CSINTSY - S15

MCO1 - Technical Report

- 1. Define the goal of the GOLD MINER agent
 - The goal of the Gold Miner is to land on the Gold Pot and avoid the Pit that exists throughout the board.
- 2. Formulate the problem
 - Miner has only 3 moves namely:
 - Scan
 - Front
 - Rotate
 - The miner has to go to the goal state, which is to find and go to the Gold Pot, while avoiding the pits and using useful beacons through the usage of the three available moves.
- 3. Determine the specific states and configurations that the agent operates on

Random

- Generated number is 1
- Generated number is 2

Smart

- Scanned nothing
- Scanned a Pit
- Scanned a Beacon
- Scanned the Gold Pot

4. Determine the specific actions, and the states (configurations) on which the actions are applicable (include illustrations for transition table)

Random

| STATE | ACTION | ILLUSTRATION: STATE | ILLUSTRATION: EFFECT |
|-----------------------|---------------|------------------------|-------------------------|
| Generated number is 1 | Moves forward | | |
| Generated number is 2 | Rotates | | |

Smart

| STATE | ACTION | ILLUSTRATION: STATE | ILLUSTRATION: EFFECT |
|----------------------|--------------------------------------------------|------------------------|-------------------------|
| Scans nothing | Scans four sides then moves forward | | |
| Detects the end tile | Does specific actions depending on the direction | | |
| Scans pit | Goes around it | | |

| Scans beacon | Forwards to the beacon, to determines whether it's useful or not | |
|---------------------------|------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------|
| Finds a useful beacon | Goes to all 4 sides of the beacon | |
| Finds a useless beacon | Activate it to prevent prioritizing on going back to it and disregard beacon | |
| Scans golden pot | Goes into golden pot | Miner has reached the Gold Pot! Number of Scans: 0 Number of Ratase: 4 Number of Fronts: 11 Exit Continue |

- 5. Specify how the goal state can be determined and detected by the agent
 - The goal state is when the miner reaches the GoldPot tile and wins the game. But if it is to be based on the code, the goal state is when the *didReachGoldPot()* method which checks if the Miner is at the same tile with the Gold Pot will return *true*.