

# Indistinguishability of Linear Compartmental Models

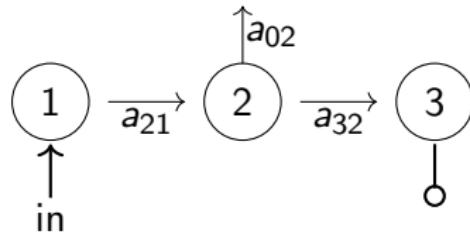
Cash Bortner\* and Nicolette Meshkat†

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†Santa Clara University

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SIAM Conference on Applied Algebraic Geometry, 2025  
University of Wisconsin, Madison, WI  
7/10/2025

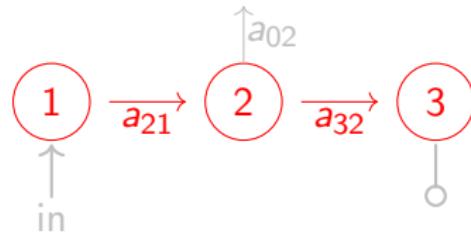
# Motivating Example



## Linear Compartmental Model

$$\begin{aligned}\mathcal{M} &= (G, In, Out, Leak) \\ &= (\vec{P}_3, \{1\}, \{3\}, \{2\}).\end{aligned}$$

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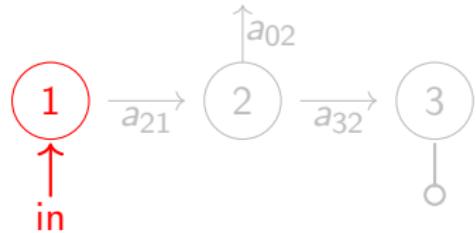


Directed Graph:  $G = \vec{P}_3$

## Linear Compartmental Model

$$\begin{aligned}\mathcal{M} &= (\textcolor{red}{G}, \textit{In}, \textit{Out}, \textit{Leak}) \\ &= (\vec{P}_3, \{1\}, \{3\}, \{2\}).\end{aligned}$$

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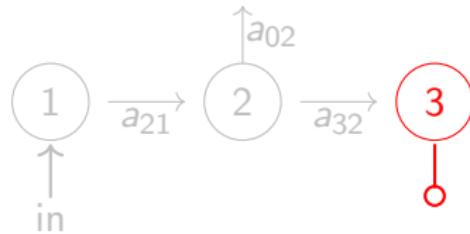


## Linear Compartmental Model

$$\begin{aligned}\mathcal{M} &= (G, \textcolor{red}{In}, \textcolor{gray}{Out}, \textcolor{gray}{Leak}) \\ &= (\vec{P}_3, \{1\}, \{3\}, \{2\}).\end{aligned}$$

Input Compartment:  $In = \{1\}$

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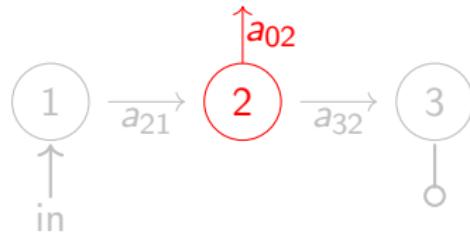


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Output Compartment:  $Out = \{3\}$

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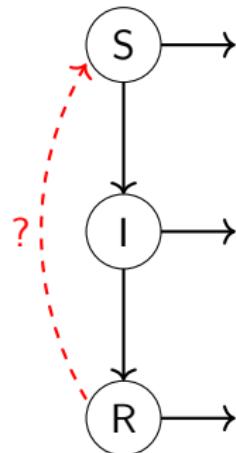
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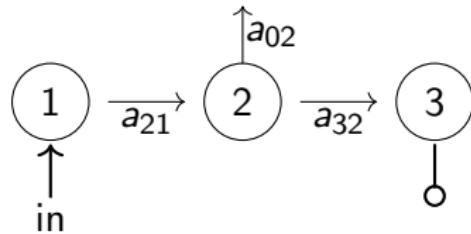
Leak Compartment:  $\text{Leak} = \{2\}$

# Compartmental Models in the Wild

- SIR Model for spread of a virus in Epidemiology (non-linear)
- SIV Model for vaccine efficiency in Epidemiology
- Modeling Pharmacokinetics for absorption, distribution, metabolism, and excretion in the blood
- Modeling different biological systems



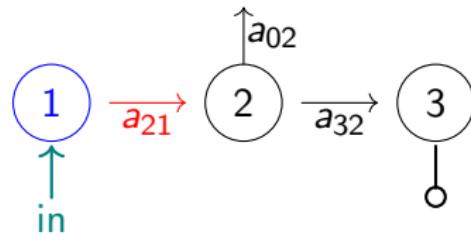
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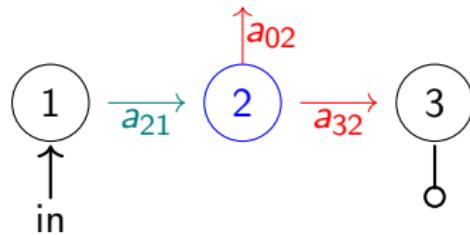
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ODEs in terms of concentrations  $x_i(t)$ , input  $u_1(t)$ , and output  $y_3(t)$ :

$$\dot{x}_1(t) = -a_{21}x_1(t) + u_1(t)$$

# Motivating Example



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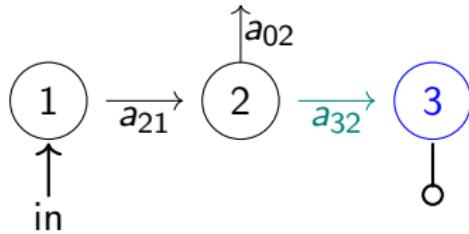
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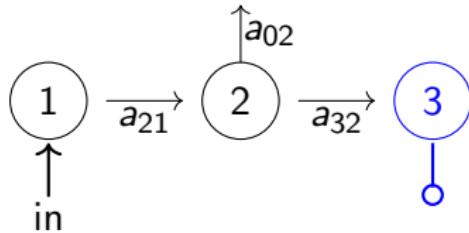
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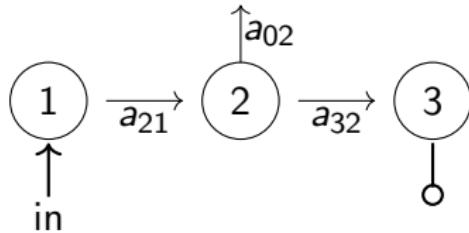
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with

$$y_3(t) = x_3(t).$$

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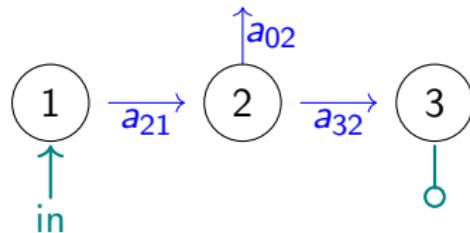
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# Motivating Example: Input/Output Equation



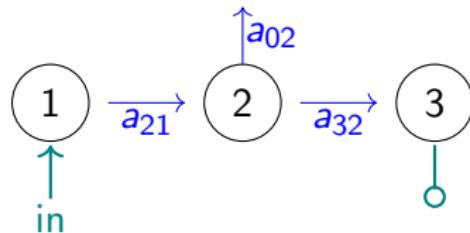
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Via an application of Cramer's Rule:

$$\det(\partial I - A)y_3 = \overbrace{\det(\partial I - A)^{1,3}}^{\text{remove row 1, col. 3}} u_1$$

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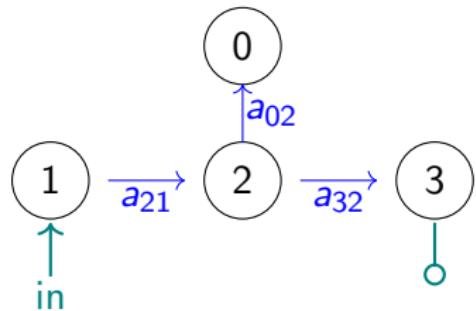
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an ODE in only the **measurable variables** and the **parameters**:

**Input/Output Equation**

## Motivating Example: Input/Output Equation

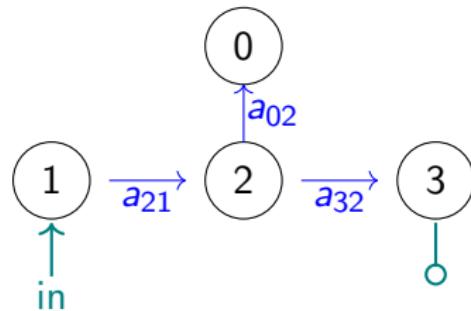


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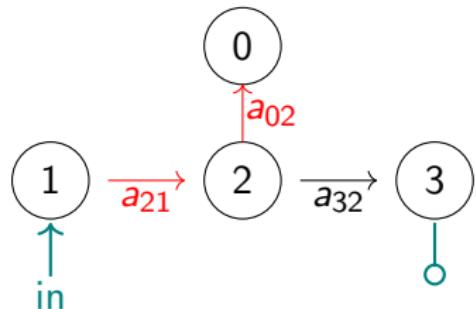
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Theorem (\$, Gross, Meshkat, Shiu, Sullivant [2023])

The coefficients of the input-output equation of a LCM  $(G, \text{In}, \text{Out}, \text{Leak})$  can be generated by *incoming forests* on graphs related to  $G$ .

- *incoming*: no vertex has more than **one** outgoing edge
- *forest*: no cycles

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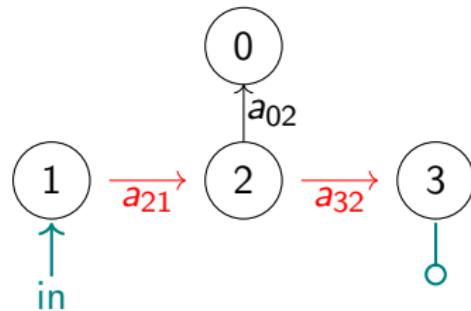
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## Definition

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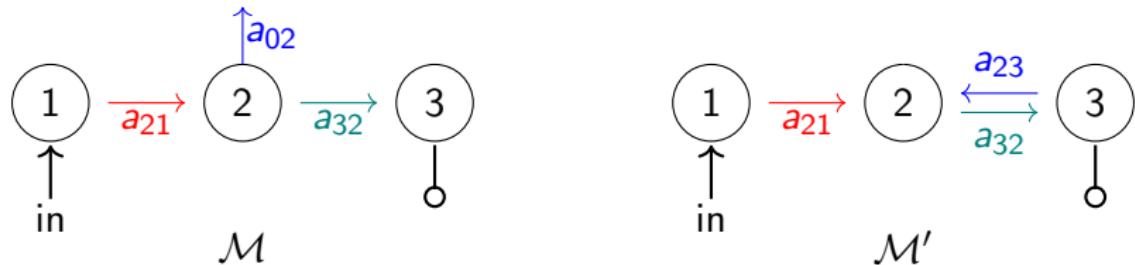
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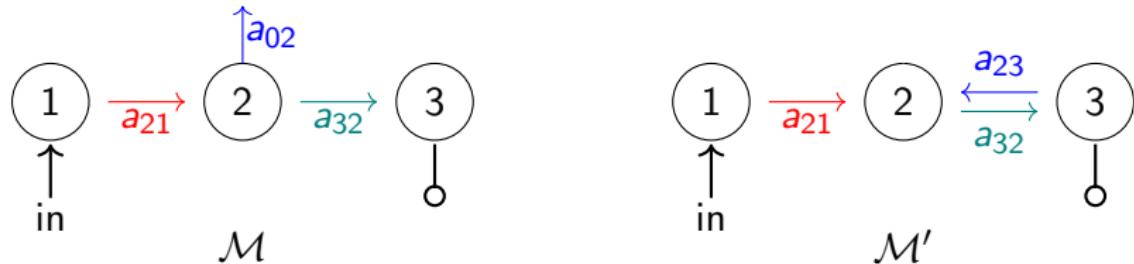
Two LCMs are *indistinguishable* if for any choice of parameters in the first model, there is a choice of parameters in the second model that will yield the same *dynamics* in both models.

What does “same dynamics” mean?

# Motivating Example: Indistinguishability



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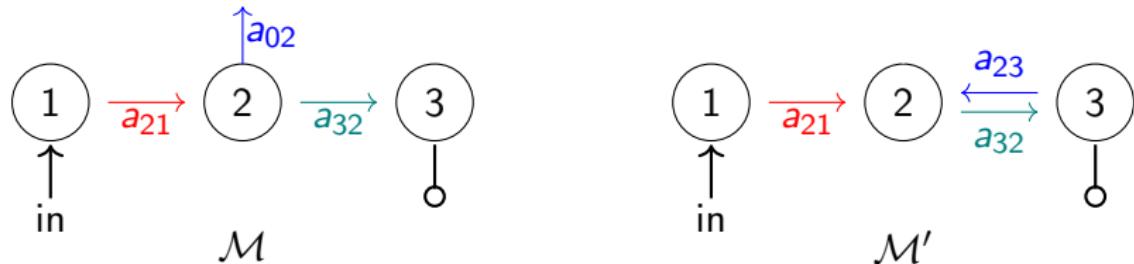
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## Remark

From the perspective of the input-output equations, we can not *distinguish* between these two very structurally different models.

# Motivating Example: Indistinguishability



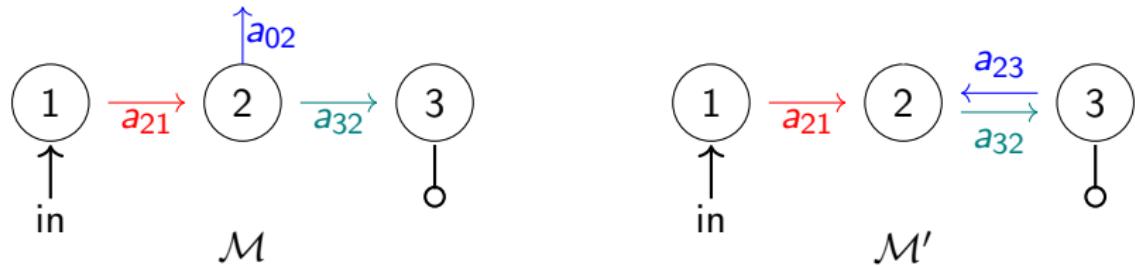
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## Working Definition

Two models are *permutation indistinguishable* if they have the same input-output equations up to renaming the parameters.

## Motivating Example: Indistinguishability

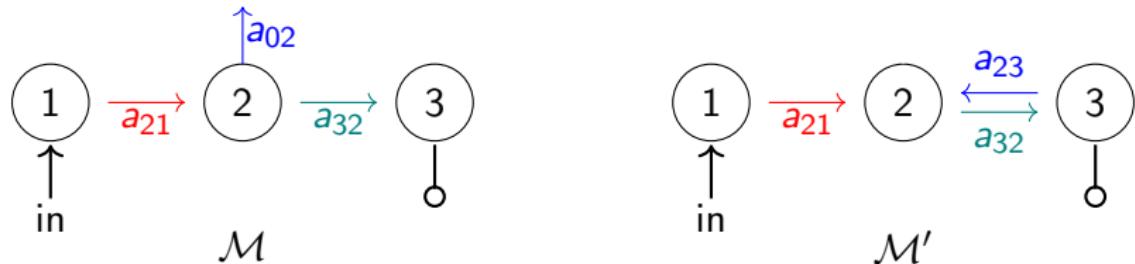


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renaming:  $\begin{pmatrix} a_{21} \\ a_{02} \\ a_{32} \end{pmatrix} \mapsto \begin{pmatrix} a_{21} \\ a_{23} \\ a_{32} \end{pmatrix}$

# Motivating Example: Indistinguishability



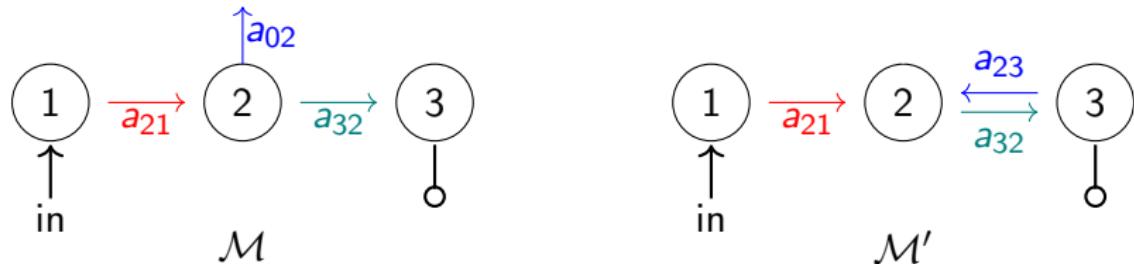
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## Remark

Permutation indistinguishability is an *equivalence relation!*

# Motivating Example: Indistinguishability



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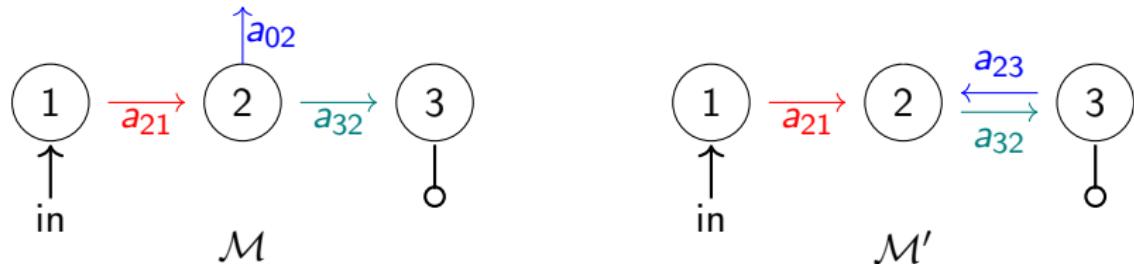
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**Question:** What is the *equivalence class* of a model?

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Permutation indistinguishability is an *equivalence relation*!

**Question:** What is the *equivalence class* of a model? (Size 1?)

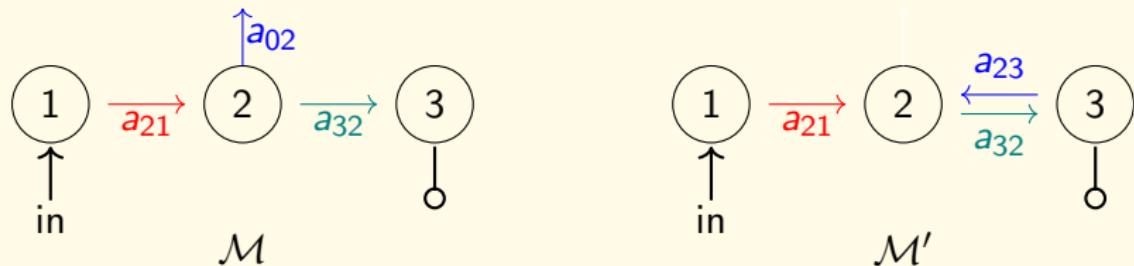
# Previous Work: Necessary Conditions for Indist.

## Theorem (Godfrey & Chapman [1990])

Two indistinguishable models must preserve the following:

1. The length of the shortest path from the input to the output
2. The number of compartments with a path to any output compartment
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4. The number of traps\*

## Example



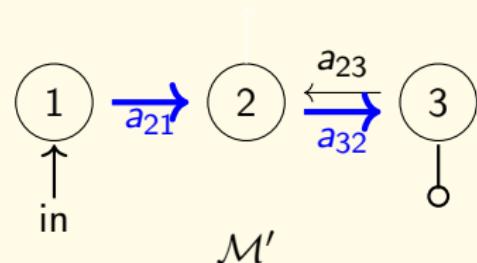
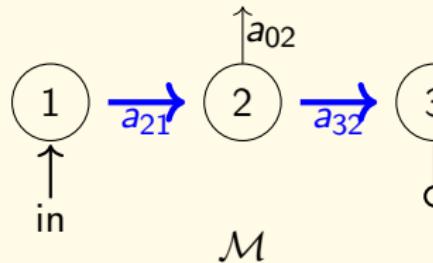
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Example (1.  $\text{Dist}(1, 3) = 2$  in both!)



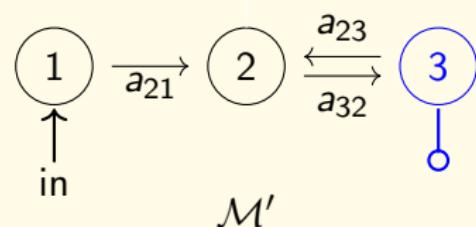
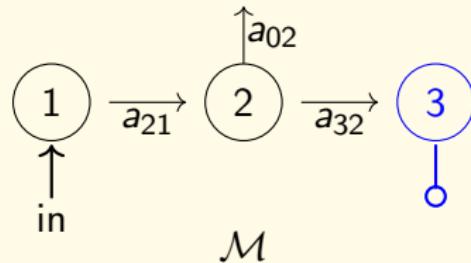
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Example (2. **Two** compartments with a path to the output!)



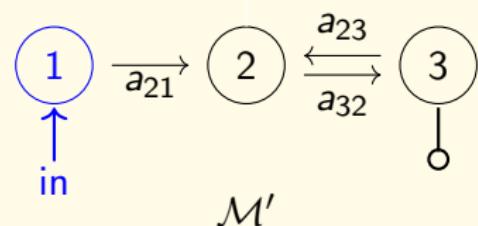
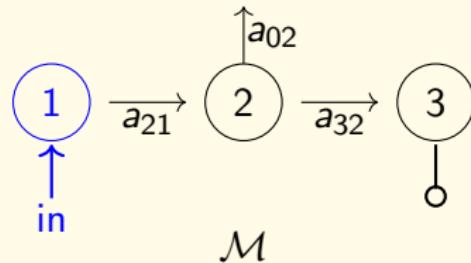
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Example (3. **Two** compartments with a path from the input!)



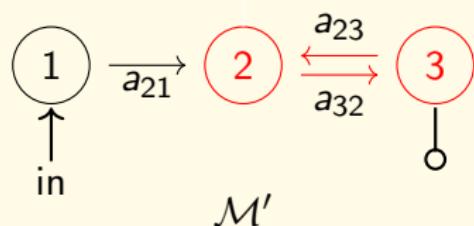
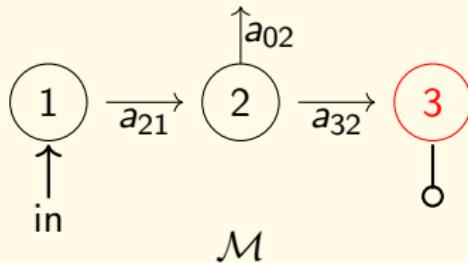
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Example (4. Each model has **one** trap!)



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### Goal:

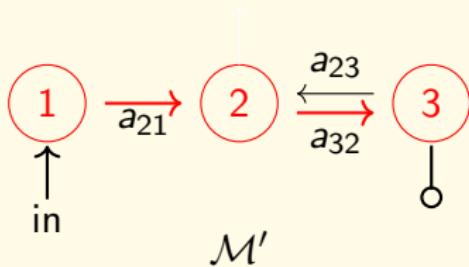
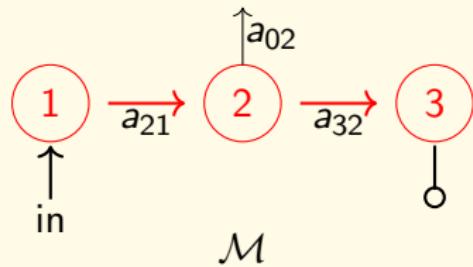
Find *sufficient* conditions for permutation indistinguishability of two models based on their graph structures.

# Skeletal Path Models

## Definition

A *skeletal path model* is an LCM whose graph contains the directed path  $\overrightarrow{P_n}$ , i.e  $1 \rightarrow 2 \rightarrow \dots \rightarrow n$ , with  $In = \{1\}$  and  $Out = \{n\}$ .

## Example



# Skeletal Path Moves: Walking the Leak

## Question

What *moves* can you perform on a basic skeletal path model resulting in an indistinguishable model?



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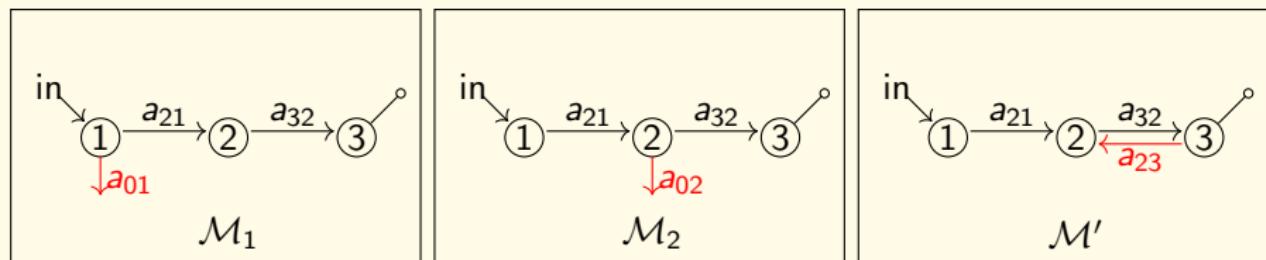
What *moves* can you perform on a basic skeletal path model resulting in an indistinguishable model?

Theorem (\$ & Meshkat [2024]; \$, Gilliana, Patel, & Tamras [2025\*])

The following skeletal path models are indistinguishable:

- $\mathcal{M}_i = (\overrightarrow{P_n}, \{1\}, \{n\}, \{i\})$  for any  $i \in \{1, 2, 3, \dots, n-1\}$
- $\mathcal{M}' = (\overrightarrow{P_n} \cup \{n \rightarrow n-1\}, \{1\}, \{n\}, \emptyset)$ .

## Example



## Proof idea

Theorem (\$ & Meshkat [2024]; \$, Gilliana, Patel, & Tamras [2025\*])

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*Proof idea 1:* Left-hand side of the input/output equation of  $\mathcal{M}_i$  given by:

$$\det(\partial I - A_i) y_n = \det \begin{pmatrix} \partial + a_{21} & 0 & \cdots & \cdots & 0 & 0 \\ -a_{21} & \ddots & \ddots & \ddots & \vdots & \vdots \\ 0 & \ddots & \partial + a_{0i} + a_{i(i-1)} & \ddots & \vdots & \vdots \\ \vdots & \ddots & -a_{i(i-1)} & \ddots & 0 & 0 \\ 0 & \cdots & \ddots & \ddots & \partial + a_{n(n-1)} & 0 \\ 0 & \cdots & \cdots & 0 & -a_{n(n-1)} & \partial \end{pmatrix} y_n$$

## Proof idea

Theorem (\$ & Meshkat [2024]; \$, Gilliana, Patel, & Tamras [2025\*])

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*Proof idea 2:*

- Under a renaming of the parameters, the incoming forests of each  $\mathcal{M}_i$  are exactly the same as the incoming forests of each  $\mathcal{M}_j$  (and  $\mathcal{M}'$ ).

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*Proof idea 2:*

- Under a renaming of the parameters, the incoming forests of each  $\mathcal{M}_i$  are exactly the same as the incoming forests of each  $\mathcal{M}_j$  (and  $\mathcal{M}'$ ).
- Thus, each of the coefficients of the respective input/output equations are indistinguishable.

# Detour Models

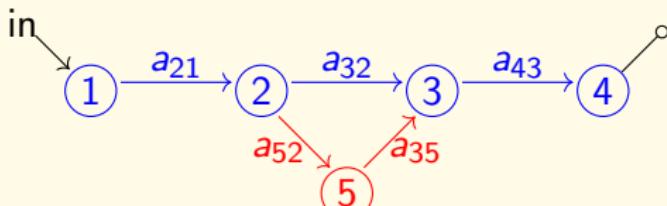
## Definition

A *detour model* is given by

$$\mathcal{M} = (\vec{P}_n \cup D_{i,j}^*, \{1\}, \{n\}, \text{Leak})$$

where  $D$  is some connected directed graph, and  $D_{i,j}^*$  includes one edge from node  $i$  and to node  $j$  in the skeletal path.

## Example



$$\mathcal{M} = (\vec{P}_4 \cup D_{2,3}^*, \{1\}, \{4\}, \emptyset)$$

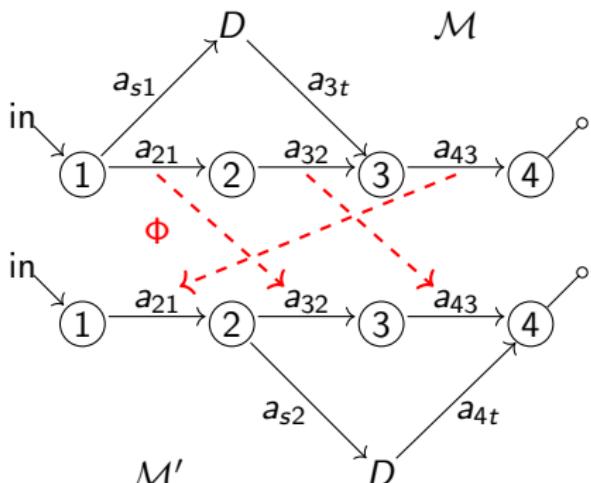
# Detour Models

Theorem (\$ & Meshkat [2024])

The following two detour models are indistinguishable:

- $\mathcal{M} = (\overrightarrow{P_n} \cup D_{i,j}^*, \{1\}, \{n\}, \text{Leak})$
- $\mathcal{M}' = (\overrightarrow{P_n} \cup D_{i+1,j+1}^*, \{1\}, \{n\}, \text{Leak})$

*Proof idea:*



- Break the  $A$  matrices into blocks, and show equivalent determinants under  $\Phi$

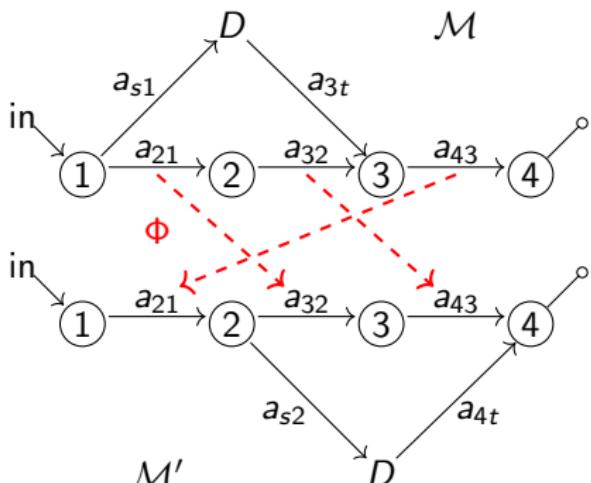
# Detour Models

Theorem (\$ & Meshkat [2024])

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*Proof idea:*



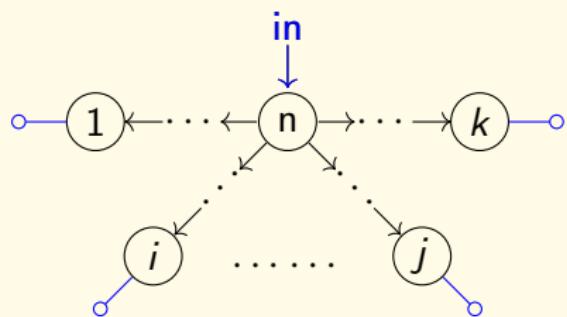
- Break the  $A$  matrices into blocks, and show equivalent determinants under  $\Phi$
- Or, the incoming forests under the renaming  $\Phi$  are the same, so the coefficients are the same!

# Source and Sink Models

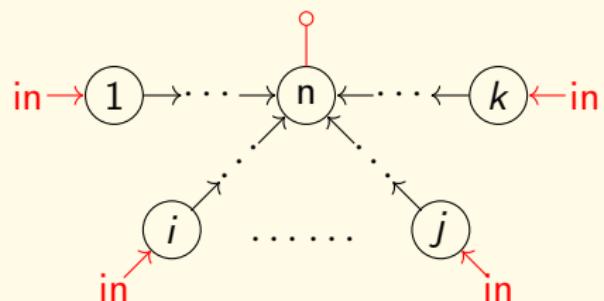
Corollary (\$ & Meshkat [2024])

We can extend results from detour models to *source* and *sink* models.

Example



Basic *Source* Model



Basic *Sink* Model

## Future Work

- These are very specific families of LCMs, but this is a proof of concept moving forward!
- More implementation of graph theory in showing sufficient conditions for other families of models
  - Cycle Models (undergraduate research project)
  - Tree Models
- Look into more general indistinguishability from a graph perspective
- Help biologists determine if the model they are using is the **only** model which yield the same dynamics

# References



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# Thank you!!!

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# This Presentation!

