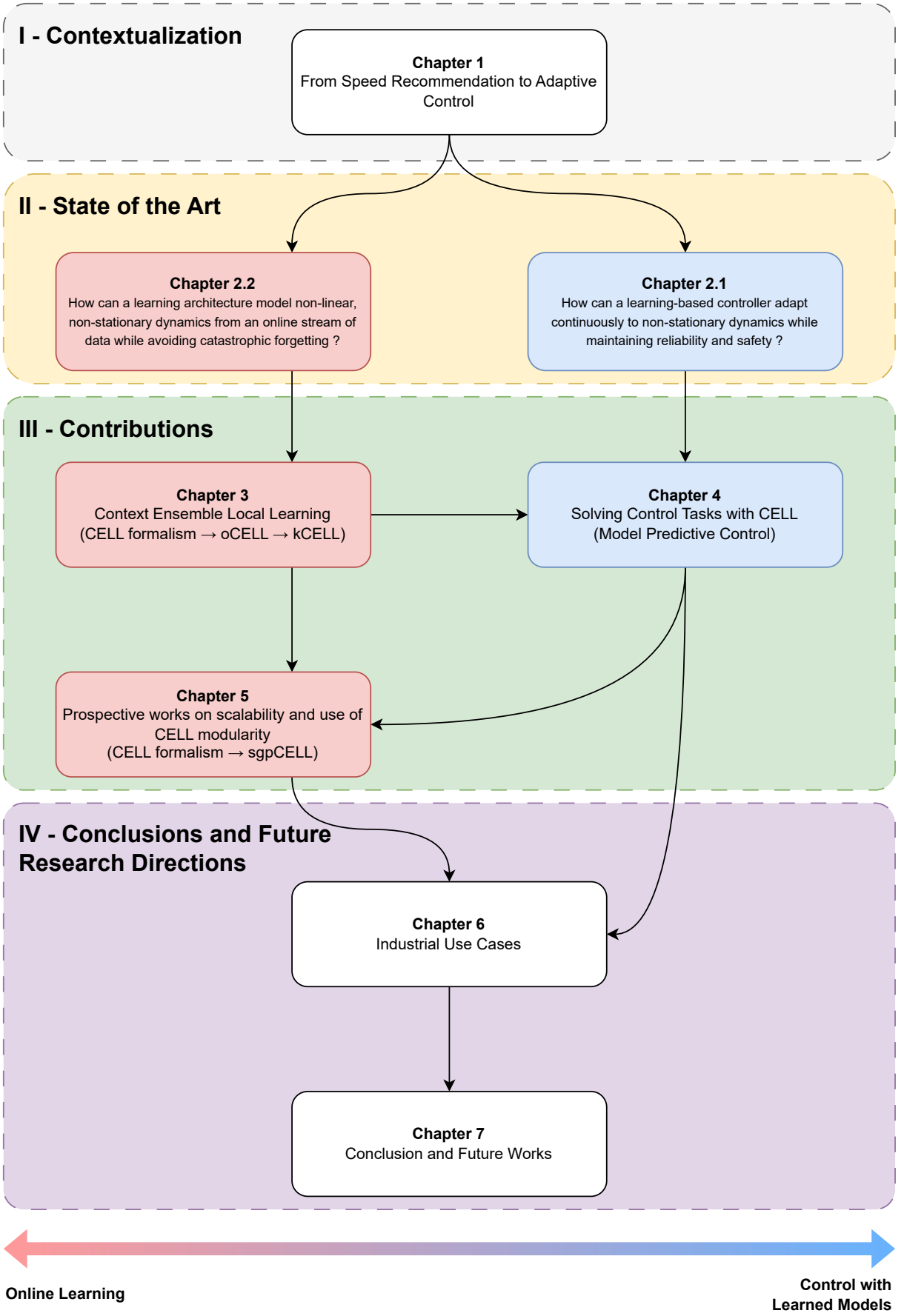
I - Contextualization
Chapter 1
From Speed Recommendation to Adaptive Control
II - State of the Art
Chapter 2.2
How can a learning architecture model non-linear, non-stationary dynamics from an online stream of data while avoiding catastrophic forgetting ?
Chapter 2.1
How can a learning-based controller adapt continuously to non-stationary dynamics while maintaining reliability and safety ?
III - Contributions
Chapter 3
Context Ensemble Local Learning
(CELL formalism → oCELL → kCELL)
Chapter 4
Solving Control Tasks with CELL
(Model Predictive Control)
Chapter 5
Prospective works on scalability and use of CELL modularity
(CELL formalism → sgpCELL)
IV - Conclusions and Future Research Directions
Chapter 6
Industrial Use Cases
Chapter 7
Conclusion and Future Works
Online Learning
Control with Learned Models