

PRELIMINARY DEFINITIONS

Definition 1. A *monad* over a category \mathcal{C} is an endofunctor $P : \mathcal{C} \rightarrow \mathcal{C}$ equipped with

- a natural transformation $\eta_A : A \rightarrow PA$ (*unit*)
- a natural transformation $\mu_A : PPA \rightarrow PA$ (*multiplication*)
- **Diagram**

Definition 2. The *Kleisli category* of a monad (P, μ, η) over a category \mathcal{C} is a category \mathcal{C}_P where

- $Obj(\mathcal{C}) = Obj(\mathcal{C}_P)$
- $Hom_{\mathcal{C}_P}(A, B) = Hom_{\mathcal{C}}(A, PB)$
- $1_A = \eta_A$
- $g \circ f = \mu_C \circ Tg \circ f : A \rightarrow PC$

Definition 3. A *monoidal category* (**mc**) is a category \mathcal{C} equipped with

- a bifunctor $\otimes : \mathcal{C} \times \mathcal{C} \rightarrow \mathcal{C}$ (*tensor product*)
- an object I (*unit object*)
- a natural isomorphism $\alpha_{A,B,C} : (A \otimes B) \otimes C \cong A \otimes (B \otimes C)$ (*associator*)
- a natural isomorphism $\lambda_A : I \otimes A \cong A$ (*left unitor*)
- a natural isomorphism $\rho_A : A \otimes I \cong A$ (*right unitor*)
- **Diagram**

Definition 4. A *symmetric monoidal category* (**smc**) is a monoidal category $(\mathcal{C}, \otimes, I)$ equipped with

- a natural isomorphism $\sigma_{A,B} : A \otimes B \rightarrow B \otimes A$ (*swap*)
- **Diagram**

Definition 5. A *strong monad* over a monoidal category $(\mathcal{C}, \otimes, I)$ is a monad (P, μ, η) equipped with

- a natural transformation $\tau_{A,B} : A \otimes P(B) \rightarrow P(A \otimes B)$ (*strength*)
- **Diagram**

Definition 6. A *cartesian monoidal category* (**cmc**) is a monoidal category $(\mathcal{C}, \otimes, I)$ in which \otimes is the categorical product and I is the terminal object in \mathcal{C} . Every object A in \mathcal{C} is equipped with

- a natural transformation $\Delta_A : A \rightarrow A \otimes A$ (*duplication*)
- a natural transformation $\delta_A : A \rightarrow I$ (*deletion*)
- **Diagram**

that determine a *unique* comonoid on A .

GENERAL COMPREHENSIONS

Definition 7. A *context* is a finite list $\vec{x} = x_1 x_2 \dots x_n$ of distinct variables, where $n = 0$ is the empty context $[]$. If \vec{x} is a context and $y \neq x_i$ for all $i \leq n$, then $\vec{x}y$ denotes the context obtained by appending y to \vec{x} . Similarly $\vec{x}\vec{y}$ denotes the context obtained by concatenating \vec{x} and \vec{y} ($x_i \neq y_j$ for all x_i in \vec{x} and y_j in \vec{y}). The *type* of a context \vec{x} is the string of the types of the variables appearing in it.

In the following definitions, \mathcal{C} is assumed to be a *symmetric cartesian monoidal category* (scmc) $(\mathcal{C}, \times, 1, \sigma)$ with a *strong monad* (P, μ, η, τ) . We use the equivalence $MA = M(A_1 \times A_2 \times \dots \times A_n)$ to denote contexts and $[t \mid x_1 \leftarrow u_1, x_2 \leftarrow u_2, \dots, x_n \leftarrow u_n] = [t \mid u_1, u_2, \dots, u_n]$ to denote comprehensions.

Definition 8. Let $\llbracket \vec{x}.u \rrbracket_M : MA \rightarrow P(MB)$ be a morphism in \mathcal{C} . The *context sensitive* morphism $\llbracket \vec{x}.\vec{u} \rrbracket_M$ of $\llbracket \vec{x}.u \rrbracket_M$ is the morphism

$$MA \xrightarrow{\Delta_{MA}} MA \times MA \xrightarrow{1_{MA} \times \llbracket \vec{x}.u \rrbracket_M} MA \times P(MB) \xrightarrow{\tau_{MA, P(MB)}} P(MA \times MB)$$

We can think of a context sensitive morphism as information preserving; the source of the morphism is present in the target.

Definition 9. Let M be a Σ -structure in \mathcal{C} . If $\vec{x}.t$ is a term-in-context over Σ and t is of type PD , then the morphism

$$\llbracket \vec{x}.t \rrbracket_M : MA \rightarrow P(MD)$$

is defined inductively by the following clauses:

- (1) If $t = [u]$ is of type PD and u is of type D

$$MA \xrightarrow{\llbracket \vec{x}.u \rrbracket_M} MD \xrightarrow{\eta_D} P(MD)$$

- (2) If $t = [u \mid v]$ is of type PD , u is of type D , and v is of type PC

$$MA \xrightarrow{\llbracket \vec{x}.\vec{v} \rrbracket_M} P(MA \times MC) \xrightarrow{P(\llbracket \vec{x}y.u \rrbracket_M)} P(MD)$$

- (3) If $t = [u \mid v, w]$ is of type PD , u is of type D , v is of type PB , and w is of type PC

$$MA \xrightarrow{\llbracket \vec{x}.\vec{v} \rrbracket_M} P(MA \times MB) \xrightarrow{P(\llbracket \vec{x}y.\vec{w} \rrbracket_M)} PP(MA \times MB \times MC) \xrightarrow{P(P(\llbracket \vec{x}yz.u \rrbracket_M))} PP(MA \times MB \times MC \times MD) \\ \xrightarrow{\mu_{MA \times MB \times MC \times MD}} P(MA \times MB \times MC \times MD)$$

Note that (2) and (3) together are sufficient to define comprehensions with non-negative finite qualifiers. The derivation of the composition in (3) is given below.

•

$$\begin{aligned} \llbracket \vec{x}.t \rrbracket_M &= \llbracket \vec{x}.[u \mid v, w] \rrbracket_M \\ &= \mu_D \circ \llbracket [[u \mid w] \mid v] \rrbracket_M \\ &= \mu_D \circ P(\llbracket \vec{x}y.[u \mid w] \rrbracket_M) \circ \llbracket \vec{x}.\vec{v} \rrbracket_M \\ &= \mu_D \circ P(P(\llbracket \vec{x}yz.u \rrbracket_M) \circ \llbracket \vec{x}y.\vec{w} \rrbracket_M) \circ \llbracket \vec{x}.\vec{v} \rrbracket_M \\ &= \mu_D \circ P(P(\llbracket \vec{x}yz.u \rrbracket_M)) \circ P(\llbracket \vec{x}y.\vec{w} \rrbracket_M) \circ \llbracket \vec{x}.\vec{v} \rrbracket_M \end{aligned}$$

Definition 10. Let $\llbracket \vec{x}.u \rrbracket_M : MA \rightarrow P(MB)$ and $\llbracket \vec{y}.v \rrbracket_M : MB \rightarrow P(MC)$ be morphisms in \mathcal{C} . The *Kleisli composition* $\llbracket \vec{x}.u \rrbracket_M \rightsquigarrow \llbracket \vec{y}.v \rrbracket_M$ of $\llbracket \vec{x}.u \rrbracket_M$ and $\llbracket \vec{y}.v \rrbracket_M$ is the morphism

$$MA \xrightarrow{\llbracket \vec{x}.u \rrbracket_M} P(MB) \xrightarrow{P(\llbracket \vec{y}.v \rrbracket_M)} PP(MC) \xrightarrow{\mu_{MC}} P(MC)$$