

0. Course Introduction + Bootcamps

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Outline of Lessons

- 1 Syllabus
- 2 Introduction to Probability and Statistics
- 3 The Joy of Sets Bootcamp
- 4 Calculus Bootcamp: Introduction + Derivatives
- 5 Calculus Bootcamp: Integration and Beyond

Lesson 0.1 — Syllabus

ISYE 6739 — Probability and Statistics

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Course Objectives: Provide introduction to probability and statistics, emphasizing applications in science and engineering.

Prerequisites: You should be familiar with a spreadsheet package like Excel. You should also know enough calculus to be able to integrate any easy function. But if not, don't panic — we'll have bootcamps for you!

Syllabus

- 0 Set Theory and Calculus Bootcamps
- 1 Getting Started with Probability
- 2 Random Variables
- 3 Bivariate Random Variables
- 4 Distributions
- 5 Getting Started with Statistics
- 6 Confidence Intervals
- 7 Hypothesis Testing
- 8 Other Goodies (time permitting)

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Lesson 0.2 — Introduction to Probability and Statistics

Next Few Lessons:

- This Probability and Statistics Intro
- Set Theory Bootcamp
- Calculus Bootcamps

Mathematical Models for describing observable phenomena:

- Deterministic
- Probabilistic

Deterministic Models

- Ohm's Law ($I = E/R$) (There's no place like Ohm.)
- Drop an object from height h_0 . After t seconds, height $h(t) = h_0 - 16t^2$.
- Deposit \$1000 in a checking account, continuously compounding at 3%.
At time t , it's worth $\$1000e^{0.03t}$.

Probabilistic Models — Involve uncertainty

- How much snow will fall tomorrow?
- Will IBM make a profit this year?
- Should I buy a call or put option?
- Can I win in blackjack if I use a certain strategy?
- What is the cost-effectiveness of a new drug?
- Which horse will win the Kentucky Derby?

Some Cool Examples

- Birthday Problem — Assume all 365 days have equal probability of being a person's birthday (ignore freaks born on Feb. 29). Then...

If there are **23** students in a class, the odds are better than 50–50 that there will be a match.

If there are **50** students, the probability is about 97%!

- Monopoly — In the long run, the property having the highest probability of being landed on is Illinois Ave.
- Stock Market — Monkeys randomly selecting stocks could have outperformed most market analysts during the past year.

- Poker — Pick 5 cards from a standard deck. Then

$$P(\text{exactly 2 pairs}) \approx 0.0475,$$

$$P(\text{full house}) \approx 0.00144,$$

$$P(\text{flush}) \approx 0.00198.$$

- A couple has two kids and at least one is a boy. What's the probability that BOTH are boys?

Possibilities: GG, BG, GB, BB. Eliminate GG since we know that there's at least one boy. Then $P(BB) = 1/3$.

- Ask Marilyn. You are a contestant at a game show. Behind one of three doors is a car; behind the other two are goats. You pick door A. Monty Hall opens door B and reveals a goat. Monty offers you a chance to switch to door C. What should you do? Answer: SWITCH!

- Vietnam Draft Lottery — not as “fair” as you might think!
- Which is the most popular soft drink? Well, in Atlanta, we know the answer to that one!
- Why are some election polls so incredibly wrong?
- How do they do real-time updates of win probabilities as a basketball game progresses?
- How can you simulate randomness on a computer, and what can you use it for?
- How can you tell if the quality of an item that your manufacturing plant is producing has started to get worse?

Working Definitions

Probability — Methodology that describes the random variation in systems.
(We'll spend about 50% of our time on this.)

Statistics — Uses sample data to draw general conclusions about the population from which the sample was taken. (50% of our time.)

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Lesson 0.3 — The Joy of Sets Bootcamp

Definition: A **set** is a collection of objects. Members of a set are called **elements**.

Notation:

A, B, C, \dots for sets

a, b, c, \dots for elements

\in for membership, e.g., $x \in A$

\notin for non-membership, e.g., $x \notin A$

U is the **universal set** (i.e., everything)

\emptyset is the **empty set**.

Examples:

$$A = \{1, 2, \dots, 10\}. \quad 2 \in A; 49 \notin A.$$

$$B = \{\text{basketball}, \text{baseball}\}$$

$$C = \{x \mid 0 \leq x \leq 1\} \text{ (“} \mid \text{” means “such that”)}$$

$$D = \{x \mid x^2 = 9\} = \{\pm 3\} \text{ (either is fine)}$$

$$E = \{x \mid x \in \mathbb{R}, x^2 = -1\} = \emptyset \text{ (}\mathbb{R} \text{ is the real line)}$$

Definition: If every element of set A is an element of set B then A is a **subset** of B , i.e., $A \subseteq B$.

Definition: $A = B$ iff (if and only if) $A \subseteq B$ and $B \subseteq A$.

Properties:

$$\emptyset \subseteq A; A \subseteq U; A \subseteq A$$

$$(A \subseteq B \text{ and } B \subseteq C) \Rightarrow (\text{implies}) A \subseteq C$$

Remark: The order in which the elements of a set are listed is immaterial, e.g., $\{a, b, c\} = \{b, c, a\}$.

Definitions: The **complement** of A with respect to U is

$$\bar{A} \equiv \{x \mid x \in U \text{ and } x \notin A\}.$$

Remark: Don't confuse complement with compliment! (“You are one fine-lookin’ set!”)

The **intersection** of A and B is $A \cap B \equiv \{x \mid x \in A \text{ and } x \in B\}$.

The **union** of A and B is $A \cup B \equiv \{x \mid x \in A \text{ or } x \in B \text{ (or both)}\}$.

(Remember **Venn diagrams**?)

Example:

Suppose $U = \{\text{letters of the alphabet}\}$, $A = \{\text{vowels}\}^*$, and $B = \{a, b, c\}$.

*We'll ignore the fact that y and w are sometimes vowels (believe it or not)!

Then

$$\bar{A} = \{\text{consonants}\}$$

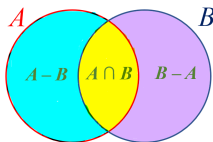
$$A \cap B = \{a\}$$

$$A \cup B = \{a, b, c, e, i, o, u\}. \quad \square$$

Definition: If $A \cap B = \emptyset$, then A and B are **disjoint** (or **mutually exclusive**).

More Definitions:

Minus: $A - B \equiv A \cap \bar{B}$



Symmetric difference or **XOR**:

$$A \Delta B \equiv (A - B) \cup (B - A) = (A \cup B) - (A \cap B)$$

The **cardinality** of A , denoted by $|A|$, is the number of elements in A . A is **finite** if $|A| < \infty$.

Examples:

$A = \{3, 4\}$ is finite, since $|A| = 2$.

$B = \{1, 2, 3, \dots\}$ is **countably infinite**, i.e., $|B| = \aleph_0$ (look up this symbol)!

$C = \{x \mid x \in [0, 1]\}$ is **uncountably infinite**, i.e., $|C| = \aleph_1$ (look it up)!

Laws of Operation:

1. **Complement Law:** $A \cup \bar{A} = U$, $A \cap \bar{A} = \emptyset$, $\bar{\bar{A}} = A$
2. **Commutative:** $A \cup B = B \cup A$, $A \cap B = B \cap A$
3. **Associative:** $A \cup (B \cup C) = (A \cup B) \cup C$,
 $A \cap (B \cap C) = (A \cap B) \cap C$
4. **Distributive:** $A \cup (B \cap C) = (A \cup B) \cap (A \cup C)$,
 $A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$
5. **DeMorgan's:** $\overline{A \cup B} = \bar{A} \cap \bar{B}$, $\overline{A \cap B} = \bar{A} \cup \bar{B}$

Proofs: Easy. Could use Venn diagrams or many other ways.

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Lesson 0.4 — Calculus Bootcamp: Introduction + Derivatives

Definition: The **function** $f(x)$ maps values of x from a certain **domain** X to a certain **range** Y , which we can denote by the shorthand $f : X \rightarrow Y$.

Example: If $f(x) = x^2$, then the function takes x -values from the real line \mathbb{R} to the nonnegative portion of the real line \mathbb{R}^+ .

Definition: We say that $f(x)$ is a **continuous** function if, for any x_0 and $x \in X$, we have $\lim_{x \rightarrow x_0} f(x) = f(x_0)$, where “lim” denotes a **limit** and $f(x)$ is assumed to exist for all $x \in X$.

Example: The function $f(x) = 3x^2$ is continuous for all x . The function $f(x) = \lfloor x \rfloor$ (round down to the nearest integer, e.g., $\lfloor 3.4 \rfloor = 3$) has a “jump” discontinuity at any integer x . \square

Definition: The **inverse** of a function $f : X \rightarrow Y$ is (informally) the “reverse” mapping $g : Y \rightarrow X$ such that $f(x) = y$ if and only if $g(y) = x$ for all appropriate x and y . The inverse of f is often written as f^{-1} , and is especially useful if $f(x)$ is a strictly increasing or strictly decreasing function. Note that $f^{-1}(f(x)) = x$.

Examples: If $f(x) = x^3$, then we have $f^{-1}(y) = y^{1/3}$. If $h(x) = e^x$, then $h^{-1}(y) = \ln(y)$. \square

Definition: If $f(x)$ is continuous, then it is **differentiable** (has a **derivative**) if

$$\frac{d}{dx}f(x) \equiv f'(x) \equiv \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$

exists and is well-defined for any given x . Think of the derivative as the slope of the function.

Examples: Some well-known derivatives are:

$$[x^k]' = kx^{k-1},$$

$$[c^x]' = c^x \ln(c), \text{ and so } [e^x]' = e^x \text{ (since } \ln(e) = 1),$$

$$[\sin(x)]' = \cos(x),$$

$$[\cos(x)]' = -\sin(x),$$

$$[\ln(x)]' = \frac{1}{x},$$

$$[\arctan(x)]' = \frac{1}{1+x^2}. \quad \square$$

Theorem: Some well-known properties of derivatives are:

$$[af(x) + b]' = af'(x),$$

$$[f(x) + g(x)]' = f'(x) + g'(x),$$

$$[f(x)g(x)]' = f'(x)g(x) + f(x)g'(x) \quad (\text{product rule}),$$

$$\left[\frac{f(x)}{g(x)} \right]' = \frac{g(x)f'(x) - f(x)g'(x)}{g^2(x)} \quad (\text{quotient rule})^1,$$

$$[f(g(x))]' = f'(g(x))g'(x) \quad (\text{chain rule})^2.$$

¹Ho dee Hi minus Hi dee Ho over Ho Ho.

²www.youtube.com/watch?v=gGAiW5dOnKo

Example: Suppose that $f(x) = x^2$ and $g(x) = \ln(x)$. Then

$$\begin{aligned}[f(x)g(x)]' &= f'(x)g(x) + f(x)g'(x) \\ &= 2x\ln(x) + x(1/x) \\ &= 2x\ln(x) + x,\end{aligned}$$

$$\begin{aligned}\left[\frac{f(x)}{g(x)}\right]' &= \frac{g(x)f'(x) - f(x)g'(x)}{g^2(x)} \\ &= \frac{[\ln(x)]2x - x^2(1/x)}{\ln^2(x)} \\ &= \frac{2x\ln(x) - x}{\ln^2(x)},\end{aligned}$$

$$[f(g(x))]' = [(g(x))^2]' = 2g(x)g'(x) = \frac{2\ln(x)}{x}. \quad \square$$

Remark: The second derivative $f''(x) \equiv \frac{d}{dx} f'(x)$ and is the “slope of the slope.” If $f(x)$ is “position,” then $f'(x)$ can be regarded as “velocity,” and $f''(x)$ as “acceleration.”

The minimum or maximum of $f(x)$ can only occur when the slope of $f(x)$ is zero, i.e., only when $f'(x) = 0$, say at the **critical point** $x = x_0$. Exception: Check the endpoints of your interval of interest as well.

Then if $f''(x_0) < 0$, you get a max; if $f''(x_0) > 0$, you get a min; and if $f''(x_0) = 0$, you get a **point of inflection**.

Example: Find the value of x that minimizes $f(x) = e^{2x} + e^{-x}$. The minimum can only occur when $f'(x) = 2e^{2x} - e^{-x} = 0$. After a little algebra, we find that this occurs at $x_0 = -(1/3)\ln(2) \approx -0.231$. It's also easy to show that $f''(x) > 0$ for all x ; and so x_0 yields a minimum. \square

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Lesson 0.5 — Calculus Bootcamp: Integration and Beyond

Integration

Definition: The function $F(x)$ having derivative $f(x)$ is called the **antiderivative** (or **indefinite integral**). It is denoted by

$$F(x) = \int f(x) dx.$$

Fundamental Theorem of Calculus: If $f(x)$ is continuous, then the area under the curve for $x \in [a, b]$ is denoted and given by the **definite integral**³

$$\int_a^b f(x) dx \equiv F(x) \Big|_a^b \equiv F(b) - F(a).$$

³“I’m *really* an integral!”

Example: Some well-known indefinite integrals are:

$$\int x^k dx = \frac{x^{k+1}}{k+1} + C \quad \text{for } k \neq -1,$$

where C is an arbitrary constant,

$$\int \frac{dx}{x} = \ln|x| + C,$$

$$\int e^x dx = e^x + C,$$

$$\int \cos(x) dx = \sin(x) + C,$$

$$\int \frac{dx}{1+x^2} = \arctan(x) + C. \quad \square$$

Example: It is easy to see that

$$\begin{aligned}\int \frac{d \text{cabin}}{\text{cabin}} &= \ln|\text{cabin}| + C \quad \text{😊} \\ &= \text{houseboat.} \quad \text{😊}\end{aligned}$$

Theorem: Some well-known properties of definite integrals are:

$$\int_a^a f(x) dx = 0,$$

$$\int_a^b f(x) dx = - \int_b^a f(x) dx,$$

$$\int_a^b f(x) dx = \int_a^c f(x) dx + \int_c^b f(x) dx.$$

Theorem: Some other properties of general integrals are:

$$\int [f(x) + g(x)] dx = \int f(x) dx + \int g(x) dx,$$

$$\int f(x)g'(x) dx = f(x)g(x) - \int g(x)f'(x) dx \quad (\text{integration by parts})^4,$$

$$\int f(g(x))g'(x) dx = \int f(u) du \quad (\text{substitution rule with } u = g(x))^5.$$

⁴www.youtube.com/watch?v=OTzLVlc-O5E

⁵www.youtube.com/watch?v=eswQl-hcvU0

Example: To demonstrate integration by parts on a definite integral, let $f(x) = x$ and $g'(x) = e^{2x}$, so that $g(x) = e^{2x}/2$. Then

$$\begin{aligned}\int_0^1 x e^{2x} dx &= \int_0^1 f(x) g'(x) dx \\&= f(x) g(x) \Big|_0^1 - \int_0^1 g(x) f'(x) dx \quad (\text{parts}) \\&= \frac{x e^{2x}}{2} \Big|_0^1 - \int_0^1 \frac{e^{2x}}{2} dx \\&= \frac{e^2}{2} - \frac{e^{2x}}{4} \Big|_0^1 \\&= \frac{e^2 + 1}{4}. \quad \square\end{aligned}$$

Definition: Derivatives of arbitrary order k can be written as $f^{(k)}(x)$ or $\frac{d^k}{dx^k} f(x)$. By convention, $f^{(0)}(x) = f(x)$.

The **Taylor series expansion** of $f(x)$ about a point a is given by

$$f(x) = \sum_{k=0}^{\infty} \frac{f^{(k)}(a)(x-a)^k}{k!}.$$

The **Maclaurin series** is simply Taylor expanded around $a = 0$.

Example: Here are some famous Maclaurin series:

$$\sin(x) = \sum_{k=0}^{\infty} \frac{(-1)^k x^{2k+1}}{(2k+1)!},$$

$$\cos(x) = \sum_{k=0}^{\infty} \frac{(-1)^k x^{2k}}{(2k)!},$$

$$e^x = \sum_{k=0}^{\infty} \frac{x^k}{k!}.$$

Example: And while we're at it, here are some miscellaneous sums that you should know:

$$\sum_{k=1}^n k = \frac{n(n+1)}{2},$$

$$\sum_{k=1}^n k^2 = \frac{n(n+1)(2n+1)}{6},$$

$$\sum_{k=0}^{\infty} p^k = \frac{1}{1-p} \quad (\text{for } -1 < p < 1).$$

Theorem: Occasionally, we run into trouble when taking indeterminate ratios of the form $0/0$ or ∞/∞ . In such cases, **L'Hôpital's Rule**⁶ is useful: If the limits $\lim_{x \rightarrow a} f(x)$ and $\lim_{x \rightarrow a} g(x)$ both go to 0 or both go to ∞ , then

$$\lim_{x \rightarrow a} \frac{f(x)}{g(x)} = \lim_{x \rightarrow a} \frac{f'(x)}{g'(x)}.$$

Example: L'Hôpital shows that

$$\lim_{x \rightarrow 0} \frac{\sin(x)}{x} = \lim_{x \rightarrow 0} \frac{\cos(x)}{1} = 1. \quad \square$$

⁶This rule makes me sick.

Double Integration

We'll have occasion to calculate several double integrals. Whereas our usual (single) integrals get us the area under a curve, double integrals represent the *volume* under a three-dimensional function.

Example: The volume under $f(x, y) = 8xy$ over the region $0 < x < y < 1$ is given by

$$\int_0^1 \int_0^y f(x, y) dx dy = \int_0^1 \int_0^y 8xy dx dy = \int_0^1 4y^3 dy = 1. \quad \square$$

We can usually swap the order of integration to get the same answer:

$$\int_0^1 \int_x^1 8xy dy dx = \int_0^1 4x(1 - x^2) dx = 1. \quad \square$$

Saved by Zero! (How to Solve for a Root)

Suppose that we want to solve some equation $g(r) = 0$ for a root r^* , where $g(r)$ is a nicely behaved continuous function.

We can use:

- trial-and-error or some sort of linear search — that's for losers! 😞
- **bisection method** — pretty fast! 😊
- **Newton's method** — really fast! 😄

Intermediate Value Theorem (IVT): If $g(\ell)g(u) < 0$, then there is a zero $r^* \in [\ell, u]$. In other words, if (i) $g(\ell) < 0$ and $g(u) > 0$ or (ii) $g(\ell) > 0$ and $g(u) < 0$, then $g(r)$ crosses 0 somewhere between ℓ and u .

Bisection uses the IVT to hone in on a zero via sequential bisecting:

- Initialization: Find lower and upper bounds $\ell_0 < u_0$ such that $g(\ell_0)g(u_0) < 0$. Then the IVT implies that $r^* \in [\ell_0, u_0]$.
- For $i = 1, 2, \dots$,
 - Let the midpoint of the current interval be $r_{i+1} \leftarrow (\ell_i + u_i)/2$.
 - If $g(r_{i+1})$ is sufficiently close to 0, or the interval width $u_i - \ell_i$ is sufficiently small, or your iteration budget is exceeded, then set $r^* \leftarrow r_{i+1}$ and STOP.
 - If the sign of $g(r_{i+1})$ matches that of $g(\ell_i)$, this means that $r^* \in [r_{i+1}, u_i]$; so set $\ell_{i+1} \leftarrow r_{i+1}$ and $u_{i+1} \leftarrow u_i$. Otherwise, $r^* \in [\ell_i, r_{i+1}]$; so set $\ell_{i+1} \leftarrow \ell_i$ and $u_{i+1} \leftarrow r_{i+1}$.

Each iteration of the algorithm chops the search area in two and therefore converges to r^* pretty quickly.

Example: Use bisection to find $\sqrt{2}$ by solving $g(x) = x^2 - 2 = 0$.

In order to initialize the bisection algorithm, we note that $g(1) = -1$ and $g(2) = 2$. So there's a zero in $[1, 2]$ just itching to be found!

step	ℓ_i	$g(\ell_i)$	u_i	$g(u_i)$	r_{i+1}	$g(r_{i+1})$
0	1	-1	2	2	1.5	0.25
1	1	-1	1.5	0.25	1.25	-0.4375
2	1.25	-0.4375	1.5	0.25	1.375	-0.1094
3	1.375	-0.1094	1.5	0.25	1.4375	0.0664
4	1.375	-0.1094	1.4375	0.0664	1.40625	-0.0225
\vdots						

You can see that r_{i+1} seems to be converging to $\sqrt{2} \doteq 1.4142$. \square

Newton's method. It's usually a lot faster than bisection. Here's a reasonable implementation.

- ➊ Initialize r_0 as some first guess of the root. Set $j \leftarrow 0$.
- ➋ Update $r_{j+1} \leftarrow r_j - g(r_j)/g'(r_j)$.
- ➌ If $|g(r_{j+1})|$ or $|r_{j+1} - r_j|$ or your budget is suitably small, then STOP and set $r^* \leftarrow r_{j+1}$. Otherwise, let $j \leftarrow j + 1$ and goto Step 2.

Example: Use Newton to find $\sqrt{2}$ by solving $g(x) = x^2 - 2 = 0$.

To do so, note that

$$r_{j+1} \leftarrow r_j - \frac{g(r_j)}{g'(r_j)} = r_{j+1} \leftarrow r_j - \frac{r_j^2 - 2}{2r_j} = \frac{r_j^2 + 2}{2r_j}.$$

If $r_0 = 1$, then we find that $r_1 = 3/2$, $r_2 = 17/12 \doteq 1.4167$,
 $r_3 = 577/408 \doteq 1.4142, \dots$ Wow, that's fast convergence! 😊