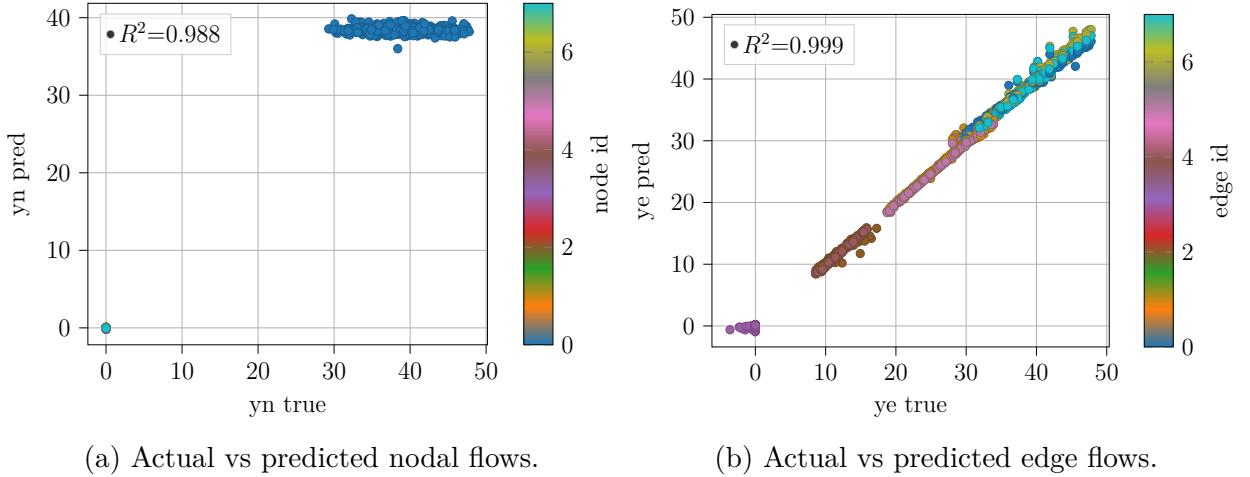


Figure 2.5: Model results using the losses associated with the flows in nodes and edges predictions in the 8-node network.

Method	Configuration		Node Value	Edge Value	Balance Value	Time
	N	E				
APOPT	✓		4.844 ± 12.874	24.221 ± 14.041	-0.001 ± 0.038	0.792 ± 0.436
GNN	✓		4.840 ± 12.794	0.455 ± 0.262	-5.711 ± 16.854	0.144 ± 0.044
GNN	✓	✓	4.767 ± 12.701	24.142 ± 14.083	-0.079 ± 1.174	0.145 ± 0.060

Table 2.1: Comparison of mean and standard deviation values for nodal flows, edge flows, nodal balance, and prediction time between the optimization model and the GNN-based model, across 100 samples. The 'N' column refers to experiments considering the nodal loss, while the 'E' column refers to experiments considering the edge loss.

CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH NEURAL NETWORKS

values are reported based on 100 samples.

Both models display similar results for nodal flows in the experiments, considering only the nodal loss (N). For instance, the APOPT model consistently records a mean nodal flow of 4.844 ± 12.874 , while the GNN shows a slightly lower mean of 4.767 ± 12.701 in experiments where both N and E were considered.

On the other hand, edge flow (E) values vary more significantly between the models. In experiments with only N, the GNN-based model achieves a much lower mean edge flow of 0.455 ± 0.262 compared to the APOPT model's 24.221 ± 14.041 . However, when both N and E were included, both models showed similar edge flow values (24.142 ± 14.083 for GNN and 24.221 ± 14.041 for APOPT), demonstrating that under these conditions, the GNN model can match the accuracy of the optimization model in predicting edge flows.

Regarding nodal balance, the APOPT model remains consistent across all experiments, showing a near-zero mean balance. The GNN-based model, however, fluctuates more, especially in the N-only experiment, with a mean balance of -5.711 ± 16.854 , though this variance diminishes to -0.079 ± 1.174 when both N and E are included.

Finally, the GNN model consistently outperforms APOPT in terms of prediction time. Across all experiments, the GNN-based model achieves much faster predictions (0.144 to 0.145 seconds) compared to the APOPT model's 0.792 seconds. This superior computational efficiency makes the GNN model particularly appealing for real-time applications.

2.2.3 Case Study II: 63-node Network (Colombia)

The second case studied corresponds to a gas transportation network consisting of 63 nodes representing the Colombian natural gas system. In the first test, where only the loss associated with the flows injected into the nodes was considered the hyperparameter tuning resulted in the following values: $N \text{ channels} = 43$, $N \text{ layers} = 2$, and $N \text{ dense} = 2$. The total loss obtained was 10.598, with the loss associated with the nodal flows. The gas balance loss was 3426.659, but it is important to note that only the nodal flows were considered during the network optimization, and the balance loss was computed after the training process.

The fig. 2.6a shows the scatter plot relating the actual injected flows at the nodes to the predicted flows. This figure demonstrates the network's ability to accurately identify which nodes had gas injections and which did not. Furthermore, with an R^2 value of 0.996, the network effectively captured the correct proportions of these injected flows, indicating a robust predictive performance. On the other hand, fig. 2.6b presents the

CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH NEURAL NETWORKS

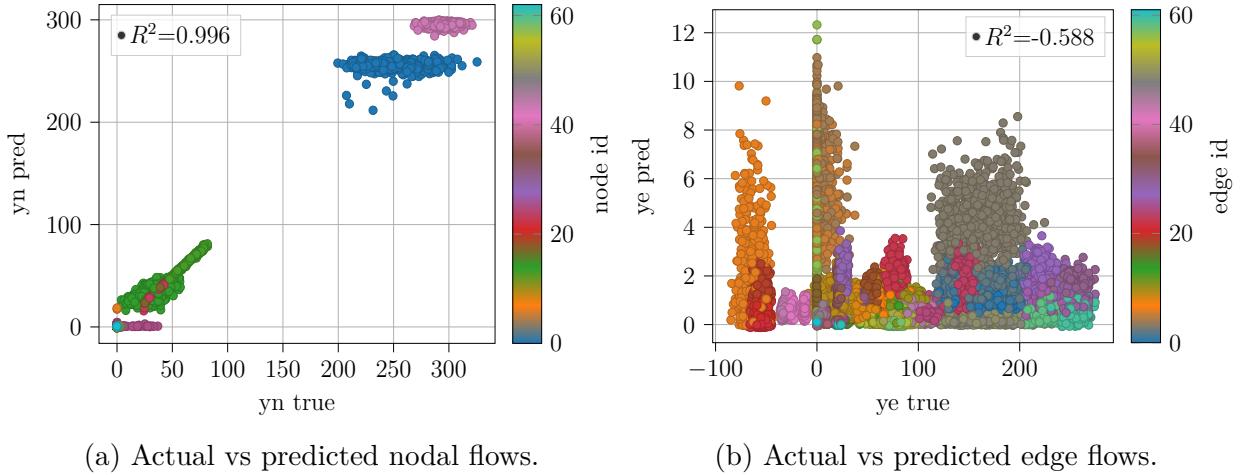


Figure 2.6: Model results using only the loss associated with nodal flow predictions in the colombian 63-node network.

relationship between the actual and predicted flows through the edges, encompassing both gas pipelines and compressors. In this case, the network struggled to predict the flow values accurately for these elements, which is unsurprising given that the loss associated with the edge flows was not included in the network's optimization process for this test.

For the current experiment stage, involving the 63-node Colombian network, a t-test was conducted to compare the computation times between the optimization model and the GNN-based model. The test yielded a T-statistic of 47.29, 198 degrees of freedom and a p-value of 4.92×10^{-110} , demonstrating a highly significant difference in the computational times. As with the previous experiments, these results confirm that the GNN-based model significantly outperformed the optimization model in terms of prediction speed.

In the next stage of this case study, predictions were made on the same system, but this time, considering not only the losses associated with the flows injected at the nodes but also those corresponding to the flows transported by the system's pipelines and compressors. For this experiment, the hyperparameter tuning resulted in $N \text{ channels} = 25$, $N \text{ layers} = 5$, and $N \text{ dense} = 4$, with a total loss of 34.399. Of this, 10.792 were associated with the predictions of the flows injected at the nodes, while 23,607 corresponded to the flows transported through the edges. The MSE for the gas balance was 279.754.

CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH NEURAL NETWORKS

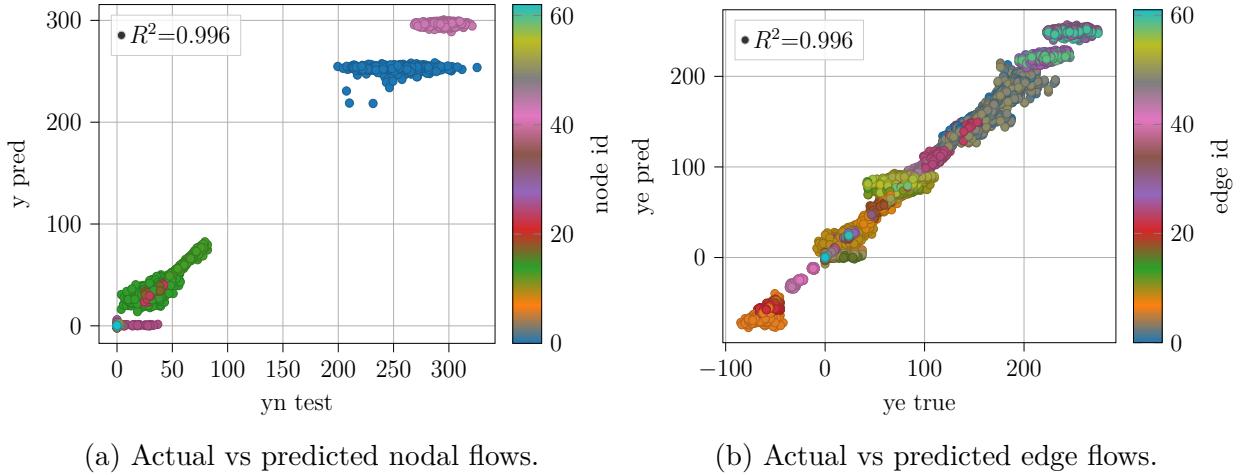


Figure 2.7: Model results using the losses associated with the predicted flows injected at the nodes and transported by the pipelines and compressors in the colombian 63-node network.

Figure 2.7a illustrates that, as in the previous case, the network can predict which nodes can inject natural gas and demonstrate a certain degree of accuracy regarding their injection capacity. The critical difference in this test, compared to the previous one, is shown in fig. 2.7b. Here, it is evident that by including the losses associated with the edges of the Colombian transportation network, the model significantly improves its predictions for these elements, achieving an R^2 value of 0.996 compared to the actual data.

In this stage, a t-test was performed to compare the computation times between the optimization model and the GNN-based model. The results yielded a T-statistic of 47.25, 198 degrees of freedom and a p-value of 4.46×10^{-110} . These values confirm with high statistical confidence that the GNN-based model significantly outperforms the optimization model in terms of computational efficiency when predicting flows across the network.

The table 2.2 presents a comparison between the optimization model (Opt) and the GNN-based model across four experiments, which vary based on the method used (Opt or GNN) and the inclusion of nodal loss (N) and edge loss (E). The comparison focuses on nodal flows, edge flows, nodal balance, and prediction time, with the mean and standard deviation calculated from 100 samples.

In terms of nodal flows, both the optimization model and the GNN-based model

CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH NEURAL NETWORKS

Method	Experiment		Node Value	Edge Value	Balance Value	Time
	N	E				
Opt	✓		11.41 ± 49.23	63.52 ± 81.62	-2.15 ± 16.49	5.01 ± 5.59
GNN	✓		11.38 ± 49.13	0.91 ± 1.26	-2.19 ± 58.56	0.13 ± 0.07
Opt	✓	✓	11.41 ± 49.23	63.52 ± 81.62	-2.15 ± 16.50	5.01 ± 5.59
GNN	✓	✓	11.40 ± 48.97	63.45 ± 81.38	-2.16 ± 16.60	0.14 ± 0.08

Table 2.2: Comparison of mean and standard deviation values for nodal flows, edge flows, nodal balance, and prediction time between the optimization model (Opt) and the GNN-based model, across 100 samples. The 'N' column refers to experiments considering the nodal loss, and the 'E' column refers to experiments considering the edge loss.

show almost identical results across all experiments. For both models, the mean nodal flow remains consistent at around 11.41, with very similar standard deviations: 49.23 for the optimization model and 49.13 and 48.97 for the GNN model in the experiments considering only nodal loss and both nodal and edge losses, respectively. This consistency highlights that both models perform similarly in predicting nodal flows.

However, the edge flow values present a more notable distinction between the two models. In the experiments without edge loss, the GNN-based model significantly outperforms the optimization model, achieving a much lower mean edge flow of 0.91 ± 1.26 , compared to the optimization model's 63.52 ± 81.62 . This demonstrates the GNN's improved capability to predict edge flows with reduced variability. In the experiments that include both nodal and edge losses, the edge flow predictions for both models converge, with the GNN reporting 63.45 ± 81.38 and the optimization model showing 63.52 ± 81.62 .

Regarding the nodal balance, the models display similar mean results. In the experiments without edge loss, the optimization model reports a mean balance of -2.15 ± 16.49 , while the GNN produces -2.19 ± 58.56 . In the experiments considering both nodal and edge losses, the mean balance results become more consistent, with the GNN model showing -2.16 ± 16.60 and the optimization model remaining at -2.15 ± 16.50 . The higher variability observed in the GNN's predictions during the nodal-only experiments is reduced when edge loss is included, indicating improved consistency.

Finally, the prediction time demonstrates the GNN's computational efficiency. In all experiments, the GNN completes predictions significantly faster than the optimization

CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH NEURAL NETWORKS

model. In the nodal-only experiments, the GNN requires just 0.13 seconds on average, compared to 5.01 seconds for the optimization model. In the nodal and edge loss experiments, the GNN’s prediction time increases only slightly to 0.14 seconds, whereas the optimization model maintains the same 5.01 seconds. This significant reduction in prediction time underscores the GNN’s efficiency in handling large-scale network predictions.

2.3 Discussion and conclusions

In this section, we analyze and summarize the performance of the proposed GNN-based model in predicting the operational parameters of natural gas transportation systems. The evaluation was conducted on two test cases: a simplified 8-node network and a more complex real-world system with 63 nodes representing the Colombian natural gas system. The results demonstrate the GNN model’s ability to deliver accurate predictions with significant improvements in computational efficiency compared to traditional optimization methods.

The 8-node network provided a controlled environment to test the GNN’s predictive capabilities. The initial experiment, where only nodal losses were considered, resulted in a MSE of 1.98. Although the model accurately identified the generating node, its predictions were more concentrated, lacking the dispersion seen in the actual values. This behavior suggests that while the GNN could capture certain trends in gas generation at the nodes, its predictive distribution did not fully align with real-world variability. However, the prediction of edge flows showed significant deviation from the actual values due to the exclusion of edge-related losses in the training process. This underperformance was expected, given this initial model’s lack of focus on edge dynamics.

The introduction of edge-related losses in the second stage of the experiment significantly improved the GNN’s performance. With optimized hyperparameters, the GNN achieved an overall loss of 2.02, reflecting its enhanced ability to predict both nodal and edge flows. Furthermore, the MSE associated with flow balancing at nodes dropped dramatically, from 284,764 to 1,719, highlighting the importance of including edge losses in the training objective. The comparison between scatter plots in fig. 4.6 and fig. 2.5 confirmed this improvement, with an R^2 of 0.999 for edge flow predictions, nearly aligning with the actual data.

The results presented in table 2.1 illustrate the excellent performance of the GNN-based model, making a trade-off in terms of computational speed and prediction accuracy. The GNN-based model demonstrated advantages over the optimization model

CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH NEURAL NETWORKS

regarding computational efficiency, as confirmed by the t-test results. When comparing the time required to generate predictions using node losses only, the GNN-based model outperformed the optimization model. The t-test produced a T-statistic of 14.94, with 198 degrees of freedom and a p-value of 1.32×10^{-34} , indicating a computational advantage for the GNN. On average, the GNN required 0.144 seconds to make predictions in the Base experiment, compared to 0.792 seconds for the optimization model. Similar results were observed in the Base-f experiment, where the GNN took 0.145 seconds, while the optimization model maintained the same prediction time of 0.792 seconds.

In the second evaluation, considering both node and edge losses, the GNN-based model again outperformed the optimization model. The t-test revealed a T-statistic of 14.81, with 198 degrees of freedom and a p-value of 3.47×10^{-34} , further reinforcing the computational advantage of the GNN. Despite the additional complexity introduced by edge flows, the GNN completed predictions faster than the optimization model, maintaining an average time of 0.144 seconds in the Base experiment and 0.145 seconds in the Base-f experiment, compared to the optimization model's consistent time of 0.792 seconds.

The performance of the GNN-based model was evaluated on the more complex 63-node Colombian natural gas system. Initially, the model was optimized using only the nodal loss, resulting in a total loss of 11.38 for nodal flows. However, its ability to capture the gas balance was less accurate, with a balance loss of -2.19 ± 58.56 . This is due to the exclusion of edge flows during optimization, similar to the first experiment on the 8-node network.

Despite this limitation, the GNN demonstrated strong predictive accuracy for nodal flows, with an R^2 value of 0.996, as seen in fig. 2.6. This high correlation shows the GNN's ability to predict nodal gas injections effectively, identifying which nodes had active injections. However, since edge flows were not considered in the loss function, predictions for edge flows were less accurate.

The computational efficiency of the GNN-based model was significant. As shown in table 2.2, the GNN completed predictions in an average of 0.13 seconds, compared to 5.01 seconds for the optimization model. The t-test confirmed this advantage, with a T-statistic of 47.29 and a p-value of 4.92×10^{-110} .

In the second experiment, where the loss function included edge flows, the GNN-based model's performance improved significantly for edge predictions. fig. 2.7 shows that including edge-related losses allowed the GNN to achieve an R^2 value of 0.996 for edge flows, closely matching the actual data. This improvement highlights the importance of accounting for edge flows to enhance overall model accuracy.

CHAPTER 2. NATURAL GAS SYSTEM PREDICTION USING GRAPH NEURAL NETWORKS

The comparison between the optimization and GNN-based models in table 2.2 shows that both approaches yielded nearly identical mean and standard deviation values for nodal and edge flows. However, the GNN model achieved these results with much greater computational efficiency. The GNN consistently required less time to generate predictions, averaging 0.14 seconds in the Base-f experiment, compared to the optimization model's 5.01 seconds. This efficiency makes the GNN a suitable choice for real-time or large-scale applications.

Chapter 3

Optimization Using Mathematical Programs with Complementarity Constraints

3.1 Formulation of Interconnected Power and Gas Systems

An interconnected system can be effectively represented by a directed graph denoted as $\{\mathcal{N}, \mathcal{E}\}$, where the sets of units \mathcal{N} and edges \mathcal{E} consider all power and gas components along with their interconnections. On the electrical power side, the system holds power units $\mathcal{N}_P \subset \mathcal{N}$, termed buses, and power edges $\mathcal{B} \subset \mathcal{E}$ or branches. The power buses comprise generators $\mathcal{G} \subset \mathcal{N}_P$ injecting power and users $\mathcal{D} \subset \mathcal{N}_P$ demanding power [37]. The branches $\mathcal{B} = \{b = (n, m) \mid n, m \in \mathcal{N}_P\}$ connect the buses to make the electrical power flow from the generators to the users. Although the physical power flow is alternating current, the system is accurately modeled using a linear direct current (DC) approximation. The DC model ignores reactive power flows and voltage magnitude fluctuations and approximates active power flows using linear transfer distribution factors [38]. Further, the linear characteristics allow stating linear programming problems. Thus, the DC model serves as an appropriate approximation for many power system operations and planning studies, providing a balance of accuracy and computational tractability [39].

Then, the optimization problem of the interconnected system seeks to minimize the operation costs for satisfying the demands of the interconnected system while encom-

CHAPTER 3. OPTIMIZATION USING MATHEMATICAL PROGRAMS WITH COMPLEMENTARITY CONSTRAINTS

passing the power and gas constraints. Specifically, the following cost function linearly combines the flows of power and gas through the operation costs of the interconnected system elements:

$$\begin{aligned} \min_{\mathcal{P}, \mathcal{F}} \quad & \sum_{g \in \mathcal{G}} C_g^t P_g^t + \sum_{d \in \mathcal{D}} C_d^t P_d^t + \sum_{w \in \mathcal{W}} C_w^t f_w^t + \\ & \sum_{p \in \mathcal{P}} C_p^t f_p^t + \sum_{c \in \mathcal{C}} C_c^t f_c^t + \sum_{u \in \mathcal{U}} C_u^t f_u^t + \\ & \sum_{s \in \mathcal{S}} C_{s+}^t f_{s+}^t + \sum_{s \in \mathcal{S}} C_{s-}^t f_{s-}^t + \sum_{s \in \mathcal{S}} C_s^t V_s^t \end{aligned} \quad (3.1)$$

where C_g^t denotes the generation cost by the g -th bus and C_d^t the unsupplied power demand for the d -th user. Regarding the natural gas system, terms C_w^t , C_p^t , C_c^t and C_u^t are the same as those used in Equation (2.14). However, some additional terms are considered in this case: C_{s+}^t , C_{s-}^t , and C_s^t represent the costs of injecting, extracting, and storing gas at the s -th storage station.

Therefore, the decision variables for the optimization problem are P_g^t for the generated power, P_d^t for the unsupplied power, f_w^t for the inject gas flow, f_p^t and f_c^t for the transported gas through pipeline p and compressor c , f_u^t for the unsupplied gas demand, f_{s+}^t , f_{s-}^t , and f_s^t for injecting, extracting, and storing gas. Traditionally, a transported gas with a positive value of $f_p^t > 0$ moves in the predefined direction, while a negative value flows in the opposite one, with no impact on the optimization process. On the other hand, compressor stations solely allow unidirectional gas flow, expressed as $f_c^t \geq 0$. By optimizing this integrated cost function while adhering to the system's operational constraints, the proposed methodology effectively balances the demands of both energy systems, leading to a comprehensive solution that minimizes costs while ensuring reliable and efficient operation.

Optimization of the integrated cost function in Equation (3.1) while adhering to the system's operational constraints must lead to a comprehensive solution balancing the demands of both energy systems while ensuring reliable and efficient operation. Three sets of operational constraints describe the within and between power and gas interplay.

The first constraint set guarantees a stable power system operation: Equation (3.2) ensures that the generated power P_g^t lies between the technical minimum \underline{P}_g^t and maximum \overline{P}_g^t . Equation (3.3) bounds the power flow through the transmission line P_l^t , preventing damages, such as overheating. Equation (3.4) models the power flow over the electrical network through the reactance-based relationship of the power flow P_l^t ,

CHAPTER 3. OPTIMIZATION USING MATHEMATICAL PROGRAMS WITH COMPLEMENTARITY CONSTRAINTS

the line susceptance B_{nm} , and the voltage angles θ_n, θ_m at buses n, m . Equation (3.5) limits the unsupplied power P_d^t to the user demand $\overline{P_d^t}$. Equation (3.6) ensures stable operating conditions within the interconnected power grid by restricting the bus voltage angles. Equation (3.7) defines the power balance at each bus, i.e., the total input and generated power must equal the total output and unsupplied power, being $\mathcal{L}_{n+} = \{(m, n') \in \mathcal{L} : n' = n\}$ and $\mathcal{L}_{n-} = \{(n', m) \in \mathcal{L} : n' = n\}$ the set of inflow and outflow transmission lines at the n -th bus, respectively.

$$\underline{P_g^t} \leq P_g^t \leq \overline{P_g^t} \quad \forall g \in \mathcal{G}, \quad (3.2)$$

$$-\overline{P_l^t} \leq P_l^t \leq \overline{P_l^t} \quad \forall l \in \mathcal{L}, \quad (3.3)$$

$$P_l^t = B_{nm}(\theta_n - \theta_m) \quad \forall l = (n, m) \in \mathcal{L}, \quad (3.4)$$

$$0 \leq P_d^t \leq \overline{P_d^t} \quad \forall d \in \mathcal{D}, \quad (3.5)$$

$$-\overline{\theta_n^t} \leq \theta_n^t \leq \overline{\theta_n^t} \quad \forall n \in \mathcal{N}_P, \quad (3.6)$$

$$\sum_{\substack{l \in \mathcal{L}_{n+} \\ g=n}} P_l^t + P_g^t = \sum_{\substack{l \in \mathcal{L}_{n-} \\ d=n}} P_l^t + P_d^t \quad \forall n \in \mathcal{N}_P \quad (3.7)$$

The second constraint set interconnects natural gas and electrical power systems through gas-fired power plants generating electricity, as expressed by Equation (3.8), where f_n^t stands for the natural gas fuel consumption to generate a power P_n^t at generator bus $n \in \mathcal{N}_I$, the heat-rate HR_n defines the generator efficiency, and the set $\mathcal{N}_I = \mathcal{G} \cap \mathcal{U}$ holds all the units in the interconnected system belonging to both the power generator and gas demand sets.

$$f_n^t = P_n^t \cdot \text{HR}_n, \quad \forall n \in \mathcal{N}_I, \quad (3.8)$$

The third constraint set models the gas transportation system: Equations (2.15) to (2.18) are considered, and next to these Equation (3.9) fixes safe operating limits for the pressure on the n -th node π_n^t as $[\underline{\pi_n^t}, \overline{\pi_n^t}]$. The constraint in Equation (3.10) asserts that the compression ratio π_m^t / π_n^t cannot physically exceed the compressor's design limitation $\beta_c \geq 1 \forall c = (n, m) \in \mathcal{C}$, enabling the representation of different compressors by adjusting the values of $\beta_c \geq 1$. Equations (3.11) and (3.12) limit the gas injection f_{s+} and extraction f_{s-} rates at storage facilities according to the feasible operating range determined by the currently stored volume V_s^t , respectively. In turn, Equation (3.13) balances the gas storage unit such that gas volume at operation period t V_s^t equals the volume from period V_s^{t-1} plus the difference between injected f_{s+}^{t-1} and extracted f_{s-}^{t-1}

*CHAPTER 3. OPTIMIZATION USING MATHEMATICAL PROGRAMS WITH
COMPLEMENTARITY CONSTRAINTS*

gas flow, a fundamental constraint for modeling the dynamics of gas storage over time. Lastly, Equation (3.22), known as the Weymouth equation, summarizes the physical behavior of gas flow through pipelines by relating the gas flow through the pipeline f_p^t to the pressures at the ends of the pipeline $\pi_n^t, \pi_m^t \forall p = (n, m) \in \mathcal{P}$. The Weymouth equation defines a nonlinear, nonconvex, disjunctive flow-pressure relationship that hampers the optimization of the gas transport system.

$$\underline{\pi}_n^t \leq \pi_n^t \leq \overline{\pi}_n^t \quad \forall n \in \mathcal{N}_f \quad (3.9)$$

$$\pi_m^t \leq \beta_c^t \pi_n^t \quad \forall c = (n, m) \in \mathcal{C} \quad (3.10)$$

$$0 \leq f_{s+}^t \leq V_{0s} - \underline{V}_s \quad \forall s \in \mathcal{S} \quad (3.11)$$

$$0 \leq f_{s-}^t \leq \overline{V}_s - V_{0s} \quad \forall s \in \mathcal{S} \quad (3.12)$$

$$V_s^t = V_s^{t-1} + f_{s-}^{t-1} - f_{s+}^{t-1} \quad \forall s \in \mathcal{S} \quad (3.13)$$

$$sgn(f_p^t)(f_p^t)^2 = K_{nm}((\pi_n^t)^2 - (\pi_m^t)^2) \quad \forall p = (n, m) \in \mathcal{P} \quad (3.14)$$

3.2 Mathematical Programming with Complementarity Constraints for Weymouth Approximation

The Weymouth equation is the fundamental model for gas flow through pipelines. However, it presents a challenge for optimal interconnected operation due to its nonlinearity, which arises from the signum function determining the gas flow direction. This nonlinearity results from the complex physics of gas flow, making it challenging to find optimal solutions for gas transportation systems [40]. Traditional optimization approaches struggle to handle the non-convex terms within the Weymouth equation. However, recent advances in optimization techniques, particularly mathematical programs with complementary constraints (MPCC), offer a promising solution to address this issue. MPCC specializes in handling complementarity constraints and non-convexities, making it well-suited to tackle the intricacies of the Weymouth equation [41]. This type of formulation involves optimization problems of the general form:

$$\mathcal{O} : \min f(x, y) \quad (3.15a)$$

$$\text{s.t. } h_i(x, y) = 0 \quad (3.15b)$$

$$g_j(x, y) \geq 0 \quad (3.15c)$$

$$0 \leq G_k(x) \perp H_k(y) \geq 0 \quad (3.15d)$$

where $f(x, y)$ is the cost function, $h(x, y)$ and $g(x, y)$ capture equality and inequality constraints in the optimization problem \mathcal{O} . Equation (3.15d) represents the complementarity conditions, with the operator \perp indicating that at a solution, either x or y must be zero while the other must remain non-negative. These conditions turn MPCC into a modeling tool for scenarios with variables exhibiting complementarity relationships, such as economic equilibrium [42], variational inequalities [43], and the intricate dynamics of natural gas transportation systems [44]. To deal with the non-convexity, this work rewrites the Weymouth equation as the following mathematical program with two complementarity constraints:

$$\begin{aligned} \mathcal{O}_W : \min_{y_p^t} & -y_p^t f_p^t \\ \text{s.t. } & y_p^t (f_p^t)^2 = K_{nm} ((\pi_n^t)^2 - (\pi_m^t)^2) \\ & -1 \leq y_p^t \leq 1 \\ & f_p^t = f_{p+}^t - f_{p-}^t \\ & 0 \leq f_{p+}^t \perp (y_p^t + 1) \geq 0 \\ & 0 \leq f_{p-}^t \perp (1 - y_p^t) \geq 0 \end{aligned} \quad (3.16)$$

where $f_{p+}^t \geq 0$ and $f_{p-}^t \geq 0$ hold the positive and negative components of the gas flow in the p -th pipeline at operation period t , for assessing directional flow.

Solving MPCC presents a unique set of challenges distinguishing it from traditional optimization problems. One notable challenge is the need for regularity properties, making MPCC more complex [45]. Compared to smooth optimization problems, where gradients and Hessians provide valuable information for optimization algorithms, MPCC often lacks these properties, leading to difficulties in devising efficient numerical methods.

3.2.1 Linear Independence Constraint Qualification (LICQ)

The Linear Independence Constraint Qualification (LICQ) is a critical condition in optimization, particularly in nonlinear programming problems (NLPs). LICQ ensures

CHAPTER 3. OPTIMIZATION USING MATHEMATICAL PROGRAMS WITH COMPLEMENTARITY CONSTRAINTS

the existence and uniqueness of Lagrange multipliers, simplifying their interpretation and enhancing the clarity of their role in constrained optimization. Additionally, LICQ provides a robust framework for local analysis, guaranteeing that the KKT conditions are sufficient for optimality when satisfied at a specific point. [46].

LICQ is a constraint qualification used in optimization problems to ensure that the gradients of the active inequality constraints and the gradients of the equality constraints are linearly independent at the minimizing point x^* of the original constrained optimization problem \mathcal{P} , understanding the set of active constraints as,

$$I(x^*) := \{1 \leq l \leq p \mid g_l(x^*) = 0\}, \quad (3.17)$$

i.e., the inequality constraints at the point x^* that lie on its boundary. The above indicates that this constraint qualification is fulfilled when the elements of the set \mathcal{F} are linearly independent at the point x^* .

$$\mathcal{F} = \{(\nabla h_1(x^*)), \dots, (\nabla h_m(x^*)), (\nabla g_n(x^*), \forall n \in I(x^*))\} \quad (3.18)$$

3.2.2 Mangasarian-Fromovitz Constraint Qualification (MFCQ)

When an optimization problem does not meet the LICQ requirements, it is possible to resort to a second, less stringent criterion to check whether the KKT conditions are satisfied. This second criterion is known as Mangasarian-Fromovitz Constraint Qualification (MFCQ). The LICQ focuses on ensuring linear independence of the gradients of the active inequality and equality constraints [47]. On the other hand, the main objective of MFCQ is to guarantee that the gradients of the equality constraints are linearly independent at the optimal point \mathbf{x}^* , and furthermore that there exists a vector $\mathbf{d} \in \mathbb{R}^n$ such that

$$\nabla h_i(\mathbf{x}^*)^\top \mathbf{d} < 0 \quad (3.19)$$

for all equality constraints.

$$\nabla g_j(\mathbf{x}^*)^\top \mathbf{d} < 0 \quad (3.20)$$

and for all active inequality constraints.

It is widely recognized that conventional constraint qualifications in nonlinear programming, such as LICQ and MFCQ, are typically not satisfied in the case of MPCC. As a result, KKT conditions commonly associated with MPCC may not be applicable or valid at a local minimization point [48]. Therefore, posing relaxed nonlinear

*CHAPTER 3. OPTIMIZATION USING MATHEMATICAL PROGRAMS WITH
COMPLEMENTARITY CONSTRAINTS*

programs (RNLP) deals with the numerical resolution of MPCC by introducing a positive regularization parameter $\epsilon \in \mathbb{R}^+$ that simplifies the solution and properly handles the inequalities [49]. These programs typically satisfy constraint qualifications, making them more amenable to efficient optimization techniques. Relaxing MPCC ensures that inequalities are appropriately treated as inactive, particularly when $G_k(x)H_k(y) \leq \epsilon$, enhancing their structural integrity. Besides, relaxed programs reliably approximate the original problem as $\epsilon \rightarrow 0$ [50]. Hence, instead of working with the original problem \mathcal{O}_W , the relaxed problem \mathcal{O}_ϵ is considered:

$$\mathcal{O}_\epsilon : \min_{y_p^t} -y_p^t f_p^t \quad (3.21a)$$

$$\text{s.t. } y_p^t (f_p^t)^2 = K_{nm}((\pi_n^t)^2 - (\pi_m^t)^2) \quad (3.21b)$$

$$f_p^t = f_{p+}^t - f_{p-}^t \quad (3.21c)$$

$$-1 \leq y_p^t \leq 1 \quad (3.21d)$$

$$f_{p+}^t (y_p^t + 1) \leq \epsilon \quad (3.21e)$$

$$f_{p-}^t (1 - y_p^t) \leq \epsilon \quad (3.21f)$$

Theoretically, the relaxed problem offers fundamental properties that tackle challenging MPCC problems [51]. Firstly, the relaxed approach guarantees the convergence to the true MPCC solution as $\epsilon \rightarrow 0$. Additionally, the boundedness of Lagrange multipliers ensures numerical stability and avoids issues with infinitely large values during optimization. Lastly, the local uniqueness of the \mathcal{O}_ϵ solution under specific conditions guarantees a single and well-defined solution. Therefore, the proposed relaxed optimization problem deals with the non-convexity in the Weymouth equation while guaranteeing the KKT conditions around ϵ , posing a standard optimization problem, and avoiding ambiguity in interpreting results.

3.3 Case studies

The current section validates the proposed MPCC approach by comparing its performance against two well-established methods for approximating the Weymouth equation: i) The Taylor series approach that piecewise approximates Weymouth with line segments [52] and ii) The SOC programming that introduces a two-stage optimization, namely, flow direction estimation and cost minimization [53]. The validation contrasts Taylor, SOC, and MPCC approaches in three case studies of interconnected systems with different complexities.

CHAPTER 3. OPTIMIZATION USING MATHEMATICAL PROGRAMS WITH COMPLEMENTARITY CONSTRAINTS

The considered validation aims to quantify the inherent errors and the cost–error trade-off of the contrasted approaches to support its real-world pertinence. Therefore, this work reports two performance metrics: the cost function in Equation (3.1) that assesses the capacity for optimally operating an integrated system and the Weymouth error metric ($WE_p^t \in \mathbb{R}^+$) for quantifying the required flow to guarantee equality for pipeline p at time instant t in Equation (3.22), as follows:

$$WE_p^t = \left| f_p^t - \left(K_{nm} |(\pi_n^t)^2 - (\pi_m^t)^2| \right)^{1/2} \right|, \quad \forall p = (n, m) \in \mathcal{P}. \quad (3.22)$$

Hence, the WE_p^t metric, measured in million standard cubic feet per day (MMSCFD), explains the approximations' inherent sensitivity and validates the significance of their differences.

3.3.1 Case Study I: 9/8 System

The network depicted in Figure 3.1 [54] interconnects a nine-bus power system and an eight-node natural gas network. The small size of case 9/8 enables fast execution, efficient analysis, and rigorous validation of the contrasted approaches. The 9/8 network also features a closed trajectory and bidirectional pipelines, allowing looped infrastructure with potential flow reversals.

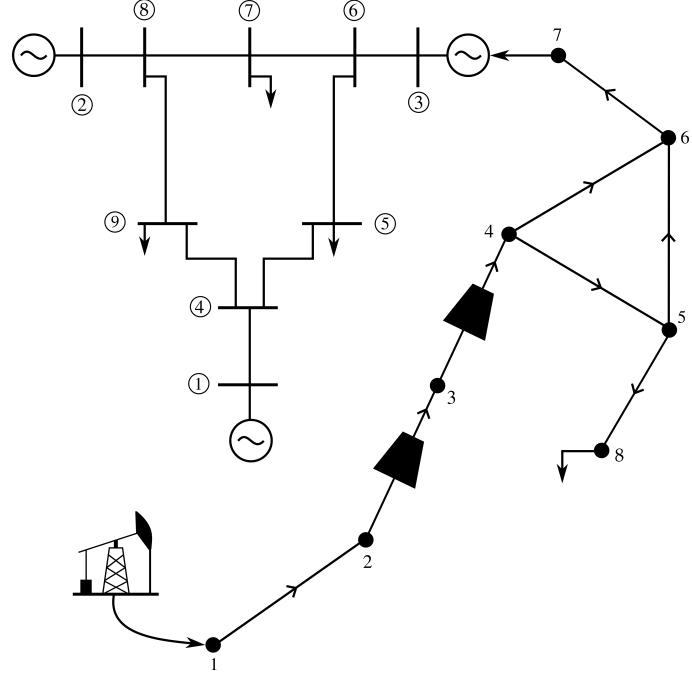


Figure 3.1: Integrated system 9/8 used in Case Study I, modified from the MPNG software.

To assess the performance of Weymouth approximation approaches on the 9/8 system, a Monte Carlo experiment estimates the cost function and Weymouth error distributions by solving the optimization problem for one day ($\mathcal{T} = \{1\}$) one hundred times with uniformly sampled natural gas demands. Further network parameter details can be found in the publicly available repository OptiGasFlow (<https://github.com/cblancom/optigasflow>, accessed on 05 April 2024). Figure 3.2 depicts the cost function histogram for Taylor, SOC, and MPCC approaches. Remarkably, the three histograms evidence identical distribution patterns, leading to regular solutions across approaches.

The boxplots in Figure 3.3 show the Weymouth approximation error distribution for each pipeline using three approaches. The error distributions, including median and interquartile range, indicate that MPCC consistently maintains accuracy throughout the network. In contrast, the widely varying errors of the Taylor and SOC approaches suggest a lack of consistency in the achieved solution. Therefore, in a small network, the proposed MPCC approach converges to identical operational costs as Taylor and SOC, even in rationing, while meeting all linear constraints and improving the Weymouth

*CHAPTER 3. OPTIMIZATION USING MATHEMATICAL PROGRAMS WITH
COMPLEMENTARITY CONSTRAINTS*

approximation.

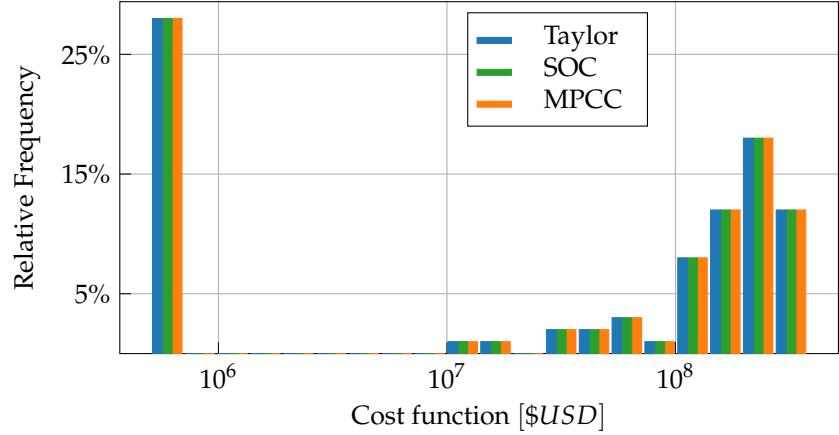


Figure 3.2: Cost function histogram for the Taylor, SOC, and MPCC Weymouth approximation approaches in the 9-bus 8-node system.

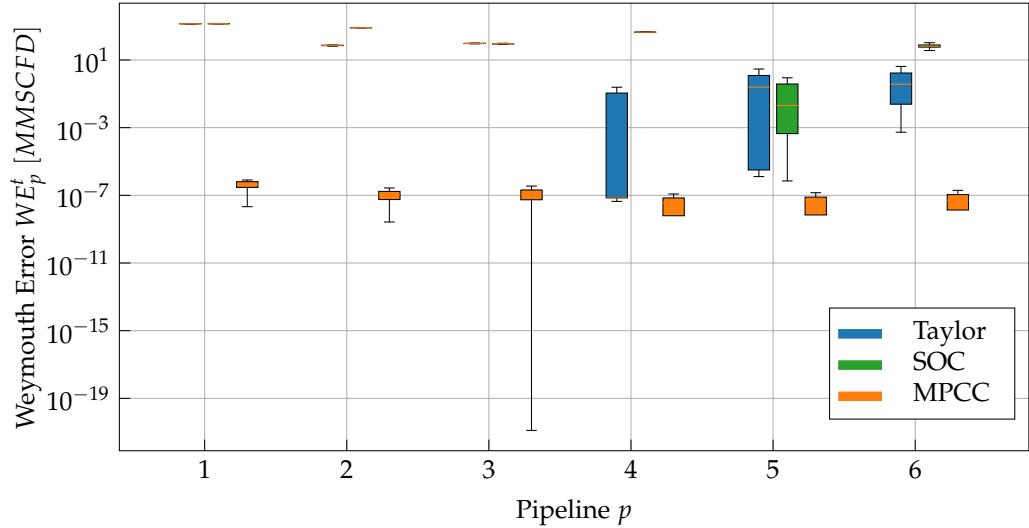


Figure 3.3: Boxplot of Weymouth error distribution for each pipeline in the 9/8 system attained by contrasted approximation approaches.

3.3.2 Case II: 118/48 System

The following case simulates a complex, large-scale electric grid system, the widely studied IEEE 118 bus system [55], consisting of 54 generator buses, 9 fed by the gas system, 186 transmission lines, and 99 users, that is, $|\mathcal{G}| = 54$, $|\mathcal{F}| = 186$, $|\mathcal{D}| = 99$. This electric grid interconnects with a 48-node natural gas system featuring 9 supply wells, 46 pipelines, eight compressor stations, and 22 user nodes through 9 connection points, i.e., $|\mathcal{W}| = 9$, $|\mathcal{P}| = 46$, $|\mathcal{C}| = 8$, $|\mathcal{U}| = 22$, $|\mathcal{I}| = 9$ [14]. The network topology deliberately introduces closed flow loops to stress the solver and the constraint approximations, as do real-world systems.

Figure 3.4 depicts the histogram of relative cost differences for the MPCC proposal to Taylor and SOC baselines from a hundred trials of the Monte Carlo experiment and a considered operation of one day ($T = 1$). It is worth noting that both baselines yielded the same cost function values. The relative difference between MPCC and the baselines is always positive, indicating that the complementarity constraint formulation consistently produces larger cost values in this system. However, the maximum difference of 6% falls within the range of real-world variations due to the dispatcher's practical decisions in line with the actual pressure–flow relationship [56].

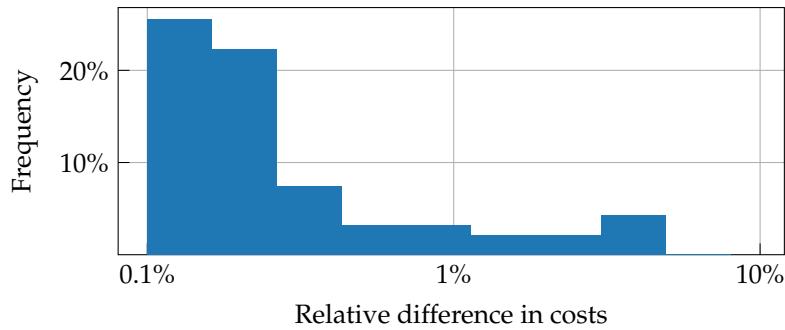


Figure 3.4: Histogram depicting the relative frequencies of cost differences obtained between MPCC and the other approaches in the 48-node 118-bus system.

Contrarily to cost function analysis, results in Figure 3.5 reveal a significant error reduction of about seven orders of magnitude (from 10^1 to 10^{-6}) under the proposed complementarity constraints. As an additional benefit, MPCC exhibits a shorter error dispersion than Taylor and SOC at most of the 46 pipelines in the network. Such behavior in the 118/48 system, also evidenced in the small 9/8 case study, proves the

CHAPTER 3. OPTIMIZATION USING MATHEMATICAL PROGRAMS WITH COMPLEMENTARITY CONSTRAINTS

reliability of MPCC in effectively addressing more complex network configurations and interconnected dynamics.

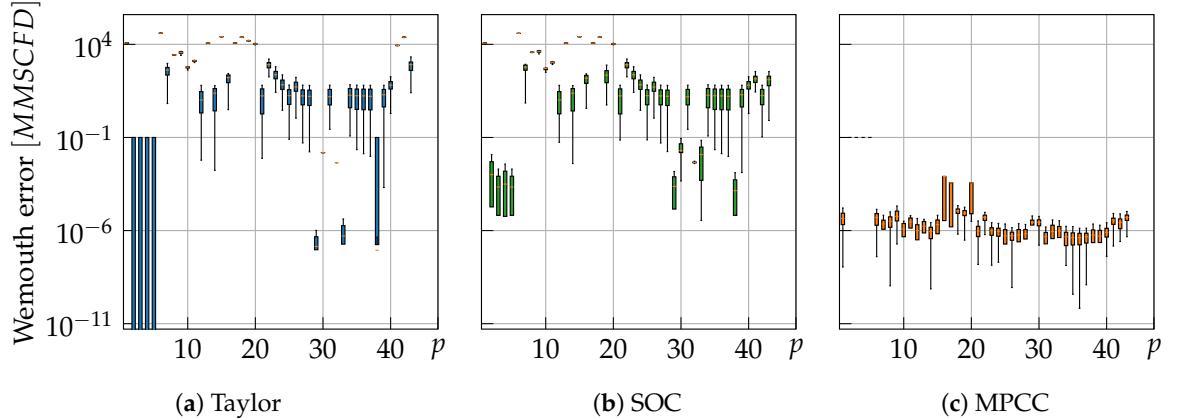


Figure 3.5: Weymouth approximation errors for each pipeline p reached by the contrasted approaches in the 118/48 study case.

3.3.3 Case Study III: 96/63 System

The last case study focuses on the Colombian power system, a complex network comprising 96 nodes ($|\mathcal{N}_P| = 96$), 49 generators ($|\mathcal{G}| = 49$), 207 transmission lines ($|\mathcal{F}| = 207$), and 80 power users ($|\mathcal{D}| = 80$). From the 49 generators, 10 are thermal power plants ($|\mathcal{I}| = 10$) fed by the natural gas transportation system, including 13 wells ($|\mathcal{W}| = 13$), 48 pipelines ($|\mathcal{P}| = 48$), 14 compressor stations ($|\mathcal{C}| = 14$), and 26 consuming users ($|\mathcal{U}| = 26$), yielding 63 nodes ($|\mathcal{N}_F| = 63$). Despite its radial structure, the gas system supports bidirectional flows in its pipelines due to the highly varying demand by thermal power plants influenced by meteorological conditions: On rainy seasons, thermal power plants dramatically reduce their demand; while on dry seasons, a large amount of gas must flow to them.

Instead of estimating the distributions of the cost function and Weymouth error as in cases 9/8 and 118/48, the 96/63 case validates the Weymouth approximations in an operation case of ten consecutive days ($|\mathcal{T}| = 10$) with randomly changing gas extraction costs. Such a complementary validation strategy allows the interconnected system to reduce gas transportation costs by exploiting its single storage station, extending the performance analysis to scheduling scenarios. Figure 3.6 illustrates the daily optimized operating cost of the integrated system over the ten-day scheduling horizon for each

CHAPTER 3. OPTIMIZATION USING MATHEMATICAL PROGRAMS WITH COMPLEMENTARITY CONSTRAINTS

tested approach. The daily cost values reveal notable similarities between the Taylor series and SOC relaxations. Nonetheless, the MPCC approach yields a 2.7% more expensive solution, from 8% cheaper to 12% more expensive, with a difference standard deviation of 6%. The above results indicate that the difference between the proposed MPCC and baseline approximations is statistically negligible and will disappear after the empirical corrections.

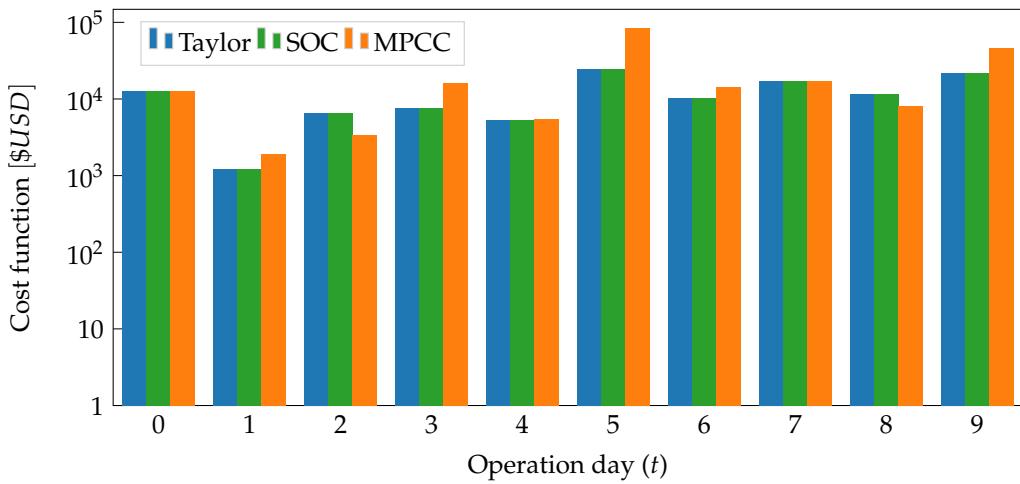


Figure 3.6: Daily operating cost obtained with each of the approaches in the 63-node 96-bus system.

Regarding the Weymouth approximation analysis, Figure 3.7 presents the error distribution and its relationship with the gas flow and the scheduled day for Taylor, SOC, and MPCC. Firstly, the error histogram in Figure 3.7a proves that the proposed MPCC formulation (in green) exhibits superior approximation accuracy to Taylor and SOC for most pipelines and days. Secondly, the scatter plot in Figure 3.7b illustrates the relationship between Weymouth error and gas pipeline flow for each approach. Note that the benchmark techniques of Taylor (blue) and SOC (orange) hold a stationary error regardless of the flow rate. In the case of MPCC (green), the larger the flow rate, the shorter the error dispersion. In addition, despite its large error dispersion at low flow rates, MPCC still delivers much lower errors than benchmark methodologies. Hence, the complementarity constraints improve the error rates of Taylor and SOC and become more reliable for higher gas flow rates.

CHAPTER 3. OPTIMIZATION USING MATHEMATICAL PROGRAMS WITH COMPLEMENTARITY CONSTRAINTS

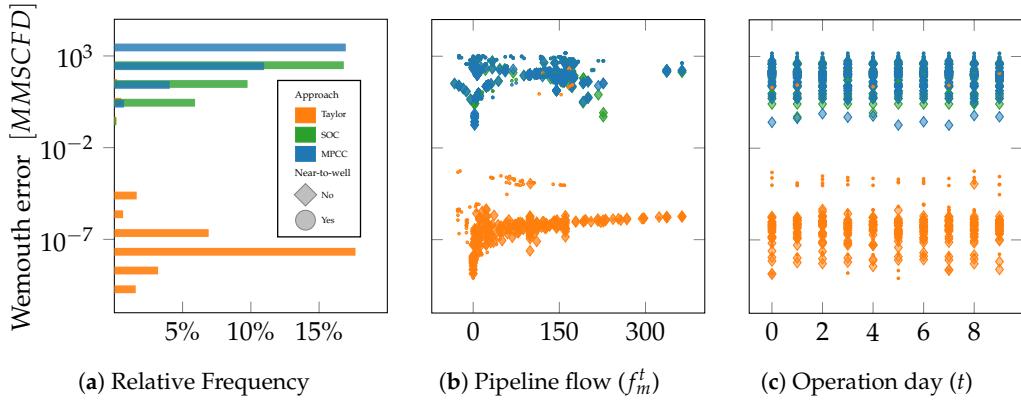


Figure 3.7: Weymouth error density on the Colombian case versus the gas flow and operation day.

Lastly, Figure 3.7c suggests independence between the Weymouth error and each scheduled day, with a stationary error distribution for all approximations. Nonetheless, MPCC holds two groups of outlying errors. The higher ones align with typical magnitudes of the benchmark techniques. The second group of errors, lying around 10^{-2} , corresponds to pipelines connected to injection wells (denoted as dots in Figure 3.8c). Since the wells are technically regulated, their fixed injection pressure hampers the flexibility of MPCC for approximating the Weymouth equation.

The heatmaps in Figure 3.8c illustrate the output-to-input pressure ratio for each of the

14 compressors over the ten days of the scheduled operation. The baseline approaches of Taylor and SOC (Figure 3.8a,b) yield constant pressure ratios stemming from an over-relaxation of the Weymouth equation that extends the feasible region to unpractical solutions. In contrast, the MPCC approach in Figure 3.8c exhibits day-to-day pressure ratio changes within each compressor. The above is because the complementarity constraints closely align with the gas transport system's real physics, restraining the range of the feasible pressure values to trade off the daily varying injection cost.

*CHAPTER 3. OPTIMIZATION USING MATHEMATICAL PROGRAMS WITH
COMPLEMENTARITY CONSTRAINTS*

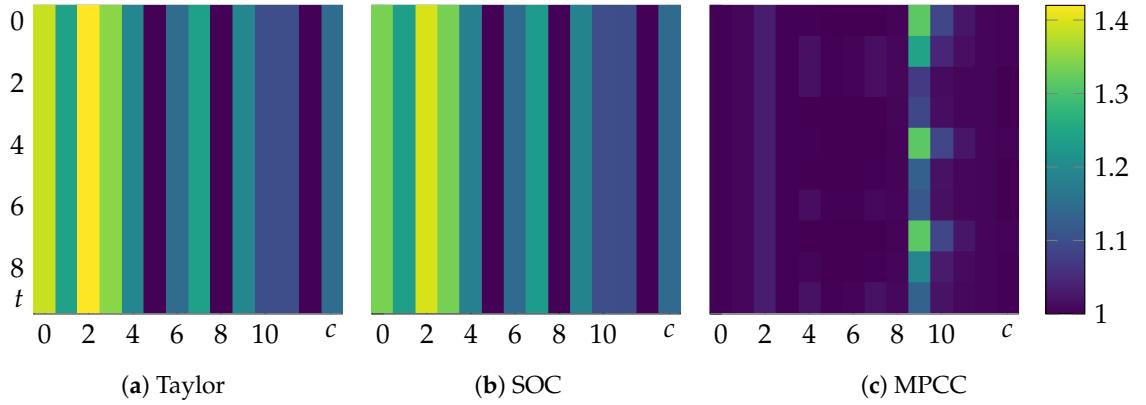


Figure 3.8: Output-to-input pressure ratio at the compressor in the 96/63 system.

As a remark, compressor nine in Figure 3.8c reaches large pressure ratios on Days 0, 1, 2, 4, and 7, overlapping with the time instants with the highest approximation errors for MPCC in Figure 3.7c. A detailed examination of these outcomes detects that compressor nine and the outlying pipeline are the two outputs of a bifurcation, the latter being followed by an injection well. Figure 3.9 exemplifies that such an interconnection is the sole over the gas network. As a hypothesis, fixing the pressure at the injection well and the flow direction at compressor nine pushes the complementarity constraints to the limits and forces the compressor to augment the pressure ratio to satisfy the forthcoming branch demand.

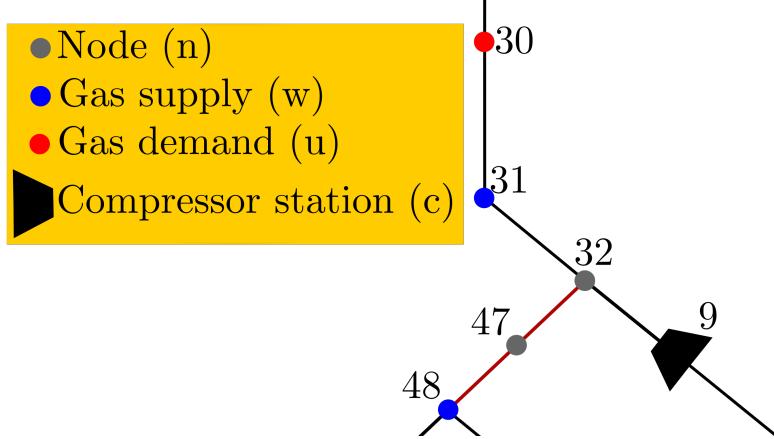


Figure 3.9: Outlying connection of well-compressor-pipeline on the system 96/63 used in Case Study III.

3.4 Conclusions

This paper presented a novel approximation for the Weymouth constraint by representing the nonconvex pressure–flow relationship as an MPCC. The MPCC-based formulation significantly benefits the optimization problems in interconnected power and gas systems using binary-behaving continuous variables related to the flow direction, which avoids costly mixed-integer approximations. Additionally, the MPCC inherently captures the complexity in the signum function, resulting in a rigorous approximation of the Weymouth equation.

The validation compared the proposed MPCC approach against the Taylor series and SOC programming approximations on optimizing the operation of interconnected power and gas transport systems. Monte Carlo experiments validated the solution reliability in two well-known case studies, while a ten-day operation planning assessed the scheduling task in a real-world case study.

Regarding cost function, the MPCC approach demonstrated a remarkable ability to balance operational costs effectively. Results on the 9/8 system proved that MPCC converges to the exact cost of Taylor and SOC in small-scale cases. For more complex networks (cases 118/48 and 96/63), MPCC yields higher operational costs than baselines due to the more rigorous Weymouth equation modeling. Nonetheless, the cost differences among approaches lie within reasonable limits and align with the dispatcher's empirical decisions.

CHAPTER 3. OPTIMIZATION USING MATHEMATICAL PROGRAMS WITH COMPLEMENTARITY CONSTRAINTS

In the case of Weymouth approximation, MPCC significantly outperforms Taylor and SOC in the tested cases. In the 118/48 and 96/63 systems, MPCC substantially reduces Weymouth approximation errors, often by several orders of magnitude, compared to traditional linearization and convex relaxation strategies. Such an accuracy improvement becomes crucial in large-scale, complex systems where precise approximation directly influences operational efficiency and system reliability. Hence, the introduced pressure-flow model mathematically benefits the optimization task, asserting its cost-effectiveness at various system scales.

The analysis of the scheduling task in the 96/63 Colombian interconnected system underscores the robustness and reliability of the MPCC approach. Despite the complexities of bidirectional flows and time-varying demand scenarios, MPCC maintains high accuracy levels in Weymouth approximation. Furthermore, the nearly negligible cost differences among approximation approaches establish MPCC as the most robust and reliable approach for short-term operational scheduling.

In conclusion, modeling the Weymouth equation as an MPCC improves the optimization of interconnected gas and power systems by balancing operational costs, minimizing approximation errors, and handling scheduling tasks. These findings establish strong evidence for the practical implementation of MPCC in gas transport optimization, particularly in scenarios demanding high accuracy and reliability in short-term operation scheduling.

Considering the current open issues on energy management, three future research directions may complement this study. Firstly, we propose to adapt MPCC to dynamic system constraints for validation in transient analysis scenarios. The second research direction accounts for the uncertainty in interconnected systems, mainly due to the growing share of low-inertia power sources, such as wind and solar, and potential gas transport failures. Hence, we plan to extend the proposed methodology to stochastic optimization, considering the varying parameters and power sources of interconnected systems. Lastly, we will integrate MPCC with distributed cooperative operation schemes considering multi-agent issues such as the lack of information due to privacy policies [57].

Chapter 4

Enhanced Natural Gas Flow Predictions Using Physics-Guided Neural Networks

Physics-Informed Neural Networks (PINNs) represent a class of neural networks where physical laws are incorporated into the learning process, guiding the model to respect these constraints. Unlike traditional neural networks, where the loss function is typically based on the discrepancy between predicted and actual data, PINNs introduce additional terms in the loss function that penalize the model for deviating from known physical principles.

In this case, the physical constraints are derived from the gas balance and the Weymouth equations, which describe the flow and pressure behavior within the gas transportation network. These constraints are integrated into our neural network as additional loss terms. Specifically, we define two layers within the network: one that calculates the error in gas balance and another that calculates the error in the Weymouth equation. The outputs of these layers are then used to adjust the network's predictions, ensuring that they adhere to the physical laws governing the system.

The inclusion of these physics-informed layers allows the network to achieve better generalization, as it is not only trained on the data but also guided by the underlying physical laws. This approach can be seen as a specialized form of regularization, where the model is penalized if its predictions do not satisfy the physical constraints. The overall loss function can be expressed as:

$$\mathcal{L}(\Theta) = \mathcal{L}_{\text{data}}(\Theta) + \mathcal{L}_{\text{balance}}(\Theta) + \mathcal{L}_{\text{weymouth}}(\Theta), \quad (4.1)$$

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

where $\mathcal{L}_{\text{data}}(\Theta)$ represents the traditional data-driven loss, $\mathcal{L}_{\text{balance}}(\Theta)$ is the loss associated with the gas balance constraint, and $\mathcal{L}_{\text{weymouth}}(\Theta)$ is the loss associated with the Weymouth equation constraint.

The gas balance constraint is enforced using a custom layer that compares the flow conservation at each node. For every node, the incoming and outgoing flows must match the net demand. This is computed by summing the edge flows using the incidence matrix \mathbf{IR} , subtracting the actual demand $\mathbf{X}_{\text{demand}}$, and adding the predicted injection \mathbf{f}_n^{in} . The output of this layer, \mathbf{b} , is given by:

$$\mathbf{b} = \mathbf{IR} \cdot \hat{\mathbf{f}}_e - \mathbf{d} + \hat{\mathbf{f}}_n, \quad (4.2)$$

where $\hat{\mathbf{f}}_e$ is the predicted edge flow, $\hat{\mathbf{f}}_n$ is the predicted nodal injection, and \mathbf{d} is the demand extracted from the input data. The corresponding loss is calculated as the mean squared error of \mathbf{b} .

The Weymouth equation constraint is implemented as another custom layer that evaluates whether the predicted flows and nodal pressures satisfy the nonlinear physical relationship between them. Specifically, this relation links the squared pressure drop across a pipe to the square of the flow, scaled by a known constant Z associated with each pipeline. The output of this layer is computed as:

$$\mathbf{w} = Z \cdot \left(\hat{\mathbf{f}}_e^2 \cdot \text{sign}(\hat{\mathbf{f}}_e) \right) - Z^2 \cdot (\mathbf{IR}^T \cdot \hat{\mathbf{p}}_n^2), \quad (4.3)$$

where $\hat{\mathbf{f}}_e$ is the predicted flow through each edge, and $\hat{\mathbf{p}}_n$ is the predicted nodal pressure. This loss penalizes any deviation from the expected nonlinear pressure-flow relationship, also using a mean squared error formulation.

Together, these physics-informed components guide the neural network toward solutions that not only fit the data but also obey the operational and physical laws of gas transport.

4.1 Methodology

In this section, we incorporate the physical laws of the gas balance and Weymouth equations to guide the model's training process. The gas balance equation, represented by eq. (4.2), ensures that the flow into and out of each node in the network adheres to the principle of mass conservation. The Weymouth equation, referred to as eq. (4.3), establishes a relationship between the flow and pressure differences across pipelines. These two equations will be the foundation for introducing physics-based constraints

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

into the neural network, ensuring the model's predictions respect the physical behavior of gas flow within the system.

In this chapter, we build upon the experimental setup outlined in section 2.2, maintaining the same general approach while incorporating new elements that account for the physics of the natural gas system. The samples are generated using the nonlinear natural gas network optimization model from chapter 3. In this process, a power-interconnected system was considered, but since this study focuses on the gas system, the power system remained constant without any variation. As in the previous setup, noise is introduced into the base values of two gas networks: a small-scale test network of 8 nodes and the more extensive Colombian natural gas transportation system. The noise levels, ranging from 5% to 25%, simulate various operating conditions, providing diverse training data.

While the GNN-based model from chapter 2 was designed as a fast alternative to the optimization-based model, this chapter introduces physics-informed elements into the network architecture. Specifically, the model now includes loss terms based on the gas balance and Weymouth equations to ensure the predicted flows comply with the physical laws governing gas transportation. These constraints, integrated through additional layers in the model, guide the learning process, penalizing deviations from the gas balance equation (eq. (2.18)) and the Weymouth equation (eq. (3.22)). The modified model maintains the same structural components, such as input channels, convolutional layers, and loss functions for node and edge predictions, with the difference that the balance equation and the Weymouth equation are now considered loss functions.

4.2 Results

In this section, we present the results of the proposed model, which now incorporates physical constraints from the natural gas system. The focus remains on the relationship between the predicted outputs and the actual observed values, evaluating the model's performance across the 8-node test network and the Colombian natural gas transportation system. By incorporating physics-based constraints, the goal is to assess the model's ability to predict critical parameters under various operational conditions while ensuring that the physical laws governing gas flow are respected.

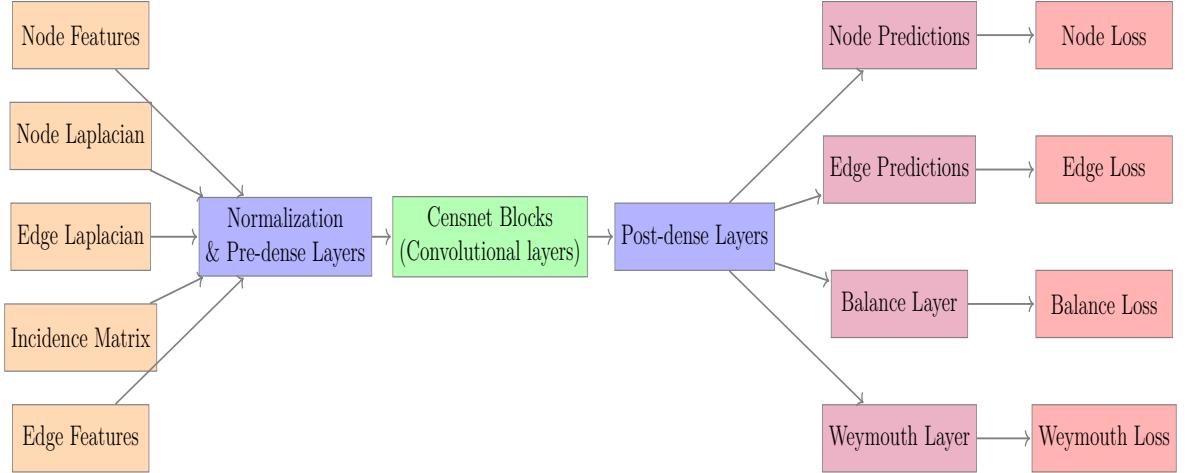


Figure 4.1: General outline of the CensNet-based model used.

4.2.1 Case Study I: 8-node Network

In this chapter, we begin with experiments that account for both node and edge losses, as it was found that considering only the node loss did not produce adequate results. The best parameters identified for this experiment were $N_{channels} = 25$, $N_{layers} = 4$, and $N_{dense} = 11$. These settings yielded a total loss of 6.816, with a node loss of 2.794 and an edge loss of 4.021.

The results corresponding to the nodes, shown in fig. 4.2a, exhibit a similar behavior to that observed in fig. 2.5a, demonstrating that the model accurately captures the injection pattern at the nodes. The correlation between the actual and predicted values is also strong, as indicated by an R^2 of 0.983.

Edge flows show some variation, as seen in fig. 4.2b, mainly when predicting the flows through the first pipeline connected to the injection field, where slight deviations from the actual flow values were observed. However, the model performed well overall, achieving an R^2 of 0.983 for the edge flows. While the first pipeline presents some prediction challenges, the accuracy in predicting flows across the rest of the pipelines remains high, demonstrating the model's ability to handle the complexity of gas transportation in this nonlinear system.

The second part of this experiment involves the additional loss associated with the gas balance, building upon the previous setup that considered both node and edge losses. The hyperparameter optimization yielded the best parameters: $N_{channels} = 61$, $N_{layers} = 2$, and $N_{dense} = 2$. These settings resulted in a total loss of 10.041,

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

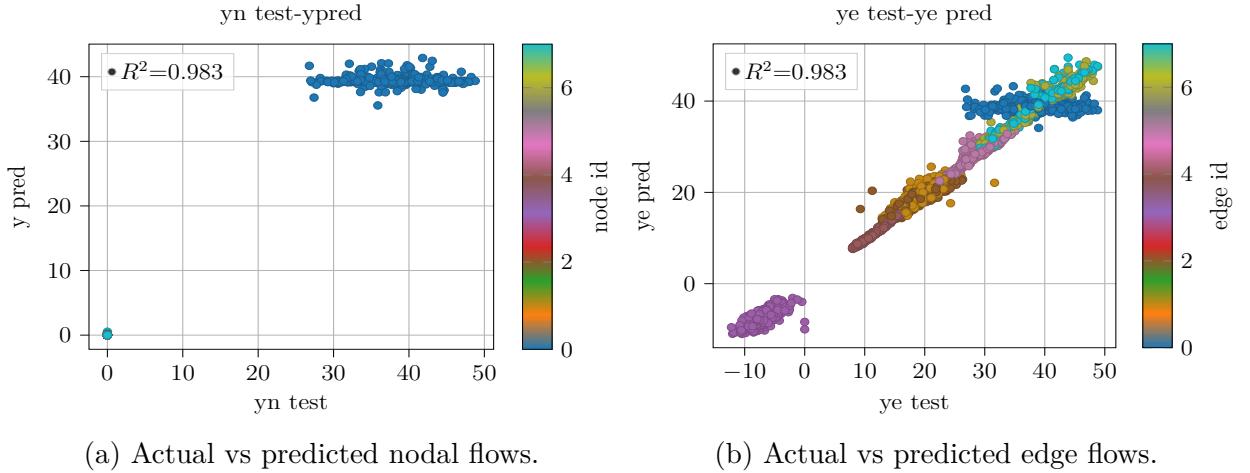


Figure 4.2: Model results using only the loss associated with nodal flow predictions in the 8-node network.

with a node loss of 2.850, an edge loss of 6.414, and a balance loss of 0.776.

The prediction behavior at the nodes, as shown in fig. 4.3a, remained consistent with the results obtained in the previous experiment, where the balance loss was not included. The model accurately captured the gas injection pattern, with an R^2 of 0.983 for node flow predictions, identical to the earlier case.

Similarly, the prediction of edge flows, shown in fig. 4.3b, followed the same general trend as before, although a slight decrease in accuracy was observed, reflected by an R^2 of 0.973. While this represents a minor reduction in performance compared to the previous experiment, the model still demonstrated a strong ability to predict gas flows through the edges, maintaining a high level of accuracy.

In the following part of this experiment, we incorporated losses associated with node and edge flows, the gas balance, and the Weymouth equation. The hyperparameter optimization for this setup yielded the following best parameters: $N_{channels} = 17$, $N_{layers} = 1$, and $N_{dense} = 4$. These settings resulted in a total loss of 20.670, with the individual losses being a node loss of 3.000, an edge loss of 11.354, a balance loss of 2.724, and a Weymouth equation loss of 3.592.

As shown in fig. 4.4a, the behavior of the node flow predictions remained consistent with the previous experiments, with an R^2 of 0.983. The model continued to accurately capture the gas injection patterns at the nodes.

However, the prediction accuracy for edge flows showed a notable deterioration, as

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

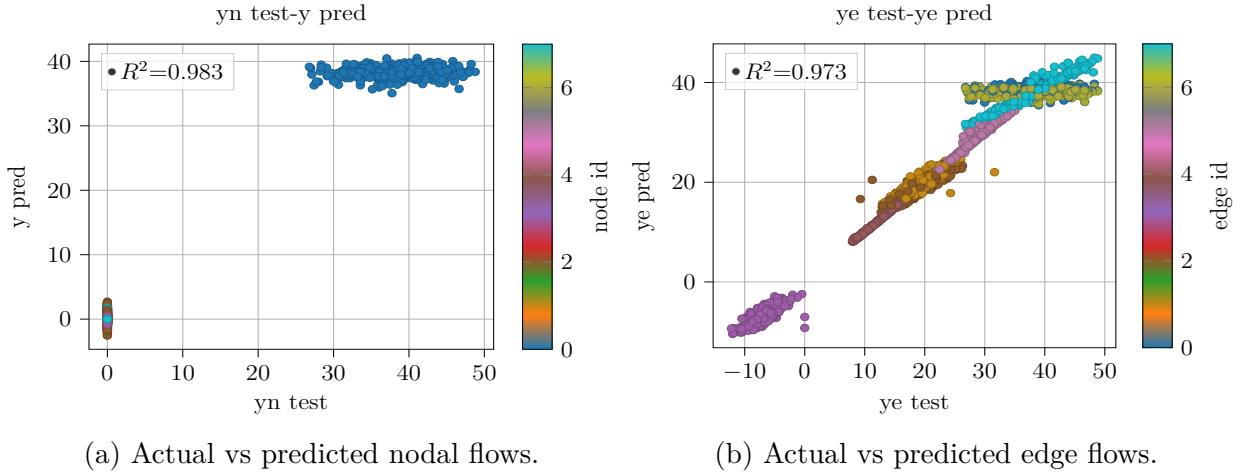


Figure 4.3: Model results using only the loss associated with nodal flow predictions in the 8-node network.

seen in fig. 4.4b. The R^2 value for edge flow predictions dropped to 0.952. This decrease in performance is primarily due to the difficulties encountered in predicting flows along edges 1, 2, 6, and 7. Edges 1 and 2 correspond to pipelines that are part of a closed path in the network, while edges 6 and 7 correspond to compressors. These complexities in the network configuration likely contributed to the reduction in predictive accuracy for these specific edges.

In the subsequent experiment, the losses associated with node flows and the physical equations—namely, the gas balance and the Weymouth equation—were considered. The hyperparameter optimization process resulted in the best parameters being $N_{channels} = 18$, $N_{layers} = 1$, and $N_{dense} = 5$. These settings led to a total loss of 10.270, with a node loss of 3.976, a balance loss of 4.747, and a Weymouth equation loss of 1.547.

The prediction at the nodes, shown in fig. 4.5a, remained largely consistent with previous experiments, though there was a slight decrease in accuracy, with the R^2 value dropping to 0.976. This minor reduction indicates that the model continues to perform well in predicting gas injection patterns at the nodes.

However, the prediction accuracy for edge flows, as seen in fig. 4.5b, experienced another decline. The R^2 value dropped to 0.899, reflecting increased difficulties in predicting flows through the compressors and the pipeline connected to the injection field.

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

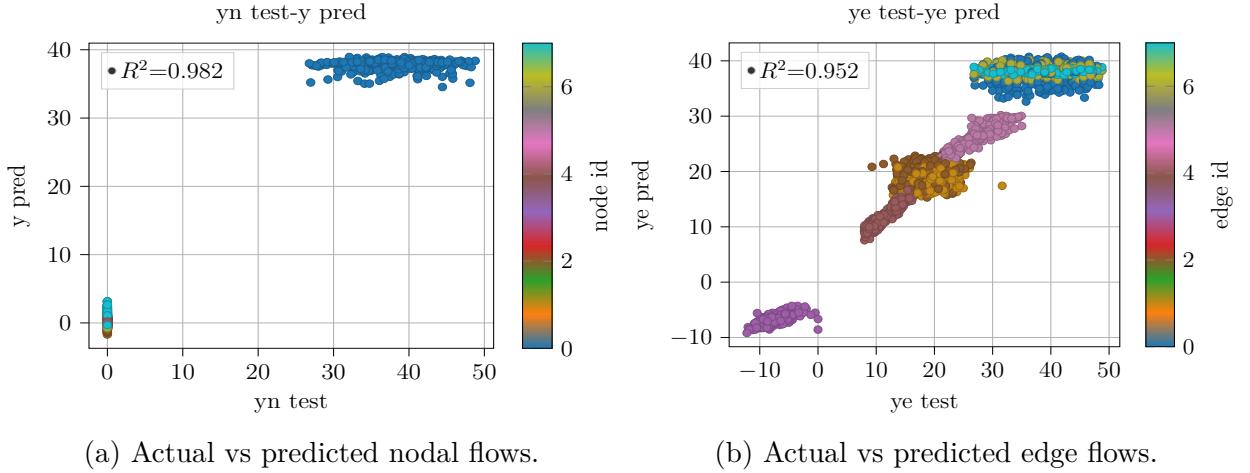


Figure 4.4: Model results using only the loss associated with nodal flow predictions in the 8-node network.

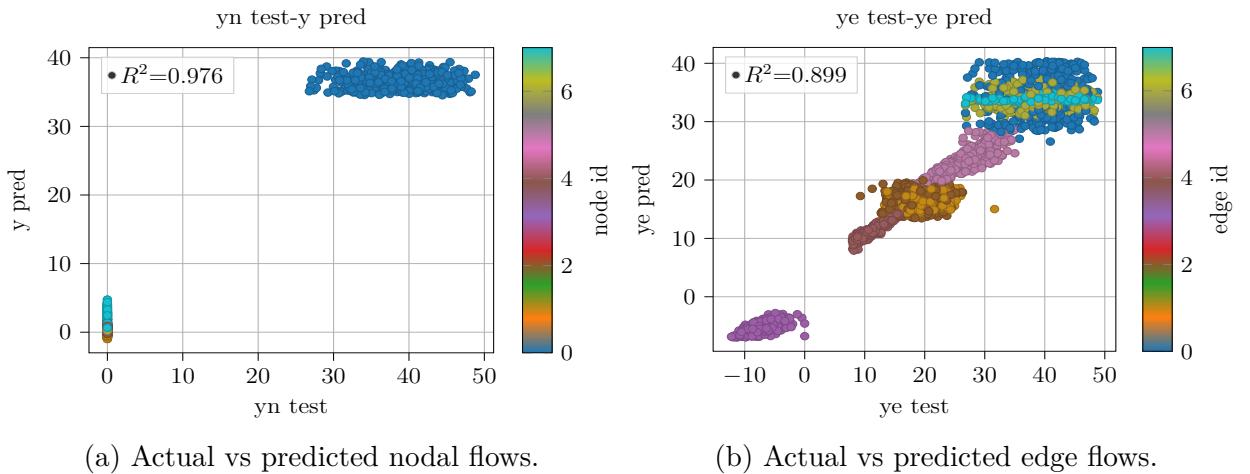


Figure 4.5: Model results using only the loss associated with nodal flow predictions in the 8-node network.

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

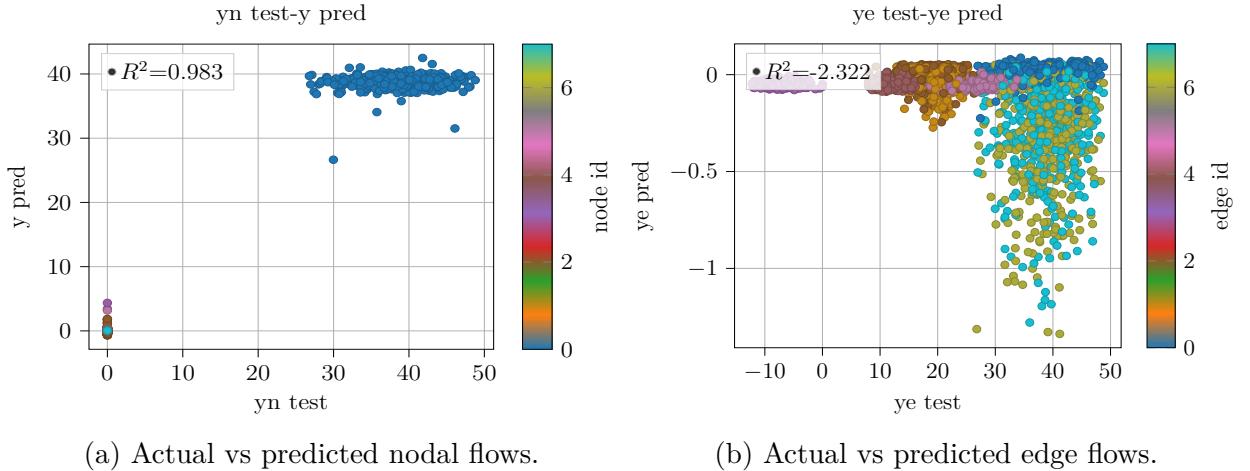


Figure 4.6: Model results using only the loss associated with nodal flow predictions in the 8-node network.

In the final stage of the experiment, only the losses associated with nodal flows and the Weymouth equation were considered. The optimal hyperparameters for this configuration were $N_{\text{channels}} = 22$, $N_{\text{layers}} = 1$, and $N_{\text{dense}} = 19$. These parameters yielded a total loss of 2.798, entirely attributed to the node loss, while the Weymouth loss was effectively zero.

The node predictions, as depicted in fig. 4.6a, continued to perform similarly to most of the previous tests, with an R^2 of 0.983, indicating consistent and accurate predictions of gas injection patterns at the nodes.

However, the edge predictions, shown in fig. 4.6b, were significantly off target in this case. The model struggled to generalize edge flows, resulting in a drastically negative R^2 of -2.32, signaling a complete failure in predicting gas flows through the network's edges.

The table 2.2 presents a comparison between the IPOPT optimization model and the GNN-based model across four experiments, varying in the inclusion of nodal loss (N) and edge loss (E). The comparison focuses on nodal flows, edge flows, nodal balance, and prediction time, with the mean and standard deviation calculated from 100 random experiments.

The IPOPT optimizer serves as the benchmark in this analysis. It achieves a mean nodal flow value of 4.81 ± 12.81 , a mean edge flow value of 23.18 ± 15.25 , and a balance value of -0.024 ± 0.308 . The prediction time for this model is 0.99 ± 0.53 seconds.

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

Method	N	E	B	W	Node Value	Edge Value	Balance Value	Time
IPOPT					4.81 ± 12.81	23.18 ± 15.25	-0.024 ± 0.308	0.99 ± 0.53
GNN	✓				4.81 ± 12.64	0.42 ± 2.36	-0.016 ± 17.448	0.13 ± 0.03
GNN	✓	✓			4.92 ± 13.02	22.96 ± 15.36	0.095 ± 1.678	0.14 ± 0.05
GNN	✓	✓	✓		4.83 ± 12.65	23.20 ± 14.92	0.004 ± 0.845	0.14 ± 0.05
GNN	✓	✓	✓	✓	4.76 ± 12.51	22.93 ± 14.64	-0.070 ± 1.665	0.14 ± 0.05
GNN	✓	✓		✓	4.88 ± 12.01	20.58 ± 12.99	0.046 ± 2.187	0.13 ± 0.03
GNN	✓			✓	4.91 ± 12.81	-0.091 ± 0.185	0.079 ± 17.225	0.14 ± 0.05

Table 4.1: Comparison of mean and standard deviation values for nodal flows, edge flows, nodal balance, and prediction time between IPOPT and GNN across different loss configurations. The columns "N", "E", "B", and "W" indicate experiments where nodal, edge, balance, and Weymouth losses were considered.

These results set the baseline for comparison against the GNN-based models.

In the first GNN experiment, which only considers nodal loss, the model predicts a nodal flow value of 4.81 ± 12.64 , closely matching the IPOPT benchmark. However, its edge flow value is considerably lower, at 0.42 ± 2.36 , reflecting the absence of an edge loss in this experiment. The balance value exhibits high variability at -0.016 ± 17.448 , indicating the model's challenge in balancing flows without edge loss. Notably, the GNN significantly reduces prediction time, averaging 0.13 ± 0.03 seconds, demonstrating its efficiency compared to the IPOPT model.

The nodal flow prediction remains consistent in the second GNN experiment, which incorporates both nodal and edge losses, with a mean of 4.92 ± 13.02 . The edge flow prediction improves significantly to 22.96 ± 15.36 , aligning closely with the IPOPT results. The balance value also improves, reducing variability with a mean of 0.095 ± 1.678 , and the prediction time remains efficient at 0.14 ± 0.05 seconds.

When balance loss is introduced alongside nodal and edge losses in the third experiment, the nodal flow value remains stable at 4.83 ± 12.65 . In comparison, the edge flow prediction improves to 23.20 ± 14.92 , closely matching the IPOPT results. The balance value becomes more consistent, with a mean of 0.004 ± 0.845 , indicating the model's enhanced ability to maintain network balance. The prediction time remains unaffected at 0.14 ± 0.05 seconds.

In the final GNN experiment, which includes the Weymouth loss along with nodal, edge, and balance losses, the nodal flow value slightly decreases to 4.76 ± 12.51 , and the edge flow value remains close to the benchmark at 22.93 ± 14.64 . The balance

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

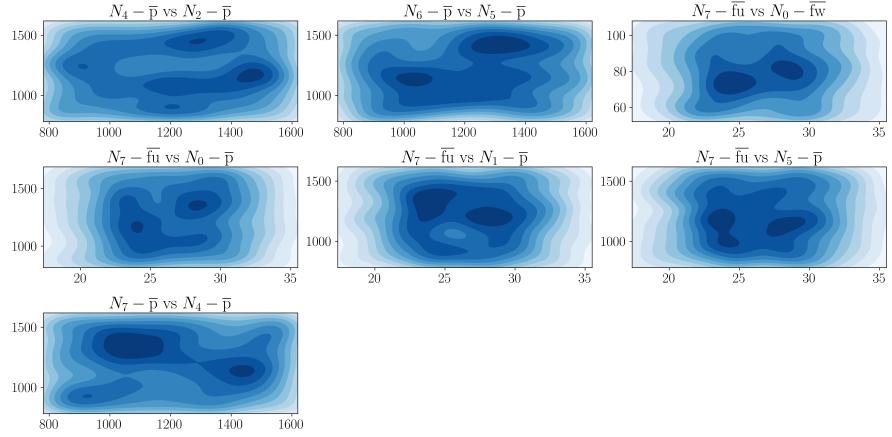


Figure 4.7: Joint PDFs between the inputs used in the 8-node network, which have two modes.

value, at -0.070 ± 1.665 , suggests a slight deviation from perfect balance, though still within acceptable variability. The prediction time remains efficient at 0.14 ± 0.05 seconds, underscoring the GNN’s capability to handle increasingly complex models without significantly increasing computational time.

Stochastic Analysis

To study the uncertainty inherent in the network further, we first computed the joint probability density functions (PDFs) for the variables used as inputs to the network. For training, each node was assigned five inputs (numbered 0 to 4), corresponding respectively to the lower limit of gas injection capacity, the upper limit of gas injection capacity, the demanded flow, the lower limit of pressure, and the upper limit of pressure. Since the lower limits are permanently fixed at zero, these two variables were excluded from the analysis. Although the training data were initially sampled from a uniform distribution, only the successfully converged samples during the optimization process were retained. Consequently, the resulting PDFs do not exhibit a uniform distribution; instead, they display a variety of distribution shapes.

Figure fig. 4.7 presents the first group of joint distributions identified in this study, characterized by the presence of two distinct modes, which likely correspond to the two main operating regimes of the system. This group includes joint patterns involving

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

the injection node (N0), the demand nodes (N6 and N7), and several intermediate or pass-through nodes (N2, N4, and N5). The observed relationships reflect the physical and topological structure of the network, particularly the connections among injection, compression, and demand points.

A relation is observed between the maximum pressure at node N4 and the maximum pressure at node N2. This is consistent with their connection via the compressor chain, where N2 is the output of compressor 1 and N4 is part of the main pipeline trajectory. Similarly, the relationship between the maximum pressures at N6 and N5 suggests a pressure dependency between this demand node and its adjacent pass-through node.

A group of distributions reveals strong associations between the maximum demand at node N7 (\bar{f}_u) and upstream variables. Specifically, N7's maximum flow shows dependence on the maximum injection flow at node N0 (\bar{f}_w), and on the maximum pressures at nodes N0, N1 (compressor 1 input), and N5. These patterns suggest that the flow capacity at the far end of the system (N7) is conditioned by both supply and compression states at the upstream nodes.

Also, a direct relationship is identified between the pressure limits of node N7 and node N4. Given their physical connection, this correlation likely reflects the way pressure constraints propagate between adjacent sections of the network.

Figure fig. 4.8 presents a second group of joint distributions identified in the study, which are characterized by low probability concentrations at their extreme values. This behavior, visually represented by lighter colors in the joint probability density functions, suggests a weaker or more dispersed correlation structure between the involved variables.

Several of these relationships involve the injection node N0 and its connection to both upstream and downstream nodes in terms of maximum pressure (\bar{p}) and maximum injection flow (\bar{f}_w). For instance, the joint distributions between the maximum pressure at N2 and N0, as well as between the maximum pressures at N3, N4, and N6 with that of N0, reveal a broadly scattered pattern. This indicates that while these variables are structurally related, their extreme values do not consistently co-occur.

A similar pattern is observed in the distributions involving the maximum pressure at N3 and the injection capacity at N0. Despite the proximity of these nodes within the system's trajectory, the weak concentration suggests a more flexible operational regime or buffering effect along the path.

Further examples include the relationships between N5 and both N0 and N2, where again, the lack of sharp density at the extremes hints at variability in how pressure is maintained or transmitted through these nodes. Lastly, the distributions between

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

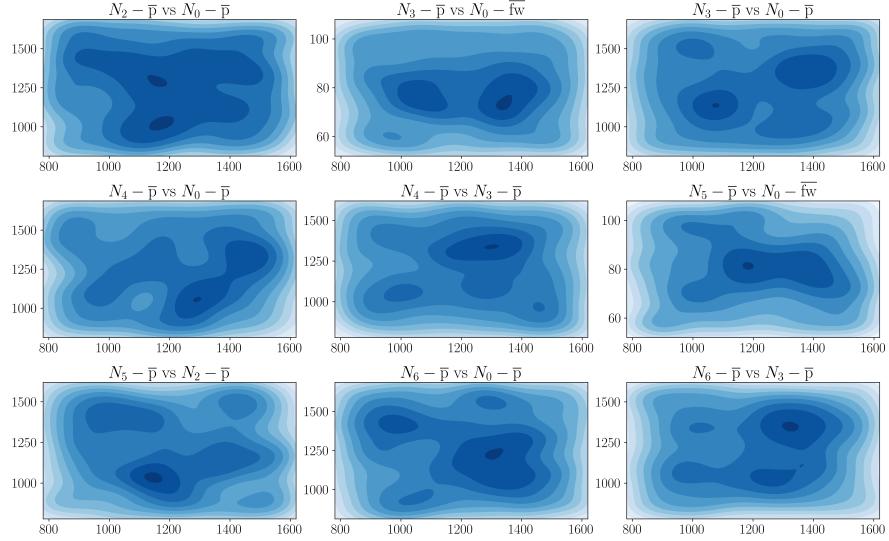


Figure 4.8: Joint PDFs between the inputs used in the 8-node network, which do not appear to have a defined mode.

the maximum pressure at N6 and both N0 and N3 continue this trend, reinforcing the interpretation that, in these cases, the system does not exhibit a strong deterministic link in the upper operational ranges of the involved variables.

Figure fig. 4.9 presents a third group of joint distributions distinguished by the presence of large dark zones in the joint probability density functions, indicating regions of high probability concentration. These distributions suggest strong dependencies between the involved variables, particularly around certain typical operating conditions of the system. A clear example is the distribution involving the maximum injection flow at node N0 and the maximum pressure at node N1, which corresponds to the input of the first compressor. The high-probability region observed here suggests a consistent relationship between the capacity to inject gas into the network and the pressure conditions at the compressor's intake, possibly reflecting operational constraints or control strategies that maintain a stable relationship between these variables.

Similarly, the joint distribution between the maximum pressure at node N1 and the pressure at node N4 — a pass-through node connected downstream — also shows a dense concentration of probability. This implies a strong coupling between the input conditions of the first compressor and the downstream pressure, likely due to the

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

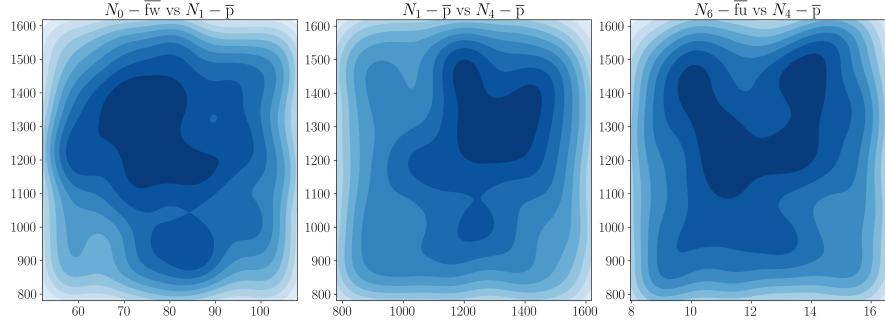


Figure 4.9: Joint PDFs between the inputs used in the 8-node network, which have a considerably wide mode with respect to the entire distribution

system's physical configuration and flow continuity. Lastly, a comparable pattern is observed in the joint distribution between the maximum demand at node N6 and the pressure at node N4. The high-probability zone here may indicate a regulatory relationship, where variations in demand at N6 are closely associated with pressure conditions at N4, possibly due to their direct physical connection and the influence of demand on local pressure levels.

To continue with the stochastic analysis, this section discusses the joint probability density functions (PDFs) that exhibit noteworthy behaviors, obtained from the output variables of the optimization model when it was supplied with the various scenarios generated through the previously described sampling process. It is important to note that, at this stage, each output variable was normalized with respect to the maximum capacity used in the corresponding scenario. That is, the values of the variables shown in this section are expressed relative to the maximum value that the variable could reach under that specific configuration.

Figure 4.10 presents the joint distributions that, at first glance, exhibit a Gaussian-like shape. However, it should be noted that these distributions tend to show greater dispersion along the first variable compared to the second. In this case, the X-axis corresponds to the normalized flow transported through pipeline E1, which connects nodes N3 and N4 and forms part of the system's closed-loop trajectory. The Y-axis in each of the four subplots represents the normalized nodal pressure at nodes N3, N4, N6, and N7, respectively. Nodes N3 and N4 are part of a compact subsystem of pass-through nodes that define the core loop of the network. N6 and N7, while functioning as demand nodes, are connected downstream of this region, with N7 specifically being supplied via

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

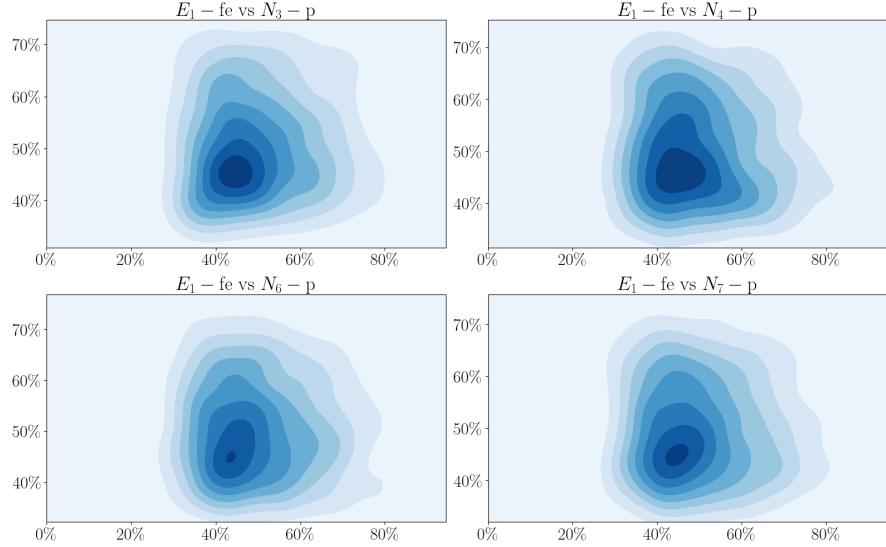


Figure 4.10: Joint PDFs between the outputs used in the 8-node network, which have a behavior quite similar to that of a Gaussian distribution.

node N4. This spatial arrangement suggests that the observed distributions highlight the interdependence between the transported flow through this central pipeline and the pressure conditions at nearby or downstream nodes. In particular, although N6 is slightly more distant, its role as a demand node may explain its inclusion in this group of correlated behaviors.

Figure 4.11 presents another group of joint probability density functions that, similar to the previous case, also exhibit a seemingly Gaussian-like behavior. However, a key difference in this case is that the X-axis in all subplots takes on negative values, ranging between 10% and 30% of the maximum limit. The variable associated with this axis in all the figures corresponds to the normalized flow transported through pipeline E3, which is the component responsible for closing the loop in the system's network structure. The variables plotted along the Y-axis correspond to various system outputs, including the normalized gas injection flow from the injection field, the nodal pressures at every node in the system and the flow transported by each pipeline.

The consistent behavior observed across these joint PDFs can be interpreted through two main considerations. First, although pipeline E3 is not essential for guaranteeing the operability of the system, it plays a key role in minimizing operational costs. As

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

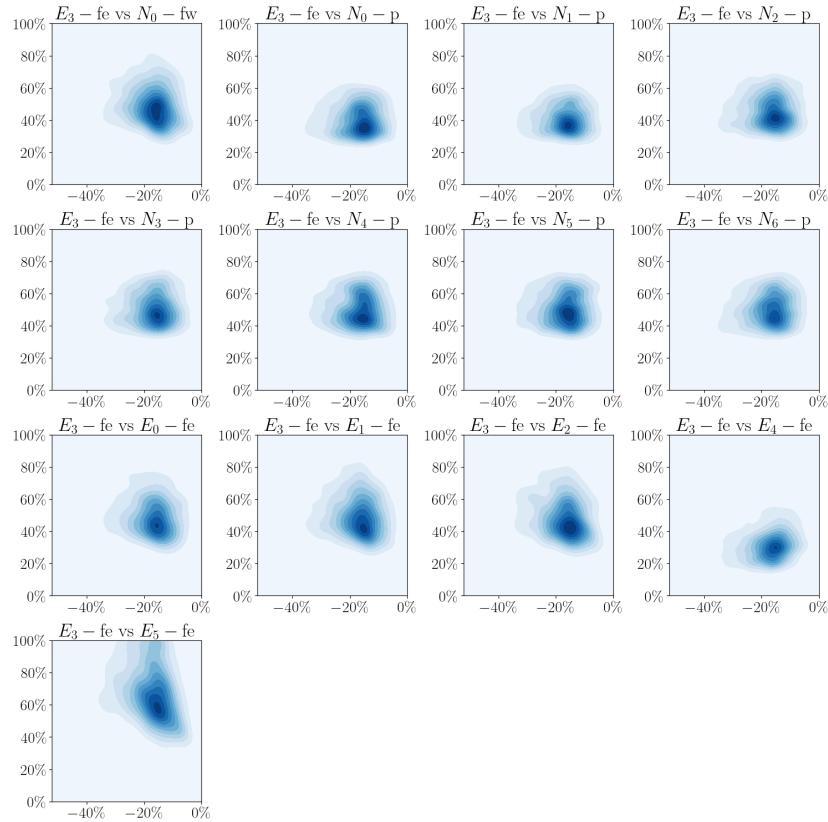


Figure 4.11: Joint PDFs between the outputs used in the 8-node network, which have a negative flow.

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

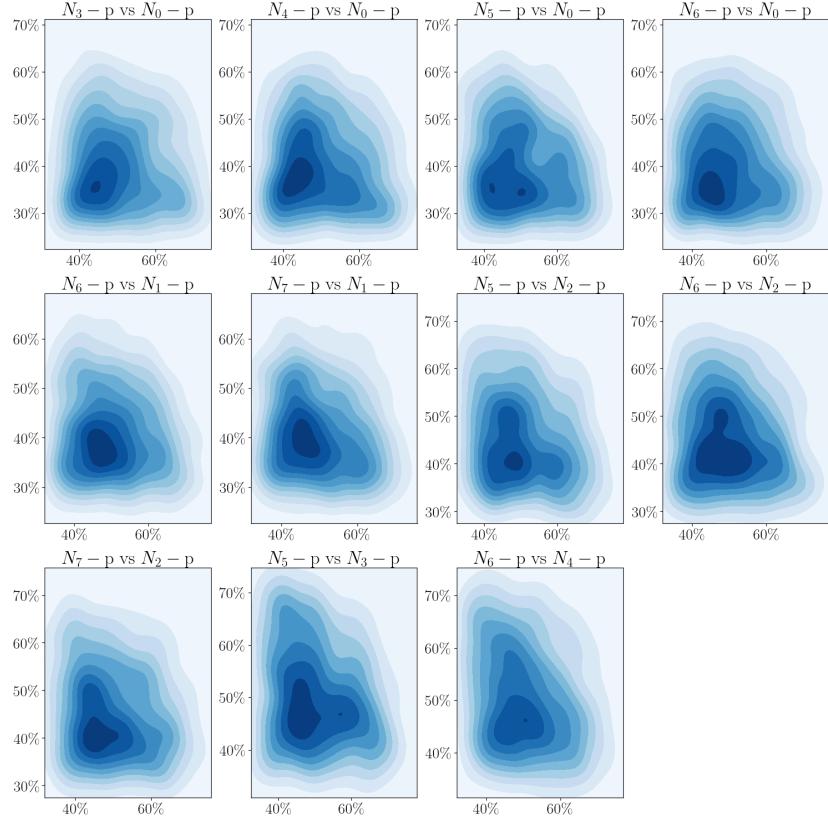


Figure 4.12: Joint PDFs between the outputs used in the 8-node network, which...

a result, its usage remains relatively low across most scenarios. Second, the negative values of the flow are due to the fact that, during the formulation of the optimization model, the assumed flow direction for this pipeline was opposite to the one actually needed to satisfy the optimal operation. Consequently, the model resolved this mismatch by assigning negative values to the transported flow in E3.

Figure 4.12 displays a third group of joint probability density functions that exhibit another notable pattern. In these distributions, both variables tend to take values within a range—approximately between 25% and 70% of their respective maximum capacities. Despite this wide span, the distributions do not resemble uniform patterns. Instead, they appear to exhibit a clear concentration of higher probability in a more restricted interval, specifically when both variables fall between 30% and 40% of their

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

normalized limits.

This behavior is particularly evident in the joint PDFs that relate nodal pressures across different yet structurally connected regions of the system. One set of these distributions involves the pressure at the injection node (N_0) and the pressures observed at downstream nodes, including the compressor-connected nodes (N_1 , N_2 , and N_3), as well as the nodes forming the closed loop (N_3 , N_4 , and N_5) and the final demand nodes (N_6 and N_7). These distributions suggest a degree of coordination in the pressure values that extends from the injection point through the compression stages and into the rest of the system.

The tendency of these variables to cluster within a narrower operational range may indicate that the system's optimal configurations favor pressure levels that are not too close to the lower or upper bounds, but rather stabilized in a middle region that ensures both efficiency and reliability. This is especially relevant in subsystems like the closed-loop segment formed by nodes N_3 , N_4 , and N_5 , which play a critical role in redistributing flow toward the demand points. The same applies to the pressures at the terminal load nodes (N_6 and N_7), which depend on adequate upstream conditions to meet demand.

To close this section, it is also relevant to examine the joint probability distributions between input and output variables (Figure fig. 4.13), particularly those in which the input variables exhibit significantly broader dispersion compared to the outputs. This behavior can be observed in a group of joint PDFs where the outputs—specifically, the flow through pipeline E_4 —tend to remain concentrated within the 20% to 40% range of their normalized capacities, while the corresponding input variables vary much more widely. It is important to highlight that, in this case, normalization was only applied to the output variables. The inputs, being defined as upper bounds or operational limits (such as the maximum allowable injection flow or pressure limits), were not normalized. Doing so would have resulted in all values being fixed at 1, effectively eliminating their variability and obscuring the nature of their influence.

The most illustrative examples of this pattern involve joint distributions between the upper bound of the injection flow at node N_0 and the flow in E_4 , as well as between the upper nodal pressure bounds at nodes N_0 through N_7 and the same pipeline output. Pipeline E_4 corresponds to the final segment delivering gas to one of the system's demand nodes. The limited range of variation in this output, despite the broad dispersion in input conditions, suggests that the optimizer consistently resolves the system by prioritizing stable and relatively low utilization of this pipeline. This might reflect either a structural limitation downstream or a strategic use of capacity to reduce operational

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

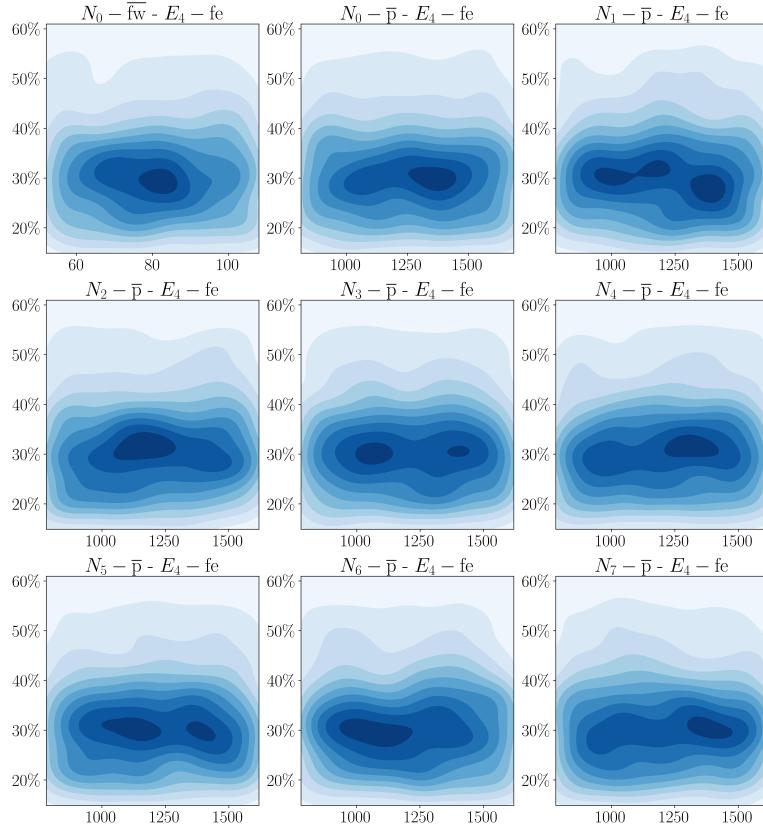


Figure 4.13: Joint PDFs between the inputs and outputs used in the 8-node network, which present a wide dispersion along second variable.

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

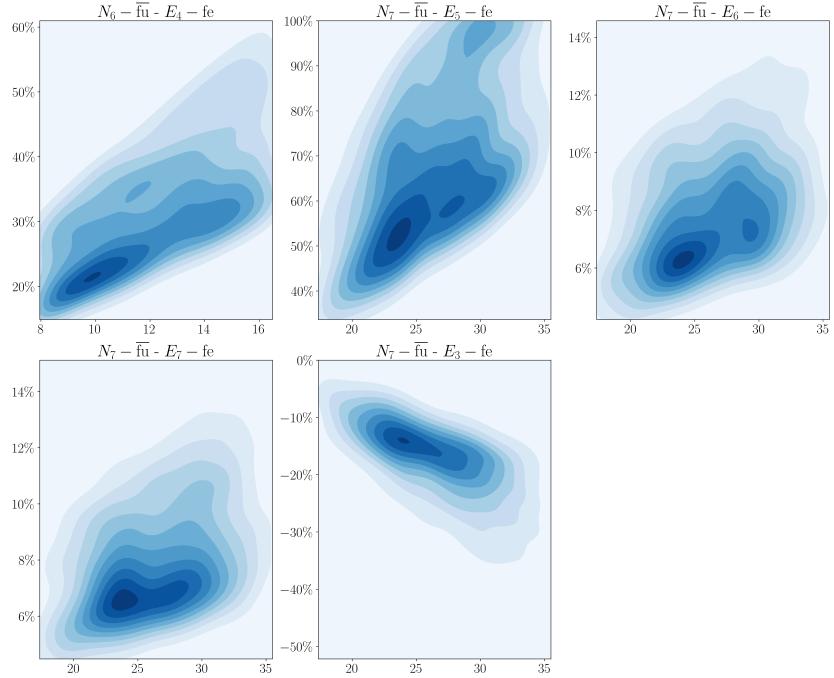


Figure 4.14: Joint PDFs between the inputs and outputs used in the 8-node network, which present a linear behavior, although with different dispersions among them.

costs, irrespective of the allowable upper bounds in the network's configuration.

Another remarkable group of joint PDFs arises from the relationship between input and output variables that exhibit a seemingly linear behavior, shown in Figure fig. 4.14. In these distributions, an increase in the input variable tends to be associated with an increase in the output variable, suggesting a positively correlated relationship. This pattern is especially evident in the pairs formed by the upper bound of the demand flow at nodes N_6 and N_7 , and the flow transported through pipelines E_4 , E_5 , E_6 , and E_7 . These pipelines are directly or indirectly responsible for supplying gas to the demand nodes, meaning that as the upper flow limits at the consumption points increase, the optimizer adjusts the flows along these pipelines accordingly, typically utilizing a larger fraction of their capacity. This suggests a direct and predictable response of the system when facing more flexible demand conditions.

However, it is important to note an exception within this group: the pair formed by the upper flow bound at node N_7 and the flow through pipeline E_3 presents a

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

negative linear relationship. In this case, an increase in the upper demand limit at N_7 is associated with a decrease in the use of pipeline E_3 . This inverse behavior can be explained by the system's looped configuration, where E_3 contributes to a closed trajectory. Under higher demand at N_7 , the optimizer might favor alternative paths that more directly satisfy the load, such as pipelines E_5 through E_7 , reducing the role of E_3 in transporting gas.

A stochastic analysis was performed to assess further the robustness of the trained GNN-based model and its ability to generalize under uncertainty. This analysis is motivated by the need to simulate and evaluate the model's responses in scenarios that were not explicitly present in the training data, thereby providing a means to quantify the variability and reliability of the model's predictions.

Initially, a kernel density estimate (KDE) was fitted to the input training data used for the GNN model. From this estimated distribution, a set of synthetic input samples, denoted as X_{sample} , was generated. These synthetic inputs were then propagated forward through the trained network, taking into account all loss components, to yield a corresponding set of output predictions, denoted as y_{sample} . In parallel, the original training inputs were propagated through the network to obtain output predictions, denoted as \bar{y}_{train} . A second KDE was then fitted using the training output data (hereafter referred to as y_{train}). Two log-likelihoods were calculated based on this second KDE: one using y_{sample} and the other using \bar{y}_{train} . The log-likelihood for the synthetic outputs, y_{sample} , was found to be $-6,696,247.56$, while the log-likelihood for the training outputs, \bar{y}_{train} , was $-6,657,534.62$. The closeness of these two values suggests that the synthetic outputs generated from the input KDE closely resemble the distribution of the training outputs.

To further evaluate the goodness-of-fit between the distributions of y_{sample} and \bar{y}_{train} , a Kolmogorov–Smirnov (K–S) test was conducted using three alternatives: two-sided, less, and more significant. The test results were as follows: a two-sided test yielded a statistic of 0.01833 with a p-value of 0.81482 (statistic location -0.34018 , sign 1); the 'less' alternative produced a statistic of 0.01167 with a p-value of 0.72137 (statistic location 0.30738 , sign -1); and the 'greater' alternative returned a statistic of 0.01833 with a p-value of 0.44640 (statistic location -0.34018 , sign 1). These statistical measures provide an initial indication that the synthetic outputs generated via the KDE-based sampling are consistent with the distribution of outputs observed during training, thereby supporting the model's capability to generalize to new, unseen scenarios.

After completing the stochastic analysis of the variables associated with the optimization model—both input and output variables—the next step involves leveraging

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

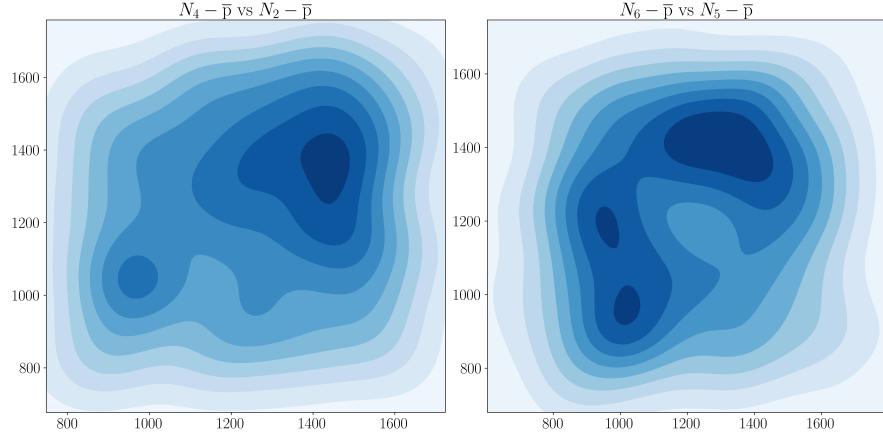


Figure 4.15: Joint PDFs between the entries used in the 8-node network, which have two modes in the KDE sampled variables

the KDE fitted to the training data. This fitted KDE was used to generate a new set of input samples that represent the learned probability distribution of the optimization model’s inputs. These samples were then propagated forward through the trained neural network model. Using the resulting network outputs, a new joint analysis was conducted, analogous to the previous one performed with the variables of the optimization model. This approach allows for evaluating the network’s ability to reproduce the statistical behavior of the system, offering an understanding of how the learned model captures the underlying probabilistic structure of the original problem.

Following the same structure presented in the first part of this analysis, we begin by highlighting the relationships that exhibit two distinct modes of operation according to their joint probability density functions. In this case, as shown in Figure fig. 4.15, only two variable pairs present this bimodal behavior when the analysis is performed using the inputs propagated through the trained neural network. These pairs are: the nodal pressure limits of N_4 and N_2 , and those of N_6 and N_5 . In both cases, the joint PDFs suggest the existence of two operational regimes, potentially associated with alternative configurations or routing strategies within the network that are learned by the neural model.

Continuing with the distributions that exhibit a very small high-probability region, four pairs of variables were identified in this case whose joint PDFs display this characteristic. These pairs are: the nodal pressure limits between N_2 and N_0 ; between N_3

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

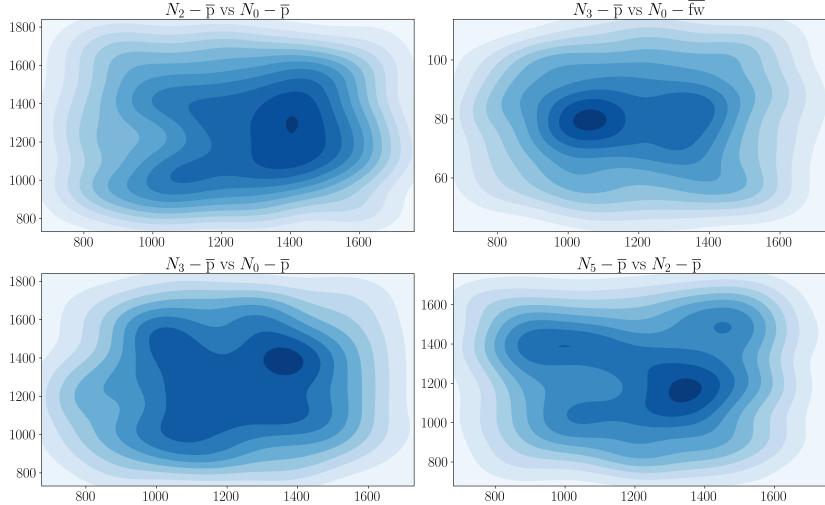


Figure 4.16: Joint PDFs between the inputs used in the 8-node network, which do not appear to have a defined mode in the KDE sampled variables.

and N_0 for both pressure and injected flow limit; and between N_5 and N_2 for nodal pressures. These distributions are characterized by a concentrated and sharply defined region of high probability, suggesting that the neural network tends to favor very specific combinations of input values during prediction. It is worth noting that, unlike in the previous analysis based on the optimization model, no distributions with broad and clearly defined high-probability zones (i.e., darker and more extensive areas) were observed.

Figure 4.17 presents a group of joint probability density functions that, while resembling Gaussian-like distributions, often exhibit some degree of skewness. A particularly striking feature in these plots is the consistent behavior of the flow transported through pipeline E_3 , the segment that completes the loop in the system's topology. In every case, this variable—represented on the X-axis—takes on negative values, typically between 10% and 30% of its normalized capacity.

This consistent negative trend can be interpreted as the network having learned that, under optimal conditions, the flow through pipeline E_3 should operate in the direction opposite to the one originally assumed in the problem formulation. The reversal in direction is not only coherent with the physical and economic constraints of the system, but also mirrors the behavior found in the optimization model. Furthermore, this

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

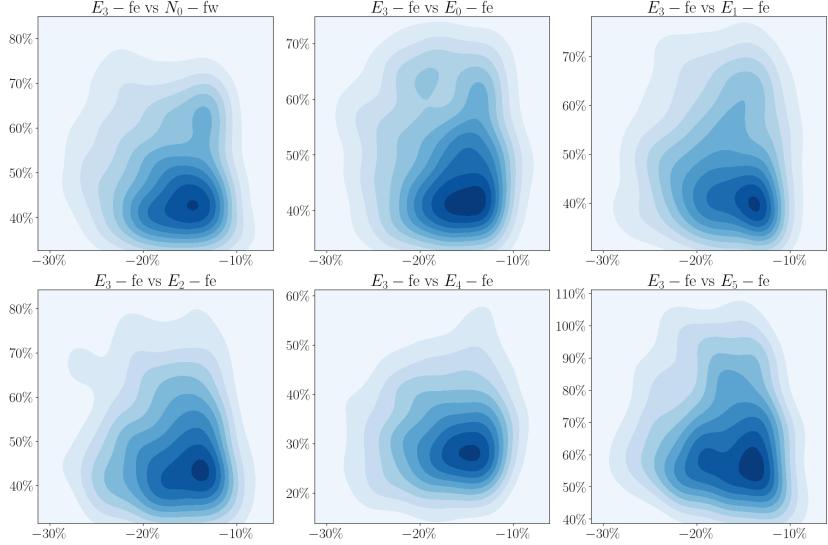


Figure 4.17: Joint PDFs between the outputs used in the 8-node network, which have a negative flow in the KDE sampled variables.

pattern is robust across a diverse set of operating scenarios, as evidenced by the variables plotted along the Y-axis, which include the total injection at node N_0 and the flows through pipelines E_0 , E_1 , E_2 , E_4 , and E_5 .

Continuing with the comparison between input and output variables, a similar pattern to that observed in the optimization model reappears in the neural network predictions. As shown in Figure fig. 4.18, there is a group of joint probability distributions where the input variables span a wide range of values, while the corresponding output—specifically, the flow through pipeline E_4 —remains narrowly concentrated between 20% and 40% of its normalized capacity. This behavior mirrors what was previously discussed for the optimization model, suggesting that, even under the learned data distribution, the network consistently predicts a relatively low and stable utilization of this particular pipeline.

The pairs exhibiting this characteristic include the upper bound on injection flow at node N_0 and the upper bounds on nodal pressures at nodes N_0 through N_7 , all compared against the predicted flow through pipeline E_4 . As in the previous case, normalization was only applied to the output variables, while the inputs were left in their original scale, reflecting their interpretation as operational constraints rather than ac-

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

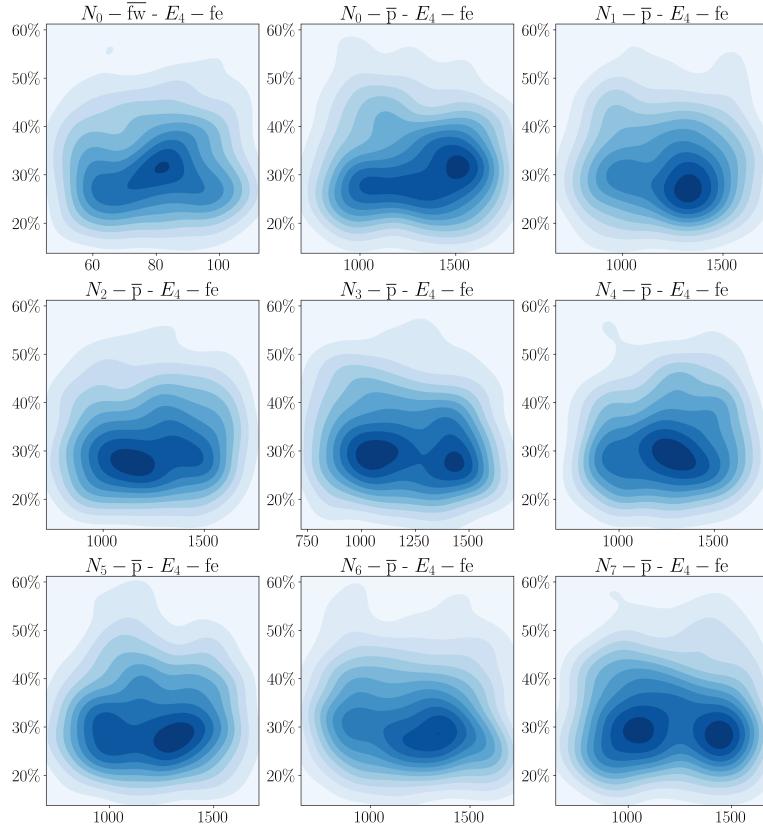


Figure 4.18: Joint PDFs between the inputs and outputs used in the 8-node network, which present a wide dispersion along second variable.

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

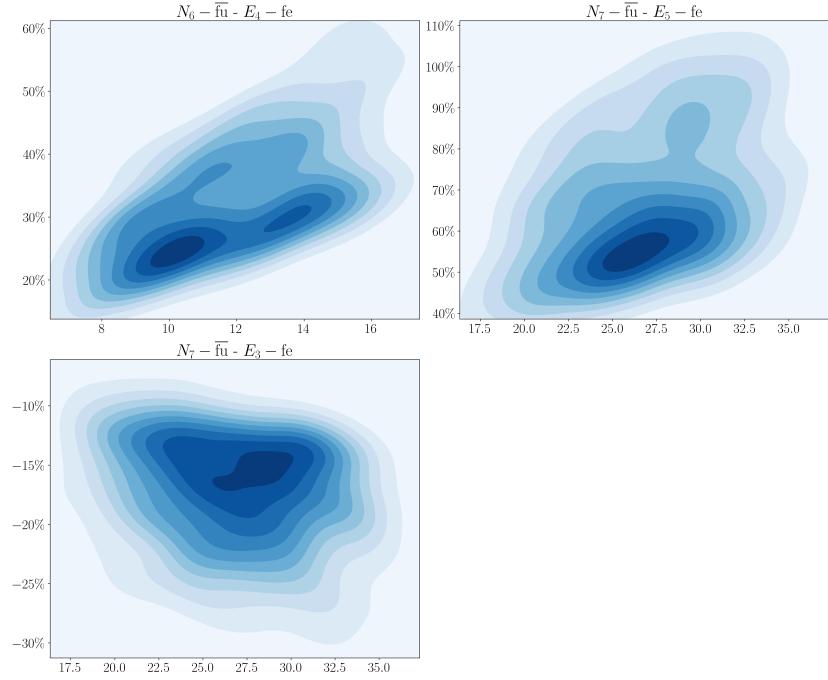


Figure 4.19: Joint PDFs between the inputs and outputs used in the 8-node network, which present a linear behavior, although with different dispersions among them.

tual realizations. The similarity in joint distribution patterns between the optimization model and the neural network predictions indicates that the trained model effectively internalized a similar resolution strategy, favoring stable usage of pipeline E_4 regardless of the variability in input conditions.

A final group of joint distributions worth highlighting involves input and output variables that exhibit a linear relationship, similar to the patterns observed in the optimization model (Figure fig. 4.19). In particular, two of the joint PDFs show a positive correlation, where increases in the input variable are associated with proportional increases in the output. This behavior is seen in the pairs formed by the upper bound of the demand flow at node N_6 and the predicted flow in pipeline E_4 , as well as between the same bound at node N_7 and the predicted flow in pipeline E_5 . These relationships suggest that the network has captured a coherent system response, in which more flexible demand conditions at the consumption nodes lead to higher utilization of the pipelines supplying them—closely resembling the optimizer’s behavior.

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

A third pair—formed by the upper demand bound at node N_7 and the flow in pipeline E_3 —also shows a strong linear pattern, though in this case the correlation is negative. That is, an increase in the input variable corresponds to a decrease in the pipeline’s predicted utilization. This result mirrors the exception found in the optimization model, and can again be attributed to the presence of a loop in the network’s structure. Under increasing demand at N_7 , the network tends to shift the flow away from pipeline E_3 , likely in favor of more direct paths that connect to the demand node. This further confirms that the trained model not only replicates the general operating tendencies of the optimization scheme but also reflects more subtle topological effects embedded in the system configuration.

4.2.2 Case Study II: 63-node Network (Colombia)

This section addresses the second case study, focusing on the Colombian natural gas network. As in the previous cases, this analysis explores various configurations of loss functionals to evaluate the predictive performance of the GNN-based model. The first experiment examines the model’s predictive capabilities when incorporating node and edge losses.

This experiment used optimized hyperparameters, with $N_{\text{channels}} = 21$, $N_{\text{layers}} = 5$, and $N_{\text{dense}} = 4$, which were selected to enhance the model’s performance. The experiment yielded a total loss of 267,600, encompassing node and edge losses, along with a calculated balance loss. Specifically, the node loss reached 17,537, while the edge loss was considerably higher at 250,063. Additionally, a balance loss of 338,729 was recorded. Notably, the balance loss was calculated to assess network consistency but was not incorporated into the model’s cost function during training; instead, it serves as an independent evaluation metric.

The GNN-based model’s predictive accuracy in this experiment was quantified using R^2 metrics, and the results are shown in fig. 4.20. The nodal predictions exhibited high accuracy, with an R^2 score of 0.993 in fig. 4.20a, indicating that the model closely approximates the observed nodal flow values. Similarly, the edge predictions achieved an R^2 score of 0.963, demonstrating robust performance in predicting edge flows. This last value can be seen in fig. 4.20b.

The second experiment evaluated the GNN-based model, focusing on losses associated with nodes and balance. Using the optimized hyperparameters $N_{\text{channels}} = 49$, $N_{\text{layers}} = 5$, and $N_{\text{dense}} = 2$, the model yielded a total loss of 24,888. This loss value includes a node loss of 17,019, a calculated edge loss of 2,912.201, and a balance loss of 7,868. In this experiment, only the node and balance losses were included in the

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

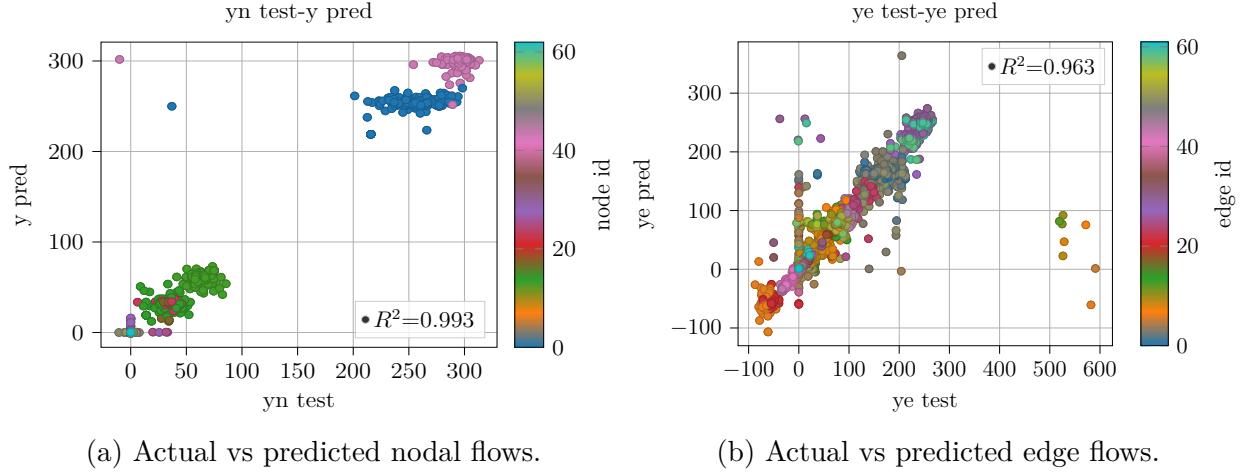


Figure 4.20: Model results using only the loss associated with nodal flow predictions in the 8-node network.

model's cost function, while the edge loss was computed independently to assess prediction accuracy for edge flows.

The predictive accuracy, evaluated using R^2 metrics, yielded $R^2 = 0.993$ for nodal predictions and $R^2 = 0.569$ for edge predictions, as shown in fig. 4.21a and fig. 4.21b. The scatterplot in fig. 4.21a illustrates the accuracy of nodal predictions, with predicted values aligning closely to the true values. In contrast, the scatterplot in fig. 4.21b reveals less consistency in edge predictions, likely due to the exclusion of edge loss from the cost function. Although a general linear trend is observable between predicted and true values in this scatterplot, a notable number of inaccurately predicted values diminish the overall R^2 , impacting the edge loss and prediction accuracy.

The third experiment evaluated the GNN-based model's predictive capabilities by incorporating losses associated with nodes, edges, and balance. With the optimized hyperparameters $N_{\text{channels}} = 20$, $N_{\text{layers}} = 5$, and $N_{\text{dense}} = 2$, the model achieved a total loss of 347,647, including a node loss of 37,684, an edge loss of 264,187, and a balance loss of 45,776. This experiment integrated all three losses into the model's cost function, allowing a more comprehensive assessment of its predictive performance.

The predictive accuracy was quantified by R^2 values of 0.984 and 0.961 for nodes and edges, respectively, as shown in fig. 4.22a and fig. 4.22b. In these scatterplots, the predictions demonstrate a clearer alignment with the true values, with both graphs illustrating shapes more similar to straight lines, which indicates improved model per-

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

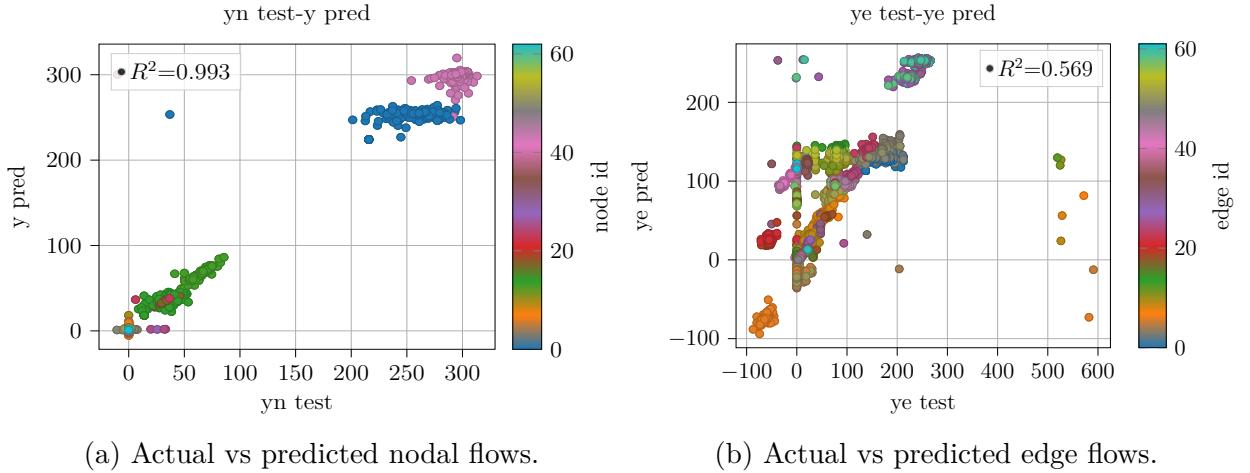


Figure 4.21: Model results using only the loss associated with nodal flow predictions in the 8-node network.

formance in capturing the underlying patterns of nodal and edge flows.

This third experiment marks the final test conducted in this study. Attempts to include the Weymouth loss were hindered by significant computational complexity, preventing the acquisition of reliable results for the model when considering the Weymouth function loss. Therefore, further tests were not feasible within the current scope.

Method	N	E	B	Node Value	Edge Value	Balance Value	Time
IPOPT	✓			11.32 ± 48.89	63.38 ± 83.11	-2.18 ± 29.78	13.65 ± 2.86
GNN	✓			11.22 ± 49.03	62.73 ± 81.99	-2.28 ± 25.48	0.15 ± 0.04
GNN	✓	✓		12.47 ± 48.89	88.32 ± 73.55	-1.03 ± 1.90	0.15 ± 0.05
GNN	✓	✓	✓	12.33 ± 48.64	63.06 ± 81.32	-1.17 ± 7.38	0.15 ± 0.04

Table 4.2: Comparison of mean and standard deviation values for nodal flows, edge flows, nodal balance, and prediction time between IPOPT and GNN across different loss configurations. The columns "N", "E", and "B" indicate experiments where nodal, edge, and balance losses were considered.

The table 4.2 provides a comparison between the IPOPT optimization model and the GNN-based model across four experiments that incorporate different combinations of nodal (N), edge (E), and balance (B) losses. The results focus on nodal flows, edge flows, nodal balance, and prediction time, with mean and standard deviation values.

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

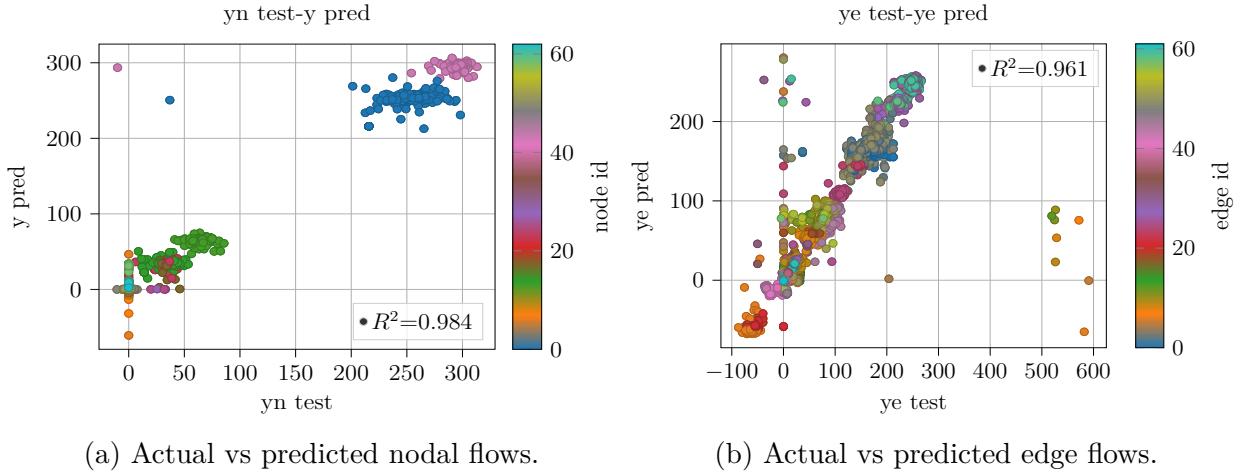


Figure 4.22: Model results using only the loss associated with nodal flow predictions in the 8-node network.

In this table, the IPOPT model serves as the baseline. It achieves a nodal flow mean of 11.32 ± 48.89 , an edge flow mean of 63.38 ± 83.11 , and a balance value mean of -2.18 ± 29.78 . The prediction time for this benchmark model is 13.65 ± 2.86 seconds, providing a standard for comparison with GNN-based models.

The first GNN experiment considers only the nodal loss. It produces a nodal flow mean of 11.22 ± 49.03 , closely aligning with the IPOPT nodal flow. The edge flow mean, at 62.73 ± 81.99 , is also similar to IPOPT's results. The balance value mean of -2.28 ± 25.48 shows moderate variability, while the GNN's prediction time is notably faster, at 0.15 ± 0.04 seconds.

In the second GNN experiment, both nodal and edge losses are incorporated. The nodal flow prediction mean slightly increases to 12.47 ± 48.89 , while the edge flow mean shows a more significant increase, reaching 88.32 ± 73.55 . The balance value improves in consistency, with a mean of -1.03 ± 1.90 , and the prediction time remains low at 0.15 ± 0.05 seconds, indicating efficient computation.

The third GNN experiment includes nodal, edge, and balance losses. Here, the nodal flow means it is 12.33 ± 48.64 , and the edge flow means returns to a closer alignment with IPOPT at 63.06 ± 81.32 . The balance value stabilizes, reaching -1.17 ± 7.38 , while the prediction time remains consistent at 0.15 ± 0.04 seconds.

This table illustrates the GNN model's capability to maintain accurate predictions and achieve lower computational time than IPOPT, especially when incorporating more

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

loss components.

An uncertainty analysis similar to the previous case was performed for the Colombian natural gas transportation network. Using the same methodology, a second kernel density estimate (KDE) was fitted to the training output data, and synthetic outputs were generated. The log-likelihood computed from the synthetic outputs was $-104,413,419.34$, while that computed from the training outputs was $-104,037,047.58$. In addition, a Kolmogorov–Smirnov (K–S) test was carried out under three different alternatives, yielding the following results: a test statistic of 0.00527 with a p-value of 0.95556 (statistic location 0.52109, statistic sign -1); a test statistic of 0.00527 with a p-value of 0.59061 (statistic location 0.52109, statistic sign -1); and a test statistic of 0.00324 with a p-value of 0.81777 (statistic location -0.73443 , statistic sign 1). These findings indicate a high similarity between the synthetic and training outputs, as the low test statistics and high p-values suggest that the two distributions are statistically indistinguishable. The slight differences in log-likelihood values further confirm that the synthetic data effectively capture the essential characteristics of the training data, thereby validating the robustness of the stochastic sampling approach for this network.

4.3 Discussion and conclusions

This chapter’s first set of experiments provides insights into the model’s capability to handle gas network predictions with various loss function combinations. Including node and edge losses in the initial experiment demonstrated the model’s capacity to accurately capture node behavior, as evidenced by a high R^2 value of 0.983 for nodal flow predictions. This result indicates the model’s ability to learn injection patterns at the nodes, even under nonlinear system conditions.

Incorporating the gas balance loss in subsequent experiments maintained the accuracy of nodal predictions, with no notable change in the R^2 for node flows. However, the slight reduction in the R^2 for edge flows to 0.973 suggests that while the gas balance constraint improved overall network consistency, it introduced additional complexity that slightly affected edge prediction performance. This outcome highlights a trade-off between accurate node predictions and balanced edge flows, indicating robust model performance with some sensitivity to changes in loss function configurations.

Further exploration of the model’s response to including the Weymouth equation loss introduced more pronounced effects, particularly on edge flow predictions. The decline in R^2 to 0.952 for edge flows indicates increased difficulty in accurately modeling flow through specific network paths, particularly in regions with closed loops or com-

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

pressor installations. This outcome underscores the challenge of incorporating multiple nonlinear physical constraints, especially in complex configurations.

In the experiment where only the Weymouth equation and node losses were considered, the model maintained a high R^2 for nodal flows. However, the extremely low R^2 for edge predictions, reaching negative values, suggests the model struggled to generalize edge flows effectively when isolated from balancing and edge losses. This finding reinforces the need for a comprehensive loss framework incorporating node and edge dynamics to ensure robust network performance, highlighting the challenges of predicting edge flows under limited constraints.

Comparing the results from chapter 2 with those in chapter 4 reveals that the addition of physical constraints in chapter 4 improves model performance, particularly in terms of balancing accuracy.

The losses presented in chapter 2 (Table 2.1) reflect initial configurations with only nodal and edge losses. In these setups, while nodal and edge values show reasonable consistency with the APOPT optimizer, the balance values exhibit higher variability, especially in the GNN configurations. For example, when both nodal and edge losses are applied, the GNN model in chapter 2 produces a balance error of -5.711 ± 16.854 , which differs significantly from the APOPT optimizer's near-zero balance error (-0.001 ± 0.038). This difference indicates that the simpler GNN models in chapter 2 lack additional constraints to replicate the physical conditions accurately.

In chapter 4, adding constraints related to balance and the Weymouth equation (Table 4.2) leads to improved balance accuracy. For instance, the GNN model with nodal, edge, and balance losses achieves a balance error of 0.004 ± 0.845 , considerably lower and more consistent with the IPOPT optimizer. This improvement demonstrates how adding balance constraints reduces variability and error associated with balance. Additionally, GNN configurations that include balance and Weymouth constraints (i.e., N, E, B, W) sustain this balance improvement while closely aligning with APOPT, which results in nodal and edge values.

In the second experiment, the performance of the GNN-based model was evaluated in three configurations with different combinations of loss functions applied to the Colombian natural gas network. For each configuration, it was possible to consider the nodal losses, the losses associated with the edges, and the gas balance dede. The analysis provides information on the trade-offs and improvements observed with each additional loss function.

The first configuration of the GNN model, which incorporated nodal and edge losses, achieved high accuracy in predicting nodal flows with an R^2 score of 0.993 while main-

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

taining an edge prediction R^2 of 0.963. This configuration showed strong performance in nodal predictions, suggesting that focusing on this loss combination allows a good approximation of nodal flows in the system. The balance loss value, calculated independently, highlighted minimal deviation, indicating that nodal accuracy alone could achieve network consistency for this setup. These results underscore the model's capacity to generalize nodal flow predictions while capturing nodal behaviors, making this configuration efficient for applications where nodal flow prediction is prioritized.

The second configuration evaluated the impact of including nodal and balance losses in the model's cost function. The results demonstrated a stable nodal prediction performance, with an R^2 score consistent at 0.993, while edge predictions dropped to an R^2 of 0.569. This reduction in edge prediction accuracy suggests that excluding edge loss from the cost function introduced inconsistencies in the edge flows, as reflected in the decreased R^2 value. Despite the moderate accuracy in edge flow predictions, the balance loss value remained relatively low, indicating stable nodal balance but highlighting a trade-off when optimizing only nodal and balance aspects.

In the third configuration, the GNN model included all three loss types: nodal, edge, and balance. This approach achieved a slightly lower R^2 of 0.984 for nodal predictions but improved the edge prediction accuracy, yielding an R^2 of 0.961. The overall alignment of predictions observed in the scatterplots suggests that incorporating all three loss functions enabled the model to more comprehensively capture the patterns of both nodal and edge flows. This approach demonstrated the most balanced trade-off between nodal and edge prediction accuracy, supporting the hypothesis that optimizing all three aspects simultaneously enhances the model's capacity to predict flows in the Colombian natural gas network.

Finally, the performance of the GNN-based model for the Colombian natural gas network is compared in two experimental configurations: Chapter 2 and Chapter 4. Each experiment considered nodal, edge, and balance loss combinations, assessing their effects on prediction accuracy and computational efficiency. Notably, due to high computational demands, the experiments in Chapter 4 did not include the Weymouth equation loss.

In Chapter 2 (Table 2.2), the GNN-based model, when only the nodal loss was applied, achieved a Node Value of 11.38 ± 49.13 and an Edge Value of 0.91 ± 1.26 , with a Balance Value of -2.19 ± 58.56 . The model showed relatively high accuracy in nodal predictions and achieved minimal edge prediction errors, highlighting the model's effectiveness in capturing nodal flows without explicitly optimizing for edge loss.

In Chapter 4 (Table 4.2), the experiments showed varied performance depending on

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

the losses included:

1. In the configuration considering only nodal loss, the GNN achieved a Node Value of 11.22 ± 49.03 and an Edge Value of 62.73 ± 81.99 , with a Balance Value of -2.28 ± 25.48 . Compared to Chapter 2, this configuration demonstrated a higher edge error, suggesting that solely optimizing nodal loss did not generalize as effectively for edge predictions as observed previously.
2. When both nodal and edge losses were included, the GNN model's Node Value increased to 12.47 ± 48.89 , with a significant rise in Edge Value error to 88.32 ± 73.55 . The Balance Value was reduced to -1.03 ± 1.90 , indicating improved nodal balance but an unfavorable impact on edge prediction. This result diverges from Chapter 2, where the inclusion of edge loss contributed to more consistent results in both nodal and edge values.
3. In the configuration considering nodal, edge, and balance losses, the GNN model achieved a Node Value of 12.33 ± 48.64 , with an Edge Value of 63.06 ± 81.32 and a Balance Value of -1.17 ± 7.38 . This approach achieved better balance accuracy but did not markedly improve edge error over configurations excluding balance loss, contrasting with Chapter 2, where combined losses had more favorable outcomes.

Across both chapters, it is clear that optimizing for multiple loss functions introduces complexity, with varied impacts on nodal and edge prediction accuracy. The Chapter 4 results indicate that including balance and edge losses improves nodal balance but can lead to edge-accuracy trade-offs. Further optimization strategies or alternative methods may be required to balance all metrics.

The stochastic analysis performed on the 8-node network provided valuable insights into the inherent uncertainty of the system. By fitting a kernel density estimate (KDE) to the training input data and generating synthetic input samples (X_{sample}), these were propagated through the trained network to obtain corresponding outputs (y_{sample}). A second KDE was then fitted to the training outputs (y_{train}), and log-likelihood values were computed for both y_{sample} and the outputs derived from the training inputs (\bar{y}_{train}). The proximity of these log-likelihood values, along with high p-values and low test statistics from the Kolmogorov–Smirnov tests, confirms that the synthetic outputs closely mirror the original training output distribution. This result validates the stochastic sampling approach and indicates that the model accurately captures the underlying data distribution, enabling rapid evaluation of new scenarios.

A similar stochastic analysis was conducted on the Colombian natural gas network. In this case, the log-likelihood computed from the synthetic outputs was $-104,413,419.34$ compared to $-104,037,047.58$ for the training outputs. The Kolmogorov–Smirnov

CHAPTER 4. ENHANCED NATURAL GAS FLOW PREDICTIONS USING PHYSICS-GUIDED NEURAL NETWORKS

tests, performed under various alternatives, yielded low test statistics and high p-values, further supporting the similarity between the two distributions. These outcomes underscore the robustness of the stochastic framework, demonstrating that the trained model generalizes well to new, unseen scenarios. Consequently, the approach enhances the understanding of model uncertainties and provides a reliable basis for rapid scenario analysis and uncertainty quantification of natural gas network operations.

Chapter 5

Conclusions and future work

5.1 Conclusions

This thesis set out to develop an optimization tool for natural gas transportation networks by combining knowledge of the network topology, an appropriate approximation of the Weymouth equation, and stochastic optimization techniques. Each specific objective contributed to achieving this goal, and the progress toward each objective is presented across the thesis chapters.

The first specific objective was to design a Graph Neural Network (GNN)-based approach that integrates natural gas network topology to reduce computational time for operational estimation. This objective was explored in Chapters 2 and 4, where a GNN-based model was applied to predict decision variables of the natural gas system while significantly reducing computation times compared to traditional optimization techniques. Both chapters included comparisons of computation times between optimizer-based methods and the GNN-based approach, with the GNN consistently providing faster results. In Chapter 2, a GNN was trained to approximate a standard linear optimization model for a simplified gas system (without pressure considerations) and then tested on more extensive networks, such as the Colombian gas system. Chapter 4 extended this work by incorporating physical constraints, like gas balance and the Weymouth equation, into the loss function, resulting in a more physically accurate model with consistent gains in computational efficiency. Across all tests, the GNN model provided predictions much faster than optimizers, demonstrating that this approach successfully meets the objective of reducing computational time for operational estimation.

CHAPTER 5. CONCLUSIONS AND FUTURE WORK

The second specific objective was to develop an optimization model for natural gas transportation systems that incorporates the Weymouth equation to reduce approximation errors in gas flow calculations. Chapter 3 addressed this objective by developing a Mathematical Program with Complementarity Constraints (MPCC)-based optimization model that accurately represents the nonlinear Weymouth equation without needing mixed-integer formulations. The MPCC approach utilized binary-behaving continuous variables to capture the bidirectional nature of gas flows and handle complex, high-demand scenarios in interconnected networks. The model was tested on real-world systems, including the Colombian gas-power system, and consistently achieved a lower error response than traditional methodologies, providing a robust and accurate tool for operational scheduling in energy systems. By effectively modeling the nonlinear constraints of the Weymouth equation, this MPCC-based model met the objective of improving accuracy in pipeline flow calculations.

The third specific objective was to develop a stochastic optimization strategy that quantifies uncertainties in gas system operation by sampling from the probability distributions of the constraints in the transportation problem. Chapters 2 and 4 provided a foundational approach to stochastic optimization by demonstrating that GNN-based models, once trained, can rapidly generate responses to various scenarios through forward propagation alone. This rapid response capability enables the GNN-based model to efficiently test multiple scenarios quickly, effectively managing uncertainties in the system without needing to solve an optimization problem from scratch for each scenario. In Chapter 2, the GNN model was shown to provide fast, low-error responses for new, unseen cases, and Chapter 4 extended this capacity by incorporating additional physical constraints, further enhancing the GNN's ability to model complex and variable network conditions with high accuracy. Although a fully probabilistic optimization framework was not implemented, the capability to quickly test many scenarios aligns with stochastic optimization principles, allowing for rapid evaluation of uncertain conditions within the network.

In summary, this thesis demonstrated the potential of GNN-based and MPCC models as complementary tools for natural gas transportation network optimization and prediction. The GNN model offered substantial computational efficiency and adaptability to network topology, while the MPCC model provided high accuracy in modeling the nonlinear constraints imposed by gas flows. Together, these approaches support real-time applications requiring computational efficiency and accuracy.

5.2 Future Work

Future research can explore several directions to enhance the application and effectiveness of GNN-based models and MPCC formulations in natural gas and energy systems. One important avenue is extending the GNN-based model to handle transient dynamics and uncertainties, which is particularly valuable in applications that involve renewable energy integration.

Another potential direction involves the development of stochastic and distributed models. Integrating stochastic modeling into the MPCC formulation could achieve a more robust optimization framework under demand fluctuations and supply variability scenarios.

Improving the design of loss functions in GNN models is another promising area. As demonstrated in this work, the performance of GNN-based models can be improved by incorporating physical constraints. In that sense, an area of interest could focus on implementing loss functions associated with the Weymouth equation with a lower computational complexity so that they can be used in complex systems.

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