Model-based Statistical Learning



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Parsimonious models for GMM

In many situations, it may be useful to consider more constrained models:

Full GTTT:
$$\Theta = \langle T_{4}, \mu_{4}, I_{4} \rangle$$

Com GTTT: $\Theta = \langle T_{4}, \mu_{4}, I_{4} \rangle$

drag $GTTT$: $\Theta = \langle T_{4}, \mu_{4}, I_{4} \rangle$

iso $GTTT$: $\Theta = \langle T_{4}, \mu_{4}, I_{4} \rangle$

$$\vdots$$

$$A = \langle I_{4}, \mu_{4}, I_{4} \rangle$$

$$\vdots$$

$$A = \langle I_{4}, \mu_{4}, I_{4} \rangle$$

$$\vdots$$

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$$\vdots$$

Parsimonious models for GMM

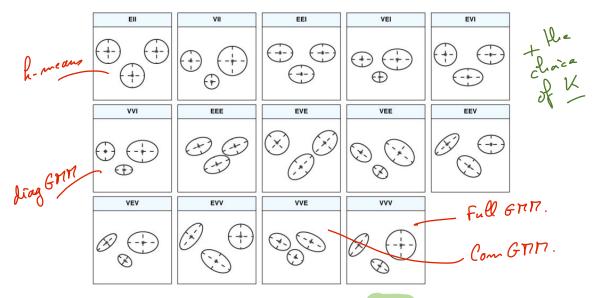


Figure: The parsimonious models of Mclust.

How to choose between models?

In packer, when facing some data set, we need to pick the appropriate number K of components and the Lest GTT model to fit on data.



Model selection The noots of model selectic can be found in Bayesia statistical theory. Let'o first consider a set of models to test: of Mr, Mr, ..., Mas and associated to prin

probabilities p(dg) (in practice we prefer to use p(dg) = p. kg The idea of model selection is to eva a specific quantity: p(olg | X). selection is to evaluate

Thanks to the Bayes theoren: $p(\partial l_g | X) \not\propto p(X | \partial l_g) p(\partial l_g) \quad (1).$ To comprte this quality, we have to evaluate it for all possible combinations of the parameters of oly $P(X|\mathcal{A}_g) = \int P(X|\mathcal{A}_g,\mathcal{O}_g) \cdot P(\mathcal{O}_g|\mathcal{A}_g) dQ_g$ Romy: due to the high-dimensional integration over Eg, this composition is very often intractable!

Note: the quantity p(X|olg) is ralled the integrated likelihood or the evidence or the marginal likelihood,

Then:

In pactice, we prefer to assid the computation problem by approximating the integrated hibelihood:

 $\mathcal{O}(x) = \underset{\mathcal{O}}{\text{arg }} \underset{\mathcal{O}}{\text{arg }} \sum_{g} \sum_$

Among the possible approximation of the integrated like lihood, the most popular one is BiC: Bayerian Information Citerian, Schwarz, 1978 $\log p(X|\partial l_g) \simeq \log p(X|\partial l_g, \hat{Q}_{HL}) - \frac{V(\partial l_g)}{2} \log (n)$

where V(olg) is the number of free parameters in the model olg, and n is the number of osevations.

For information, Bic is both an asymptotic approximation of the maginal like Cilood (Bic p(X/dg)) and a second order Taylor expension of the integral, around it maximum Eps.

In practice:

H= argman Bic (ds).

Ruh: it is worth mentioning floot, unfahmately, the assumptions made about the regularity of the models in BiC are not satisfied for mixture models!

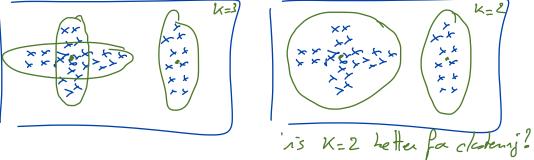
=> Faturately, Bic is behaves very well for mixture models and even when n < +00.

What we do: Al = Foll GMR with 4=2 En Sirc -> Bic (d.) de = dias GAR - K=2 ER & -> Biddle Olz = FILL GMM _ K=3 EN S _ Bic(43/ 8/4 = diag BMR _ K=3 = ER 2 -> Ble (da)

and we choose It's because Bic (Olz) is the largest one. with Molot:

kunh: Bic (and Aic which is a close criteria)
can be used for model selection in all
situations: regression, clostering,...

Model selection for distensy; The notion of mixture components and closters may defler in some specific gimations and it would be gent to have a MS outerian that takes this into account.



A soud way to answer this it to come back to the model selection throng and consider the integated complete likelihood instead of the integated likelihood: et = degmax p(X,Y) ofg) Then, it is possible to make the same approximations. p(X, Y | olg) ~ log p(X | ôg, dlg) - Y(olg) log(m) - 1 \(\frac{1}{2} \) \(\frac{1