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## 1 Week 3 Module 3: Part 1 - Basics of Fourier Analysis

### 1.1 Introduction to Fourier Analysis

#### 1.1.1 Sustainable dynamic systems exhibit oscillatory behavior

- A train has got an engine which makes the wheels turn in circular motion
- Waves, ebb and flow can be modeled as sinusoidal fashion
- Musical instruments generates sound by vibrating at a certain fundamental frequency
- Intuitivly: things that don't move in circles can't last
  - bombs

- rockets
- human beings

### 1.1.2 Descriptin of the oscillations in the plane

**Period**  $P$

**Frequency**  $f = \frac{1}{P}$

**Ordinate**  $\sin(ft)$

**Abscissa**  $\cos(ft)$

### 1.1.3 Example Sinusoidal Detectors in our Body:

**cochlea** In the inner ear that detects air pressure sinusoids at frequencies from 20 to 20kHz

**retina** In the eye to detect electromagnetic sinusoids with frequency 430THz to 790THz. This is the frequency of lights in the visible spectrum

Humans anlayze complex signals (audio, images) in terms of their sinusoidal components

Frequency Domain semms to be as good a the time domain

### 1.1.4 Fundamental Questions: Can we decompse any signal into sinusoidal elements?

- Yes, Fourier showed us how to do it exactly
- Analysis
  - From time domain to frequency domain
  - Find the contribution of different frequencies
  - Discover "hidden" signal properties
- Synthesis
  - From frequency domain to time domain
  - Create signals with known frequency content
  - Fit signals to specific frequency regions

## 1.2 The Discrete Fourier Transform (DFT)

### 1.2.1 The DFT as a change of basis

### 1.2.2 The Fourier Basis for $\mathbb{C}^N$ in "Signal" Notation

$$w_k[n] = e^{j\frac{2\pi}{N}nk} \text{ with } n, k = 0, 1, \dots, N-1 \quad (1)$$

### 1.2.3 The Fourier Basis in Vector Notation

$$\{\mathbf{w}^{(k)}\}_{k=0,1,\dots,N-1} \text{ with } w_n^{(k)} = e^{j\frac{2\pi}{N}nk}, n = 0, 1, \dots, N-1 \quad (2)$$

$N$  Dimension of vector space

$k$  Index for different vectors and goes from 0..N-1

$n$  Index of element in each vector goes from 0..N-1

### 1.2.4 Definition of the DFT

#### Basis Expansion Vector Notation

##### Analysis Formula

$$X_k = \langle \mathbf{w}^{(k)}, \mathbf{x} \rangle \quad k = 0, \dots, N-1 \quad (3)$$

$X_k$  Coefficient for the new basis. Inner Product of  $\mathbf{x}$  with each vector  $\mathbf{w}^{(k)}$

$\mathbf{x}$  An arbitrary vector of  $\mathbb{C}^N$

$\mathbf{w}^{(k)}$  New basis

##### Synthesis Formula

$$\mathbf{x} = \frac{1}{N} \sum_{k=0}^{N-1} X_k \mathbf{w}^{(k)} \quad k = 0, \dots, N-1 \quad (4)$$

## TODO Basis Expansion Matrix Form

### Basis Expansion Signal Notation

- Consider explicitly the operations involved in the transformation
- This notion is particularly useful if you want to consider the algorithmic nature of the transform

### Analysis Formula N-point signal in the frequency domain

$$X[k] = \sum_{n=0}^{N-1} x[n] e^{-j \frac{2\pi}{N} nk}, k = 0, 1, \dots, N-1$$

$X[k]$  Signal vector in the frequency domain

$x[n]$  Signal vector in the (discrete) time domain

**Reminder** This is the inner Product in explicit form

### Synthesis Formula N-point signal in the time domain

$$x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j \frac{2\pi}{N} nk}, k = 0, 1, \dots, N-1$$

$X[k]$  Signal vector in the frequency domain

$\frac{1}{N}$  Normalisation coefficient

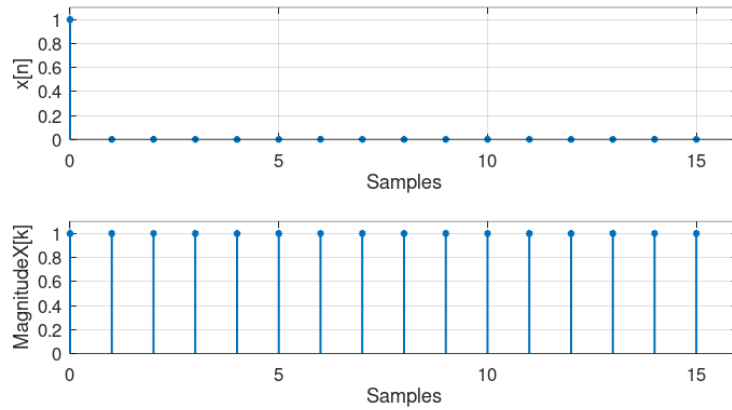
**Reminder** This is the inner Product in explicit fashion

### 1.2.5 Examples

#### DFT of the impulse function

$$x[n] = \delta[n]$$

$$X[k] = \sum_{n=0}^{N-1} \delta[n] e^{-j\frac{2\pi}{N}nk} = 1$$

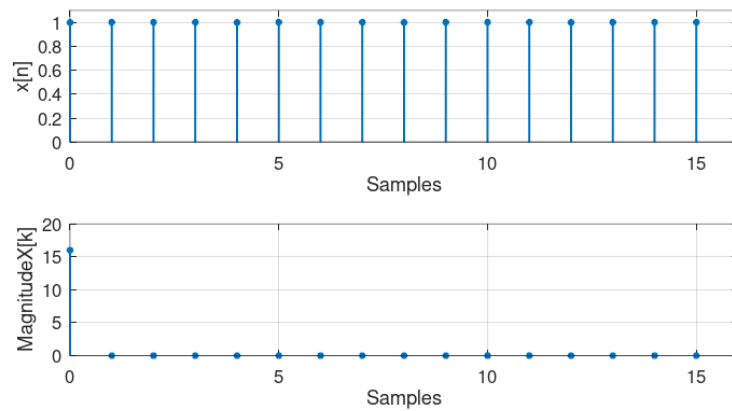


- The delata contains all frequencies over the range of all possible frequencies

### DFT of the unit step

$$x[n] = 1$$

$$X[k] = \sum_{n=0}^{N-1} e^{-j\frac{2\pi}{N}nk} = N\delta[k]$$



### DFT Cosine Calculation Problem 1

$$x[n] = 3 \cos(2\pi/16 \times n), \quad x[n] = \mathbb{C}^{64}$$

1. Determine dimension and fundamental frequency of the signal

- Dimension of space  $N = 64$
- Fundamental frequency  $\omega = \frac{2\pi}{N} = \frac{2\pi}{64}$   
All frequencies in the fourier basis will be a multiple of the fundamental frequency  $\omega$ . With this in mind we can start by expressing our sinuoid as a multiple of the fundamental frequency in space  $\mathbb{C}^{64}$ .

2. Express the signal as a multiple of the fundamental frequency in space.

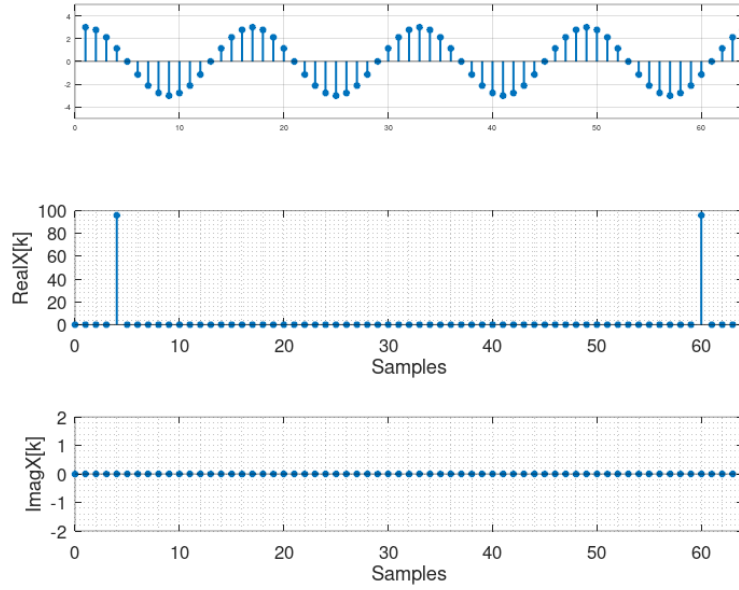
$$\begin{aligned} X[n] &= 3 \cos\left(\frac{2\pi}{16}n\right) \\ &= 3 \cos\left(\frac{2\pi}{64}4n\right) \\ &= \frac{3}{2} \left[ e^{j\frac{2\pi}{64}4n} + e^{-j\frac{2\pi}{64}4n} \right], \text{ with Euler: } \cos(\omega) = \frac{e^{j\omega} + e^{-j\omega}}{2} \\ &= \frac{3}{2} \left[ e^{j\frac{2\pi}{64}4n} + e^{j\frac{2\pi}{64}60n} \right], \text{ with: } j\frac{2\pi}{64}60n = -j\frac{2\pi}{64}4n + j2\pi n \\ &= \frac{3}{2} \langle w_4[n] + w_{60}[n] \rangle \end{aligned}$$

- $w_4[n]$  Basis vector number 4
- $w_{60}[n]$  Basis vector number 60  
Now we don't like this minus. So what we're going to do is exploit the fact that we can always add an integer multiple of  $2\pi$  to the exponent of the complex exponential. And the point will not change on the complex plane.
- **The original signal is now expressed as the sum of two fourier basis vectors**

3. Calculate the DFT with the analysis formula

$$\begin{aligned} X[k] &= \langle w_k[n], x[n] \rangle, \text{ with: } k = 0, 1, \dots, N-1 \\ &= \begin{cases} 96 & \text{for } k = 4, 60 \\ 0 & \text{otherwise} \end{cases} \end{aligned}$$

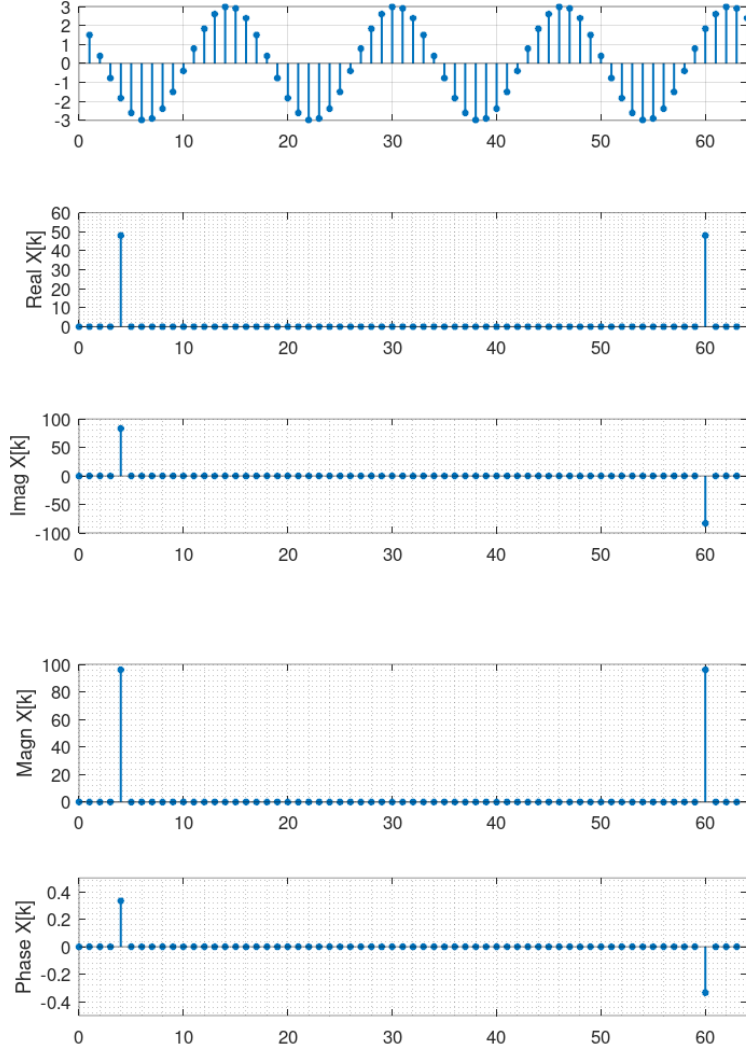
- $w_k[n]$  Canonical basis vector number k



## DFT Cosine Calculation Problem 2

$$x[n] = 3 \cos(2\pi/16 n + \pi/3), x[n] \in \mathbb{C}^{64}$$

$$X[k] = \begin{cases} 96e^{j\frac{\pi}{3}} & \text{for } k = 4 \\ 96e^{-j\frac{\pi}{3}} & \text{for } k = 96 \\ 0 & \text{otherwise} \end{cases}$$



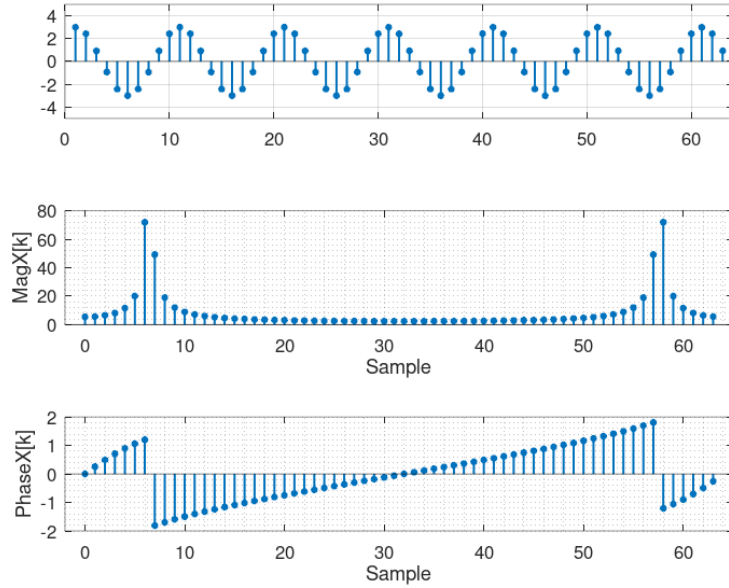
The calculation of the phase just does not work out of the box with octave.

### DFT Cosine Calculation Problem 3

$$x[n] = 3 \cos(2\pi/10 n), x[n] \in \mathbb{C}^{64}$$

$$X[k] = \begin{cases} 96e^{j\frac{\pi}{3}} & \text{for } k = 4 \\ 96e^{-j\frac{\pi}{3}} & \text{for } k = 96 \\ 0 & \text{otherwise} \end{cases}$$





### 1.2.6 Properties of the DFT

**Linearity**  $DFT\alpha x[n] + \beta y[n] = DFT\alpha x[n] + DFT\beta y[n]$

### 1.2.7 Interpreting a DFT Plot

- Frequency coefficient  $< \pi[0 \dots N/2]$  are interpreted as counter clock wise rotation in the plane
- Frequency coefficient  $> \pi[N/2 \dots N-1]$  are interpreted as clock wise rotation in the plane
- The fastest frequency of the signal in the vector space is at  $N/2$



#### Energy of a Signal



The square magnitude of the  $k$ -th DFT coefficient is proportional to the signal's energy at frequency  $\omega = (\frac{2\pi}{N})k$

- Energy concentrated on single frequency (counterclockwise and clockwise combine to give real signal)

$$x1[n] = 3 \cos(2 \pi / 16 n), x[n] \in \mathbb{C}^{64}$$

$$x1[n] = u[n] - u[n - 4]$$

- For real signals the DFT is **symmetric** in magnitude
  - $|X[k]| = |X[N - k]|$ , for  $k = 1, 2, \dots [N/2]$
  - For real signals, magnitude plots need only  $[N/2] + 1$  points

### 1.2.8 DFT Analysis

#### Daily Temperature (2920 days)

- The recorded signal

#### TODO Add daily temp image

- average value (0-th DFT coefficient:  $12.3^\circ$ )
- DFT main peak for  $k = 8$ , value  $6.4^\circ\text{C}$
- 8 cycles over 2920 days
- $period = \frac{2920}{8} = 365 \text{ days}$
- temperature excursion:  $12.3^\circ \pm 12.8^\circ\text{C}$

The fastest positive frequency of a signal is at  $\frac{N}{2}$  samples. Since a full revolution of  $2\pi$  requires  $N$  samples, the discrete frequency corresponding with  $\frac{N}{2}$  is  $\pi$ .

#### Labeling Frequency Band Axis

- If "clock" of a System is  $T_s$ 
  - fastest (positive) frequency is  $\omega = \pi$
  - sinusoid at  $\omega = \pi$  needs two samples to do a full revolution
  - time between samples:  $T_s = \frac{1}{F_s}$  seconds
  - real world period for fastest sinusoid:  $2T_s$  seconds

– real world frequency for fastest sinusoid:  $F_s/2$  Hz

- The discrete frequency  $x$  of a sinusoid component at peak  $k$  can be determined as follows:

$$\frac{x}{k} = \frac{N}{2\pi}, \text{ with } k=0\dots N-1 \quad (5)$$

- The real world frequency of a sinusoid component at peak  $k$  can be determined as follows:

$$\begin{aligned} \frac{x}{k} &= \frac{2\pi}{N}, \text{ with } k=0\dots N-1 \\ \frac{f_s}{2} &\rightarrow \pi, f_s \text{ sampling frequency} \\ \frac{x}{k} &= \frac{f_s}{N} \\ x &= \frac{k f_s}{N} \end{aligned}$$

**Example 1** A DFT analysis of a signal with length  $N = 4000$  samples at a frequency  $f_s = 44.1kHz$  shows a peak at  $k = 500$ . What is the corresponding frequency in Hz of this digital frequency in Hz.

- Solution

$$\begin{aligned} \frac{x}{k} &= \frac{2\pi}{N} \\ x &\rightarrow \frac{2\pi k}{N} \\ \frac{f_s}{2} &\rightarrow \pi \\ x &= \frac{k}{N} f_s = 55125.5 \end{aligned}$$

**Example 2** Calculation of the corresponding frequency vector for a signal for which its spectrum is analysed with the fourier transform

- Sampling Period:  $T_s = 1/1000s$
- Sampling Frequency:  $f_s = 1/T = 1000Hz$

- Vector Length  $N = 2^{10} = 1024$

$$\frac{X}{k} = \sum_{n=1}^N x[n] e^{-j2\pi(k-1)(\frac{n-1}{N})}$$

$$f(k) = \frac{k-1}{NT}, \text{ corresponding Frequency in Hz}$$

- StackOverflow

```
clear all;
close all;
N = 1024;    # vector length
Fs = 1000;   # Sample Frequency Fs = 1000Hz
Ts = 1/Fs;   # Sampling Period Ts = 0.001s
f1 = 60;     # 50Hz
f2 = 120;    # 120Hz

n = 0:Ts:(N-1)*Ts;           # time vector
x = sin(2*pi*f1*n) + sin(2*pi*f2*n); # a sinusoid signal
xr = x + 2*randn(size(n));    # a noisy signal

X = fft(xr);                  # FFT
X2 = 1/N*abs(X);              # FFT magnitude full buffer length
F2 = Fs*(0:(N-1))/N;          # Frequency vector full buffer length

X1 = X2(1:N/2+1)/2;           # FFT magnitude half buffer length
X1(2:end-1) = 2*X1(2:end-1);  # Arranged values
F1 = Fs*(0:(N/2))/N;          # Frequency vector half buffer length

figure( 1, "visible", "off" )

subplot(2,1,1)
plot(Fs*n(1:100),xr(1:100));
title('Zeitbereich')
ylabel('Amplitude');
xlabel('Zeit [ms]')
set(gca, "fontsize", 24);

subplot(2,1,2)
```

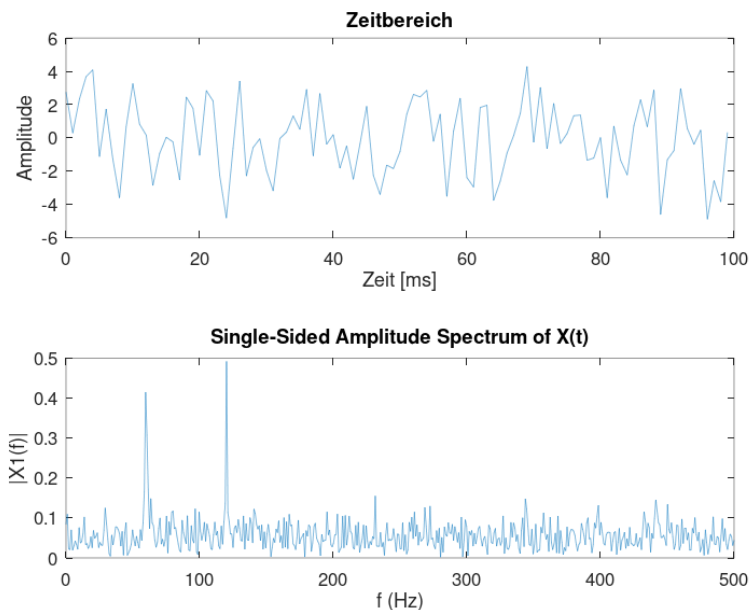
```

plot(F1,X1)
title('Single-Sided Amplitude Spectrum of X(t)')
xlabel('f (Hz)')
ylabel('|X1(f)|')
set(gca, "fontsize", 24);

## subplot(2,1,3);
## plot(F2,X2);
## title('Two-Sided Amplitude Spectrum of X(t)')
## ylabel('|X2(f)|')
## xlabel('Frequenz [Hertz]')
## set(gca, "fontsize", 24);

# Org-Mode specific setting
print -dpng "-S800,600" ./image/eth-example.png;
ans = "./image/eth-example.png";

```



### DFT Example - Analysis of Musical Instruments

- The fundamental note is the **first peak** in the spectrum

- The relative size of the harmonics gives the timber or the character of an instrument

### 1.2.9 TODO DFT Synthesis

### 1.2.10 DFT Examples

#### Tide Prediction in Venice

#### MP3 Compression

- MP3 compression approx. factor 20 or more
- Compression introduces noise from approximation error
- [Noise Shaping](#) : Error shaped as the signal in the Fourier domain.
- [Perceptual Compression](#) includes the human hearing system properties into compression algorithm

#### Video Signal of the Day: The first man-made signal from outer space

$$f = \frac{\omega f_s}{2\pi}$$

- A [multiplication](#) in time domain corresponds to a [convolution](#) in frequency domain

### 1.3 The Short-Time Fourier Transform STFT

- STFT is a clever way of using DFT
- Spectrogram, is a graphical way to represent the STFT data

#### The short-time Fourier transform

- DTMF Dual-Tone Multi Frequency dialing
- Time representation obscures frequency
- Frequency representation obscures time

$$x[m; k] = \sum_{n=0}^{L-1} x[m + n] e^{-j \frac{2\pi}{L} nk}$$

- **m** Starting point of the localized DFT
- **k** Is the DFT index

### ONGOING The spectrogram

- color-code the magnituded: dark is small, white is large
- use  $10\log_{10}(|X[m, k]|)$  to see better (powr in dBs)
- plot spectral slices one after another

#### 1.3.1 STFT Example

