

OpenCMISS-iron examples and tests used by OpenCMISS developers at University of Stuttgart, Germany

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1 TEST SUMMARY

Passed tests: 180 / 206

1.1 Details

Content of: example-0001/results/failed.tests

Content of: example-0001-u/results/failed.tests

current_run/l2x1x0_n8x4x0_i8_s0/Example.part0.exnode
current_run/l2x1x0_n8x4x0_i8_s1/Example.part0.exnode

| CHeart - Iron |₂ = 0.05804
| CHeart - Iron |₂ = 0.05804

Content of: example-0002/results/failed.tests

Content of: example-0003/results/failed.tests

Failed tests:

current_run/l2x1x0_n2x1x0_i1_s0/Example.part0.exnode
current_run/l2x1x0_n4x2x0_i1_s0/Example.part0.exnode
current_run/l2x1x0_n8x4x0_i1_s0/Example.part0.exnode
current_run/l2x1x0_n2x1x0_i2_s0/Example.part0.exnode
current_run/l2x1x0_n4x2x0_i2_s0/Example.part0.exnode
current_run/l2x1x0_n8x4x0_i2_s0/Example.part0.exnode
current_run/l2x1x0_n2x1x0_i1_s1/Example.part0.exnode
current_run/l2x1x0_n4x2x0_i1_s1/Example.part0.exnode
current_run/l2x1x0_n8x4x0_i1_s1/Example.part0.exnode
current_run/l2x1x0_n2x1x0_i2_s1/Example.part0.exnode
current_run/l2x1x0_n4x2x0_i2_s1/Example.part0.exnode
current_run/l2x1x0_n8x4x0_i2_s1/Example.part0.exnode
current_run/l2x1x1_n2x1x1_i1_s0/Example.part0.exnode
current_run/l2x1x1_n4x2x2_i1_s0/Example.part0.exnode
current_run/l2x1x1_n8x4x4_i1_s0/Example.part0.exnode
current_run/l2x1x1_n2x1x1_i2_s0/Example.part0.exnode
current_run/l2x1x1_n4x2x2_i2_s0/Example.part0.exnode
current_run/l2x1x1_n8x4x4_i2_s0/Example.part0.exnode
current_run/l2x1x1_n2x1x1_i1_s1/Example.part0.exnode
current_run/l2x1x1_n4x2x2_i1_s1/Example.part0.exnode
current_run/l2x1x1_n8x4x4_i1_s1/Example.part0.exnode
current_run/l2x1x1_n2x1x1_i2_s1/Example.part0.exnode
current_run/l2x1x1_n4x2x2_i2_s1/Example.part0.exnode
current_run/l2x1x1_n8x4x4_i2_s1/Example.part0.exnode

| CHeart - Iron |₂ = 44.2627
| CHeart - Iron |₂ = 37.2770
| CHeart - Iron |₂ = 32.2165
| CHeart - Iron |₂ = 27.3358
| CHeart - Iron |₂ = 22.1869
| CHeart - Iron |₂ = 19.7449
| CHeart - Iron |₂ = 44.2627
| CHeart - Iron |₂ = 37.2770
| CHeart - Iron |₂ = 32.2165
| CHeart - Iron |₂ = 27.3358
| CHeart - Iron |₂ = 22.1869
| CHeart - Iron |₂ = 19.7449
| CHeart - Iron |₂ = 124.749
| CHeart - Iron |₂ = 128.672
| CHeart - Iron |₂ = 143.606
| CHeart - Iron |₂ = 94.2619
| CHeart - Iron |₂ = 98.7606
| CHeart - Iron |₂ = 118.047
| CHeart - Iron |₂ = 124.749
| CHeart - Iron |₂ = 128.672
| CHeart - Iron |₂ = 143.606
| CHeart - Iron |₂ = 94.2619
| CHeart - Iron |₂ = 98.7606
| CHeart - Iron |₂ = 118.047

Content of: example-0004/results/failed.tests

No failed tests.

Content of: example-0005/results/failed.tests

No failed tests.

Content of: example-0011/results/failed.tests

No failed tests.

Content of: example-0012/results/failed.tests

No failed tests.

Content of: example-0013/results/failed.tests

Content of: example-0201-u/results/failed.tests
No failed tests.

Content of: example-0302-u/results/failed.tests

Content of: example-0401/results/failed.tests
No failed tests.

Content of: example-0402/results/failed.tests
No failed tests.

2 INTRODUCTION

This document contains information about examples used for testing *OpenCMISS-iron*. Read: How-to¹ and [1].

2.1 Cogui files for cmgui-2.9

2.2 Variations to consider

- Geometry and topology
 - 1D, 2D, 3D
 - Length, width, height
 - Number of elements
 - Interpolation order
 - Generated or user meshes
 - quad/hex or tri/tet meshes
- Initial conditions
- Load cases
 - Dirichlet BC
 - Neumann BC
 - Volume force
 - Mix of previous items
- Sources, sinks
- Time dependence
 - Static
 - Quasi-static
 - Dynamic
- Material laws
 - Linear
 - Nonlinear (Mooney-Rivlin, Neo-Hookean, Ogden, etc.)
 - Active (Stress, strain)
- Material parameters, anisotropy
- Solver
 - Direct
 - Iterative
- Test cases
 - Numerical reference data
 - Analytical solution
- A mix of previous items

¹ <https://bitbucket.org/hessenthaler/opencmiss-howto>

2.3 Folder structure

TBD..

3 PROGRESS

People working on setting up tests in alphabetical order (surnames) with initials:

- CB : Christian Bleiler
- NE : Dr.-Ing. Nehzat Emamy
- AH : Andreas Hessenthaler
- TK : Thomas Klotz
- AK : Aaron Krämer
- BM : Benjamin Maier
- SM : Sergio Morales
- MM : Mylena Mordhorst
- HS : Harry Saini

3.1 Equations to test

Test single-physics problems before multi-physics problems!

- Diffusion equation (Laplace, Poisson, Generalized Laplace, ALE Diffusion, etc.)
- Linear elasticity equation (compressible and incompressible)
- Finite elasticity equation (compressible and incompressible Mooney-Rivlin, etc.)
- Navier-Stokes equation (ALE, Stokes, etc.)
- Monodomain equation
- CellML models
- Skeletal muscle models
- Fluid-structure interaction
- etc.

3.2 Setting up a new test

Use the following guideline to set up a new test:

1. Check if it is already there
2. Talk to other developers
3. Create a new subfolder examples/example-xxxx
4. Document the setup (computational domain, etc.) in examples/example-xxxx/doc/example.tex
5. Set up example with all parameters as command line arguments, see Section [2.2](#)

6. Set up reference results (CHeart, Abaqus, analytical solution, etc.)
7. Set up script to run all tests in your example directory
8. Set up script to perform comparison between iron results and reference results
9. Set up visualization scripts
10. Compile, run, test, visualize your example
11. Compile, run, test, visualize all examples

For each example, progress is documented in the respective section titles with the following **TAG**:

- **DOCUMENTED**: finish the documentation of the example (spatial domain, number of time steps, boundary conditions, etc.)
- **COMPILES**: example compiles (for default parameters)
- **RUNS**: example runs (for default parameters)
- **CONVERGES**: no convergence issues (for default parameters, results not plausible)
- **PLAUSIBLE**: results look sensible (for default parameters)
- **VALIDATED**: for all parameter sets it gives the correct results as compared to CHeart/Abaqus/analytical solution (includes visualization scripts, run scripts, comparison scripts, documentation!, ...)

Move all tags **CONVERGE**, **PLAUSIBLE** to **VALIDATED**.

Next steps include:

- Everybody runs everything!
- Meeting with Oliver
- Meeting with Auckland

3.3 Long-term goals

- Different testing targets
 - SMALL : small, fast tests
 - BIG : same as before; further, bigger and more complex geometries, convergence analysis
 - PARALLEL : same as before but in parallel
- Add more examples/those which were on the agenda but not started
- Jenkins continuous testing, integration and deployment
 - test SMALL/BIG/PARALLEL targets
 - integrate with GitHub (pull-requests triggers Jenkins, merge on success)

4 DIFFUSION EQUATION

4.1 Equation in general form

The governing equation is,

$$\partial_t u + \nabla \cdot [\sigma \nabla u] = f, \quad (1)$$

with conductivity tensor σ . The conductivity tensor is,

- defined in material coordinates (fibre direction),
- diagonal,
- defined per element.

4.2 Example-0001 [VALIDATED]

Example uses generated regular meshes and solves a static problem, i.e., applies the boundary conditions in one step.

4.2.1 Mathematical model - 2D

We solve the following scalar equation,

$$\nabla \cdot \nabla u = 0 \quad \Omega = [0, 2] \times [0, 1], \quad (2)$$

with boundary conditions

$$u = 0 \quad x = y = 0, \quad (3)$$

$$u = 1 \quad x = 2, y = 1. \quad (4)$$

No material parameters to specify.

4.2.2 Mathematical model - 3D

We solve the following scalar equation,

$$\nabla \cdot \nabla u = 0 \quad \Omega = [0, 2] \times [0, 1] \times [0, 1], \quad (5)$$

with boundary conditions

$$u = 0 \quad x = y = z = 0, \quad (6)$$

$$u = 1 \quad x = 2, y = z = 1. \quad (7)$$

No material parameters to specify.

4.2.3 Computational model

- Commandline arguments are:

float: length along x-direction

float: length along y-direction

float: length along z-direction (set to zero for 2D)

integer: number of elements in x-direction

integer: number of elements in y-direction

integer: number of elements in z-direction (set to zero for 2D)

integer: interpolation order (1: linear; 2: quadratic)

integer: solver type (0: direct; 1: iterative)

- Commandline arguments for tests are:

2.0 1.0 0.0 2 1 0 1 0

2.0 1.0 0.0 4 2 0 1 0

2.0 1.0 0.0 8 4 0 1 0

2.0 1.0 0.0 2 1 0 2 0

2.0 1.0 0.0 4 2 0 2 0

2.0 1.0 0.0 8 4 0 2 0

2.0 1.0 0.0 2 1 0 1 1

2.0 1.0 0.0 4 2 0 1 1

2.0 1.0 0.0 8 4 0 1 1
2.0 1.0 0.0 2 1 0 2 1
2.0 1.0 0.0 4 2 0 2 1
2.0 1.0 0.0 8 4 0 2 1
2.0 1.0 1.0 2 1 1 1 0
2.0 1.0 1.0 4 2 2 1 0
2.0 1.0 1.0 8 4 4 1 0
2.0 1.0 1.0 2 1 1 2 0
2.0 1.0 1.0 4 2 2 2 0
2.0 1.0 1.0 8 4 4 2 0
2.0 1.0 1.0 2 1 1 1 1
2.0 1.0 1.0 4 2 2 1 1
2.0 1.0 1.0 8 4 4 1 1
2.0 1.0 1.0 2 1 1 2 1
2.0 1.0 1.0 4 2 2 2 1
2.0 1.0 1.0 8 4 4 2 1

4.2.4 *Result summary*

We use CHeart rev. 6292 to produce numerical reference solutions.

Passed tests: 24 / 24

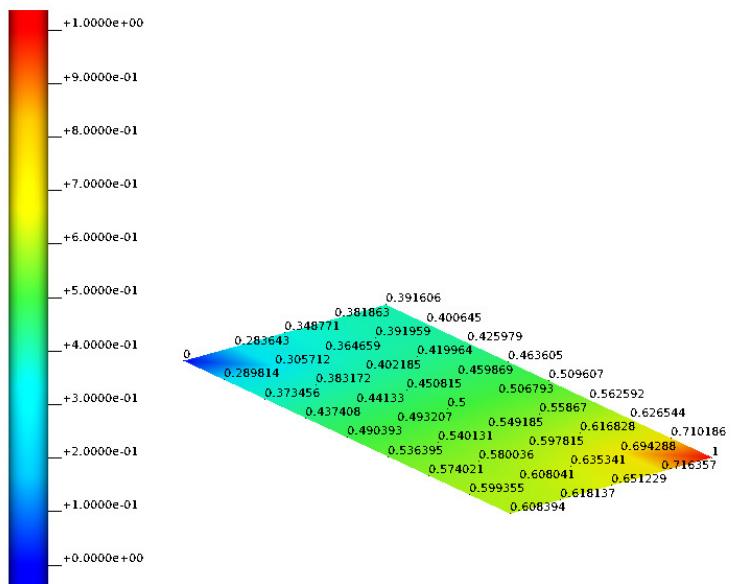


Figure 1: 2D results, iron reference w/ command line arguments [2.0 1.0 0.0 8 4 0 1 0].

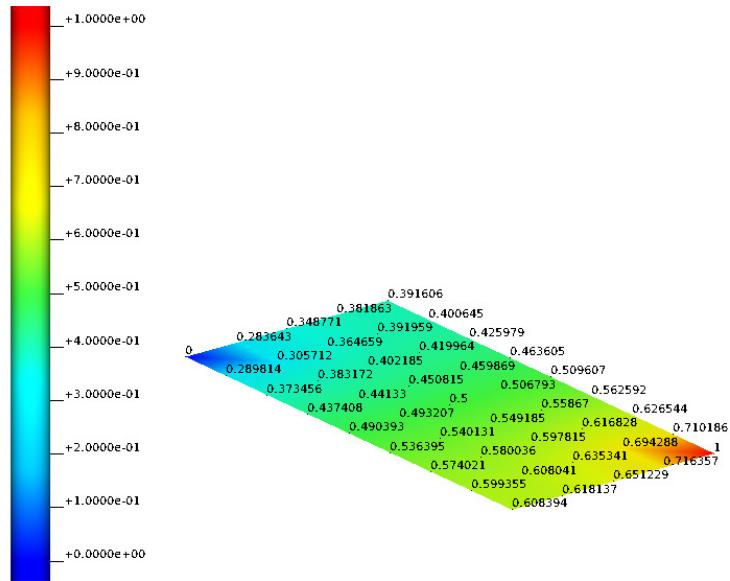


Figure 2: 2D results, current run w/ command line arguments [2.0 1.0 0.0 8 4 0 1 0].

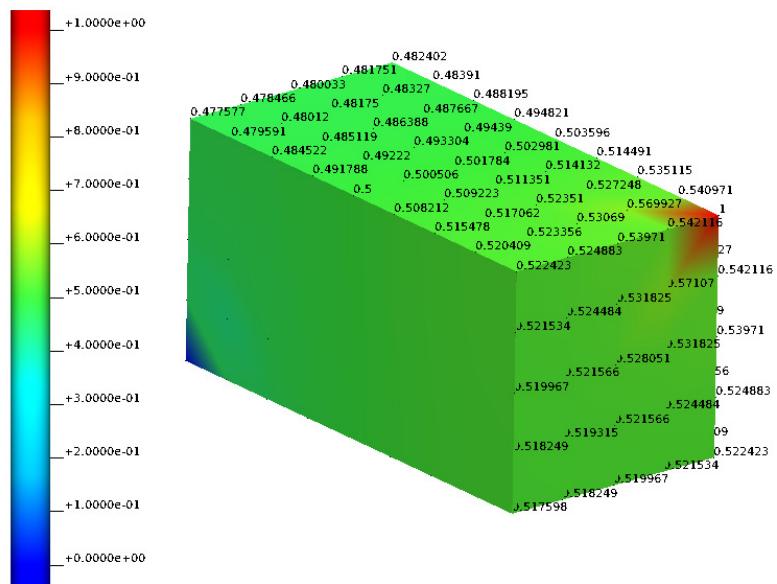


Figure 3: 3D results, iron reference w/ command line arguments [2.0 1.0 1.0 8 4 4 1 0].

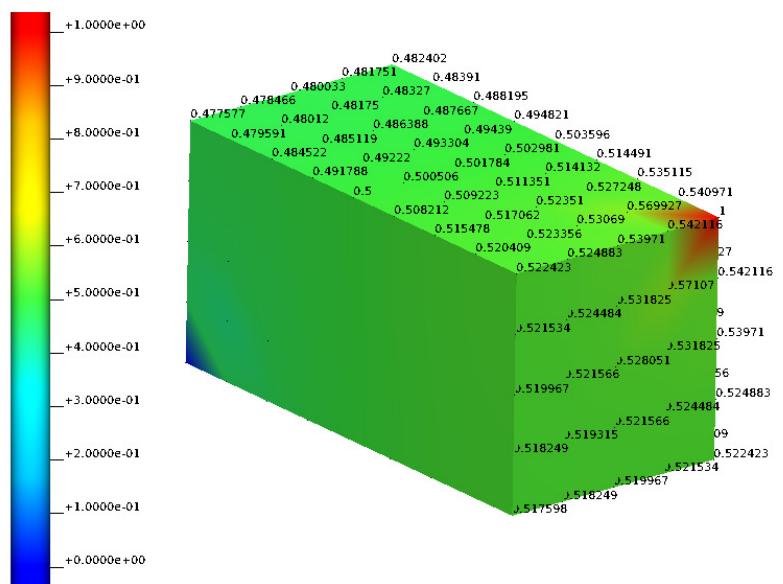


Figure 4: 3D results, current run w/ command line arguments [2.0 1.0 1.0 8 4 4 1 0].

4.3 Example-0001-u [PLAUSIBLE]

Example uses user-defined regular meshes in CHearm mesh format and solves a static problem, i.e., applies the boundary conditions in one step.

Issues: Interpolation type 8 (quadratic simplex) gives significantly different results compared to CHearm whereas all other simplex mesh results correspond rather well..

4.3.1 Mathematical model - 2D

We solve the following scalar equation,

$$\nabla \cdot \nabla u = 0 \quad \Omega = [0, 2] \times [0, 1], \quad (8)$$

with boundary conditions

$$u = 0 \quad x = y = 0, \quad (9)$$

$$u = 1 \quad x = 2, y = 1. \quad (10)$$

No material parameters to specify.

4.3.2 Mathematical model - 3D

We solve the following scalar equation,

$$\nabla \cdot \nabla u = 0 \quad \Omega = [0, 2] \times [0, 1] \times [0, 1], \quad (11)$$

with boundary conditions

$$u = 0 \quad x = y = z = 0, \quad (12)$$

$$u = 1 \quad x = 2, y = z = 1. \quad (13)$$

No material parameters to specify.

4.3.3 Computational model

- Commandline arguments are:

float: length along x-direction

float: length along y-direction

float: length along z-direction (set to zero for 2D)

integer: number of elements in x-direction

integer: number of elements in y-direction

integer: number of elements in z-direction (set to zero for 2D)

integer: interpolation order (1: linear; 2: quadratic)

integer: solver type (0: direct; 1: iterative)

- Commandline arguments for tests are:

2.0 1.0 0.0 2 1 0 1 0

2.0 1.0 0.0 4 2 0 1 0

2.0 1.0 0.0 8 4 0 1 0

2.0 1.0 0.0 2 1 0 2 0

```

2.0 1.0 0.0 4 2 0 2 0
2.0 1.0 0.0 8 4 0 2 0
2.0 1.0 0.0 8 4 0 7 0
2.0 1.0 0.0 8 4 0 8 0
2.0 1.0 0.0 2 1 0 1 1
2.0 1.0 0.0 4 2 0 1 1
2.0 1.0 0.0 8 4 0 1 1
2.0 1.0 0.0 2 1 0 2 1
2.0 1.0 0.0 4 2 0 2 1
2.0 1.0 0.0 8 4 0 2 1
2.0 1.0 0.0 8 4 0 7 1
2.0 1.0 0.0 8 4 0 8 1
2.0 1.0 1.0 2 1 1 1 0
2.0 1.0 1.0 4 2 2 1 0
2.0 1.0 1.0 8 4 4 1 0
2.0 1.0 1.0 2 1 1 2 0
2.0 1.0 1.0 4 2 2 2 0
2.0 1.0 1.0 8 4 4 2 0
2.0 1.0 1.0 8 4 4 7 0
2.0 1.0 1.0 8 4 4 8 0
2.0 1.0 1.0 2 1 1 1 1
2.0 1.0 1.0 4 2 2 1 1
2.0 1.0 1.0 8 4 4 1 1
2.0 1.0 1.0 2 1 1 2 1
2.0 1.0 1.0 4 2 2 2 1
2.0 1.0 1.0 8 4 4 2 1
2.0 1.0 1.0 8 4 4 7 1
2.0 1.0 1.0 8 4 4 8 1

```

- Note: Binary uses command line arguments to search for the relevant mesh files.

4.3.4 Result summary

We use CHeart rev. 6292 to produce numerical reference solutions.

Passed tests: 30 / 32

current_run/l2x1x0_n8x4x0_i8_s0/Example.part0.exnode	CHeart	- Iron	_2 = 0.05804
current_run/l2x1x0_n8x4x0_i8_s1/Example.part0.exnode	CHeart	- Iron	_2 = 0.05804

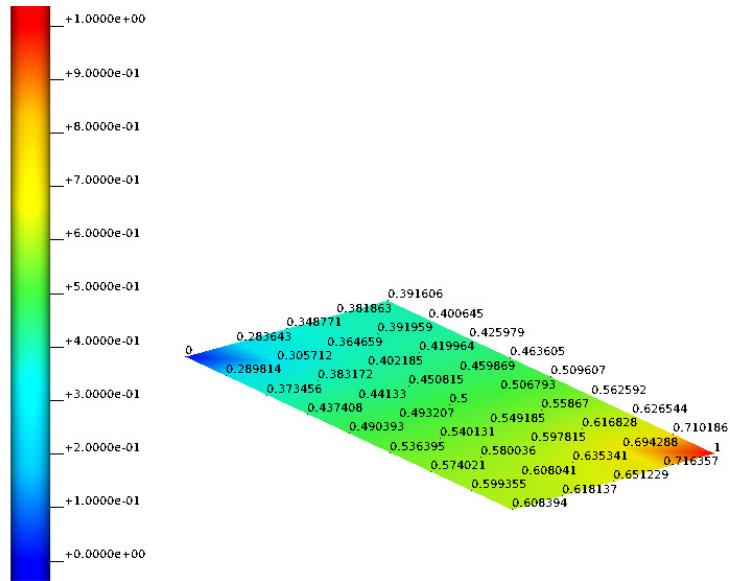


Figure 5: 2D results, iron reference w/ command line arguments [2.0 1.0 0.0 8 4 0 1 0].

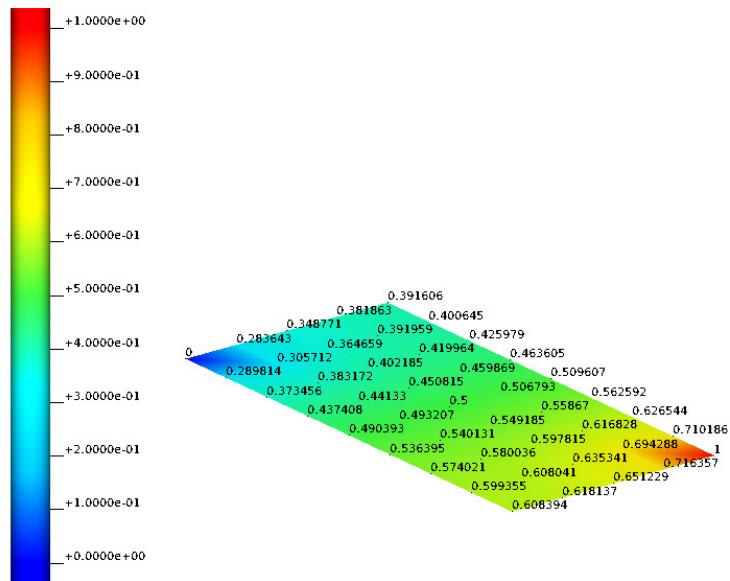


Figure 6: 2D results, current run w/ command line arguments [2.0 1.0 0.0 8 4 0 1 0].

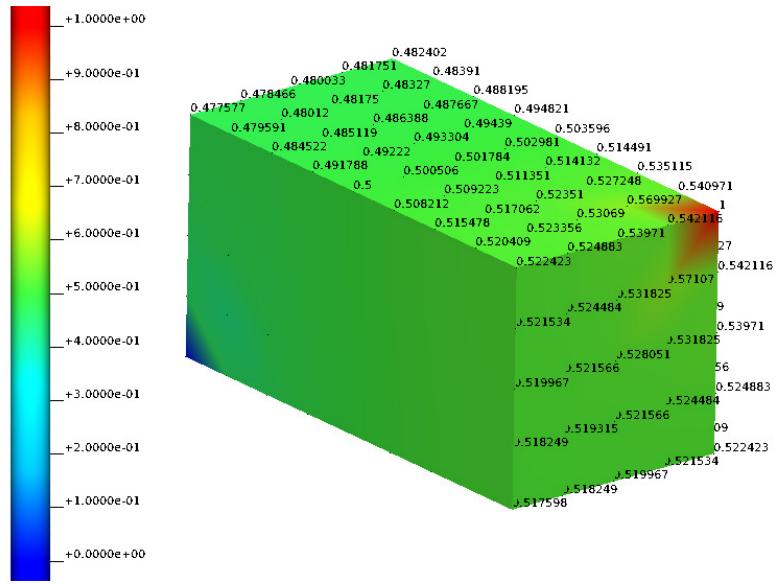


Figure 7: 3D results, iron reference w/ command line arguments [2.0 1.0 1.0 8 4 4 1 0].

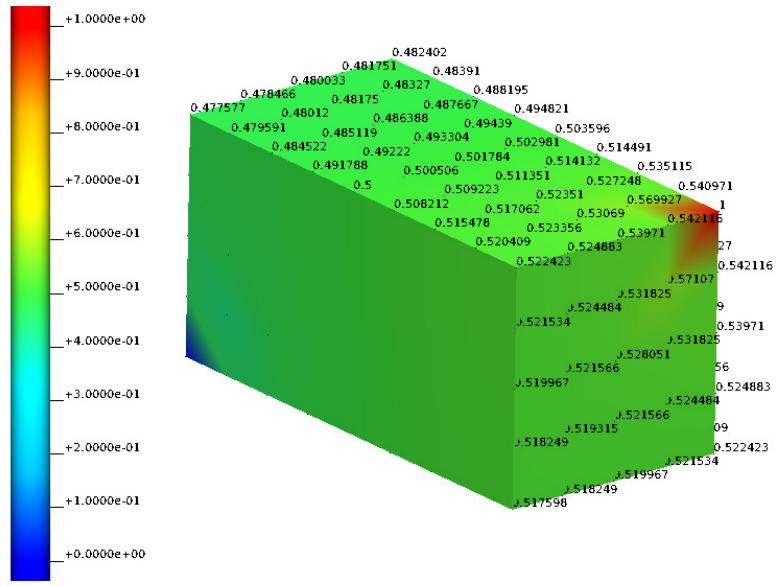


Figure 8: 3D results, current run w/ command line arguments [2.0 1.0 1.0 8 4 4 1 0].

4.4 Example-0002 [VALIDATED]

Example uses generated regular meshes and solves a static problem, i.e., applies the boundary conditions in one step.

4.4.1 Mathematical model - 2D

We solve the following scalar equation,

$$\nabla \cdot \nabla u = 0 \quad \Omega = [0, 2] \times [0, 1], \quad (14)$$

with boundary conditions

$$u = 15y \quad x = 0, \quad (15)$$

$$u = 25 - 18y \quad x = 2. \quad (16)$$

No material parameters to specify.

4.4.2 Mathematical model - 3D

We solve the following scalar equation,

$$\nabla \cdot \nabla u = 0 \quad \Omega = [0, 2] \times [0, 1] \times [0, 1], \quad (17)$$

with boundary conditions

$$u = 15y \quad x = 0, \quad (18)$$

$$u = 25 - 18y \quad x = 2. \quad (19)$$

No material parameters to specify.

4.4.3 Computational model

- Commandline arguments are:

float: length along x-direction

float: length along y-direction

float: length along z-direction (set to zero for 2D)

integer: number of elements in x-direction

integer: number of elements in y-direction

integer: number of elements in z-direction (set to zero for 2D)

integer: interpolation order (1: linear; 2: quadratic)

integer: solver type (0: direct; 1: iterative)

- Commandline arguments for tests are:

2.0 1.0 0.0 2 1 0 1 0

2.0 1.0 0.0 4 2 0 1 0

2.0 1.0 0.0 8 4 0 1 0

2.0 1.0 0.0 2 1 0 2 0

2.0 1.0 0.0 4 2 0 2 0

2.0 1.0 0.0 8 4 0 2 0

2.0 1.0 0.0 2 1 0 1 1

2.0 1.0 0.0 4 2 0 1 1

```

2.0 1.0 0.0 8 4 0 1 1
2.0 1.0 0.0 2 1 0 2 1
2.0 1.0 0.0 4 2 0 2 1
2.0 1.0 0.0 8 4 0 2 1
2.0 1.0 1.0 2 1 1 1 0
2.0 1.0 1.0 4 2 2 1 0
2.0 1.0 1.0 8 4 4 1 0
2.0 1.0 1.0 2 1 1 2 0
2.0 1.0 1.0 4 2 2 2 0
2.0 1.0 1.0 8 4 4 2 0
2.0 1.0 1.0 2 1 1 1 1
2.0 1.0 1.0 4 2 2 1 1
2.0 1.0 1.0 8 4 4 1 1
2.0 1.0 1.0 2 1 1 2 1
2.0 1.0 1.0 4 2 2 2 1
2.0 1.0 1.0 8 4 4 2 1

```

4.4.4 Result summary

We use CHeart rev. 6292 to produce numerical reference solutions.

Passed tests: 24 / 24

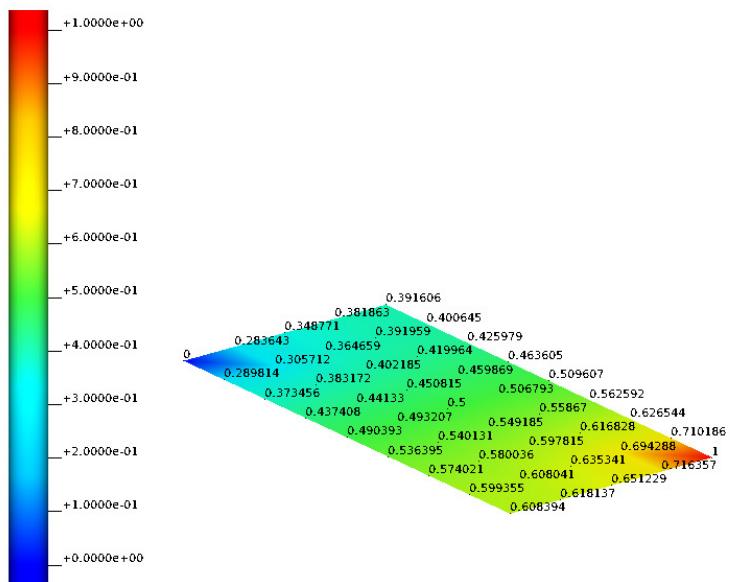


Figure 9: 2D results, iron reference w/ command line arguments [2.0 1.0 0.0 8 4 0 1 0].

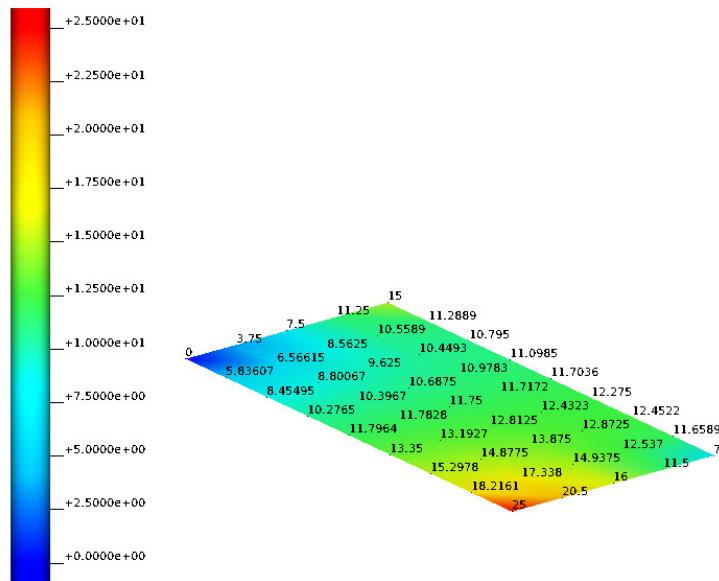


Figure 10: 2D results, current run w/ command line arguments [2.0 1.0 0.0 8 4 0 1 0].

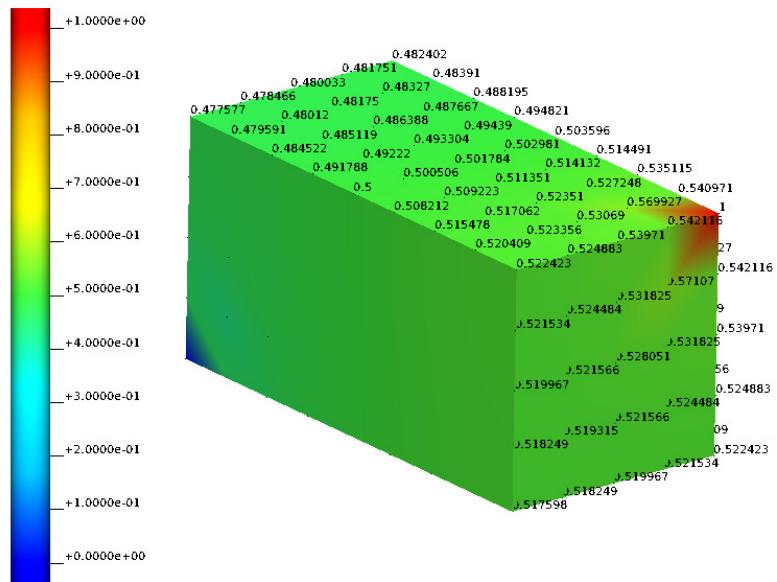


Figure 11: 3D results, iron reference w/ command line arguments [2.0 1.0 1.0 8 4 4 1 0].

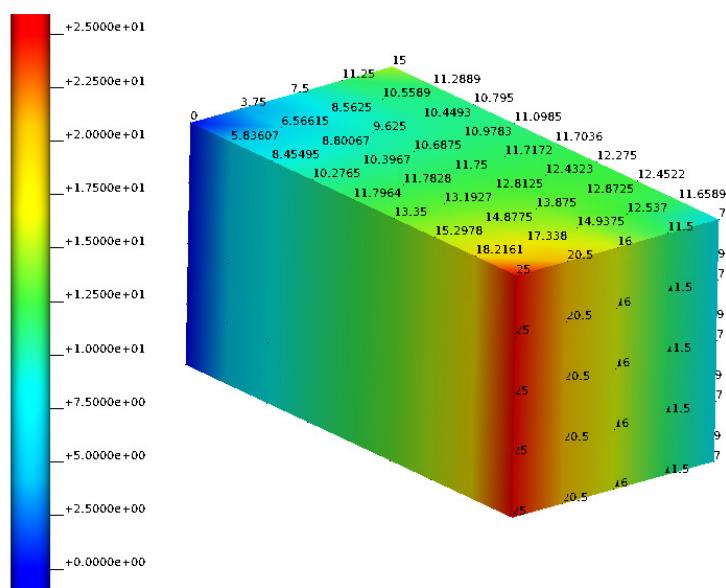


Figure 12: 3D results, current run w/ command line arguments [2.0 1.0 1.0 8 4 4 1 0].

4.5 Example-0003 [COMPILES]

Example uses generated regular meshes and solves a static problem, i.e., applies the boundary conditions in one step.

Issues: Not clear how to prescribe Neumann BC. Results seem weird. Reference results are set up.

4.5.1 Mathematical model - 2D

We solve the following scalar equation,

$$\nabla \cdot \nabla u = 0 \quad \Omega = [0, 2] \times [0, 1], \quad (20)$$

with boundary conditions

$$u = 15y \quad x = 0, \quad (21)$$

$$\partial_n u = 25 - 18y \quad x = 2. \quad (22)$$

No material parameters to specify.

4.5.2 Mathematical model - 3D

We solve the following scalar equation,

$$\nabla \cdot \nabla u = 0 \quad \Omega = [0, 2] \times [0, 1] \times [0, 1], \quad (23)$$

with boundary conditions

$$u = 15y \quad x = 0, \quad (24)$$

$$\partial_n u = 25 - 18y \quad x = 2. \quad (25)$$

No material parameters to specify.

4.5.3 Computational model

- Commandline arguments are:

float: length along x-direction

float: length along y-direction

float: length along z-direction (set to zero for 2D)

integer: number of elements in x-direction

integer: number of elements in y-direction

integer: number of elements in z-direction (set to zero for 2D)

integer: interpolation order (1: linear; 2: quadratic)

integer: solver type (0: direct; 1: iterative)

- Commandline arguments for tests are:

2.0 1.0 0.0 2 1 0 1 0

2.0 1.0 0.0 4 2 0 1 0

2.0 1.0 0.0 8 4 0 1 0

2.0 1.0 0.0 2 1 0 2 0

2.0 1.0 0.0 4 2 0 2 0

```

2.0 1.0 0.0 8 4 0 2 0
2.0 1.0 0.0 2 1 0 1 1
2.0 1.0 0.0 4 2 0 1 1
2.0 1.0 0.0 8 4 0 1 1
2.0 1.0 0.0 2 1 0 2 1
2.0 1.0 0.0 4 2 0 2 1
2.0 1.0 0.0 8 4 0 2 1
2.0 1.0 1.0 2 1 1 1 0
2.0 1.0 1.0 4 2 2 1 0
2.0 1.0 1.0 8 4 4 1 0
2.0 1.0 1.0 2 1 1 2 0
2.0 1.0 1.0 4 2 2 2 0
2.0 1.0 1.0 8 4 4 2 0
2.0 1.0 1.0 2 1 1 1 1
2.0 1.0 1.0 4 2 2 1 1
2.0 1.0 1.0 8 4 4 1 1
2.0 1.0 1.0 2 1 1 2 1
2.0 1.0 1.0 4 2 2 2 1
2.0 1.0 1.0 8 4 4 2 1

```

4.5.4 Result summary

We use CHeart rev. 6292 to produce numerical reference solutions.

Passed tests: 0 / 24

Failed tests:

```

current_run/l2x1x0_n2x1x0_i1_s0/Example.part0.exnode
current_run/l2x1x0_n4x2x0_i1_s0/Example.part0.exnode
current_run/l2x1x0_n8x4x0_i1_s0/Example.part0.exnode
current_run/l2x1x0_n2x1x0_i2_s0/Example.part0.exnode
current_run/l2x1x0_n4x2x0_i2_s0/Example.part0.exnode
current_run/l2x1x0_n8x4x0_i2_s0/Example.part0.exnode
current_run/l2x1x0_n2x1x0_i1_s1/Example.part0.exnode
current_run/l2x1x0_n4x2x0_i1_s1/Example.part0.exnode
current_run/l2x1x0_n8x4x0_i1_s1/Example.part0.exnode
current_run/l2x1x0_n2x1x0_i2_s1/Example.part0.exnode
current_run/l2x1x0_n4x2x0_i2_s1/Example.part0.exnode
current_run/l2x1x0_n8x4x0_i2_s1/Example.part0.exnode
current_run/l2x1x0_n2x1x0_i1_s0/Example.part0.exnode
current_run/l2x1x1_n2x1x1_i1_s0/Example.part0.exnode
current_run/l2x1x1_n4x2x2_i1_s0/Example.part0.exnode
current_run/l2x1x1_n8x4x4_i1_s0/Example.part0.exnode
current_run/l2x1x1_n2x1x1_i2_s0/Example.part0.exnode
current_run/l2x1x1_n4x2x2_i2_s0/Example.part0.exnode
current_run/l2x1x1_n8x4x4_i2_s0/Example.part0.exnode
current_run/l2x1x1_n2x1x1_i1_s1/Example.part0.exnode
current_run/l2x1x1_n4x2x2_i1_s1/Example.part0.exnode
current_run/l2x1x1_n8x4x4_i1_s1/Example.part0.exnode
current_run/l2x1x1_n2x1x1_i2_s1/Example.part0.exnode

```

CHeart	- Iron	_2 = 44.2627
CHeart	- Iron	_2 = 37.2770
CHeart	- Iron	_2 = 32.2165
CHeart	- Iron	_2 = 27.3358
CHeart	- Iron	_2 = 22.1869
CHeart	- Iron	_2 = 19.7449
CHeart	- Iron	_2 = 44.2627
CHeart	- Iron	_2 = 37.2770
CHeart	- Iron	_2 = 32.2165
CHeart	- Iron	_2 = 27.3358
CHeart	- Iron	_2 = 22.1869
CHeart	- Iron	_2 = 19.7449
CHeart	- Iron	_2 = 124.749
CHeart	- Iron	_2 = 128.672
CHeart	- Iron	_2 = 143.606
CHeart	- Iron	_2 = 94.2619
CHeart	- Iron	_2 = 98.7606
CHeart	- Iron	_2 = 118.047
CHeart	- Iron	_2 = 124.749
CHeart	- Iron	_2 = 128.672
CHeart	- Iron	_2 = 143.606
CHeart	- Iron	_2 = 94.2619

```
current_run/l2x1x1_n4x2x2_i2_s1/Example.part0.exnode  
current_run/l2x1x1_n8x4x4_i2_s1/Example.part0.exnode
```

| CHeart - Iron |₂ = 98.7606
| CHeart - Iron |₂ = 118.047

Figure 13: 2D results, iron reference w/ command line arguments [2.0 1.0 0.0 8 4 0 1 0].

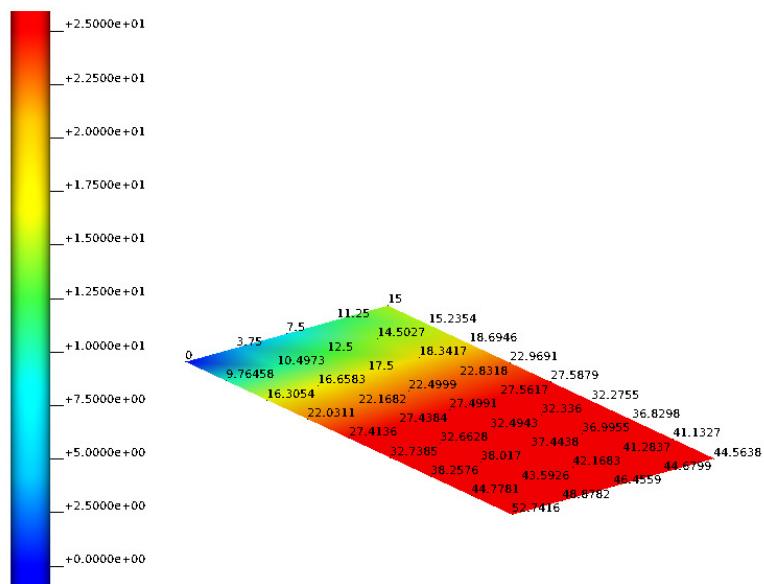


Figure 14: 2D results, current run w/ command line arguments [2.0 1.0 0.0 8 4 0 1 0].

Figure 15: 3D results, iron reference w/ command line arguments [2.0 1.0 1.0 8 4 4 1 0].

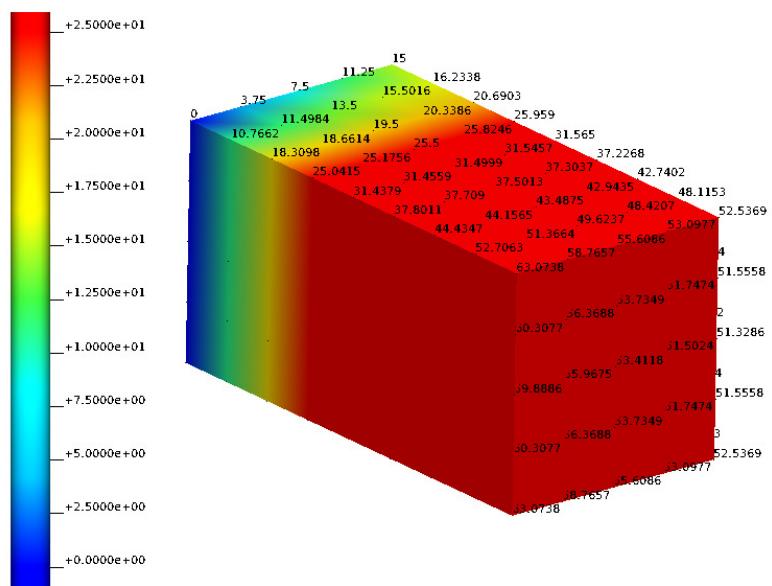


Figure 16: 3D results, current run w/ command line arguments [2.0 1.0 1.0 8 4 4 1 0].

4.6 Example-0004 [VALIDATED]

Example uses generated regular meshes and solves a static problem, i.e., applies the boundary conditions in one step.

4.6.1 Mathematical model - 2D

We solve the following scalar equation,

$$\nabla \cdot \nabla u = 0 \quad \Omega = [0, 2] \times [0, 1], \quad (26)$$

with boundary conditions

$$u = 2.0e^x \cdot \cos(y) \quad \text{on } \partial\Omega. \quad (27)$$

No material parameters to specify.

4.6.2 Computational model

- Commandline arguments are:

integer: number of elements in x-direction
 integer: number of elements in y-direction
 integer: number of elements in z-direction (set to zero for 2D)
 integer: interpolation order (1: linear; 2: quadratic)
 integer: solver type (0: direct; 1: iterative)

- Commandline arguments for tests are:

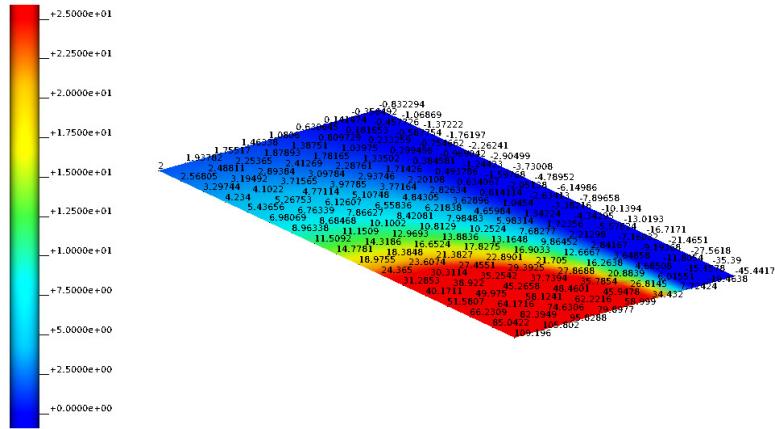
```
4 2 0 1 0
8 4 0 1 0
2 1 0 2 0
4 2 0 2 0
8 4 0 2 0
4 2 0 1 1
8 4 0 1 1
2 1 0 2 1
4 2 0 2 1
8 4 0 2 1
100 50 0 1 0 (not tested yet..)
100 50 0 2 0 (not tested yet..)
100 50 0 1 1 (not tested yet..)
100 50 0 2 1 (not tested yet..)
```

4.6.3 Result summary

We use CHeart rev. 6292 to produce numerical reference solutions.

Passed tests: 10 / 10

No failed tests.



4.7 Example-0005 [VALIDATED]

Example uses two user-defined (2d and 3d) unregular meshes and solves a patch test in form of a static problem, i.e., applies the boundary conditions in one step. Here, a Laplace problem with two Dirichlet boundary conditions is solved. The analytical solution for this setting is known and results in a linear distribution of the scalar Laplace parameter u . The numerical solution has to recover this the linear distribution in order to pass the Patch test. 2d and 3d meshes are according to MacNeil and Harder (1985).

4.7.1 Mathematical model - 2D

We solve the following scalar equation,

$$\nabla \cdot \nabla u = 0 \quad \Omega = [0, 0.24] \times [0, 0.12], \quad (28)$$

with boundary conditions

$$u = 0 \quad x = 0, \quad (29)$$

$$u = 1 \quad x = 0.24. \quad (30)$$

No material parameters to specify.

4.7.2 Mathematical model - 3D

We solve the following scalar equation,

$$\nabla \cdot \nabla u = 0 \quad \Omega = [0, 1] \times [0, 1] \times [0, 1], \quad (31)$$

with boundary conditions

$$u = 0 \quad x = 0, \quad (32)$$

$$u = 1 \quad x = 1. \quad (33)$$

No material parameters to specify.

4.7.3 Computational model

- Commandline arguments are:

integer: dimension (2: 2d; 3: 3d)

integer: interpolation order (1: linear; 2: quadratic)

integer: solver type (0: direct; 1: iterative)

- Commandline arguments for tests are:

2 1 0

2 2 0

2 1 1

2 2 1

3 1 0

3 2 0

3 1 1

3 2 1

4.7.4 Result summary

Since the analytical result is known and the numerical results have to recover the linear distribution of u , the comparisons are done with the analytical solution.

Passed tests: 8 / 8

No failed tests.

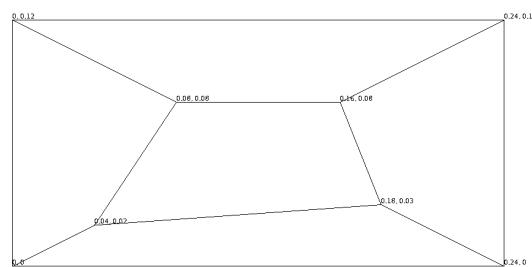


Figure 19: 2D geometry and mesh.

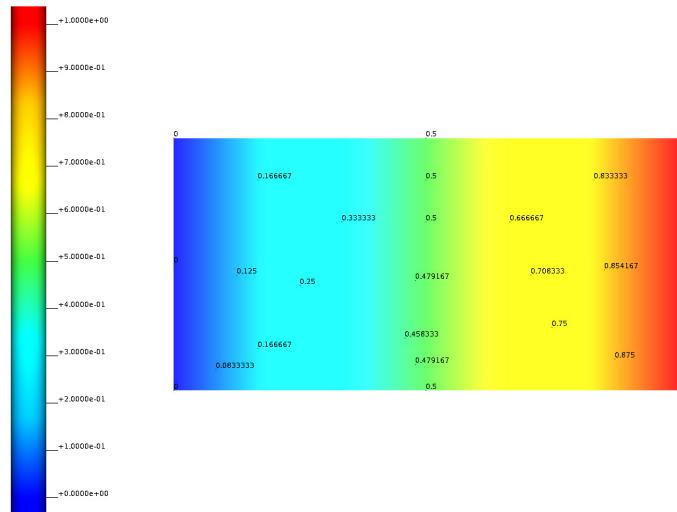


Figure 20: 2D results, iron reference w/ command line arguments [2 2 0].

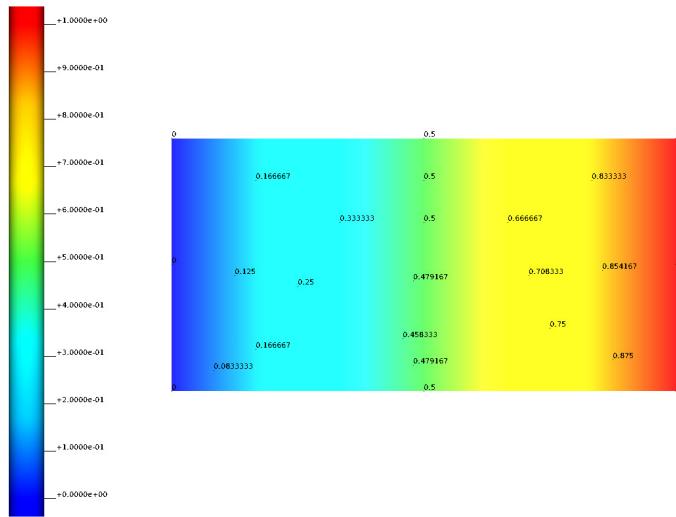


Figure 21: 2D results, current run w/ command line arguments [2 2 0].

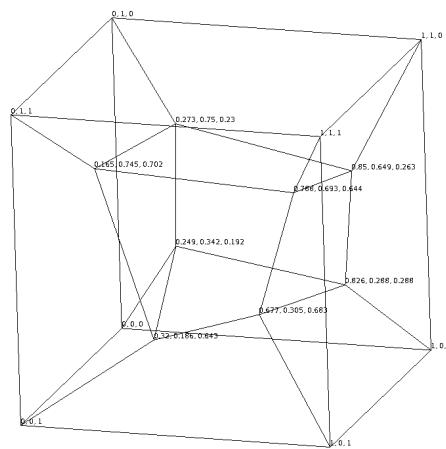


Figure 22: 3D geometry (unit cube) and mesh.

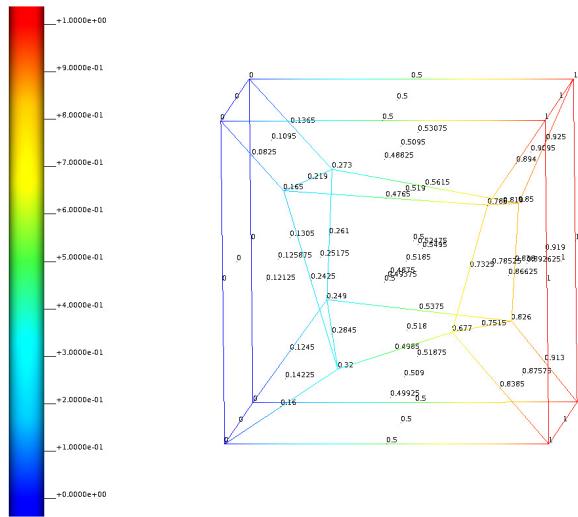


Figure 23: 3D results, iron reference w/ command line arguments [3 2 0].

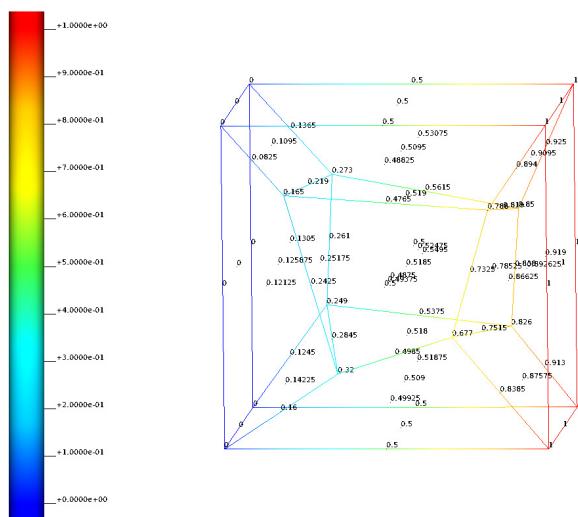


Figure 24: 3D results, current run w/ command line arguments [3 2 0].

4.8 Example-0011 [VALIDATED]

Example uses generated regular meshes and solves a static problem, i.e., applies the boundary conditions in one step.

4.8.1 Mathematical model - 2D

We solve the following scalar equation,

$$\nabla \cdot [\sigma \nabla u] = 0 \quad \Omega = [0, 2] \times [0, 1], \quad (34)$$

with boundary conditions

$$u = 0 \quad x = y = 0, \quad (35)$$

$$u = 1 \quad x = 2, y = 1. \quad (36)$$

The conductivity tensor is defined as,

$$\sigma(x, t) = \sigma = I. \quad (37)$$

4.8.2 Mathematical model - 3D

We solve the following scalar equation,

$$\nabla \cdot [\sigma \nabla u] = 0 \quad \Omega = [0, 2] \times [0, 1] \times [0, 1], \quad (38)$$

with boundary conditions

$$u = 0 \quad x = y = z = 0, \quad (39)$$

$$u = 1 \quad x = 2, y = z = 1. \quad (40)$$

The conductivity tensor is defined as,

$$\sigma(x, t) = \sigma = I. \quad (41)$$

4.8.3 Computational model

- Commandline arguments are:

float: length along x-direction

float: length along y-direction

float: length along z-direction (set to zero for 2D)

integer: number of elements in x-direction

integer: number of elements in y-direction

integer: number of elements in z-direction (set to zero for 2D)

integer: interpolation order (1: linear; 2: quadratic)

integer: solver type (0: direct; 1: iterative)

float: σ_{11}

float: σ_{22}

float: σ_{33} (ignored for 2D)

- Commandline arguments for tests are:

```

2.0 1.0 0.0 2 1 0 1 0 1 1
2.0 1.0 0.0 4 2 0 1 0 1 1
2.0 1.0 0.0 8 4 0 1 0 1 1
2.0 1.0 0.0 2 1 0 2 0 1 1
2.0 1.0 0.0 4 2 0 2 0 1 1
2.0 1.0 0.0 8 4 0 2 0 1 1
2.0 1.0 0.0 2 1 0 1 1 1 1
2.0 1.0 0.0 4 2 0 1 1 1 1
2.0 1.0 0.0 8 4 0 1 1 1 1
2.0 1.0 0.0 2 1 0 2 1 1 1
2.0 1.0 0.0 4 2 0 2 1 1 1
2.0 1.0 0.0 8 4 0 2 1 1 1
2.0 1.0 1.0 2 1 1 1 0 1 1 1
2.0 1.0 1.0 4 2 2 1 0 1 1 1
2.0 1.0 1.0 8 4 4 1 0 1 1 1
2.0 1.0 1.0 2 1 1 2 0 1 1 1
2.0 1.0 1.0 4 2 2 2 0 1 1 1
2.0 1.0 1.0 8 4 4 2 0 1 1 1
2.0 1.0 1.0 2 1 1 1 1 1 1 1
2.0 1.0 1.0 4 2 2 1 1 1 1 1
2.0 1.0 1.0 8 4 4 1 1 1 1 1
2.0 1.0 1.0 2 1 1 2 1 1 1 1
2.0 1.0 1.0 4 2 2 2 1 1 1 1
2.0 1.0 1.0 8 4 4 2 1 1 1 1

```

4.8.4 *Result summary*

We use CHeart rev. 6292 to produce numerical reference solutions.

Passed tests: 24 / 24

No failed tests.

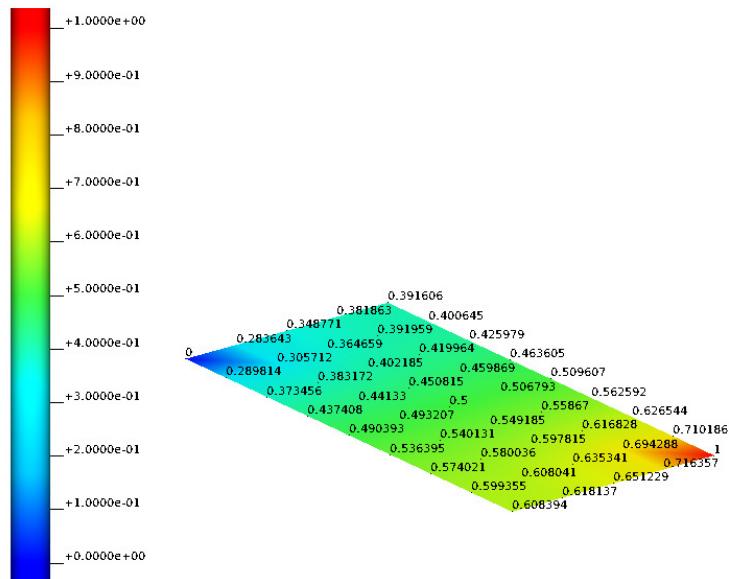


Figure 25: 2D results, iron reference w/ command line arguments [2.0 1.0 0.0 8 4 0 1 0 1 1].

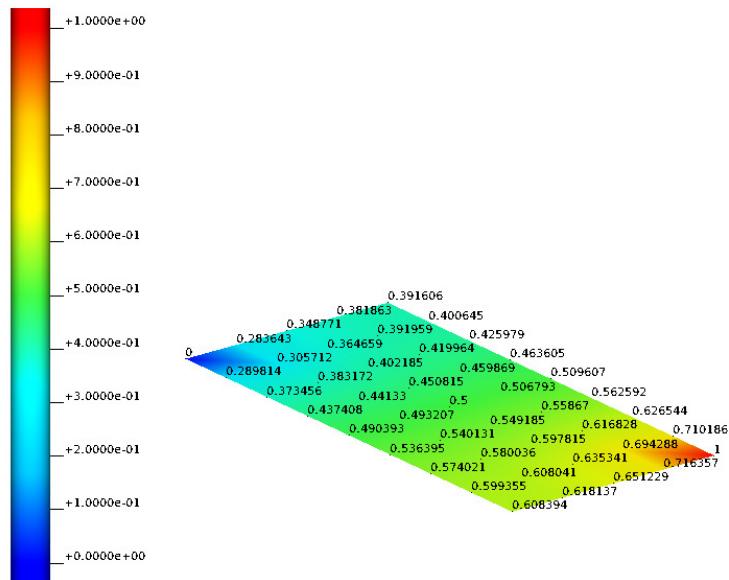


Figure 26: 2D results, current run w/ command line arguments [2.0 1.0 0.0 8 4 0 1 0 1 1].

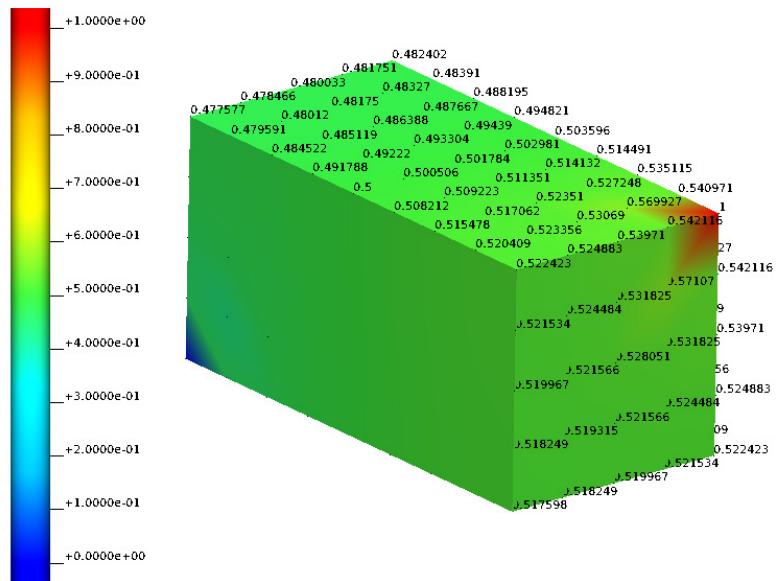


Figure 27: 3D results, iron reference w/ command line arguments [2.0 1.0 1.0 8 4 4 1 0 1 1].

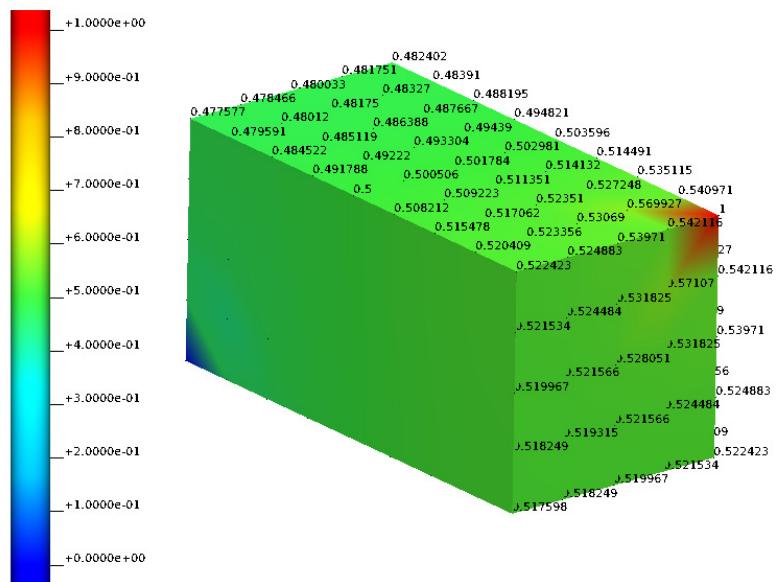


Figure 28: 3D results, current run w/ command line arguments [2.0 1.0 1.0 8 4 4 1 0 1 1].

4.9 Example-0012 [VALIDATED]

Example uses generated regular meshes and solves a static problem, i.e., applies the boundary conditions in one step.

4.9.1 Mathematical model - 2D

We solve the following scalar equation,

$$\nabla \cdot [\sigma \nabla u] = 0 \quad \Omega = [0, 2] \times [0, 1], \quad (42)$$

with boundary conditions

$$u = 0 \quad x = y = 0, \quad (43)$$

$$u = 1 \quad x = 2, y = 1. \quad (44)$$

The conductivity tensor is defined as,

$$\sigma(x, t) = \sigma = \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}. \quad (45)$$

4.9.2 Mathematical model - 3D

We solve the following scalar equation,

$$\nabla \cdot [\sigma \nabla u] = 0 \quad \Omega = [0, 2] \times [0, 1] \times [0, 1], \quad (46)$$

with boundary conditions

$$u = 0 \quad x = y = z = 0, \quad (47)$$

$$u = 1 \quad x = 2, y = z = 1. \quad (48)$$

The conductivity tensor is defined as,

$$\sigma(x, t) = \sigma = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 7 \end{bmatrix}. \quad (49)$$

4.9.3 Computational model

- Commandline arguments are:

float: length along x-direction

float: length along y-direction

float: length along z-direction (set to zero for 2D)

integer: number of elements in x-direction

integer: number of elements in y-direction

integer: number of elements in z-direction (set to zero for 2D)

integer: interpolation order (1: linear; 2: quadratic)

integer: solver type (0: direct; 1: iterative)

float: σ_{11}

float: σ_{22}

float: σ_{33} (ignored for 2D)

float: angle 1

float: angle 2

float: angle 3

- Commandline arguments for tests are:

```

2.0 1.0 0.0 2 1 0 1 0 2 3 0 0 0 0
2.0 1.0 0.0 4 2 0 1 0 2 3 0 0 0 0
2.0 1.0 0.0 8 4 0 1 0 2 3 0 0 0 0
2.0 1.0 0.0 2 1 0 2 0 2 3 0 0 0 0
2.0 1.0 0.0 4 2 0 2 0 2 3 0 0 0 0
2.0 1.0 0.0 8 4 0 2 0 2 3 0 0 0 0
2.0 1.0 0.0 2 1 0 1 1 2 3 0 0 0 0
2.0 1.0 0.0 4 2 0 1 1 2 3 0 0 0 0
2.0 1.0 0.0 8 4 0 1 1 2 3 0 0 0 0
2.0 1.0 0.0 2 1 0 2 1 2 3 0 0 0 0
2.0 1.0 0.0 4 2 0 2 1 2 3 0 0 0 0
2.0 1.0 0.0 8 4 0 2 1 2 3 0 0 0 0
2.0 1.0 1.0 2 1 1 1 0 2 3 7 0 0 0
2.0 1.0 1.0 4 2 2 1 0 2 3 7 0 0 0
2.0 1.0 1.0 8 4 4 1 0 2 3 7 0 0 0
2.0 1.0 1.0 2 1 1 2 0 2 3 7 0 0 0
2.0 1.0 1.0 4 2 2 2 0 2 3 7 0 0 0
2.0 1.0 1.0 8 4 4 2 0 2 3 7 0 0 0
2.0 1.0 1.0 2 1 1 1 1 2 3 7 0 0 0
2.0 1.0 1.0 4 2 2 1 1 2 3 7 0 0 0
2.0 1.0 1.0 8 4 4 1 1 2 3 7 0 0 0
2.0 1.0 1.0 2 1 1 2 1 2 3 7 0 0 0
2.0 1.0 1.0 4 2 2 2 1 2 3 7 0 0 0
2.0 1.0 1.0 8 4 4 2 1 2 3 7 0 0 0

```

4.9.4 *Result summary*

We use CHeart rev. 6292 to produce numerical reference solutions.

Passed tests: 24 / 24

No failed tests.

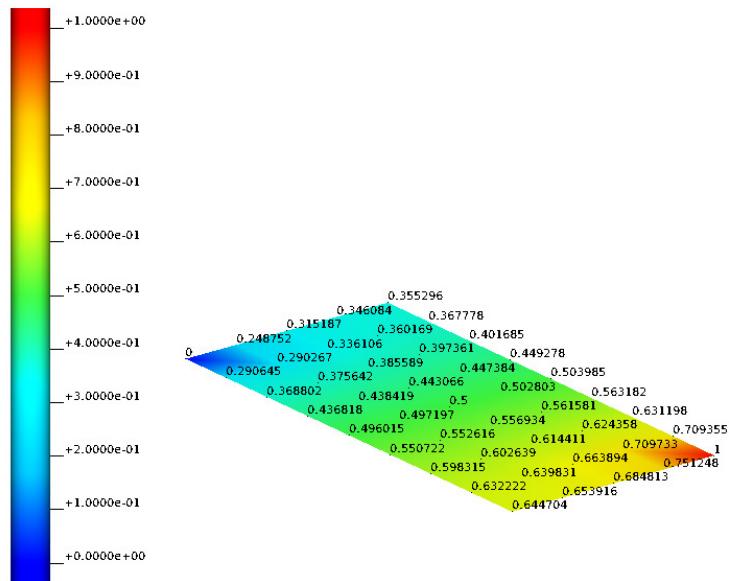


Figure 29: 2D results, iron reference w/ command line arguments [2.0 1.0 0.0 8 4 0 1 0 2 3 0 0 0 0].

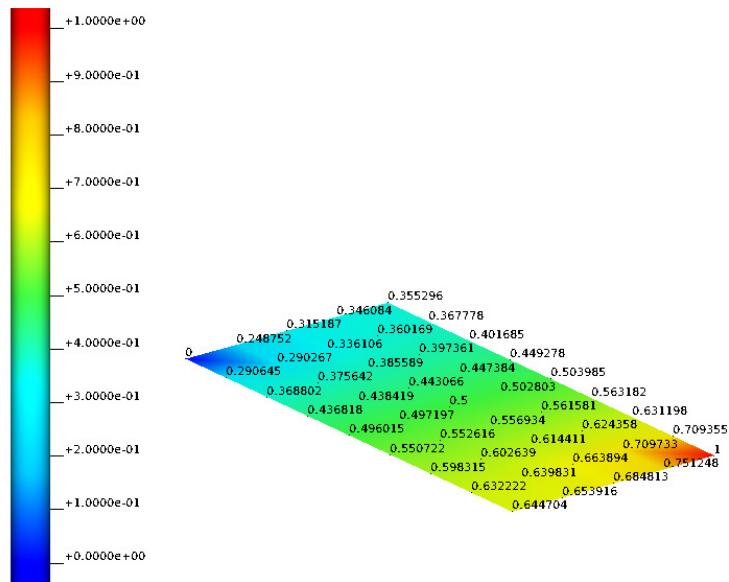


Figure 30: 2D results, current run w/ command line arguments [2.0 1.0 0.0 8 4 0 1 0 2 3 0 0 0 0].

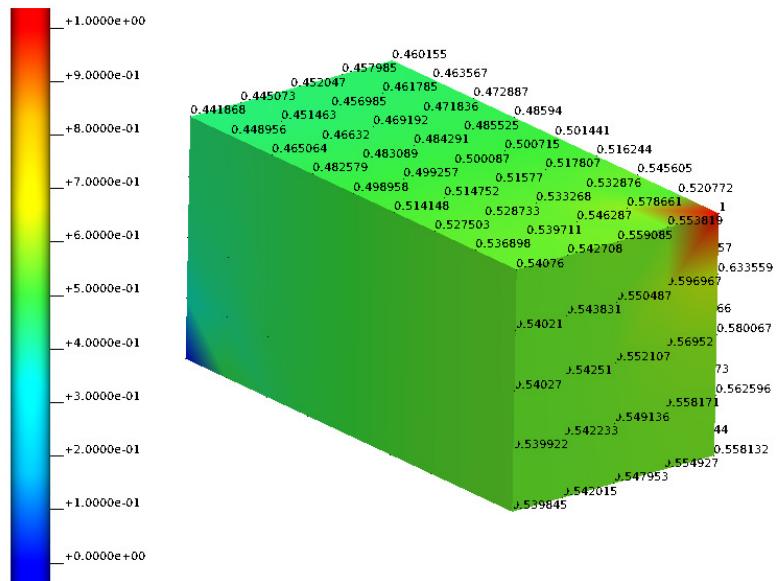


Figure 31: 3D results, iron reference w/ command line arguments [2.0 1.0 1.0 8 4 4 1 0 2 3 7 0 0 0].

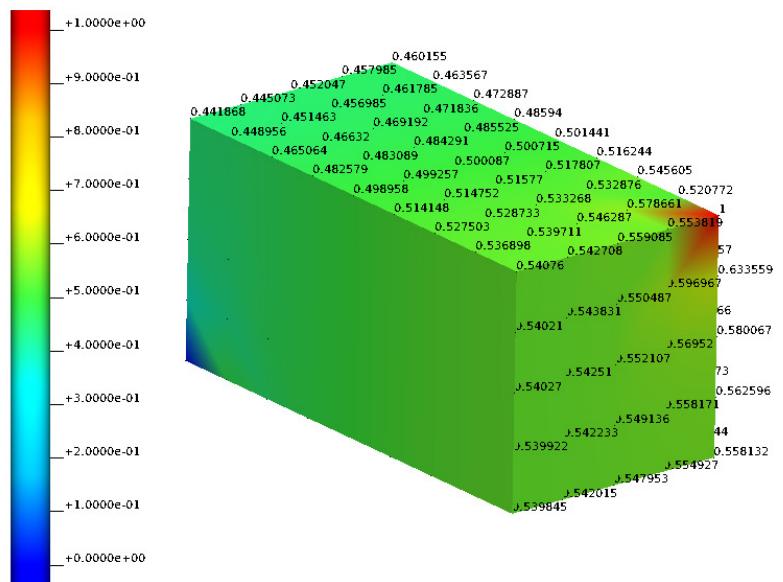


Figure 32: 3D results, current run w/ command line arguments [2.0 1.0 1.0 8 4 4 1 0 2 3 7 0 0 0].

4.10 Example-0013 [VALIDATED]

Example uses generated regular meshes and solves a static problem, i.e., applies the boundary conditions in one step.

4.10.1 Mathematical model - 2D

We solve the following scalar equation,

$$\nabla \cdot [\sigma \nabla u] = 0 \quad \Omega = [0, 2] \times [0, 1], \quad (50)$$

with boundary conditions

$$u = 0 \quad x = y = 0, \quad (51)$$

$$u = 1 \quad x = 2, y = 1. \quad (52)$$

The conductivity tensor is defined as,

$$\sigma(x, t) = \sigma = \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}. \quad (53)$$

Rotation of fibres by 30 degrees (first angle).

4.10.2 Mathematical model - 3D

We solve the following scalar equation,

$$\nabla \cdot [\sigma \nabla u] = 0 \quad \Omega = [0, 2] \times [0, 1] \times [0, 1], \quad (54)$$

with boundary conditions

$$u = 0 \quad x = y = z = 0, \quad (55)$$

$$u = 1 \quad x = 2, y = z = 1. \quad (56)$$

The conductivity tensor is defined as,

$$\sigma(x, t) = \sigma = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 7 \end{bmatrix}. \quad (57)$$

Rotation of fibres by (30, 40, 10) degrees.

4.10.3 Computational model

- Commandline arguments are:

float: length along x-direction

float: length along y-direction

float: length along z-direction (set to zero for 2D)

integer: number of elements in x-direction

integer: number of elements in y-direction

integer: number of elements in z-direction (set to zero for 2D)

integer: interpolation order (1: linear; 2: quadratic)

integer: solver type (0: direct; 1: iterative)

float: σ_{11}

```

float:  $\sigma_{22}$ 
float:  $\sigma_{33}$  (ignored for 2D)
float: angle 1
float: angle 2
float: angle 3

```

- Commandline arguments for tests are:

```

2.0 1.0 0.0 2 1 0 1 0 2 3 0 0.523598775598299 0 0
2.0 1.0 0.0 4 2 0 1 0 2 3 0 0.523598775598299 0 0
2.0 1.0 0.0 8 4 0 1 0 2 3 0 0.523598775598299 0 0
2.0 1.0 0.0 2 1 0 2 0 2 3 0 0.523598775598299 0 0
2.0 1.0 0.0 4 2 0 2 0 2 3 0 0.523598775598299 0 0
2.0 1.0 0.0 8 4 0 2 0 2 3 0 0.523598775598299 0 0
2.0 1.0 0.0 2 1 0 1 1 2 3 0 0.523598775598299 0 0
2.0 1.0 0.0 4 2 0 1 1 2 3 0 0.523598775598299 0 0
2.0 1.0 0.0 8 4 0 1 1 2 3 0 0.523598775598299 0 0
2.0 1.0 0.0 2 1 0 2 1 2 3 0 0.523598775598299 0 0
2.0 1.0 0.0 4 2 0 2 1 2 3 0 0.523598775598299 0 0
2.0 1.0 0.0 8 4 0 2 1 2 3 0 0.523598775598299 0 0
2.0 1.0 1.0 2 1 1 1 0 2 3 7 0.523598775598299 0.698131700797732
0.174532925199433
2.0 1.0 1.0 4 2 2 1 0 2 3 7 0.523598775598299 0.698131700797732
0.174532925199433
2.0 1.0 1.0 8 4 4 1 0 2 3 7 0.523598775598299 0.698131700797732
0.174532925199433
2.0 1.0 1.0 2 1 1 2 0 2 3 7 0.523598775598299 0.698131700797732
0.174532925199433
2.0 1.0 1.0 4 2 0 2 1 2 3 7 0.523598775598299 0.698131700797732
0.174532925199433
2.0 1.0 1.0 8 4 4 1 1 2 3 7 0.523598775598299 0.698131700797732
0.174532925199433
2.0 1.0 1.0 2 1 1 1 2 3 7 0.523598775598299 0.698131700797732
0.174532925199433
2.0 1.0 1.0 4 2 2 1 1 2 3 7 0.523598775598299 0.698131700797732
0.174532925199433
2.0 1.0 1.0 8 4 4 1 1 2 3 7 0.523598775598299 0.698131700797732
0.174532925199433
2.0 1.0 1.0 2 1 1 2 1 2 3 7 0.523598775598299 0.698131700797732
0.174532925199433
2.0 1.0 1.0 4 2 2 2 1 2 3 7 0.523598775598299 0.698131700797732
0.174532925199433
2.0 1.0 1.0 8 4 4 2 1 2 3 7 0.523598775598299 0.698131700797732
0.174532925199433

```

4.10.4 Result summary

We use CHeart rev. 6292 to produce numerical reference solutions.

Passed tests: 24 / 24

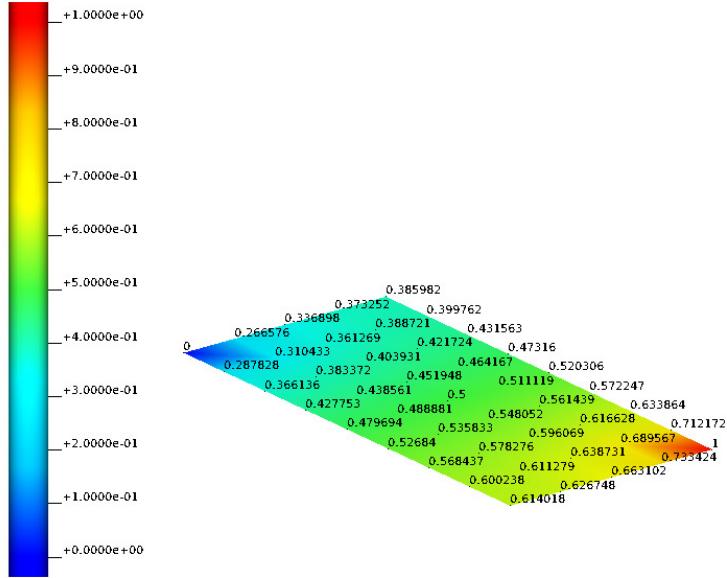


Figure 33: 2D results, iron reference w/ command line arguments [2.0 1.0 0.0 8 4 0 1 0 2 3 0 0.523598775598299 0 0].

4.10.5 Misc

OpenCMISS-iron assumes the conductivity tensor defined in local element Ξ coordinates and uses the fibre angles to rotate the conductivity tensor internally. The script `src/matlab/compute_conductivity_tensor.m` can be used to compute the conductivity tensor in world coordinates, since CHeart assumes the conductivity tensor to be defined in world coordinates. Thus, if one sets up a new test, one has to compute the conductivity tensor in world coordinates as input for CHeart to derive numerical reference data.

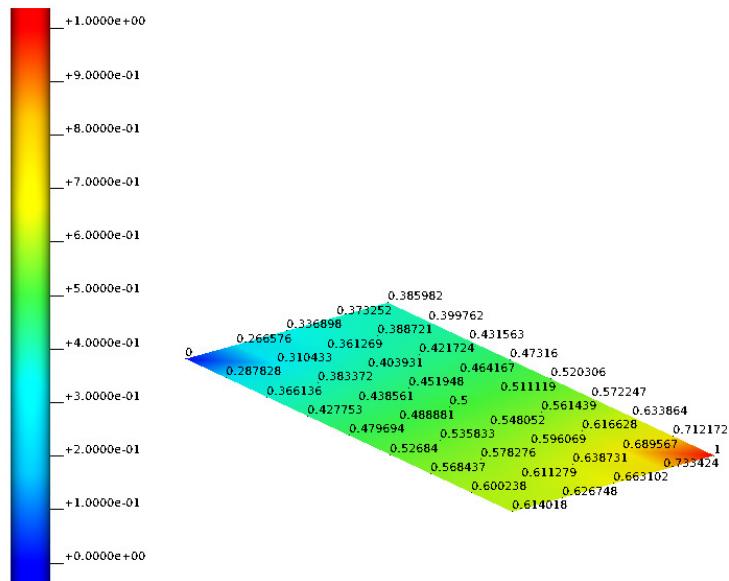


Figure 34: 2D results, current run w/ command line arguments [2.0 1.0 0.0 8 4 0 1 0 2 3 0 0.523598775598299 0 0].

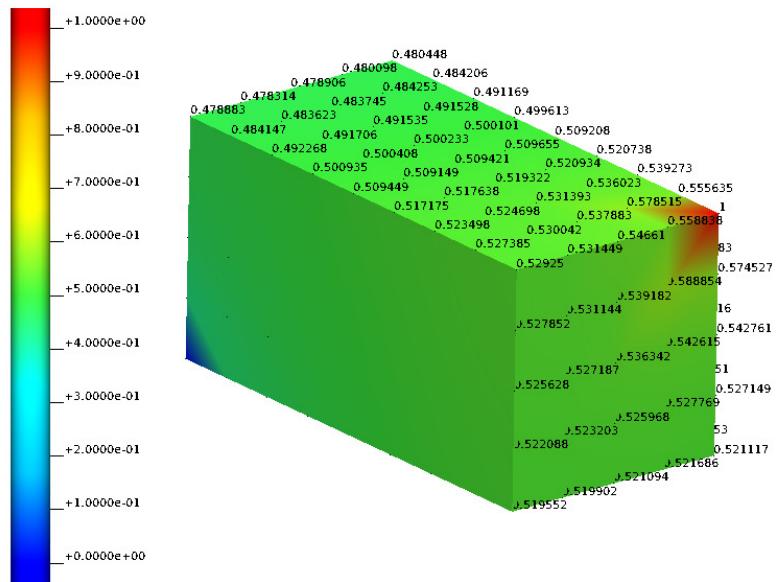


Figure 35: 3D results, iron reference w/ command line arguments [2.0 1.0 1.0 8 4 1 0 2 3 7 0.523598775598299 0.698131700797732 0.174532925199433].

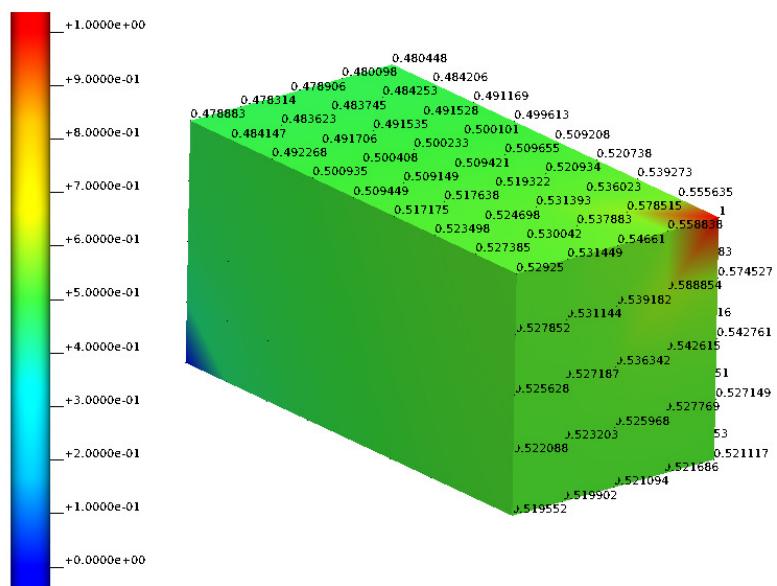


Figure 36: 3D results, current run w/ command line arguments [2.0 1.0 1.0 8 4 4 1 0 2 3 7 0.523598775598299 0.698131700797732 0.174532925199433].

5 LINEAR ELASTICITY

5.1 Equation in general form

$$\partial_{tt} \mathbf{u} + \nabla \cdot \boldsymbol{\sigma}(\mathbf{u}, t) = \mathbf{f}(\mathbf{u}, t) \quad (58)$$

5.2 Example-0101 [PLAUSIBLE]

5.2.1 Mathematical model

We solve the following equation (both 2D and 3D domains are considered),

$$\nabla \cdot \sigma(\mathbf{u}, t) = 0 \quad \Omega = [0, 160] \times [0, 120] \times [0, 120], t \in [0, 5], \quad (59)$$

with time step size $\Delta t = 1$ and $\mathbf{u} = [u_x, u_y]$ in 2D $\mathbf{u} = [u_x, u_y, u_z]$ in 3D. The boundary conditions in 2D are given by

$$u_x = 0 \quad x = 0, \quad (60)$$

$$u_y = 0 \quad y = 0, \quad (61)$$

$$u_x = 8 \quad x = 160, \quad (62)$$

and in 3D by

$$u_x = 0 \quad x = 0, \quad (63)$$

$$u_y = 0 \quad y = 0, \quad (64)$$

$$u_z = 0 \quad z = 0, \quad (65)$$

$$u_x = 8 \quad x = 160. \quad (66)$$

The material parameters are

$$E = 10000 \text{ MPa}, \quad (67)$$

$$\nu = 0.3, \quad (68)$$

$$(69)$$

5.2.2 Computational model

- Commandline arguments are:

float: length along x-direction

float: length along y-direction

float: length along z-direction (set to zero for 2D)

integer: number of elements in x-direction

integer: number of elements in y-direction

integer: number of elements in z-direction (set to zero for 2D)

integer: interpolation order (1: linear; 2: quadratic)

integer: solver type (0: direct; 1: iterative)

float: elastic modulus

float: Poisson ratio

float: displacement percentage load

- Command line arguments for tests are:

160 120 0 8 6 0 1 0 10000 0.3 0.05

160 120 0 16 12 0 1 0 10000 0.3 0.05

160 120 0 32 24 0 1 0 10000 0.3 0.05

160 120 120 8 6 6 1 0 10000 0.3 0.05

160 120 120 16 12 12 1 0 10000 0.3 0.05

160 120 120 32 24 24 1 0 10000 0.3 0.05

```

160 120 0 8 6 0 2 0 10000 0.3 0.05
160 120 0 16 12 0 2 0 10000 0.3 0.05
160 120 0 32 24 0 2 0 10000 0.3 0.05
160 120 120 8 6 6 2 0 10000 0.3 0.05
160 120 120 16 12 12 2 0 10000 0.3 0.05
160 120 120 32 24 24 2 0 10000 0.3 0.05

```

5.2.3 Validation

The iron results are compared to those from Abaqus (version 2017). The figures below show selected results from the validation simulations carried out in Abaqus and provide a qualitative validation. A quantitative validation was carried out by comparing the horizontal displacement u_y along the free-edge ($y = 120$ for 2D and $y = z = 120$ for 3D) and computing the L₂-norm according to

$$L_2\text{-norm} = \frac{1}{N} \times \sum_{i=1}^N \sqrt{\left(u_{y,\text{abaqus}}^i - u_{y,\text{iron}}^i\right)^2}, \quad (70)$$

where N is the total number of nodes along the free-edge. The results over the mesh refinements are given in Table 1.

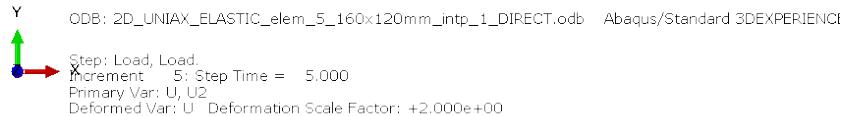
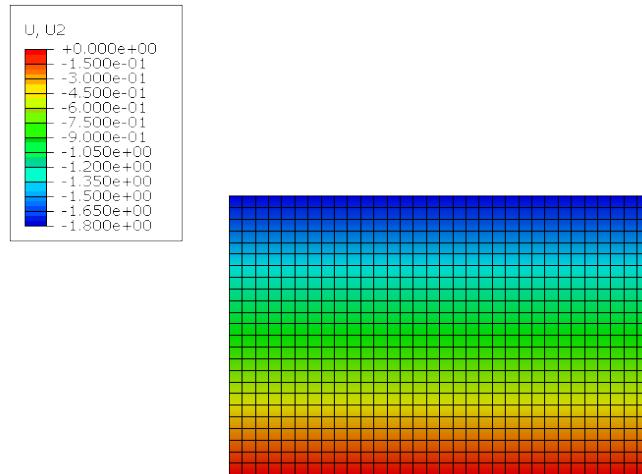


Figure 37: Results, Abaqus 2D fine mesh.

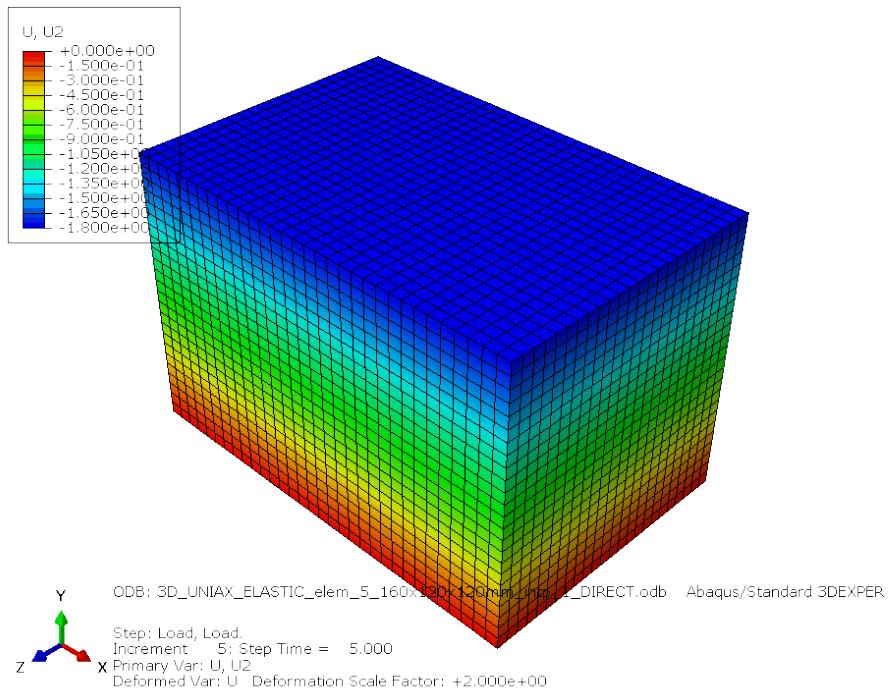


Figure 38: Results, abaqus 3D fine mesh.

Dimension	Mesh	L_2 -norm	Interpolation
2D	Coarse	5.322×10^{-16}	Linear
2D	Medium	1.559×10^{-15}	Linear
2D	Fine	2.900×10^{-15}	Linear
3D	Coarse	3.071×10^{-17}	Linear
3D	Medium	2.125×10^{-17}	Linear
3D	Fine	2.924×10^{-17}	Linear
2D	Coarse	9.728×10^{-16}	Quadratic
2D	Medium	2.039×10^{-15}	Quadratic
2D	Fine	2.159×10^{-15}	Quadratic
3D	Coarse	6.687×10^{-16}	Quadratic
3D	Medium	...	Quadratic
3D	Fine	...	Quadratic

Table 1: Quantitative error between Abaqus 2017 and iron simulations for linear elastic uniaxial extensions

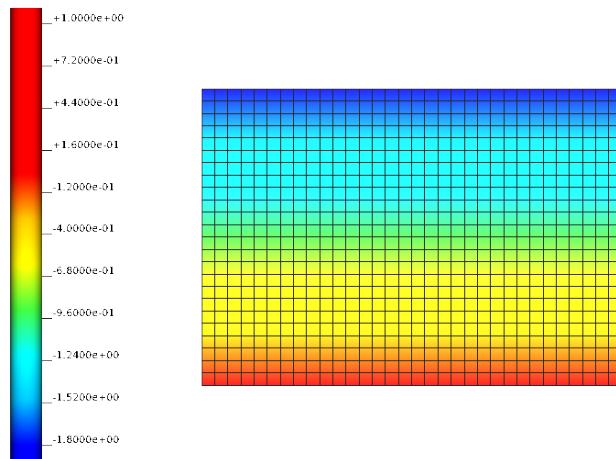


Figure 39: Results, iron 2D fine mesh.

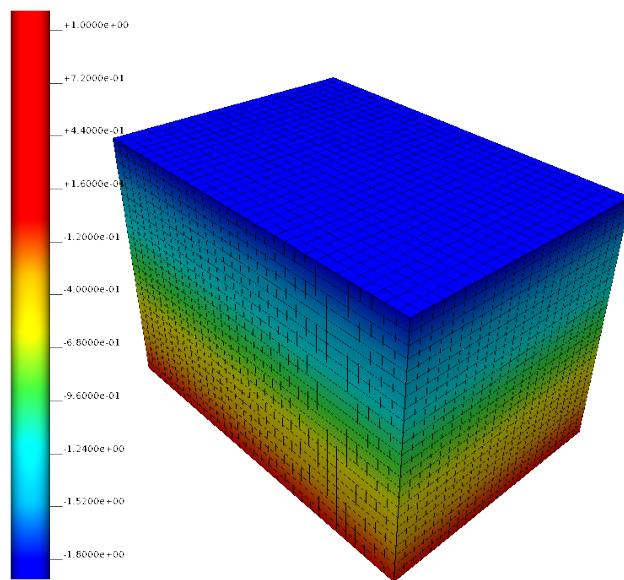


Figure 40: Results, iron 3D fine mesh.

5.3 Example-0102 [PLAUSIBLE]

5.3.1 Mathematical model

We solve the following equation (both 2D and 3D domains are considered),

$$\nabla \cdot \sigma(\mathbf{u}, t) = 0 \quad \Omega = [0, 160] \times [0, 120] \times [0, 120], t \in [0, 5], \quad (71)$$

with time step size $\Delta t = 1$ and $\mathbf{u} = [u_x, u_y]$ in 2D $\mathbf{u} = [u_x, u_y, u_z]$ in 3D. The boundary conditions in 2D are given by

$$u_x = u_y = 0 \quad x = 0, \quad (72)$$

$$u_x = 0 \quad x = 160, \quad (73)$$

$$u_y = 8 \quad x = 160, \quad (74)$$

and in 3D by

$$u_x = u_y = u_z = 0 \quad x = 0, \quad (75)$$

$$u_x = u_z = 0 \quad x = 160, \quad (76)$$

$$u_y = 8 \quad x = 160. \quad (77)$$

The material parameters are

$$E = 10000 \text{ MPa}, \quad (78)$$

$$\nu = 0.3, \quad (79)$$

$$(80)$$

5.3.2 Computational model

- Commandline arguments are:

float: length along x-direction

float: length along y-direction

float: length along z-direction (set to zero for 2D)

integer: number of elements in x-direction

integer: number of elements in y-direction

integer: number of elements in z-direction (set to zero for 2D)

integer: interpolation order (1: linear; 2: quadratic)

integer: solver type (0: direct; 1: iterative)

float: elastic modulus

float: Poisson ratio

float: displacement percentage load

- Command line arguments for tests are:

160 120 0 8 6 0 1 0 10000 0.3 0.05

160 120 0 16 12 0 1 0 10000 0.3 0.05

160 120 0 32 24 0 1 0 10000 0.3 0.05

160 120 120 8 6 6 1 0 10000 0.3 0.05

160 120 120 16 12 12 1 0 10000 0.3 0.05

160 120 120 32 24 24 1 0 10000 0.3 0.05

160 120 0 8 6 0 2 0 10000 0.3 0.05

```

160 120 0 16 12 0 2 0 10000 0.3 0.05
160 120 0 32 24 0 2 0 10000 0.3 0.05
160 120 120 8 6 6 2 0 10000 0.3 0.05
160 120 120 16 12 12 2 0 10000 0.3 0.05
160 120 120 32 24 24 2 0 10000 0.3 0.05

```

5.3.3 Validation

The iron results are compared to those from Abaqus (version 2017). The figures below show selected results from the validation simulations carried out in Abaqus and provide a qualitative validation. A quantitative validation was carried out by comparing the horizontal displacement u_x along the free-edge ($y = 120$ for 2D and $y = z = 120$ for 3D) and computing the L₂-norm according to

$$L_2\text{-norm} = \frac{1}{N} \times \sum_{i=1}^N \sqrt{(u_{y,\text{abaqus}}^i - u_{y,\text{iron}}^i)^2}, \quad (81)$$

where N is the total number of nodes along the free-edge. The results over the mesh refinements are given in Table 2.

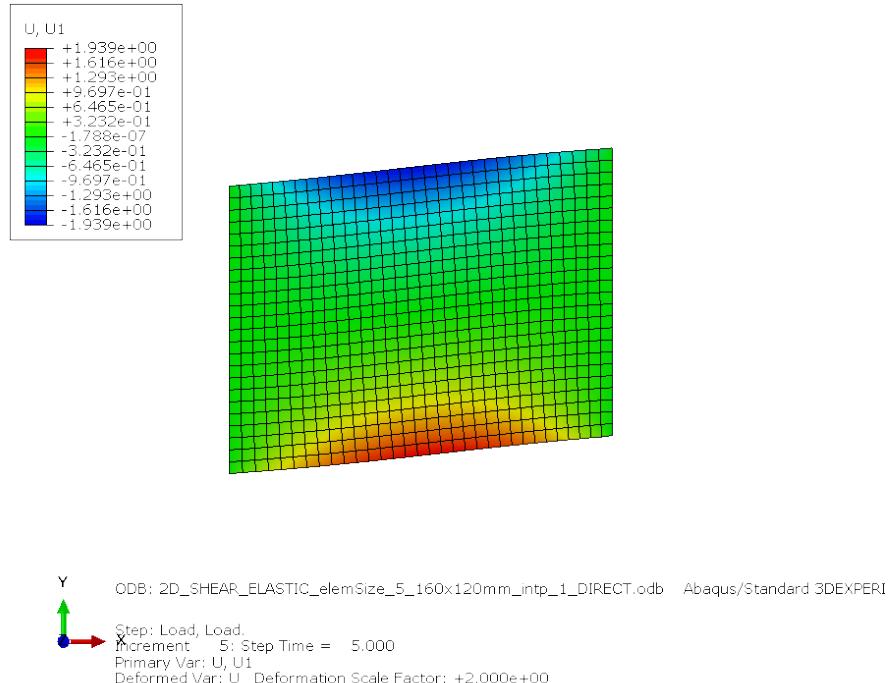


Figure 41: Results, Abaqus 2D fine mesh.

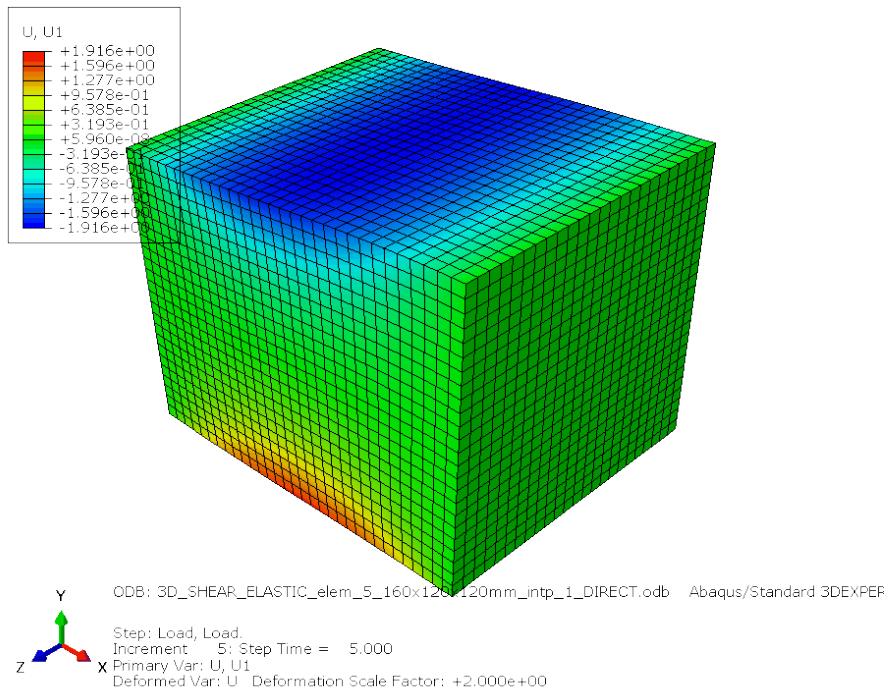


Figure 42: Results, abaqus 3D fine mesh.

Dimension	Mesh	L_2 -norm	Interpolation
2D	Coarse	6.696×10^{-3}	Linear
2D	Medium	1.273×10^{-3}	Linear
2D	Fine	2.489×10^{-4}	Linear
3D	Coarse	4.234×10^{-4}	Linear
3D	Medium	4.184×10^{-5}	Linear
3D	Fine	3.781×10^{-6}	Linear
2D	Coarse	3.036×10^{-4}	Quadratic
2D	Medium	6.099×10^{-5}	Quadratic
2D	Fine	1.089×10^{-5}	Quadratic
3D	Coarse	...	Quadratic
3D	Medium	...	Quadratic
3D	Fine	...	Quadratic

Table 2: Quantitative error between Abaqus 2017 and iron simulations for linear elastic shear

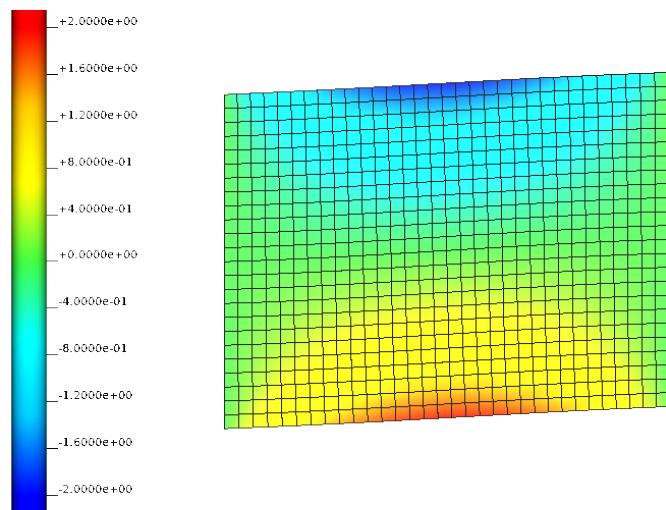


Figure 43: Results, iron 2D fine mesh.

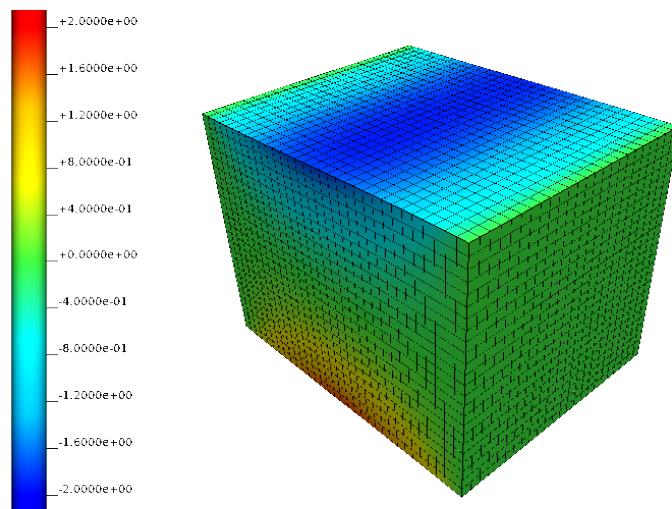


Figure 44: Results, iron 3D fine mesh.

5.4 Example-0111 [PLAUSIBLE]

5.4.1 Mathematical model

We solve the following equation (both 2D and 3D domains are considered),

$$\nabla \cdot \sigma(\mathbf{u}, t) = \mathbf{f}(\mathbf{u}, t) \quad \Omega = [0, 160] \times [0, 120] \times [0, 120], t \in [0, 5], \quad (82)$$

with time step size $\Delta t = 1$ (used for load stepping) and $\mathbf{u} = [u_x, u_y]$ in 2D $\mathbf{u} = [u_x, u_y, u_z]$ in 3D. The boundary conditions in 2D are given by

$$u_x = 0 \quad x = 0, \quad (83)$$

$$u_y = 0 \quad y = 0, \quad (84)$$

$$f(u_x) = 6.0 \times 10^4 \quad x = 160, \quad (85)$$

and in 3D by

$$u_x = 0 \quad x = 0, \quad (86)$$

$$u_y = 0 \quad y = 0, \quad (87)$$

$$u_z = 0 \quad z = 0, \quad (88)$$

$$f(u_x) = 7.2 \times 10^6 \quad x = 160. \quad (89)$$

The material parameters are

$$E = 10000 \text{ MPa}, \quad (90)$$

$$\nu = 0.3, \quad (91)$$

$$(92)$$

5.4.2 Computational model

- Commandline arguments are:

float: length along x-direction

float: length along y-direction

float: length along z-direction (set to zero for 2D)

integer: number of elements in x-direction

integer: number of elements in y-direction

integer: number of elements in z-direction (set to zero for 2D)

integer: interpolation order (1: linear; 2: quadratic)

integer: solver type (0: direct; 1: iterative)

float: elastic modulus

float: Poisson ratio

float: XXX

- Command line arguments for tests are:

160 120 0 8 6 0 1 0 10000 0.3 XXX

160 120 0 16 12 0 1 0 10000 0.3 XXX

160 120 0 32 24 0 1 0 10000 0.3 XXX

160 120 120 8 6 6 1 0 10000 0.3 XXX

160 120 120 16 12 12 1 0 10000 0.3 XXX

```

160 120 120 32 24 24 1 0 10000 0.3 XXX
160 120 0 8 6 0 2 0 10000 0.3 XXX
160 120 0 16 12 0 2 0 10000 0.3 XXX
160 120 0 32 24 0 2 0 10000 0.3 XXX
160 120 120 8 6 6 2 0 10000 0.3 XXX
160 120 120 16 12 12 2 0 10000 0.3 XXX
160 120 120 32 24 24 2 0 10000 0.3 XXX

```

5.4.3 Validation

The iron results are compared to those from Abaqus (version 2017). The figures below show selected results from the validation simulations carried out in Abaqus and provide a qualitative validation. A quantitative validation was carried out by comparing the horizontal displacement u_y along the free-edge ($y = 120$ for 2D and $y = z = 120$ for 3D) and computing the L₂-norm according to

$$L_2\text{-norm} = \frac{1}{N} \times \sum_{i=1}^N \sqrt{(u_{y, \text{abaqus}}^i - u_{y, \text{iron}}^i)^2}, \quad (93)$$

where N is the total number of nodes along the free-edge. The results over the mesh refinements are given in Table 3.

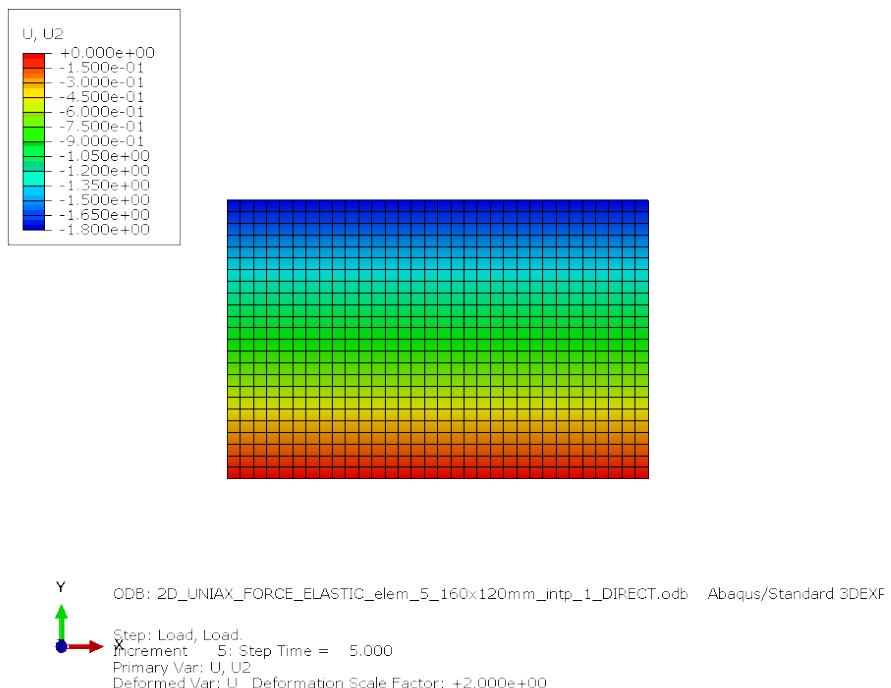


Figure 45: Results, Abaqus 2D fine mesh.

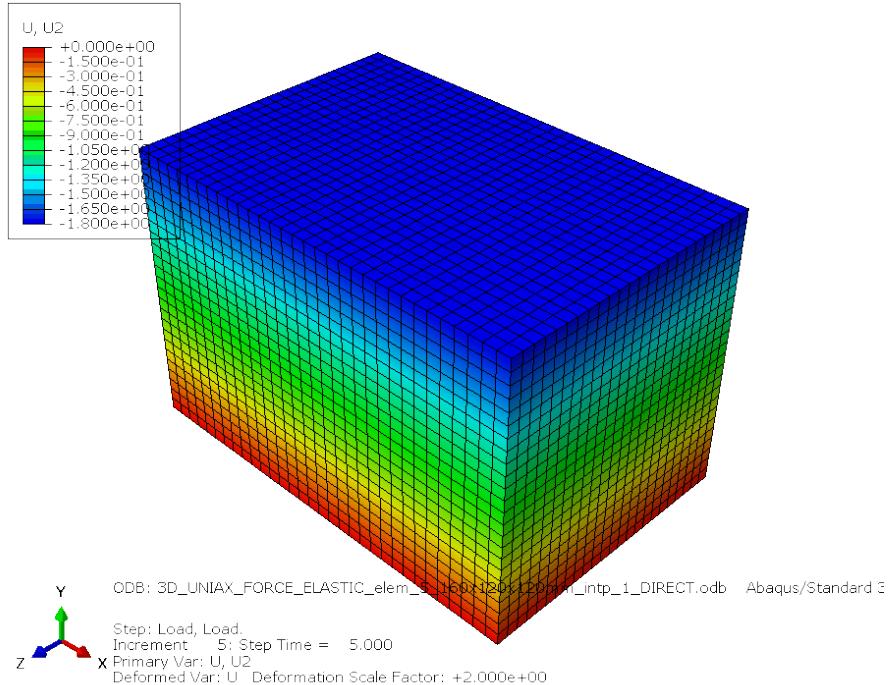


Figure 46: Results, abaqus 3D fine mesh.

Dimension	Mesh	L_2 -norm	Interpolation
2D	Coarse	...	Linear
2D	Medium	...	Linear
2D	Fine	...	Linear
3D	Coarse	...	Linear
3D	Medium	...	Linear
3D	Fine	...	Linear
2D	Coarse	...	Quadratic
2D	Medium	...	Quadratic
2D	Fine	...	Quadratic
3D	Coarse	...	Quadratic
3D	Medium	...	Quadratic
3D	Fine	...	Quadratic

Table 3: Quantitative error between Abaqus 2017 and iron simulations for linear elastic uniaxial extensions

Figure 47: Results, iron 2D fine mesh.

Figure 48: Results, iron 3D fine mesh.

5.5 Example-0112 [PLAUSIBLE]

5.5.1 Mathematical model

We solve the following equation (both 2D and 3D domains are considered),

$$\nabla \cdot \sigma(\mathbf{u}, t) = \mathbf{f}(\mathbf{u}, t) \quad \Omega = [0, 160] \times [0, 120] \times [0, 120], t \in [0, 5], \quad (94)$$

with time step size $\Delta t = 1$ and $\mathbf{u} = [u_x, u_y]$ in 2D $\mathbf{u} = [u_x, u_y, u_z]$ in 3D. The boundary conditions in 2D are given by

$$u_x = u_y = 0 \quad x = 0, \quad (95)$$

$$u_x = 0 \quad x = 160, \quad (96)$$

$$f(u_y) = 6.0 \times 10^4 \quad x = 160, \quad (97)$$

and in 3D by

$$u_x = u_y = 0 \quad x = 0, \quad (98)$$

$$u_x = 0 \quad x = 160, \quad (99)$$

$$u_z = 0 \quad z = 0, \quad (100)$$

$$f(u_y) = 7.2 \times 10^6 \quad x = 160. \quad (101)$$

The material parameters are

$$E = 10000 \text{ MPa}, \quad (102)$$

$$\nu = 0.3, \quad (103)$$

$$(104)$$

5.5.2 Computational model

- Commandline arguments are:

float: length along x-direction
 float: length along y-direction
 float: length along z-direction (set to zero for 2D)
 integer: number of elements in x-direction
 integer: number of elements in y-direction
 integer: number of elements in z-direction (set to zero for 2D)
 integer: interpolation order (1: linear; 2: quadratic)
 integer: solver type (0: direct; 1: iterative)
 float: elastic modulus
 float: Poisson ratio
 float: XXX

- Command line arguments for tests are:

```
160 120 0 8 6 0 1 0 10000 0.3 XXX
160 120 0 16 12 0 1 0 10000 0.3 XXX
160 120 0 32 24 0 1 0 10000 0.3 XXX
160 120 120 8 6 6 1 0 10000 0.3 XXX
160 120 120 16 12 12 1 0 10000 0.3 XXX
```

```

160 120 120 32 24 24 1 0 10000 0.3 XXX
160 120 0 8 6 0 2 0 10000 0.3 XXX
160 120 0 16 12 0 2 0 10000 0.3 XXX
160 120 0 32 24 0 2 0 10000 0.3 XXX
160 120 120 8 6 6 2 0 10000 0.3 XXX
160 120 120 16 12 12 2 0 10000 0.3 XXX
160 120 120 32 24 24 2 0 10000 0.3 XXX

```

5.5.3 Validation

The iron results are compared to those from Abaqus (version 2017). The figures below show selected results from the validation simulations carried out in Abaqus and provide a qualitative validation. A quantitative validation was carried out by comparing the horizontal displacement u_x along the free-edge ($y = 120$ for 2D and $y = z = 120$ for 3D) and computing the L₂-norm according to

$$L_2\text{-norm} = \frac{1}{N} \times \sum_{i=1}^N \sqrt{(u_{y, \text{abaqus}}^i - u_{y, \text{iron}}^i)^2}, \quad (105)$$

where N is the total number of nodes along the free-edge. The results over the mesh refinements are given in Table 4.

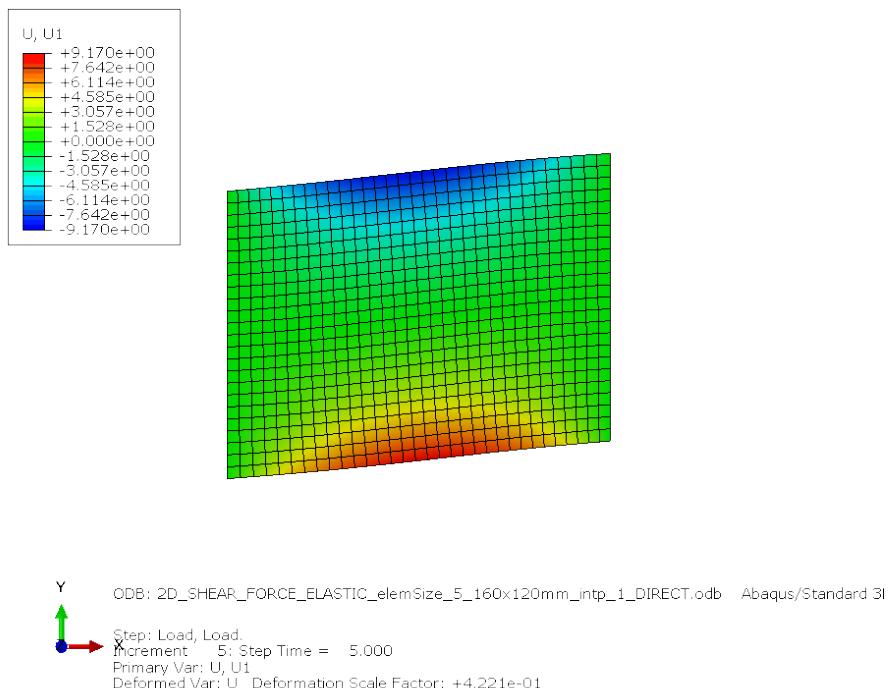


Figure 49: Results, Abaqus 2D fine mesh.

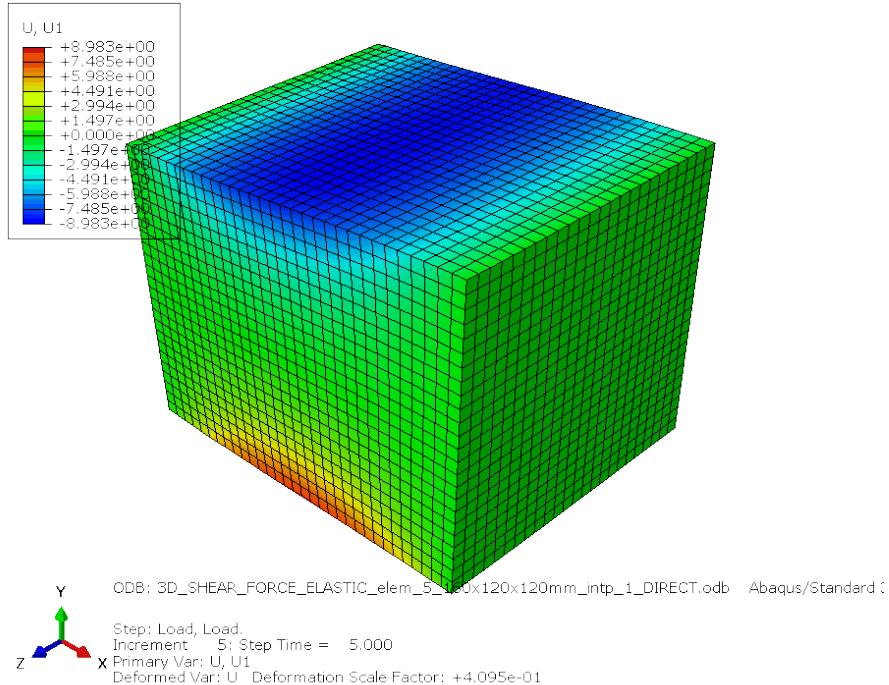


Figure 50: Results, abaqus 3D fine mesh.

Figure 51: Results, iron 2D fine mesh.

Figure 52: Results, iron 3D fine mesh.

Dimension	Mesh	L_2 -norm	Interpolation
2D	Coarse	...	Linear
2D	Medium	...	Linear
2D	Fine	...	Linear
3D	Coarse	...	Linear
3D	Medium	...	Linear
3D	Fine	...	Linear
2D	Coarse	...	Quadratic
2D	Medium	...	Quadratic
2D	Fine	...	Quadratic
3D	Coarse	...	Quadratic
3D	Medium	...	Quadratic
3D	Fine	...	Quadratic

Table 4: Quantitative error between Abaqus 2017 and iron simulations for linear elastic shear

6 FINITE ELASTICITY

6.1 Example-0201-u [PLAUSIBLE]

Example uses generated or user-defined regular meshes in CHeart mesh format and solves a static problem, i.e., applies the boundary conditions in one step.

Issues/TBD: 2D, analytical Jacobian

6.1.1 Mathematical model - 3D

We solve the following scalar equation,

$$\nabla \cdot \mathbf{P}(\mathbf{u}, t) = 0 \quad \Omega = [0, L_X] \times [0, L_Y] \times [0, L_Z], \quad (106)$$

with 1st Piola-Kirchhoff stress tensor in d dimensions,

$$\mathbf{P} = \frac{2\mu}{[\det \mathbf{F}]^{2/d}} \left(\mathbf{F} - \frac{\mathbf{F} : \mathbf{F}}{d} \mathbf{F}^{-T} \right) + p \mathbf{F}^{-T} \quad (107)$$

corresponding to a Neo-Hookean constitutive law (Neo-Hooke parameter μ) with Dirichlet boundary conditions

$$u_x = 0 \quad X = 0, \quad (108)$$

$$u_x = u_y = u_z = 0 \quad X = Y = Z = 0, \quad (109)$$

$$u_x = \lambda * L_X \quad X = L_X. \quad (110)$$

or Dirichlet/Neumann boundary conditions

$$u_x = 0 \quad X = 0, \quad (111)$$

$$u_x = u_y = u_z = 0 \quad X = Y = Z = 0, \quad (112)$$

$$\mathbf{t} = \begin{bmatrix} \mu(\lambda - \frac{\mu}{\lambda^2}) \\ 0 \\ 0 \end{bmatrix} \quad X = L_X. \quad (113)$$

with stretch λ and traction \mathbf{t} .

Note: The pressure has an opposite sign compared to CHeart and Ker-MOR.

6.1.2 Computational model

- Commandline arguments are:

float: initial length along x-direction

float: initial length along y-direction

float: initial length along z-direction

integer: number of elements in x-direction

integer: number of elements in y-direction

integer: number of elements in z-direction

integer: use direct solver?

integer: use finite-difference Jacobian

float: 1st Mooney-Rivlin parameter

float: 2nd Mooney-Rivlin parameter (set to zero)

integer: use generated mesh?
 float: maximum stretch
 integer: use only Dirichlet BC?

- Commandline arguments for tests are:

```
2.0 1.0 1.0 4 2 2 1 1 17.85 0.0 1 0.2 1
2.0 1.0 1.0 4 2 2 1 1 17.85 0.0 1 0.2 0
2.0 1.0 1.0 8 4 4 1 1 17.85 0.0 1 0.2 1
2.0 1.0 1.0 8 4 4 1 1 17.85 0.0 1 0.2 0
2.0 1.0 1.0 16 8 8 1 1 17.85 0.0 1 0.2 1
2.0 1.0 1.0 16 8 8 1 1 17.85 0.0 1 0.2 0
2.0 1.0 1.0 4 2 2 1 1 17.85 0.0 0 0.2 1
2.0 1.0 1.0 4 2 2 1 1 17.85 0.0 0 0.2 0
2.0 1.0 1.0 8 4 4 1 1 17.85 0.0 0 0.2 1
2.0 1.0 1.0 8 4 4 1 1 17.85 0.0 0 0.2 0
2.0 1.0 1.0 16 8 8 1 1 17.85 0.0 0 0.2 1
2.0 1.0 1.0 16 8 8 1 1 17.85 0.0 0 0.2 0
```

- Note: Binary uses command line arguments to search for the relevant mesh files if user-defined meshes are selected.

6.1.3 *Result summary*

We use iron reference results that were compared against an analytical solution.

Passed tests: 12 / 12

No failed tests.

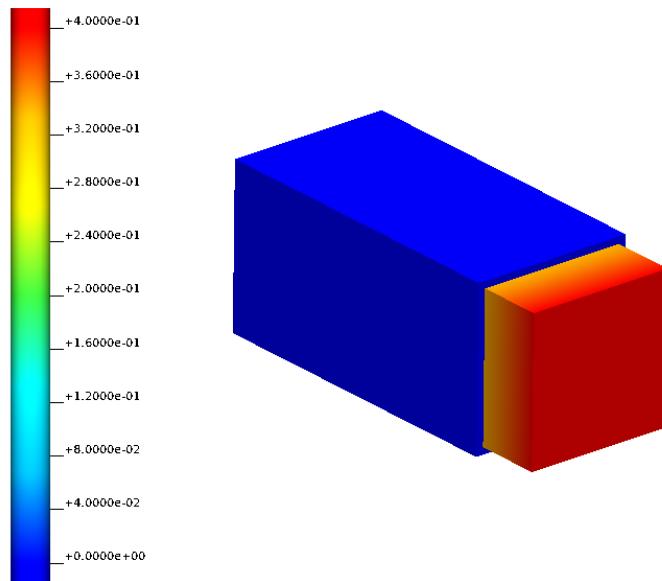


Figure 53: 3D results, iron reference w/ command line arguments [...].

Figure 54: 3D results, current run w/ command line arguments [...].

6.2 Example-0204-u [PLAUSIBLE]

Example uses user-defined hexahedral mesh (tibialis anterior with skin) in CHeart mesh format and solves a static problem, i.e., applies the boundary conditions in one step.

6.2.1 Mathematical model - 3D

We solve the following scalar equation,

$$\nabla \cdot \mathbf{P}(\mathbf{u}, t) = 0 \quad \Omega, \quad (114)$$

with 1st Piola-Kirchhoff stress tensor in d dimensions,

$$\mathbf{P} = \frac{2\mu}{[\det \mathbf{F}]^{2/d}} \left(\mathbf{F} - \frac{\mathbf{F} : \mathbf{F}}{d} \mathbf{F}^{-T} \right) + p \mathbf{F}^{-T} \quad (115)$$

corresponding to a Neo-Hookean constitutive law (Neo-Hooke parameter μ) with Dirichlet boundary conditions

$$u_x = u_y = u_z = 0 \quad \text{BOTTOM}, \quad (116)$$

$$u_x = u_y = u_z = 2 \quad \text{TOP}. \quad (117)$$

Undeformed geometry and deformed geometry with pressure field in Figure 55 (left). Deformed geometry with displacement field in Figure 56.

Note: The pressure has an opposite sign compared to CHeart and Ker-MOR.

6.2.2 Computational model

- Commandline arguments are:

string: Mesh input file

integer: solver type (0 - iterative, 1 - direct)

integer: Jacobian type (0 - analytic, 1 - finite difference)

float: 1st Mooney-Rivlin parameter

float: 2nd Mooney-Rivlin parameter (set to zero)

float: absolute displacement at top surface in each coordinate direction

integer: number of load increments

integer: BC type at top surface (0 - Dirichlet BC, 1 - Neumann_integrated, 2 - Neumann_point)

- Commandline arguments for tests are:

TBD

- Note: Binary uses command line arguments to search for the relevant mesh files if user-defined meshes are selected.

6.2.3 Result summary

We use CHeart revision 6411 to compare all displacement components and the pressure field (reference value: RSE of normalized RMSE of components is 0.00484848482722).

Passed tests: 1 / 12

Failed tests:

```
Folder reference/iron/s0_fd0_bc0/ does not exist.
Folder reference/iron/s0_fd0_bc1/ does not exist.
Folder reference/iron/s0_fd0_bc2/ does not exist.
Folder reference/iron/s0_fd1_bc0/ does not exist.
Folder reference/iron/s0_fd1_bc1/ does not exist.
Folder reference/iron/s0_fd1_bc2/ does not exist.
Folder reference/iron/s1_fd0_bc0/ does not exist.
Folder reference/iron/s1_fd0_bc1/ does not exist.
Folder reference/iron/s1_fd0_bc2/ does not exist.
Folder reference/iron/s1_fd1_bc1/ does not exist.
Folder reference/iron/s1_fd1_bc2/ does not exist.
```

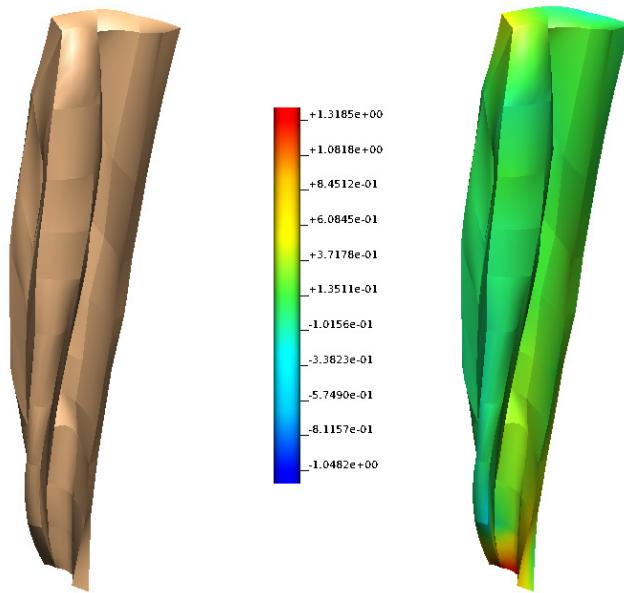


Figure 55: Iron reference run, undeformed geometry and deformed geometry with pressure field.

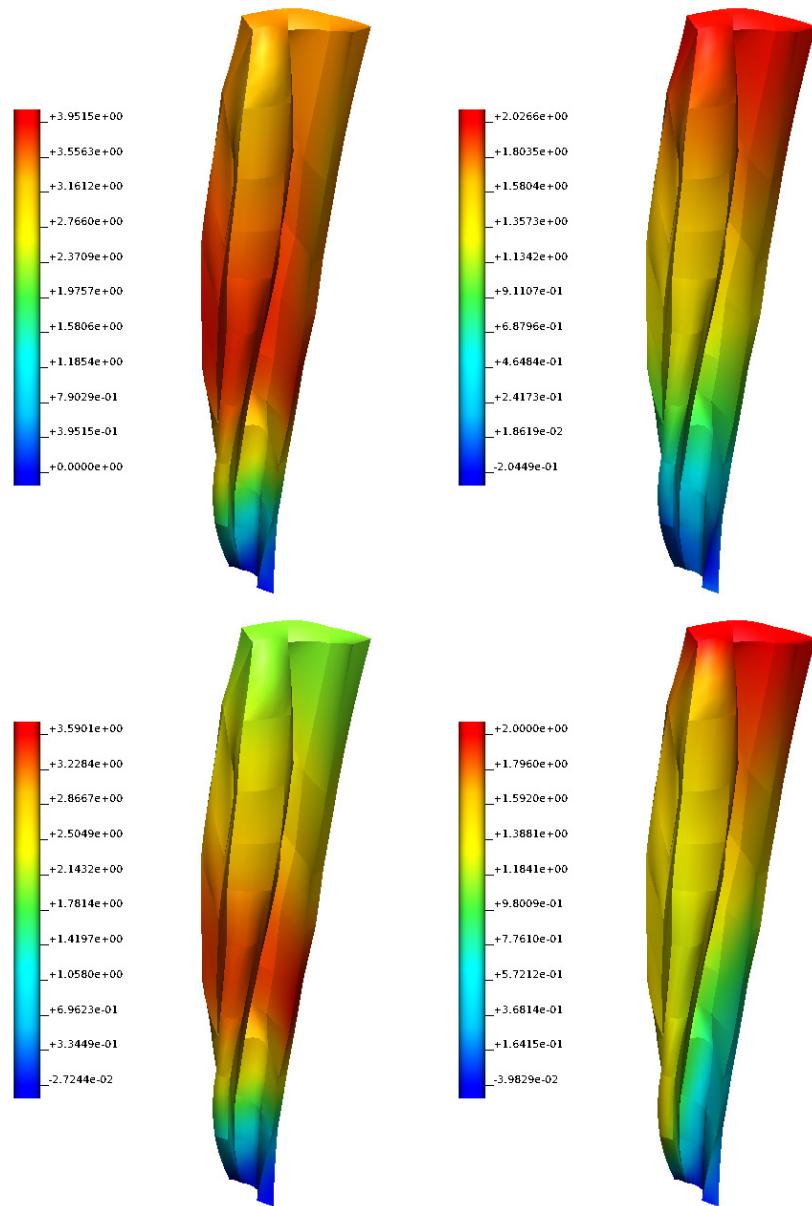


Figure 56: Iron reference run, top-left to bottom-right: Deformed geometry with displacement field magnitude, x-component, y-component and z-component.

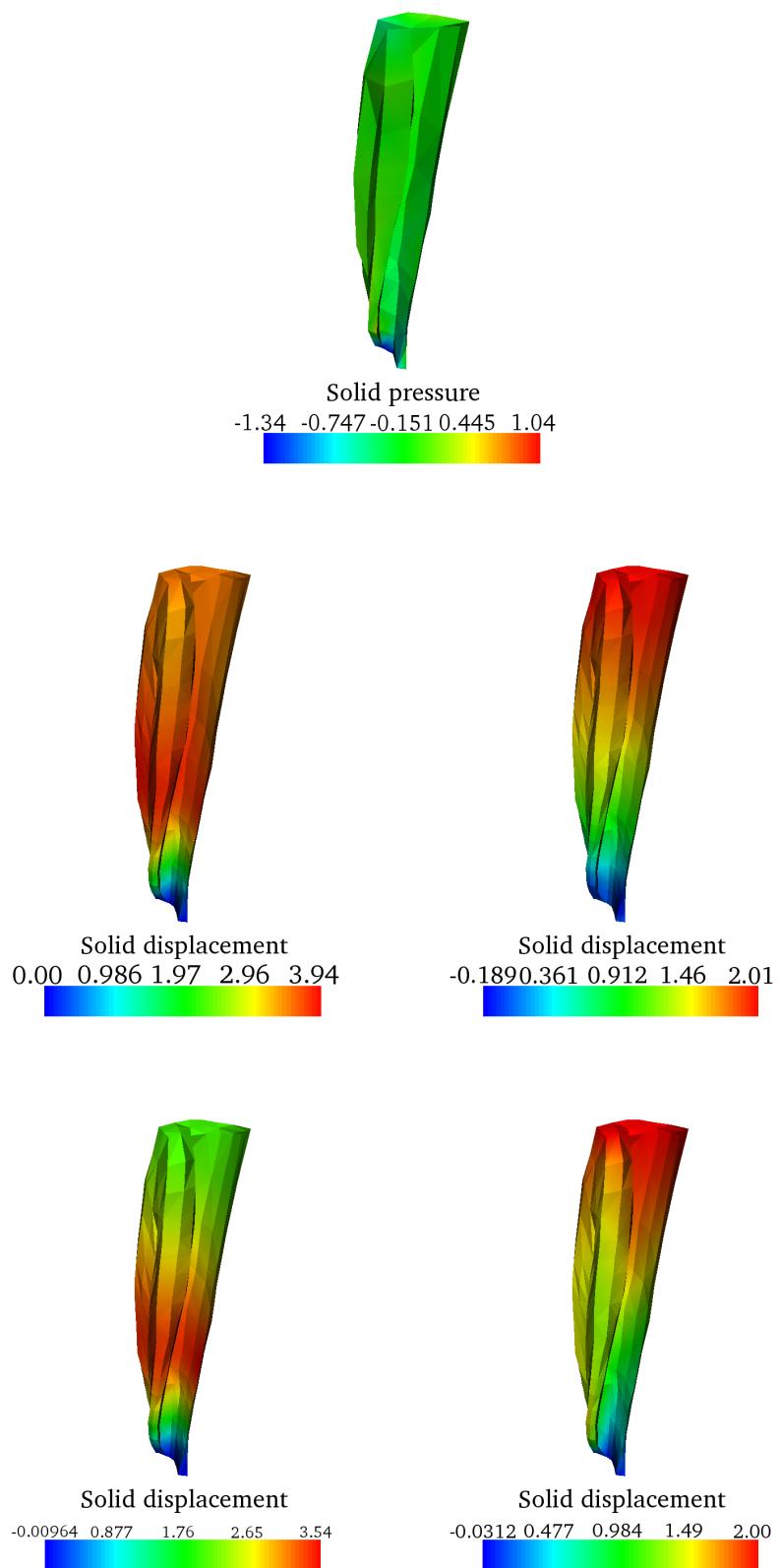


Figure 57: CHeart reference run, top-left to bottom-right: Deformed geometry with displacement field magnitude, x-component, y-component and z-component.

7 NAVIER-STOKES FLOW

7.1 Equation in general form

$$\partial_t(\rho \mathbf{v}) + \nabla \cdot (\rho \mathbf{v} \otimes \mathbf{v} + p \mathbf{I}) = \rho \mathbf{f} \quad (118)$$

7.2 Example-0302-u [COMPILES]

Example uses user-defined simplex meshes in CHart mesh format with quadratic/linear interpolation for velocity/pressure and solves a dynamic problem.

Setup is the well-known lid-driven cavity problem on the unit square or unit cube in two and three dimensions.

Current issue: does not converge after 30 some time iterations (2D and 3D).

Visualization issue: In exelem-file, replace

1. constant(2)*constant, no modify, grid based.
#xi1=0, #xi2=0
2. constant(2)*constant, no modify, grid based.

with

1. constant*constant, no modify, grid based.
#xi1=0, #xi2=0
2. constant*constant, no modify, grid based.

and likewise for 3D, replace

1. constant(2;3)*constant*constant, no modify, grid based.
#xi1=0, #xi2=0, #xi3=0
2. constant(2;3)*constant*constant, no modify, grid based.

with

1. constant*constant*constant, no modify, grid based.
#xi1=0, #xi2=0, #xi3=0
2. constant*constant*constant, no modify, grid based.

7.2.1 Mathematical model - 2D

We solve the incompressible Navier-Stokes equation,

$$\partial_t(\rho \mathbf{v}) + \nabla \cdot (\rho \mathbf{v} \otimes \mathbf{v}) - \nabla \cdot (\mu \nabla \mathbf{v} - \rho \mathbf{I}) = \rho \mathbf{f} \quad \Omega = [0, 1] \times [0, 1], \quad (119)$$

$$\nabla \cdot \mathbf{v} = 0, \quad (120)$$

with boundary conditions

$$\mathbf{v} = 0 \quad x = 0, \quad (121)$$

$$\mathbf{v} = 0 \quad x = 1, \quad (122)$$

$$\mathbf{v} = 0 \quad y = 0, \quad (123)$$

$$\mathbf{v} = [1, 0]^T \quad y = 1. \quad (124)$$

Viscosity $\mu = 0.0025$, density $\rho = 1$. Thus, Reynolds number $Re = 400$.

7.2.2 Mathematical model - 3D

We solve the incompressible Navier-Stokes equation,

$$\partial_t(\rho \mathbf{v}) + \nabla \cdot (\rho \mathbf{v} \otimes \mathbf{v}) - \nabla \cdot (\mu \nabla \mathbf{v} - p \mathbf{I}) = \rho \mathbf{f} \quad \Omega = [0, 1] \times [0, 1] \times [0, 1], \quad (125)$$

$$\nabla \cdot \mathbf{v} = 0, \quad (126)$$

with boundary conditions

$$\mathbf{v} = 0 \quad x = 0, \quad (127)$$

$$\mathbf{v} = 0 \quad x = 1, \quad (128)$$

$$\mathbf{v} = 0 \quad y = 0, \quad (129)$$

$$\mathbf{v} = [1, 0]^T \quad y = 1, \quad (130)$$

$$\mathbf{v} = 0 \quad z = 0, \quad (131)$$

$$\mathbf{v} = 0 \quad z = 1. \quad (132)$$

Viscosity $\mu = 0.01$, density $\rho = 1$. Thus, Reynolds number $Re = 100$.

7.2.3 Computational model

- Commandline arguments are:

integer: number of dimensions (2: 2D, 3: 3D)

integer: mesh refinement level (1, 2, 3, ...)

float: start time

float: stop time

float: time step size

float: density

float: viscosity

integer: solver type (0: direct; 1: iterative)

- Commandline arguments for tests are:

2 1 0.0 1.0 0.001 0.0025 1.0 0

2 2 0.0 1.0 0.001 0.0025 1.0 0

2 3 0.0 1.0 0.001 0.0025 1.0 0

2 1 0.0 1.0 0.001 0.0025 1.0 1

2 2 0.0 1.0 0.001 0.0025 1.0 1

2 3 0.0 1.0 0.001 0.0025 1.0 1

3 1 0.0 1.0 0.001 0.01 1.0 0

3 2 0.0 1.0 0.001 0.01 1.0 0

3 3 0.0 1.0 0.001 0.01 1.0 0

3 1 0.0 1.0 0.001 0.01 1.0 1

3 2 0.0 1.0 0.001 0.01 1.0 1

3 3 0.0 1.0 0.001 0.01 1.0 1

- Note: Binary uses command line arguments to search for the relevant mesh files.

7.2.4 *Result summary*

We use CHeart rev. 6292 to produce numerical reference solutions.

8 MONODOMAIN

8.1 Example-0401 [PLAUSIBLE]

8.1.1 Mathematical model

We solve the Monodomain Equation

$$\sigma \Delta V_m(t) = A_m \left(C_m \frac{\partial V_m}{\partial t} + I_{\text{ionic}}(V_m) \right) \quad \Omega = [0, 1] \times [0, 1], \quad t \in [0, 3.0] \quad (133)$$

where $V_m(t)$ is given by the Hodgkin-Huxley system of ODEs [2]
with boundary conditions

$$V_m = 0 \quad x = y = 0, \quad (134)$$

$$V_m = 0 \quad x = y = 1. \quad (135)$$

and initial values

$$V_m(t = 0) = -75$$

Additionally a stimulation current I_{stim} is applied for $t_{\text{stim}} = [0, 0.1]$ at the center node of the domain (i.e. at $(x, y) = (\frac{1}{2}, \frac{1}{2},)$).

Material parameters:

$$\sigma = 3.828$$

$$A_m = 500$$

$$C_m = 0.58 \quad \text{for the slow-twitch case}, \quad C_m = 1.0 \quad \text{for the fast-twitch case}$$

$$I_{\text{stim}} = 1200 \quad \text{for the slow-twitch case}, \quad I_{\text{stim}} = 2000.0 \quad \text{for the fast-twitch case}$$

8.1.2 Computational model

- This example uses generated meshes

- Commandline arguments are:

number elements X

number elements Y

interpolation order (1: linear; 2: quadratic)

solver type (0: direct; 1: iterative)

PDE step size

stop time

output frequency

CellML Model URL

slow-twitch

ODE time-step

- Commands for tests are:

```
./folder/src/example 24 24 1 0 0.005 3.0 1 hodgkin_huxley_1952.cellml F 0.0001
./folder/src/example 24 24 1 0 0.005 3.0 1 hodgkin_huxley_1952.cellml F 0.005
./folder/src/example 10 10 1 0 0.005 3.0 1 hodgkin_huxley_1952.cellml F 0.0001
mpirun -n 2 ./folder/src/example 24 24 1 0 0.005 3.0 1 hodgkin_huxley_1952.cellml
```

```
mpirun -n 8 ./folder/src/example 24 24 1 0 0.005 3.0 1 hodgkin_huxley_1952.cellml
./folder/src/example 2 2 1 0 0.005 3.0 1 hodgkin_huxley_1952.cellml F 0.0001
mpirun -n 2 ./folder/src/example 2 2 1 0 0.005 3.0 1 hodgkin_huxley_1952.cellml F
```

- This is a dynamic problem.

8.1.3 Results

Passed tests: 0 / 0

No failed tests.

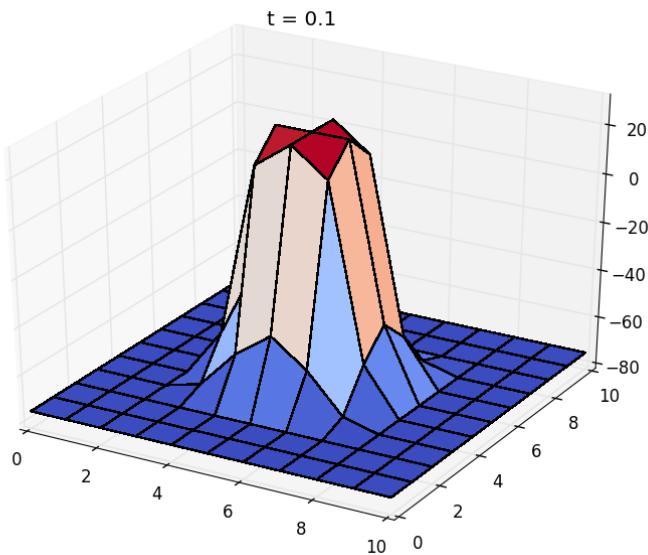


Figure 58: Result of scenario with 10×10 elements, $t = 20$, direct solver, $p = 1$ process

With the 'big' target there will be animations created. You get a better understanding of the solutions by looking at them in `iron-tests/examples/example-0401/doc/figures`.

8.1.4 Validation

We compare with a Matlab implementation as well as with reference iron files.

The matlab scripts use finite difference discretization instead of finite elements. The results are qualitatively the same but exactly. The compare script also tests for matlab reference data which is only included for the 2 examples with 24×24 elements. There is a big L_2 -error. The tolerance is set to a high value to allow for the tests to succeed. With this the comparing mechanism is tested. Maybe in the future someone succeeds to generate suitable matlab data that then can just be exchanged without having to rewrite the compare script.

The iron files to compare with are the output of the simulation as of Aug. 2017. In that way we can check if the simulation brakes with respect to the current state. In order to keep file sizes minimal the comparision is only conducted for time steps $t = 0.01, 0.1, 0.2, 1, 2, 3$ for the 'big' target and $t = 0.1, 0.2, 1$ for the 'fast' target.

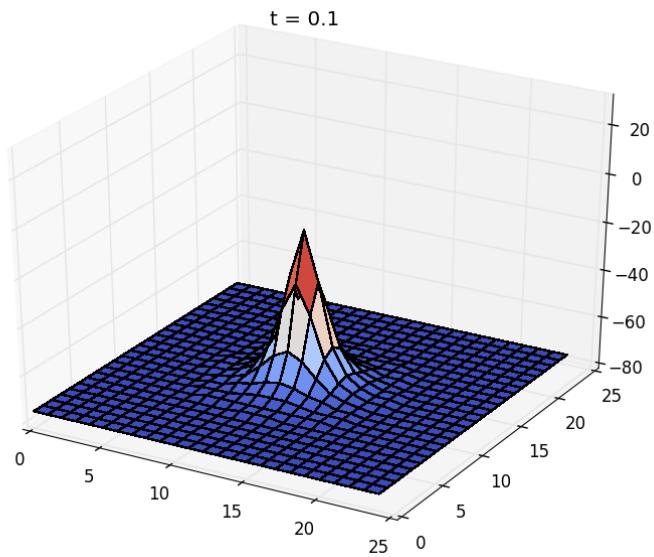


Figure 59: Result of scenario with 24×24 elements, $t = 20$, direct solver, $p = 1$ process

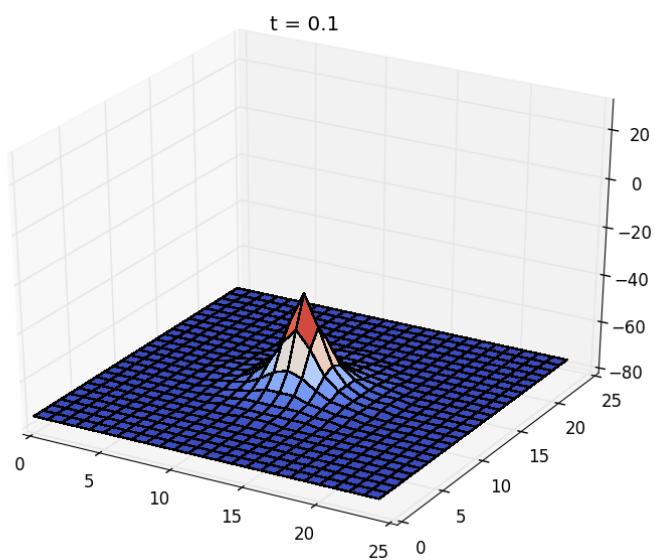


Figure 60: Result of scenario with 24×24 elements, $t = 20$, iterative solver, $p = 1$ process

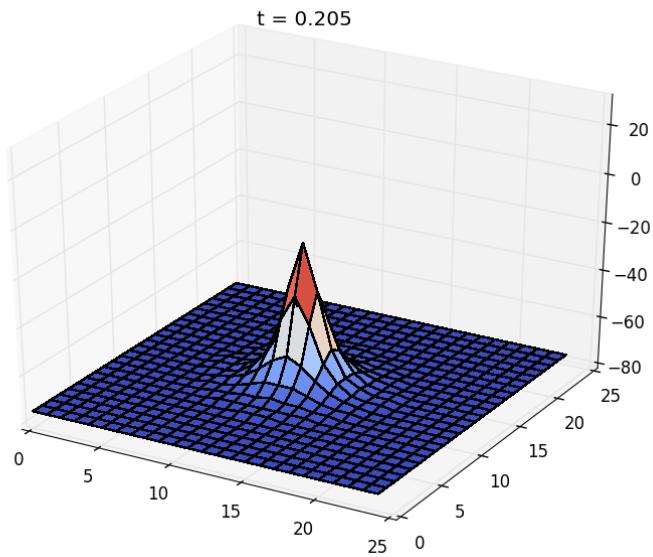


Figure 61: Result of scenario with 24×24 elements, $t = 20$, iterative solver, $p = 2$ processes

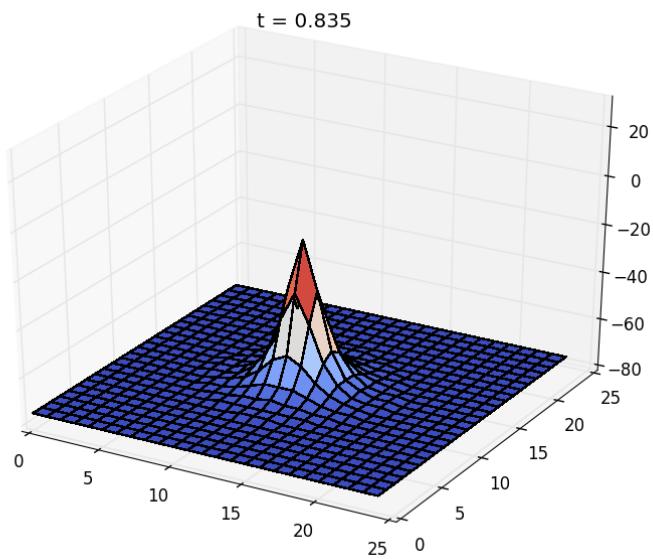


Figure 62: Result of scenario with 24×24 elements, $t = 20$, iterative solver, $p = 8$ processes

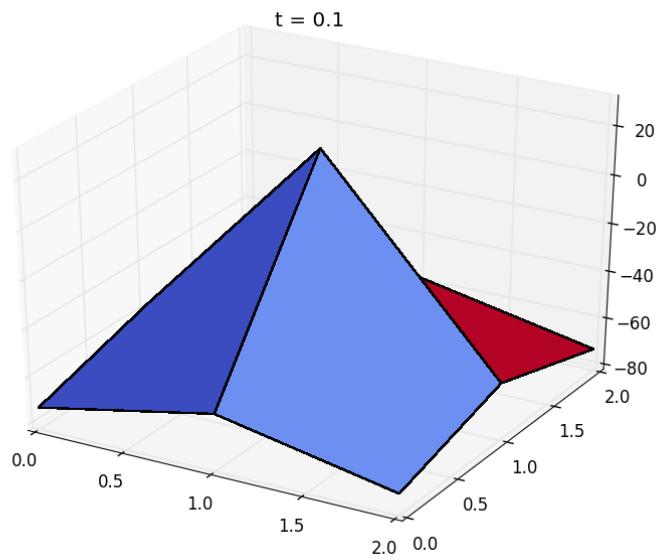


Figure 63: Result of scenario with 2×2 elements, $t = 20$, direct solver, $p = 1$ process

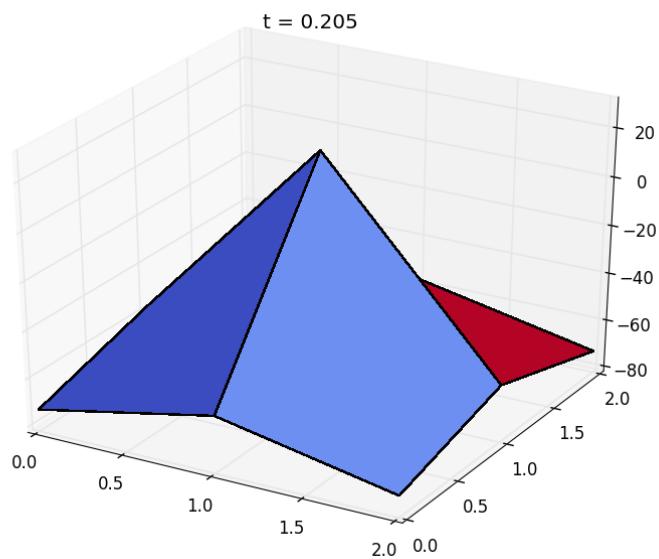


Figure 64: Result of scenario with 2×2 elements, $t = 20$, direct solver, $p = 2$ processes

8.2 Example-0402 [PLAUSIBLE]

8.2.1 Mathematical model

We solve the Monodomain Equation

$$\sigma \Delta V_m(t) = A_m \left(C_m \frac{\partial V_m}{\partial t} + I_{ionic}(V_m) \right) \quad \Omega = [0, 1] \times [0, 1], \quad t \in [0, 3.0] \quad (136)$$

where $V_m(t)$ is given by the CellML description of Noble's 1998 improved guinea-pig ventricular cell model system of ODEs [3]

with boundary conditions

$$V_m = 0 \quad x = y = 0, \quad (137)$$

$$V_m = 0 \quad x = y = 1. \quad (138)$$

and initial values

$$V_m(t = 0) = -75$$

Additionally a stimulation current I_{stim} is applied for $t_{stim} = [0, 0.1]$ at the center node of the domain (i.e. at $(x, y) = (\frac{1}{2}, \frac{1}{2})$).

Material parameters:

$$\sigma = 3.828$$

$$A_m = 500$$

$$C_m = 0.58 \quad \text{for the slow-twitch case,} \quad C_m = 1.0 \quad \text{for the fast-twitch case}$$

$$I_{stim} = 1200 \quad \text{for the slow-twitch case,} \quad I_{stim} = 2000.0 \quad \text{for the fast-twitch case}$$

8.2.2 Computational model

- This example uses generated meshes

- Commandline arguments are:

number elements X

number elements Y

interpolation order (1: linear; 2: quadratic)

solver type (0: direct; 1: iterative)

PDE step size

stop time

output frequency

CellML Model URL

slow-twitch

ODE time-step

- Commands for tests are:

`./folder/src/example 24 24 1 0 0.005 3.0 1 n98.xml F 0.0001`

`./folder/src/example 24 24 1 0 0.005 3.0 1 n98.xml F 0.005`

`./folder/src/example 10 10 1 0 0.005 3.0 1 n98.xml F 0.0001`

```

mpirun -n 2 ./folder/src/example 24 24 1 0 0.005 3.0 1 n98.xml F 0.0001
mpirun -n 8 ./folder/src/example 24 24 1 0 0.005 3.0 1 n98.xml F 0.0001
./folder/src/example 2 2 1 0 0.005 3.0 1 n98.xml F 0.0001
mpirun -n 2 ./folder/src/example 2 2 1 0 0.005 3.0 1 n98.xml F 0.0001

```

- This is a dynamic problem.

8.2.3 Results

Passed tests: 0 / 0

No failed tests.

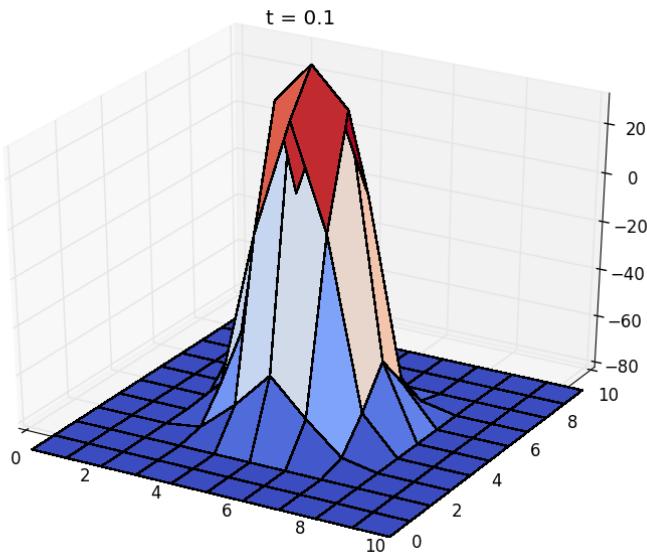


Figure 65: Result of scenario with 10×10 elements, $t = 20$, direct solver, $p = 1$ process

With the 'big' target there will be animations created. You get a better understanding of the solutions by looking at them in `iron-tests/examples/example-0402/doc/figures`.

8.2.4 Validation

We compare with reference iron files of Aug. 2017. See also the notes on `example-0401`.

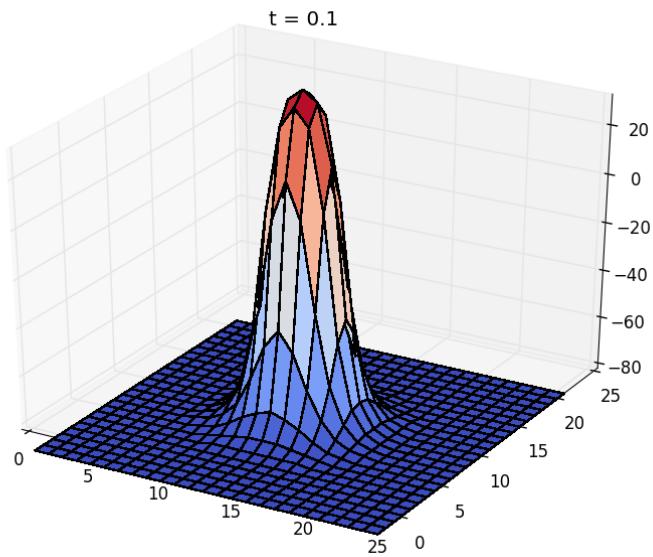


Figure 66: Result of scenario with 24×24 elements, $t = 20$, direct solver, $p = 1$ process

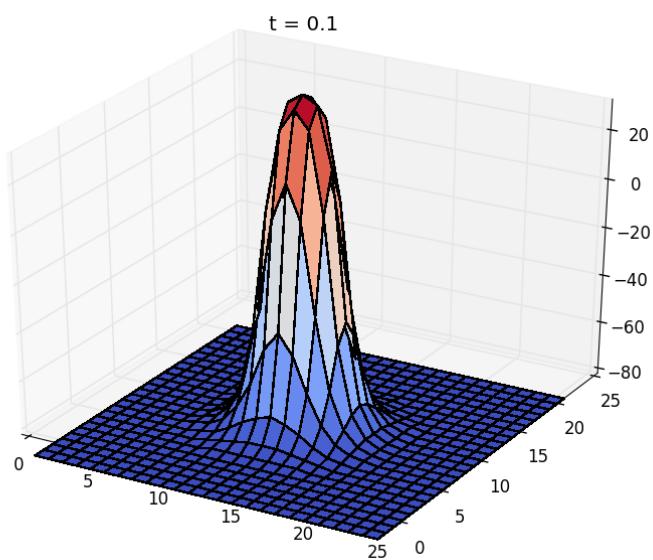


Figure 67: Result of scenario with 24×24 elements, $t = 20$, iterative solver, $p = 1$ process

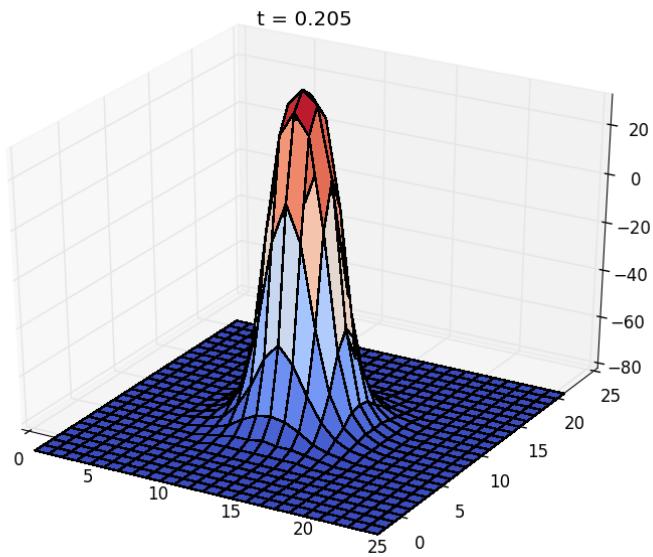


Figure 68: Result of scenario with 24×24 elements, $t = 20$, iterative solver, $p = 2$ processes

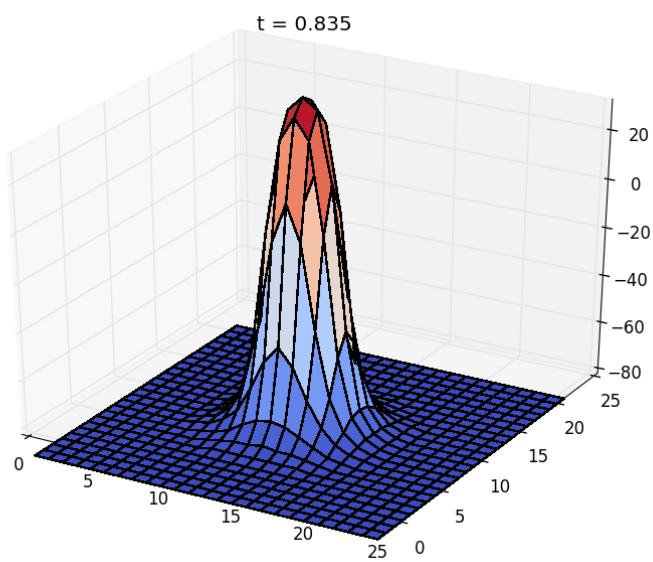


Figure 69: Result of scenario with 24×24 elements, $t = 20$, iterative solver, $p = 8$ processes

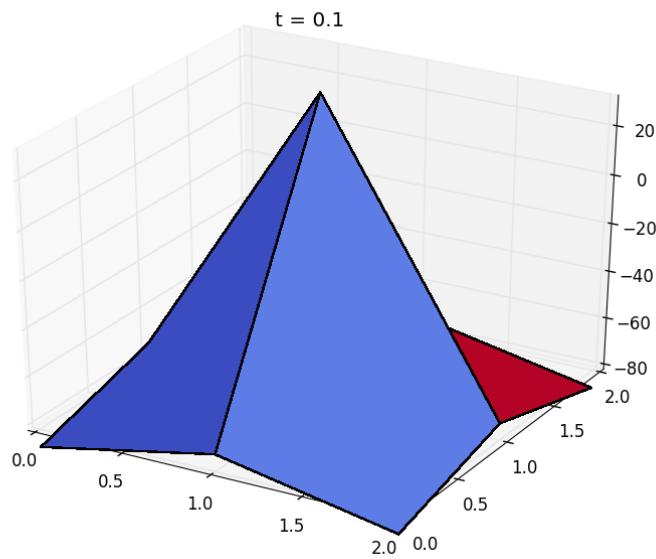


Figure 70: Result of scenario with 2×2 elements, $t = 20$, direct solver, $p = 1$ process

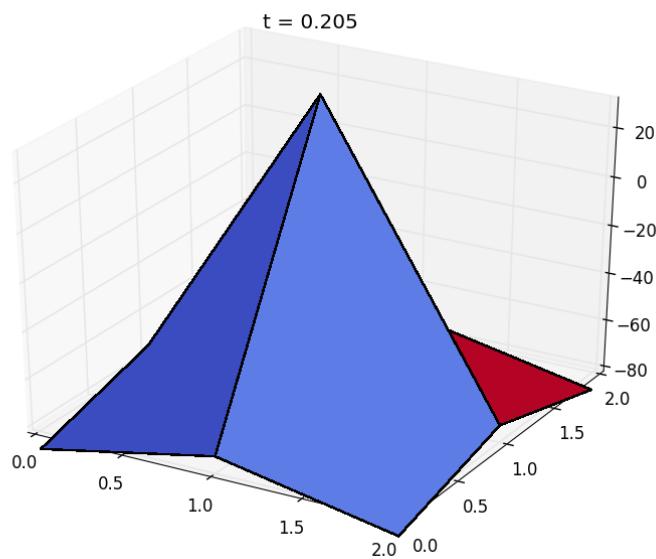


Figure 71: Result of scenario with 2×2 elements, $t = 20$, direct solver, $p = 2$ processes

8.3 Example-0404-c [PLAUSIBLE]

8.3.1 Mathematical model

We solve the Monodomain Equation

$$\sigma \Delta V_m(t) = A_m \left(C_m \frac{\partial V_m}{\partial t} + I_{ionic}(V_m) \right) \quad \Omega = [0, 1], \quad t \in [0, 10.0] \quad (139)$$

where $V_m(t)$ is given by the Hodgkin-Huxley system of ODEs [2]
with Neumann boundary conditions

$$\frac{\partial u}{\partial n} = 0 \quad x = 0, \quad (140)$$

$$\frac{\partial u}{\partial n} = 0 \quad x = 1. \quad (141)$$

and initial values

$$V_m(t = 0) = -75$$

Additionally a stimulation current I_{stim} is applied for $t_{stim} = [0, 0.5]$ at the center node of the domain (i.e. at $(x, y) = (\frac{1}{2}, \frac{1}{2},)$).

Material parameters:

$$\sigma = 3.828$$

$$A_m = 500$$

$$C_m = 0.58 \quad \text{for the slow-twitch case,} \quad C_m = 1.0 \quad \text{for the fast-twitch case}$$

$$I_{stim} = \begin{cases} 75/10 \cdot (2X) & \text{for } X \geq 10 \text{ reference elements} \\ 75 & \text{for } < 10 \text{ reference elements} \end{cases} \quad \text{for the slow-twitch case,}$$

$$I_{stim} = \begin{cases} 75/12 \cdot (2X) & \text{for } X \geq 12 \text{ reference elements} \\ 75 & \text{for } < 12 \text{ reference elements} \end{cases} \quad \text{for the fast-twitch case}$$

8.3.2 Computational model

- This example uses generated meshes

- Commandline arguments are:

number of elements

order of interpolation

solver type (0: direct; 1: iterative)

time step PDE

end time

output file stride

cellml model file

if slow-twitch (T: slow-twitch, F: fast-twitch)

time step ODE

- Commandline arguments for tests are:

64 2 0 0.01 10 5 hodgkin_huxley_1952.cellml F 0.01

64 2 0 0.005 10 10 hodgkin_huxley_1952.cellml F 0.005

```

64 2 0 0.001 10 50 hodgkin_huxley_1952.cellml F 0.001
64 2 0 0.0005 10 100 hodgkin_huxley_1952.cellml F 0.0005
64 2 0 0.00025 10 200 hodgkin_huxley_1952.cellml F 0.00025

```

- This is a dynamic problem.
- More test cases for 2nd order should be constructed.

8.3.3 Results

We run the scenario for different time step widths and examine the experimental order of convergence.

Figure 72: V_m for time $t = 1.0$, different time step widths $dt \in \{0.01, 0.005, 0.001, 0.0005, 0.00025\}$

Figure 73: Error at $t = 1.0$ for different time steps widths. The slope (=experimental order of convergence) should be around 1.

Figure 74: V_m for time $t = 3.0$, different time step widths $dt \in \{0.01, 0.005, 0.001, 0.0005, 0.00025\}$

Figure 75: Error at $t = 3.0$ for different time steps widths. The slope (=experimental order of convergence) should be around 1.

8.3.4 Validation

The purpose of this test case is to see if convergence orders are as expected, no actual validation of the output takes place.

9 CELLML MODEL

REFERENCES

- [1] Chris Bradley, Andy Bowery, Randall Britten, Vincent Budelmann, Oscar Camara, Richard Christie, Andrew Cookson, Alejandro F Frangi, Thiranja Babarenda Gamage, Thomas Heidlauf, et al. OpenCMISS: a multi-physics & multi-scale computational infrastructure for the vph-/physiome project. *Progress in biophysics and molecular biology*, 107(1):32–47, 2011.
- [2] Alan L Hodgkin and Andrew F Huxley. Propagation of electrical signals along giant nerve fibres. *Proceedings of the Royal Society of London. Series B, Biological Sciences*, pages 177–183, 1952.
- [3] Denis Noble, Anthony Varghese, Peter Kohl, and Penelope Noble. Improved guinea-pig ventricular cell model incorporating a diadic space, ikr and iks, and length-and tension-dependent processes. *Canadian Journal of Cardiology*, 14(1):123–134, 1998.