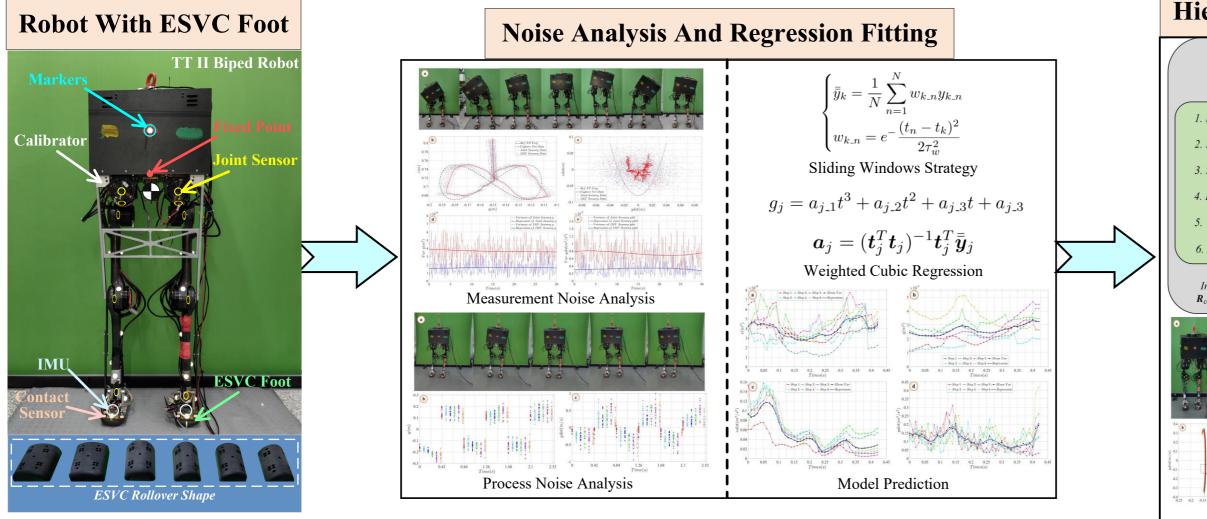
Noise Analysis and Hierarchical Adaptive Body State Estimator For Biped Robot Walking With ESVC Foot



Hierarchical Adaptive Estimation & Validation

